NONLINEAR DECLINE-RATE DEPENDENCE AND INTRINSIC VARIATION OF TYPE Ia SUPERNOVA LUMINOSITIES

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ABSTRACT

Published B and V fluxes from nearby Type Ia supernovae are fitted to light-curve templates with 4-6 adjustable parameters. Separately, B magnitudes from the same sample are fitted to a linear dependence on $B-V$ color within a post-maximum time window prescribed by the CMAGIC method. These fits yield two independent SN magnitude estimates $B_{\max}$ and B_{BV} . Their difference varies systematically with decline rate Δm_{15} in a form that is compatible with a bilinear but not a linear dependence; a nonlinear form likely describes the decline-rate dependence of $B_{\max}$ itself. A Hubble fit to the average of $B_{\max}$ and B_{BV} requires a systematic correction for observed $B-V$ color that can be described by a linear coefficient $\mathcal{R} = 2.59 \pm 0.24$, well below the coefficient $R_B \approx 4.1$ commonly used to characterize the effects of Milky Way dust. At 99.9% confidence the data reject a simple model in which no color correction is required for SNe that are clustered at the blue end of their observed color distribution. After systematic corrections are performed, $B_{\max}$ and B_{BV} exhibit mutual rms intrinsic variation equal to 0.074 ± 0.019 mag, of which at least an equal share likely belongs to B_{BV} . SN magnitudes measured using maximum-luminosity or CMAGIC methods show comparable rms deviations of order ≈ 0.14 mag from the Hubble line. The same fit also establishes a 95% confidence upper limit of 486 km s^{-1} on the rms peculiar velocity of nearby SNe relative to the Hubble flow.

Subject headings: supernovae: general — cosmology: observations — distance scale

1. INTRODUCTION

Well before the Universe was found to be accelerating (Perlmutter et al. 1998; Garnavich et al. 1998; Schmidt et al. 1998; Riess et al. 1998; Perlmutter et al. 1999), Type Ia supernovae (SNe), the study of which underpinned that discovery, were thought to be standard candles. Even before the Type Ia subclass was identified, Kowal (1968) studied the distribution of Type I SN luminosities, and Pskovskii (1977) observed that brighter SNe exhibit slower decline rates. The standardization of Type Ia SNe sharpened when Phillips (1993) introduced a brighter-slower correction that was linear in the decline-rate parameter Δm_{15} (the change in magnitude from maximum light to 15 rest-frame days thereafter). That correction was refined by Hamuy et al. (1996a) and by Phillips et al. (1999) (henceforth Phil99), who added a quadratic term. Tripp (1998), Tripp & Branch (1999), and Parodi et al. (2000) fit a correction that was linear both in Δm_{15} and in a second parameter, $B-V$ color. In these two-parameter studies the observed brighter-bluer correlation was compensated by a fit color coefficient $\mathcal{R} \approx 2.5$. Perlmutter et al. (1997) and Goldhaber, Groom et al. (2001) (henceforth Perl97 and Gold01) stretched the time axis of a fixed template to approximate different SN light curves; that linear stretch factor substituted for Δm_{15} in their alternative brighter-slower correction.

Given an adequate training set – here an ensemble of SNe in the nearby Hubble flow whose deviations Δ_i from

a fiducial absolute SN magnitude are deduced from their redshifts – the problem of estimating the deviation Δ of a single SN, using a set $\{x_j\}$ of its measured parameters, is amenable to general solution. In principle the x_j can include any parameter that may add to knowledge of Δ : fluxes in various bands at various phases, spectral line amplitudes, *etc.* One example of such a solution is given in Appendix A. Present progress along these more general lines is exemplified by the MLCS2k2 package and its predecessors described by Riess, Press, & Kirshner (1995, 1996), Riess et al. (1998), and Jha (2002). As those authors found, multivariate approaches to SN standardization are severely limited by low training statistics. For example, the MLCS2k2 training set did not adequately constrain the color-correction coefficient R_V , for which an external value was imposed.

This paper aims to extend understanding of the systematic corrections that help standardize Type Ia supernova luminosities, and of the intrinsic variations which blur that standard. Large resources now are devoted to projects that use standardized SNe to measure with exquisite precision the parameters determining the Universe's recent acceleration, and even larger efforts will be needed to track the evolution of its equation of state, revealing the sources of that acceleration. Even small advances in such understanding can have big implications for the realization of these projects.

In this paper, we make use of only a few properties of nearby SNe – luminosity, color and decline rate – that are simple to characterize. In that sense our approach to SN standardization is traditional, in the vein of work cited in the first paragraph. Nevertheless, we do bring

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fresh tools to this study. By taking the difference between the two simplest measures of SN magnitude – luminosity at peak, and luminosity at fixed color using the CMAGIC method (Wang et al. 2003, henceforth Wang03) – we impose a new, more precise constraint on the (non-linear) form of their decline-rate dependence, and we set a robust lower bound on the intrinsic variation suffered by at least one of these measures. By applying a newly extended light-curve fitting method and standard error propagation consistently to each SN in the sample, we obtain a Hubble fit that sets a significant upper bound on the rms peculiar velocity of SNe relative to the Hubble flow.

In Section 2 our light-curve (LC) and CMAGIC fitting methods are introduced. Their outputs are shown to be independent, and the corrections made to them for extinction and time dilation are described. Section 3 identifies the photometric data sample that is processed by these methods, and the subsample of SNe to which Hubble fits are applied. Section 4 reveals the new information gained by comparing the LC and CMAGIC fit magnitudes. In Section 5 the result of a Hubble fit to the average of these outputs is presented; this is the final step in a global fit to the sample. Section 6 uses the global fit parameters to quantify the deviations of the LC and CMAGIC outputs from the Hubble line. Section 7 explores properties of the subset of SNe assumed to be largely free of extinction by host-galactic dust. The paper concludes with a summary and discussion.

2. METHODS FOR FITS TO PHOTOMETRIC DATA

We used two complementary methods to estimate SN magnitudes. The first, a light-curve method described in §2.1, is based on the fit peak magnitudes in the B and V bands, and on the fit difference Δm_{15} between the peak B magnitude and its value 15 rest-frame days later. These three key numbers and their uncertainties are supplied by our own LC fits to published measured fluxes in these bands. The fits were performed by a newly and substantially extended version of the algorithm of Perl97 and Gold01, in which the time axes of fixed templates were linearly stretched to best represent the flux data. After color and decline-rate corrections, the SN magnitude yielded by our LC method is called $B_{\max}$.

Our second method for estimating SN magnitudes, summarized in §2.2, is based on the output of the CMAGIC algorithm introduced by Wang03. This algorithm exploits the nearly linear dependence of B magnitude upon $B-V$ color over a period extending, for typical SNe, from ≈ 6 to ≈ 27 rest-frame days after maximum light. A least-squares linear fit to published magnitudes and colors measured within that range yields an intercept B_{BV} at fixed color $B-V = 0.6$. The above mentioned LC fit in the B band is also used to supply Δm_{15} and the phase at maximum. After color and decline-rate corrections, the SN magnitude yielded by our CMAGIC method is called B_{BV} .

By no means are either of these methods restricted to the B and V bands. Much study has been devoted to their extension to the R , I , and U bands (Wang03; Wang, L. et al. 2005, in preparation, henceforth Wang05a; Goldhaber, G. et al. 2005, in preparation). However, since this paper relies on comparing the results of these two meth-

ods, sufficient data must exist to complete both types of fit for each SN. Were we additionally to require successful LC and CMAGIC fits to the same SNe in the R , I , or U band, our sample size at best would halve. Data in these additional bands therefore remain outside this paper’s scope.

2.1. Light Curve Fits

This study requires use of a light-curve fit algorithm only for interpolating or extrapolating measured fluxes to compute $B_{\max}$, $V_{\max}$, and Δm_{15} . Here no other use is made of the LC fit parameters, and no physical significance need be ascribed to them. For completeness, nevertheless, we describe briefly the parametrization that we employed. More information on this algorithm is supplied in Wang05a.

The set of published flux measurements (for example in the B band) for a single SN was fit to the function

$$f(t; \Gamma_0, t_0, s_0, \tau_0, \epsilon_0, t_d) = \Gamma_0 [\mathcal{T}_B(t^*(t - t_0; s_0, \tau_0)) + \epsilon_0 \mathcal{T}_B(t^*(t - t_0 - t_d; s_0, \tau_0))] \quad (1)$$

where t is the rest-frame phase of the SN flux measurement; Γ_0 is an overall normalization; $\mathcal{T}_B(t_r)$ is a fiducial template for B band flux *vs.* rest-frame phase t_r that peaks at $t_r = 0$; and t_0 is the phase at which the first (main) term reaches its peak. In the first term, the “stretched” phase t^* , discussed further in Appendix B, is an odd function of $t - t_0$ with parameters s_0 and τ_0 . The “stretch” parameter s_0 is equal to dt/dt^* at $t = t_0$; the “duration” parameter τ_0 is such that dt/dt^* is damped to unity when $|t - t_0| \gg \tau_0$. Relative to the main term, the second (delayed) term is different only in that its phase at peak amplitude is delayed by t_d and its amplitude is reduced by the factor ϵ_0 . The special case $\{\tau_0 = \infty$ (no damping); $\epsilon_0 = 0$ (no delayed term) $\}$ was studied by Perl97 and Gold01; under those conditions their parameter s is equivalent to s_0 . In all fits here, the parameter τ_0 is allowed to vary along with Γ_0 , t_0 , and s_0 ; when ϵ_0 is nonzero, as is permitted (Appendix B) for a minority of SNe, ϵ_0 and t_d vary as well. Within a band, usually all available data were fitted, including those in the “tail” region $t^* \gtrsim 30$ dy. Here we are not concerned with results that are specific to the tail region, or the transition thereto, because we emphasize methods that may profitably be applied to faint SNe that (unlike the nearby sample) are sensitive to cosmological acceleration.

For neighboring bands the LC fit procedure is the same (except for choice of template). Smoothed versions of the B template described by Gold01 and of the V template described by Knop et al. (2003) are used. Parameters that are fit to data in different bands are nearly independent, with only two exceptions: for all bands in which a given SN is fitted, ϵ_0 either is left free or is set to zero; and the epochs of peak flux are required to align within certain loose windows. To satisfy the latter conditions, all bands were fit at once. For decline-rate corrections we did not use Δm_{15}^V in the V band as a substitute for, or in combination with, the B band value: though a satisfactory correlation of Δm_{15}^V with Δm_{15} was seen, and reasonable Hubble fits using Δm_{15}^V alone or in combination with Δm_{15} were produced, tighter Hubble residuals were obtained by using Δm_{15} alone. Neither did we substitute the fit parameter $1/s_0$ for Δm_{15} , because Δm_{15} is correlated also with the companion parameter τ_0 .

For various choices of the stretch function $t^*(t)$ in equation (1), our LC fit results for $B_{\max}$ and $V_{\max}$ are stable. Measuring Δm_{15} is more delicate: because the time derivative of the flux at day 15 can be large, a small error in the definition of the date of maximum flux can translate into a large error in Δm_{15} . Especially near those times, both $t^*(t)$ and the template parametrization must be smoothly differentiable. Accordingly we employed a particular choice of $t^*(t)$ for which details are supplied in Appendix B.

In summary, we have applied to the full SN sample a uniform mathematical approach for determining their peak magnitudes and decline rates. The approach is self-consistent, with covariance matrices used to propagate the raw flux errors through to the final uncertainties. As a check of these methods, we subjected accurate graphs of each of our LC fits to detailed inspection which confirmed that, within quoted uncertainties, the measured fluxes are represented satisfactorily by these fits.

As an alternative approach, we could have attempted to combine and use the published results of different light-curve fits, employing various methodologies, that had been performed on these SNe. The dangers in such an attempt become evident when one compares our values of parameters such as Δm_{15} and peak magnitude with those found *e.g.* in the useful compilation of Reindl et al. (2005). Significant differences are found, particularly in values of Δm_{15} . For example, the compiled values of Δm_{15} are largely confined above a lower limit of ≈ 0.84 – 0.87 mag, with several exactly equal to 0.87 . Other SNe are clustered at $\Delta m_{15} = 1.13$ and 1.69 . Such artifacts, which are not found in our own Δm_{15} distributions, appear to have arisen from limitations in the number of well-observed SN light curves that were available for use as discrete templates by the published fits.

2.2. Fits to B Magnitude vs. $B-V$ Color

The CMAGIC method described by Wang03 begins with pairs of fluxes measured in the B and V bands at the same epoch t_i . These flux pairs are converted to raw magnitude pairs $\{B_i, V_i\}$ and entered on a plot of B_i vs. $(B_i - V_i)$. In parallel, the above-described LC fit is used to determine the decline-rate parameter Δm_{15} and the rest-frame phase t_{peak} of peak B flux. To those pairs $\{B_i, V_i\}$ which lie within a fiducial region $t_b - t_{\text{peak}} < t_i < t_e - t_{\text{peak}}$, a weighted least-squares linear fit is performed in which the errors on B_i and V_i are taken to be independent. At least three pairs must participate in the fit, providing a minimum of one constraint. The fit outputs are B_{BV}^{raw} , the intercept of the best-fit line with the fixed color $B_i - V_i = 0.6$ mag; the slope β_{BV} of that line; and their errors. (Our B_{BV}^{raw} is equivalent to $B_{BV0.6}$ of Wang03 and Conley et al. (2005) (henceforth Conl05).) The boundaries $\{t_b - t_{\text{peak}}, t_e - t_{\text{peak}}\}$ of the CMAGIC linear region are $\{(7 \text{ mag})/\Delta m_{15}, (30 \text{ mag})/\Delta m_{15}\}$ dy for normal SNe, and $\{(10 \text{ mag})/\Delta m_{15}, (29 \text{ mag})/\Delta m_{15}\}$ dy for spectroscopically SN1991T-like SNe.

As noted by Wang03, the average slope β_{BV} is very nearly equal to 2, with an rms intrinsic scatter (apart from photometric error) that is less than 0.1. If β_{BV} either were assumed or were measured always to have the same value, as is nearly the case, our choice of intercept color $B_i - V_i = 0.6$ would be immaterial. Here this par-

ticular value is chosen for compatibility with earlier work (Wang03; Conl05), and for its consistency with the intercept color that minimizes both the measured rms Hubble residual of B_{BV} and the |covariance| between the intercept and β_{BV} .

2.3. Photometric Errors

Sources of photometric SN data are diverse; reported errors on data points are not always reliable, and their covariances normally are unavailable. Additional systematic errors arise from observations on different telescopes and from uncertainties in the adopted light curve models. To gain confidence in the errors on LC and CMAGIC fit outputs, we examined the distributions of confidence levels (CLs) for each type of fit. Ideally both distributions should be uniform between 0 and 1. However, typically the LC fits had smaller CLs than expected, likely because, even with 4–6 adjustable parameters, the templates were not flexible enough to fully track the detailed evolution of well-measured flux data. Conversely, the CLs for CMAGIC fits typically were larger than expected, perhaps because published photometric errors in the CMAGIC linear region are slightly conservative. To address this issue for each type of fit, we mapped the observed CL distribution onto a uniform one while maintaining each SN's rank in the distribution. This was done by scaling all fit errors that were output for a particular SN by $(\chi_{\text{orig}}^2/\chi_{\text{unif}}^2)^{1/2}$, where χ_{orig}^2 is the original χ^2 statistic and χ_{unif}^2 is the value which allows that SN to maintain its rank in the uniform CL distribution. For the LC and CMAGIC fits, the median error-scaling factors were 1.57 and 0.78, respectively.

2.4. Extinction of $B_{\max}$ and B_{BV}

As a first step, standard corrections for the effects of Milky Way (MW) dust were applied to all of the LC and CMAGIC fit outputs that require it. This step will be discussed in §3. In this section, on the other hand, we are concerned with extinction by intervening dust outside the MW. An experimentally related issue is the effect upon SN luminosity of variation in intrinsic SN color.

If intervening dust outside the MW causes true $B-V$ to differ from raw (*i.e.* observed) $(B-V)^{\text{raw}}$ by $\delta(B-V) \equiv (B-V) - (B-V)^{\text{raw}}$, then, according to the law of Cardelli et al. (1989) (henceforth Card89), all true B magnitudes differ from raw B magnitudes by $\delta B \equiv B - B^{\text{raw}} = R_B \delta(B-V)$, where R_B is approximately constant and of size ≈ 4.1 if the dust is parametrized as is common for MW dust. For maximum-luminosity analysis, the SN color is measured here by the difference $E \equiv B_{\max}^{\text{raw}} - V_{\max}^{\text{raw}}$ between the B magnitude at $B_{\max}$ and the V magnitude at $V_{\max}$, as determined, respectively, by the nearly independent LC fits in the B and V bands. More generally, using the Card89 law to describe the effects on raw SN luminosity both of intrinsic SN color variation and of intervening dust, and, following van den Bergh (1995), denoting by $\mathcal{R}$ the color-correction coefficient parametrizing those combined effects, color-corrected $B_{\max}$ is related to color-uncorrected $B_{\max}^{\text{raw}}$ by

$$B_{\max} = B_{\max}^{\text{raw}} - \mathcal{R}E. \quad (2)$$

(Beginning in §4, we shall use the symbol $B_{\max}$ to denote the maximum B magnitude after full corrections,

which depend both on observed color and on decline rate, are applied. In the present discussion, nevertheless, for simplicity we do not include a decline-rate correction to $B_{\max}^{\text{raw}}$.)

For CMAGIC analysis, however, equation (2) does not hold: the change due to intervening dust in the CMAGIC output B_{BV} , defined as the B magnitude at fixed color $B-V$, will be smaller. Because it must continue to be measured at the same fixed color, the true value of B_{BV} should differ from the raw value B_{BV}^{raw} by only that portion of δB which is orthogonal to $\delta(B-V)$:

$$\begin{aligned}\delta B_{BV} &= \delta B - \frac{dB}{d(B-V)} \delta(B-V) \\ &= (R_B - \beta_{BV}) \delta(B-V).\end{aligned}\quad (3)$$

Again taking into account the effects both of intrinsic SN color variation and of intervening dust, the corresponding effective color-correction coefficient for B_{BV} is $\mathcal{R} - \beta_{BV}$.

In raw form, before correction for color or decline rate, B_{BV}^{raw} uses only the B and V fluxes that are measured in the CMAGIC linear region, beginning at least several days after maximum light. Nevertheless, to define that region and to measure the decline rate, in parallel one performs a light-curve fit that does also use the fluxes measured near maximum, normally in the B band. To measure and correct for the SN color, in principle a second LC fit in the V band would allow the maximum-luminosity color E to be calculated. However, to preserve greatest orthogonality to maximum-luminosity analysis, the CMAGIC method substitutes a complementary measure of SN color that is unaffected by the details and uncertainties of the V light curve near maximum. This is done by exploiting the unique linear combination

$$\mathcal{E} \equiv \frac{B_{\max}^{\text{raw}} - B_{BV}^{\text{raw}}}{\beta_{BV}} \quad (4)$$

of $B_{\max}^{\text{raw}}$ and B_{BV}^{raw} that permits $\delta\mathcal{E} = \delta(B-V)$ in the example to which equation (3) pertains. For CMAGIC analysis, $\mathcal{E}$ is not the only possible color measure, but it is a choice that has become conventional and is adopted throughout this paper.

In analogy to equation (2), the arguments following equation (3) require

$$B_{BV} = B_{BV}^{\text{raw}} - (\mathcal{R} - \beta_{BV})\mathcal{E}. \quad (5)$$

Using equation (4) to evaluate $\mathcal{E}$, equation (5) becomes

$$B_{BV} = B_{\max}^{\text{raw}} - \mathcal{R}\mathcal{E}. \quad (6)$$

Comparison of eqs. (6) and (2) emphasizes that B_{BV} and $B_{\max}$ are independent only in that they use different measures of SN color to correct $B_{\max}^{\text{raw}}$. When the CMAGIC color $\mathcal{E}$ closely tracks the maximum-luminosity color E , as is usually the case, B_{BV} and $B_{\max}$ maintain the same sensitivity to uncertainties in $\mathcal{R}$.

2.5. Covariance of $B_{\max}$ and B_{BV}

Given the close relationship between $B_{\max}$ and B_{BV} revealed by eqs. (2) and (6), it is natural to examine their mutual correlation. Using a Monte Carlo technique, Conl05 studied the covariance due to photometric error between B_{BV}^{raw} and $B_{\max}^{\text{raw}}$ after correcting these quantities only for decline-rate dependence. In that study, $B_{\max}^{\text{raw}}$ was determined by an LC fit of the type used by Perl97

and Gold01, as discussed in §2.1. A mean Pearson correlation coefficient of ≈ 0.15 was determined. Since a covariance at that level would not have had a significant effect, correlations due to photometric error between entirely uncorrected B_{BV}^{raw} and $B_{\max}^{\text{raw}}$ were not taken into account in the error propagation performed here. On the other hand, correlations due to photometric error in *corrections* to B_{BV} and $B_{\max}$ are more significant: for example, after extinction corrections, both quantities depend on $B_{\max}^{\text{raw}}$. Such correlations are included straightforwardly in our error propagation, as are correlations due to peculiar velocity and extinction by MW dust.

On a related note, it is of possible academic interest to identify the conditions, if any, that would cause corrected B_{BV} and $B_{\max}$ to become fully correlated. We find that when β_{BV} is fixed, and stretch and time-of-maximum are determined for both B and V bands by a B -template fit, the maximum-luminosity and CMAGIC methods are fully correlated if “magic templates” are used and if V observations outside the CMAGIC linear region are discarded; and if the number of B observations is minimal, or if the B points used by CMAGIC are taken from the B template fit. (“Magic templates” m_B and m_V satisfy $dm_B/d(m_B - m_V) = \beta_{BV}$ in the CMAGIC linear region.) None of these conditions are met by the analysis reported here. Appendix C demonstrates that B_{BV} and $B_{\max}$ indeed are fully correlated for a hypothetical case that does satisfy these requirements.

2.6. K Corrections

The Hubble expansion not only dilates the apparent SN evolution, but also causes its light to be bluer at rest-frame emission than at detection. To translate published photometric data from observed to standard rest-frame passbands, we employed a particular K -correction method, discussed more fully in Wang05a, that is described only briefly below.

For the actual range of redshifts $0.003 < z < 0.079$ of the SNe in our fitted sample, light detected at the peak of the V (B) passband was emitted at a rest-frame wavelength that is blueshifted by up to 35% (60%) of the wavelength interval by which the peak of the adjacent B (U) passband is separated. Nevertheless, in part because the light curve is fit nearly independently in each passband, the functional forms used by both our LC (§2.1) and CMAGIC (§2.2) fits are flexible enough to permit both types of fit to be performed to the *observed* data *before* K corrections for these wavelength shifts were applied; a posterior K correction needed to be applied only to the five fit outputs $B_{\max}^{\text{raw}}$, $V_{\max}^{\text{raw}}$, Δm_{15} , B_{BV}^{raw} , and β_{BV} . We index these outputs by k ($1 \leq k \leq 5$).

The framework for our K corrections begins with that established by Hamuy et al. (1993), who directly applied the spectrophotometric data from three library SNe to the task of K -correcting a time series of observed B and V magnitudes belonging to other SNe that lacked spectral data. At present we benefit from a library of >30 SNe for which spectroscopic as well as good photometric data are available. For the B and V bands we constructed a set of SN light curve pairs, with each pair characterized by a different raw color E_i . We then used the spectroscopic data to modify each pair so that it corresponded to each of a set of hypothetical redshifts z_j . After applying standard LC and CMAGIC fit procedures to

TABLE 1
NUMBER OF SNe PASSING CUMULATIVE CUTS THAT YIELD THE
BASE, PLOTTED, AND FITTED SAMPLES.

Condition satisfied (cumulative)	No. of SNe retained	Sample name
No. of SNe initially considered	110	...
Enough data to fit $B_{\max}$ and B_{BV}	84	...
$z < 0.1$	82	...
$\Delta m_{15} < 1.7$	77	...
$B_{\max} - V_{\max} < 0.5$	75	...
$1.5 < \beta_{BV} < 2.5$	71	...
Not peculiar (SN2002cx)	70	base
$\sqrt{\sigma^2(B_{\max}^{\text{raw}}) + 4\sigma^2(V_{\max}^{\text{raw}}) + \sigma^2(B_{BV}^{\text{raw}})} < 0.25$	61	plotted
Each SN adds $\Delta\chi^2 < 8$ to global fit	56	fitted

the entire collection of light curve pairs, we recorded the differences $\{K_k(E_i, z_j)\}$ between fit output k at $z = z_j$ and the same output at $z = 0$. For a given j and k , the corrections $\{K_k(E_i, z_j)\}$ were fit to a linear function of the E_i , with parameters μ_j^k and ψ_j^k . In turn, the $\{\mu_j^k\}$ and $\{\psi_j^k\}$ each were fit to cubic polynomial functions of the z_j . When applied to a real SN, the K correction to the k^{th} fit output was calculated by evaluating the polynomial that was fit to the $\{K_k(E_i, z_j)\}$ at that SN's raw color E and redshift z .

We found this scheme attractive because its implementation is straightforward and because the K corrections are smooth functions of z and, like B_i itself in the CMAGIC region, they are linear functions of color. Examples of results from this scheme are provided in Appendix D.

3. FITS TO PHOTOMETRIC DATA

For inclusion in this analysis, the available sample of nearby SNe was subjected to a set of standard cuts that are listed in Table 1. First, as noted in §2, enough data were needed so that both a light-curve and CMAGIC fit could be made to each SN. Primarily this meant that at least three pairs $\{B_i, V_i\}$ of magnitudes were required to have been measured in the CMAGIC linear region. These requirements eliminated one quarter of the candidates. Secondly, to avoid sensitivity to cosmological acceleration and to bound the range of redshift over which K corrections are performed (§2.6), we required $z < 0.1$. Thirdly, we consider highly subluminal and fast-declining “SN1991bg-like” SNe to be a recognizably distinct subset. If lumped together with the main sample, they would only muddy its characteristics. As this $\approx 6\%$ subset is too small to analyze separately, we simply cut it out by requiring $\Delta m_{15} < 1.7$ mag. Fourthly, a standard loose cut $E < 0.5$ mag on raw $B - V$ color eliminated only two severely reddened candidates. As noted in §2.2, the CMAGIC fit slope β_{BV} is clustered near 2 with an intrinsic scatter < 0.1 . Our fifth cut, $1.5 < \beta_{BV} < 2.5$, eliminated four SNe whose CMAGIC slopes are pathological and/or poorly measured. Finally we discarded a single candidate, SN2000cx, whose properties are widely considered to be highly atypical of SNe Ia. (Other candidates that also might be considered to be peculiar failed earlier cuts.) These standard cuts left a “base sample” of 70 SNe.

FIG. 1.— SNe per 0.025 vs. $\Sigma \equiv [\sigma^2(B_{\max}^{\text{raw}}) + 4\sigma^2(V_{\max}^{\text{raw}}) + \sigma^2(B_{BV}^{\text{raw}})]^{1/2}$. The arrow shows the position of the cut $\Sigma < 0.25$.

To the base sample we applied a “well-measured” cut which requires explanation. Normally, when several measurements of a physical quantity are combined and a proper error analysis is applied, nothing is lost by including measurements that are far less precise than those which dominate the result. One of our main interests here, however, is the intrinsic variation of absolute SN magnitudes. In the simplest picture, this is determined by subtracting the calculated variance due to photometric error from the observed total variance. If unusually poorly measured SNe are included, both variances inflate, and the precision of their difference suffers. As will be seen in §4.1, our main information on intrinsic SN variation comes from comparing the maximum-luminosity $B - V$ color E to the CMAGIC color $\mathcal{E}$. As is discussed in Appendix B, the photometric error on $\Delta E \equiv \mathcal{E} - E$ is tracked roughly by the simple quantity

$$\Sigma \equiv \sqrt{\sigma^2(B_{\max}^{\text{raw}}) + 4\sigma^2(V_{\max}^{\text{raw}}) + \sigma^2(B_{BV}^{\text{raw}})}, \quad (7)$$

where the σ 's are raw errors output by the LC and CMAGIC fit procedures described in §2.1 and §2.2. To identify a stable sample for further analysis, we chose to cut on Σ , as opposed to the precise error on ΔE , because the latter depends on fit parameters that were expected to evolve as the analysis matured. Figure 1 exhibits the distribution in Σ of the 70 SNe in the base sample. Remaining after the cut $\Sigma < 0.25$ are the 61 SNe which comprise the “plotted sample”.

For completeness, Table 1 lists a final cut that will be justified in §5.3. Unlike all cuts discussed so far, the final cut takes into account the residuals from fits that demand consistency between maximum-luminosity color E and CMAGIC color $\mathcal{E}$ (§4), and from Hubble fits to the average of $B_{\max}$ and B_{BV} (§5). It excludes as outliers five of the 61 SNe in the plotted sample, yielding a “fitted sample” of 56 SNe. These outliers are excluded from the $\Delta E = 0$ and Hubble fits, but they continue to be included in the figures, identified by open-circle symbols.

Table 2 presents the results of our LC and CMAGIC fits to the plotted sample. Tabulated are the SN name; the symbol “ $\star$ ” if the host galaxy is E, E/S0, or S0; the number of adjustable parameters in the LC fit to one band (see §2.1); the raw peak luminosities in the B and V bands; the decline rate Δm_{15} ; the raw CMAGIC luminosity B_{BV}^{raw} and slope β_{BV} ; the redshift z in the CMB frame; the excess $B - V$ color $E^{\text{MW}}(B - V)$ due to Milky Way

TABLE 2
RESULTS OF LIGHT-CURVE AND CMAGIC FITS.

SN	E or S0 host	No. of params in LC fit	$B_{\max}^{\text{raw}}$ (mag)	$V_{\max}^{\text{raw}}$ (mag)	Δm_{15} (mag)	B_{BV}^{raw} (mag)	β_{BV}	z_{cmb}	E^{MW} ($B-V$) (mag)	Ref
1990N		4	12.537(031)	12.626(011)	1.134(023)	13.831(026)	2.123(113)	0.00447	0.026	(1)
1990O		4	16.223(056)	16.248(035)	0.937(059)	17.575(021)	2.118(059)	0.03060	0.093	(2)
1990af	*	4	17.767(018)	17.728(012)	1.594(030)	18.965(052)	2.038(190)	0.04992	0.035	(2)
1991T		6	11.412(054) ^a	11.455(009)	1.183(084) ^a	12.415(082)	2.029(236)	0.00693	0.022	(3)
1991U		4	16.487(102)	16.577(053)	1.172(044)	17.646(029)	1.961(079)	0.03096	0.062	(2)
1991ag		6	14.452(060)	14.419(073)	0.896(033)	15.807(050)	1.982(116)	0.01388	0.062	(2)
1992A	*	4	12.609(018)	12.489(018)	1.349(017)	13.654(040)	2.006(133)	0.00594	0.017	(4)
1992ag		6	16.250(058)	16.152(033)	1.080(066)	17.226(135)	1.842(257)	0.02734	0.097	(2)
1992al		4	14.479(017)	14.531(014)	1.217(017)	15.923(012)	2.179(032)	0.01350	0.034	(2)
1992bc		6	15.107(039)	15.142(019)	0.750(024)	16.816(035)	2.074(116)	0.01978	0.022	(2)
1992bg		4	16.753(046)	16.770(026)	1.160(039)	18.097(031)	2.189(092)	0.03648	0.185	(2)
1992bh		4	17.614(031)	17.546(015)	0.972(078)	18.730(033)	2.112(092)	0.04530	0.022	(2)
1992bk	*	4	18.259(068)	18.214(049)	1.631(043)	19.377(028)	1.720(122)	0.05885	0.015	(2)
1992bl		4	17.409(055)	17.374(040)	1.502(045)	18.661(060)	2.276(183)	0.04223	0.011	(2)
1992bo	*	4	15.748(021)	15.754(019)	1.631(019)	16.925(027)	1.838(098)	0.01811	0.027	(2)
1992bp		4	18.258(029)	18.308(022)	1.354(031)	19.605(056)	1.721(153)	0.07858	0.069	(2)
1993B		4	18.437(062)	18.431(038)	1.321(047)	19.610(055)	1.867(194)	0.07009	0.079	(2)
1993H		4	16.709(023)	16.528(018)	1.566(026)	17.403(033)	2.039(090)	0.02507	0.060	(2)
1993O	*	4	17.615(025)	17.672(021)	1.278(027)	18.966(035)	2.149(187)	0.05293	0.053	(2)
1993ag	*	4	17.803(028)	17.722(023)	1.283(039)	18.861(049)	1.983(243)	0.05004	0.112	(2)
1994D	*	4	11.762(019) ^a	11.855(019) ^a	1.555(027) ^a	13.223(048)	2.089(125)	0.00261	0.022	(5)
1994M	*	4	16.324(034)	16.265(021)	1.409(033)	17.500(111)	1.993(454)	0.02431	0.024	(6)
1994Q	*	4	16.518(108)	16.428(060)	0.961(061)	17.599(041)	2.033(200)	0.02897	0.017	(6)
1994S		4	14.808(029)	14.807(041)	0.869(099)	16.208(026)	1.989(067)	0.01616	0.021	(6)
1994ae		4	13.117(055) ^a	12.985(032)	1.072(052) ^a	14.402(028)	2.050(122)	0.00539	0.031	(6)
1995D	*	4	13.230(016)	13.264(014)	0.977(015)	14.610(030)	2.178(117)	0.00654	0.058	(6)
1995ac		6	17.056(032) ^a	17.094(032) ^a	0.852(070) ^a	18.444(026)	2.050(127)	0.04882	0.042	(6)
1995ak		4	16.056(046)	16.056(047)	1.486(054)	17.184(038)	1.929(174)	0.02300	0.043	(6)
1995al		4	13.319(017)	13.187(018)	0.964(017)	14.318(038)	2.027(116)	0.00587	0.014	(6)
1995bd		6	15.220(016)	14.910(016)	0.776(035)	16.172(062)	2.163(093)	0.01599	0.495	(6)
1996C		4	16.617(077) ^a	16.528(041) ^a	0.940(038) ^a	17.856(040) ^a	2.182(115) ^a	0.03007	0.014	(6)
1996X	*	6	12.978(018) ^a	13.007(018) ^a	1.307(021) ^a	14.271(017)	2.037(042)	0.00800	0.069	(6, 7)
1996bl		4	16.677(029)	16.627(021)	0.851(038)	17.938(024)	1.928(068)	0.03485	0.105	(6)
1996bo		4	15.838(023)	15.515(012)	1.171(030)	16.346(021)	2.096(091)	0.01632	0.078	(6)
1996z		4	14.409(091)	13.992(098)	1.060(073)	14.901(022)	2.487(387)	0.00796	0.063	(6)
1997E	*	4	15.108(019)	15.055(013)	1.394(028)	16.233(014)	1.836(062)	0.01332	0.124	(8)
1997bp		4	13.891(026) ^a	13.761(026) ^a	1.288(109) ^a	14.651(065) ^a	1.831(121) ^a	0.00944	0.044	(8)
1997bq		4	14.442(025)	14.342(024)	1.160(020)	15.276(018)	1.994(049)	0.00960	0.024	(8)
1997br		6	13.596(028) ^a	13.418(028) ^a	1.139(034) ^a	14.026(072)	2.313(148)	0.00630	0.113	(9)
1997cw		6	15.863(067)	15.586(081)	0.997(034)	16.488(030)	1.823(083)	0.01595	0.073	(8)
1998ab		6	16.137(076) ^a	16.113(076) ^a	1.098(035) ^a	17.200(024)	2.247(106)	0.02784	0.017	(8)
1998bu		6	12.130(015)	11.774(010)	0.977(024)	12.842(039)	2.015(088)	0.00416	0.025	(10)
1998dm		4	14.761(042)	14.551(029)	0.986(032)	15.392(036)	2.146(115)	0.00556	0.044	(8)
1998ec		4	16.309(059)	16.134(056)	1.062(031)	17.088(027)	2.051(079)	0.02012	0.085	(8)
1998es		6	13.836(013)	13.760(008)	0.742(015)	15.099(031)	1.654(177)	0.00957	0.032	(8)
1999aa		6	14.741(014)	14.722(009)	0.810(019)	16.165(008)	1.801(029)	0.01525	0.040	(11)
1999aw		6	16.694(028) ^a	16.745(019) ^a	0.787(026) ^a	18.245(015)	1.736(071)	0.03924	0.032	(12)
1999dk		4	14.817(027)	14.783(014)	1.002(029)	15.880(025)	2.148(076)	0.01395	0.054	(13)
1999dq		6	14.405(016)	14.342(009)	0.953(028)	15.475(055)	2.074(106)	0.01308	0.110	(8)
1999ee		6	14.853(007)	14.566(007)	0.904(008)	15.650(014)	2.081(032)	0.01055	0.020	(14)
2000E		6	12.784(064) ^a	12.757(064) ^a	1.070(115) ^a	13.884(010)	1.752(015)	0.00422	0.364	(15)
2000ce		4	16.961(061)	16.518(030)	0.961(032)	17.152(032)	2.183(059)	0.01650	0.057	(13)
2000cf		4	17.087(059)	17.103(018)	1.316(056)	18.327(034)	2.068(111)	0.03646	0.032	(8)
2000cn		4	16.601(009)	16.399(010)	1.582(027)	17.322(036)	1.972(389)	0.02321	0.057	(8)
2000dk	*	4	15.354(027) ^a	15.330(012)	1.440(042) ^a	16.424(030)	1.971(157)	0.01645	0.070	(8)
2001V		6	14.606(064) ^a	14.546(064)	0.730(081) ^a	15.766(086)	1.858(286)	0.01604	0.020	(16)
2001ba		4	16.322(025)	16.342(014)	0.911(024)	17.761(059)	2.367(255)	0.03053	0.064	(17)
2001el		4	12.793(027) ^a	12.691(027) ^a	1.161(022) ^a	13.621(008)	2.092(028)	0.00365	0.014	(18)
2002bo		4	13.927(018)	13.591(016)	1.335(032)	14.395(067)	1.874(127)	0.00547	0.025	(19)
2002el		4	16.153(025)	16.179(020)	1.375(025)	17.381(044)	1.961(139)	0.02238	0.085	(20)
2002er		4	14.266(012)	14.108(012)	1.253(010)	15.070(037)	1.984(079)	0.00855	0.157	(21)

REFERENCES. — (1) Lira et al. (1998); (2) Hamuy et al. (1996b); (3) Altavilla et al. (2004); (4) Suntzeff (1996); (5) Richmond et al. (1995); (6) Riess et al. (1999); (7) Salvo et al. (2001); (8) Jha (2002); (9) Li et al. (1999); (10) Jha et al. (1999); (11) Krisciunas et al. (2000); (12) Ströger et al. (2002); (13) Krisciunas et al. (2001); (14) Stritzinger et al. (2002); (15) Valentini et al. (2003); (16) Vinko et al. (2003); (17) Krisciunas et al. (2004); (18) Krisciunas et al. (2003); (19) Benetti et al. (2004); (20) Wang, L. & Li, W.D. 2005, in preparation; (21) Pignata et al. (2004).

^aThe uncertainty in this quantity has been adjusted as discussed in Appendix B.

FIG. 2.— Maximum-luminosity color $E \equiv B_{\max}^{\text{raw}} - V_{\max}^{\text{raw}}$ vs. decline rate Δm_{15} calculated from our light curve fits. Closed squares (colored violet in electronic edition) show SNe from elliptical (E) and E/S0 host galaxies; open squares (colored blue in electronic edition) show SNe from S0 hosts. SNe from remaining (late-type) hosts are divided into those with normal color, shown by closed triangles (colored green in electronic edition); and those that are reddened, shown by closed circles (colored red in electronic edition). Open circles depict SNe that do not participate in the global fit.

dust in the line of sight to the SN; and the photometry references that supplied the data for our fits. All fit quantities have been K -corrected. The tabulated uncertainties were propagated from the published photometry errors; uncertainties that are flagged in Table 2’s footnote were adjusted as discussed in Appendix B. The origins of the SNe in Table 2 are diverse, but they are drawn mainly from Hamuy et al. (1996b); Riess et al. (1999); and Jha (2002). The SN fluxes that were input to our LC and CMAGIC fits were taken from the compilation used by Conl05.

All $B_{\max}^{\text{raw}}$, $V_{\max}^{\text{raw}}$, and B_{BV}^{raw} magnitudes in Table 2 have been corrected for MW dust extinction using the dust map of Schlegel et al. (1998) and the law of Card89. The corrections to $B_{\max}^{\text{raw}}$ and $V_{\max}^{\text{raw}}$ used extinction coefficients $R_B = 4.15$ and $R_V = 3.14$, respectively, while, following equation (3), the correction to B_{BV}^{raw} used a coefficient that was smaller than R_B by the value of β_{BV} measured for the particular SN being corrected. More generally, quantities appearing anywhere in this paper that require correction for the effects of MW dust, whether they are numbers or symbols in equations, should be assumed already to have been corrected for these effects. If necessary, our numerical corrections can be undone by using the values of $E^{\text{MW}}(B-V)$ found in Table 2.

To help visualize the LC fit results, Fig. 2 displays a scatter plot of maximum-luminosity color E vs. Δm_{15} . As detailed in the caption, different symbols divide the sample by host-galaxy morphology. In §7 the characteristics of the portion of Fig. 2 in which SNe are clustered at $|E| \lesssim 0.1$ are explored.

4. COMPARISONS OF $B_{\max}$ TO B_{BV}

$B_{\max}$ can be compared to the CMAGIC output B_{BV} with substantially higher precision than is achieved by subjecting either of these luminosity measures to its own Hubble fit. Primarily this is true because $B_{\max} - B_{BV}$ is immune to fluctuations in SN peculiar velocity that, in our range $z < 0.1$, are a major source of uncertainty in Hubble fits. (As well, $B_{\max} - B_{BV}$ is blind to cosmological variations in Hubble’s law.) After correction for observed SN color has been performed (as is implied throughout this paper if the $^{\text{raw}}$ notation is absent), $B_{\max} - B_{BV}$ has the additional advantage that it depends only multiplicatively upon the effective color-correction coefficient $\mathcal{R}$, a phenomenological parameter that must separately be fit. As eqs. (2) and (6) show, one may divide $B_{\max} - B_{BV}$ by $\mathcal{R}$ to obtain the difference $\Delta E \equiv \mathcal{E} - E$ between the CMAGIC color $\mathcal{E} \equiv (B_{\max}^{\text{raw}} - B_{BV}^{\text{raw}})/\beta_{BV}$ and the maximum-luminosity color $E \equiv B_{\max}^{\text{raw}} - V_{\max}^{\text{raw}}$. It is to the study of ΔE , which is completely independent of $\mathcal{R}$ as well as SN peculiar velocity, that this section is devoted. A drawback of studying ΔE is that any systematic variation it may exhibit cannot, without more information, be apportioned uniquely between $B_{\max}$ and B_{BV} .

Because the observed SN color is influenced by intrinsic SN color as well as intervening dust, and because $B_{\max}$ and B_{BV} probe epochs at which intrinsic SN color might possibly be manifested differently, in principle ΔE might vary systematically with observed color itself. After correcting ΔE for systematic dependence on SN decline rate, to which we shall return shortly, we tested this possibility by fitting ΔE to a linear function of E . The additional free parameter allowed χ^2 to diminish by only 0.1, lending no support to this possibility. Accordingly, in the rest of this paper, we make no systematic color correction to ΔE itself, and, in results that are based on eqs. (2) and (6), we draw no distinction between values of $\mathcal{R}$ used for calculating corrected $B_{\max}$ as opposed to B_{BV} .

4.1. Decline-Rate Dependence of Color Difference

Figure 3 shows the dependence upon the decline-rate parameter Δm_{15} of the color difference ΔE . Though we were aware of the gentle nonlinearity in Δm_{15} of Hubble residuals for B and V already reported by Phil99, we were unprepared for the striking appearance of Fig. 3, which has acquired the nickname “dogleg plot”. The data there are fit to a bilinear parametrization

$$0 = \Delta E - \alpha_{\Delta E}(\Delta m_{15} - 1.1) - \alpha'_{\Delta E}|\Delta m_{15} - 1.1| + \text{const}, \quad (8)$$

with a “kink” at the nominal centroid $\Delta m_{15} = 1.1$ mag. (Evidently, for fast decliners ($\Delta m_{15} > 1.1$) the decline-rate coefficient is $\alpha_{\Delta E} + \alpha'_{\Delta E}$, and for slow decliners it is $\alpha_{\Delta E} - \alpha'_{\Delta E}$.) If only photometric errors on ΔE are taken into account, χ^2 is unacceptably large (99.5 for 53 degrees of freedom (dof)). Adding in quadrature to the photometric errors a modest rms noise (*i.e.* intrinsic scatter) term $n_{\Delta E} = 0.029$ mag reduces χ^2 to its most probable value of 51, where its probability density is larger by the factor $\exp(7.2)$. The same likelihood ratio would be associated with a gaussian fluctuation of $\sqrt{14.4} = 3.8$ standard deviations (3.8σ). Therefore, in the difference between CMAGIC and maximum-luminosity

FIG. 3.— Decline rate Δm_{15} (mag) vs. the difference ΔE (mag) between CMAGIC and maximum-luminosity colors. In this plot the abscissa is uncorrected for decline-rate dependence. The fit line is the function in equation (8). SNe marked by open circles are omitted from the fit.

$B-V$ color, intrinsic noise clearly is present at a modest level (0.029 ± 0.007 mag).

Only after noise is added to bring $\chi^2/\text{dof} \rightarrow 1$ as $\text{dof} \rightarrow \infty$ can the errors on the fit parameters be trusted. These parameters and their errors are shown in the upper portion of Table 3. Various alternate conditions for the fit are exhibited in the lower portion of the same table, together with the corresponding $\Delta\chi^2$ penalty that is assessed when each condition is enforced. The ΔE data definitely reject the hypothesis of no Δm_{15} dependence at all ($\Delta\chi^2 = 86.1$ for 2 dof). Fitting the data to the bilinear parametrization from equation (8), both a nonzero linear coefficient $\alpha_{\Delta E}$ (7.5σ) and a nonzero kink coefficient $\alpha'_{\Delta E}$ (5.8σ) are required. Therefore, in ΔE the presence of a nonlinear decline-rate dependence is firmly established.

Especially because the bilinear parametrization is non-standard, it is natural to explore alternatives. Obviously, the first derivative with respect to Δm_{15} of any parametrization ideally should be continuous. For the bilinear case this could be accomplished by substituting a small curved segment for the corner at $\Delta m_{15} = 1.1$. Here we omit this feature because the data near the corner are too sparse to determine the curvature there. The most common nonlinear form is a quadratic. As recorded in the final row of Table 3, a $\Delta\chi^2$ penalty of +7.5 is paid for substituting a quadratic function of Δm_{15} for the bilinear form. Statistically, with respect to the bilinear

TABLE 3
RESULTS OF BILINEAR FIT TO DATA IN
FIG. 3.

Result of ΔE fit	Fit value
$n_{\Delta E}$	0.029 ± 0.007
$\alpha_{\Delta E}$	0.23 ± 0.03
$\alpha'_{\Delta E}$	-0.30 ± 0.05
χ^2 / dof	51.0 / 53
Fit conditions ^a	$\Delta\chi^2$
default (as above)	0
$n_{\Delta E} = 0$	+48.5
$\alpha_{\Delta E} = 0$	+57.1
$\alpha'_{\Delta E} = 0$	+33.6
$\alpha_{\Delta E} = \alpha'_{\Delta E} = 0$	+86.1
quadratic (not bilinear)	+7.5

^aOther parameters are allowed to vary.

form, this sets the betting odds against the quadratic at 43:1. Another factor weighing against a quadratic parametrization is its asymptotic behavior: the data in Fig. 3 do not appear to prefer a steeper slope in Δm_{15} as the extremes in that parameter are approached. For all further analysis in this paper we continue to parametrize the Δm_{15} dependence by a bilinear function like that in equation (8).

With intrinsic noise and nonlinear decline-rate dependence established as basic features of $B_{\text{max}} - B_{BV}$ by the results in Fig. 3 and Table 3, the key issue not yet addressed is raised: how is responsibility for these features apportioned between B_{max} and B_{BV} ? This statistically challenging issue must be attacked using Hubble fits, to which we now turn.

5. HUBBLE FIT TO AVERAGE OF B_{MAX} AND B_{BV}

With a relatively precise fit to the difference of B_{max} and B_{BV} now in hand, we choose as the input to our primary Hubble fit the orthogonal linear combination of these two magnitudes, *i.e.* their unweighted average $\langle B \rangle$. As will be demonstrated in §5.3, the sum of χ^2 for both of these fits is equivalent to the χ^2 for a global fit to all of the B_{max} and B_{BV} data. Although this is the simplest and most straightforward type of global fit, it is not the only possible approach: for example, one could set aside the fit to $B_{\text{max}} - B_{BV}$ and substitute simultaneous Hubble fits to B_{max} and B_{BV} . That approach would have required taking careful account of the $\{B_{\text{max}}, B_{BV}\}$ covariance matrix for each SN, including the large off-diagonal term due to peculiar velocity. Using that approach, the striking decline-rate dependence shown in Fig. 3 could have been reproduced, but the data supporting it would have been buried in the details of those matrices.

All Hubble fits performed in this paper assume a flat universe with the ratio Ω_M of mass to critical densities set at 0.3. Over the range in redshift of the SNe we consider, $z < 0.1$, the results of these fits are insensitive to variations in Ω_M and Ω_Λ that reasonably would be allowed by current world data. Also, for every Hubble fit that is reported here, as well as for every fit to $\Delta E = 0$, a constant overall magnitude offset is included that always is allowed to assume its own best fit value, independent of the offset determined by any other fit. (For Hubble fits, this offset is essentially the absolute SN

magnitude combined with the Hubble constant.) The best fit values of these offsets are left unreported in this paper since they are irrelevant to its goals. Because only linear color corrections are used here, any constant offset in color plays the same role as a constant overall offset and therefore leaves unaffected any fit results that we report. Accordingly this paper does not distinguish between a color $B-V$ and its excess with respect to an expected color.

Apart from the assumptions implicit in using particular B and V light-curve templates, and in exploiting the observed linear relationship between B magnitude and $B-V$ color in the CMAGIC region, all analysis in this paper makes no prior assumption. Specifically, because the effects of extinction by host-galactic dust and of intrinsic SN color variation are not yet well characterized, we accept and use the observed $B-V$ color without applying to it any correction based *e.g.* on a Bayesian prior. The statistical error analysis applied here is frequentist: in a multiparameter fit, when a single parameter is varied and the change in likelihood is recorded, all other parameters (including the offset) are allowed also to vary for best compatibility with that excursion. (If instead we had chosen to integrate over a likelihood surface, implicitly we would have had to apply a Bayesian prior.) Thus our calculated errors are never assumed to be symmetric; when an average error is reported, the calculated errors lie within $\pm 5\%$ of it.

5.1. Correcting $\langle B \rangle$ for Color and Decline Rate

Because $\Delta B \equiv B_{\max} - B_{BV}$ is proportional to ΔE (eqs. (2) and (6)), the bilinear dependence of ΔE upon Δm_{15} should map into a bilinear Δm_{15} -dependent correction to $B_{\max}$, B_{BV} , or both. The Hubble fit described here allows for both. Allowing for corrections for both color and decline-rate dependence, the more general form of eqs. (2) and (6) becomes

$$B_{\max} = B_{\max}^{\text{raw}} - \mathcal{R}E - \mathcal{D}(\Delta m_{15}; \alpha_{\max}, \alpha'_{\max}) \quad (9)$$

$$B_{BV} = B_{BV}^{\text{raw}} - \mathcal{R}\mathcal{E} - \mathcal{D}(\Delta m_{15}; \alpha_{BV}, \alpha'_{BV}), \quad (10)$$

where the function $\mathcal{D}(\Delta m_{15}; \alpha, \alpha')$ is shorthand for the bilinear decline-rate dependence introduced in equation (8):

$$\mathcal{D}(\Delta m_{15}; \alpha, \alpha') \equiv \alpha(\Delta m_{15} - 1.1) + \alpha'|\Delta m_{15} - 1.1|. \quad (11)$$

Apart from the “kink” term in $\alpha'_{\max}$, the corrections described by equation (9) are equivalent to those introduced by Tripp (1998). The coefficients α_{BV} and α'_{BV} for B_{BV} are not the same as the coefficients $\alpha_{\max}$ and $\alpha'_{\max}$ for $B_{\max}$; rather, the two pairs of coefficients are linked by the decline-rate corrections to $\Delta E \equiv \mathcal{E} - E$ given by equation (8). Straightforwardly, the average $\langle B \rangle$ of $B_{\max}$ and B_{BV} is corrected for color and decline rate by a similar relation:

$$\langle B \rangle = B_{\max}^{\text{raw}} - \mathcal{R}\langle E \rangle - \mathcal{D}(\Delta m_{15}; \alpha_{\langle B \rangle}, \alpha'_{\langle B \rangle}), \quad (12)$$

where $\langle E \rangle \equiv (E + \mathcal{E})/2$ and the decline-rate coefficients $\alpha_{\langle B \rangle}$ and $\alpha'_{\langle B \rangle}$ are equal to the average of those for $B_{\max}$ and B_{BV} . Table 4 provides a full list of the bilinear decline-rate coefficients and their interrelationships. There, in terms of the color coefficient $\mathcal{R}$ and of the decline-rate coefficients for correcting ΔE and $B_{\max}$, the last column supplies the decline-rate coefficients used to correct ΔB , $\langle B \rangle$, and B_{BV} .

TABLE 4
DEFINITIONS OF BILINEAR DECLINE-RATE CORRECTION COEFFICIENTS USED IN THE FIT TO $\Delta E = 0$; USED FOR CORRECTING ΔB ; AND USED IN HUBBLE FITS TO $B_{\max} = \mu$, $\langle B \rangle = \mu$, AND $B_{BV} = \mu$.

Coef- ficient	Multiplying	To correct	Is equivalent to
$\alpha_{\Delta E}$	$(\Delta m_{15} - 1.1)$	ΔE	$\dots$
$\alpha'_{\Delta E}$	$ \Delta m_{15} - 1.1 $	ΔE	$\dots$
$\alpha_{\Delta B}$	$(\Delta m_{15} - 1.1)$	ΔB	$\mathcal{R}\alpha_{\Delta E}$
$\alpha'_{\Delta B}$	$ \Delta m_{15} - 1.1 $	ΔB	$\mathcal{R}\alpha'_{\Delta E}$
$\alpha_{\max}$	$(\Delta m_{15} - 1.1)$	$B_{\max}$	$\dots$
$\alpha'_{\max}$	$ \Delta m_{15} - 1.1 $	$B_{\max}$	$\dots$
$\alpha_{\langle B \rangle}$	$(\Delta m_{15} - 1.1)$	$\langle B \rangle$	$\alpha_{\max} - \frac{\mathcal{R}}{2}\alpha_{\Delta E}$
$\alpha'_{\langle B \rangle}$	$ \Delta m_{15} - 1.1 $	$\langle B \rangle$	$\alpha'_{\max} - \frac{\mathcal{R}}{2}\alpha'_{\Delta E}$
α_{BV}	$(\Delta m_{15} - 1.1)$	B_{BV}	$\alpha_{\max} - \mathcal{R}\alpha_{\Delta E}$
α'_{BV}	$ \Delta m_{15} - 1.1 $	B_{BV}	$\alpha'_{\max} - \mathcal{R}\alpha'_{\Delta E}$

For completeness, this section concludes with a brief discussion of the “effective color” E^{eff} that multiplies the color-correction coefficient $\mathcal{R}$ in eqs. (10) and (12). This detail will be relevant only for visualizing the quality of the fit that determines $\mathcal{R}$. In eqs. (9), (10), and (12), the coefficients $\mathcal{R}$ are all the same, but they multiply colors – E , $\mathcal{E}$, and $\langle E \rangle$ – that obviously are different. Less obvious is the fact that the right-hand term in each of eqs. (10) and (12) itself is a linear function of $\mathcal{R}$, through the dependence of $\alpha_{BV}^{(r)}$ and $\alpha_{\langle B \rangle}^{(r)}$ upon $\mathcal{R}$ that is shown in the last four rows of Table 4. Using the information tabulated there to reexpress $\alpha_{BV}^{(r)}$ and $\alpha_{\langle B \rangle}^{(r)}$ in terms of $\alpha_{\max}^{(r)}$ and $\alpha_{\Delta E}^{(r)}$, and collecting into E^{eff} the sum of the coefficients of $\mathcal{R}$ in equation (10) and in equation (12), one obtains the effective colors

$$B_{BV} : E_{BV}^{\text{eff}} = \mathcal{E} - \mathcal{D}(\Delta m_{15}; \alpha_{\Delta E}, \alpha'_{\Delta E}) \quad (13)$$

$$\langle B \rangle : E_{\langle B \rangle}^{\text{eff}} = \langle E \rangle - \mathcal{D}(\Delta m_{15}; \frac{1}{2}\alpha_{\Delta E}, \frac{1}{2}\alpha'_{\Delta E}). \quad (14)$$

When it is uncorrected for color, the Hubble residual *e.g.* of $\langle B \rangle$ should exhibit a linear dependence on $E_{\langle B \rangle}^{\text{eff}}$ with slope $\mathcal{R}$.

5.2. Propagating Intrinsic Noise into $\langle B \rangle$

Leaving aside sources of noise that are common to both $B_{\max}$ and B_{BV} , and introducing a mild assumption that is discussed fully in Appendix E, the rms intrinsic noise $n_{\Delta B}$ that is measured in the comparison of $B_{\max}$ to B_{BV} propagates into $\langle B \rangle$ as $n_{\langle B \rangle} = n_{\Delta B}/2$. Therefore, using the factor $\mathcal{R}$ to relate the intrinsic noise in ΔB to that in ΔE , the added rms intrinsic noise $n_{\Delta E} = 0.029 \pm 0.007$ mag that was required by the fit to $\Delta E = 0$ (Table 3) propagates into an added rms intrinsic noise term $n_{\langle B \rangle} = \mathcal{R}n_{\Delta E}/2$ in the average $\langle B \rangle$ of $B_{\max}$ and B_{BV} .

As is also discussed in Appendix E, intrinsic noise that is common to both $B_{\max}$ and B_{BV} may be present, together with common-mode noise from the effects of peculiar velocity along the line of sight. In principle, measuring the redshift dependence of the common-mode noise would allow the effects of peculiar velocity to be resolved from those of other sources. However, the SN sample statistics available to us do not permit a clean separation. Instead we resort to parametrizing the sum of all sources of common-mode noise as the manifestation of a

FIG. 4.— Pull ($\equiv$ residual/error) from Hubble fit to $\langle B \rangle$ vs. pull from fit to $\Delta E = 0$. SNe that lie within the circle (filled points) contribute $\Delta\chi^2 < 8$ to the global χ^2 and are included in the fits.

single effective rms SN velocity v_{eff} relative to the Hubble flow. In §5.6 we report the value of v_{eff} determined from the data, from which we deduce an upper limit on the true rms peculiar velocity.

5.3. Equivalent Global Fit and Fitted Sample

Figure 4 shows for each SN the pull (defined as the residual divided by the error on that residual) for the Hubble fit to $\langle B \rangle$ vs. the pull for the fit to $\Delta E = 0$ described in §4.1. The insignificant correlation between the two pulls, measured by the Pearson correlation coefficient $|R| < 0.05$, confirms that, as expected, the two fits are orthogonal. Therefore the sum of χ^2 for both fits is equivalent to the χ^2 for a global fit to the parameters $\alpha_{\Delta E}$, $\alpha'_{\Delta E}$, $\alpha_{\langle B \rangle}$, $\alpha'_{\langle B \rangle}$, and $\mathcal{R}$ (plus offsets). Note that the decline rate parameters for B_{max} and B_{BV} are also fully specified by the global fit (Table 4). One SN contributes two degrees of freedom to the global fit: one dof for the Hubble fit to $\langle B \rangle$ and one dof for the fit to $\Delta E = 0$. Its contribution to the global χ^2 is equal to the sum of the squares of the same pulls exhibited for that SN in Fig. 4.

If it lies outside the circle of radius $\sqrt{8}$ displayed in Fig. 4, one SN contributes to the global χ^2 an increment $\Delta\chi^2 > 8$ for 2 dof. If the pulls were distributed according to gaussian statistics, for our sample size an average of one SN would be expected to lie outside this circle. In fact five SNe lie outside: four mainly because of a large $|\text{pull}|$ in the Hubble fit, and one primarily because of a large $|\text{pull}|$ in the fit to $\Delta E = 0$. As previously noted in §3, we exclude from fits all five of these SNe, leaving a fitted sample of 56 SNe. Using open-circle symbols we continue to exhibit these outliers in plots.

5.4. Decline-Rate Correction to Hubble Fit for $\langle B \rangle$

In Fig. 5 the decline rate Δm_{15} is plotted vs. the Hubble residual for $\langle B \rangle$. In this plot $\langle B \rangle$ is fully corrected

FIG. 5.— Decline rate Δm_{15} vs. Hubble residual $(\langle B \rangle - \mu)$, which here is uncorrected for its dependence on Δm_{15} . The line is a bilinear function of Δm_{15} from the global fit, from which SNe marked by open circles are omitted.

for the effects of color, as will be discussed in §5.5, but it is left uncorrected for decline rate. The line is the correction determined by the global fit and described by equation (12). The best-fit kink at $\Delta m_{15} = 1.1$ is less pronounced than that observed for ΔE (Fig. 3). Because the decline-rate dependence is much smoother for the sum of B_{max} and B_{BV} than for their difference, the kink in decline-rate dependence should (and does) appear with opposite sign in the Hubble residuals for B_{max} and B_{BV} ; this point will be discussed further in §6.1. In Table 5, the top two rows list the globally fit coefficients of Δm_{15} and $|\Delta m_{15}|$ that correct the Hubble residuals of $\langle B \rangle$ via equation (12); these parameters determine the line in Fig. 5.

5.5. Color Correction to Hubble Fit for $\langle B \rangle$

Figure 6 exhibits the color correction to $\langle B \rangle$. On the ordinate is plotted the effective color $E_{\langle B \rangle}^{\text{eff}}$ from equation (14); this is the coefficient of $\mathcal{R}$ in equation (12). As in Fig. 5, the horizontal coordinate is the Hubble residual for $\langle B \rangle$; however, in this plot $\langle B \rangle$ is fully corrected for the effects of decline rate, but it is left uncorrected for color. Again, the line is determined by the global fit; in this case the correction is purely linear, with best fit slope $\mathcal{R} = 2.59 \pm 0.24$. This result is inconsistent either with a null correction or with a coefficient typical of Milky Way dust: for the alternate values $\mathcal{R} = 0$ or $\mathcal{R} = 4.1$, respectively, χ^2 increases by >115 or >32 .

When the color is measured with less than perfect

TABLE 5
BILINEAR DECLINE-RATE CORRECTION
COEFFICIENTS FOR $\langle B \rangle$, $B_{\max}$, AND
 B_{BV} FROM THE GLOBAL FIT.

Result of global fit	Fit value
$\alpha_{\langle B \rangle}$	0.48 ± 0.09
$\alpha'_{\langle B \rangle}$	-0.14 ± 0.18
$\alpha_{\max}$	0.78 ± 0.09
$\alpha'_{\max}$	-0.54 ± 0.19
α_{BV}	0.18 ± 0.12
α'_{BV}	0.25 ± 0.21
$\alpha_{\max} - \alpha_{BV}$	0.60 ± 0.09
$\alpha'_{\max} - \alpha'_{BV}$	-0.79 ± 0.16
Fit conditions ^a	$\Delta\chi^2$
default (as above)	0
$\alpha'_{\max} = 0$	+7.2
$\alpha_{\max} + \alpha'_{\max} = 0$	+2.3
$\alpha_{BV} = \alpha'_{BV} = 0$	+9.2
$\alpha_{\max} - \alpha_{BV} = 0^b$	+57.1
$\alpha'_{\max} - \alpha'_{BV} = 0^b$	+33.6

^aOther parameters are allowed to vary.

^bFrom Table 3.

FIG. 6.— Effective color $E_{\langle B \rangle}^{\text{eff}}$ ($\equiv$ coefficient of $\mathcal{R}$, defined in equation (14)) *vs.* residual from Hubble fit to $\langle B \rangle$ when the latter is left uncorrected by terms that are proportional to $\mathcal{R}$. The line is a linear function of the ordinate determined by the global fit, from which SNe marked by open circles are omitted.

precision, the slope $\mathcal{R}$ will be underestimated. In this analysis, the effects of finite color resolution were unfolded by two different methods described in Appendix F. These methods yielded corrections to $\mathcal{R}$ of +3.8% and +7.0%, respectively. For comparison to other determinations of $\mathcal{R}$, which are likely to involve color resolutions similar to ours, we prefer to quote the uncorrected value $\mathcal{R} = 2.59 \pm 0.24$. On the other hand, if our value of $\mathcal{R}$ is to be compared to other determinations for which the effects of color resolution already have been unfolded, we estimate our own correction for those effects to be given by the average of our two methods: $\Delta\mathcal{R}/\mathcal{R} = +0.054 \pm 0.027$, where a 50% systematic error is assigned to the correction.

As an essential check, we have used the results of pseudoexperiments based on two independent Monte Carlo simulations to study the distributions both of pulls and residuals in $\mathcal{R}$ and other fit parameters. In these pseudoexperiments, minimizing global χ^2 to obtain $\mathcal{R}_{\text{fit}}$ does reproduce on average the color-correction coefficient $\mathcal{R}_{\text{true}}$ that was input to the simulation; measuring the variation of χ^2 with $\mathcal{R}_{\text{fit}}$ does predict the dispersion of $\mathcal{R}_{\text{fit}} - \mathcal{R}_{\text{true}}$ that is measured. As is conventional, our global fit minimizes $\chi^2 = \delta^\dagger \mathcal{H} \delta$, where δ is a vector of differences and $\mathcal{H}$ is the information (inverse covariance) matrix. This minimization problem belongs to the class in which both δ and $\mathcal{H}$ depend on the fit parameters; the latter dependence occurs because the uncertainties in Hubble residuals grow *e.g.* as $\mathcal{R}$ increases. For these Monte Carlo checks to be satisfied, we found it essential to allow $\mathcal{H}$ to vary continuously as the fit parameters were being optimized.

We also tested an iterative stepwise fitting technique in which χ^2 was minimized with $\mathcal{H}$ held fixed, then $\mathcal{H}$ was recalculated using the newly updated parameters, *etc.*, until the iteration converged. This caused our Monte Carlo checks to fail badly. If applied to the real SN sample analyzed here, the stepwise technique would yield a value of $\mathcal{R}$ that is 10.2% below that obtained with the validated fitting procedure. Also, the measures of Hubble-line deviation to be discussed in §6.3 would be marginally reduced (by $\approx 3\%$). This is understandable: slightly undercorrecting *e.g.* for color variation can marginally improve the Hubble dispersion if the uncertainty associated with that correction can be reduced. Nevertheless, all results presented in this paper are based on the Monte Carlo-validated fitting technique described in the previous paragraph, even at the expense of marginally larger Hubble dispersions. We made this choice not only because the color- and decline-rate correction coefficients are physical properties of the SNe that we wish to report accurately, but also because in future campaigns, as the photometric errors *e.g.* in color become relatively less important, the correction coefficients which minimize the Hubble dispersion will approach their true values.

5.6. Upper Limit on Peculiar Velocity

As described in §5.2, a single effective rms SN velocity v_{eff} is used to parametrize the effects both of peculiar velocity v_{pec} along the line of sight relative to the Hubble flow, and of any other non-photometric noise component that is common to $B_{\max}$ and B_{BV} . In the Hubble fit for $\langle B \rangle$, v_{eff} is adjusted to maximize the probability density of χ^2 , yielding the best fit value $v_{\text{eff}} = 382^{+60}_{-52} \text{ km s}^{-1}$. As

FIG. 7.— Decline rate Δm_{15} vs. Hubble residual $(B_{\max} - \mu)$, which here is uncorrected for its dependence on Δm_{15} . The line is the bilinear function of Δm_{15} from the global fit, from which SNe marked by open circles are omitted.

noted in §5.2, measuring v_{eff} yields an upper bound on SN peculiar velocity. The corresponding 95% confidence upper limit is $v_{\text{pec}} < 486 \text{ km s}^{-1}$.

In the literature, estimates are available for the peculiar velocities of individual SNe in the Local Group; applying corrections based on those estimates would improve significantly our Hubble fits. However, our aim here is to use local SNe to characterize the peculiar velocities of distant SNe, for which such estimates generally are unavailable. Therefore the results quoted above for v_{eff} and v_{pec} intentionally were left uncorrected for the estimated velocities, relative to the Hubble flow, of local SNe.

6. RESULTS FOR B_{MAX} AND B_{BV}

As emphasized in §5.3, the fit to $\Delta E = 0$ and the Hubble fit to $\langle B \rangle$ together comprise a global fit that fully determines the decline-rate and color corrections to be applied to B_{max} and B_{BV} as well as to $\langle B \rangle$ and ΔE . In principle, no separate Hubble fits to B_{max} or B_{BV} are required. Figure 7 plots the decline rate Δm_{15} vs. the Hubble residual for B_{max} . The corresponding decline-rate coefficients for B_{max} (and also for B_{BV}) are supplied in Table 5. There the symbols α and α' refer, respectively, to coefficients of $(\Delta m_{15} - 1.1)$ and $|\Delta m_{15} - 1.1|$; they are fully defined in Table 4. For alternate fits in which one or more decline-rate coefficients or combinations thereof are forced to vanish, the lower part of Table 5 exhibits the corresponding $\Delta\chi^2$ penalty.

As a check, independent Hubble fits to each of B_{max} and B_{BV} were performed, allowing $\mathcal{R}$ and both bilinear decline-rate coefficients to seek optimum values independent of the global fit. Relative to values of χ^2 obtained for Hubble fits to B_{max} and B_{BV} using parameters determined by the global fit, values of χ^2 for these independent fits were smaller by less than 0.8 and 2.5, respectively. This confirms that the global fit is a reasonable description of both B_{max} and B_{BV} .

6.1. Decline-Rate Corrections to B_{max} and B_{BV}

As a guide to the variety of numerical results from the global fit that are included in Table 5, first we highlight those features which are firmly established by the data. In particular, the results exhibited in rows 7 and 8 of Table 5, derived from results of the fit to $\Delta E = 0$ summarized in Table 3, emphasize that B_{max} and B_{BV} cannot share the same decline-rate coefficients. Because a kink in decline-rate correction at $\Delta m_{15} = 1.1$ is a feature of Type Ia SNe that may not be familiar to every reader, here we focus particularly on the coefficients α' of $|\Delta m_{15} - 1.1|$. Because the tabulated values of α'_{max} and α'_{BV} are nonzero, respectively, only by 2.7 and 1.2 standard deviations, a reader might imagine that the data marginally would allow both to vanish. However, because the difference between those coefficients is nonzero at the 5.8σ level, at least one of B_{max} and B_{BV} must be described by a nonzero kink. Other firmly established features include the need for a conventional decline-rate-correction term that is linear in Δm_{15} for both $\langle B \rangle$ and B_{max} (rows 1 and 3 of the table).

Conversely, the data may allow certain coefficients in Table 5, or combinations thereof, to vanish. As one example, the result for $\alpha'_{\langle B \rangle}$ found in the second row of the table allows the decline-rate correction to $\langle B \rangle$ to be purely linear; that would correspond to the case in which the fit line in Fig. 5 is straight. As a second example, fast-declining SNe (with $\Delta m_{15} > 1.1$) are corrected by a coefficient of $(\Delta m_{15} - 1.1)$ that is equal to $\alpha + \alpha'$. As shown for corrections to B_{max} in the fourth-from-last row of Table 5, $\alpha_{\text{max}} + \alpha'_{\text{max}}$ is only 1.5 standard deviations from zero. Therefore the data do not conclusively reject the proposition that fast-declining SNe require no decline-rate correction whatsoever to B_{max} ; that would correspond to the case in which the top part of the “dog-leg” line in Fig. 7 is exactly vertical.

Regarding the CMAGIC luminosity B_{BV} , the third-from-last row of Table 5 examines the proposition that B_{BV} requires no decline-rate correction for any SN: when two dof are removed by nulling both α_{BV} and α'_{BV} , χ^2 grows by 9.2 (confidence level 0.01). Evidently the data disfavor this proposition. More restrictively, slow-declining SNe (with $\Delta m_{15} < 1.1$) are corrected by a $(\Delta m_{15} - 1.1)$ coefficient equal to $\alpha - \alpha'$; the results in rows 5 and 6 of Table 5 clearly permit $\alpha_{\text{BV}} - \alpha'_{\text{BV}}$ to vanish. Therefore the data do allow slow-declining SNe to remain uncorrected for decline rate if analyzed using the CMAGIC method. For color as well, some of these SNe might acceptably remain uncorrected: “bluish” SNe (with $B - V$ color $\mathcal{E} \lesssim 0.1$) have a color correction to B_{BV} that is no greater than $(\mathcal{R} - \beta_{\text{BV}})\mathcal{E} \approx (2.6 - 2)(0.1) \approx 0.06$ magnitudes.

TABLE 6
CONSEQUENCES OF ALLOCATING THE INTRINSIC NOISE IN ΔE
ALL TO B_{BV} , ALL TO $B_{\max}$, OR EQUALLY TO BOTH.

Quantity	Noise allocation		
...	all to B_{BV}	equal	all to $B_{\max}$
Conditions and Hubble fit results:			
Noise in $B_{\max}$ (mag)	0	0.052	0.074 ^a
Noise in B_{BV} (mag)	0.074 ^a	0.052	0
χ^2 ($B_{\max}$ residuals)	43.2	39.3	36.5
χ^2 (B_{BV} residuals)	57.8	66.1	80.2
Relative likelihood	1	1/3.3	1/44

^aFor $(B_{\max} - B_{BV})$ the fit noise is 0.074 ± 0.019 mag.

6.2. Allocating Intrinsic Noise to $B_{\max}$ or B_{BV}

As explained in §5.2, the intrinsic noise term $n_{\Delta E}$ that is required by the fit to $\Delta E = 0$ propagates into a noise term $n_{\langle B \rangle} = \mathcal{R}n_{\Delta E}/2$ in the Hubble fit for $\langle B \rangle$. Table 6 presents the χ^2 for the Hubble fit to $B_{\max}$, the χ^2 for the Hubble fit to B_{BV} , and the relative likelihood (proportional to the product of the two χ^2 densities) for three scenarios: (a) all of $n_{\langle B \rangle}$ is allocated to B_{BV} ; (b) $1/\sqrt{2}$ of $n_{\langle B \rangle}$ is allocated to B_{BV} and $1/\sqrt{2}$ to $B_{\max}$; (c) all of $n_{\langle B \rangle}$ is allocated to $B_{\max}$. All of the fits that contribute to the table use the parameters of the global fit. Scenario (a) is favored, so it is the basis for the global fit results that are presented in this paper. Scenarios (b) and (c) are progressively less likely, by factors of 3.3 and 44, respectively; evidently scenario (b) is not strongly disfavored relative to (a). Although the data do not conclusively reject scenario (c), it is unlikely that all of the noise in the difference between $B_{\max}$ and B_{BV} is due to noise that is confined to $B_{\max}$.

6.3. Quantifying Deviations about the Hubble Line

From the distribution of a property m of any statistically limited sample, estimating the variance of the measured variance in m of that sample requires no assumption about the shape of the true m distribution. In part for that reason, the unweighted rms Hubble residual σ (the square root of the variance) is a useful standard measure of SN uniformity. A drawback of the rms is that, if included in the sample, SNe with unusually large uncertainties in m can dominate this measure, pushing the rms upward. This shortcoming may be addressed by use of the weighted rms (wrms), denoted by σ_w . The square of σ_w is the mean square deviation of m from the function to which it is fit, weighted by the inverse square uncertainty assigned to m for each SN. (Equations defining both σ and σ_w are provided in Appendix A.) These definitions take proper account of the reduction in dof due to the number of variable parameters in the fit function.

While it is invariant to the overall scale of the uncertainties assigned to m , the wrms is fragile if the individual uncertainties are assigned inaccurately. As a pathological example, if 100 identical SNe are observed with identical methods, and if the uncertainty in m of the first SN erroneously is set to 1% of the value assigned to the rest, the wrms underestimates the true rms typically by a factor of $\gtrsim 7$.

TABLE 7
WEIGHTED RMS DEVIATION, RMS DEVIATION, AND CORE DEVIATION (MAG) FROM THE HUBBLE LINE OVER THE RANGE $0.015 < z < 0.1$ FOR $\langle B \rangle$, $B_{\max}$, AND B_{BV} USING THE GLOBAL FIT AND FOR B_{BV} USING A B_{BV} -ONLY FIT.

Hubble deviation of	Type of fit	Weighted rms	rms	$1.483 \times$ median residual
$\langle B \rangle$	global	0.129	0.152 ± 0.018	0.116
$B_{\max}$	global	0.130	0.152 ± 0.015	0.144
B_{BV}	global	0.155	0.176 ± 0.018	0.158
B_{BV}	B_{BV} only	0.132	0.144 ± 0.015	0.120

Both the rms and the wrms are highly sensitive to the presence or absence of a few SNe far out on the tails of the distribution. This sensitivity is addressed here by introducing as a third measure of SN uniformity the median absolute residual $\text{med}(|m_i - \mu(z_i)|)$, or “core deviation”. We scale this quantity by the factor 1.483 so that it is equivalent to the rms for a pure gaussian distribution in the limit $N/N_{\text{dof}} \rightarrow 1$.

6.4. Hubble-line Deviations of $\langle B \rangle$, $B_{\max}$, and B_{BV} .

The first three rows of Table 7 list the wrms, rms, and core deviations from the Hubble line for $\langle B \rangle$, $B_{\max}$, and B_{BV} , using the single set of correction coefficients obtained from the global fit. To suppress the effects of peculiar velocity, only SNe with $z > 0.015$ are included in these averages (Fig. 8 exhibits the sample’s z distribution). We estimate the uncertainties in values of the weighted rms and core deviation to be similar to the relatively well-defined uncertainties in the values of the rms that appear in the table. That these uncertainties are as large as their estimates is emphasized by the final row of Table 7, which shows the result of substituting for the output of the global fit the output of a Hubble fit that was made only to B_{BV} . Residuals from the B_{BV} -only fit are shown in Fig. 8. In this fit, after adding 0.053 mag of noise in quadrature to the photometric errors in B_{BV} , we rejected as outliers five SNe chosen to minimize χ^2 for the B_{BV} -only fit rather than for the global fit. The resulting χ^2 probability density was maximal. Two SNe that had been excluded from the global fit, SN1992bp and SN1994ae (Fig. 4), were replaced as outliers by SN1995ac and SN2001V. As is apparent, substituting the B_{BV} -only for the global fit perturbed the Hubble-line deviations for B_{BV} by amounts comparable to other differences found in the table. Weighing all of the information in Table 7, it is evident that, with the available statistics, the Hubble-line deviations for all three measures of SN luminosity – $\langle B \rangle$, $B_{\max}$, and B_{BV} – are comparable and of order ≈ 0.14 mag, and are not easily distinguished from each other. Note that these deviations arise from the effects of photometric error and peculiar velocity as well as intrinsic noise.

7. CHARACTERISTICS OF THE BLUE RIDGE

SNe that are considered to be part of the “blue ridge” are grouped in a region roughly defined as $|B_{\max} - V_{\max}| \lesssim 0.1$; the word “ridge” refers to the contour of this group on a plot of color *vs.* decline rate, as in Fig. 2. SNe in the blue ridge are thought largely to be free of extinction due to host-galactic dust (Hatano et al. 1998;

FIG. 8.— $\log_{10}(\text{redshift } z)$ vs. CMAGIC Hubble residual ($B_{BV} - \mu$). The points are residuals from the B_{BV} -only fit. Five SNe excluded as outliers are suppressed. The curve shows the $\pm 1\sigma$ uncertainty in residual associated with the assumed rms line-of-sight peculiar velocity of 400 km/s relative to the Hubble flow. Accounting for the dof removed by the corrections, the unweighted rms deviation from the fit (straight line) of the points with $z > 0.015$ is 0.144 ± 0.015 mag (Table 7).

Commins 2004). If this is so, sufficiently well-observed variation of SN color within the ridge area could reveal the distribution of intrinsic SN color. Here we examine whether such observed color is correlated with decline rate Δm_{15} , and whether SN luminosities require correction for its variation.

7.1. Decline-Rate Dependence of Ridgeline

We have searched for evidence of a linear dependence upon Δm_{15} of the blue ridgeline by making an unbinned maximum-likelihood fit of the data in Fig. 2 to a “ridge” color-distribution function (whose most probable color varies as $\mathcal{A}(\Delta m_{15} - 1.1)$, where $\mathcal{A}$ is a fit constant), plus a Δm_{15} -independent “tail” color-distribution function that is nonzero only on the red side of the ridge peak. (For the narrow purpose of this fit, the advantage of this simple color-distribution function over a more realistic model, such as that of Hatano et al. (1998), is that SNe far outside the ridgeline have smaller influence on the fit results.) Within statistics ($\sigma(\mathcal{A}) \approx 0.06$), we find no evidence for a nonzero value of the coefficient $\mathcal{A}$. Because our blue ridge is consistent with being Δm_{15} -independent, the only variations with decline rate of our corrections for SN color are those represented by eqs. (13–14).

7.2. Do SNe in the Blue Ridge Require Color Correction?

If SNe that are clustered in the blue ridge are largely unextinguished by host-galactic dust, so that they exhibit mainly a spread in intrinsic color, any necessary color correction to their luminosities could depart substantially from corrections that normally are applied to extinction by dust. In particular, the data might require little or no correction to luminosity for intrinsic color variation. If this simple picture were correct, restricting analysis to SNe that are clustered in the blue ridge could substitute for implementing a color correction.

To test this simple model, we need to identify those SNe which truly belong to the blue ridge group. To perform this identification while avoiding any chance of prejudice against the model, adventurously we allow the Hubble residuals of the SNe, as well as their colors, to play a role in the process of SN selection. For simplicity and for ready comparison with other work, in this section we consider only the Hubble residuals for $B_{\max}$, and, in Hubble fits to $B_{\max}$, we allow all extraneous parameters including decline-rate coefficients to assume their best fit values independent of the results of any other fit.

Our scheme for identifying a group of SNe that have a relatively good chance of obeying the simple model described above is illustrated in the scatter plot shown in Fig. 9. There, for each SN, the abscissa is its pull in the Hubble fit to $B_{\max}$ assuming no color correction, *i.e.* $\mathcal{R} = 0$. The ordinate is a “color pull” whose numerator is the excess of $B_{\max} - V_{\max}$ above a typical value of 0.02 mag, divided by the sum in quadrature of the photometric error and a characteristic intrinsic color rms of 0.03 mag taken from Phil99. As in Fig. 4, SNe that lie within the circle have a sum of pulls squared that is less than 8. These 41 SNe comprise the sample that we select to have a relatively good chance of obeying the “ $\mathcal{R} = 0$ ” simple model. Among the SNe rejected by this cut are SN1993O, which is hosted by an elliptical galaxy; and SN1992bh and SN1995al, which belong to a range of observed color that we do find to be characteristic of the observed colors of SNe that are hosted by E, E/S0, and S0 galaxies.

It may appear naïve to accept as many as 41 of the 56-SN fitted sample (Table 1) into a sample to be tested for freedom from extinction. However, the mean and rms $B_{\max} - V_{\max}$ for all 41 of these SNe (0.022 and 0.061, respectively) are comparable to those (0.022 and 0.062) of the sample of 13 SNe hosted by E, E/S0, or S0 galaxies, whose reddening would be expected to be less significant than for the balance of SNe that occurred in spiral galaxies.

The final step in testing the simple “ $\mathcal{R} = 0$ ” model is to subject this 41-SN subsample to two alternative Hubble fits: one with $\mathcal{R} = 0$ and the other with $\mathcal{R} = 2.59$, the result of the global fit described in §5.5. The details of the SN selection and fit results are shown in Table 8. In the top half of the table, the color and Hubble pulls are those described above. In the bottom half, the values of χ^2 are for Hubble fits to $B_{\max}$ with $\mathcal{R}$ fixed to either of the two indicated values. Even for the restricted subsample of SNe that is fit, χ^2 for the $\mathcal{R} = 2.59$ fit is substantially smaller than for $\mathcal{R} = 0$, by a difference of 13.8. Therefore, with 99.9% confidence, the data reject

FIG. 9.— “Color pull” (defined in the text) *vs.* pull in a color-uncorrected Hubble fit to $B_{\max}$, for SNe in five classes depicted by the same symbols (and colors in electronic edition) that are used in Fig. 2. SNe that are clustered within the circle of radius $\sqrt{8}$ are identified as having a relatively good chance of not requiring a correction for color variation.

TABLE 8

DETAILS OF SN SELECTION AND RESULTS OF FITS THAT REJECT A SIMPLE MODEL IN WHICH SNE THAT ARE CLUSTERED WITHIN THE BLUE RIDGE REQUIRE NO COLOR CORRECTION.

Quantity	Inside cluster	Outside cluster
Pull ² (color) + pull ² (Hubble)	< 8	> 8
SNe with E, E/S0, or S0 hosts	12	1
SNe with late-type hosts	29	14
Conditions and results for Hubble fits to $B_{\max}$:		
$\mathcal{R}$ (fixed in fit to 41 SNe)	2.59 ^a	0 ...
χ^2 (of fixed- $\mathcal{R}$ fit to 41 SNe)	31.8	45.6 ...
Relative likelihood	1	0.001 ...

^aFrom global fit to 56 SNe, $\mathcal{R} = 2.59 \pm 0.24$.

the hypothesis that SNe in the blue ridge group require no color correction. Whether this correction is for intrinsic color or for dust, it is needed. Had we selected the test sample less aggressively – for example, had we declined to include among the selection criteria the sizes of the $\mathcal{R} = 0$ Hubble residuals themselves – this conclusion would only be strengthened.

7.3. Color Corrections to SNe with E, E/S0, or S0 Hosts

Of the 41-SN subsample chosen for the test just described, 12 are hosted by elliptical, E/S0, or S0 galaxies. A thirteenth, SN1993O, has an elliptical host but was rejected from that subsample because, if uncorrected for color, it exhibited a large $\mathcal{R} = 0$ Hubble [residual] (Fig. 9). One might well ask whether these SNe, hosted by relatively ancient galaxies with little remaining dust, also require a nonzero color coefficient $\mathcal{R}$.

From the data considered in this paper, unfortunately, the answer is ambiguous. If SN1993O continues to be omitted from the Hubble fits, the remaining 12 SNe that are hosted by E+E/S0+S0 galaxies show little preference for either of the two values of $\mathcal{R}$ over the other. On the other hand, if SN1993O is included, $\mathcal{R} = 2.59$ is preferred over $\mathcal{R} = 0$. Because a robust result cannot hinge on including or excluding a single SN, a definite conclusion on the color correction of SNe in elliptical, E/S0, and S0 galaxies is not reached here.

8. SUMMARY AND DISCUSSION

Applying both a substantially extended light-curve-fitting algorithm and the CMAGIC prescription of Wang03 to published B and V fluxes from a systematically chosen sample of nearby SNe, we have compared the outputs $B_{\max}$ and B_{BV} of these two types of fit both to each other and to Hubble’s-law expectation. After applying standard corrections for observed SN color, but before applying decline-rate corrections, the difference $B_{\max} - B_{BV}$ reduces to $\mathcal{R} \Delta E$, where $\mathcal{R}$ is a generalized linear color-correction coefficient of the type measured by Tripp (1998); and $\Delta E \equiv \mathcal{E} - (B_{\max} - V_{\max})$ is the difference between standard measures of $B-V$ color used, respectively, by the CMAGIC and light-curve fit methods.

After ΔE is corrected for SN decline rate Δm_{15} , close agreement in the two measures of $B-V$ color is achieved: their mutual rms is only 0.053 ± 0.006 mag. The required correction is compatible with a bilinear but not a linear Δm_{15} dependence (Fig. 3); the nonlinear term is highly significant (5.8σ). Also, to bring the χ^2 for the fit to $\Delta E = 0$ down to an acceptable level, the propagated photometric errors in ΔE must be augmented in quadrature by an intrinsic noise term $n_{\Delta E} = 0.029 \pm 0.007$ mag rms.

In CMAGIC plots of B *vs.* $B-V$ shown in their Figs. (1-4), Wang03 distinguished between SNe that did or did not show a “bump” near maximum light. As is evident from those plots, SNe which did exhibit a bump had a B flux at maximum that was larger than would have been obtained by extrapolating to the same epoch the linear fit to B *vs.* $B-V$ that was made in the post-maximum CMAGIC region. Therefore the prominence of a bump in the CMAGIC plot is intimately related to the difference between $B_{\max}$ and B_{BV} , and therefore to the size of ΔE . Wang03 noted further that SNe which exhibited a bump tended to be slow decliners, with low Δm_{15} . The continuous dependence of ΔE upon Δm_{15} depicted in our Fig. 3 suggests that SNe may not be bifurcated into bumpless and bumpy subsets; rather, their systematic differences $B_{\max} - B_{BV}$ may be described by a continuous (but nonlinear) function of SN decline rate that reaches its nadir for the slowest decliners, as would be expected from Wang03’s observations.

Turning to results from our light-curve fits, we have studied the group of SNe which inhabit the “blue ridge”

region $|B_{\max} - V_{\max}| \lesssim 0.1$. In particular, on a plot of $B_{\max} - V_{\max}$ vs. Δm_{15} (Fig. 2), we sought but did not find evidence for a linear Δm_{15} -dependence of the $B-V$ color about which this group is clustered: within an uncertainty of ≈ 0.06 the best fit Δm_{15} coefficient $\mathcal{A}$ is consistent with zero. Taking $\mathcal{A} = 0$ as a fair representation of the blue ridge topology on this plot, and using the result of our best fit to the Δm_{15} -dependence of ΔE , we can deduce the topology of the blue ridge on a plot of CMAGIC color $\mathcal{E}$ vs. Δm_{15} . On such a plot, for $\Delta m_{15} < 1.1$ the color of the ridgeline would redden in proportion to Δm_{15} with a slope $\alpha_{\Delta E} - \alpha'_{\Delta E} = 0.53$ (Table 3); at higher decline rates it would deredden with a much gentler slope $\alpha_{\Delta E} + \alpha'_{\Delta E} = -0.07$. On their plot of $\mathcal{E}$ vs. Δm_{15} , Wang03 fit the blue ridge to a linear dependence on Δm_{15} over its full range, obtaining a slope equal to 0.25 ± 0.04 , in agreement with our average slope $\alpha_{\Delta E} = 0.23 \pm 0.03$. To sum up, when measured at peak luminosity the blue ridge color shows little dependence on decline rate; but when the color assigned to SNe in the ridge is strongly influenced by post-maximum values of $B-V$, as occurs for the CMAGIC color $\mathcal{E}$, the ridge color tends to redden as the decline rate steepens, particularly for slow decliners.

From their study of $B_{\max} - V_{\max}$ vs. Δm_{15} , Phil99 reported a blue ridge slope $\mathcal{A} = 0.114 \pm 0.037$ for SNe that were preselected to exhibit low $B-V$ color excess in the nebular phase (30-90 days after maximum light). This Δm_{15} dependence is intermediate between the dependences we observe, with no comparable preselection, for $B_{\max} - V_{\max}$ and for $\mathcal{E}$. Our Δm_{15} dependence for $B_{\max} - V_{\max}$ is not significantly different from that of Phil99.

A Hubble fit to the average of $B_{\max}$ and B_{BV} , when combined with the fit to $\Delta E = 0$, is equivalent to a global fit that specifies the color and decline-rate corrections for both $B_{\max}$ and B_{BV} . It yields the $B-V$ color-correction coefficient $\mathcal{R} = 2.59 \pm 0.24$. This value, which parametrizes the effects both of extinction by host-galactic dust and of intrinsic SN color variation, lies well below the coefficient $R_B \approx 4.1$ that conventionally is used for Milky Way dust. The fit result would increase by $\Delta \mathcal{R}/\mathcal{R} = +0.054 \pm 0.027$ if we were to unfold the effects of finite color resolution, and it would diminish by $\Delta \mathcal{R}/\mathcal{R} = -0.102$ if we were to bias it by performing a stepwise rather than a continuous χ^2 minimization, as is discussed in §5.5. Our measurement of $\mathcal{R}$ is consistent with the values 2.09 ± 0.38 ; 2.44 ; 2.46 ± 0.46 ; and 2.19 ± 0.33 obtained, respectively, by Tripp (1998); Tripp & Branch (1999); Parodi et al. (2000); and Guy et al. (2005). (Note, however, that Tripp & Branch (1999) and Guy et al. (2005) report having performed a stepwise χ^2 minimization.) Our result for $\mathcal{R}$ is incompatible with the values 1.71 and 3.5 used, respectively, by Saha et al. (1999) and Altavilla et al. (2004).

That $\mathcal{R}$ is significantly below the canonical value of ≈ 4.1 for Milky Way dust is a real puzzle that we would like to understand. Very recently, Wang (2005) advanced an explanation of the low value of R_B that involves scattering by dust clouds located in the circumstellar (CS) environment. From CS dust at the radius (10^{16} cm) modeled in that paper, scattered light would be delayed significantly relative to unscattered light emitted directly

by the SN, distorting the evolution of its observed luminosity and color. In the present paper, where statistical analysis of our 56-SN sample yields an example of the low value of R_B which CS dust purports to explain, similar statistical techniques may be used to search for such distortions. For example, larger amounts of CS dust could make the decline rate parameter Δm_{15} appear smaller as a result of the delay in scattered light, causing a negative correlation between color and decline rate.

Pursuing this point, Fig. 3(a-b) of (Wang 2005) illustrates the effects of that paper's CS dust model on a single SN. Its $B-V$ color is $E \approx -0.03$ when unextinguished, vs. $E \approx 0.24$ after absorption and scattering by CS dust. Taking into account the change in time of $B_{\max}$, Δm_{15} drops from ≈ 0.95 without extinction to ≈ 0.70 after CS dust extinction, yielding the quotient $Q \equiv \Delta(\Delta m_{15})/\Delta E \approx -0.25/0.27 \approx -0.92$. If one interprets Q as the coefficient of a linear dependence upon E of (observed) Δm_{15} , for these variables one predicts a Pearson correlation coefficient $R_{\text{pred}} = Q \sigma(E)/\sigma(\Delta m_{15}) \approx -0.52 \pm 0.08$, where the error arises from uncertainties on the standard deviations σ of E and Δm_{15} . For comparison we examined the 43 late-type SNe shown by closed triangles and closed circles in Fig. 2, whose correlation between E and Δm_{15} is $R_{\text{obs}} = 0.07 \pm 0.16$. Barring a $\gtrsim 3\sigma$ fluctuation, R_{obs} would have been sensitive statistically to the CS dust prediction. However, if part of the spread in E were due to variation in *intrinsic* color E_{intr} , and if true Δm_{15} were *positively* correlated with E_{intr} (as suggested by Fig. 5(a) of Phil99), a negative correlation due to CS dust could have been cancelled, accounting for our low value of R_{obs} . We also searched for a more general dependence of Δm_{15} upon E by dividing the same 43-SN sample into reddened vs. unreddened subsamples (filled circles vs. filled triangles in Fig. 2). Their difference in $\langle E \rangle$ matched ΔE of the single SN modeled by (Wang 2005). Again, at a comparable level of sensitivity, we did not observe the relative drop in $\langle \Delta m_{15} \rangle$ predicted for the reddened subsample. As models of circumstellar dust around SNe are refined, statistical constraints of the type described here should prove valuable.

Resuming the summary of this paper's results, we return briefly to SNe that inhabit the blue ridge. There we selected a subsample of SNe that offer a relatively good chance of not requiring any color correction. Notwithstanding the possible bias in their selection, in separate fits to the Hubble residuals of $B_{\max}$ these SNe prefer $\mathcal{R} = 2.59$ to $\mathcal{R} = 0$ with a likelihood ratio of 1000:1.

The nonlinear decline-rate correction required to reconcile the $B_{\max} - V_{\max}$ and CMAGIC colors forces $B_{\max} - B_{BV}$, which is proportional to the color difference, to exhibit the same nonlinearity. Therefore, with the same 5.8σ significance, a nonlinear decline-rate dependence must characterize either $B_{\max}$, B_{BV} , or both. When the global fit is used to apportion that nonlinearity between $B_{\max}$ and B_{BV} , the nonlinear term is insignificant in B_{BV} (1.2σ) and is only marginally significant in $B_{\max}$ (2.7σ). Therefore we conclude only that the required nonlinearity is unlikely to be confined fully to B_{BV} . Accepting our best-fit nonlinear parametrization of the Δm_{15} -dependence of $B_{\max}$ (Fig. 7), over the indicated range of Δm_{15} its maximum [deviation] from the best-fit *linear* parametrization is 0.13 mag. Therefore

the need for a nonlinear decline-rate correction should not seriously challenge the validity of cosmological results based on past high- z SN observations, upon which scant photon statistics have imposed other uncertainties that typically are greater.

Phil99 introduced a decline-rate correction that was quadratic in Δm_{15} . In Hubble fits to the more limited data then available, their quadratic term was not significant (0.9σ), and the sign of their best fit nonlinearity was such that faster decliners require steeper corrections. In the present analysis, slower decliners require steeper corrections (Fig. 7). However, it is unreasonable to compare Fig. 7 directly with the results of Phil99; their $B_{\max}$ magnitudes were corrected for host-galactic reddening using a color coefficient $R_B \approx 4.1$ that is characteristic of Milky Way dust, whereas ours were corrected for host-galactic reddening plus intrinsic SN color variation using the coefficient $\mathcal{R} = 2.59 \pm 0.24$ that we measure in the current analysis. We note that, for slow decliners, our best fit Δm_{15} correction to the CMAGIC output B_{BV} is consistent with nil.

The proportionality of $B_{\max} - B_{BV}$ to the color difference ΔE causes the measured noise $n_{\Delta E}$ to map into a mutual intrinsic scatter $n_{\Delta B} = 0.074 \pm 0.019$ mag in $B_{\max}$ vs. B_{BV} . The values of χ^2 for Hubble fits to $B_{\max}$ and B_{BV} are such that the maximum likelihood occurs when all of $n_{\Delta B}$ is confined to B_{BV} . However, the data do not significantly prefer that solution to one in which, for example, $1/\sqrt{2}$ of $n_{\Delta B}$ is apportioned to each luminosity measure. At the level of a 44:1 likelihood ratio, it is unlikely that all of $n_{\Delta B}$ is confined to $B_{\max}$. Even the full 0.074 mag is not a high level of scatter compared to the additional errors of ≈ 0.15 -0.18 mag often added in quadrature to photometric errors on the luminosities of high- z SNe.

Of course, additional intrinsic scatter that similarly affects both $B_{\max}$ and B_{BV} may be present. Lacking the statistical power to separate it from the effects of pecu-

liar velocity, we lump those noise sources into an effective rms SN velocity $v_{\text{eff}} = 382^{+60}_{-52}$ km s $^{-1}$. This places a 95% confidence upper limit of 486 km s $^{-1}$ on the true rms line-of-sight peculiar velocity of nearby SNe relative to the Hubble flow. Most recent SN analyses employ values of the rms peculiar velocity that are below this limit; a particular exception is the recent SN calibration paper of Wang, X. et al. (2005), whose analysis used a value of 600 km s $^{-1}$. An rms peculiar velocity of 500 km s $^{-1}$, barely above our limit, was assumed by Tonry et al. (2003) and Barris et al. (2004).

Applying three different measures of dispersion, we find that $B_{\max}$, B_{BV} , and their unweighted average are scattered about the Hubble line by amounts that are comparable and of order $\approx 0.14 \pm 0.02$ mag (for $0.015 < z < 0.1$), and that are not easily distinguished from each other (Table 7). The uncertainties inherent in such measures are substantial, not only from random fluctuations but also from systematic variations in identification and treatment of outliers and in other methodologies. We urge caution in interpreting these and other estimates of the uniformity of Type Ia SNe.

Our priorities for extension of the work described in this paper include achieving a better understanding of correlations among the published uncertainties in raw flux measurements made on individual SNe, and putting that understanding to use in further-refined light-curve fits. In particular, we look forward to better quantification of the systematic errors that are assigned to the fit outputs.

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APPENDIX

A. STATISTICS

In the Introduction, reference is made to the possibility of a general solution to the problem of estimating the deviation Δ of a single SN from a fiducial absolute SN magnitude, using a set $\mathbf{x} \equiv \{x_j\}$ ($1 \leq j \leq n$) of its measured parameters. Given a training set consisting of an ensemble of N SNe in the nearby Hubble flow whose corresponding deviations Δ_i ($1 \leq i \leq N$) are deduced from their redshifts, an example of such a general solution is provided by the $\tilde{\alpha}$ PDE recipe of Knuteson et al. (2002). A covariance matrix

$$\Sigma_{kl} = \frac{1}{N} \sum_{i=1}^N ((\mathbf{v}_i)_k - \bar{\mathbf{v}}_k) ((\mathbf{v}_i)_l - \bar{\mathbf{v}}_l) \quad (\text{A1})$$

is constructed, where $\mathbf{v}_i \equiv (\mathbf{x}_i, \Delta_i)$, $\bar{\mathbf{v}}_i$ is the mean $\mathbf{v}_i$, and k, l index the $(n+1)$ components of $\mathbf{v}$. The best estimate of Δ maximizes the joint probability density

$$p(\mathbf{x}, \Delta) = \frac{1}{N(\sqrt{2\pi}h)^{(n+1)} \det^{1/2}(\Sigma)} \sum_{i=1}^N \exp \left(-\frac{(\mathbf{v} - \mathbf{v}_i)^\dagger \Sigma^{-1} (\mathbf{v} - \mathbf{v}_i)}{2h^2} \right), \quad (\text{A2})$$

where h is a smoothing parameter determined by N and n .

In §6.3, reference is made to the unweighted rms Hubble residual σ . It is defined by

$$\sigma^2 \equiv \frac{1}{N_{\text{dof}}} \sum_{i=1}^N (m_i - \mu(z_i))^2, \quad (\text{A3})$$

FIG. B1.— Six-parameter light-curve fits to B and V vs. rest-frame epoch for the highly extinguished Type Ia SN 1995bd. Measured data points are shown by circles, with error bars indicating the 1σ uncertainties.

where N_{dof} is the number N of SNe with corrected magnitude m_i at redshift z_i , less the number of parameters in the fit function $\mu(z)$. Reference is made also to the weighted rms (wrms) Hubble residual σ_w . It is defined by

$$\sigma_w^2 \equiv \frac{N}{N_{\text{dof}}} \sum_{i=1}^N \frac{(m_i - \mu(z_i))^2}{\sigma_i^2} / \sum_{i=1}^N \frac{1}{\sigma_i^2}, \quad (\text{A4})$$

where σ_i is the total uncertainty in m_i , taking into account photometry, intrinsic noise, and peculiar velocity.

B. LIGHT CURVE FIT DETAILS

In §2.1, reference is made to the “stretched” SN phase t^* introduced in equation (1). We used the function

$$t^*(t; s_0, \tau_0) = t \left(1 + \left(\frac{1}{s_0} - 1 \right) \frac{1 + (t/\tau_0)^2}{1 + (t/\tau_0)^6} \right). \quad (\text{B1})$$

Also in §2.1, reference is made to the fact that our light-curve fits to a minority of SNe employed six parameters (including the delayed parameters ϵ_0 and t_d in equation (1)), rather than four. As is seen in Table 2, 18 of 61 fitted SNe fell into that category. Of those, 16 are the subset of the 61 SNe that were identified spectroscopically to be SN1991T-like. As well, adding two parameters improved the quality of fit to SN1996X and SN1998bu. Figure B1 exhibits a sample 6-parameter light-curve fit.

In §3 it is asserted that the quantity Σ (equation (7)) roughly tracks the photometric error on $\Delta E \equiv \mathcal{E} - E$. From the definitions of $\mathcal{E}$ and E in §3,

$$\beta_{BV} \Delta E = \beta_{BV} V_{\text{max}}^{\text{raw}} - (\beta_{BV} - 1) B_{\text{max}}^{\text{raw}} - B_{BV}^{\text{raw}}. \quad (\text{B2})$$

After approximating $\beta_{BV} \approx 2$, neglecting uncertainties in corrections for Milky Way extinction, and taking the three raw quantities in equation (B2) to be uncorrelated (see §2.5), the photometric error on its right-hand side reduces to Σ .

Also in §3, reference is made to adjustment of the photometric fit errors that are flagged by the footnote in Table 2. These adjustments were occasioned by the detailed graphical inspections of fit results noted in §3. When the result of a photometric fit showed a systematic deviation from measured fluxes, usually owing to rigidity of the light-curve template, we left all best-fit values untouched but perturbed upward the error assigned to the fit parameter, *e.g.* $B_{\text{max}}^{\text{raw}}$, to bring it into $\lesssim 2\sigma$ agreement with the data. No account was taken of the implications for Hubble fits. When the error in $B_{\text{max}}^{\text{raw}}$ was scaled, so was the error in Δm_{15} . Overall, 13% of the errors quoted in Table 2 were adjusted.

C. EXAMPLE OF $B_{\text{MAX}} \equiv B_{BV}$

Under the special conditions enumerated in §2.5, B_{max} and B_{BV} are fully correlated. As a simple example that satisfies these conditions, suppose that only three measurements $\{B_1, B_2, B_3\}$ of raw B magnitude are made. In the LC fit to the B band, after one fixes $\tau_0 = \infty$ and $\epsilon_0 = 0$ in equation (1) and optimizes the three remaining parameters Γ_0 , t_0 , and s_0 , normally one obtains a best fit light curve that passes exactly through the three measured B points. Suppose further that only a single measurement V_3 of V magnitude is made, at the same epoch t_3 as B_3 . In the LC fit to the V band, t_0 and s_0 must then be determined by their B -band values, while, in this limiting case, only Γ_0 may be optimized. Again the best fit light curve passes through the single measured V point. Within an additive constant, using the fact that all residuals vanish,

$$B_{\text{max}}^{\text{raw}} = B_3 - m_B(T_3); \quad (\text{C1})$$

$$V_{\text{max}}^{\text{raw}} = V_3 - m_V(T_3); \quad (\text{C2})$$

$$E = B_3 - V_3 - (m_B(T_3) - m_V(T_3)), \quad (\text{C3})$$

TABLE D1
 K CORRECTIONS TO $B_{\max}$, $V_{\max}$, Δm_{15} , B_{BV}
(MAG), AND β_{BV} , FOR FOUR SNE WITH REDSHIFTS
AND COLORS LISTED IN THE LAST TWO ROWS.

K correction for SN to quantity	1992bp	1992al	1995ak	2000cn
$B_{\max}$	-0.027	0.009	0.008	-0.013
$V_{\max}$	0.043	0.012	0.009	-0.005
Δm_{15}	-0.118	-0.019	-0.049	-0.093
B_{BV}	0.223	0.022	0.037	0.040
β_{BV}	-0.226	-0.019	-0.038	-0.038
Characteristics of K -corrected SNe:				
z	0.0786	0.0135	0.0230	0.0232
E	-0.050	-0.051	0.000	0.202

TABLE D2
COEFFICIENTS OF z , z^2 , AND z^3 FROM THE CUBIC
FITS SHOWN IN FIG. D1(b), (c), (d), AND (e).

Fig. D1	Coefficient of z	Coefficient of z^2	Coefficient of z^3
(b)	-0.97119	28.9034	-187.314
(c)	3.86474	-23.3410	165.731
(d)	-1.17487	16.5470	-259.775
(e)	3.04291	-10.4068	149.714

where $m_{B,V}$ are the template magnitudes and $T_3 \equiv (t_3 - t_0)/s_0$. If t_3 lies within the CMAGIC linear region, one may fix β_{BV} at a representative value β_0 and use the single pair $\{B_3, V_3\}$ to determine B_{BV}^{raw} ; within a constant,

$$B_{BV}^{\text{raw}} = \beta_0 V_3 - (\beta_0 - 1) B_3 ; \quad (\text{C4})$$

$$\mathcal{E} = B_3 - V_3 - \beta_0^{-1} m_B(T_3) . \quad (\text{C5})$$

Forming $\Delta E \equiv \mathcal{E} - E$ and taking its differential,

$$d(\Delta E) = d(m_B(T_3) - m_V(T_3)) - \beta_0^{-1} dm_B(T_3) . \quad (\text{C6})$$

If the templates are “magic” – that is, if they satisfy the condition $dm_B/d(m_B - m_V) = \beta_0$ in the CMAGIC linear region – the differential $d(\Delta E)$ vanishes: apart from an additive constant, the two color measures E and $\mathcal{E}$ are equivalent, and so are $B_{\max}$ and B_{BV} (eqs. (2) and (6)). Therefore, if the data are minimal and the templates are magic, the maximum-luminosity and CMAGIC analyses are mutually equivalent.

D. K CORRECTION DETAILS

A brief description of our approach to K corrections is found in §2.6. Table D1 exhibits the difference between K -corrected and K -uncorrected $B_{\max}$, $V_{\max}$, Δm_{15} , B_{BV} , and β_{BV} , for four selected SNe whose redshifts and colors $E \equiv B_{\max}^{\text{raw}} - V_{\max}^{\text{raw}}$ are provided in the final two rows. SN1992bp was selected because it has the largest redshift in the sample; SN1992al differs from it primarily in redshift. SN1995ak and SN2000cn were included because they differ from each other primarily in color.

Additional details of the K correction method are provided in Fig. D1 and Table D2. Figure D1(a) exhibits linear fits to the dependence upon $B - V$ color of the K corrections to B and V magnitudes of SN1994D. The 1σ error bars are estimated by varying the choice of library spectral template while warping it to reproduce the observed SN color. The slopes and intercepts of these lines are fit to cubic functions of z shown in Figs. D1(b-e), whose fit coefficients are provided in Table D2. The K corrections to $B_{\max}$, $V_{\max}$, Δm_{15} , B_{BV} , and β_{BV} are obtained by evaluating the K corrections to B and/or V magnitudes at the appropriate $B - V$ colors.

E. NOISE DETAILS

In gaussian approximation and in the basis $\{B_{\max}, B_{BV}\}$ of the measured B magnitudes, the noise in a single SN’s measured luminosity from all sources other than photometric error is expressed by the noise covariance matrix

$$Y = \begin{pmatrix} \sigma_{\max}^2 & V_c \\ V_c & \sigma_{BV}^2 \end{pmatrix} , \quad (\text{E1})$$

where the off-diagonal element V_c in principle is bounded only by $-\sigma_{\max}\sigma_{BV} \leq V_c \leq \sigma_{\max}\sigma_{BV}$.

FIG. D1.— Illustration of K correction method. (a) K corrections at $z = 0.05$ to B magnitudes (full circles) and V magnitudes (open circles) of SN1994D *vs.* observed $B - V$ color. The lines are linear fits with intercept μ and slope ψ . (b-e) Dependence on z of (b,d) μ and (c,e) ψ for (b,c) B and (d,e) V magnitudes. The fit curves are cubic polynomials in z .

Because allocating the measured noise between B_{max} and B_{BV} is challenging statistically, it is advantageous to approximate Y as the sum of two simpler matrices

$$Y = \begin{pmatrix} \sigma_{u,\text{max}}^2 & 0 \\ 0 & \sigma_{u,BV}^2 \end{pmatrix} + \begin{pmatrix} V_c & V_c \\ V_c & V_c \end{pmatrix}. \quad (\text{E2})$$

The first covariance matrix arises from sources of noise $\sigma_{u,\dots}^2$ that are completely uncorrelated between B_{max} and B_{BV} , while the second represents noise sources (including peculiar velocity and, at higher redshift than considered here, weak lensing) that affect both measurements equally. Equation (E2) is an approximation to equation (E1) only in that it restricts the off-diagonal element of Y to the range $0 \leq V_c \leq \min(\sigma_{\text{max}}^2, \sigma_{BV}^2)$. (This is the “mild assumption” to which reference is made in §5.2.) Intrinsic noise can contribute to either of the terms in equation (E2).

After the noise covariance matrix Y from equation (E2) is transformed to the basis $\{\Delta B, \langle B \rangle\}$, its diagonal elements are

$$\sigma_{\Delta B}^2 = \sigma_{u,\text{max}}^2 + \sigma_{u,BV}^2; \quad (\text{E3})$$

$$\sigma_{\langle B \rangle}^2 = \frac{1}{4}(\sigma_{u,\text{max}}^2 + \sigma_{u,BV}^2) + V_c. \quad (\text{E4})$$

Apart from sources of noise V_c that are common to both B_{max} and B_{BV} , it is evident from eqs. (E3-E4) that the rms noise $n_{\Delta B}$ that is measured in the comparison of B_{max} to B_{BV} propagates into $\langle B \rangle$ as $n_{\langle B \rangle} = n_{\Delta B}/2$.

In §5.2, reference is made also to the possibility of using the redshift dependence of the common-mode noise to resolve the effects of peculiar velocity from those of other sources. Such analysis, which is not pursued here due to insufficient statistics, would use an equation of the form

$$\sigma_{\max}^2 = \sigma_{u,\max}^2 + V_c^{\text{int}} + \left(\frac{C}{z} \frac{v_{\text{pec}}}{c} \right)^2, \quad (\text{E5})$$

where V_c^{int} is the portion of V_c that is z -independent. The factor $C(z)$ is equal to 5, multiplied by a correction that, for a flat universe with $\Omega_M = 0.3$, ranges from 1.00 to 1.05 over the redshift range (0.003 to 0.079) of the actual SNe in our fitted sample.

F. COLOR RESOLUTION DETAILS

In §5.5, reference is made to two different methods of estimating the correction to $\mathcal{R}$ from the effects of finite color resolution. In these methods the average color $\langle E \rangle$ (equation (12)) was used. In the first method, the SNe were redistributed in color so that a twice-resolution-smearred color ideogram of the redistributed SNe matched a once-resolution-smearred ideogram of the unredistributed SNe. During the redistribution, the SN excursions were limited by requiring $\chi^2/\text{dof} = 1$, *i.e.* the rms excursion of a SN was limited to one standard deviation in its own color resolution. Using the color-redistributed SNe as indicators of the true SN color distribution, a linear least-squares fit was made to a scatter plot of redistributed color *vs.* observed color for each SN. The fit slope was 0.962, implying that when $\mathcal{R}$ is fit to the observed SN color it is underestimated by 3.8%.

In the second method, a once-resolution-smearred color ideogram first was mildly smoothed using a multigaussian to yield an “apparent” color distribution. Next, a continuous “true” color distribution was identified such that after two gaussian smearings it matched the apparent distribution. In this method the smearing width was set to the median color resolution of the SN set. Next, by smearing the true distribution only once, the average true color that contributes to each apparent color was determined. Then an analytic function was fitted to a plot of (average true color – apparent color) *vs.* apparent color. Using this function, the ratio ρ of average true color to apparent color was constructed as a function of apparent color. Finally, the global fit described in §5 was repeated with each SN’s observed color multiplied by ρ . Relative to the standard fit value, $\mathcal{R}$ was found to increase by 7.0%.

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