National Ignition Facility
Sub-System Design Requirements
Supervisory Control Software
SSDR 1.5.2

J. Woodruff
P. VanArsdall
E. Bliss

August 29, 1996

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Supervisory Control Software
SSDR 1.5.2
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# Table of Contents

<table>
<thead>
<tr>
<th>Paragraph</th>
<th>Title</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.0</td>
<td>Scope</td>
</tr>
<tr>
<td>2.0</td>
<td>Applicable Documents</td>
</tr>
<tr>
<td>2.1</td>
<td>Applicable NIF Project Documents</td>
</tr>
<tr>
<td>2.2</td>
<td>Applicable US Government Orders and Standards</td>
</tr>
<tr>
<td>2.3</td>
<td>Applicable National Consensus Codes and Standards</td>
</tr>
<tr>
<td>2.4</td>
<td>Applicable LLNL Standards</td>
</tr>
<tr>
<td>2.5</td>
<td>Supporting Documentation Standards</td>
</tr>
<tr>
<td>2.6</td>
<td>References</td>
</tr>
<tr>
<td>3.0</td>
<td>Requirements and Verification</td>
</tr>
<tr>
<td>3.1</td>
<td>System Definition</td>
</tr>
<tr>
<td>3.1.1</td>
<td>System Description</td>
</tr>
<tr>
<td>3.1.2</td>
<td>System Functions</td>
</tr>
<tr>
<td>3.1.3</td>
<td>System Diagrams</td>
</tr>
<tr>
<td>3.1.3.1</td>
<td>Supervisory Software Relationship to FEP Software</td>
</tr>
<tr>
<td>3.1.3.2</td>
<td>Supervisory Control and FEP Software Hierarchy</td>
</tr>
<tr>
<td>3.1.4</td>
<td>System Interfaces</td>
</tr>
<tr>
<td>3.1.5</td>
<td>Major Subsystems, Supervisory Control Software- WBS 1.5.2</td>
</tr>
<tr>
<td>3.2.00</td>
<td>Supervisory Control Software, Functional Requirements</td>
</tr>
<tr>
<td>3.2.01</td>
<td>Supervisory Control Software, Application Software</td>
</tr>
<tr>
<td>3.2.02</td>
<td>Supervisory Control Software, Look and Feel</td>
</tr>
<tr>
<td>3.2.03</td>
<td>Supervisory Control Software, GUI Application</td>
</tr>
<tr>
<td>3.2.04</td>
<td>Supervisory Control Software, Software Languages</td>
</tr>
<tr>
<td>3.2.04.1</td>
<td>Supervisory Control Software, Standard Software Language, Ada</td>
</tr>
<tr>
<td>3.2.04.2</td>
<td>Supervisory Control Software, Secondary Software Language, C/C++</td>
</tr>
<tr>
<td>3.2.04.3</td>
<td>Supervisory Control Software, QA Level Requirements</td>
</tr>
<tr>
<td>3.2.05</td>
<td>Supervisory Control Software, Machine Interlocks</td>
</tr>
<tr>
<td>3.2.06</td>
<td>Supervisory Control Software, Hardware Platform</td>
</tr>
<tr>
<td>3.2.07</td>
<td>Supervisory Control Software, On-line Configuration</td>
</tr>
<tr>
<td>3.2.08</td>
<td>Supervisory Control Software, Diagnostic Suite Definition</td>
</tr>
<tr>
<td>3.2.09</td>
<td>Supervisory Control Software, Pre-Shot Requirements</td>
</tr>
<tr>
<td>3.2.10</td>
<td>Supervisory Control Software, Shot Time Requirements</td>
</tr>
<tr>
<td>3.2.11</td>
<td>Software Requirements Specification (SRS)</td>
</tr>
<tr>
<td>3.2.12</td>
<td>Supervisory Control Software, Access to Distributed Control Points</td>
</tr>
<tr>
<td>3.2.13</td>
<td>Modes of Operation, Segmented and Concurrent Operation</td>
</tr>
<tr>
<td>3.2.14</td>
<td>Supervisory Control Software, Documentation and Manuals</td>
</tr>
<tr>
<td>3.2.15</td>
<td>Lifetime, Replaceability, Reliability, Availability, Maintainability</td>
</tr>
<tr>
<td>3.2.15.1</td>
<td>Lifetime</td>
</tr>
<tr>
<td>3.2.15.2</td>
<td>Replaceability</td>
</tr>
<tr>
<td>3.2.15.3</td>
<td>Reliability</td>
</tr>
<tr>
<td>3.2.15.4</td>
<td>Availability</td>
</tr>
<tr>
<td>3.2.15.5</td>
<td>Maintainability</td>
</tr>
<tr>
<td>3.2.16</td>
<td>Recovery From Abnormal Event</td>
</tr>
<tr>
<td>3.2.17</td>
<td>Human Factors</td>
</tr>
<tr>
<td>3.4</td>
<td>Logistics</td>
</tr>
<tr>
<td>3.4.1</td>
<td>Maintenance</td>
</tr>
<tr>
<td>6.0</td>
<td>Revision Record</td>
</tr>
</tbody>
</table>
1.0 Scope
This System Design Requirement document establishes the performance, design, development, and test requirements for the Supervisory Control Software, WBS 1.5.2, which is part of the NIF Integrated Computer Control System (ICCS). This document responds directly to the requirements detailed in ICCS (WBS 1.5) which is the document directly above.

2.0 Applicable Documents
This section lists DOE orders, codes, and standards which are applicable to the NIF Integrated Computer Control System. The applicable portions of these documents apply. Applicable LLNL standards are being considered contingent upon the decision of final site selection.

2.1 Applicable NIF Project Documents
National Ignition Facility Functional Requirements and Primary Criteria, Revision 1.4, Mar 1996.

2.2 Applicable US Government Orders and Standards
US. Government DOE General Orders: (fd = flowdown from SDR004, nfd = no flowdown)
DOE 5700.6C—Quality Assurance (fd)

US. Government DOE Orders relating to Safeguards and Security:
None apply to this document.

2.3 Applicable National Consensus Codes and Standards
General Standards:
None apply to this document.

Safety Standards:
None apply to this document.

Software and Electronic Standards:
Ethernet IEEE-802.3 Local Area Network for Data Communications
FDDI Fiber Distributed Data Interface, ANSI Standard X3.139-1987
RS-232C EIA Serial interface standard
RS-485 EIA Multi-drop serial interface standard
IEEE-488 Standard Digital Interface for Programmable Instrumentation, ANSI/IEEE Std 488.1-1987 and
ANSI/IEEE Std 488.2-1987
VMEbus IEEE-1014
RS-170 EIA Video interface standard
X11 X Window System, Version 11, windows graphics standard, MIT X Consortium
OSF/Motif Motif graphical user interface, Open Systems Foundation
Postscript Text and graphics printing language, Adobe Systems Inc.
POSIX IEEE-1003 portable application programming environment
TCP/IP Protocol stack for network communications
OSI/ISO Open Systems Interconnect protocol stack for network communications
OSF/DCE Distributed Computing Environment, Open Systems Foundation
OSF/DME Distributed Management Environment, Open Systems Foundation

2.4 Applicable LLNL Standards
None apply to this document.
2.5 Supporting Documentation Standards
Instrument Society of America, ISA-S5.1, Instrumentation Symbols and Identification
Instrument Society of America, ISA-S5.2, Binary Logic Diagrams for Process Operations
Instrument Society of America, ISA-S5.3, Graphics Symbols for Distributed Control/Shared Display
Instrumentation, Logic and Computer Systems
Instrument Society of America, ISA-S5.4, Instrument Loop Diagrams
Instrument Society of America, ISA-S5.5, Graphics Symbols for Process Displays
Software Guidelines Standards, Practices, and Conventions (Final DRAFT), Applications Development
Department, Lawrence Livermore National Laboratory, August 10, 1992
The Software Productivity Consortium, Ada Quality and Style Guidelines for Professional Programmers

2.6 References
NIF-LLNL-95-044/L-15958-2, National Ignition Facility Quality Assurance Program Plan, September 1995
NIF-LLNL-94-017/L-15958-5, NIF Ancillary Software Quality Assurance Plan, January 12, 1994
NIF-LLNL-93058, National Ignition Facility Functional Requirements and Primary Criteria

3.0 Requirements and Verification

3.1 System Definition

3.1.1 System Description
This system provides supervisory software for integrated control of the distributed subsystems, manual operator controls, and displays and reports laser and target area shot data.

Application software is organized as subsystems. Alignment, laser diagnostics, power conditioning, optical pulse generation, and target diagnostics are each assigned a primary operator console in the control room. A sixth subsystem is devoted to experiment configuration and overall integration functions. All subsystem controls and status are provided with graphic user interfaces suitable to operator action.

3.1.2 System Functions
3.1.3 System Diagrams

3.1.3.1 Supervisory Software Relationship to FEP Software
3.1.3.2 Supervisory Control and FEP Software Hierarchy

Integrated Computer Control Software
3.1.4 System Interfaces
The ICCS Supervisory Control Software has interfaces to the following WBS systems:

- WBS 1.5.3 Integrated Timing System (FEP)
- WBS 1.5.4.1 Integrated Safety System (FEP)
- WBS 1.5.4.2 Integrated Safety System, Access Control (FEP)
- WBS 1.5.5 Automatic Alignment (FEP)
- WBS 1.5.6.3 Facility Environmental Monitor
- WBS 1.5.6.1 Video Distribution (FEP)
- WBS 1.5.6.3 Environmental Monitor (FEP)
- WBS 1.8.6.3 Target Auxiliary Systems (FEP)
- WBS 1.8.3.11 Target Diagnostics Control Room (FEP)
- WBS 1.7.3 Wavefront Control (FEP)
- WBS 1.7.2 Beam Diagnostics (FEP)
- WBS 1.7.1 Alignment Systems (FEP)
- WBS 1.3.4 Power Conditioning (FEP)
- WBS 1.3.3 Pockels Cell System (FEP)
- WBS 1.3.1 OPG (FEP)
- WBS 1.3.1 OPG Modulator (FEP)
- WBS 1.3.1.1 OPG/MOR (FEP)
- WBS 1.3.1.5 OPG/Preamp (FEP)

3.1.5 Major Subsystems, Supervisory Control Software - WBS 1.5.2
Consists of WBSs:
- 1.5.2.1 System Integration Software
- 1.5.2.2 Alignment Controls Software
- 1.5.2.3 Power Conditioning Software
- 1.5.2.4 Laser Diagnostics Software
- 1.5.2.5 Target Diagnostics Software
- 1.5.2.6 Master Oscillator and Preamplifier Software
- 1.5.2.7 Shot Director Controls and Status Software
3.2.00 Supervisory Control Software, Functional Requirements

The Supervisory Control Software

- provides supervisory software for integrated control of the distributed subsystems:
  - power conditioning
  - laser alignment and wave front controls
  - laser beam diagnostics
  - target diagnostics
  - optical pulse generation
- provides manual operator controls for maintenance
- displays laser- and target-area configuration schematically
- displays and report laser- and target-area shot data
- provides special motor-slewing operator controls for alignment
- configures laser- and target-area sensors and instruments using FEP capabilities, store shot configuration as part of shot data
- coordinates FEP-level machine interlocks to protect against component damage caused by improper operation
- retrieves data from distributed FEPs
- provides reusable integration software for upper-level systems
  - interprocess communication
  - distributed shot number
  - event logging
  - alarm processing
- sequences slower control elements not connected to hardware timing system
- reduces and stores laser diagnostic data in on-line database
- analyzes laser performance and models power balance
- processes selected target diagnostics data for rapid assessment of experimental results
- coordinates automatic alignment system

3.2.01 Supervisory Control Software, Application Software

Detailed requirements for each major element of the supervisory software shall be documented in a separate Software Requirements Specification (SRS). The SRS shall specify requirements including performance, concurrency, persistence, and other dynamic specifications that may imply system partitioning or a particular method of implementation. Each SRS shall describe the functional requirements that the subsystem must provide, including:

- services that are required by the respective Front End Processors
- configuration data that characterize equipment being controlled
- user interfaces
- data processing and archival
- automatic sequencing
- status and alarm processing
- data logging and trending.

3.2.02 Supervisory Control Software, Look and Feel

All application GUIs shall provide a consistent look and feel across all subsystems to ameliorate the potential of operator errors. The look (presentation of information) and feel (way in which the operator interacts with the application) shall follow the similar conventions throughout the control system, including use of color, use of symbols, and style of operator input.

3.2.03 Supervisory Control Software, GUI Application

The applications GUI shall allow the operator to control the layout of the workstation, including number, sizing and placement of windows.
As a goal, all GUI applications should attempt to allow recovery of an operator defined screen layout configuration, on a per-operator basis. That is, an individual operator should be able to define a screen “window” configuration, and retrieve the layout, to effectively customize the screen, and arrive at a familiar operating presentation at runtime.

3.2.04 Supervisory Control Software, Software Languages

3.2.04.1 Supervisory Control Software, Standard Software Language, Ada
The standard software language shall be Ada. Exceptions shall be by design review.

3.2.04.2 Supervisory Control Software, Secondary Software Language, C/C++
The secondary software language shall be C/C++. Exceptions shall be by design review.

3.2.04.3 Supervisory Control Software, QA Level Requirements
The Supervisory Control Software shall adhere to the following Quality Level specifications. Reference for QA Level is the NIF QA Plan as stated in paragraph 2.6 of this document.

<table>
<thead>
<tr>
<th>WBS Code</th>
<th>Software Component</th>
<th>QA Level</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.5.2.1</td>
<td>System Integration Software</td>
<td>Q-Level 2</td>
</tr>
<tr>
<td>1.5.2.2</td>
<td>Alignment Controls Software</td>
<td>Q-Level 3</td>
</tr>
<tr>
<td>1.5.2.3</td>
<td>Power Conditioning Software</td>
<td>Q-Level 3</td>
</tr>
<tr>
<td>1.5.2.4</td>
<td>Laser Diagnostics Software</td>
<td>Q-Level 2</td>
</tr>
<tr>
<td>1.5.2.5</td>
<td>Target Diagnostics Software</td>
<td>Q-Level 3</td>
</tr>
<tr>
<td>1.5.2.6</td>
<td>Master Oscillator and Preamplifier Software</td>
<td>Q-Level 3</td>
</tr>
<tr>
<td>1.5.2.7</td>
<td>Shot Director Controls and Status Software</td>
<td>Q-Level 3</td>
</tr>
</tbody>
</table>

3.2.05 Supervisory Control Software, Machine Interlocks
Machine interlocks, via a configuration database, shall be used to keep the beam path clear, and assure that attenuators or gain settings are established before a shot so that components cannot be damaged. Other machine interlock functions shall be implemented as needed.

3.2.06 Supervisory Control Software, Hardware Platform
The Supervisory Software shall operate in the hardware environment specified in ICCS, Computer Systems SSDR.

3.2.07 Supervisory Control Software, On-line Configuration
Supervisory Control Software shall utilize a configuration database to configure all dynamic control point operating parameters (such as calibrations, I/O channels, etc.).

3.2.08 Supervisory Control Software, Diagnostic Suite Definition
The Target Diagnostic Instruments Suite and setup for each instrument shall be defined via a database configuration file.

3.2.09 Supervisory Control Software, Pre-Shot Requirements
- ICCS shall provide supervisory software for integrated control of five distributed subsystems:
  - power conditioning
  - optical pulse generation
  - laser beam control, including alignment and wave front controls
  - laser beam diagnostics
  - target diagnostics
• For each subsystem, controls shall be provided to the operator that enable the following functions:
  • provide manual operator controls for installation, maintenance and problem diagnosis
  • examine the status of each controlled device
  • coordinate FEP-level machine interlocks to protect against component damage caused by improper
    operation
  • provide display of status data from auxiliary systems (gas pressures, coolant fluid flow, vacuum
    system, radiation safety monitors)
  • report events to the operator
  • display laser- and target-area equipment configuration schematically
  • report and archive equipment- and safety-interlock status
  • maintain an audit trail of operator actions and equipment responses
  • assure the orderly coordination of activities performed by different operators
  • archive beam diagnostic images as required to support damage inspection
  • support the diagnosis of failures in the software, computer systems, stored data, and network
  • archive laser performance data to facilitate performance tuning on later shots

3.2.10 Supervisory Control Software, Shot Time Requirements
• ICCS shall coordinate all subsystem activities to execute a shot under the direction of the Shot Director:
  • prepare the laser to execute a shot
  • sequence such slower control elements as are not connected to the hardware timing system
  • reduce and store laser diagnostic data in on-line database
  • collect, display, and archive data generated in a shot
  • store shot configuration as part of shot data
  • analyze laser performance and model and provide power balance feedback to the OPG
  • process selected target diagnostics data for rapid assessment of experimental results
  • analyze wavefront data
  • analyze Laser Diagnostic data

3.2.11 Software Requirements Specification (SRS)
Detailed requirements for each major element of the supervisory software shall be documented in a separate
Software Requirements Specification. The SRS shall include functional requirements for user interfaces, data
processing and archival, automatic sequencing, control system configuration, status processing, alarm processing,
and data logging and trending.

The SRS shall also include performance, persistence, concurrency, or other dynamic requirements as well as other
architectural requirements that may imply system partitioning or a particular method of implementation.

3.2.12 Supervisory Control Software, Access to Distributed Control Points
Access to all distributed control points that are integrated into the control system shall be made by Front End
Processors that implement the hardware-level interface to the control points. The FEP software shall implement
those functional requirements that are determined by requirements analysis to be allocated to the FEP layer in the
controls architecture. The requirements analysis shall be guided by the physical properties and performance
constraints of the control hardware, and by those operational scenarios requiring operation independent of the
supervisory software or local control.

A separate Software Requirements Specification (SRS) shall be provided for each FEP. These SRS documents
shall be used to further define the requirements of the supervisory software.
3.2.13 Modes of Operation, Segmented and Concurrent Operation
The Supervisory Control Software shall support several modes of operation including:
- Configuration Setup
- Preshot-alignment
- Shot Countdown
- Post-shot data collection and archival
- Post-shot data reduction and presentation
- Maintenance
- Partial laser system operation

The Supervisory Control Software shall be capable of operating the NIF in a segmented mode with the segments functioning concurrently in different configurations. As an example, a portion of the laser may be under maintenance or construction and the rest of the laser operational. The Supervisory Control Software shall support the area under construction with appropriate test sequences, diagnostics and construction debugging tools, while simultaneously supporting shot sequences on the operational segment of the laser.

3.2.14 Supervisory Control Software, Documentation and Manuals
Documentation and manuals shall be provided to:
- Train and serve as a reference for Operations Staff
- Serve as a reference for future software development staff to facilitate modifications and additions that will be required over the life of the project.

The Supervisory Control Software System shall provide sufficient documentation to comply with the NIF Quality Assurance Plan, and DOE Order 5700.6C, Quality Assurance, Criterion-4 Documents and Records, which states: "Documents shall be prepared, reviewed, approved, issued used and revised to prescribe processes, specify requirements or establish design. Records shall be specified, prepared, reviewed approved and maintained."

Examples of documents that should be controlled include drawings, data files, calculations, specifications, computer codes, purchase orders, vendor supplied documents, procedures, work records and data sheets and test records. Revisions should be reviewed by the organizations that originally prepared and approved the documents. Controlled documents should be distributed to those doing the work.

3.2.15 Lifetime, Replaceability, Reliability, Availability, Maintainability

3.2.15.1 Lifetime
Lifetime: The Supervisory Control Software shall operate for 30 years.

3.2.15.2 Replaceability
Replaceability: Any portion of the Supervisory Control Software which cannot reasonably be designed for 30 year lifetime shall be designed to be replaced or repaired at reasonable cost in a timely manner consistent with the overall availability of the System.

3.2.15.3 Reliability
Reliability: The Supervisory Control Software shall have an overall reliability of 99.70%. Reliability is defined as the probability of meeting the minimum requirements of the experiment per no-yield shot.

3.2.15.4 Availability
Availability: The Supervisory Control Software shall have a shot availability of at least 97.22%. The Supervisory Control Software is unavailable when it is undergoing unplanned maintenance. Unplanned maintenance includes failure detection and active repair as well as logistic and administrative downtimes.
3.2.15.5 Maintainability
Maintainability: The Supervisory Control Software shall have a scheduled maintenance plan that fits within an overall annual plant goal of 69 days. The unplanned maintenance goal is 7.5 days per year. Opportunistic maintenance activities are performed between shots and during other system downtimes.

3.2.16 Recovery From Abnormal Event
The time required for the Supervisory Control Software to recover from any abnormal event shall be less than the maximum times cited below, as a function of the expected yearly frequency of occurrence of the event.

<table>
<thead>
<tr>
<th>Expected Frequency of Occurrence Per Year, $F$</th>
<th>Maximum Recovery Time</th>
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<tbody>
<tr>
<td>$F \geq 1$</td>
<td>24 hours</td>
</tr>
<tr>
<td>$1 &gt; F &gt; 1e^{-2}$</td>
<td>1 week</td>
</tr>
<tr>
<td>$1e^{-2} &gt; F \geq 5e^{-4}$</td>
<td>3 months</td>
</tr>
</tbody>
</table>

Probabilities listed in DOE-STD-1020-94 shall be used for natural phenomena.

For frequent events, the maximum allowed recovery time may be restricted by availability requirements to be less than that shown in the table above.

To meet the above Maximum Recovery Time requirements, Supervisory Controls shall maintain an off-site (other than the NIF facility) backup storage facility.

3.2.17 Human Factors
The Supervisory Control Software shall be designed in an ergonometric fashion to ensure that reliability during operation and maintenance is sustained at a level consistent with meeting overall availability and reliability objectives. Consistency in displays, warnings, and human interfaces should be maintained throughout the Supervisory Control Software and, if possible, throughout the NIF facility (i.e., GUI displays, access ports, tooling).

3.4 Logistics

3.4.1 Maintenance
As a part of the design/construction project, the Supervisory Control Software shall provide all equipment required to inspect, service, and maintain all subsystems within the Supervisory Control Software to meet the maintainability and availability requirements. Maintenance equipment shall include software maintenance tools, software backup tools, etc., and other special tools not otherwise available within the NIF, that are necessary to perform any planned (scheduled or unscheduled) maintenance activity.

6.0 Revision Record

<table>
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<th>Date</th>
<th>Change by</th>
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