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Numerical solution of a tunneling equation

C. Y. Wang
M. D. Carter
D. B. Batchelor
E. F. Jaeger

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ABSTRACT

A numerical method is presented to solve mode conversion equations resulting from the use of radio frequency (rf) waves to heat plasmas. The solutions of the mode conversion equations contain exponentially growing modes, and ordinary numerical techniques give large errors. To avoid the unphysical growing modes, a set of boundary conditions are found, that eliminate the unphysical modes. The mode conversion equations are then solved with the boundary conditions as a standard two-point boundary value problem. A tunneling equation (one of the mode conversion equations without power absorption) is solved as a specific example of this numerical technique although the technique itself is very general and can be easily applied to solve any mode conversion equation. The results from our numerical calculation agree very well with those found from asymptotic analysis.

1 INTRODUCTION

In radio frequency (rf) heating of fusion plasmas, the mode conversion from an incident fast wave to ion Bernstein wave (IBW) plays an important role. The mode conversion process can be described by a fourth- or higher-order ordinary differential equation, which is called a mode conversion equation. Mode conversion equations can be solved globally by using multiple layer[1,2], finite difference[3], and finite element methods[4], or can be solved locally by using Green's function[5], shooting[6,7], mode expansion[8], and invariant imbedding methods[9]. In this paper we discuss only the numerical methods to solve the mode conversion equations locally. Mode conversion equations are very difficult to solve numerically because of exponentially growing components[10]. The idea of the Green's function method is to find a solution for simplified homogeneous equations and use it to construct integral equations.[5,11] The success of this technique depends on the numerical solutions of the homogenous equations, which are nontrivial and contain exponentially growing components too. The shooting method uses an initial value ordinary differential equation (ODE) solver to integrate mode conversion equations many times to find all independent solutions, from which transfer matrices are constructed.[7,10] A key to the success of this method is to avoid the effects from the exponentially growing components. This is done by calculating the transfer matrices at each step and stopping when the change of the parameters is small enough. If one integrates too far, the growing components will dominate the solutions and undermine the accuracy of the method. Although meaningful numerical results can be found by using this method, the method intrinsically is numerically unstable. The mode expansion method used in Ref. [8] has some arbitrariness on the effect of the exponentially growing modes, which is controlled by an input parameter. The invariant imbedding method isolates the exponentially growing mode from the other well-behaved solutions to the mode conversion equation and uses an initial value ODE solver to solve the well-behaved solutions. This method is numerically stable but difficult to set up, especially when there is more than one exponentially growing mode — for example, in a sixth-order mode conversion equation. Due to these difficulties, all these methods were used to solve a fourth-order mode conversion equation, which has only one exponentially growing mode.

In this paper, we present a finite difference method to solve the mode conversion equation. The method is numerically stable and easy to implement. As can be seen from Sec. 2, the method also gives very accurate solutions compared with analytical asymptotic analysis, whereas the results found by the other methods were not compared with those from asymptotic analysis and their accuracy is hardly known. The main idea of this technique is to first find a set of appropriate boundary conditions which force the exponentially growing modes and other unphysical modes to vanish. Then, these boundary conditions and the mode conversion equations are solved as a standard two-point boundary value problem. In this paper, we will use this method to solve a tunneling equation — one of the mode conversion equations without power absorption. However, the method itself is not limited to this case and can be used to solve any mode conversion equation. For example, a sixth-order mode conversion equation with power absorption and one more exponentially growing mode on each side of the mode conversion layer is discussed in Sec. 4.

The tunneling equation solved in this paper is

$$y^{iv} + \lambda^2 x y'' + (\lambda^2 x + \gamma)y = 0, \quad (1)$$

where $y = y(x)$, $y'' = d^2y/dx^2$, $y^{iv} = d^4y/dx^4$, and λ and γ are constant parameters. The solution for $\gamma < -1$ was analyzed by Faulconer[12]. The solution for $\gamma > -1$ was first analyzed by Erokhin[13], and later by Ngan and Swanson in applying it to the tunneling problem at the ion cyclotron harmonic.[14] The reason we choose this equation as a specific example is that its asymptotic solution for $|x| \rightarrow \infty$ is available [14,15] and can be compared with our numerical results. Although Eq. (1) has four independent solutions, in this paper we consider only a fast wave incident from $-\infty$ or $+\infty$, or a slow wave incident from $+\infty$. These solutions are the only three with physical interest, but the other solution can be found in the same fashion.

The organization of this paper is as follows. In Sec. 2 we present the numerical method to solve the tunneling equation (1). In Sec. 3 we give the numerical results and compare our results with those from asymptotic analysis. In Sec. 4 we conclude by discussing the implications of the numerical method.

2 NUMERICAL METHOD

Before we use the finite difference method to solve the tunneling equation as a two-point boundary value problem, we need to find boundary conditions that eliminate the exponentially growing mode and other unphysical modes. We first convert the fourth-order ODE (1) to a set of four first-order ODEs:

$$\frac{dy}{dx} = M \cdot y, \quad (2)$$

where $y = (y, y', y'', y''')$ and

$$M = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ (\lambda^2 x + \gamma) & 0 & -\lambda^2 x & 0 \end{bmatrix}. \quad (3)$$

The asymptotic solution for large $|x|$ can be expanded in terms of Wentzel-Kramers-Brillouin (WKB) modes. We assume that the WKB mode is

$$y = Y \exp \left[i \int^x k(x') dx' \right], \quad (4)$$

where Y is a vector with four elements and has weak dependence on x . Substituting y into the ODE (2), we obtain a characteristic equation,

$$\det(M - ikI) = 0, \quad (5)$$

where I is the 3×3 unit matrix. The characteristic equation gives four eigenvalues,

$$k = \pm \left\{ \lambda^2 x / 2 \pm \left[\lambda^4 x^2 / 4 - (\lambda^2 x + \gamma) \right]^{1/2} \right\}^{1/2}. \quad (6)$$

Each eigenvalue k has its corresponding eigenvector, $Y = [1, ik, (ik)^2, (ik)^3]$.

To clearly see the physical meaning of each WKB mode, we expand Eq. (6) for large $|x|$ although the expansion is not needed in our numerical computation. For $x \rightarrow -\infty$, we get

$$k_{1,2}^- = \pm 1 \quad (7)$$

and

$$k_{3,4}^- = \mp i\lambda|x|^{1/2}. \quad (8)$$

For $x \rightarrow +\infty$, we get

$$k_{1,2}^+ = \pm 1 \quad (9)$$

and

$$k_{3,4}^+ = \pm \lambda x^{1/2}. \quad (10)$$

The $k = 1$ mode is a fast wave traveling in the $+x$ direction, and the $k = -1$ mode is a fast wave traveling in the $-x$ direction. The k_3^- mode exponentially decays away from the mode conversion layer, and the k_4^- mode exponentially grows, which is the reason for the instability of other numerical techniques. For a physical solution, the growing mode has to be avoided for large $-x$. The k_3^+ mode represents a slow wave having positive phase velocity but negative energy flow.[15] The k_4^+ represents a slow wave having negative phase velocity but positive energy flow.

2.1 Fast wave incident from $-\infty$

For a fast wave incident from $-\infty$ k_1^- , we have a reflected fast wave k_2^- and an exponentially decaying mode k_3^- for $x \rightarrow -\infty$. For $x \rightarrow +\infty$, we have a transmitted fast wave k_1^+ and a slow wave k_4^+ .

The asymptotic solution for $x \rightarrow -\infty$ can be expanded as

$$y = \sum_{i=1}^4 C_i^- Y_i^-, \quad (11)$$

where Y_i^- are the eigenvectors corresponding to eigenvalues k_i^- and the exponential factors $\exp(i \int^x k_i^- dx')$ are absorbed into the unknown expansion coefficients C_i^- .

To eliminate the exponentially growing mode k_4^- , we simply set $C_4^- = 0$. In order for Eq. (11) to have nontrivial C_1^- , C_2^- , and C_3^- , we obtain from Eq. (11)

$$\det \begin{bmatrix} y & 1 & 1 & 1 \\ y' & ik_1^- & ik_2^- & ik_3^- \\ y'' & (ik_1^-)^2 & (ik_2^-)^2 & (ik_3^-)^2 \\ y''' & (ik_1^-)^3 & (ik_2^-)^3 & (ik_3^-)^3 \end{bmatrix} = 0, \quad (12)$$

which is a homogenous equation. The physical meaning of this condition is that the exponentially growing mode vanishes at the surface where the condition is imposed. If we can numerically satisfy the above condition, the exponentially growing mode will be avoided.

The asymptotic solution for $x \rightarrow +\infty$ can be expanded as

$$y = \sum_{i=1}^4 C_i^+ Y_i^+, \quad (13)$$

where Y_i^+ are the eigenvectors corresponding to eigenvalues k_i^+ . To eliminate the unphysical modes k_2^+ and k_3^+ (which represent a fast wave incident from $+\infty$ and a slow wave with energy flowing from $+\infty$, respectively), we set $C_2^+ = C_3^+ = 0$. In order for Eq. (13) to have nontrivial C_1^+ and C_4^+ , we obtain from Eq. (13)

$$\det \begin{bmatrix} y & 1 & 1 \\ y' & ik_1^+ & ik_4^+ \\ y'' & (ik_1^+)^2 & (ik_4^+)^2 \end{bmatrix} = 0 \quad (14)$$

and

$$\det \begin{bmatrix} y' & ik_1^+ & ik_4^+ \\ y'' & (ik_1^+)^2 & (ik_4^+)^2 \\ y''' & (ik_1^+)^3 & (ik_4^+)^3 \end{bmatrix} = 0. \quad (15)$$

The physical meaning of these two conditions is that there is no fast wave incident from $+\infty$ or no slow wave energy flowing from $+\infty$.

We solve the set of first-order ODEs (2) with the boundary conditions given by Eq. (12) at $x = x^-$, and Eqs. (14) and (15) at $x = x^+$. A normalization $y = 1$ is used at either end. This is a well-posed two-point boundary value problem: four first-order ODEs and four boundary conditions. Here, x^- and x^+ are chosen far enough from the mode conversion layer so that the asymptotic WKB expansion is valid. In our actual calculation, the eigenvalues are calculated from Eq. (6), rather than Eqs. (7)–(10), and each mode is numerically identified.

2.2 Fast wave incident from $+\infty$

For a fast wave incident from $+\infty$ k_2^+ , we have a reflected fast wave k_1^+ and a slow wave k_4^+ for $x \rightarrow +\infty$. (Actually, there is no reflected fast wave, but this fact is known only after the ODEs are solved. This fact will serve a good test for the accuracy of the numerical method.) For $x \rightarrow -\infty$, we have a transmitted fast wave k_2^- and an exponentially decaying mode k_3^- . To eliminate the fast wave k_1^- incident from $-\infty$ and the exponentially growing mode k_4^- for $x \rightarrow -\infty$, we set $C_1^- = C_4^- = 0$ in Eq. (11) and obtain

$$\det \begin{bmatrix} y & 1 & 1 \\ y' & ik_2^- & ik_3^- \\ y'' & (ik_2^-)^2 & (ik_3^-)^2 \end{bmatrix} = 0 \quad (16)$$

and

$$\det \begin{bmatrix} y' & ik_2^- & ik_3^- \\ y'' & (ik_2^-)^2 & (ik_3^-)^2 \\ y''' & (ik_2^-)^3 & (ik_3^-)^3 \end{bmatrix} = 0. \quad (17)$$

To eliminate the slow wave with energy flowing from $+\infty$, we set $C_3^+ = 0$ in Eq. (13) and have

$$\det \begin{bmatrix} y & 1 & 1 & 1 \\ y' & ik_1^+ & ik_2^+ & ik_4^+ \\ y'' & (ik_1^+)^2 & (ik_2^+)^2 & (ik_4^+)^2 \\ y''' & (ik_1^+)^3 & (ik_2^+)^3 & (ik_4^+)^3 \end{bmatrix} = 0. \quad (18)$$

Equations (16) and (17) at $x = x^-$, Eq. (18) at $x = x^+$, and a normalization $y = 1$ at either end constitute the boundary conditions for a fast wave incident from $+\infty$.

2.3 Slow wave incident from $+\infty$

For a slow wave incident from $+\infty$ k_3^+ , we have a fast wave k_1^+ from the mode conversion and a reflected slow wave k_4^+ for $x \rightarrow +\infty$. For $x \rightarrow -\infty$ we have a fast wave k_2^- from the mode conversion and an exponentially decaying mode k_3^- . To eliminate the fast wave k_1^- incident from $-\infty$ and the exponentially growing mode k_4^- for $x \rightarrow -\infty$, we set $C_1^- = C_4^- = 0$ in Eq. (11) and obtain

$$\det \begin{bmatrix} y & 1 & 1 \\ y' & ik_2^- & ik_3^- \\ y'' & (ik_2^-)^2 & (ik_3^-)^2 \end{bmatrix} = 0 \quad (19)$$

and

$$\det \begin{bmatrix} y' & ik_2^- & ik_3^- \\ y'' & (ik_2^-)^2 & (ik_3^-)^2 \\ y''' & (ik_2^-)^3 & (ik_3^-)^3 \end{bmatrix} = 0. \quad (20)$$

To eliminate the fast wave incident from $+\infty$ for $x \rightarrow +\infty$, we set $C_2^+ = 0$ in Eq. (13) and have

$$\det \begin{bmatrix} y & 1 & 1 & 1 \\ y' & ik_1^+ & ik_3^+ & ik_4^+ \\ y'' & (ik_1^+)^2 & (ik_3^+)^2 & (ik_4^+)^2 \\ y''' & (ik_1^+)^3 & (ik_3^+)^3 & (ik_4^+)^3 \end{bmatrix} = 0. \quad (21)$$

Equations (19) and (20) at $x = x^-$, Eq. (21) at $x = x^+$, and a normalization $y = 1$ at either end constitute the boundary conditions for a slow wave incident from $+\infty$.

3 NUMERICAL SOLUTION

Since this is a standard two-point value problem, we use a routine in the Numerical Algorithm Group (NAG) library, which solves a linear two-point boundary value problem for a system of ODEs using a deferred correction technique. Figure 1 shows the dispersion curves found from Eq. (6) for $\lambda = 3$ and $\gamma = 1$. The mode conversion layer is located around $x = 0$.

3.1 Fast wave incident from $-\infty$

Figure 2 shows the numerical solution with boundary conditions given by Eq. (12) imposed at $x = -10$, and by Eqs. (14) and (15) with $y = 1$ at $x = 10$. Since our solution satisfies Eqs. (12), (14) and (15), it does not contain the exponentially growing mode at large $-x$, the incident fast wave from $+\infty$, or the slow wave with energy flowing from $+\infty$.

To check the accuracy of the numerical solution, we calculate a conserved quantity for the tunneling equation (1) [15],

$$P(y) = y'''y'''' + y''''y'' - y''y'''' - \gamma y'y'' - c.c. \quad (22)$$

This conserved quantity is related to energy flux in rf heating of plasmas [15] and will be used later to define scattering coefficients. The largest relative error of P for the solution within $(-10, 10)$ shown in Fig. 2 is 3×10^{-6} .

To compare these results with the results from asymptotic analysis, we use the conserved quantity to define the transmission, reflection, and mode conversion coefficients. For a fast wave incident from $-\infty$ towards $+\infty$, we define the transmission coefficient as

$$T_p = \left| \frac{P(C_1^+ Y_1^+)}{P(C_1^- Y_1^-)} \right|^2, \quad (23)$$

the reflection coefficient as

$$R_p = \left| \frac{P(C_2^- Y_1^-)}{P(C_1^- Y_1^-)} \right|^2, \quad (24)$$

and the mode conversion coefficient as

$$C_p = \left| \frac{P(C_4^+ Y_4^+)}{P(C_1^- Y_1^-)} \right|^2, \quad (25)$$

where C_i^- and C_i^+ are defined in Eqs. (11) and (13), respectively, and can be found after the ODEs are solved. Using the asymptotic solutions in Ref. [15], we find that our definitions of T_p , R_p , and C_p are related to T , R and C in Ref. [15] by $T_p = T^2$, $R_p = R^2$, and $C_p = \rho C^2$, where $\rho = (1 - e^{-2\eta})^{-1}$ and $\eta = \pi(1 + \gamma)/2\lambda^2$ is called the tunneling factor. Our definitions have the advantage of being independent of the specific WKB mode normalization and are easy to implement in the numerical computation for solutions in a finite domain. Equation (22) implies [15]

$$T_p + R_p + C_p = 1. \quad (26)$$

For the solution shown in Fig. 2, we have $T_p = 49.74\%$, $R_p = 25.22\%$, and $C_p = 25.04\%$. As another check of the numerical accuracy, the sum of T_p , R_p , and C_p differs from unity by 2×10^{-6} . From the asymptotic analysis in Ref. [15], $T_p = e^{-2\eta} = 49.75\%$, $R_p = (1 - e^{-2\eta})^2 = 25.25\%$, and $C_p = e^{-2\eta}(1 - e^{-2\eta}) = 25.00\%$. We can see that our numerical results agree with those from the asymptotic analysis very well.

3.2 Fast wave incident from $+\infty$

For a fast wave incident from $+\infty$, we solve the ODEs given by Eq. (2) with boundary conditions given by Eqs. (16) and (17) at $x = -10$, and by Eq. (18) and $y = 1$ at $x = 10$. The solution is shown in Fig. 3. The largest relative error of the conserved quantity P defined in Eq. (22) is 8×10^{-6} . Now the transmission, the reflection, and the mode conversion coefficients are defined as

$$T_p = \left| \frac{P(C_2^- Y_2^-)}{P(C_2^+ Y_2^+)} \right|^2, \quad (27)$$

$$R_p = \left| \frac{P(C_1^+ Y_1^+)}{P(C_2^+ Y_2^+)} \right|^2, \quad (28)$$

$$C_p = \left| \frac{P(C_4^+ Y_4^+)}{P(C_2^+ Y_2^+)} \right|^2. \quad (29)$$

The numerical results of these coefficients for the solution shown in Fig. 3 are $T_p = 49.74\%$, $R_p = 1.2 \times 10^{-6}$, and $C_p = 50.26\%$. The sum of T_p , R_p , and C_p differs from unity by 4×10^{-6} . From the asymptotic analysis in Ref. [15], $T_p = e^{-2\eta} = 49.75\%$, $R_p = 0$, and $C_p = 1 - e^{-2\eta} = 50.25\%$. Note that the boundary condition given by Eq. (18) allows the presence of the reflected fast wave, but, as expected from asymptotic analysis[15], the solution of the ODEs does not contain the reflected fast wave. This provides another demonstration of the accuracy of the numerical method.

3.3 Slow wave incident from $+\infty$

For a slow wave incident from $+\infty$, we solve the ODEs given by Eq. (2) with Eqs. (19) and (20) for boundary conditions at $x = -10$. Equation (21) and $y = 1$ are used for boundary conditions at $x = 10$. The solution is shown in Fig. 4. The largest relative error of the conserved quantity P defined in Eq. (22) is 2.3×10^{-5} . The coefficients for the mode conversion to a fast wave traveling towards $-\infty$, the slow wave reflection, and the mode conversion to a fast wave traveling towards $+\infty$ are defined as

$$C_p^- = \left| \frac{P(C_2^- Y_2^-)}{P(C_3^+ Y_3^+)} \right|^2, \quad (30)$$

$$R_p = \left| \frac{P(C_4^+ Y_4^+)}{P(C_3^+ Y_3^+)} \right|^2, \quad (31)$$

$$C_p^+ = \left| \frac{P(C_1^+ Y_1^+)}{P(C_3^+ Y_3^+)} \right|^2. \quad (32)$$

The numerical results of these coefficients for the solution shown in Fig. 4 are $C_p^+ = 25.04\%$, $R_p = 24.70\%$, and $C_p^- = 50.26\%$. The sum of C_p^- , R_p , and C_p^+ differs from unity by 6×10^{-6} . The solution from the asymptotic analysis in Ref. [15] is $C_p^- = e^{-2\eta}(1 - e^{-2\eta}) = 25.00\%$, $R_p = e^{-4\eta} = 24.75\%$, and $C_p^+ = 1 - e^{-2\eta} = 50.25\%$.

4 CONCLUSION

In this paper we demonstrate that a finite difference method can be used to solve a mode conversion equation without the difficulty of exponentially growing modes associated with other techniques. This numerical method is quite general and can be applied to solve any mode conversion equation provided appropriate boundary conditions can be found to eliminate unphysical components of the solutions. The ODEs can then be easily solved by using a standard two-point boundary value solver. This technique has also been successfully applied to solve a sixth-order mode conversion equation with power absorption. The sixth-order equation has one more exponentially growing mode on each side of the mode conversion layer compared with the fourth-order tunneling equation (1). These results will be reported in a future publication.

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Figure 1: The dispersion curves for the tunneling equation (1) with $\lambda = 3$ and $\gamma = 1$. The solid and dashed lines represent the real and imaginary parts, respectively, of k^2 .

Figure 2: The numerical solution for the tunneling equation (1) with $\lambda = 3$ and $\gamma = 1$, and a fast wave incident from $-\infty$: (a) y vs x , (b) y' vs x , (c) y'' vs x , and (d) y''' vs x . The solid lines are real parts, and the dotted lines are imaginary parts.

Figure 3: The numerical solution for the tunneling equation (1) with $\lambda = 3$ and $\gamma = 1$, and a fast wave incident from $+\infty$: (a) y vs x , (b) y' vs x , (c) y'' vs x , and (d) y''' vs x . The solid lines are real parts and the dotted lines are imaginary parts.

Figure 4: The numerical solution for the tunneling equation (1) with $\lambda = 3$ and $\gamma = 1$, and a slow wave incident from $+\infty$: (a) y vs x , (b) y' vs x , (c) y'' vs x , and (d) y''' vs x . The solid lines are real parts and the dotted lines are imaginary parts.

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84. O. Pavlichenko, Kharkov Physical-Technical Institute, Academical St. 1, 310108 Kharkov, Ukraine
85. Deputy Director, Southwestern Institute of Physics, P.O. Box 15, Leshan, Sichuan, China (PRC)
86. Director, The Institute of Plasma Physics, P.O. Box 1126, Hefei, Anhui, China (PRC)
87. R. H. McKnight, Experimental Plasma Research Branch, Division of Development and Technology, Office of Fusion Energy, Office of Energy Research, ER-542 Germantown, U.S. Department of Energy, Washington, DC 20545
88. D. Crandall, Director, Division of Applied Plasma Physics, Office of Fusion Energy, Office of Energy Research, ER-54 Germantown, U.S. Department of Energy, Washington, DC 20545

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103. Theory Department Read File, c/o T. Kamimura, National Institute for Fusion Studies, Nagoya 464, Japan
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114. M. Ballico, Max-Planck Institut für Plasmaphysik, Boltzmannstrasse 2, D-8046 Garching, Federal Republic of Germany
115. E. Barbato, Associazione EURATOM-ENEA sulla Fusione, Centro Ricerca Energia Frascati, C.P. 65, I-00044 Frascati (Roma), Italy
116. A. Bécoulet, Association EURATOM-CEA sur la Fusion Controlée, Centre d'Etudes Nucléaires de Cadarache, B. P. No. 1, F-13108 Saint Paul lez Durances, France

117. S. Bernabei, Plasma Physics Laboratory, Princeton University, P.O. Box 451, Princeton, NJ 08543
118. A. Bers, Plasma Fusion Center, Massachusetts Institute of Technology, 38-260, Cambridge, MA 02139
119. V. Bhatnagar, JET Joint Undertaking, Abingdon, Oxfordshire OX14 3EA, England
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121. M. Brambilla, Max-Planck Institut für Plasmaphysik, Boltzmannstrasse 2, D-8046 Garching, Federal Republic of Germany
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