Summary Report on Liquid-Liquid Contactor Scoping Experiments and Validation Test Case Definition

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May 31, 2012

work sponsored by
U.S. Department of Energy,
Office of Nuclear Energy, Science and Technology
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31 May 2012

1 Introduction

This report presents an overview of a set of wide ranging experiments that was conducted during the first half of FY12 using the capability of the Contactor Electrical Resistance Tomography (CERT) Facility. This facility includes the capability for multiphase measurements of flow in liquid–liquid contactors using ERT as well as high-speed imaging with the current test focus on an instrumented engineering-scale annular centrifugal contactor having a 5 inch rotor (CINC-V5). The purpose of the efforts during this current FY are to explore a range of flow conditions for multiphase operation to gain broad insight into observable trends and quantities after which detailed measurements will be made for specific controlled test conditions to provide data for validation of advanced computational fluid dynamics models which are being developed under a separate work package (FT-12AN030901).

In addition to the Redlake X5plus camera, a Redlake MotionPro Y7 camera was also available on loan from another research group at Argonne. The Y7 is capable of grayscale imaging at 7500 frames per second at full resolution (1920×1080) and has excellent light sensitivity (can be used for time-resolved particle image velocimetry (PIV)). This camera was used for the bubble imaging described in Section 2.3. Imaging at the bubble scale was done using an Infinity K1 CentriMax lens with an MX-4 objective attachment.

The process solutions used for these tests were:

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Aqueous Phase: 37.5 wt% aluminum nitrate (1M) in 8 wt% nitric acid (1M)

Organic Phase: 40 vol% tributyl phosphate (lab grade) in dodecane (technical grade mixture of isomers)

The addition of aluminum nitrate to the aqueous phase and use of 40 vol% TBP was intended to produce a measurable electrical conductivity in the organic phase and enable electrical resistance tomography (ERT) measurements under organic continuous conditions. Indeed, the measured conductivities of the two phases were 169 mS/cm and 7.6 µS/cm, respectively. Challenges related to ERT measurements for this phase system are described in Section 3.2.

Tests were conducted at three different total flow rates (5, 10, 15 LPM) at an O/A of 1, and at three different O/A ratios (0.33, 1, 3) for a total flow rate of 10 LPM. The rotor speed generally used was 1800 RPM and each set of tests were done for four different mixing vane configurations, four-, six-, and eight-straight vanes (4V, 6V, 8V) and eight curved vanes (CV). The general purpose of this phase of testing was to explore a wide range of conditions for the four available vane types in order to investigate general liquid–liquid operation and identify conditions for later detailed experimentation and acquisition of CFD validation quality data. Observations and measurements were made using high-speed video of both the housing side and the mixing vane region under the rotor. ERT measurements using the single 32-electrode array positioned in the housing near the bottom edge of the rotor (top of the vanes) were made solely for the liquid-liquid cases at 10 LPM and O/A of 0.33 (aqueous continuous).

2 High-speed Imaging

As an example of the general flow patterns seen in the mixing zone during these experiments, a snapshot from the high-speed imaging of flow in the 4V geometry at 10 LPM and O/A = 1 is shown in Figure 1. The banding of the aqueous phase (dyed dark blue) is evident as well as several turbulent Taylor-Couette vortices. Note that the organic phase inlet flow enters just to the right of the viewing area and can be seen as droplets and a liquid film descending above the electrode array on the right. As noted in previous investigations using the CINC-V2 contactor, the liquid height in the mixing zone was oscillatory and the image shown is at or just subsequent to a minimum in liquid height.
Figure 1: Snapshot of flow in 4V geometry at 10 LPM and O/A = 1. Flow is from right to left.
2.1 Annular Liquid Height Comparisons

Figure 2 shows time averages of the high-speed images of the flow as viewed from the side for the three flow rates at an O/A flow ratio of 1. A test for the highest flow rate in the 4V geometry was not performed as the liquid volume in the mixing zone was filled beyond the height of the inlets under these conditions—the inlet height is just above the top of the image. The same trends in liquid height as seen in the single liquid (water) tests reported in FY11 are evident here: 4V > 6V > 8V > CV. In the liquid–liquid case, the differences in liquid height are enhanced over the water case as the mixture viscosity for the liquid-liquid dispersion is greater than that of water leading to higher liquid height in all cases. Banding of the aqueous phase is also apparent in individual snapshots, but is somewhat washed out by the time-averaging evidencing the dynamic axial motion and variability of the bands, particularly for larger liquid height cases such as in the 4V and 6V geometries. Interestingly, the liquid height for 6V at 5 LPM is roughly equal to that for 8V at 10 LPM and CV at 15 LPM such that top-left to bottom-right diagonals in the image matrix have roughly equivalent liquid height.

The variation in liquid height with O/A ratio for the four vane types (at 10 LPM total flow) is shown in Figure 3. It was observed that with increasing organic flow fraction there was seen greater liquid height and also greater air entrainment as evidenced by increased light scattering. The variation across the vane types is most pronounced at O/A = 1. This is thought to be due to the mixture viscosity having a maximum in the range of 1:1 phase ratio.

2.2 Mixing Vane Region

The flow underneath the rotor for each of the vane types is shown in Figure 4 with the bottom row showing instantaneous snapshots and the top row time-averaged images. Note that all cases are at 10 LPM, O/A = 1, and 1800 RPM except the CV case which is at 1200 RPM. Images were taken at 500 fps (X5plus camera). Under these conditions, the dyed aqueous phase is dispersed and darker regions should thus be aqueous-rich. At first inspection, it was unexpected that the center of each rotating region between vanes would have a higher concentration of the more heavy phase. However, recent CFD simulations using coupled dispersed/segregated phase models have confirmed that these dark regions are indeed aqueous-rich. While it seems counterintuitive that the heavy phase would go towards the center of rotation rather than outward, as the dispersed phase, the droplets also have the tendency to go towards regions of lower flow velocity, a tendency which appears to dominate over density variations in this case. It can be seen that for the 6V and 8V cases, these regions are most pronounced and an additional counter-rotating vortex is observed in
Figure 2: Time-averaged images of annular liquid holdup at O/A = 1 for four different vane types (columns) and three different flow rates (rows). All cases are at a rotor speed of 1800 RPM.
Figure 3: Time-averaged images of annular liquid holdup at 10 LPM for four different vane types (columns) and three different O/A flow ratios (rows). All cases are at a rotor speed of 1800 RPM.
Figure 4: Instantaneous snapshots (bottom) and time-average images (top) for flow at 10 LPM and O/A = 1 in the mixing vane region for four different vane types. The rotor speed was 1800 RPM in all cases except CV which was at 1200 RPM. Rotor rotation is in a clockwise direction.
the center near the rotor axis as noted in earlier CFD simulations [1].

Figure 5 shows an image taken at higher frame rate (1000-1500 fps) for a smaller region of interest around a single vane section for the 8V and CV cases. Both are at an O/A of 3 and using rotation speeds of 1800 RPM and 1200 RPM for the two cases, respectively. Unlike the straight vanes packages for the smaller CINC-V2 contactor, all supplied vane types for the larger V5 unit used here have vanes that do not extend all the way to the housing wall. As demonstrated in previous CFD simulations [2], the addition of a vane-wall gap leads to a region of high rotating velocity near the housing wall and reduces the vanes’ pumping efficiency leading to a higher overall annular liquid height. Thus, in each case there is a high velocity region just outside the vane. In the straight vane case, the flow impinges on the upstream side (with respect to rotor rotation) of the vane and flows radially inward with a visual appearance analogous to traditional turbulent flow.
over a flat plate. In the curved vane case, the flow is more efficiently directed radially inward on the upstream side, however, on the backside of the vane there is separation of the flow and a stagnation region near the radial midpoint of the vane. As noted previously, low flow regions are characterized by darkened appearance due to dispersed phase accumulation. The general flow pattern are around the curved vane is reminiscent of aerodynamic flow over a wing at high angle of attack where flow separation occurs.

One interesting, but yet unanswered, question is how the overall mixing is distributed between the fraction that occurs in the vane region under the rotor as opposed to the annular region. In this regard, the addition of a vane-wall gap introduces and additional source of turbulence and droplet shearing in the sharp outer vane edge bordering the high velocity region. It is not clear if this region of enhanced mixing has a significant impact on overall mixing and more detailed analyses—both experimental and computational—are needed to better understand this issue. Additionally, it is also not clear whether the increased liquid height observed in cases with fewer vanes leads to the production of very fine droplets which do not separate adequately in the rotor and lead to an increase in other-phase carry-over and degradation of stage efficiency. However, based on the testing that has been done with the CERT facility to date, no measurable difference in carry-over from the feed tank balance monitoring has been observed for the different vane types that would suggest over-mixing in such cases.

### 2.3 In-situ Bubble/Droplet Size Imaging

Quantitative data for dispersed phase droplet sizes can not only lend insight into the questions mentioned in the previous section regarding over-mixing, but are also critical for validation of advanced CFD models aimed at prediction of liquid–liquid interfacial area. A limited set of single droplet and multiple droplet imaging studies had been planned through a separate FY12 work package at INL. Unfortunately, this project was left unfunded for FY12 due to budget constraints. As such data is critical to the CFD validation mission of this work, it was deemed worthwhile to explore the feasibility of performing droplet size measurements, in this case in situ in the CINC-V5 contactor as part of this project. Note that similar in situ high-speed imaging for liquid–liquid flow in a CINC-V2 contactor has been done at Oak Ridge National Laboratory as part of a lab-funded effort a few years ago. While these experiments have been mentioned in several ORNL presentations\(^1\) there are as yet no published data that have been made available. Depending on the quality of data and documentation, characterization, and control of the flow conditions, these data could be extremely useful to the CFD validation goals of this current effort and also provide a

\(^{1}\)e.g. D. DePaoli July 20, 2011 presentation [here](#).
means of exploring equipment scaling by comparison with the similar measurements planned here for the CINC-V5. In fact, if FY13 funding allows, it would be worthwhile to support from the Separations Program a small work package to provide ORNL the means to accelerate the release of these data sets. At the very least, we are consulting with the ORNL researchers who did this work to gain insights and advice for overcoming common challenges with lighting and image post-processing.

Figure 6 shows a comparison of sample images taken with the Y7 camera at 7500 fps for two different O/A flow ratios (1 and 3) for the CV geometry. The black region is the inner end of the vane (toward the rotor axis) which has a thickness of 1.59 mm (1/16 in). Under these conditions, contrast between the liquid phases is small as are the liquid droplets themselves. Consequently, the fluid particles more readily seen are are entrained air bubbles as in this case. It was apparent from these and other experimental observations that the amount of entrained air was significant in all cases—a fact that has previously not been fully appreciated by most researchers including the author. It was observed that the O/A ratio also had an impact on the amount of entrainment with high values (more organic phase) having more entrainment—something noted in the ORNL work—as shown in Figure 6. While of little interest from a solvent extraction perspective, such observations on gas entrainment may be of use for contactor applications in gas-liquid contacting as have been proposed in the literature.

The evaluation of several image processing options is underway for quantification of bubble size distributions from such images and enable comparison between various cases. In addition, a higher magnification lens objective for the configurable K1 CentriMax lens used here is also being acquired which will allow imaging over a field of view of approximately 1 mm by 1 mm and enable resolution of liquid drops down to the micron scale. Given the budgetary constraints of this project in the current FY, it is anticipated that only a preliminary effort in this area can be made in the near term but it is planned that more significant effort can be put towards this important task in FY13 given adequate funding.

3 ERT

3.1 3D ERT Reconstructions

As described in the final report for this project in FY11, various methods exist for processing the acquired voltage measurements from the ERT system into a reconstructed cross-sections of conductivity. It was shown there that processing using an open-source toolkit called Eidors3D en-
Figure 6: Snapshots taken at 7500 fps for the flow near the inside edge of a single vane in the CV system at a total flow rate of 10 LPM and two different O/A flow ratios.
abled explicit meshing of vane geometry and reconstruction of volume fraction fields with greater fidelity. Due to the constrained geometry of the centrifugal contactor and the placement of the circular array of electrodes near the top of the vanes and the bottom of the rotor, it would seem that a full 3D reconstruction would give an even better representation of the data and a more physically realistic result.

A comparison of reconstructions made in 2D (a) and 3D (b) for a water-only measurement in the 4V geometry is shown in Figure 7. Note that in the 3D case, only a small portion of the annular region above the rotor bottom was included. While this positive result demonstrates the possibility of 3D reconstructions, there were significant computational challenges in its achievement. In particular, only a relatively coarse mesh consisting of \( \sim 35K \) tetrahedral elements could be used due to significant memory requirements—approximately 18 GB of RAM at the peak—of the ‘inverse problem’ solution using Eidors3D (version 3.5). Additional work is required to determine if other methods or modifications to the processing scheme are available to decrease these requirements and enable greater spatial resolution of the reconstruction. Additionally, there is the not insignificant challenge of understanding how uncertainty is introduced into the data through the reconstruction process.

![Figure 7: Comparison of 2D (a) and 3D (b) ERT reconstructions using Eidors3D for data from a water-air measurement in the 4V system. The 3D case shows a clipped version of the conductivity map for ease of visualization.](image)
3.2 Liquid–Liquid ERT

As for ERT measurements in the liquid–liquid system, significant challenges were discovered due to the extreme difference in conductivity of the two phases. While the measurable conductivity of the organic phase made configuration of the measurement system (ITS P2+ ERT System) for organic continuous operation possible, due to the high conductivity of the aqueous phase, faulty measurements were produced even at modest phase fractions. Thus it was chosen to pursue only aqueous continuous measurements. However, due to the very high conductivity of the aqueous phase, even using the system’s maximum injection current of 75 mA there was significant noise in the measurements (+/- 10%).

Figure 8 gives an example of reconstructions using ITS’s SCG software package for measurements under aqueous continuous conditions at O/A = 0.33 and 10 LPM in each of the vane types. While the general features of the flow as seen previously in Figure 4 are evident, there is also a strange asymmetry common among each vane type that is perhaps due to faulty measurements or

![Figure 8: Selected frame from ERT reconstruction using the SCG software for each of the four vane types.](image)
amplification of noise in the reconstruction. While reconstructions with explicitly meshed vanes should yield much better results, the noise in the measurements and the fact that the injection current of the ERT system is insufficient for the high aqueous phase conductivity leads to the conclusion that the chosen phase composition will not work and modifications are necessary to enable successful ERT measurements. While ITS currently has in development an ERT system capable of significantly higher currents needed for high conductivity solutions such as this, it will be necessary for the given setup to achieve reduction in the aqueous phase conductivity as discussed in the following section.

Conductivity measurements using the vertical electrode arrays are also possible for the liquid–liquid system under aqueous continuous conditions as described in the FY11 report. Additional measurements of this type were not part of these scoping experiments.

4 Validation Test Case Definition

One of the primary goals of this research effort is the acquisition of experimental data which will be sufficiently characterized and detailed to enable validation of the multiphase CFD methodology and simulations being conducted under the companion modeling project. The CFD solver under development is aimed at prediction of stage performance indicators such as extraction efficiency and other-phase carryover in annular centrifugal contactors and other liquid–liquid extraction devices. In order to achieve this, computational models are required which can predict liquid–liquid interfacial area for complex multiphase flow regimes spanning complete phase-segregation to phase-dispersed. Such a goal requires the development of a hybrid computational methodology which enable selective sharp interface capturing as well as multi-fluid inter-dispersion modeling with variable droplet sizes. The development of such a unique capability unavailable in commercial CFD tools is well under way and testing to date has been successful.

A variety of experimental data are necessary for rigorous validation of such novel hybrid multiphase CFD tools. These are described here:

**Droplet Size** Prediction of liquid–liquid interfacial area requires accurate models for prediction of dispersed phase droplet size distributions. Prediction of droplet sizes in turn requires underlying models for prediction of the rates of droplet coalescence and breakup. Thus data are required for validation of the individual breakup and coalescence models and/or data for the actual droplet size distributions under relevant localized conditions. This would include droplet size measurements *in situ* as well as measurements of residual dispersed phase volumes in other-phase effluents.
**Droplet drag** Droplet motion is governed by inter-phase momentum transfer terms for the individual phase momentum equations. A variety of drag models exist and information is needed to guide the selection of appropriate models for the current application. A companion computational effort at LANL (only minimally funded for FY12) on droplet-scale studies along with the planned (but unfunded in FY12) INL experiments mentioned previously are aimed at providing data in this regard.

**Interfacial Area** While this can be inferred from the droplet size, it can also be measured directly through chemical means using well-characterized irreversible reaction systems as an overall, device-averaged quantity. Such measurements for a CINC-V2 contactor are described in the work of Schuur et al. [3]. Along with overall interfacial area, these studies provide certain useful bulk quantities such as phase hold-up (estimations only), residence time distributions, and droplet size distributions. Unfortunately, the focus of this work was on biological applications so the feed rates are extremely low (e.g. <100 ml/min) as are the rotor speeds used (<30 hz (1800 RPM)).

**Phase Velocities and Turbulence** Accurate prediction of velocities and turbulence quantities is necessary for accurate prediction of all other flow variables including those which are directly related to stage performance such as phase hold-up (residence time) and droplet size (break-up and coalescence models are functions of the turbulence dissipation rate $\varepsilon$). Velocity measurements using optical methods (LDV, PIV) are limited to the near wall region as the flows in these systems are opaque under typical conditions.

**Volume Fraction Distributions** Local volume fraction measurements provide another means of direct validating model predictions for multiphase mixing and flow. Annular liquid height is also useful, albeit as a more composite quantity. The ERT methods currently being applied provide a non-intrusive method for measurement of such quantities.

**Mass Transfer Coefficients** Similar to drag models (momentum transfer), mass transfer information is strictly more of a required input to the simulations and requires experimental or direct numerical simulation level computational information to guide the selection of models and parameters.

Ultimately, the overall stage extraction efficiency could be an additional quantity for validation, however, the various detailed data outlined above are required to enable accurate prediction of this composite quantity as well as to identify the main sources of uncertainty.
Based on the needs outlined above, the capabilities currently available, and the funding scope of the current project, only a targeted set of validation experiments for selected quantities can be conducted during the remainder of FY12. As such, the focus will be on acquisition of quantitative data principally for the 4V geometry at 10 LPM total flow at different O/A ratios. Experiments will include acquisition of time-resolved conductivity measurements of annular liquid height as well as ERT measurements of phase fraction—both to be conducted in aqueous continuous regimes only. Additionally, droplet size imaging analysis will be performed for multiple O/A ratios at multiple points under the rotor as well as on the side of the housing if optical clarity of the acrylic allows it. As time allows, some preliminary PIV measurements will also be performed.

As noted, the high electrical conductivity of the current aqueous phase presents challenges to ERT measurements. As such, the aqueous phase will be switched to low nitric acid (0.1 M or lower if necessary). A first series of experiments will be run with the current organic phase of 40 vol% TBP which will then be diluted with dodecane to 30 vol% TBP and the tests repeated. Along with the existing data such as are presented here for the current phase system, this will provide additional measurements for comparison of the effects of phase properties. Characteristics of the phase properties including density, electrical conductivity, viscosity, interfacial tension, surface tension, and contact angle will be measured where reliable data are not available in the literature.

References


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