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April 2, 2012

Society of Exploration Geophysicist (SEG)
Las Vegas, NV, United States
November 4, 2012 through November 9, 2012

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Full moment tensor and source location inversion based on full waveform adjoint inversion: application at the Geysers geothermal field

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SUMMARY

Source parameters, namely full moment tensor and source location, are investigated based on a full waveform adjoint inversion. The method relies on full wave simulations and takes advantage of the misfit between observed and synthetic seismograms. An adjoint wavefield is calculated by back-propagating the difference between observed and synthetics from the receivers to the source. The interaction between this adjoint wavefield and the regular forward wavefield helps define source parameter Fréchet derivatives, that is, the sensitivity of the misfit with respect to the source parameters. We demonstrate the method on two synthetic cases before tackling a recent event recorded at the Geysers geothermal field.

INTRODUCTION

The development of high-performance computing and numerical techniques enabled global and regional tomography to reach high levels of precision, and seismic adjoint tomography has become a state-of-the-art tomographic technique (e.g., Tape et al., 2009; Peter et al., 2011). Here we focus on the determination of source parameters (full moment tensor and location) based on the same approach. The first section gives a summary of the theory. In the second section we investigate the potential of recovering source parameters using a 1D structural model of the Geysers area (model GIL7 by Dreger and Romanowicz, 1994). Forward and adjoint numerical simulations are performed using a spectral-element code (open source SPECFEM3D, Komatitsch et al., 2005).

THEORY

Kim et al. (2011) have recently presented a detailed analysis of adjoint centroid-moment tensor inversion with an illustration of the technique for southern California regional earthquakes. Here we aim at focusing the same approach at a local scale and ultimately at characterizing smaller events.

Centroid-moment tensor (CMT) solutions are calculated by minimizing waveform differences between observed and simulated seismograms based on an adjoint method. The non-linear adjoint CMT inversion algorithm based on a conjugate-gradient method requires three simulations at each iteration

- a forward simulation to obtain the synthetics for the current source parameters,
- an adjoint simulation triggered by the injection of time-reversed differences between observed and synthetics at each receivers acting as simultaneous sources,
- a forward simulation to compute the step length in the conjugate-gradient direction.

A CMT solution is defined by a moment tensor \mathbf{M} , a centroid location \mathbf{x}_s , and a source time function S . To derive the CMT source parameters of an event, we minimize the squared differences between observed seismograms (data) \mathbf{d} recorded at a series of stations located at \mathbf{x}_r and simulated seismograms (synthetics) \mathbf{s} calculated for a preliminary source model $\mathbf{m} = \mathbf{M}, \mathbf{x}_s, S$. Such a misfit writes as

$$\chi = \frac{1}{2} \sum_{rp} \int w_{rp}(t) \|\mathbf{s}(\mathbf{x}_r, t; \mathbf{m}) - \mathbf{d}(\mathbf{x}_r, t)\|^2 dt, \quad (1)$$

where data and synthetics have been filtered, and w_{rp} refers to a windowing function assigned to the p th window at the r th receiver. Such a windowing is realized using the semi-automated open source software FLEXWIN (Maggi et al., 2009), which warrants maximizing the number of meaningful misfit measurements while avoiding seismic noise.

Let's recall that the forward wave equation writes as

$$\rho \ddot{\mathbf{s}} = \nabla \cdot (\mathbf{c} \nabla \mathbf{s}) - \mathbf{M} \cdot \nabla \delta(\mathbf{x} - \mathbf{x}_s) S(t). \quad (2)$$

where ρ and \mathbf{c} are the density and the elastic tensor, respectively. Kim et al. (2011) demonstrate that the adjoint wave equation is simply

$$\rho \ddot{\mathbf{s}}^\dagger = \nabla \cdot (\mathbf{c} \nabla \mathbf{s}^\dagger) + \sum_{rp} [w_{rp}(t) (\mathbf{s} - \mathbf{d})(T - 2t_0 - t) \delta(\mathbf{x} - \mathbf{x}_r)]. \quad (3)$$

where the subscript \dagger is used to define the adjoint wavefield. Note that the adjoint source is the time-reversed, windowed and filtered waveform difference between data and synthetics at each stations. Also note that except for the source, forward and adjoint wave equations (2-3) are strictly identical meaning that the same solver can be used as long as the source is properly defined.

Based on the expression of the variation of χ and the linearized expression of the variation of equations (2-3) with respect to the source parameters, the Fréchet derivatives for the moment tensor \mathbf{M} and the centroid location \mathbf{x}_s can be expressed as

$$\frac{\partial \chi}{\partial M_{ij}} = \int \varepsilon_{ij}^\dagger S(T - 2t_0 - t) dt, \quad (4)$$

$$\frac{\partial \chi}{\partial x_i^s} = \int \partial_{x_i^s} [\mathbf{M} : \varepsilon^\dagger] S(T - 2t_0 - t) dt, \quad (5)$$

where $\varepsilon^\dagger = \frac{1}{2} [\nabla \mathbf{s}^\dagger + (\nabla \mathbf{s}^\dagger)^T]$ is the adjoint strain tensor. Note that similar Fréchet derivatives for the source time function can be derived (see Kim et al., 2011, for details).

It is interesting to note that contrary to the structural Fréchet derivatives (e.g., Tromp et al., 2005; Morency et al., 2009), the source parameter Fréchet derivatives are only function of the adjoint wavefield, whereas the formers result of the interaction between forward and adjoint wavefields. This means that to

Full moment tensor inversion

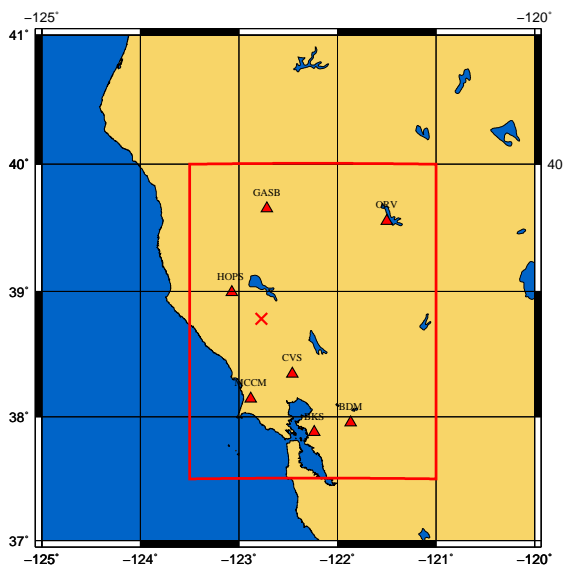


Figure 1: The red rectangle represents the numerical domain investigated, which corresponds to a $225 \text{ km} \times 280 \text{ km} \times 36 \text{ km}$ box. The red triangles refer to the recording stations and the cross gives the location of the source studied (a synthetic event and an event from the Northern California Earthquake Data Center (NCEDC) catalog).

calculate source parameter Fréchet derivatives, one does not need to have stored or to recalculate on the fly the forward wavefield when performing the adjoint calculation and constructing the kernels.

Once the Fréchet derivatives calculated, the key is to use the information they carry in terms of the variation of the misfit function with respect to the source parameters, to iteratively reduce this misfit and thereby constrain the source parameters. To do so we use a conjugate-gradient algorithm.

APPLICATION

In the following we illustrate the technique with synthetic and real cases. Notice that in all cases the signals are filtered, and preprocessing also includes removing the instrument response for the real case.

Synthetic cases

Using the GIL7 1D velocity model, we generate synthetic observed and modeled seismograms based on a known CMT solution and an erroneous CMT solution, respectively. Waveforms are recorded at the stations BDM, BKS, CVS, GASB, HOPS, MCCM and ORV from the Berkeley (BK) network displayed in Figure 1. The goal is then to recover the accurate known CMT solution, starting with the erroneous CMT solution: case (a) only the moment tensor coefficients are wrong,

Table 1: Focal mechanism, centroid location, and moment tensor components for the synthetic cases.

	initial m_{00}	case (a) m_{06}	case (b) m_{12}	solution
Mw (-)	4.27	4.27	4.27	4.27
moment [‡]	3.22	3.25	3.20	3.22
latitude (⁰)	38.7823	38.7823	38.7823	38.7823
longitude (⁰)	-122.7715	-122.7715	-122.7715	-122.7715
depth (km)	$4.68^a / 6.00^b$	4.68	4.53	4.68
Mrr [‡]	-0.5446	-0.5676	-0.5464	-0.5446
Mtt [‡]	1.0869	-0.5208	-0.8061	-0.5423
Mpp [‡]	-0.5423	1.0592	1.3594	1.0859
Mrt [‡]	-0.4956	-0.8680	-0.7131	-0.7289
Mrp [‡]	-0.7289	-0.4854	-0.4661	-0.4956
Mtp [‡]	2.9528	2.9565	2.8267	2.9528

[‡] Scalar moment and moment tensor coefficients unit is 10^{22} dyne.cm

and case (b) moment tensor coefficients and depth are wrong.

The results of the iterative inversions are displayed in Fig. 2, and show an excellent convergence to the exact solution in 6 and 12 iterations for the case (a) and (b), respectively. The misfit reduction corresponding to case (a) and (b) is of 99 % and 97 %, respectively, indicating a proper station azimuthal coverage to resolve events in the area. Table 1 offers a closer look at the source parameters for the initial erroneous model m_{00} , the final iterative solution for case (a) m_{06} and (b) m_{12} , and the exact solution. Finally, in Fig. 3 we display a comparison of the 3-component seismograms recorded at the station BDM between the "data", the initial model m_{00} , and the inverted model m_{06} . Signals have been filtered between 20 and 50 s. One can appreciate the improvement of the fit between "data" and synthetics. Similar improvement in fitting to "data" is observed when performing the 7 parameter inversion. Note that in that case, in order to resolve the depth, the signals are filtered between 2 and 8 s.

January 4th 2009 event at the Geysers, NCEDC ID 51214595

In this section, we present a source parameter inversion for an event which took place on January 4th 2009 at the Geysers. We use data from the NCEDC recorded at the stations BDM, BKS, CVS, GASB, HOPS, MCCM and ORV (displayed in Figure 1). The initial source solution m_{00} is a deviatoric solution from the NCEDC catalog (see Table 2). A good correspondence between data and synthetics is found when filtering between 20 and 50 s. These periods are relatively insensitive to the details of the crustal structure, making the use of a 1D model adequate (e.g., Pasyanos et al., 1996). This yields to a weak sensitivity to depth, which cannot be accurately recovered. We therefore focus on inverting only the moment tensor for now.

Full moment tensor inversion

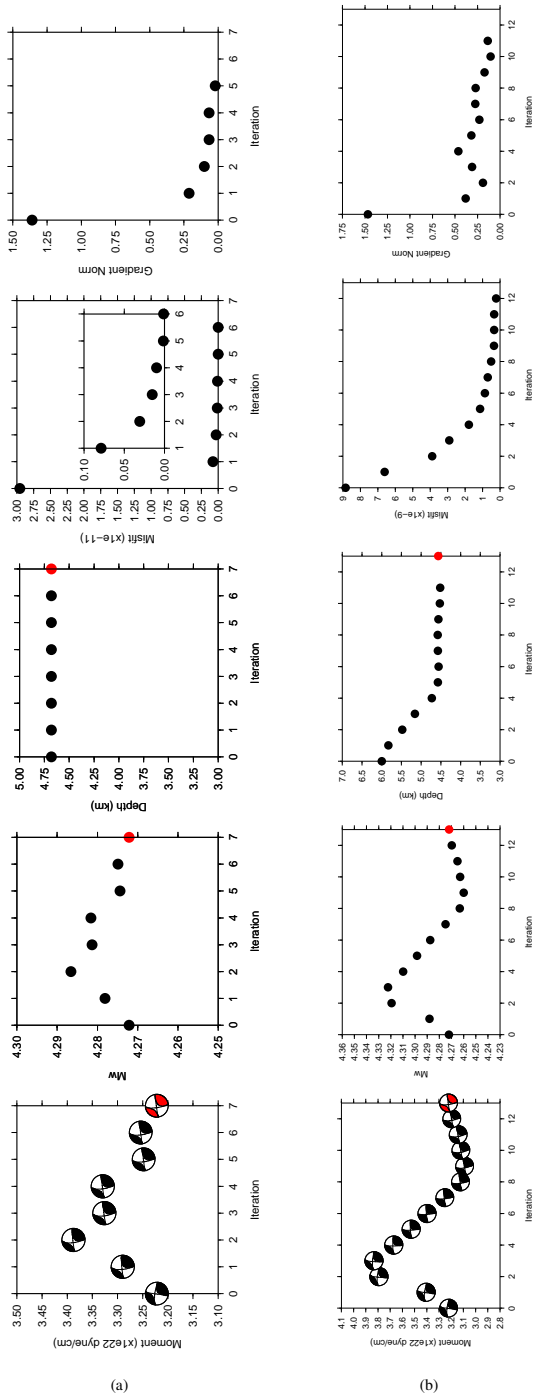


Figure 2: Column (a) presents the iterative inversion for 6 parameters (moment tensor coefficients) when the location is known, and column (b) presents the iterative inversion for 7 parameters (moment tensor coefficients and depth). The exact solution is in red. Each panel displays the scalar moment, magnitude, depth, misfit, and norm of the gradient, from bottom to top.

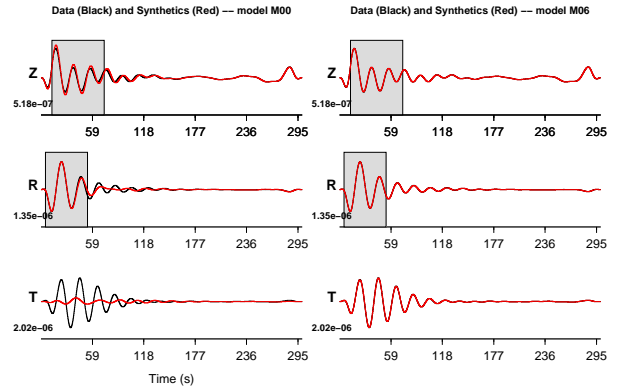


Figure 3: Synthetic case: comparison of the 3-component seismograms at station BDM between "data" (black) and initial model m_{00} and final models m_{06} for the 6 parameter inversion. Signals have been filtered between 20 and 50 s. The shaded rectangles correspond to the windows picked by FLEXWIN where waveform measurements used during the inversion are calculated. [Z: vertical, R: radial and T: transversal]

Results of the iteration are displayed in Fig. 4. One can see that contrary to the synthetic cases performed with a fully constrained velocity model, the misfit reaches a plateau at a non zero values. The misfit reduction in that case is of 47 %. The final model is the best solution that can be reached with the 1D velocity model used and the source location determined from the NCEDC catalog. The improvement of the fitting between data and synthetic 3-component seismograms is displayed in Fig. 5. Remaining differences can be in part attributed to the fact that 3D heterogeneities in the crust are not well accounted for.

CONCLUSIONS

We use a full waveform adjoint method to investigate the inversion for source parameters, namely full moment tensor and source location, at the Geysers geothermal field. The event considered here is of magnitude 4+, which allows to use low frequency signals and a simple 1D velocity model. We note that in that case, depth resolution is weak. To improve this latter, one needs to use a more accurate 3D velocity model to account for 3D heterogeneities in the crust. Nevertheless, we were able to invert for the moment tensor coefficients. The future work and strategy is to improve the 1D velocity model by realizing a local adjoint tomography, to be able to invert for depth. By performing a high frequency 3D adjoint tomography using the dense Calpine/Unocal network and dataset available through the NCEDC website, the resulting 3D velocity model would allow to resolve even smaller events.

ACKNOWLEDGMENTS

This work was performed under the auspices of the U.S. Department of Energy by Lawrence Livermore National Laboratory under Contract DE-AC52-07NA27344.

Full moment tensor inversion

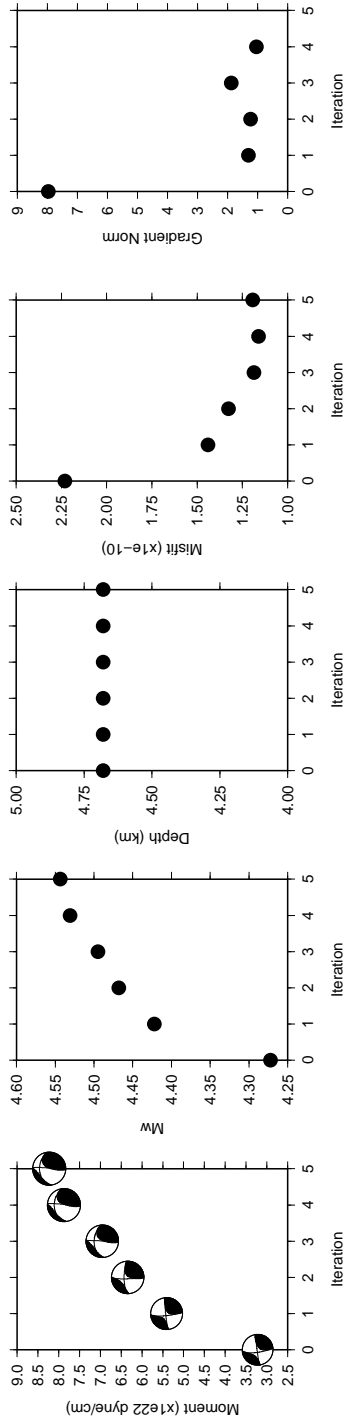


Figure 4: January 4th 2009 event at the Geysers: iterative inversion for the 6 moment tensor coefficients. Each panel displays the scalar moment, magnitude, depth, misfit, and norm of the gradient, from bottom to top. The initial source solution m_{00} is a deviatoric solution from the NCEDC catalog. Convergence is achieved after 5 iterations.

Table 2: Focal mechanism, centroid location, and moment tensor components for the January 4th 2009 event at the Geysers. The initial CMT solution corresponds to the deviatoric solution from the NCEDC catalog.

	initial m_{00}	final model m_{05}
Mw (-)	4.27	4.54
moment [‡]	3.22	8.23
latitude ($^{\circ}$)	38.7823	38.7823
longitude ($^{\circ}$)	-122.7715	-122.7715
depth (km)	4.68	4.68
M_{rr} [‡]	-0.5446	-0.7175
M_{tt} [‡]	-0.5423	0.3137
M_{pp} [‡]	1.0869	1.5910
M_{rt} [‡]	-0.7289	-1.841
M_{rp} [‡]	-0.4956	-5.7520
M_{tp} [‡]	2.9528	5.4476

[‡] Scalar moment and moment tensor coefficients unit is 10^{22} dyne.cm

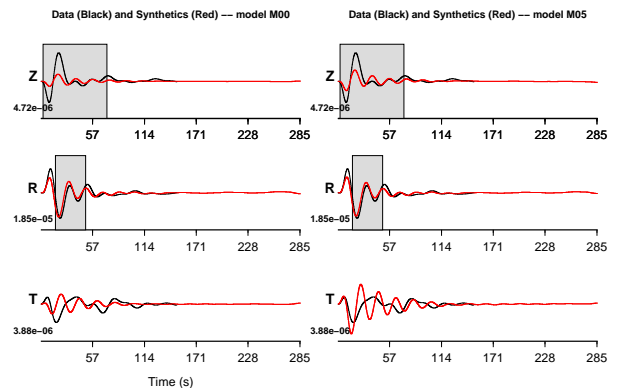


Figure 5: January 4th 2009 event at the Geysers: comparison of the 3-component seismograms at station HOPS between data and the initial model m_{00} and final model m_{05} .

Full moment tensor inversion

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