Conf 94/203--25

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**Presented at
First World Conference on Photovoltaic Energy Conversion
Waikoloa, Hawaii
December 5-9, 1994**

December 12, 1994

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A SOLAR MODULE FABRICATION PROCESS FOR HALE SOLAR ELECTRIC UAVS

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ABSTRACT

We describe a fabrication process used to manufacture high power-to-weight-ratio flexible solar array modules for use on high-altitude-long-endurance (HALE) solar-electric unmanned air vehicles (UAVs). These modules have achieved power-to-weight ratios of 315 and 396 W/kg for 150 μ m-thick monofacial and 110 μ m-thick bifacial silicon solar cells, respectively. These calculations reflect average module efficiencies of 15.3% (150 μ m) and 14.7% (110 μ m) obtained from electrical tests performed by Spectrolab, Inc. under AM0 global conditions at 25°C, and include weight contributions from all module components (solar cells, lamination material, bypass diodes, interconnect wires, and adhesive tape used to attach the modules to the wing). The fabrication, testing, and performance of 32 m² of these modules will be described.

INTRODUCTION

A span-loaded flying-wing vehicle, known as the RAPTOR PATHFINDER, is being employed as a technology integration platform to enable high altitude long endurance flight [1]-[2] for weeks or months. It requires lightweight flexible solar modules able to endure mechanical stress and adverse environmental conditions. It therefore, presents a photovoltaic application that is intermediate to conventional low cost terrestrial installations and expensive space satellite installations. The airplane has a 30.5 meter wingspan with a 2.44 meter chord, and was originally built and flown in 1983 by AeroVironment, Inc. Flight altitudes exceeding 3.05 km were achieved at that time using Ag/Zn batteries as the power source. The flight envelope of the original aircraft has been expanded for high-altitude flight through major upgrades to its structure and electric propulsion systems. In

addition, the plane has been converted to solar electric powered flight by covering the upper wing skin with lightweight flexible solar array modules. First generation modules containing 350 μ m thick single crystal silicon solar cells were used to provide approximately one-half of the electrical power in a series of flight tests which took place between 10/93 and 1/94. This paper describes the development of a lightweight flexible solar array module fabrication process used on 32 m² of second generation solar modules. These second generation modules contain both 110 and 150 μ m thick single crystal silicon solar cells. The combination of first and second generation modules to be flown on the Pathfinder wing for the high altitude flight tests is shown in Fig. 1. These tests are scheduled to begin in the spring of 1995.

SOLAR CELL SELECTION AND DESCRIPTION

The PATHFINDER airplane solar cell selection is a function of many parameters including the solar cell: (i) efficiency, (ii) weight, (iii) reliability, (iv) flexibility, (v) bifaciality, (vi) availability, and (vii) cost. In addition, the PATHFINDER wing dimensions are fixed at 30.5 by 2.44 meters, and solar modules cannot be mounted on the front 25% and rear 5% of the wing due to aerodynamic considerations. Thus, the maximum area available for solar module coverage is (30.5m) x (2.44m) x (0.7) = 52.1m². Because of this limited area we have made the decision to use the most efficient, reasonably priced, and lightest weight solar cells available. The type of solar cell meeting all these criteria is single crystal silicon. Thin film (<10 μ m thick) a-Si solar cells are very low cost but do not yet have large area efficiencies high enough to justify their use in this application (see, for example [3]). Other promising thin film materials such as CdTe and CuInSe₂ [4]-[5] have shown

Fig. 1. PATHFINDER wing showing the solar module configuration for high altitude flight testing. Three single crystal silicon cell thicknesses are used, namely; 110, 150, and 350 μm . There are a total of 57 rib bay sections, and the plane is divided into 5 sections namely, one center, 2 mid, and 2 tip panels.

impressive efficiencies for small area cells, but again do not yet have high enough efficiencies over large areas to be useful for this fixed wing application. GaAs and GaAs/Ge solar cells are very efficient and have less radiation degradation [6] but are too heavy and expensive. Very thin film GaAs cells [7] would be ideal except that they are again too costly and currently not available for large area applications.

Single crystal silicon solar cells are suited for this application because of their relatively low cost and high efficiency. Since much of the PV industry is based on these type of cells, manufacturing costs have already scaled compared to the other technologies. Additionally, single crystal silicon cells are used in a wide variety of applications from major terrestrial installations with cell efficiencies of 14% (AM1.5 global) and costing in the \$5/Watt range, to solar race cars with cell efficiencies over 22% (AM1.5) costing in the \$100's/Watt, to space satellite systems costing even more.

Silicon solar cells are also made in a wide variety of cell thicknesses depending on the application. The first generation cells used on the PATHFINDER test flights made from 10/93 to 1/94 used 350 μm thick standard terrestrial single crystal solar cells made by Siemens Solar, Inc. Some of these solar panels will still be on the plane for the high altitude flights commencing in the spring 1995 time frame. The second generation modules described in this work contain commercially available solar cells. The solar cells are made from single crystal Cz silicon that is thinned to 150 μm for the monofacial cells and 110 μm for the bifacial cells. Both are

Spectrolab type K-6 solar cells with diffused Al and ^{11}B implanted back surface fields for the mono- and bifacial cells, respectively. Average efficiencies for the 6.73cm x 6.98cm solar cells are 15.7% for the 150 μm cells and 15.0% for the 110 μm cells (frontside illumination only). Bifacial response is desired for some of the solar modules because the transparent wing will transmit Albedo to the cell backsides.

SOLAR ARRAY LAMINATE SELECTION

The solar array laminate materials must be lightweight, highly transmissive, UV stable, and able to withstand the extreme temperatures seen at high altitudes. Fluoropolymers are ideally suited for this application because they are: virtually chemically inert, highly transmissive in the visible spectrum, dimensionally stable for temperatures between -70°C to 107°C , highly abrasion resistant, and exhibit very little UV degradation. Candidate polymer materials with these properties include the fluoropolymers ethylene-chlorotrifluoroethylene (HalarTM) and polyvinylidene fluoride (TedlarTM). Both of these fluoropolymers have high melting temperatures ($>240^{\circ}\text{C}$), and low embrittlement temperatures ($<-72^{\circ}\text{C}$).

As part of the selection process we have performed experiments to determine the photovoltaic response versus incident angle for the two films laminated to solar cells with a silicone transfer adhesive (Dielectric Polymer Neltape 1001). The results of these experiments are shown in Fig. 2. The angular photoresponse of solar cells laminated to 12.5 μm

Fig 2. Normalized photovoltaic response vs. incident angle for Tedlar and Halar based laminates.

Tedlar is higher than for 25µm of Halar, making this material more suited for our application. This is because Tedlar has a higher transmission of light for $\lambda < 700\text{nm}$. In addition, the Tedlar is commercially available in thinner layers than the Halar, and modules made from these two laminates will have slightly different weights as shown in Fig. 3. These two results indicate that Tedlar is the best laminate material for this application.

Fig. 3. Weight density vs. Si solar cell thickness (µm) for Si solar cells and modules made from the Tedlar and Halar laminate structures.

SOLAR ARRAY LAMINATE STRUCTURE AND LAMINATION PROCESS

The laminate structure itself consists of two fluoropolymer Tedlar/silicone adhesive sandwiched layers that encapsulate the solar cells. The result is a sealed planar solar cell array laminate

structure that protects the solar cells and provides additional stability on the top and bottom. We have chosen very thin layers of laminate and adhesive in order to fabricate a high power to weight ratio solar array modules. The Tedlar film is 12.5µm, and the unsupported silicone adhesive film is 50µm. Together they add up to 178 gm/m² (0.036 lb/ft²) for the top and bottom layers.

The module fabrication process involves laminating the electrically connected solar cells between the top and bottom Tedlar/silicone adhesive layers. This encapsulates the silicon solar cells as shown in Fig. 4. The process is best described by illustration (see Fig. 5). As the release liner is removed, the top and bottom laminate layers are fed between the laminating rollers. The electrically connected solar cells are then fed through the apparatus and sealed

Fig. 4. Solar array module structure with sealed solar cells. Silicon solar cell thicknesses of 150 µm (6 mil) and 110 µm (4.3 mil) are used in this work.

by the top and bottom laminate layers. The cells pass through the apparatus twice. The first pass is at room temperature and causes the solar cells to be laminated to the top and bottom layers. The second pass is at 100°F (37°C) and causes the silicone adhesive layers to reflow and seal the solar array module. After electrical testing and sorting by I_{sc} , the submodules are attached to the PATHFINDER wing using Tedlar/silicone adhesive tape and vacuum bagging to insure uniform pressure.

SUBMODULE DESCRIPTION AND PERFORMANCE

The solar cells are interconnected into strings of 7 cells per row with 0.51mm a spacing between cells and 8 rows per submodule (1 submodule = 7 x 8 array of cells) as shown in Fig. 6. Seven bypass diodes have been attached to heat sinking electrical

Fig. 5. Schematic of array lamination process. The polyethylene release liners are removed and the top and bottom laminate layers are fed to the laminating rollers. The electrically connected solar cells are then fed through the rollers to laminate them into a solar array module.

tab leads and soldered into both sides of each submodule for redundant protection against open circuit failures. These diodes are very small (2mmx2mm), thin (350 μ m) and are rated for $V_B = -40V$ and $I_F = 3A$.

The solar cell interconnects have been chosen to have low resistance while being lightweight and flexible. We use 25 μ m thick Ag etched-mesh interconnects which electrically interconnect the solar cells along each edge. Modules made using these interconnects have been mechanically tested in our wing stress simulation apparatus. This apparatus simulates PATHFINDER take off, landing, and up to a 5g load on the wing by subjecting the module to ± 0.115 cm tension-compression cycles over a 51 cm rib bay section. This is the predicted worst case dimensional change expected for the flexible PATHFINDER airplane. No electrical or open circuit failures due to broken solar cells and/or interconnects have been observed after over 20,000 tension/compression cycles. These submodules are thus flexible enough under predicted worst case conditions to withstand PATHFINDER flight. Each submodule has an aperture area of 47.3cm x

Fig. 6. Schematic of PATHFINDER submodule showing the 7 x 8 cell array, bypass diode locations, and dimensions.

56.2 cm (0.268m²). The corresponding average aperture-area efficiencies as measured by Spectrolab under AMO global (25°C) testing conditions are 15.3% and 14.7% (frontside illumination only) for the Type I and II solar cells, respectively. A summary of the submodule electrical characteristics is shown in Table I. Here we see that the maximum power voltage for each

Table I. Submodule electrical performance.

Solar Cell Type	Type I monofacial	Type II bifacial
Cell Thickness (μm)	150	110
Average AMO submodule efficiency (%)	15.29	14.76
Submodule Voc (V)	34.91	34.70
Submodule Isc (A)	2.073	2.062
Submodule Vmp (V)	28.34	27.59
Submodule Imp (A)	1.949	1.933
Average Fill Factor	0.7637	0.7453

submodule is approximately 28V. In order to achieve the desired bus voltage of > 100V, we must interconnect the submodules into groups of 4 in series to make what we call a module. For the sake of clarification, submodules are laminated individually, and modules are comprised of 4 series connected submodules having a total operating voltage of $\approx 112\text{V}$.

The submodule weights and electrical performance for the two types of solar cells is shown in Table II. Here we see that very high power to weight ratios are obtained with these modules with 315 and 396 W/kg for the Type I and II solar cells, respectively.

Table II. Submodule powers and weights.

Solar Cell Type	Type I monofacial	Type II bifacial
Cell Thickness (μm)	150	110
Solar Cell + Interconnect Weight (gm)	118.20	77.30
Total submodule weight (gm)	175.60	134.70
Total AMO Power Frontside Only (Watts)	55.25	53.34
Power to Weight Ratio Frontside Only (Watts/kg)	315	396
Additional bifacial power from 15% Albedo (Watts)	0.00	8.00
Power to Weight Ratio with 15% Albedo (Watts/kg)	315	455

If we add the bifacial component expected for the Type II cells (15% Albedo), we obtain a power to weight ratio of 455 W/kg. Actual power to weight ratios for the submodules will be better than this because of the low operating temperatures expected in the 12,000 to 24,000 meter (40-80,000 ft.) altitude range predicted for PATHFINDER during its spring 1995 test flights.

We have simulated the average cell temperature and maximum solar power versus altitude for the Type II (110 μm bifacial) solar cells taking into consideration the curvature of the wing surface. The results are summarized in Fig. 7 (a-c). In (a)

Fig. 7. Simulation of solar intensity, cell operating temperature, and maximum solar power versus altitude for the Type II (110 μm bifacial) solar cells.

the solar intensity versus altitude is shown. In (b) the average cell temperature is calculated using estimates for radiative and convective cooling and the experimentally determined value for α of 0.62. This low value of α coupled with the average efficiency $\eta=0.147$ results in a corresponding low temperature of operation determined by $[\alpha-\eta] = 0.473$. The minimum cell operating temperature of 264K (-9°C) occurs at an altitude of approximately 12.5 km. At higher altitudes the air pressure continues to drop and ability for the cells to cool decreases. An increase in the solar cell operating temperature is predicted. In (c) the maximum solar power versus altitude is shown. It continues to increase with altitude due to solar irradiation increasing and cell operating temperature decreasing. At 12.5 km the maximum power begins to slightly decrease with altitude due to the increase in cell operating temperature.

PATHFINDER PERFORMANCE

The actual solar array to be flown on PATHFINDER in the spring of 1995 contains the number of cells and modules shown in Table III. Of the total number of solar cells (8730), 2016 are Spectrolab Type I, 4704 are Spectrolab Type II, and 2010 are Siemens terrestrial type cells from the generation one type of module. The total number of rib bays covered is 40.05 out of a possible 57, and the total area of the array is 40.4 m². The solar array weight considering all modules, interconnects, and tape is 27.6kg which represent 13% of the total plane weight.

Table III. Actual PATHFINDER solar array for spring 1995 test flights.

Solar Cell Type	Type I monofacial	Type II bifacial	Siemens monofacial	Totals
Cell Thickness (μm)	150	110	350	
Total number of solar cells	2016	4704	2010	8730
Total number of submodules	36	84	26	146
Total number of modules	9	21	8	38
Total number of rib bays covered	12	28	10.05	40.05
Total area of modules (m ²)	9.6	22.5	8.3	40.4
Total weight of modules (kg)	11.3	6.3	10.0	27.6

Using the actual solar array allows the altitude versus time of day to be predicted for PATHFINDER. The simulation takes into account all parameters

affecting flight, including solar array power, total plane weight, motor efficiency, sun angle, propeller efficiency, air density, etc... versus altitude. In Fig. 8 we show the predicted altitude versus time of day for PATHFINDER assuming that the date is July 20 and the take off point is at 35°N latitude (e.g. Edward's AFB, CA). We see that for a 0700 take off time the plane will climb steadily until it reaches a maximum altitude of 23.8km at around 1400 hours. At this point the amount of solar power available is not enough to overcome the reduced lift supplied by the 3% of an atmosphere present at this altitude and the plane flies approximately level. Note the plane's altitude goes slightly higher and lower at this point because it is flying in a station keeping pattern which will point the array away from the sun during part of the time. At 1800 hours the plane is brought down in order to land before dark.

Fig. 8. Simulation of PATHFINDER altitude vs. time of day using the actual solar array containing the submodules fabricated for this work and earlier modules fabricated by Siemens. A maximum altitude of 23.8 km (78,000 ft.) is predicted.

SUMMARY

We have developed an array lamination process to fabricate high power-to-weight ratio solar modules suitable for high altitude unmanned air vehicles such as the PATHFINDER. This process involves: (i) electrically interconnecting the solar cells with a flexible interconnect, (ii) soldering bypass diodes along both sides to protect against open circuit failures, and (iii) laminating the resulting solar cell array between two Tedlar/silicone adhesive sandwiched layers. The laminate materials, Tedlar and silicone, have been chosen to minimize UV degradation, withstand the extreme thermal variations imposed by long-endurance high-altitude flight, and accommodate the flexing of the wing. The modules have achieved 315 W/kg (150μm

Spectrolab Type I) and 390 W/kg (110 μ m Spectrolab Type II). Since the wing material is transparent, a 15% Albedo will boost the power to weight ratio to 455W/kg for submodules containing the Type II bifacial cells.

ACKNOWLEDGMENTS

The work was performed under the auspices of the U.S. Department of Energy under Contract W-7405-Eng-48. The authors would like to thank Bart Hibbs of AeroVironment for the altitude simulations and Mark Cohen, Jim Daley, Bob Curtin, and Ray Morgan of AeroVironment, Inc. for valuable insights, discussions, and suggestions.

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