FY12 Summary Report on Liquid-Liquid Contactor Experiments for CFD Model Validation

Chemical Sciences and Engineering Division
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FY12 Summary Report on Liquid-Liquid Contactor Experiments for CFD Model Validation

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September 28, 2012

work sponsored by
U.S. Department of Energy,
Office of Nuclear Energy, Science and Technology
1 Introduction

This report presents a summary of preliminary experiments performed in the latter half of FY12 using the capability of the Contactor Electrical Resistance Tomography (CERT) Facility. This facility includes the capability for multiphase measurements of flow in liquid–liquid contactors using ERT as well as high-speed imaging with the current test focus on an instrumented engineering-scale annular centrifugal contactor having a 5 inch rotor (CINC-V5). In addition, a smaller CINC-V2 (2 inch rotor) contactor was also added to the facility and made possible the exploration of equipment scaling for liquid–liquid operation. The purpose of the efforts during this current FY were to explore a range of flow conditions for multiphase operation to gain broad insight into observable trends and quantities after which detailed measurements will be made for specific controlled test conditions to provide data for validation of advanced computational fluid dynamics models which are being developed under a separate work package (FT-12AN030901). In FY13, this project and the CFD modeling project are to be combined into a single Work Package named “Contactor Modeling and Validation Data”.

In addition to the CINC-V2 contactor that was added to the facility during this period, we also acquired a high-power, short pulse (700 ns) strobe light (Prism Science’s SPOT+ unit) for use in obtaining short exposure images of liquid–liquid droplets for size distribution investigations. As the short pulse of the strobe allows for an ‘effective’ shuttering speed of 700 ns when synced with
a camera, it was possible to use a standard DSLR camera (a 10.2 Mpx Nikon D60 was used here though a newer higher resolution model has recently been acquired) which has significantly higher image resolution compared to available high-speed cameras. Towards this end we also expanded the capability of the Infinity K1 CentriMax lens with an MX-6 objective attachment which allows imaging on a field of view (FOV) of approximately 1 mm x 1 mm. Preliminary efforts at droplet imaging using these tools will be discussed later on.

The process solutions used for repeat tests in the CINC-V2 were the same as those used previously for the CINC-V5 as reported in ANL-LTR-CERT-12-001:

**Aqueous Phase:** 37.5 wt% aluminum nitrate (1M) in 8 wt% nitric acid (1M)

**Organic Phase:** 40 vol% tributyl phosphate (lab grade) in dodecane (technical grade mixture of isomers)

For ERT testing in the instrumented CINC-V5 contactor, the liquid phases were modified as described later in Section 4.

Tests for the CINC-V2 were conducted at two different total flow rates (500 and 1000 mL/min) at an O/A of 1, and at three different O/A ratios (0.33, 1, 3) for a total flow rate of 1000 ml/min. The rotor speed used was 3600 RPM (typical for V2) and each set of tests were done for the three different mixing vane configurations available for this system: four- and eight-straight vanes (4V, 8V) and eight curved vanes (CV). A six-vane plate was not available for the V2. The general purpose of these additional tests were to explore a range of conditions for the different available vane types in order to investigate general liquid–liquid operation and compare with previous observations in the larger CINC-V5 contactor. Observations and measurements were made using high-speed video of the housing side—which in the case of the V2 was a quartz cylinder as described in Wardle et al. [1].
2 Comparison of Scaling: High-speed Imaging of CINC-V2

Figure 2 shows snapshots of the characteristic minimum and maximum liquid heights for the three vane types at the 500 ml/min flow rate and O/A = 1. While similar trends are seen versus the previous observations of liquid height in the CINC-V5 contactor (Figure 3), there are some differences due to slight changes in the vane geometry between the two contactor sizes. While some variation in coloration of the different case might be expected due to differences in the amount of entrained air and extent of mixing between the two liquids, for the images shown in Figure 2 the inconsistencies in color between the various case is largely due to difference in the camera/lighting configuration (lens aperture, focus quality, color balance, etc.) Specifically, the straight vanes for the V2 contactor extend all the way to the housing wall with no gap between the outside edge of the vane and the housing wall. In contrast, the straight vanes in the larger V5 unit all have a gap of \( \sim 0.25 \) in (half the annular gap) between the vane and the wall. This results in a slightly higher liquid height in all straight vane cases in the V5.

There are also differences in the curved vane geometry between the two scales; while both have a gap between the vane edge and the wall (approximately half the annular gap width in both cases), the V5 vanes have a uniform vane height while the V2 vanes have a stepped region with half the height on the outer \( \sim 1/3 \) of the vane length as described in Wardle et al. [2]. This results in a slightly higher liquid height (in relative terms) in the V2 (with the stepped vane height) as compared to the V5 due to a decrease in the pumping efficiency of the vanes.

It is clear that even minor variation in vane geometry can have a measurable effect on liquid height—what is yet to be quantified is the magnitude of this effect in terms of parameters which affect operational efficiency (e.g. mixing zone hold-up, dispersed phase droplet size). As described in the following section, \textit{in-situ} measurements of droplet size are one method to quantify some of these differences.

3 Feasibility of \textit{in-situ} Bubble/Droplet Size Imaging

Quantitative data for dispersed phase droplet sizes can not only lend insight into the questions mentioned in the previous section regarding comparative mixing for different configurations, but are also critical for validation of advanced CFD models aimed at prediction of liquid–liquid interfacial area which rely on the accuracy of capturing droplet size distributions which rely on ‘calibrated’ models for droplet breakup and coalescence.
Figure 2: Snapshots from high-speed imaging of flow at 500 ml/min, O/A=1 for the three vane types (4V, 8V, CV) showing minimums (bottom row) and maximums (top row) in liquid height. The height of the organic inlet is noted on the 4V lower image for reference.
Recently, a research effort at Sandia (Wyatt et al., unpublished)\(^1\) has conducted droplet size distribution measurements in a CINC-V2 annular centrifugal contactor (with curved housing vanes [cast]\(^2\)). While this work has not yet been published, it provides the only available data set of this type and the researchers were kind enough to discuss their methods and even supply preliminary data for comparison with simulations conducted under the companion modeling project to this current effort. The experiments at Sandia were done at a total flow rate of 300 ml/min—significantly

\(^1\)This project was funded internally through an LDRD which ends in FY12 and was unfortunately only discovered (and then, only serendipitously) by Wardle very recently (July 2012) else earlier collaboration would have been possible.

\(^2\)Very late in FY12, an additional vane plate having 4 straight vanes was sent from Argonne to Sandia and a brief round of tests was planned prior to the close of the project funding there. Note that the curved vanes used in the Sandia contactor are slightly different from those reported in Wardle et al. [2] which were machined rather than cast. For the cast vanes, the vane height was constant and did not have the lower stepped region near the outer portion as in the case of the machined ones. It is thought this may actually result in slightly lower annular liquid height in the cast curved vanes compared to the earlier machined version. This was seen to be the case for full height vanes in the larger V5 contactor.
lower than for typical operation—and for varying O/A ratios less than 0.333 (O:A, 1:3) for organic dispersion in water. Only the data for O/A = 0.333 is used here. The organic phase was polydimethylsiloxane (PDMS, $\rho = 0.918$) dyed with fluorescent Nile Red to aid in phase discrimination and the droplet size was determined through manual analysis of high-speed imaging with a minimum visible radius in the range of $\sim 10$ microns. Data was taken for rotor speeds ranging from 1100 to 3000 RPM. Two different PDMS compositions were used having kinematic viscosities of 5 and 20 cSt. These data have obvious limitations (low flow rate, organic dispersed only, curved vanes only [liquid height in mixing zone was not documented, but was likely quite low]) which make the conditions less than ideal for equipment performance. However, they are the only data currently available and at a minimum demonstrate the feasibility of performing in-situ droplet size measurements in centrifugal contactors. As an example of the data obtained, Figure 4 shows a plot of the size distributions at several rotor speeds for O/A = 0.333.

Given the budgetary constraints of this project in the current FY, only a preliminary effort was made to perform our own measurements of this kind. Due to the critical nature of this data to the success of companion simulation efforts, it is planned that more directed effort will be put towards this important task in FY13. Even so, given the funding levels of the combined computational/experimental FY13 Work Package, only targeted experiments will be feasible.

Our preliminary investigations were conducted using the SPOT+ strobe light and SLR camera system to look at droplets in liquid–liquid dispersions. Tests were done with nitric acid/dodecane-

![Figure 4: Droplet size distribution data from Wyatt et al. for PDMS dispersed in water in a CINC-V2 at an O/A of 0.333.](image-url)
TBP phase pairs for aqueous-dyed (methylene blue) or organic dyed (Nile Red) conditions. Figure 5 shows an example for successive snapshots of a coalescing liquid–liquid dispersion (O/A = 0.333, 30 vol% TBP in dodecane and 0.01 M nitric acid) in a graduated cylinder where the time between images is approximately 3-5 s. While many overlapping droplets can be visually identified and manual measurement using ImageJ (or other similar software) has been demonstrated, all attempts at developing an automatic image analysis tool have been unsuccessful. This is a generally remarked challenge for all liquid–liquid droplet size measurements reported in the literature—the phase contrast is so small that common methods including thresholding, binary transformation, and circle detection fail to work or are not efficient enough to give a representative picture of the full size distribution (e.g. bias towards specific scales). Preliminary measurements were also taken during operation of the V2 contactor. From the preliminary testing that has been done, the following list outlines some significant, but not insurmountable, challenges to in-situ droplet size measurements:

**Camera focusing:** For the very small field of view (∼1 mm x 1 mm) provided by the microscope-like lens required for these measurements, there is a very narrow depth-of-field which makes focusing the image a significant challenge. In addition vibrations also become problematic and care must be taken to isolate the camera and lens. Modification to the setup have been made which should help in this regard for future measurements. This includes a vibration isolated optical breadboard and 3-axis translation stages for the camera mounting which should enable very fine movements of the entire camera to aid in focusing.

**Phase discrimination:** Contrast between the two liquids is very limited—unlike bubbles, which are much more distinguishable (see Figure 5). Fluorescent dye can help but does not completely solve this issue. Adequate lighting is, of course, a very related challenge; however, it appears that the SPOT+ strobe gives very good light output—so much so that the camera lens aperture had to be nearly closed to get good contrast. Too much light is a good problem to have as it provides greater flexibility and range of operation.

**Phase loading limitations:** Droplet identification at high phase loading (O/A near 1) becomes a challenge as droplets are packed very densely and multiple overlapping droplets can be seen. This is evident in the images shown in Figure 5.

**Image analysis:** As noted earlier and related to the above items in this list, image analysis is a significant challenge. It requires painstaking manual analysis of images in which user must identify each droplet individually. It may be possible to develop a more automated method.
Figure 5: Evolution (from top left) of drop size for a coalescing liquid–liquid dispersion in a graduated cylinder. Along with the many liquid drops, some air bubbles are also visible (e.g. large bubble near interface in bottom row, middle image).
using some combination of image preprocessing and algorithm refinement; however, given the challenges reported in this area by others and the experience of the author in this regard, it may not be easily achieved.

There is also the significant additional inherent limitation to opaque multiphase flows of being able to only measure what can be visually observed at the outer surface of the housing. Likely, this is not very representative of the droplet size throughout—CFD simulations to date have demonstrated that the droplet sizes are significantly smaller near the rotor. Even so, this can be accounted for when comparing to simulations by comparing droplet size predictions at the same location in simulation and experiments.

4 Liquid–Liquid ERT

As noted in the M4 milestone report from earlier in FY12 (ANL-LTR-CERT-12-001), for ERT measurements in the liquid–liquid system, significant challenges were discovered due to the extreme difference in conductivity of the two phases. While the measurable conductivity of the organic phase made configuration of the measurement system (ITS P2+ ERT System) for organic continuous operation theoretically possible, due to the high conductivity of the aqueous phase, faulty measurements were produced even at modest phase fractions. Thus it was chosen to pursue only aqueous continuous measurements. However, due to the very high conductivity of the aqueous phase, even using the system’s maximum injection current of 75 mA there was significant noise in the measurements (±10%). As such, the aqueous phase was switched to low nitric acid (0.01 M) and the organic phase changed to the more standard 30 vol% TBP in dodecane. Clean solutions were made for each phase.3

In order to test the viability of the new phases for ERT measurements, a set of data was taken for the 4V geometry at 10 LPM using the 32-electrode circular array. It was found that the recommended injection current determined by the p2+ system was 55 mA, well below the 75 mA maximum for the system. Using this injection current and optimizing settings for the data acquisition for both speed and noise reduction, we were able to obtain data with an error (based on noise in the signal under constant conditions) of less than ±4%. Figure 6 gives a comparison of two ERT images processed with ITS’s SCG software for the 32-electrode circular array at the bottom of the rotor for liquid–liquid operation using the new liquid phase pair. Similar to what was shown in ear-

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3 Due to the salting out of nitrate ions into the organic phase by the aluminum nitrate in the original aqueous phase, it was not possible to even reuse the organic phase as additional waste would be generated in trying to wash it clean of extracted nitrate in order to maintain low electrical conductivity in the new aqueous phase.
Figure 6: Comparison of SCG reconstruction with standard mesh input (left) and modified mesh with vanes (right).

lizer reports using reconstructions from the open-source package Eidors, the addition of the vanes seems to give better comparison with external observation during operation. Additionally, one interesting ‘feature’ has been identified in all measurements of this type made in the instrumented V5 contactor—that is, a tendency toward a low conductivity region in the vicinity of electrodes 17–19. After noticing this in multiple reconstructions of disparate conditions, it seems that this may be an artifact of the grounding configuration of the sensors. In particular, there is a single ground for the 32-electrode array that is located just above electrode 17. While ITS recommends such a configuration for their typical application (mixing in cylindrical tanks), it appears that the restricted geometry of the contactor results in a non-uniform electrical path to ground at typical operating conditions generating the observed artifacts in the measured conductivity field. Modifications are planned for the sensor configuration to provide a more uniform ground throughout the vessel and give more reliable results by having four linked ground electrodes at 90° intervals around the housing.

4.1 ‘Tomography’ Measurements for Liquid Height

While it has been shown previously (see FY11 report) that conductivity measurements using ‘electrode scans’ (potential of each electrode individually relative to ground) of the vertical electrode arrays are also possible for the liquid–liquid system under aqueous continuous conditions, mea-
surements of this type are quite slow (1 every 2-3 s) and therefore an effort was made to develop a technique to measure annular liquid height using tomography data from the usual rotating adjacent injection pair measuring scheme for which the system has been optimally configured. Using such a configuration it is possible to take measurements on a single plane in the 10s of Hz range. One drawback of this measurement scheme is that some electrode information is lost. Whereas the electrode scans provide a measurement at each electrode location individually, for tomographic data, only the data from a single injection pair (the two bottommost electrodes, 1&2) is useful meaning that the first measurement pair is for electrodes 3&4 with the resulting data point being at a height between the two; the last available measurement is then for the electrode pair 15&16. The result is that for the electrode scans there are 16 measurements (one for each electrode) and for the tomographically-obtained values there are only 13 (for the 13 adjacent pair combinations, 2&3, 3&4, and so on through 15&16).

A python script was written to process the data from tomographic measurements to give a map of liquid fraction along the height of the electrode array. Unfortunately, it appears that this may require additional refinement as the initial results at least show some strange artifacts relative to similar (albeit much slower) measurements from electrode scans (Figure 7). It is not clear what caused the signal dropout at $\sim 4$ cm and above $\sim 7$ cm in the tomographic measurements as compared to the electrode scan data. If this can be corrected, the speed of this measurement scheme offers a significant advantage compared to electrode scans.

Figure 7: Comparison of axial volume fraction data reconstructions from electrode scans (left) and adjacent injection-pair measurement (right).
5 Summary and Future Work

Based on the data needs for liquid–liquid contactor CFD model validation, a number of experimental techniques have been explored and the status of these efforts has been presented here. It is anticipated that targeted experimental measurements providing well-characterized validation quality data sets can be conducted in the coming FY. Beyond droplet size and phase fraction measurements, an additional need is for phase velocity and turbulence data. While some of the equipment required for such measurements is available (e.g. PIV-capable high-speed camera) through partnerships with other research groups at the laboratory, it may be useful to partner with a university perhaps through an NEUP project to obtain velocity data. While several NEUP proposal submission attempts have been made in the past through partnerships with the University of Wisconsin–Madison and Texas A&M University, these have unfortunately been unsuccessful. To what degree it is possible given the structure of the NEUP program, FCR&D programmatic support of future proposals in this regard would be very helpful.

6 Acknowledgments

Thanks to Jing Gao of the University of Illinois at Chicago for high-speed imaging of the CINC-V2 while working as a graduate research aide during this past summer.

References

