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CAMPAIGN

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# Final Report of the Mexico City 1991 Lidar Measurements Campaign\*\*

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## **Foreword**

The authorship shown in this project report reflects the Los Alamos National Laboratory lidar personnel that contributed significantly to the development, preparation, and execution of the 1991 Mexico City lidar measurements campaign. The data presented here was processed, analyzed and interpreted by the principal author (C. R. Quick, Jr.). The views and opinions expressed here, are not necessarily those of other Los Alamos lidar personnel. Any errors or omissions are the responsibility of the primary author. Any questions regarding the data and its interpretation should be addressed to the primary author.

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## **Introduction**

Over the last two decades, Mexico City, like many large industrial and populous urban areas, has developed a serious air pollution problem, especially during the winter months when there are frequent temperature inversions and weak winds. The deterioration in air quality is the result of several factors. The basin within which Mexico City lies is Mexico's center of political, administrative and economic activity, generating 34% of the gross domestic product and 42% of the industrial revenue, and supporting a population which is rapidly approaching the 20 million mark. The basin is surrounded by mountains on three sides which inhibit rapid dispersal of pollutants. Emissions from the transportation fleet (more than 3 million vehicles) are one of the primary pollution sources, and are mostly uncontrolled. Catalytic converters are just now being introduced into the fleet.

The Mexico City Air Quality Research Initiative is an international collaborative project between the Los Alamos National Laboratory and the Mexican Petroleum Institute dedicated to the investigation of the air quality problem in Mexico City. The main objective of the project is to identify and assess the cost and benefits of major options being proposed to improve the air quality. The project is organized into three main activity areas:

**Task 1 : Modeling and simulation**

**Task 2 : Characterization and Measurements**

**Task 3 : Strategic Evaluation**

**Task 1** is concerned with the development and adaptation of computer codes that will model the basic meteorology of the Mexico City basin (3-dimensional, time-dependent calculations of the wind and temperature fields), the pollutant transport and dispersion over and beyond the urban terrain, and the photochemistry. Ultimately, the models will be used to make predictions of the effect that various mitigation strategies would have on the spatial and temporal variations of selected air quality

parameters, such as ozone, carbon monoxide, nitrogen oxides, and visibility levels.

Task 2 is charged with characterizing the meteorology and ambient air quality with appropriate measurement and data gathering efforts. The data obtained will be used to validate the performance of the atmospheric models being developed.

Task 3 will provide socioeconomic analyses of proposed air quality improvement strategies using the atmospheric model predictions of the effect on the selected air quality parameters.

In February of 1991, a major measurements campaign was carried out in an attempt to gather sufficient information to allow a basic understanding of the meteorological processes that dominate the behavior of the atmosphere above the valley in which Mexico City is located. The campaign involved approximately 100 investigators from Mexico and the US. In addition to standard EPA ground based instrumentation designed to measure the concentration of major pollutants, numerous advanced measurement techniques were utilized, including a fully instrumented aircraft laboratory, a real-time infrared vehicle emission monitor, a mobile lidar system for aerosol characterization, a mobile lidar for SO<sub>2</sub> measurements, tethered sonde instrumentation, time lapse photography, satellite imagery, rawinsonde monitoring, solar radiation monitors, particle-induced x-ray elemental analysis of aerosol particles, a cloud ceilometer, and GC/MS analysis of hydrocarbon samples.

The focus of this report is on the data obtained with the Los Alamos lidar system designed to examine the spatial and temporal distribution of aerosol particles present during high air pollution periods. The main objectives of the lidar measurements were to characterize the mixing-layer, its height, texture and breakup, the manner in which plumes are transported and dispersed, and to obtain information regarding the atmospheric opacity.

A mobile lidar system designed to characterize the spatial and temporal variation of the concentration of atmospheric aerosol particles over kilometer scale distances was deployed at three different locations within the Mexico City basin over a period of two weeks in February of 1991. The vertical distribution of aerosols was examined many times an hour over a period of several days at each location. The vertical scans



showed complicated atmospheric layering as well as systematic temporal variations. Occasional horizontal scans were also taken, revealing the location of major aerosol sources such as glass manufacturing, steel making operations, and major highways, as well as minor sources such as roads, burning refuse and restaurant activity. A few three-dimensional volume scans of the atmospheric aerosol were also carried out.

## **Lidar Technique**

In the lidar experimental technique shown schematically in Fig. 1, a laser is used to generate a pulse of light that is launched into the atmosphere in a predetermined direction. As the pulse of light propagates through the air, it is scattered in all directions, primarily by aerosol particles within its path. A small fraction of this scattered light travels back towards the laser source where it is collected with a large telescope and measured with a photodetector. The photodetector signal is proportional to the volume backscattering coefficient of the aerosol particles. In general, the volume backscattering coefficient is a function of the aerosol particle chemical composition, size, and shape. The time it takes the backscattered photons to arrive back at the light source determines the distance to the aerosol scatterers. By making angular scans (vertical and horizontal) of the laser/telescope direction, the spatial variation of aerosol concentration can be mapped out (in 1-, 2- or 3-dimensions) over kilometer distances, with a few meters resolution, in a few minutes.

## **Lidar System Description**

A photograph of the mobile lidar system used in Mexico City is shown in Fig. 2. Briefly, a Nd:YAG laser operating at  $1.06 \mu\text{m}$ , 10 pulses-per-second, 1 mrad divergence is located within the vehicle (step-van). The energy-per-pulse was adjusted to be 30-50 mJ so as to minimize the nominal optical hazard distance (less than 2 km). The laser beam is made parallel, with a Coude' system, to the optical axis of a 16" diameter, f/8

telescope that is mounted on top of the step-van. The laser/telescope assembly is moved under computer (ALR 486 PC) control in discrete angular steps to execute vertical (see Fig. 3), horizontal, or combination scans of the atmosphere. Laser photons scattered backwards towards the lidar by the atmospheric aerosol particles are collected by the telescope and focused onto a silicon avalanche photodiode (APD) mounted on the back of the telescope. A 3-nm bandpass filter was used to block out solar background. The APD/filter combination allowed night and day operation. A light-funnel assembly, consisting of a tapered cone, was used to increase the telescope field-of-view to approximately 3 mrad. Signals from the APD (10-MHz frequency response) were transmitted through a fiber optic cable/receiver system to a CAMAC-based digital transient waveform recorder (LeCroy TR8818, 8 bit) sampling at 100-MHz. A PC computer running a turbo-Pascal data acquisition program was used to store, display and analyze the digitized data waveforms. Typically 10 laser shots (1 sec) were averaged together at each scan angle and stored to disk (0.5 sec). Several types of scans were taken: vertical, horizontal, 3-dimensional, and time-domain. For vertical scans, the laser/telescope elevation angle was increased while holding the azimuth angle constant. For horizontal scans, the azimuth angle was varied while holding the elevation angle constant. The laser beam/telescope are defined as having an  $Az=90^\circ$  when they are aimed directly away from the back end of and parallel to the length of the truck.  $Az=0^\circ$  ( $180^\circ$ ) corresponds to the left (right) hand side of the truck looking from the front towards the back. For 3-dimensional scans both the elevation and azimuth angles were varied according to a predetermined pattern. For time-domain scans, both elevation and azimuth angles are held constant, and the computer stores the average result of a selected number of shots, repeating this procedure a predetermined number of times, one right after the other. The usual time required to complete a vertical or horizontal scan varied from 1-5 minutes depending on the number of angles in the scan and the number of laser shots per angle.

### **Measurement Locations**

The Los Alamos lidar was located at three different sites:

### 1) Thermo-electric power plant (Feb. 16-18)

The power plant is located northeast of city center at about  $98^{\circ} 58' 18''$  longitude and  $19^{\circ} 37'$  latitude, at an elevation of approximately 2240-m above sea level. The Los Alamos tethersonde was located within 100-m of the lidar truck, approximately due west. The site was approximately 29 km from the airport. During the 16th & 17th, the lidar truck was aligned so that its  $Az=90^{\circ}$  corresponded to  $276^{\circ}$  magnetic north or  $284^{\circ}$  true north, and approximately directly over the tethersonde location. After 1:15 pm on the 17th, the lidar truck was turned around, so that its  $Az=90^{\circ}$  corresponded to  $92^{\circ}$  magnetic north or approximately  $100^{\circ}$  true north. The  $SO_2$  lidar from the Institute for Electrical Investigations was co-located with the LANL lidar. Available power was such that either the  $SO_2$  lidar or the aerosol lidar could operate. Figs. 4 & 5 indicate the approximate position of the lidar truck on a city street map for the two predominant scan directions. The lidar  $Az=90^{\circ}$  direction turned out to be very close to the direction in which several large cooling towers were present. The cooling towers produced, at periodic time intervals, large concentrations of water vapor aerosols which formed plumes that were often too thick to allow passage of the laser light when at low elevation angles.

### 2) CINVESTAV (Feb. 19-23)

The Centro de Investigacion y Estudios Avanzados (CINVESTAV) is located north of city center at about  $99^{\circ} 7' 42''$  longitude and  $19^{\circ} 30' 35''$  latitude, at an elevation of approximately 2240-m above sea level, about 1-km northeast of the Polytechnic Institute soccer stadium where the tethersonde was located. The site was approximately 13 km from the airport. For Feb. 19-22, the lidar truck was oriented such that its  $Az=90^{\circ}$  pointed directly towards the tethersonde location, which corresponded to approximately  $211^{\circ}$  magnetic or  $219^{\circ}$  true north. On Feb. 23, the lidar truck was turned around to face almost due north so that its  $Az=90^{\circ}$  corresponded to  $349^{\circ}$  magnetic or  $357^{\circ}$  true north. Figs. 6 & 7 show the approximate lidar truck locations on a city street map.

### 3) UNAM Botanical Gardens (Feb. 25 - Mar. 1)

The UNAM botanical gardens site is located southwest of city center at about  $99^{\circ} 11' 42''$  longitude and  $19^{\circ} 18' 56''$  latitude, at an elevation of approximately 2320-m above sea level, or about 80-100 m above city center. The site was approximately 24 km from the airport. The lidar truck was oriented such that its  $Az=90^{\circ}$  corresponded to approximately  $32^{\circ}$  magnetic or  $40^{\circ}$  true north. At this time the tether sonde was located at a site in Xochimilco, south of the city. Given the elevation at this site, lidar data taken at an elevation angle of  $0^{\circ}$  actually monitors aerosol particles at a variety of altitudes on range and direction (up-slope, down-slope, etc.). Fig. 8 shows the approximate location of the lidar truck on a city map.

### Data Log Summary

A log detailing the main parameters of all the stored data files is included as Appendix A. The data log indicates the date and time the data was taken, the scan type, the number of shots averaged, the azimuth angle with respect to the lidar truck, the azimuth angle with respect to true north, the elevation angle, the avalanche photodiode detector (APD) voltage, the amount of attenuation in the signal chain, and whether or not a 10 MHz filter was being used. The APD voltage shown does not correspond exactly to the voltage on the APD detector itself because of the temperature compensation circuit employed which attempts to maintain a constant APD gain. True APD voltages are probably 30-40 V lower than indicated in the bias column. There are hard copies of most data files except for the time-domain scans and some of the 3-dimensional scans. The APD detectivity vs bias voltage is shown in Appendix B.

### Data Analysis Strategy

Only a few of the days during which lidar data was gathered were examined in detail. The selection process was based primarily on two factors : good data overlap between all the instruments deployed in the

campaign (NCAR aircraft, satellite, lidar, tethered sonde, etc.) and air quality index (IMECA) levels for ozone, as measured by the SEDUE (Mexico's equivalent to U.S. EPA) ground-based grid monitors. February 17 was selected on the basis of it being a "normal" day, with a typical  $O_3$  concentration ( $IMECA_{max} = 147$ , NW sector). February 22 was selected due to the fact that it was the highest ozone level observed during the two-week measurements period ( $IMECA_{max} = 280$ , SW sector). The February 26-28 period was selected because it exhibited a change in the typical spatial distribution pattern, evolving from high concentrations in the southwest on the 26<sup>th</sup> to high concentrations in the northeast on the 28<sup>th</sup>.

### **Lidar Data Plot Generation Procedures**

The limited amount of analysis time available combined with the sheer volume of lidar data obtained and the immediately available image processing technology dictated that the data be processed in a simple manner. The data display procedures followed occasionally led to unusual plots. Two of the more noticeable effects to be described in this section are connected with atmospheric extinction, which is normally not removed from the data, and the occasional presence of clouds in the atmosphere.

The data analysis procedures used to generate the 2-D color plots were as follows. As the 2-D raw data files (stored on optical disks) were read into the computer, the data analysis program calculated the zero-signal baseline associated with each angle trace by taking the average value of a pre-selected portion of the signal curve, typically the last few hundred range bins, where the aerosol return signal had fallen into the noise. This baseline value is subtracted from each data point in the corresponding trace to produce signals that start and end at 0 digitizer counts (0 mV). Each data point was then multiplied by the square of its corresponding range value (in meters) to remove the  $1/r^2$  fall-off character of lidar return signals (see section below). The resulting 2-D data file was then plotted in color where the amplitude of the range corrected signal assumed one of 16 possible colors. In other words, whatever the range of lidar return signal, for plotting purposes the signal is broken down into 16 levels only. This

has the effect of greatly reducing the spatial resolution of the plotted data, and can produce a staircase appearance in the plots as one color changes into another. To allow different regions within the scanned volume to be displayed with high contrast, the plotting program can adjust the "exposure" level so that a selected range of signal level uses the entire range of available colors. Normally, the portion of the signal that is greater than the maximum value selected is set to the lowest possible value in the color scale (the color scheme rolls over). In the 2-D plots contained within this report, these over-exposed regions show up as white areas.

The radial features which originate at zero range and continue for several hundred meters (up to 1 km depending on APD detector bias voltage) represent the rising part of the lidar return signal and is due to an instrumental artifact related to the manner in which the laser beam enters the field-of-view of the telescope. It is normally not used in analysis.

Plots were also made of selected individual data traces that make up the complete 2-D scans. In these plots, the lidar return signal at a particular elevation angle is extracted from the 2-D files and plotted separately. Normally the data shown represents the average of a given number of laser shots (usually 10 or 50), and the individual traces are subjected to a 10 range bin average smoothing routine. The data is corrected for  $1/r^2$  fall off but not for atmospheric extinction. The rising part of the signal does not indicate a low concentration of aerosols but rather reflects the previously discussed laser/telescope field-of-view overlap. Although the rising part is not normally used in data analysis, it can reveal the presence of sharp, well defined atmospheric layers.

The fact that atmospheric extinction has not been removed from the data leads to several systematic effects in the plots. Extinction will cause the range corrected lidar return signal to diminish with range and so, in general, there will tend to be a bias in the color plot in which the near regions appear to contain a higher concentration of aerosols than the far regions. The effects of atmospheric extinction, random and systematic noise on the lidar data plots are discussed in more detail in Appendix C.

## **Lidar Data Examples**

### **1) Individual angle data**

Fig. 9 shows an example of a lidar return signal taken at a  $30^\circ$  elevation angle at the UNAM site at approximately 7:55 am. This trace is one of many that make up the complete scan (vertical in this case). The data is the average of 50 laser shots, and the resulting data file was subjected to a 10 point smoothing routine. The rising part of the signal (up to about 400 m in this example) does not indicate a low concentration of aerosols but rather reflects an instrumental characteristic related to how the laser beam enters the field-of-view of the telescope. This particular example shows that there are two strong gradients in aerosol concentration: one at an altitude of about 450 m, and a second transition at about 1.9 km.

## 2) Vertical and horizontal scans

An example of a vertical scan taken at the thermo-electric power plant site is shown in Fig. 10. It is made up of an angular sequence of 96 traces. The color bar indicates approximately the relative concentration of aerosol particles (in arbitrary units). The scan shows the strong atmospheric stratification that is occurring at this particular time. Many layers or bands of aerosol particles are visible. The area within the first few hundred meters that shows as white is actually an "overexposed" area, where the signal levels exceed the range indicated in the color bar. Close examination of this area shows that there is a strong gradient in aerosol concentration occurring at an altitude of 200-300 m, most likely due to a thermal inversion. The height of this low-lying layer will be the altitude to which air pollutants can disperse, until later in the morning when the thermal inversion dissipates.

The variation in mixing layer height and texture is illustrated in Fig. 11 and 12. Fig. 11 is an example of a vertical scan taken at about 7:21 am at the CINVESTAV site that shows the height of the mixing layer as being approximately 225 m. By 10:47 am, Fig. 12 shows the mixing layer has become extremely convoluted, reaching altitudes as high as 900-1000 m.

An example of a horizontal scan taken at the CINVESTAV site is shown in Fig. 13. Overlaying this scan on a city map showed that the bright plumes observed here (shown in white and red) are connected with activities at a glass manufacturing plant and a steel making operation. This

scan illustrates the lidar system's ability to pinpoint, locate, and identify the sources of atmospheric aerosols.

Fig. 14 shows an example of a vertical scan taken at the UNAM botanical gardens site. Huge plumes are seen rising from the city at specific locations. At this time of day, aerosols released into the atmosphere can be lofted up towards the top of the mix-layer which is at about 2.5 km. Note the structure in the elevated boundary layer compared to the relatively flat case in Fig. 10. The plume between 2 and 3 km away may be associated with a major highway in the area. Clean cool air from above can be seen mixing with the polluted air below. The aerosol patterns give the impression that wind circulation is occurring.

## Data Compilations

To provide a readily available temporal record of the variation of lidar aerosol return signals, single angle data was extracted from each of the vertical scans. Typically, 10°, 30°, and 50° or 0°, 10°, and 30° data were extracted, corrected for  $1/r^2$  fall-off, corrected for angle so as to show altitude above ground (except for 0° data), and plotted out. The 10° data is most useful for examining the behavior of aerosol layers close to the ground, especially in the early morning hours when thermal inversions often occur close to the ground. However, the 10° data are also the most affected by atmospheric extinction effects, as the beam traverses a much larger distance to get to the same altitude compared to the 30° or 50° data. The 30° and 50° data are most useful to see the distribution of aerosols to the top of the planetary boundary layer (typically 2-3 km). The 0° data is most useful to obtain atmospheric extinction information. The plots of most of the data files taken the selected days are available in a separate binder. This data-compilation binder also includes a selected subset of the vertical scan color plots. The vertical scan plots are most useful to examine the height, structure and texture of the aerosol layers. Some of the effects of systematic and random noise on the data plots are discussed in appendix C.



## Interpretation of Lidar Data

An approximate, simplified formula for the signal vs range observed by the 1.06  $\mu\text{m}$  elastic scattering system is:

$$S(r) = C G(r) \beta(r) T(r) / r^2$$

where

- $S(r)$  = signal level detected at a range  $r$
- $C$  = instrumental system constant
- $G(r)$  = geometrical overlap factor
- $\beta(r)$  = volume backscattering coefficient
- $T(r)$  = round-trip atmospheric transmission at 1.06  $\mu\text{m}$ .

The instrumental system constant,  $C$ , includes such factors as the telescope transmission efficiency, APD gain and efficiency, laser pulse energy and width, signal attenuation, filter transmission, etc. The geometrical overlap factor,  $G(r)$ , attempts to describe the manner in which the laser beam, with its associated divergence, gradually enters the telescope's field-of-view (FOV) with range. It is a measure of the fractional laser energy within the FOV and approaches a constant in the telescope's far field region (constant = 1 if laser beam entirely within telescope FOV). The volume backscattering coefficient,  $\beta(r)$ , is proportional to the number of photons scattered backwards from the incident laser pulse by the aerosol particles located at range  $r$ . In general,  $\beta(r)$  depends not only on the concentration of aerosol particles but on the chemical composition, shape, and size distribution. The atmospheric transmission factor,  $T(r)$ , reflects the round-trip atmospheric attenuation at 1.06  $\mu\text{m}$  of the outgoing laser beam as it propagates out to range  $r$ , and of the backscattered photons as they propagate from range  $r$  back towards the telescope.  $T(r)$  is usually represented in terms of Beer's law as :

$$T(r) = \exp \left\{ - 2 \int_0^r \sigma(r') dr' \right\}$$

where  $\sigma(r)$  is the extinction coefficient at range  $r$ . Finally, the  $r^2$  term represents the decrease with range of the backscatter solid angle subtended by the telescope. The lidar data described in this report are presented as  $r^2 S(r)$ , thus effectively removing the  $r^2$  behavior.

The interpretation of data obtained with this particular lidar system configuration is complicated by two fundamental uncertainties :

- 1) changes in particle chemical composition, shape, and size distributions with range and/or altitude
- 2) uncertainty in the relationship between the volume backscattering coefficient and associated extinction coefficient, partly due to 1) above.

There are many reasons why changes in particle chemical composition, shape, and size distributions can occur : the laser beam passes through a plume associated with a particular type of aerosol source, the size of the aerosol particle changes with altitude as it picks up moisture from the atmosphere, etc. The current lidar data set cannot provide an independent measure of these effects.

$\beta(r)$  and  $\sigma(r)$  are a manifestation of the same physical process (photon scattering) and are thus related to each other. The relationship is affected by such factors as the shape of the particle and the complex index of refraction. A common assumption concerning the relationship between  $\beta(r)$  and  $\sigma(r)$  used to interpret lidar data consists of letting  $\beta(r)$  be directly proportional to  $\sigma(r)$

Given the rather complicated nature of aerosol sources and structures in a highly polluted urban environment, the lack of accurate data concerning the instrumental constant, and the fundamental difficulties mentioned in 1) and 2) above, it has not been possible at the time of this writing to accurately and reliably remove the effects of atmospheric extinction from the bulk of the data, except in the selected cases described in the atmospheric extinction section later in this document.

Qualitatively, atmospheric attenuation in the lidar data presented here manifests itself in various ways. In the extracted single angle data files, extinction causes a systematic decrease in the observed range-corrected signal return. However, it is sometimes rather difficult to decide whether a particular decrease in signal is due to atmospheric attenuation being high or is due simply to a decreasing concentration of aerosols with

range. Given the range of visibility normally encountered during the measurements (extinction coefficients in the range of  $0.1-0.5 \text{ km}^{-1}$ ), it is fairly safe to assume that most of the time, the abrupt changes (sharp gradients within a few hundred meters) in signal indicate a rapid reduction of aerosol particle concentration, and are a good measure of the height of a layer.

A great deal of care must be taken when interpreting the extracted single angle data. Single line-of-sight data can be easily misleading due to the presence of highly localized aerosol structures such as plumes. For example, a scan at  $10^\circ$  might exhibit an abrupt transition at a particular elevation which is not due to a large scale atmospheric layering phenomenon but rather to the laser beam exiting a fairly well defined plume. Interpretation of the single angle data should always be verified by comparison with the two-dimensional scans which can help distinguish between a localized feature and larger scale (several km's) phenomena.

Examples of some of the effects described above on the visual appearance of the data plots are presented and discussed in appendix C.

### **Height of the Mixing-Layer as Derived From Lidar Data**

Of primary concern to the atmospheric models attempting to describe the air pollution in an urban area is the height of the mixing-layer (ML): the height to which contaminants produced by activity on the surface can be dispersed via turbulent mixing. The height of the ML deduced from the lidar data will be discussed in this section.

The use of lidars to determine the height of the mixing-layer has been demonstrated and discussed before by several investigators.<sup>1-9</sup> Essentially, atmospheric conditions such as temperature inversions can greatly inhibit the upward movement of particles and other air pollutants, leading to a sharp gradient in their concentration vs altitude. In general, lidars are expected to give good measurements of the mixing height except in cases where there are not enough particles to give a good return, there is not enough optical contrast in the spatial distribution of particles, or there has not been enough time since the onset of a temperature inversion to allow the aerosols to accumulate or become stratified. Comparisons to

sodar, microwave radar, meteorological tower and radiosonde (rawinsonde) instrumentation have been carried out.<sup>3,5,6,9</sup> Lidar data has been shown to give good measurements of the ML height, although there can be significant, sometimes systematic differences with other instrumentation. The accuracy of the lidar measurements as compared to other instrumentation is often dependent on the definition of the mix-layer height used in the analysis. Different investigators have historically used somewhat varying definitions, probably influenced by the characteristics of the instrumentation being used at the time. For a discussion of the differences in mixing-layer height determination by a variety of instruments see Kaimal, et al.<sup>6</sup>

Lidar data itself has been interpreted using a variety of definitions for the mixing height depending on the atmospheric conditions present during the measurement. In geographical areas with low aerosol concentrations, lidar return signals tend to show a peak at the base of the capping inversion.<sup>6</sup> In urban areas with high aerosol concentrations, the backscatter signal is expected to decrease suddenly above the mixing height, and the altitude at which the maximum negative gradient occurs has been taken as the inversion base.<sup>6</sup> Both of these definitions suffer from the fact that late in the morning, when turbulent convective cells or plumes begin to rise, the surface that describes the mixing height over a given geographical area (several km in dimension) becomes very irregular. Warm dirty air from below becomes entrained with cold clean air from above and thus, a single lidar return signal, obtained at a particular azimuth and elevation angle, will give an answer that can vary over a wide range depending on whether the laser beam happens to exit through the highest point of the convective plume or between plumes. More recently, Boers et al.<sup>8</sup> have determined mixing height from 2-dimensional lidar scans where the azimuth is held constant while the elevation angle is varied in small steps over a given range of angles as was done in the Mexico City field campaign. Boers, et al.<sup>8</sup> interpreted the lidar backscatter signals following the work of Deardorff et al.<sup>10</sup>, who define the mean mixing height as the level at which 50% of the horizontal area exhibits the signal level of the clear air region above. Excellent agreement was found between the lidar mean mixing height and the values obtained from balloon and kytoon temperature soundings (correlation coefficient of 0.99). An example of

this technique as applied to the Mexico City data is shown in Fig. 15. The entrainment zone, defined as the difference between the height reached by only the most vigorous of convective cells and the height below which the mixed layer air covers 90-95% of the total possible area<sup>8</sup>, and the mean mixing height were visually estimated in this example. Even this last definition of mixing height can be very difficult to apply accurately to the lidar data obtained in Mexico City.

In general, the color 2-D elevation angle scans combined with the single angle extracted data plots will be used to make visual estimates of the mixing heights. In the early morning hours, when the atmosphere is highly stratified, the maximum gradient in the color plots will be used as the measure of mixing height. Later in the day, when the mixing-layer surface becomes convoluted, the mean mixing height definition described above will be the basis of the height estimate. Individual angle data can be very misleading, primarily because of its spatially localized nature which makes it difficult to distinguish true large-scale features from isolated events due to localized structures. It must be kept in mind that because of the limited field-of-view available at some of the sites, the lidar system cannot clearly see aerosol structures below heights of about 100 m.

Estimates of the ML height as a function of time will be given in tabular form. Also included in the tables will be the height of a second atmospheric boundary level that is commonly observed in the lidar data at all the sites monitored. This second boundary level correlates well with upper level temperature inversions seen by the rawinsondes (see rawinsonde section below) and undergoes substantial diurnal variations. It is also the height to which particles can rise after the low level inversion rises and dissipates.

Examination of a subset of the entire sequence of 2-D elevation angle scans together with the extracted angle data yields the following tables showing the lidar estimate of the mixing-layer height. For these tables, when two low lying features occur, both will be indicated. The height of the elevated boundary level (discussed above) is shown as well.

**February 17**

On February 17, the lidar system was located at the thermo-electric power plant site, which in retrospect is not a good site for ML height measurements. The presence of nearby large cooling towers and stacks creates substantial difficulty in the interpretation of lidar data in terms of ML heights. Hot air plumes can easily be lofted above low lying thermal inversion layers. Some of the scans clearly show a plume rising to 800 m in the middle of the night, apparently feeding aerosols into several layers along the way (see 17feb80.2d in data compilation). It is often not clear whether a sharp decrease in signal is due to a large-scale ML phenomenon or due to a plume of finite extent that happens to be at a given altitude at the time of the scan (this is especially true when looking at the single angle extracted data plots). The 2-D elevation angle scans taken during the early morning hours of the 17th show a highly stratified atmosphere with a great many aerosol layers or bands. When the towers are running at a greatly reduced output, a group of two or more layers within the first 75-300 m of altitude can be seen. It is not clear whether it is only the lowest of the layers that is defining the height to which freshly generated particles and other pollutants can rise, or whether it is the topmost layer in the group that represents the true limit.

Time of Day	Estimate of mixing-layer height (m)	elevated boundary level (m)
2:28 am	250	2400
3:05 am	200	2000
6:47 am	100, 300	2000
7:55 am	125, 300	1950
9:18 am	300	1700
1:06 pm	1800	1800
8:18 pm		3100
10:22 pm		2800

No lidar data is available between 1 and 8 pm due to a power failure at the thermoelectric plant. The temperature profiles measured by the

tethersonde instrument indicated surface radiation inversions below 100 m in the early morning hours.

### February 22

On February 22 the lidar system was located at the CINVESTAV site. The early morning hours of February 22 are characterized by a very strong gradient in the vertical aerosol distribution. The decrease in aerosol return signal starts at altitudes as low as 100 m, decreasing by an order of magnitude by an altitude of 250-300 m. The 2-D scans show that there was a source of aerosols (unidentified) within 1 km of the lidar site (see 22feb34.2d in data compilation). Lidar data estimates of the ML height are as follows:

Time of Day	Estimate of mixing-layer height (m)	elevated boundary level (m)
4:22 am	250	2500
6:28 am	250	2200
7:24 am	250	2200
8:49 am	300	2200
9:28 am	400	2200
9:59 am	600	2200
10:49 am	800	2300
11:30 am	1150	2600
11:57 am	1250	2700
12:12 am	1350	2700
1:33 pm	1800	2700
3:14 pm	2700	2700
4:44 pm		3100
5:17 pm		3700
6:23 pm		3800
7:56 pm		3500
10:30 pm	650	3300

The height of the ML is not shown past 3 pm because it has coalesced with the upper level inversion, becoming indistinguishable from it. Late in the evening there is evidence in the lidar data that a low lying inversion has re-formed (see 22feb103.2d in data compilation).

### February 26-28

On February 26-28 the lidar system was located at the National Autonomous University of Mexico (UNAM) in the botanical gardens area. This particular site was located a 80-100 m elevation compared to downtown Mexico City, on the mountain slopes to the southwest. Most of the scans were in a downslope direction. The altitude specified in the data plots and the table that follows **has not been corrected** for local elevation.

#### February 26

Time of Day	Estimate of mixing-layer height (m)	elevated boundary level (m)
2:30 am	nwd	2100
4:19 am	nwd	2100
6:24 am	200	1950
8:54 am	250	1850
9:25 am	400	1750
10:22 am	475	1800
11:16 am	650	1950
12:09 pm	nwd	2000
1:02 pm	2400	2400
2:02 pm		2600
3:22 pm		3000
4:54 pm		2900
5:22 pm		2850



6:06 pm		2600
7:45 pm		2600
9:28 pm		2400
10:33 pm	200	2150

nwd = not well defined in the data

### February 27

Time of Day	Estimate of mixing-layer height (m)	elevated boundary level (m)
0:47 am	200	nwd
3:01am	100	nwd
5:20 am	100	nwd
6:16 am	150	nwd
8:18 am	300	nwd
9:45 am	300	nwd
10:32 am	500	nwd
10:51 am	850	nwd
11:32 am	1000	1800
12:30 am	2500	2500
7:29 pm	200	1600
8:29 pm	200	1600

nwd = not well defined in the data

### February 28 :

Time of Day	Estimate of mixing-layer height (m)	elevated boundary level (m)
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0:36 am	300	1600
2:39 am	200	1500
4:47 am	200	1600
5:48 am	250	1700
6:27 am	200	1600
7:30 am	250	1200
8:28 am	250	1100
11:40 am	750	nwd
12:15 am	1900	1900
1:34 pm	3000	3000
5:16 pm		2800
6:29 pm		2100
11:48 pm	450	nwd

nwd = not well defined in the data

### **Conclusions on lidar mixing-layer height measurements**

The thermo-electric site was not an ideal site for mixing-layer height measurements. The environment was very complicated due to the local sources and the field-of-view prevented examination of possible inversions below 100 m in altitude. It is clear that there was substantial stratification of the atmosphere throughout the early morning hours.

The ML on February 22 exhibited a common pattern. In the early morning hours, particles are confined to within the first few hundred meters of elevation. As the sun rises and starts to warm the earth's surface, the ML height starts to rise, slowly at first. After approximately 10 am, the ML height increases rapidly so that by early afternoon (1-2 pm) it has reached elevations above 2 km, and begins to merge with an upper level boundary layer.

The particular lidar system configuration used for these measurements has some difficulty determining accurately the height of the ML under very stratified atmospheric conditions where there is more than one sharp aerosol layer very close to the ground (< 100m altitude). This situation is mostly due to the restricted field-of-view at the selected sites

and the range-dependent laser/telescope overlap function. A more fundamental problem arises from trying to determine whether it is only the lowest of a group of layers that effectively confines new surface-generated particles and pollutants. In any case, the lidar instrument shows where the particles and stable pollutants are currently concentrated.

The 2-D lidar scans graphically show the difficulties in trying to assign a single height to the mixing-layer. The convective turbulence cells that transport pollutants to higher elevation late in the morning, give rise to very complicated surfaces, such that the height measured at a given spatial location is subject to a lot of intrinsic variability.

There is some evidence in the scans suggesting that the low-lying ML is becoming re-established early in the evening as the earth's surface starts to cool.

The upper level boundary layer exhibits a temporal variation following what appears to be a diurnal cycle.

### **Time Sequences of Lidar Return Signals**

An animated time sequence of 2-D vertical scans can show the temporal evolution of the atmospheric aerosol spatial distribution in great detail. However, this approach requires some type of viewing screen for presentation. A simpler way to visualize the basic changes and trends in aerosol levels that are taking place as a function of time, and more amenable to the printed page, is as follows. First, range corrected data at a particular elevation angle ( $30^\circ$  for example) are extracted from a sequence of 2-D files taken under approximately the same conditions (same azimuth angle and APD bias voltage), corrected for angle to indicate altitude instead of range, and corrected for electronic signal voltage attenuation. The extracted files are cast into 3-D matrix form, where the coordinates specify the time, altitude, and signal level. Linear interpolation between points and a smoothing routine are used to generate visually smooth grid of equally spaced points which is plotted using a color scale to represent the signal amplitude. Thus, a particular color will indicate a constant signal amplitude level.

Fig. 16 shows the result of following the procedure outlined above on a time sequence of scans taken on February 22 at the CINVESTAV site. In this case, the height of the mixing layer (ML) stays within the first few hundred meters until about 7 am. As the rising sun starts to warm the surface and convective cells start to move upwards, the height of the ML starts to increase, slowly at first. By 12 noon the ML has reached altitudes higher than 1 km. In addition, the plot shows that even though the ML height increases with time and, therefore, there is a larger volume of air to disperse pollutants into, the concentration of aerosols at low altitude is also increasing with time. This is probably due to increased output from the aerosol emission sources in the area (vehicular and industrial) as the level of human activity picks up.

A second example of a temporal sequence of lidar return signals is shown in Fig. 17 for the data obtained February 26 at the UNAM botanical gardens site. Although this example follows the ML height pattern discussed in the example above, it differs in that there was a large concentration of particles aloft during the early morning hours which appears to have disappeared fairly quickly by sun-up. The temporal variation of the elevated boundary layer (described in previous sections) also shows up fairly well. This plot also suggests that the ML height starts to decrease at about 3 or 4 pm. By 9 pm the concentration of particles has dropped considerably.

### **Atmospheric Extinction Derived From Lidar Data**

When the atmosphere is homogeneous (i.e. no variation in the concentration or physical parameters of the aerosol particles with range) it is not necessary to know the particle size distribution or the details of its backscattering characteristics in order to extract extinction information from the lidar return signals. When  $\beta(r)$  is approximately constant with range  $r$ , then the signal is easily interpreted in terms of a simple exponential decay function (slope method of inversion) governed by the extinction coefficient,  $\sigma(r)$ , which now is also invariant with range. In the present lidar data set, the homogeneous atmosphere condition is most often observed in the horizontal dimension (constant altitude), as the vertical

distribution of aerosols usually exhibits an altitude dependence. The first two sites where the lidar equipment was located (see above) did not allow lidar measurements to be made along strictly horizontal paths (typically 8-10° minimum elevation angle, see data logs). However, the UNAM botanical gardens site (February 26-28) did provide unobstructed views of the atmosphere at 0° elevation. Some care must be taken in examining the data from this site because the site itself was located partly up the mountain slopes to the southwest, at an altitude of 80-100 m above the valley floor, so that the data obtained at 0° elevation angle does not maintain a constant altitude above the surface until after the laser beam leaves the slope area.

By extracting the 0° elevation angle data from the vertical scans taken on February 26-28 and choosing only those cases where the horizontal homogeneity condition is approximately satisfied, atmospheric extinction information can be obtained. Frequently, large plumes and other aerosol structures precluded analysis of the data. Fig. 18 is an example of a "good" case for extinction analysis, showing the range corrected lidar return signal for 0° elevation extracted from a vertical scan taken on February 26 at approximately 11:52 am. The atmospheric extinction coefficient  $\sigma$  at 1.06  $\mu\text{m}$  was obtained by using a least-squares (LSQ) fitting procedure to the first 1 km of useable data. The LSQ fit for the data in Fig. 18 is shown in Fig. 19. Fig. 20 shows the result of repeating this analysis procedure for a time sequence of vertical scans taken on February 26, which yields the temporal variation of the atmospheric extinction coefficient at 1.06  $\mu\text{m}$  near this particular lidar site, at an altitude of 80-100 m, in a direction looking primarily towards the city ( $Az = 40^\circ$  true north). The observed  $\sigma$  ranges from 0.1 to 0.4  $\text{km}^{-1}$ . Note the increase in  $\sigma$  that occurs at about 7-8 am and again at about 8 pm. This may be correlated to the morning and evening rush hour traffic. Unfortunately, the necessary atmospheric conditions that would have allowed continuous monitoring of  $\sigma$  during the next few days to verify this pattern were not established, and only additional fragments of extinction vs time were obtained. The values of  $\sigma$  obtained from the data of February 26 through 28 is shown in Fig. 21.

In general, aerosol extinction coefficients are a function of wavelength, so that the extinction and visibility information derived from the lidar data at 1.06  $\mu\text{m}$  need to be adjusted to get values that represent the

situation for visible light. A given visibility at 1.06  $\mu\text{m}$  indicates a somewhat lesser visibility in the visible region. Accurate transformation of the 1.06  $\mu\text{m}$  data to the visible range of wavelengths requires detailed knowledge of the aerosol particle scattering properties (shape, composition and size distribution). However, if the size distribution of the optically significant particles follows, as is common, a simple power law (Junge model), the extinction coefficient would scale as :

$$\sigma(\lambda) = \text{Constant} \cdot \lambda^{-\xi}$$

where  $\lambda$  is the wavelength, and  $\xi$  is a parameter that has been found to be in the 0.5-2.0 range<sup>11</sup>. Thus for  $\sigma$  in the range of 0.1-0.4  $\text{km}^{-1}$  at 1.06  $\mu\text{m}$ , the corresponding range in the visible (0.55  $\mu\text{m}$ ) would be 0.14-0.4  $\text{km}^{-1}$  to 0.56-1.6  $\text{km}^{-1}$ .

### **Comparison of Lidar Data to NCAR Measurements**

A fully instrumented aircraft belonging to the National Center for Atmospheric Research (NCAR) (King Air, Al Schanot, project manager) executed a variety of flight patterns over the valley of Mexico to gather information about the major air pollutant species such as  $\text{O}_3$ ,  $\text{SO}_2$ ,  $\text{CO}$ ,  $\text{NO}_x$ , aerosol particles, etc., as well as major meteorological parameters such as temperature, relative humidity, wind direction and velocity, solar radiation, etc. Most relevant to the lidar instrument for the purpose of comparison is the aerosol data that was obtained using an ASAS aerosol probe, which relies on an optical light scattering method to determine aerosol particle concentration and size distribution information. In particular, the NCAR aircraft measured the concentration of particles and pollutants as a function of altitude at a specific time of day. The data that will be shown here were obtained as the aircraft made its initial ascent after take-off from the airport. In the comparisons that follow, several factors should be kept in mind : 1) the aircraft is sampling different portions of the atmosphere than the lidar system, typically at least 10 km apart, 2) the lidar system collects aerosol backscattering data on a time scale of seconds per line-of-sight whereas the NCAR ascent data takes about 10 minutes as

the aircraft climbs in altitude, and 3) the aircraft passes through an atmospheric layer over a limited region of space, thus sampling the height of the layer at that particular location.

In order to compare the NCAR ascent data to the two-dimensional scan lidar data, a very simple approach was taken to keep the computational data processing time to a reasonable level. Essentially, line-of-sight data at selected angles was extracted from 2-D scans taken at a time close to the NCAR ascent time, subjected to a ten range bin average, corrected for  $1/r^2$  fall-off and plotted in terms of altitude above ground level.

The NCAR ASAS probe data gives the concentration of aerosol particles (per  $\text{cm}^3$ ) with sizes in the 0.12 -3.12  $\mu\text{m}$  diameter range in the following size-range bins :

Bin Number	Particle Diameter ( $\mu\text{m}$ )
1	0.120 - 0.145
2	0.145 - 0.195
3	0.195 - 0.270
4	0.270 - 0.370
5	0.370 - 0.495
6	0.495 - 0.645
7	0.645 - 0.820
8	0.820 - 1.020
9	1.020 - 1.245
10	1.245 - 1.495
11	1.495 - 1.770
12	1.770 - 2.070
13	2.070 - 2.395
14	2.395 - 2.745
15	2.745 - 3.120

The total number of particles in the 0.12-3.12  $\mu\text{m}$  diameter range is heavily dominated by the small particles (bins 1,2,3), with typical concentrations exceeding  $10^3 \text{ cm}^{-3}$  per bin. The larger particle bins usually

had readings on the order of  $1 \text{ cm}^{-3}$ . Some of the particle size distribution data is shown in Appendix D.

The ASAS probe data tapes showed an entry for each particle size bin every second during the ascent, which normally took about 10 minutes. However, many of the entries were 0. In order to produce a smooth plot of particle concentration vs altitude, 20 seconds of data were averaged and plotted at the average altitude during the time segment. This produced plots with data points every 150-200 m of altitude.

In general, aerosol light scattering cross-sections decrease rapidly as the particle diameter becomes smaller than the wavelength of light being used. Thus, given the  $1.06 \text{ }\mu\text{m}$  laser wavelength used in the present lidar system, only the particle concentration data for particles with diameters greater than  $0.2 \text{ }\mu\text{m}$  (bins 3-15) was used for comparison to the lidar data. It should be kept in mind that the observed lidar signal is the result of a complicated superposition of backscattering efficiencies from a wide range of particle sizes and compositions.

#### NCAR Ascent of February 22, 1991.

Fig. 22 shows the NCAR aerosol data (solid line) obtained during the ascent portion of the flight on the morning of February 22 in the vicinity of the airport. Superimposed on the same plot is the range corrected lidar return signal (dotted line, scaled and shifted for comparison purposes) obtained at an elevation angle of  $30^\circ$  during a 2-D scan taken at the CINESTAV site (approximately 13 km from the airport) at a slightly earlier time. Recall that the rising part of the lidar signal is an instrumental artifact. The two instruments show reasonable agreement. Both show the same general features : a fairly sharp decrease in particle concentration at an altitude of about 400-500 m, and a second transition region at an elevation of 2200-2300 m. The 2-D scan from which the single lidar trace was taken is shown in Fig. 23 and it shows that the ML is starting to exhibit a fair amount of variability at this point in time. Thus, the agreement between the aircraft data (which samples one portion of the ML boundary) and the one angle lidar data cannot be expected to be better than the variability in the ML height.



The NCAR potential temperature data is plotted in Fig. 24. It indicates a temperature inversion at about 400-500 m, and thus the lidar data is accurately reflecting the inversion height in this instance.

A comparison between the NCAR ozone vs altitude profile and the lidar data is shown in Fig. 25. The ozone distribution reflects the ML height, although there appears to be significant ozone concentration even above the ML. Again, the agreement between the two instruments is good, given the variability in the surface defined by the ML height. Examples of the altitude profiles of other major air pollutants is shown in Appendix E. Some stable pollutants like CO do not appear to be very sensitive to the presence of a temperature inversion.

#### NCAR Ascent of February 26, 1991

Fig. 26 shows the NCAR aerosol data (solid line) obtained during the ascent portion of the flight on February 26 in the vicinity of the airport. Superimposed on the same plot is the range corrected lidar return signal (dotted line, scaled and shifted for comparison purposes) obtained at an elevation angle of  $30^\circ$  during a 2-D scan taken at the UNAM site (approximately 20 km from the airport) at a slightly later time. There is good agreement in the altitude at which the particle density drops rapidly. The 2-D scan itself is shown in Fig. 27. Again, note the structure that is developing in the ML. The potential temperature data for this flight is shown in Fig. 28. The temperature inversion does not become strong until about 500 m of altitude which agrees with the ASAS probe and the lidar system data.

Fig. 29 is a comparison between the lidar data and the NCAR ozone information. In this case the distribution of ozone with altitude does not agree as well with the aerosol distribution (NCAR or lidar) as the previous example.

#### Comparison of Lidar Data to Rawinsonde Results

Instrumented free-ascending balloons (rawinsondes) were released at the Mexico City International Airport 6 or 7 times a day throughout the month of February. The instrument package monitors air temperature, pressure, potential temperature, relative humidity, wind speed and wind direction and radios the data back to the receiving station at the release point. Typical ascent rates are 5-10 m/s. Examples of some rawinsonde data compared to lidar data are presented in the material in this section. The comparisons will focus on the potential temperature (PT) measured by the balloon releases that occurred close in time to the NCAR flights. Additional examples of the rawinsonde data can be found in Appendix E. It must be kept in mind that the rawinsonde data is being taken at a location that is far removed ( $> 10$  km) from the lidar sites. In addition, the rawinsonde balloon rises very quickly, thus effectively sampling the atmosphere in a narrow region of space and time. Time-sequences of PT profiles obtained throughout the days selected for analysis can be found in Appendix F.

### Rawinsonde of February 17

On this date, the NCAR aircraft had a flight at about 10 am. Unfortunately, there was no electrical power available at this particular time at thermo-electric power plant site which prevented the lidar system from taking data. Thus, the lidar data obtained close in time to an earlier rawinsonde flight will be examined. Fig. 30 shows the PT vs altitude measured by the 8 am rawinsonde flight. Superimposed on the temperature data is the lidar range-corrected backscatter return signal observed at an elevation angle of  $10^\circ$ , scaled and shifted for comparison purposes. The PT profile increases with altitude indicating a ground based thermal inversion, most likely caused by radiation cooling of the earth's surface throughout the night. This atmospheric condition implies very stable air with little mixing or upward movement of ground-generated particles and pollutants. The 2-D vertical scan color plot obtained at this time is shown in Fig. 31 and clearly shows many aerosol layers or bands, indicating a highly stratified atmosphere. The  $10^\circ$  lidar return signal shows at least two layers or particles at low elevations confirming the lack

of upward mobility at this time. If the altitude of the lowest layer is taken as the mixing-layer height for particles being produced at this time, then the lidar estimate of the mixing-depth is on the order of 100 m above ground. Note that due to the restricted field-of-view at this site ( $8^\circ$  minimum elevation angle at this site), the lidar instrument cannot easily detect the presence of layers at altitudes less than about 75 m. Fig. 32 shows the same potential temperature profile shown in Fig. 30, but superimposed with lidar data obtained at a higher elevation angle ( $30^\circ$ , same 2-D vertical scan). Fig. 32 shows the effect that a sharp increase in PT has on the particle distribution at elevated altitudes. The elevated inversion occurring at 1800-1900 m also acts as a lid to prevent the upward dispersal of particles at higher elevations.

#### Rawinsonde of February 22

The rawinsonde data obtained at noon will be used for this day. Fig. 33 shows PT vs altitude along with  $30^\circ$  elevation lidar data extracted from a 2-D elevation scan taken at about the same time (scaled and shifted). The PT profile indicates highly unstable (turbulent) atmosphere to an altitude of about 400 m, becoming less so or neutral between 400 and 1000 m, and finally changing to very stable conditions at altitudes greater than about 1000-1300 m. Taking the first increase in PT as the ML height, it occurs at about 1000-1100 m. The lidar 2-D elevation scan shown in Fig. 34 indicates that the ML surface is substantially convoluted at this time ranging in height from 1100 to 1500 m, entirely consistent with the PT profile. Note the presence of localized aerosol features in the lidar 2-D scan. This points out the fact that although things are supposed to be well mixed within the ML, there can still be substantial structure present.

#### Rawinsonde of February 26

The 11 am rawinsonde sounding will be used for this day. Figs. 35 and 36 show PT vs altitude along with  $10^\circ$  and  $30^\circ$  elevation angle lidar data, respectively, extracted from a 2-D elevation angle scan taken at about

the same time (Fig. 37). The PT profile indicates two strong temperature inversion regions : one occurring at an altitude of about 700 m (which is identified as the height of the ML) and a second inversion at an altitude of about 1900 m. The raw lidar data reflects both of these features. The effect of the first inversion is most easily seen in the 10° data (see Fig. 35), whereas the effect of the elevated inversion is readily apparent in the 30° data.

### Conclusion

In the selected examples, the lidar aerosol backscatter return data reflects the presence of temperature inversions in the atmosphere, both at low and elevated altitudes. A more detailed comparison between rawinsonde and lidar data focusing on atmospheric structure and turbulence information is in progress and will be available at a later time.

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The NCAR data was processed with the assistance of Mary Alice Garcia and the rawinsonde data was taken by Servicio Meteorologico Nacional personnel operating out of the Mexico City International Airport. Dyan Seville-Jones assisted with the lidar plot generation process.

# Figures

## Figure Captions

1. Schematic of basic elastic lidar technique as applied to aerosol scattering.
2. Photograph of the elastic lidar truck deployed in Mexico City. The movable telescope/detector assembly sit on top of the roof. A Nd:YAG laser system operating at  $1.06\ \mu\text{m}$ , 10 Hz sits inside. The laser beam exits the truck through the roof and is made collinear with the optical axis of the telescope. The entire assembly moves under microcomputer control to execute a variety of scan patterns. Photograph courtesy of Dr. Javier Tejeda, Instituto Mexicano del Petroleo.
3. Photograph exemplifying a vertical scan over Mexico City. The laser wavelength was changed to  $0.532\ \mu\text{m}$  ( $2^{\text{nd}}$  harmonic of the  $1.06\ \mu\text{m}$  fundamental), so that the laser beam path could be observed and photographed. The image is a multiple exposure. After taking data at the initial angular setting, the laser/telescope assembly moves upward in a series of elevation-angle steps, pausing at each location to take data. This scan pattern generates a two dimensional view of the vertical structure of atmospheric aerosols along a particular azimuth direction. Photograph courtesy of Dr. Javier Tejeda, Instituto Mexicano del Petroleo.
4. Map of the Mexico City basin area showing the three different sites selected for lidar measurements : the thermo-electric power plant in the northeast area, the CINVESTAV site near the National Politecnic Institute just north of city center, and the Botanical Gardens site at the National Autonomous University of Mexico (UNAM) in the southwest corner of the basin.
5. Expanded scale city map the of thermo-electric power plant lidar site.
6. Expanded scale city map of the CINVESTAV lidar site looking south, towards the tethersonde location.
7. Expanded scale city map of the CINVESTAV lidar site looking north, towards an industrial area of the city.
8. Expanded scale city map of the botanical gardens site at UNAM, looking north.



9. Example of an elastic aerosol lidar return signal taken at an elevation angle of  $30^\circ$ , plotted as a function of altitude. This trace is one of many that make up a complete scan. The data is the average of 50 laser shots and was subjected to a 10 point smoothing routine. The data is presented in a range-corrected format. No attempt was made to remove the effects of atmospheric extinction. The rising part of the signal (up to about 400 m in this example) does not indicate a low concentration of aerosols but rather reflects an instrumental characteristic related to how the laser beam enters the field-of-view of the telescope/detector assembly. This particular example shows that there are two strong gradients in aerosol concentration: one at an altitude of 450 m, and a second transition at about 1.9 km.

10. Example of a vertical scan taken at the thermo-electric power plant site made up of an angular sequence of 96 traces. The color bar roughly indicates the relative concentration of aerosol particles (in arbitrary units). The scan shows the strong atmospheric stratification that is occurring at this particular time. Many layers or bands of aerosol particles are visible.

11. Example of a vertical scan taken at about 7:21 am at the CINVESTAV site that shows the height of the mixing layer as being approximately 225 m

12. Example of a vertical scan taken at about 10:47 am at the CINVESTAV site illustrating how the mixing layer has become extremely convoluted, reaching altitudes as high as 900-1000 m.

13. Example of a horizontal scan taken at the CINVESTAV site over an industrial area of the city. Overlaying this scan on a city map showed that the bright plumes observed here (shown in red) are connected with activities at a glass manufacturing plant and a steel making operation.

14. Example of a vertical scan taken at the UNAM botanical gardens site. Huge plumes are seen rising from the city at various locations. At this time of day, aerosols released into the atmosphere can be lofted up towards the top of the mix-layer which is at about 2.5 km. Note the structure in the elevated boundary layer compared to the relatively flat case in Fig. 10. Clean cool air from above can be seen mixing with the polluted air below.

The aerosol patterns give the impression that wind circulation is occurring as part of the entrainment process.

15. Example of a vertical scan taken at 11:40 am at the UNAM site showing the convoluted mixing layer produced by the entrainment process, as well as the visual estimate of the average mixing layer height.

16. Example of a time sequence of vertical lidar soundings obtained at the CINVESTAV site looking directly over the tethersonde location. To generate this plot, range-corrected data from a single azimuth ( $90^\circ$ ) and elevation ( $50^\circ$ ) angle was extracted from a temporal sequence of 2-D vertical scans and placed into a matrix with time as the horizontal axis, altitude as the vertical axis, and aerosol return signal amplitude indicated via a color bar as shown. The matrix data was subjected to a nearest neighbor smoothing routine. The height of the mixing layer (ML) stays within the first few hundred meters until about 7 am. As the rising sun starts to warm the surface and convective cells start to move upwards, the height of the ML starts to increase, slowly at first. By 12 noon the ML has reached altitudes higher than 1 km.

17. Example of a time sequence of vertical lidar soundings obtained at the UNAM site. To generate this plot, range-corrected data from a single azimuth and elevation angle was extracted from a temporal sequence of 2-D vertical scans and placed into a matrix with time as the horizontal axis, altitude as the vertical axis, and aerosol return signal amplitude indicated via a color bar as shown. The matrix data was subjected to a nearest neighbor smoothing routine. Although this example follows the mixing layer height pattern discussed in the Fig. 16, it differs in that there was a large concentration of particles aloft during the early morning hours which appears to have disappeared fairly quickly by sun-up.

18. Example of a range corrected lidar return signal for  $0^\circ$  elevation extracted from a vertical scan taken on February 26 at approximately 11:52 am at the UNAM site.

19. Example of a segment of range corrected lidar return signal obtained at  $0^\circ$  elevation extracted from a vertical scan taken on February 26 at approximately 11:52 am at the UNAM site. The solid line represents a least-squares-fit to the data and yields an extinction coefficient of approximately  $0.27 \text{ km}^{-1}$  at  $1.06 \mu\text{m}$ .
20. Temporal variation of the atmospheric extinction coefficient at  $1.06 \text{ mm}$  near the UNAM lidar site on February 26, 1991, at an altitude of 80-100 m above ground, in a direction looking primarily towards the city ( $Az = 40^\circ$  true north). The increase in extinction at about 7 am and again at about 6 pm may be correlated to the morning and evening traffic rush hours.
21. Temporal variation of the atmospheric extinction coefficient at  $1.06 \text{ mm}$  near the UNAM lidar site during the period of February 26-28, at an altitude of 80-100 m above ground, in a direction looking primarily towards the city ( $Az = 40^\circ$  true north).
22. Comparison between the NCAR aerosol data (solid line) obtained during the ascent portion of the flight on the morning of February 22 (10:13-10:21 am) in the vicinity of the airport and the range corrected lidar return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $30^\circ$  during a 2-D scan taken at the CINVESTAV site (approximately 13 km from the airport) at a slightly earlier time (10:06 am).
23. Two-D vertical lidar scan taken at the CINVESTAV site close in time to the time of the vertical ascent of the NCAR instrumented aircraft on February 22, 1991.
24. Potential temperature vs altitude measured by the NCAR aircraft during the ascent of February 22, 1991, 10:13-10:21 am.
25. Comparison between the NCAR vertical distribution of ozone concentration (solid line) obtained during the ascent portion of the flight on the morning of February 22 (10:13-10:21 am) in the vicinity of the airport and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $30^\circ$

during a 2-D scan taken at the CINVESTAV site (approximately 13 km from the airport) at a slightly earlier time (10:06 am).

26. Comparison between the NCAR aerosol data (solid line) obtained during the ascent portion of the flight on the morning of February 26 (10:20-10:31 am) in the vicinity of the airport and the range corrected lidar return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $10^\circ$  during a 2-D scan taken at the UNAM site (10:32 am, approximately 24 km from the airport).

27. Two-D vertical lidar scan taken at the UNAM site close in time to the time of the vertical ascent of the NCAR instrumented aircraft on February 26, 1991.

28. Potential temperature vs altitude measured by the NCAR aircraft during the ascent of February 26, 1991, 10:20-10:31 am.

29. Comparison between the NCAR vertical distribution of ozone concentration (solid line) obtained during the ascent portion of the flight on the morning of February 26 (10:20-10:31 am) in the vicinity of the airport and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $10^\circ$  during a 2-D scan taken at the UNAM site (approximately 24 km from the airport, 10:32 am).

30. Comparison between the vertical profile of potential temperature measured by the airport rawinsonde (solid line) on the 8 am launch of February 17, 1991, and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $10^\circ$  during a 2-D scan taken at the thermo-electric power plant site (approximately 29 km from the airport, 7:55 am).

31. Two-D vertical lidar scan taken at the thermo-electric power plant site close in time to the time of the February 17, 1991, 8 am launch of the rawinsonde from the Mexico City international airport.

32. Comparison between the vertical profile of potential temperature measured by the airport rawinsonde (solid line) on the 8 am launch of February 17, 1991, and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an

elevation angle of  $30^\circ$  during a 2-D scan taken at the thermo-electric power plant site (approximately 29 km from the airport, 7:55 am).

33. Comparison between the vertical profile of potential temperature measured by the airport rawinsonde (solid line) on the 12 pm launch of February 22, 1991, and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $10^\circ$  during a 2-D scan taken at the CINVESTAV site (approximately 13 km from the airport, 12 pm).

34. Two-D vertical lidar scan taken at the CINVESTAV site close in time to the time of the February 22, 1991, 12 pm launch of the rawinsonde from the Mexico City international airport.

35. Comparison between the vertical profile of potential temperature measured by the airport rawinsonde (solid line) on the 11 am launch of February 26, 1991, and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $10^\circ$  during a 2-D scan taken at the UNAM site (approximately 24 km from the airport, 10:57 am).

36. Comparison between the vertical profile of potential temperature measured by the airport rawinsonde (solid line) on the 11 am launch of February 26, 1991, and the lidar aerosol return signal (dotted line, arbitrarily scaled and shifted for comparison purposes) obtained at an elevation angle of  $30^\circ$  during a 2-D scan taken at the UNAM site (approximately 24 km from the airport, 10:57 am).

37. Two-D vertical lidar scan taken at the UNAM site close in time to the time of the February 26, 1991, 11 am launch of the rawinsonde from the Mexico City international airport.

# LIDAR Method

*(Light Detection and Ranging)*

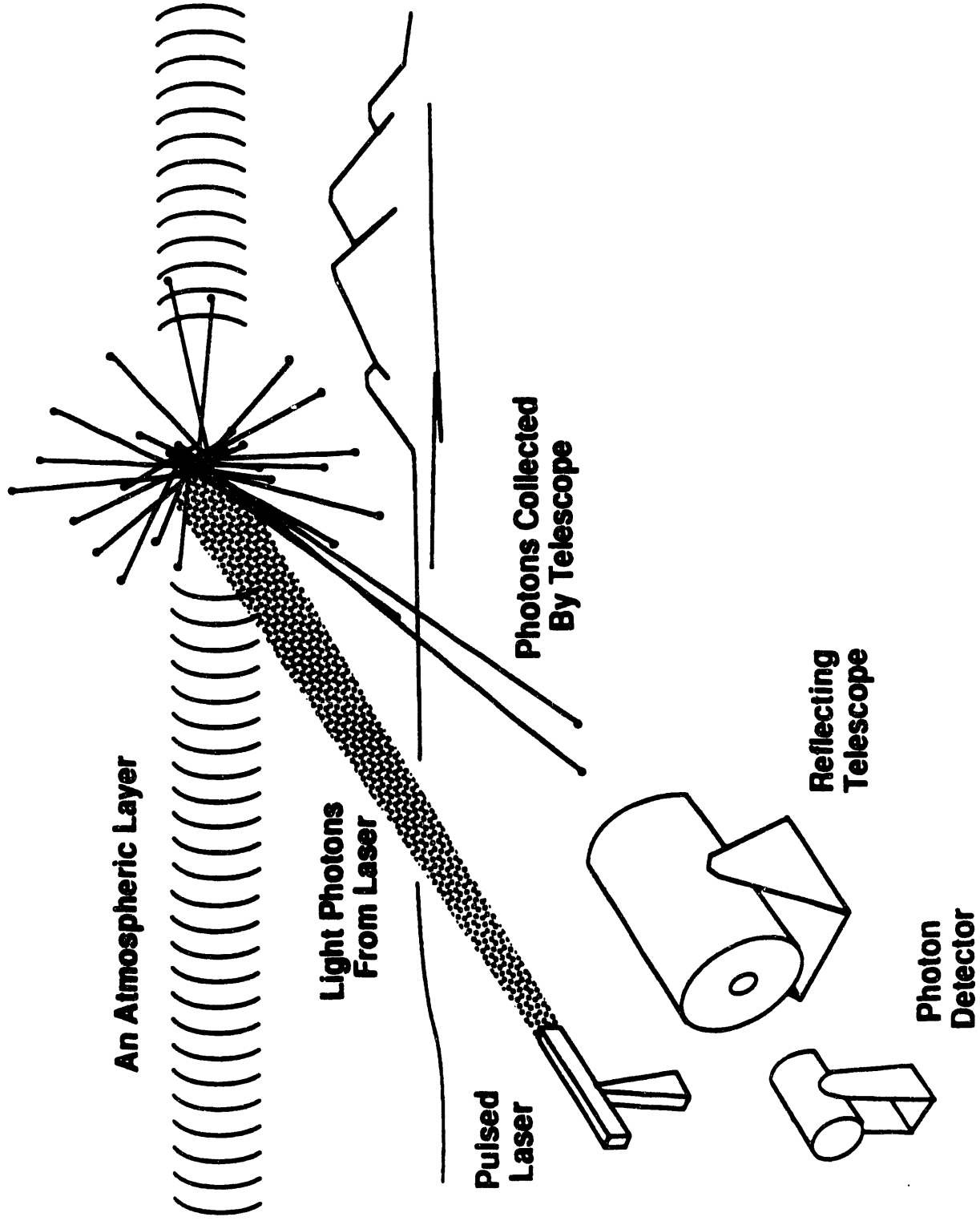


Fig. 1

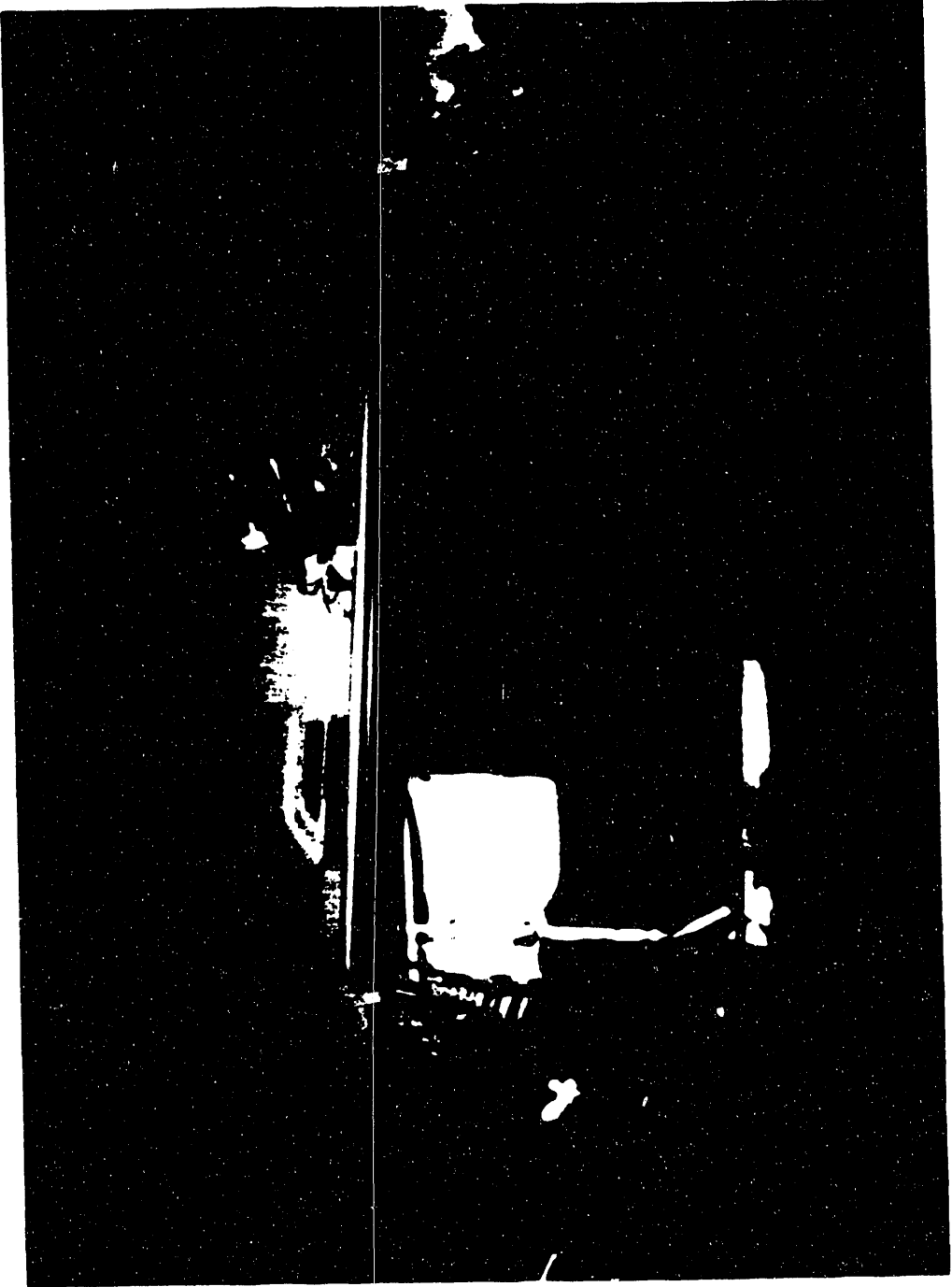


Fig. 2

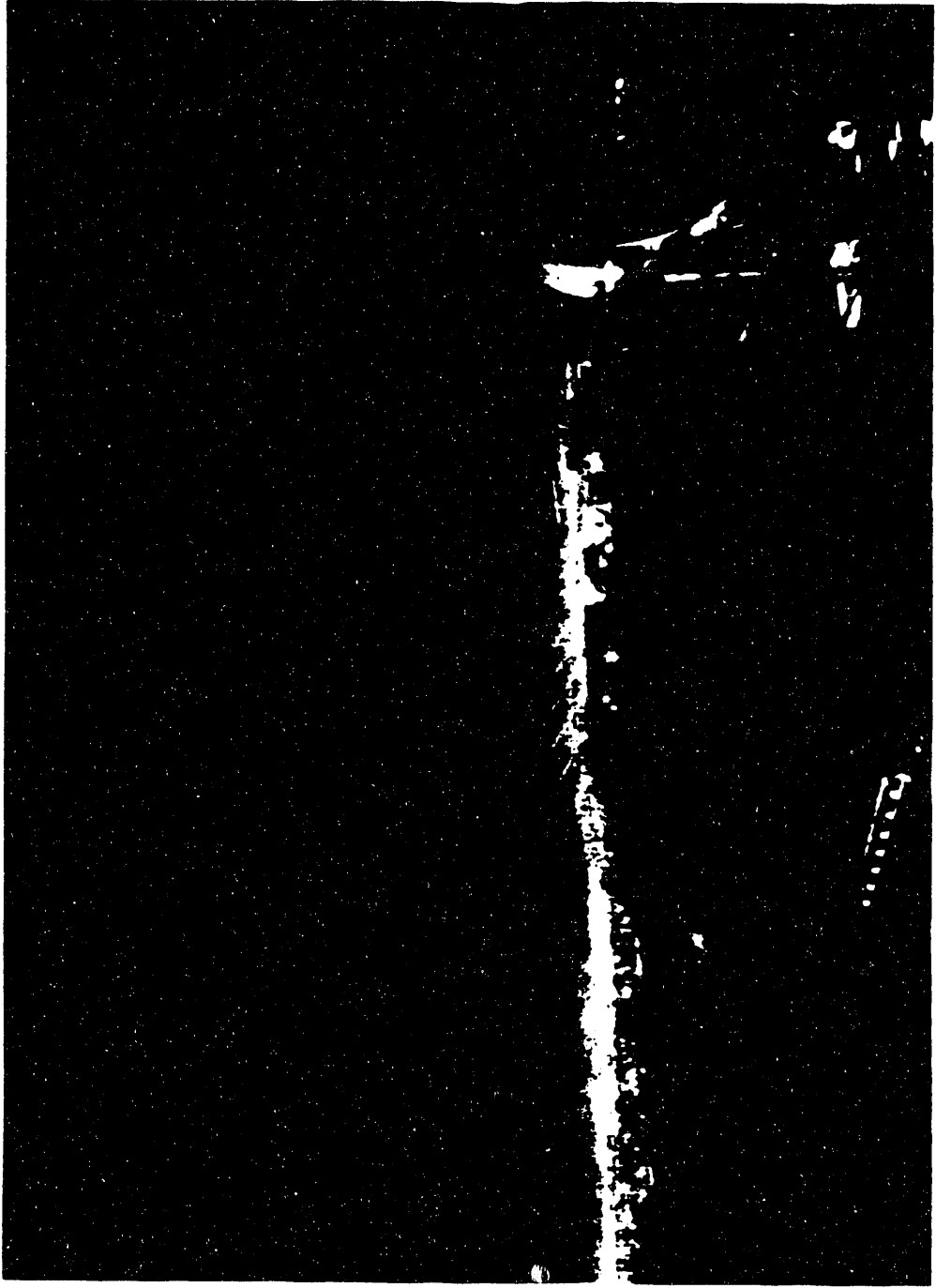


Fig. 3



# Mexico City

## Los Alamos Lidar Site Locations

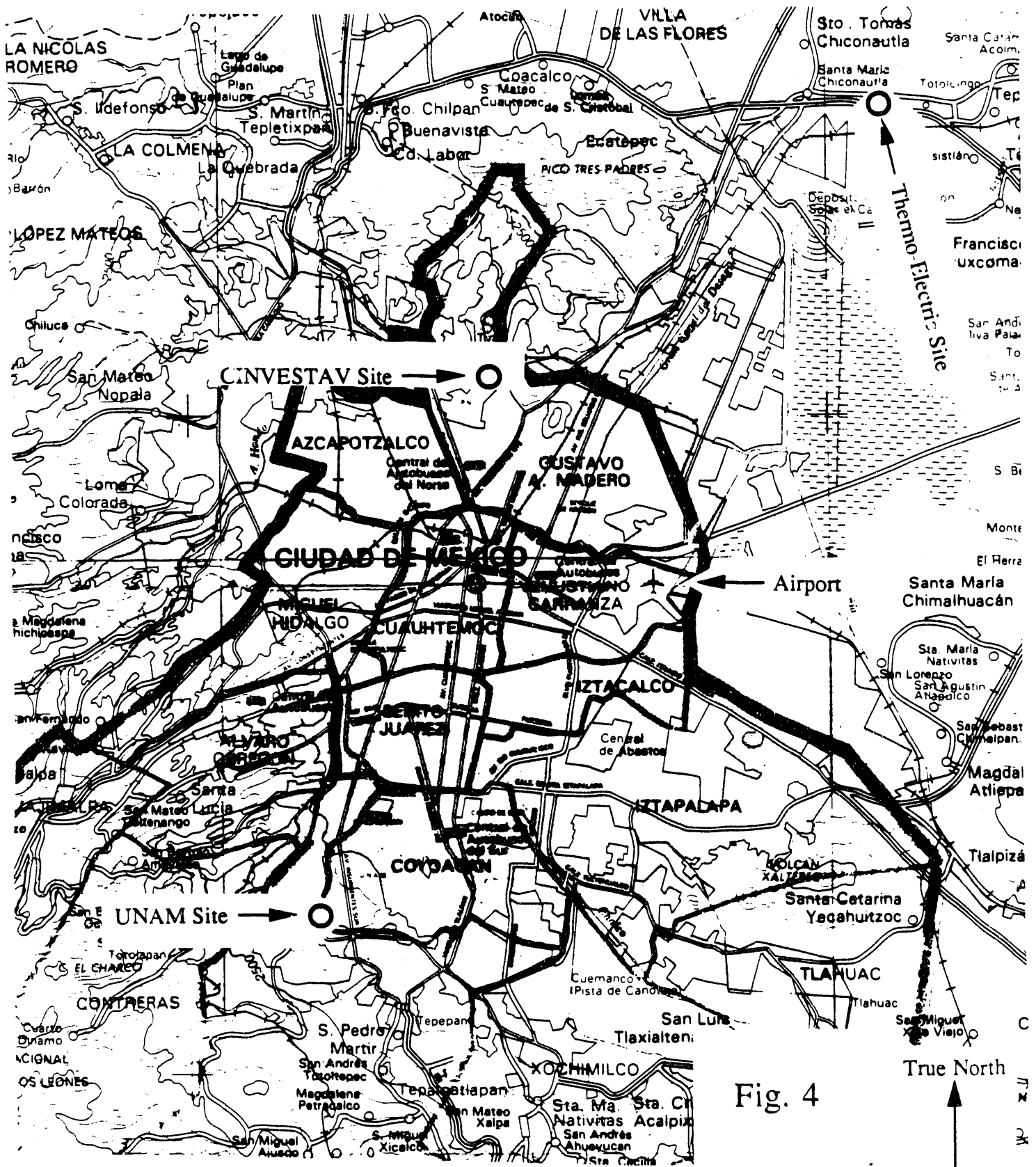


Fig. 4

# Thermo-Electric Power Plant Site

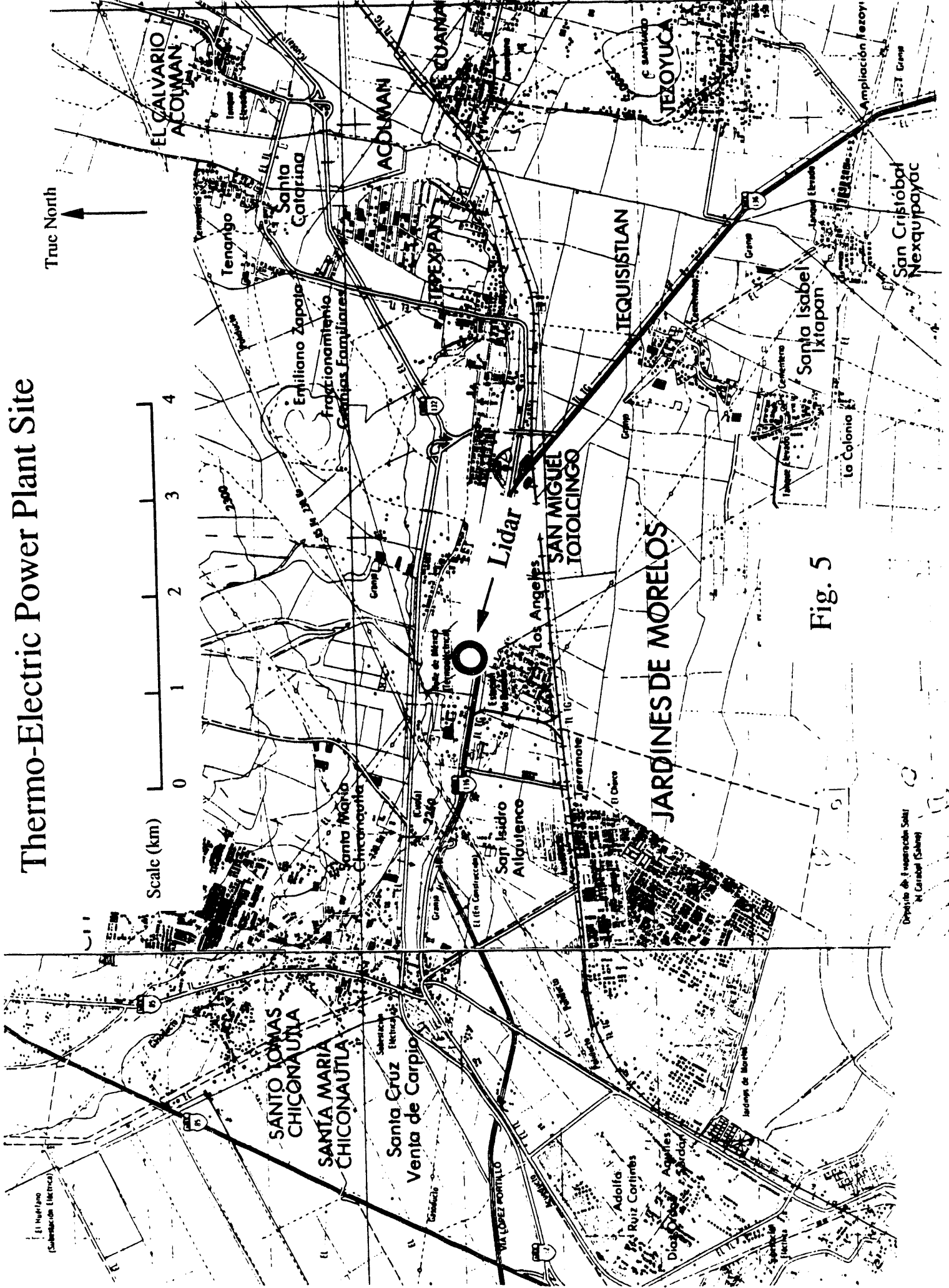
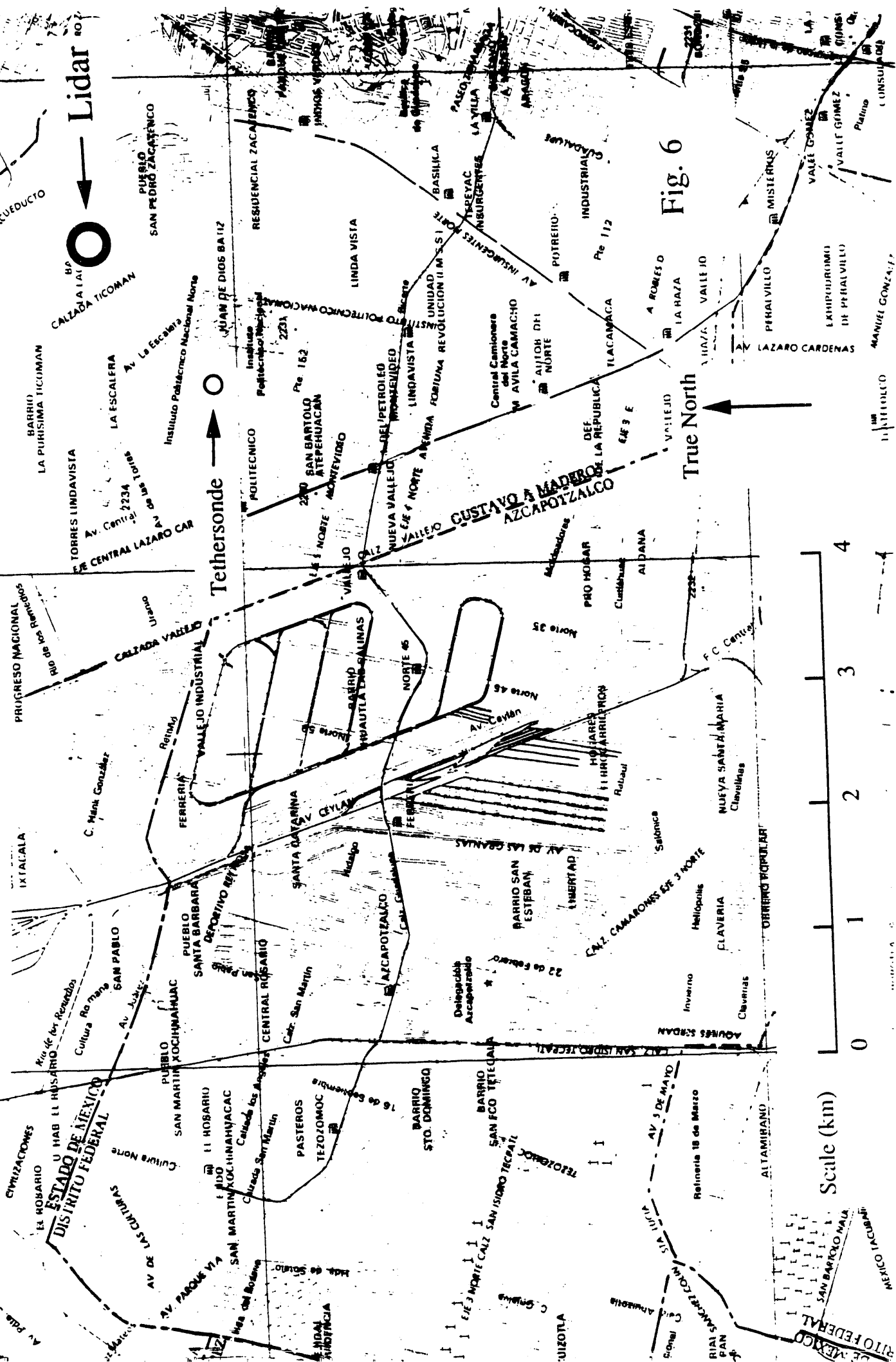


Fig. 5

Dirección de Investigación Sotil  
de Caridad (Sotil)

# CINVESTAV Site

(National Polytechnic Institute)



Scale (km)



Fig. 6

# CINVESTAV Site

## (National Polytechnic Institute)

True North

Scale (km)

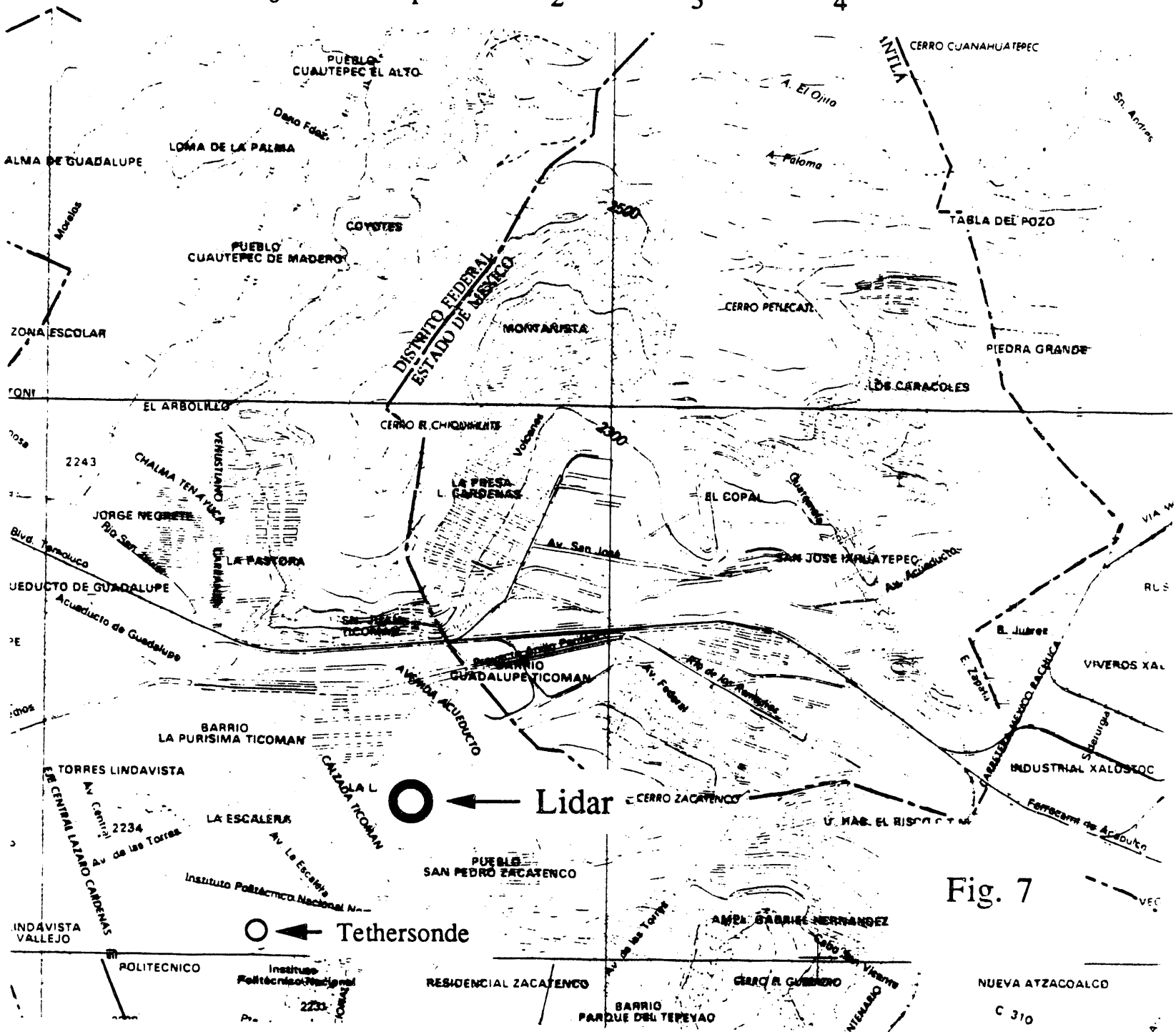
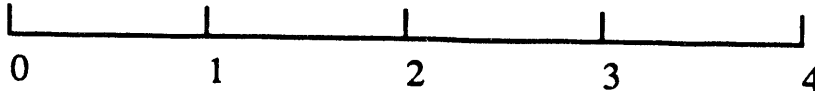
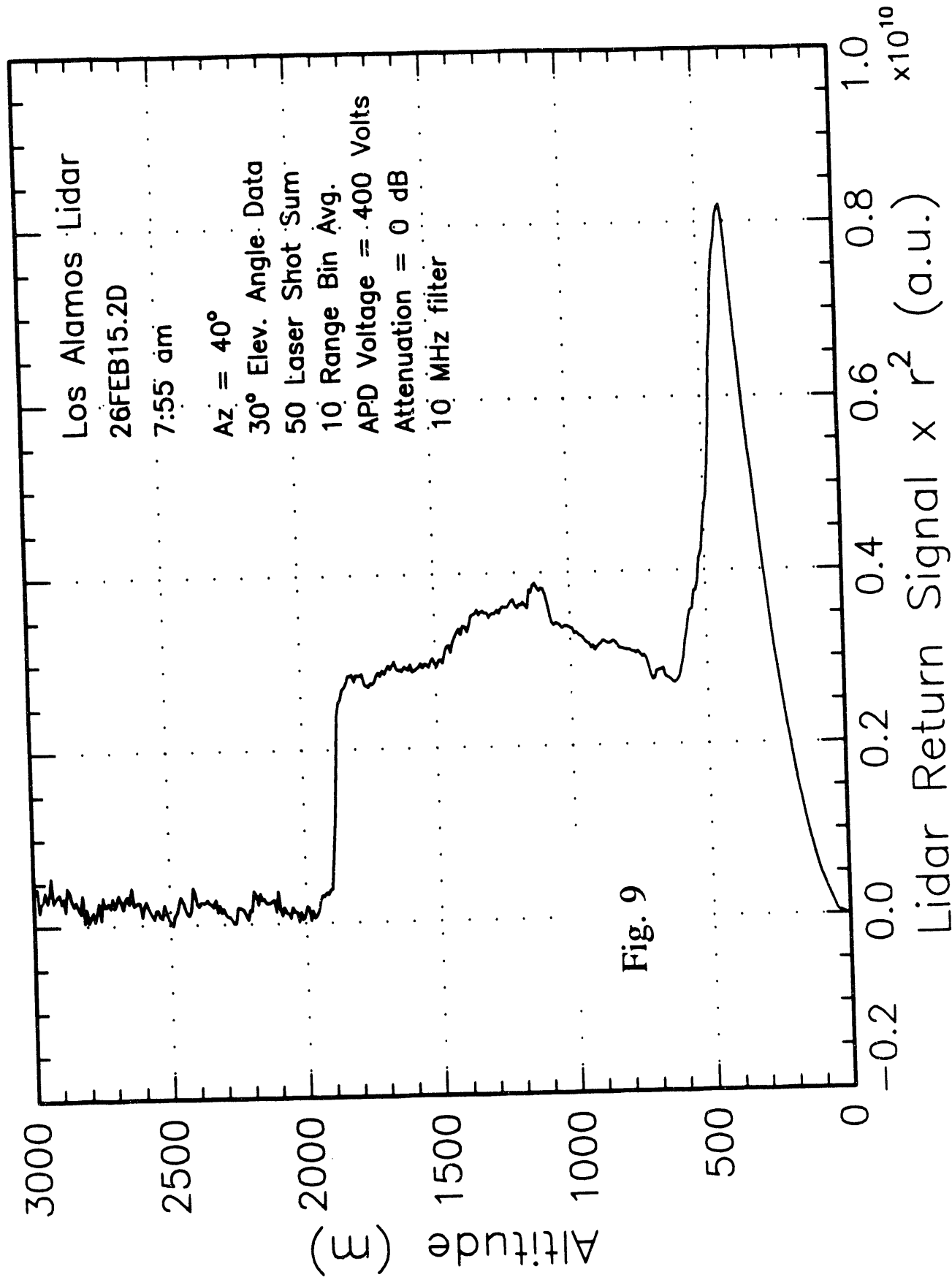


Fig. 7

NUEVA ATZACOALCO  
C 310



UNAM Site February 26, 1991



2-17-1991 6:42 Scans=50 Az: 60.00 Elev: 10.00; Vertical scan 1 deg step

Vertical Scan; File:E:\FEB17.91\17FEB87.2D

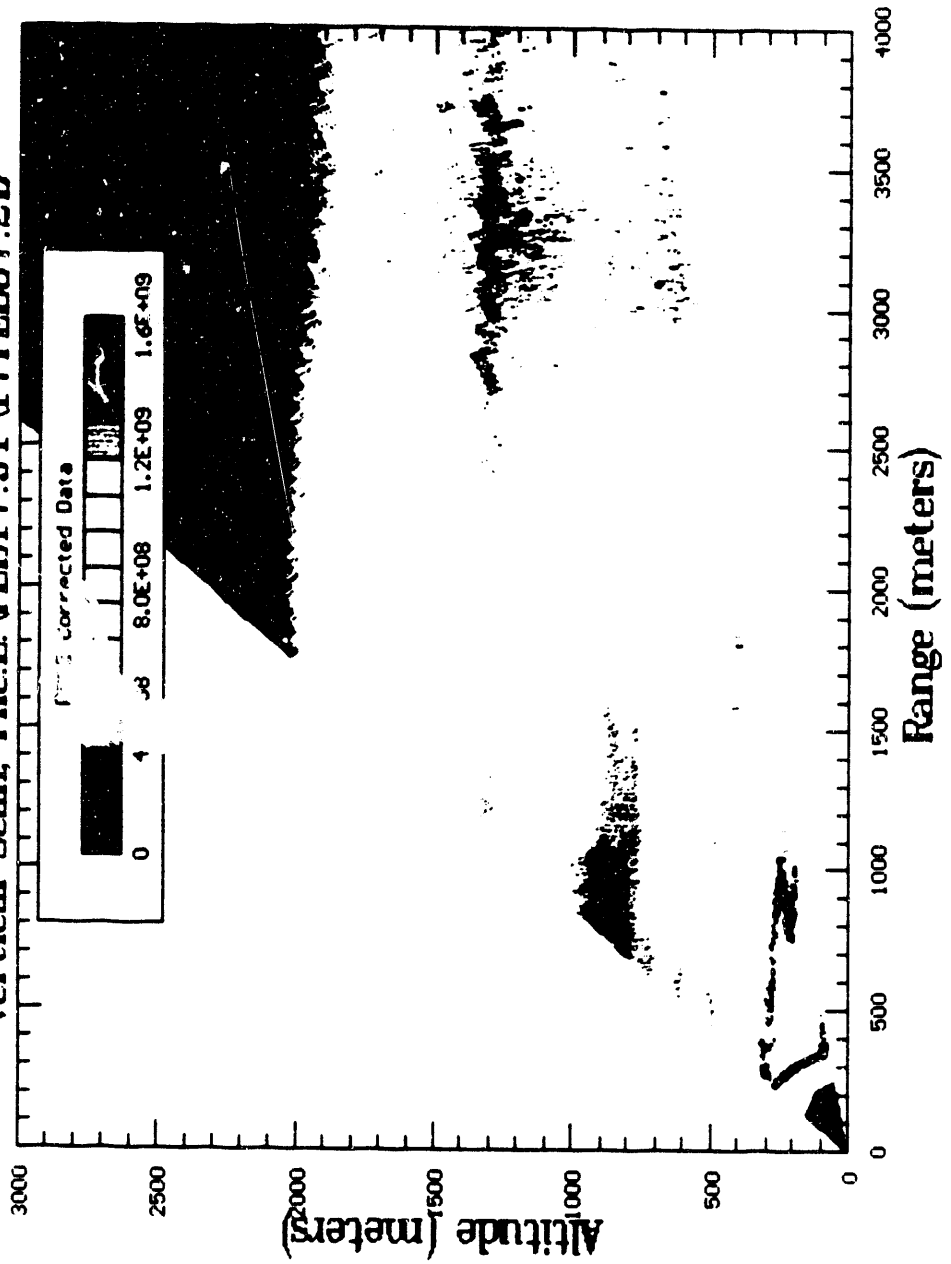


Fig. 10

2/22/1991 7:21 Scans=10 Az: 90.00 Elev: 8.00; 12az/8-50X1/250v/16db

### Vertical Scan; File:E:\FEB22.91\22FEB25.2D

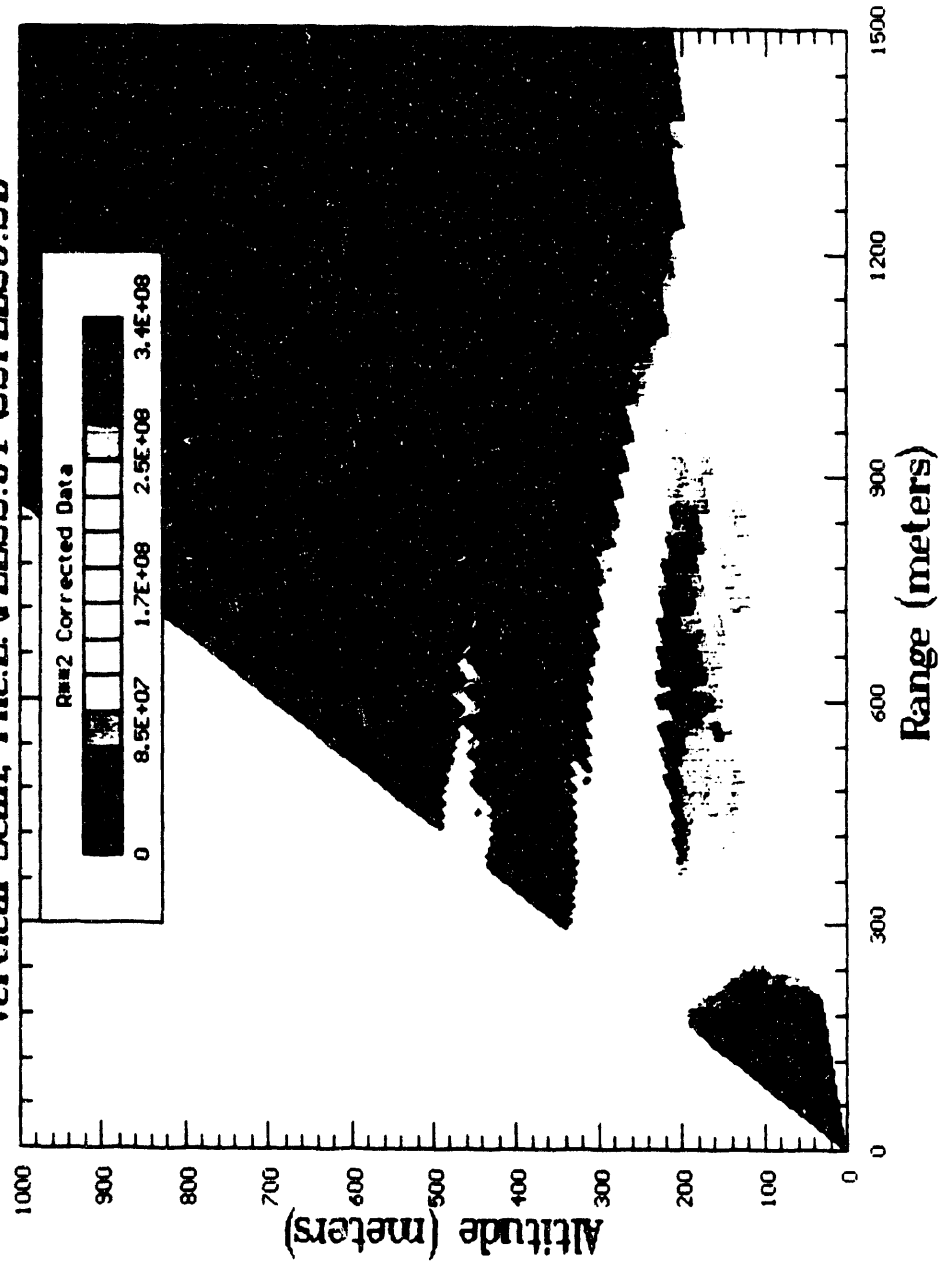


Fig. 11



2-22/1991 10:47 Scans=10 Az: 90.00 Elev: 8.00; Vertical scan-120/8-50x1/250v/16db

Vertical Scan; File:E:\FEB22.91\22FEB42.2D

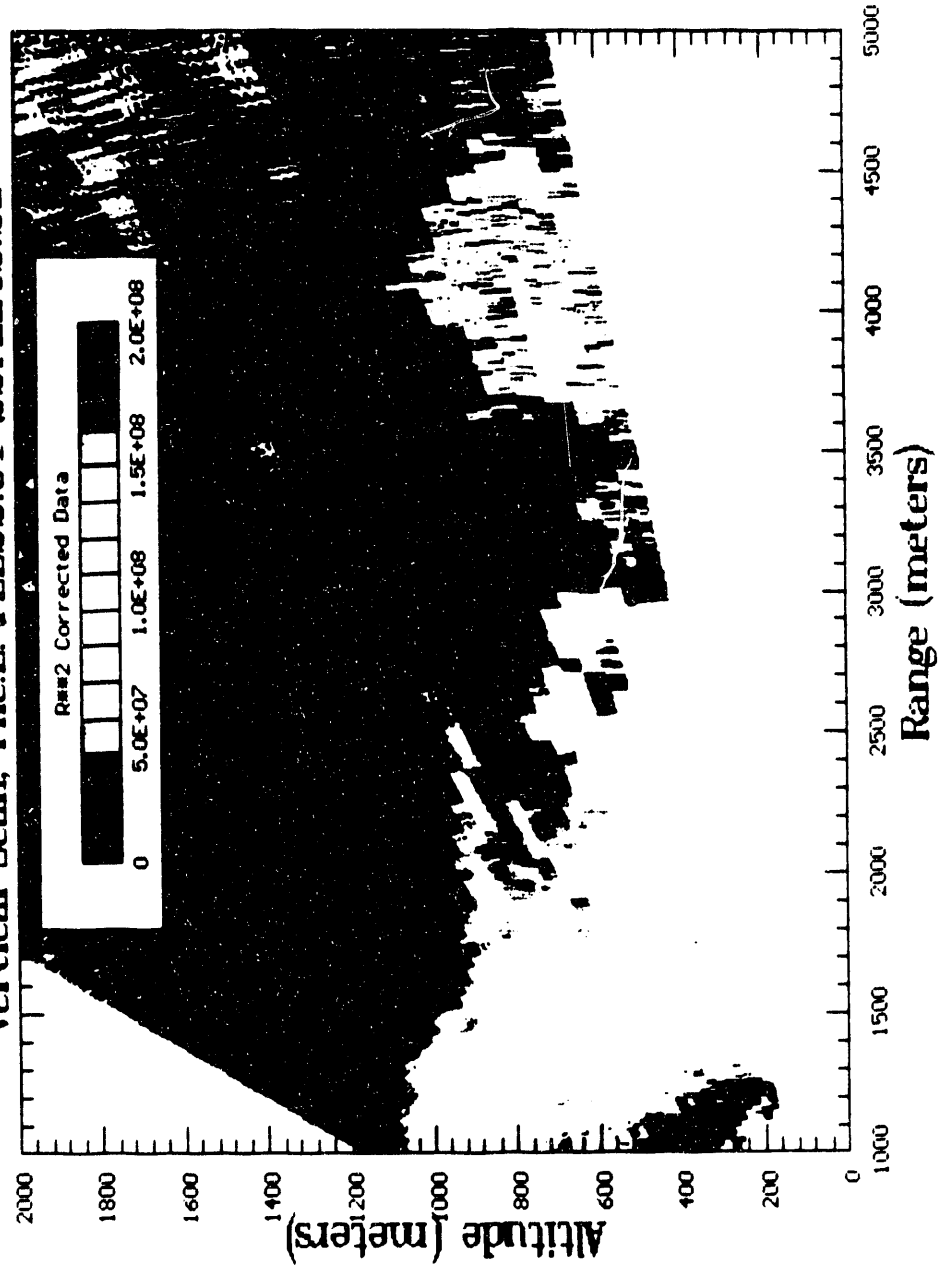


Fig. 12

2/23/1991 5:45 Scans=10 Az: 110.00 Elev: 10.00; valley btun tur's & glass plnt

### Horizontal Scan: File:E\FEB23.91\23FEB19.2D

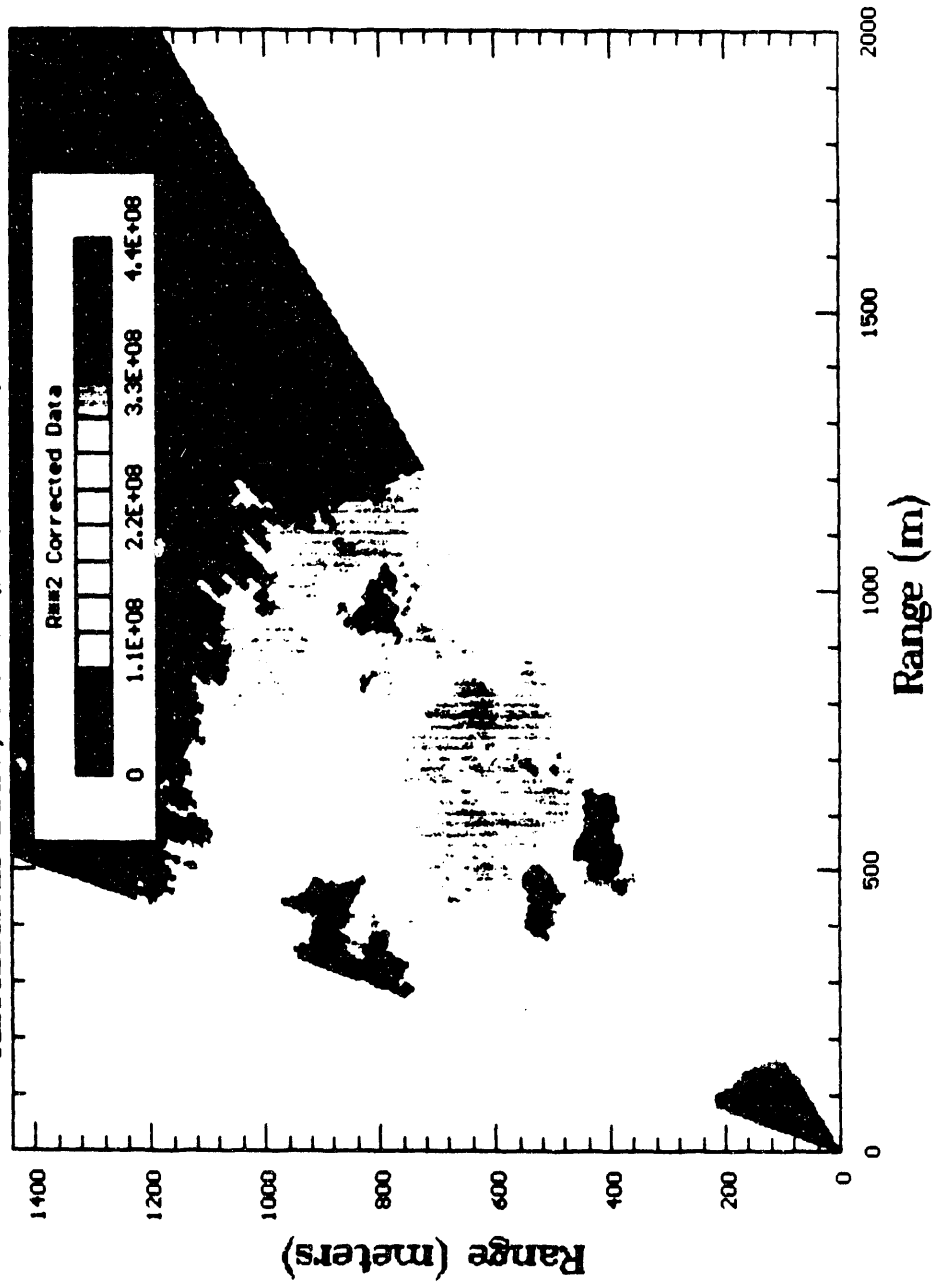


Fig. 13

2/27/1991 12:30 Scans=25 Az: 42.00 Elev: 2.00; Vertical scan over perrificio highway 2-40x

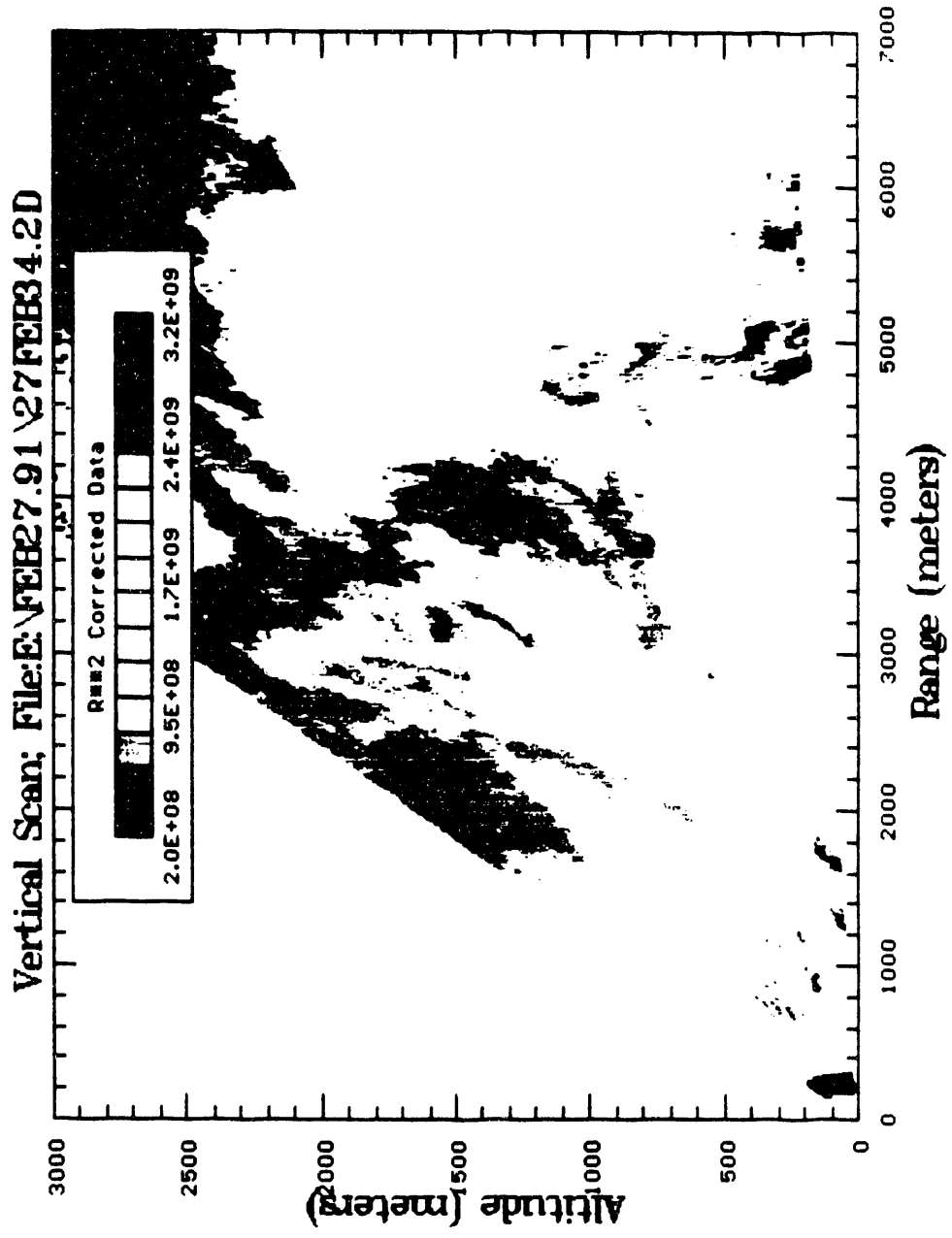


Fig. 14

2/28/1991 11:40 Scans=25 Az: 90.00 Elev: 0.00; Vertical scan 90 az and 0-50 x 0.5, 25 shots

### Vertical Scan: File:E:\FEB28.91\28FEB48.2D

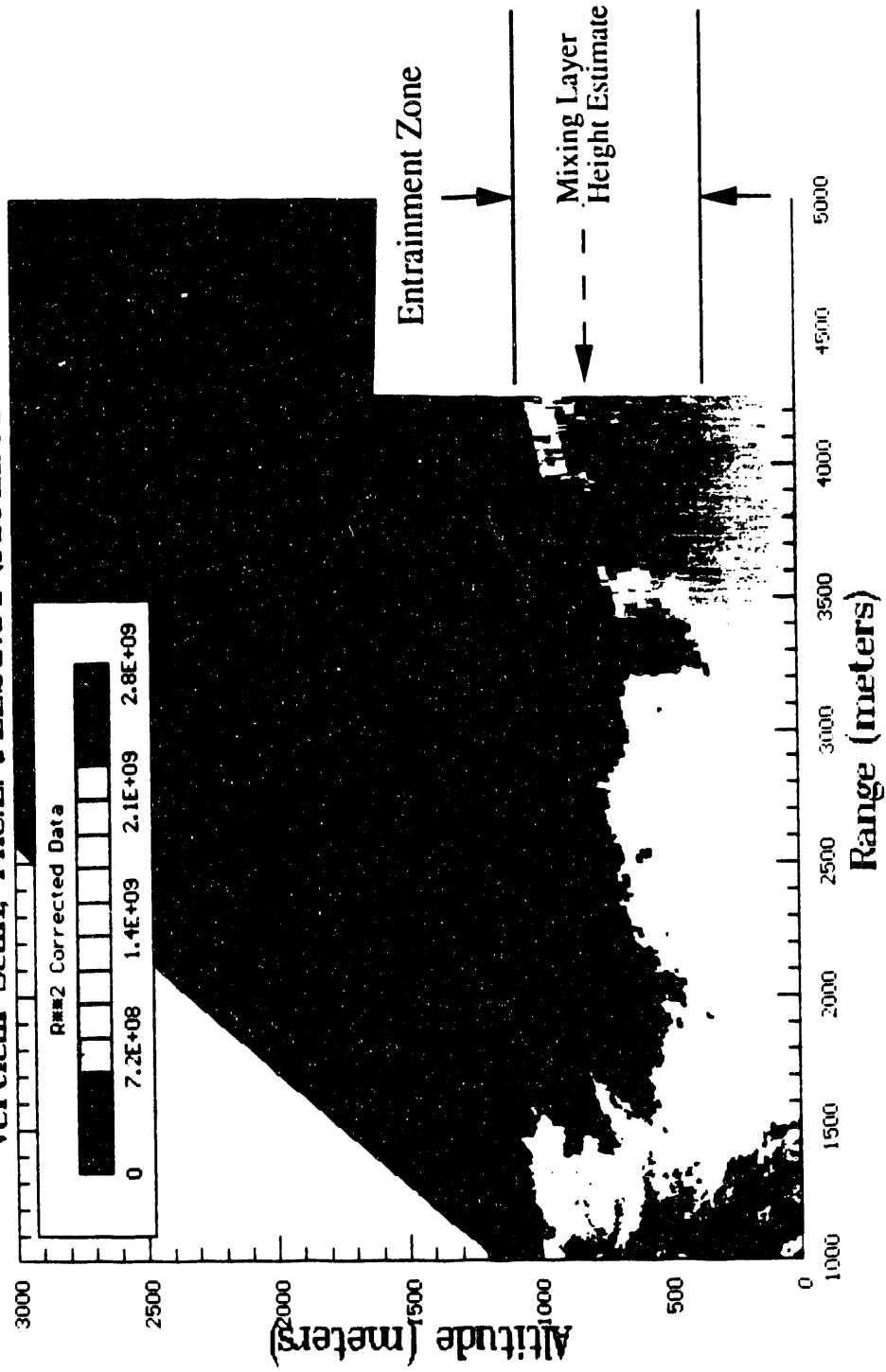


Fig. 15

# CINVESTAV Site, February 22, 1991

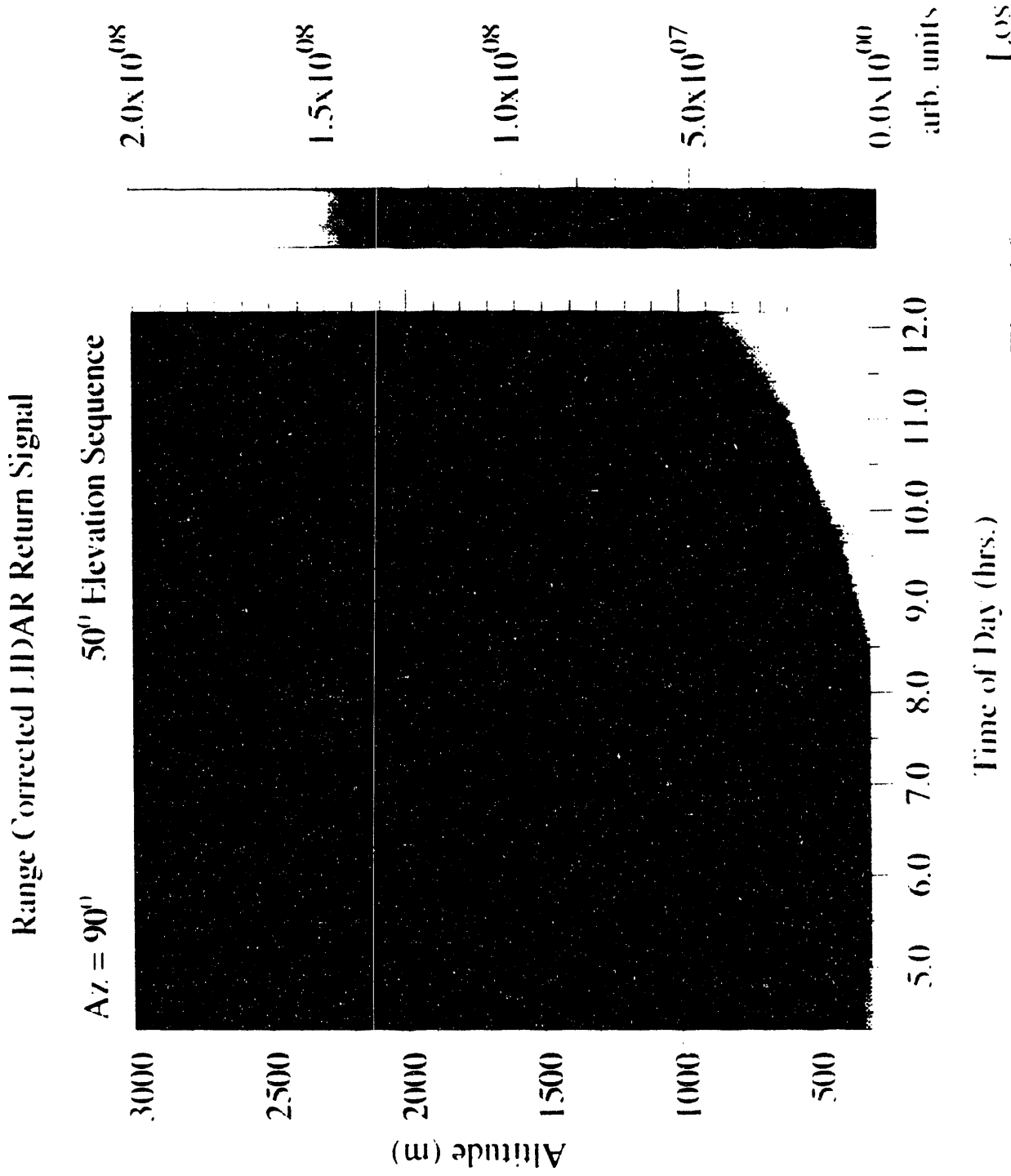
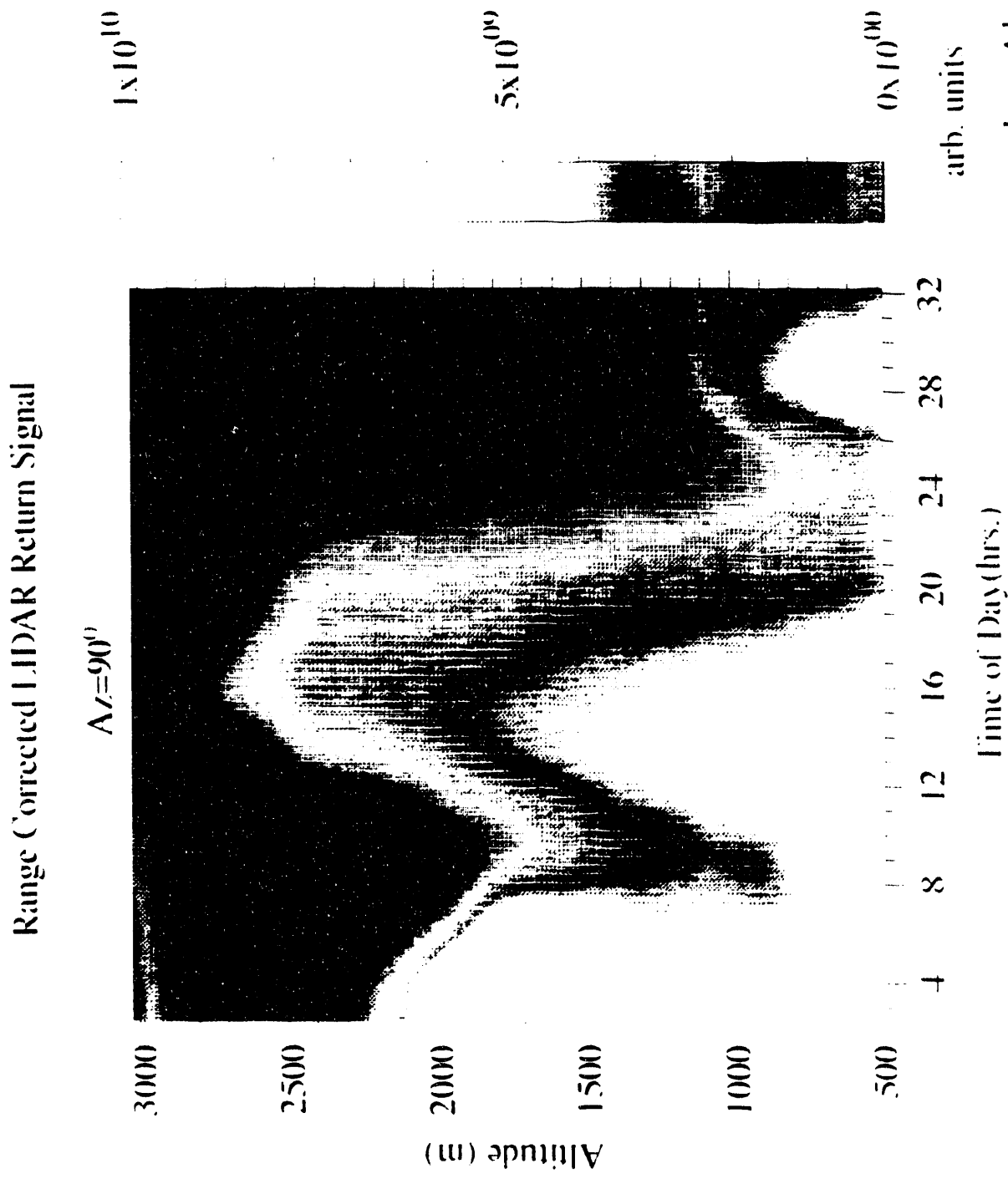


Fig. 16

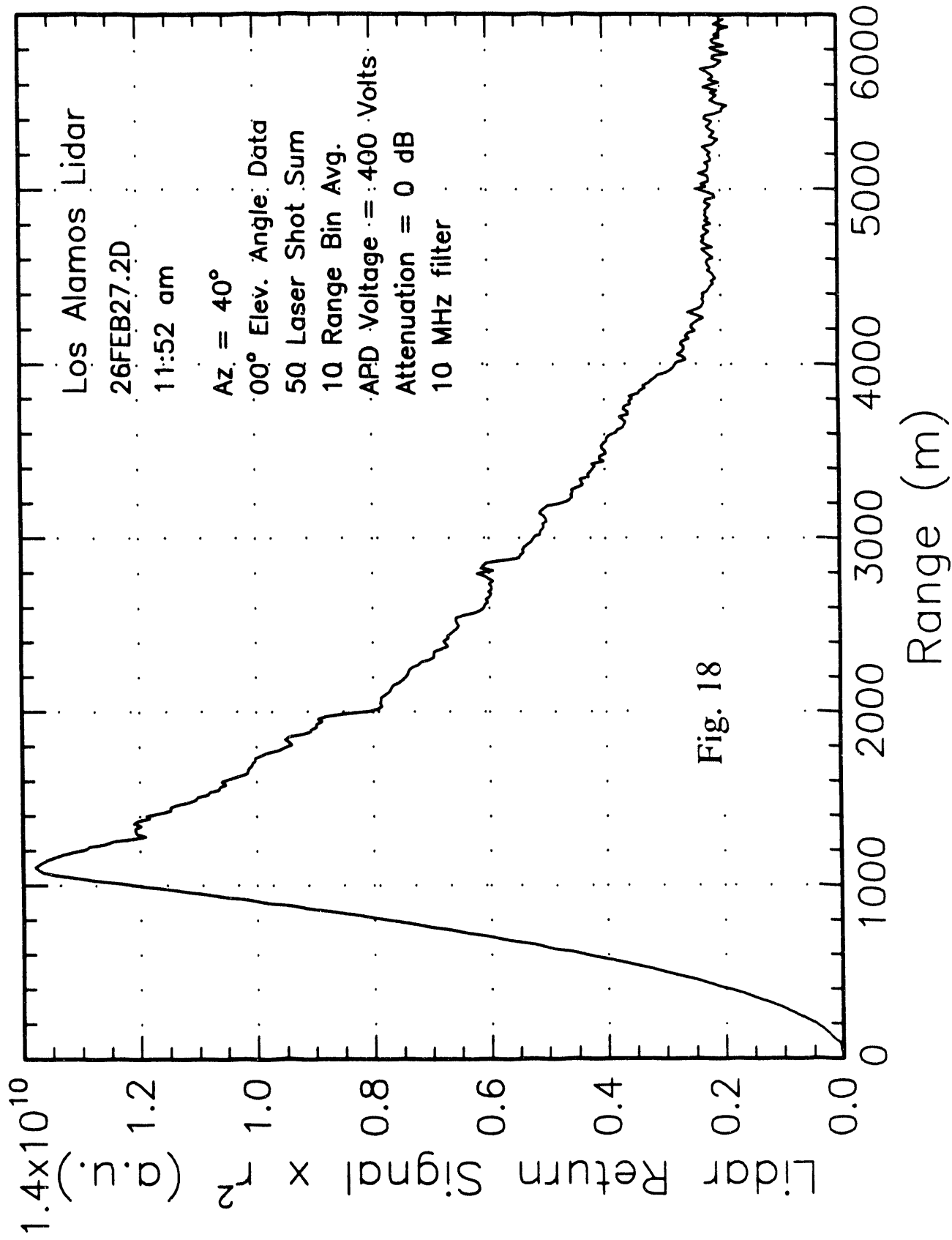
# UNAM Botanical Gardens, February 26-27, 1991



Los Alamos

Fig. 17

# UNAM Site February 26, 1991



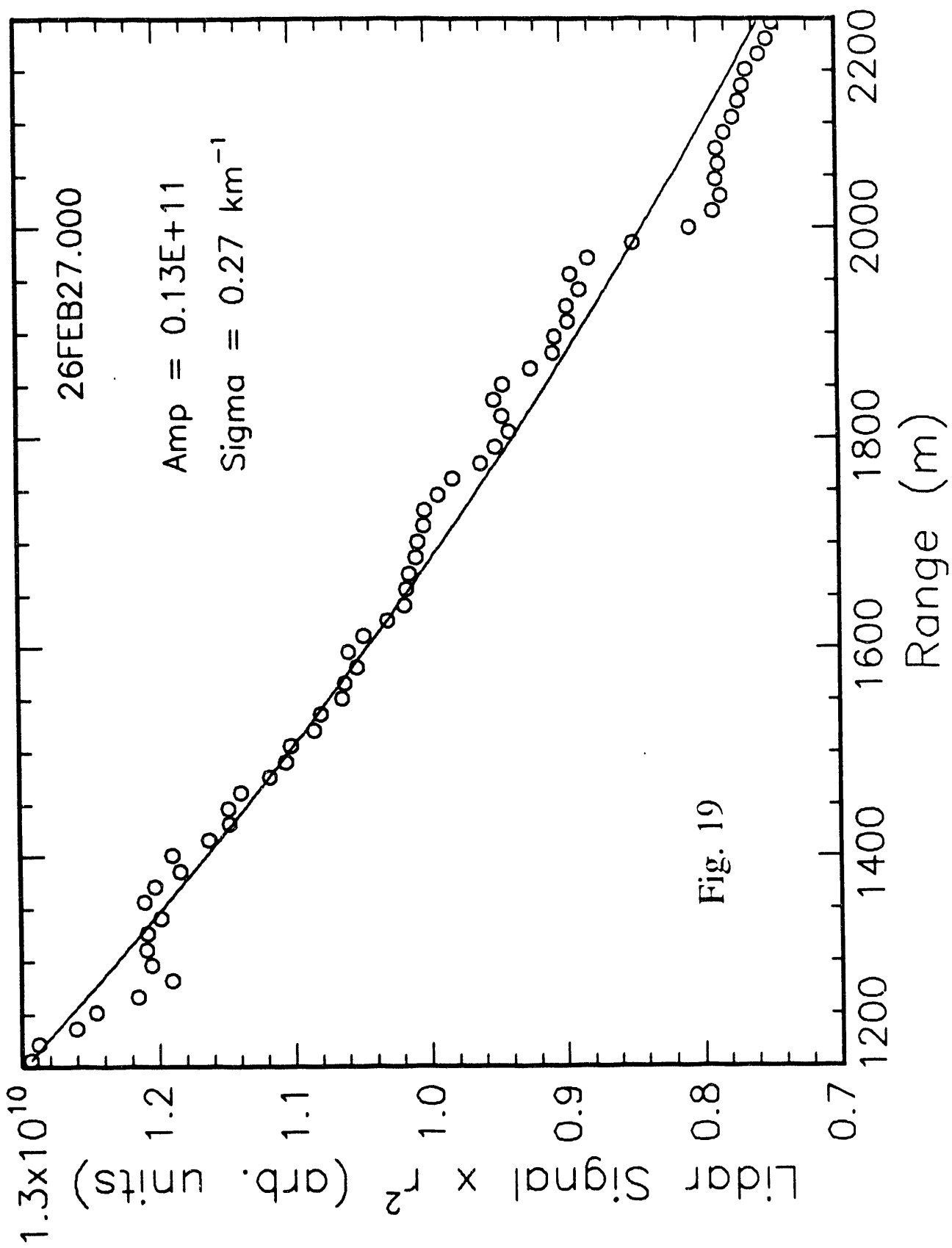
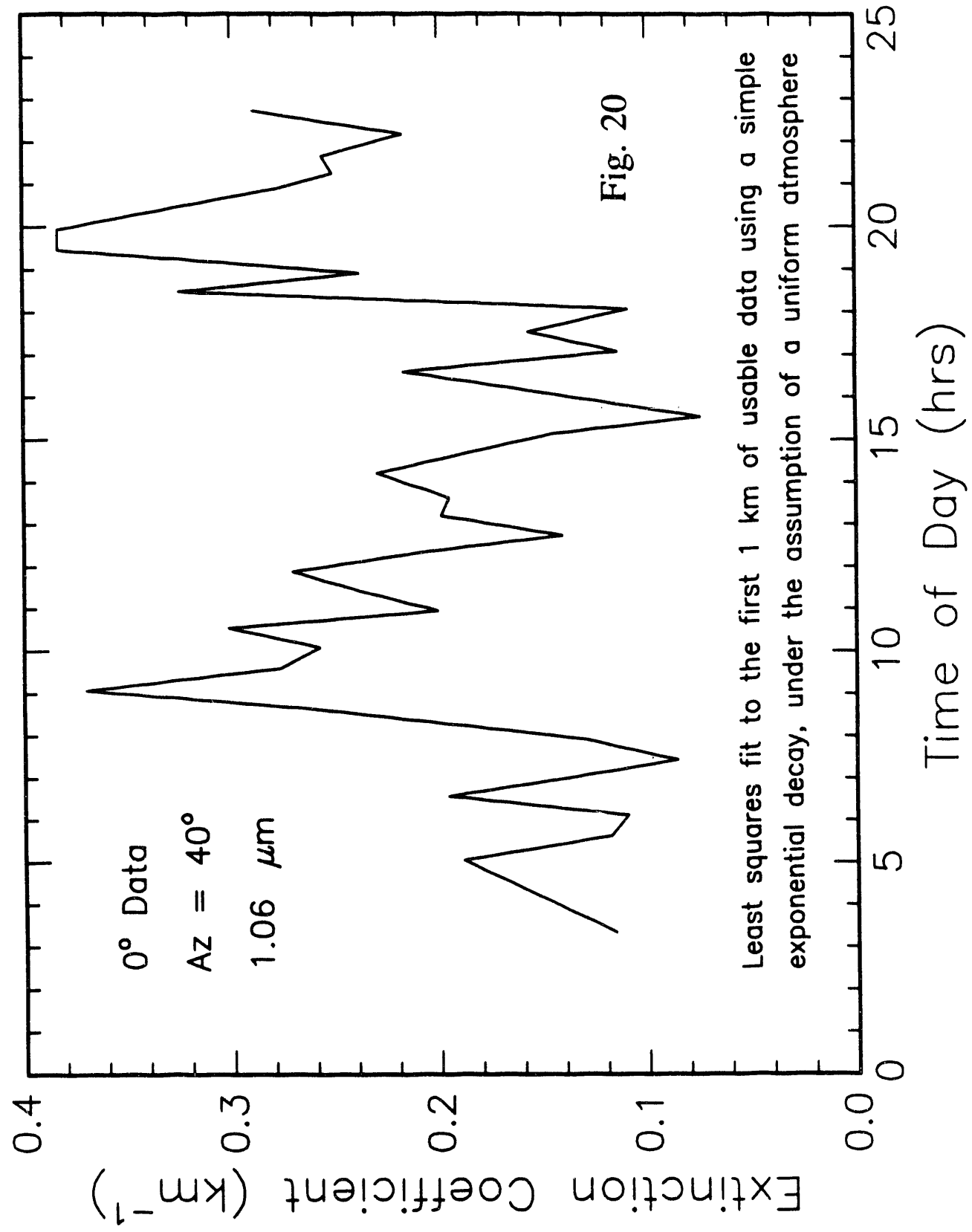


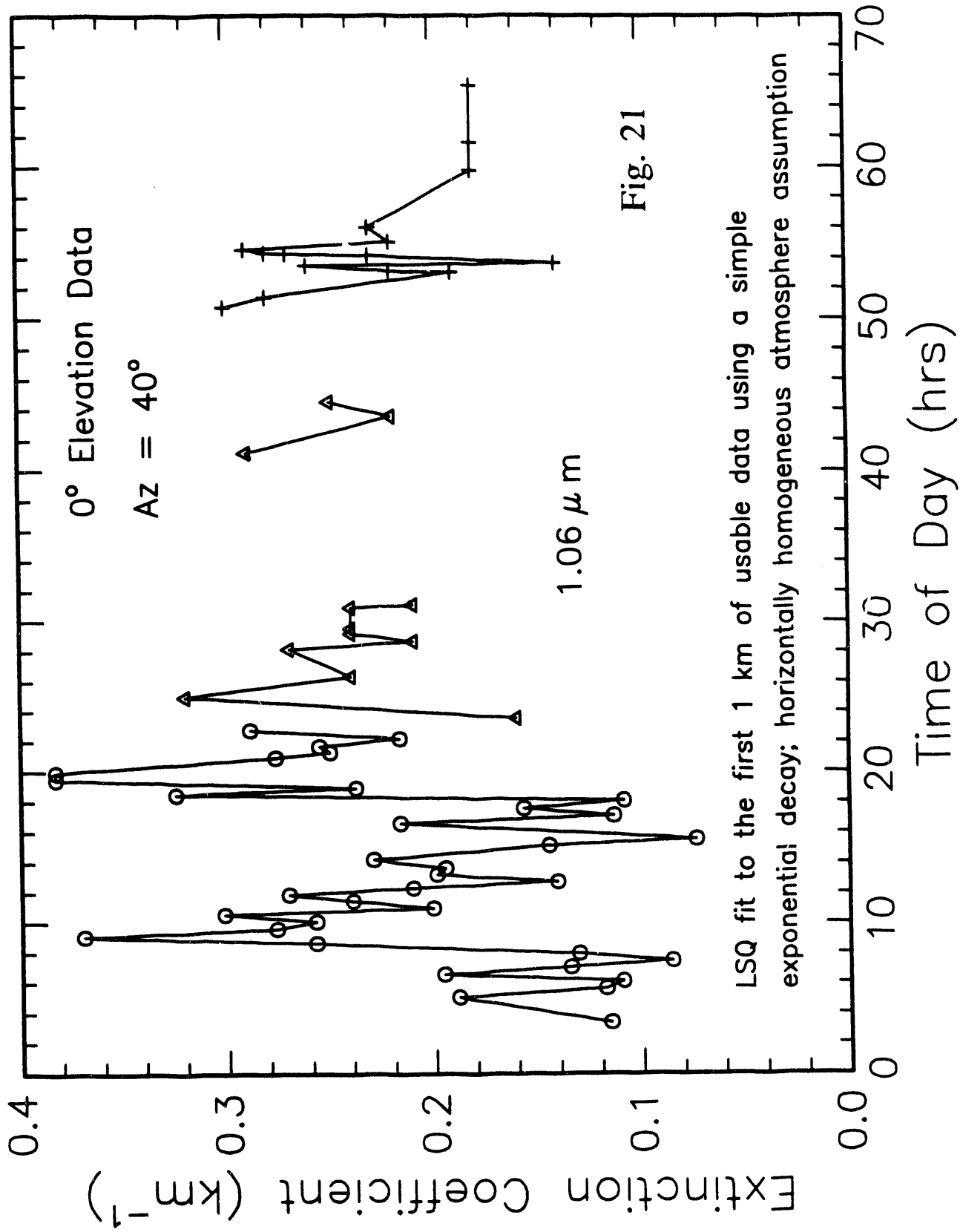
Fig. 19



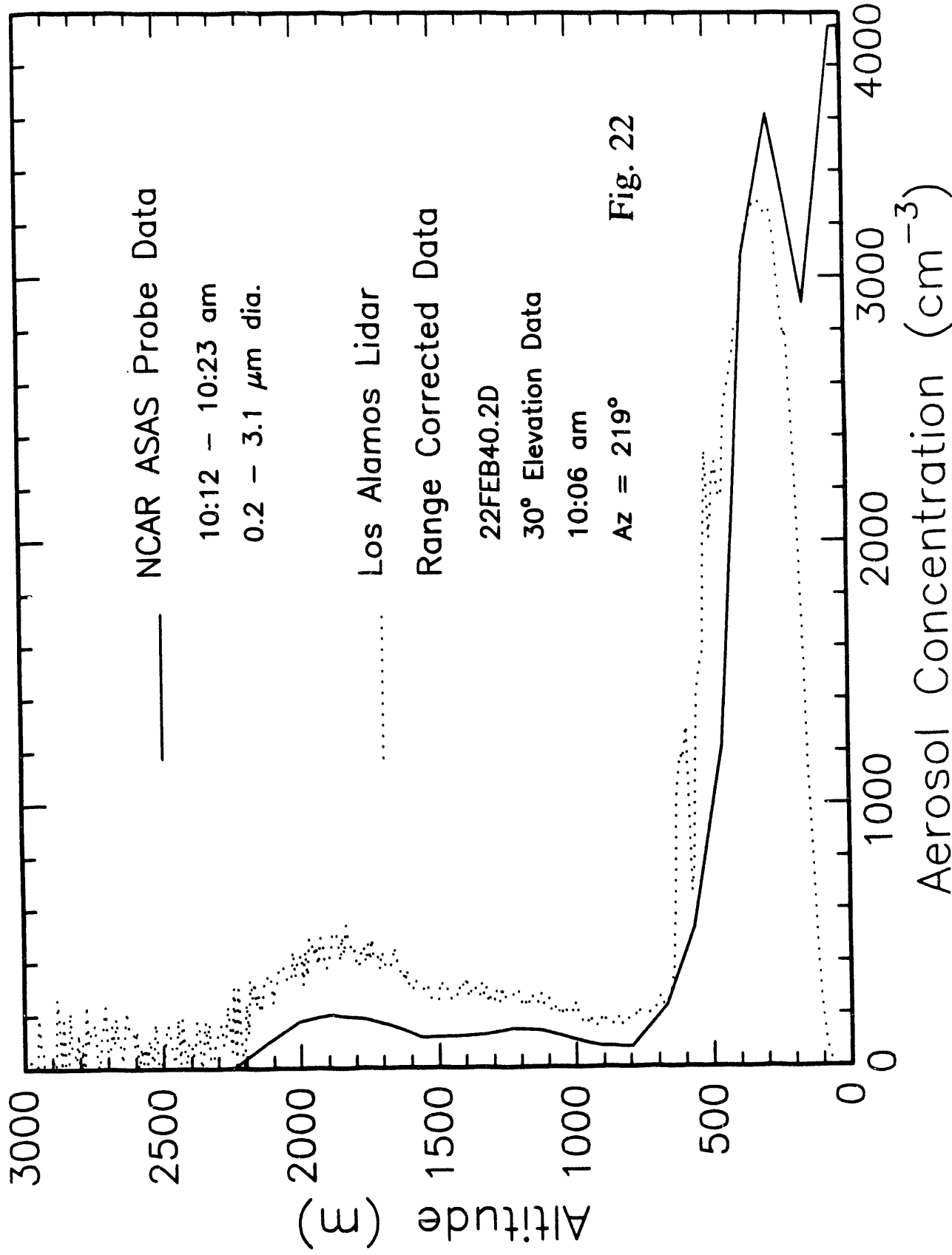
UNAM Site February 26, 1991



UNAM Site February 26-28, 1991



# Mexico City February 22, 1991



2/22/1991 10:1 Scans=10 Az: 90.00 Elev: 8.00; Vertical scan/90/8-50x1/2500/10 db/10MHZ

### Vertical Scan; File:E\FEB22.91\22FEB40.2D

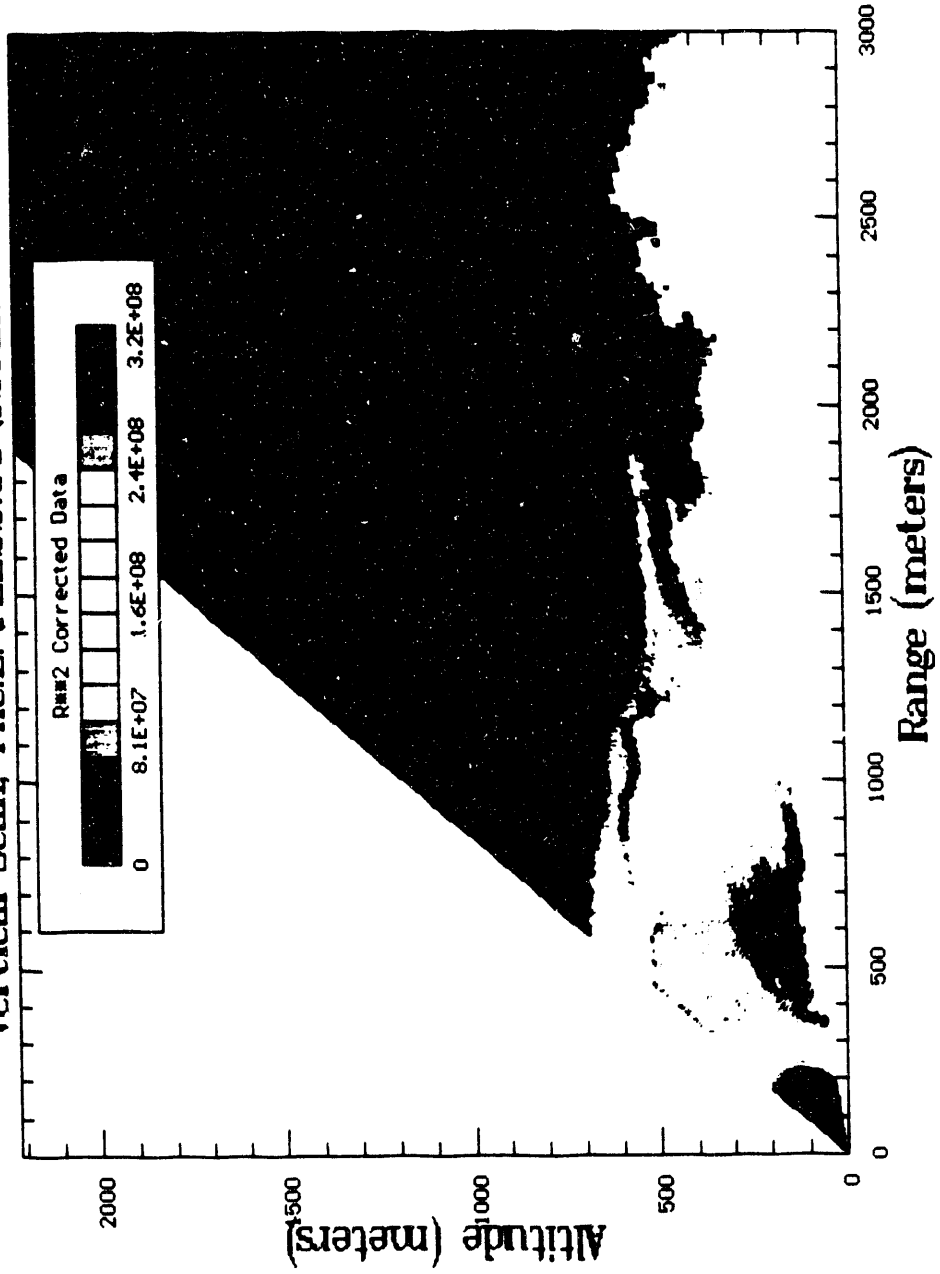
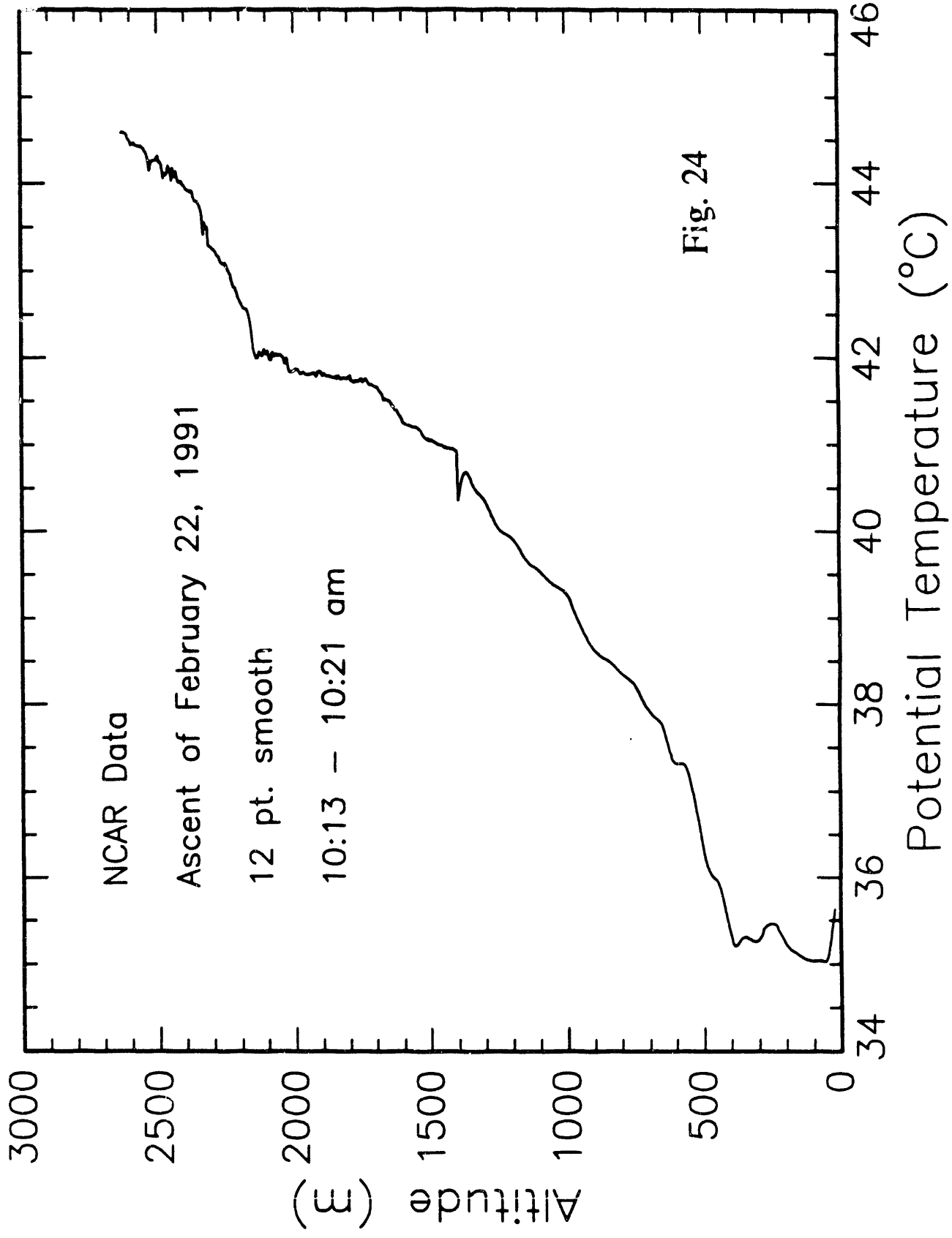
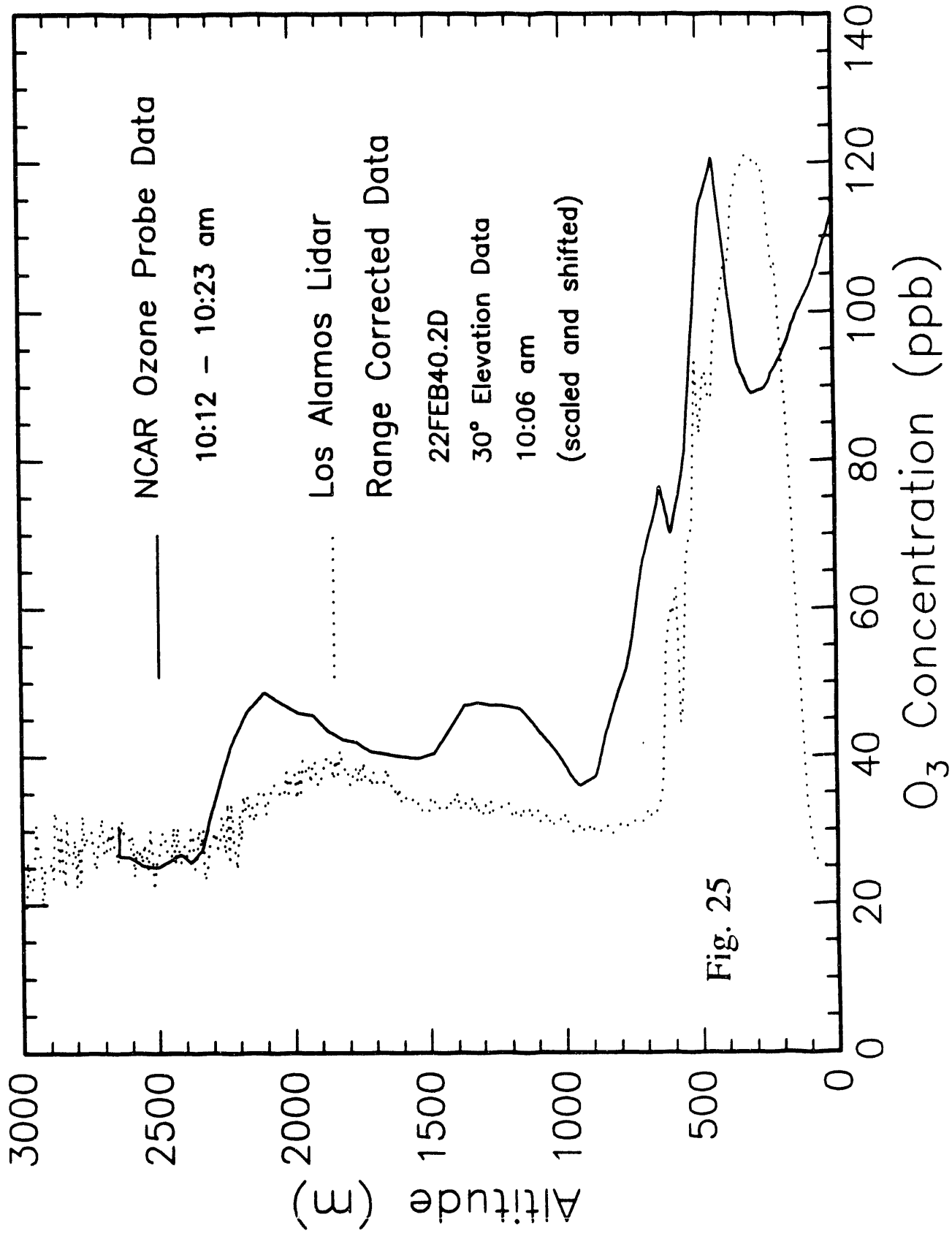


Fig. 23

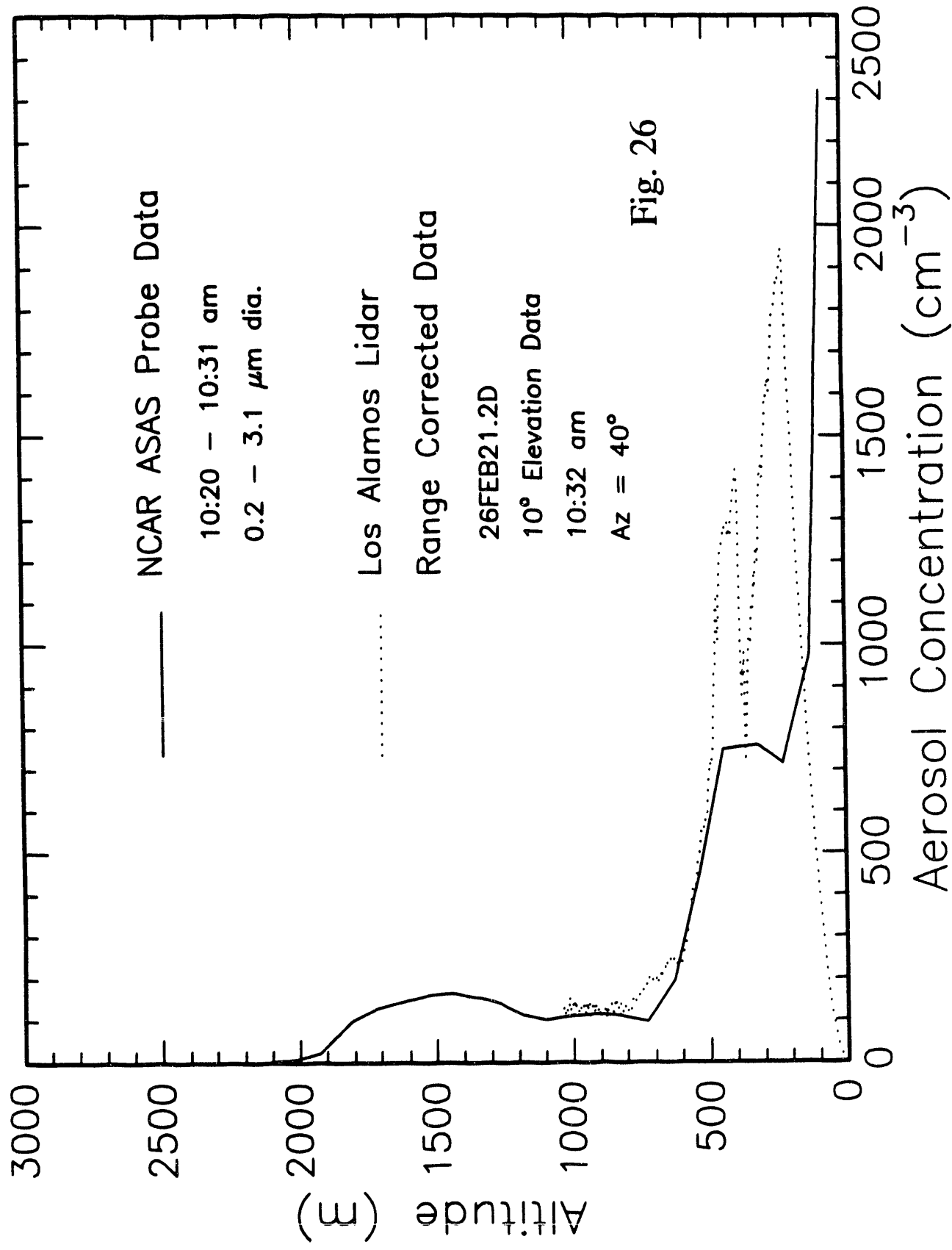
# Mexico City February 22, 1991



Mexico City February 22, 1991



# Mexico City February 26, 1991



2-26-1991 10:22 Scans=50 Azi: 90.00 Elev: 0.00; vert scan 0-30x.25

### Vertical Scan: File:E:\FEB26.91\26FEB21.2D

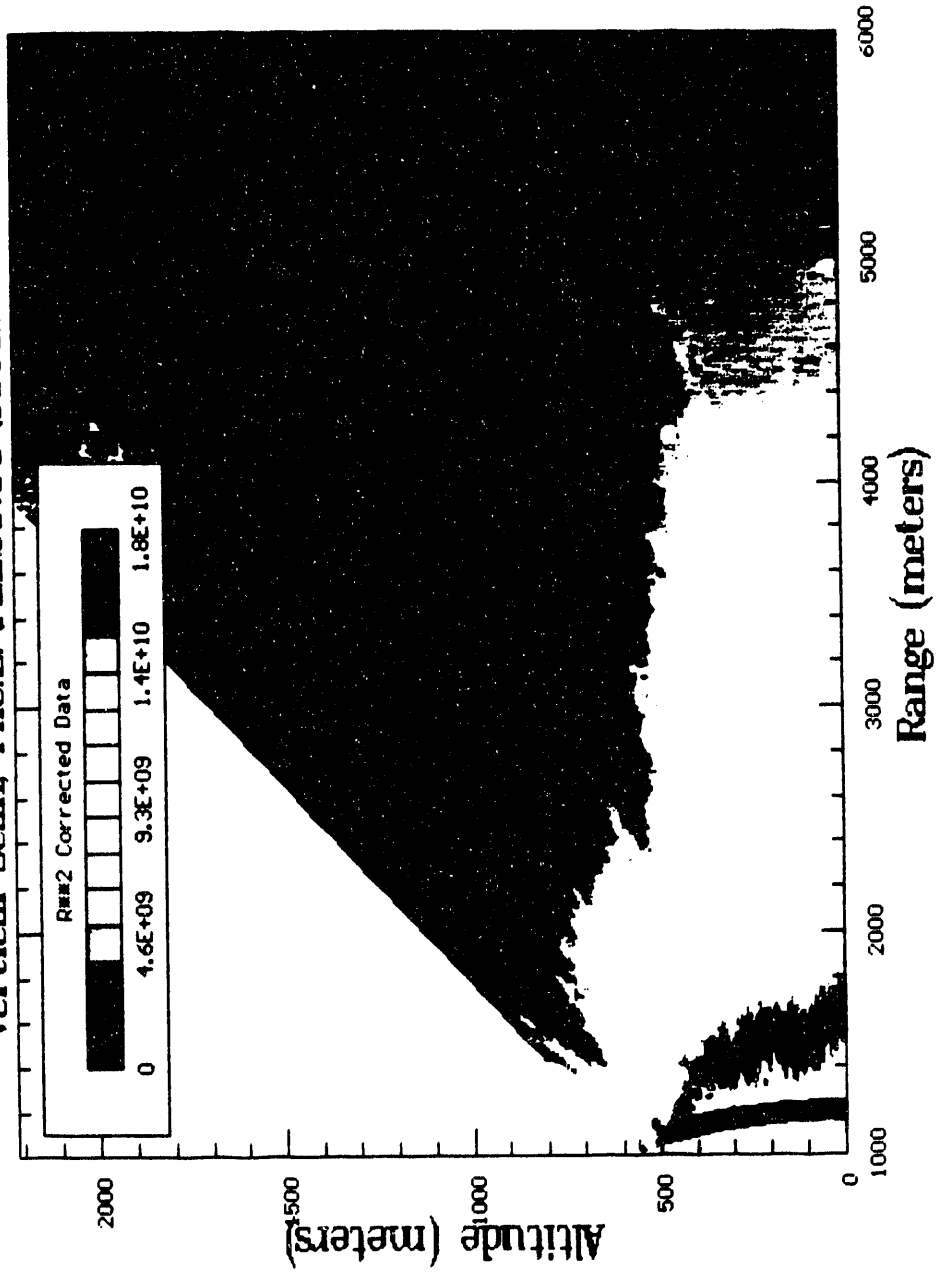
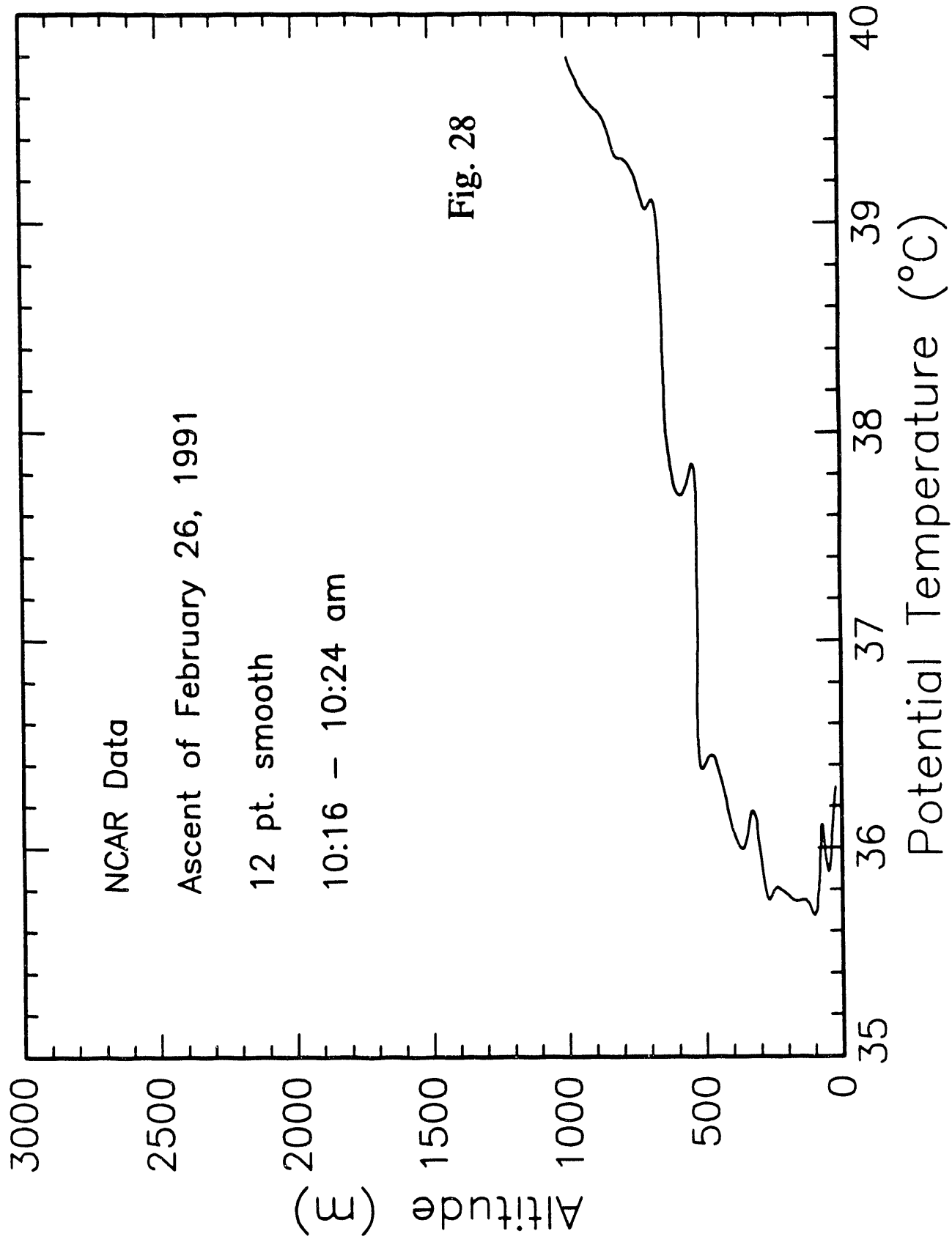


Fig. 27



# Mexico City February 26, 1991



# Mexico City February 26, 1991

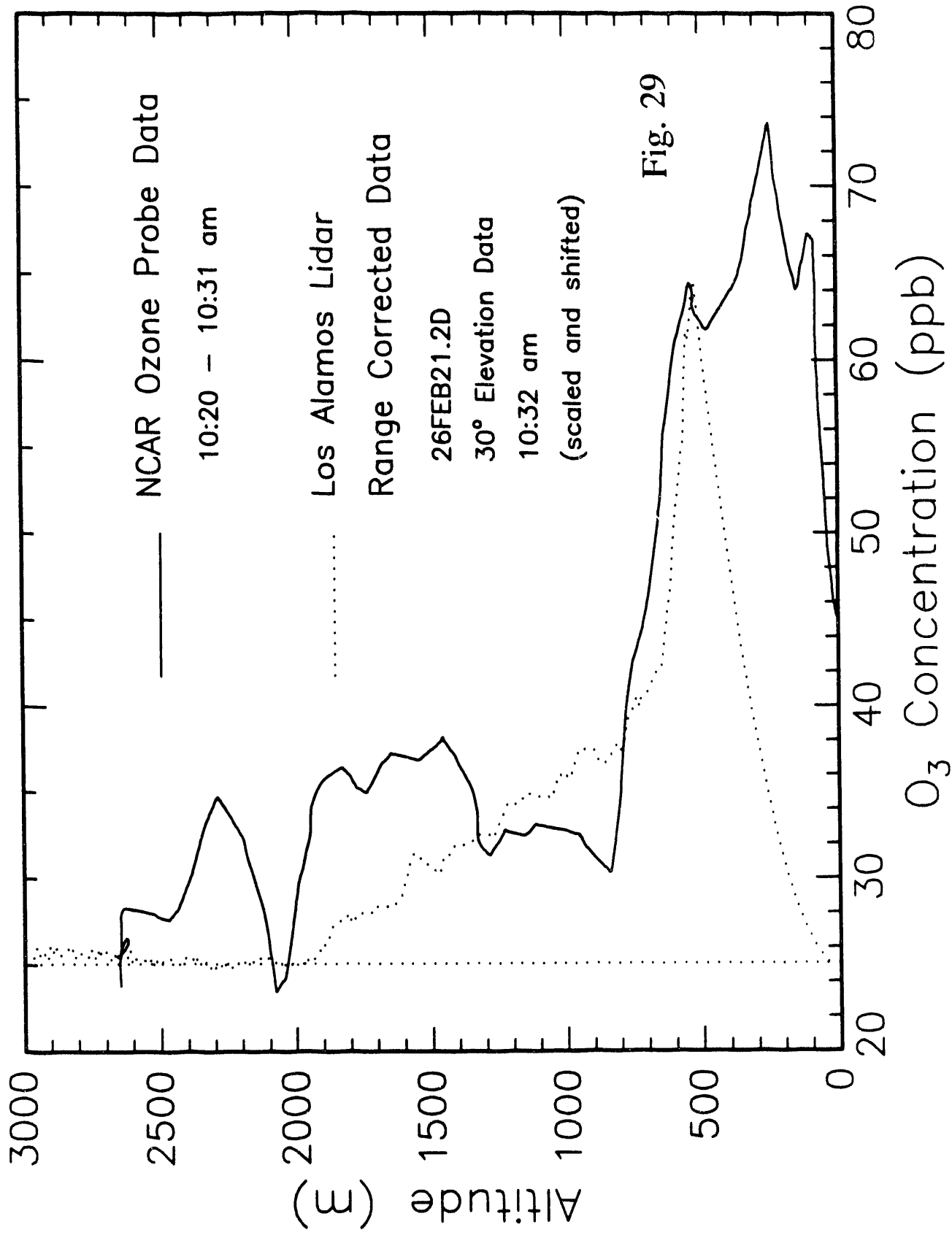
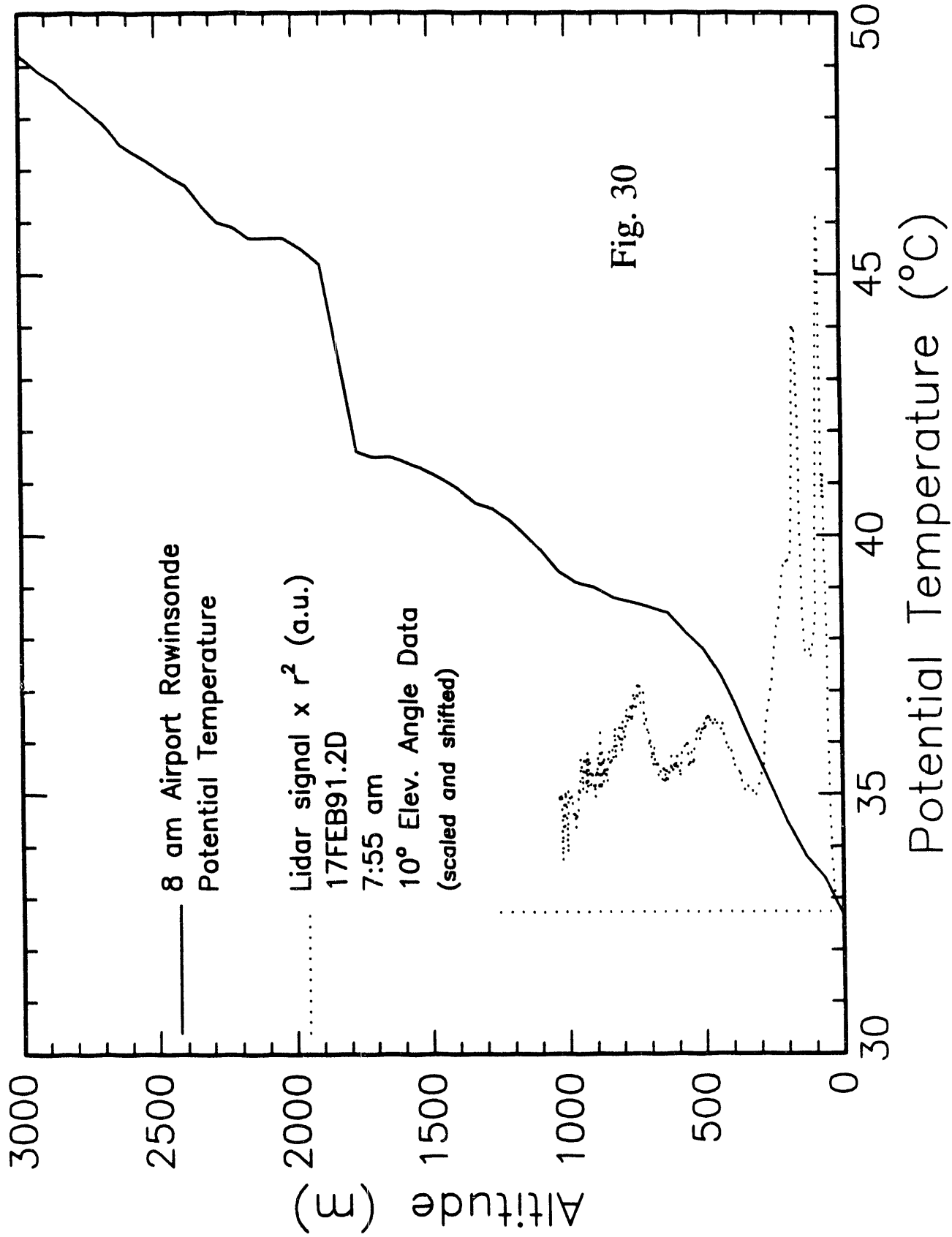


Fig. 29

Mexico City February 17, 1991



2/17/1991 7:50 Scans=50 Az: 60.00 Elev: 10.00; Vertical scan 1 deg step

**Vertical Scan; File:E:\FEB17.91\17FEB91.2D**

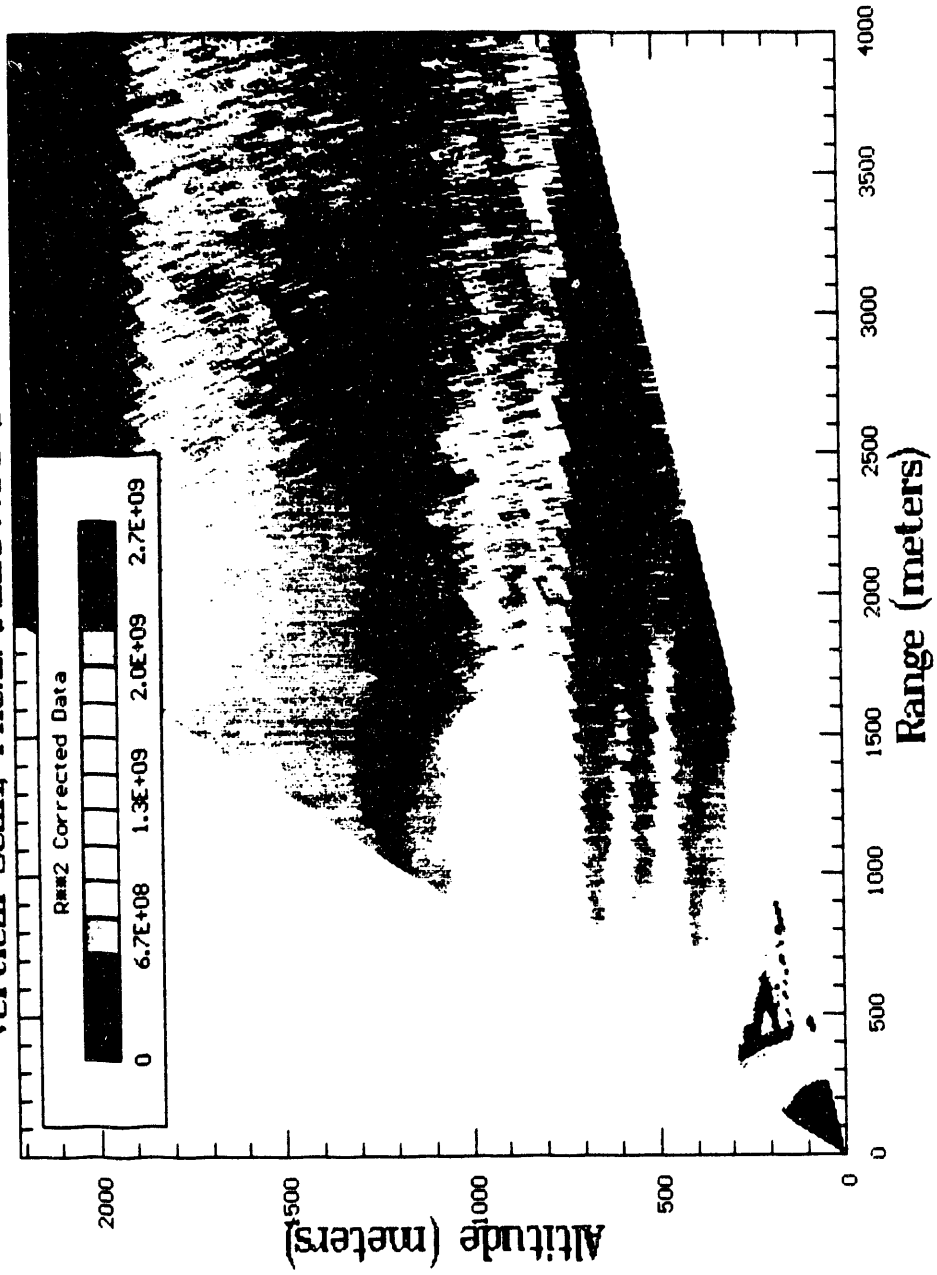
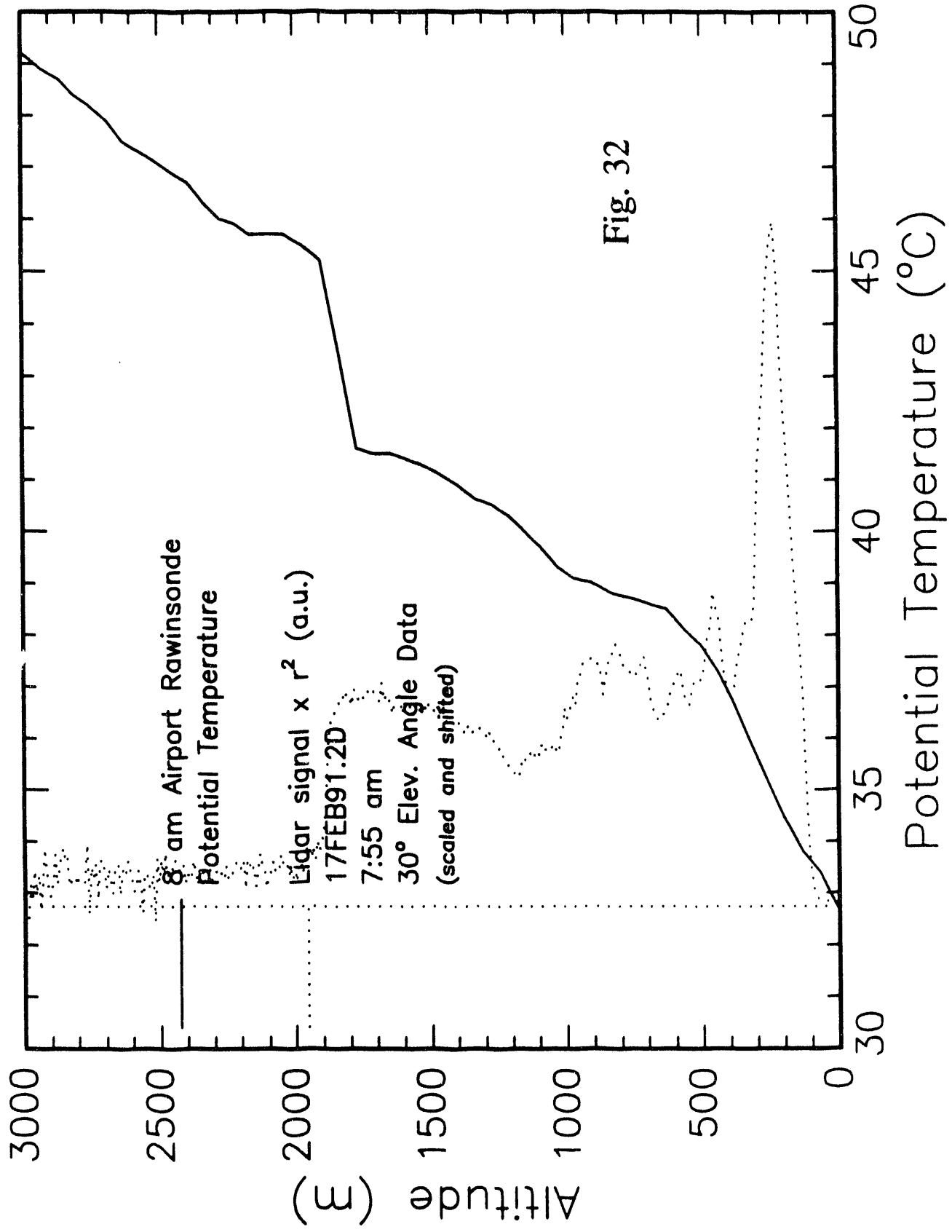


Fig. 31

Mexico City February 17, 1991



Mexico City February 22, 1991

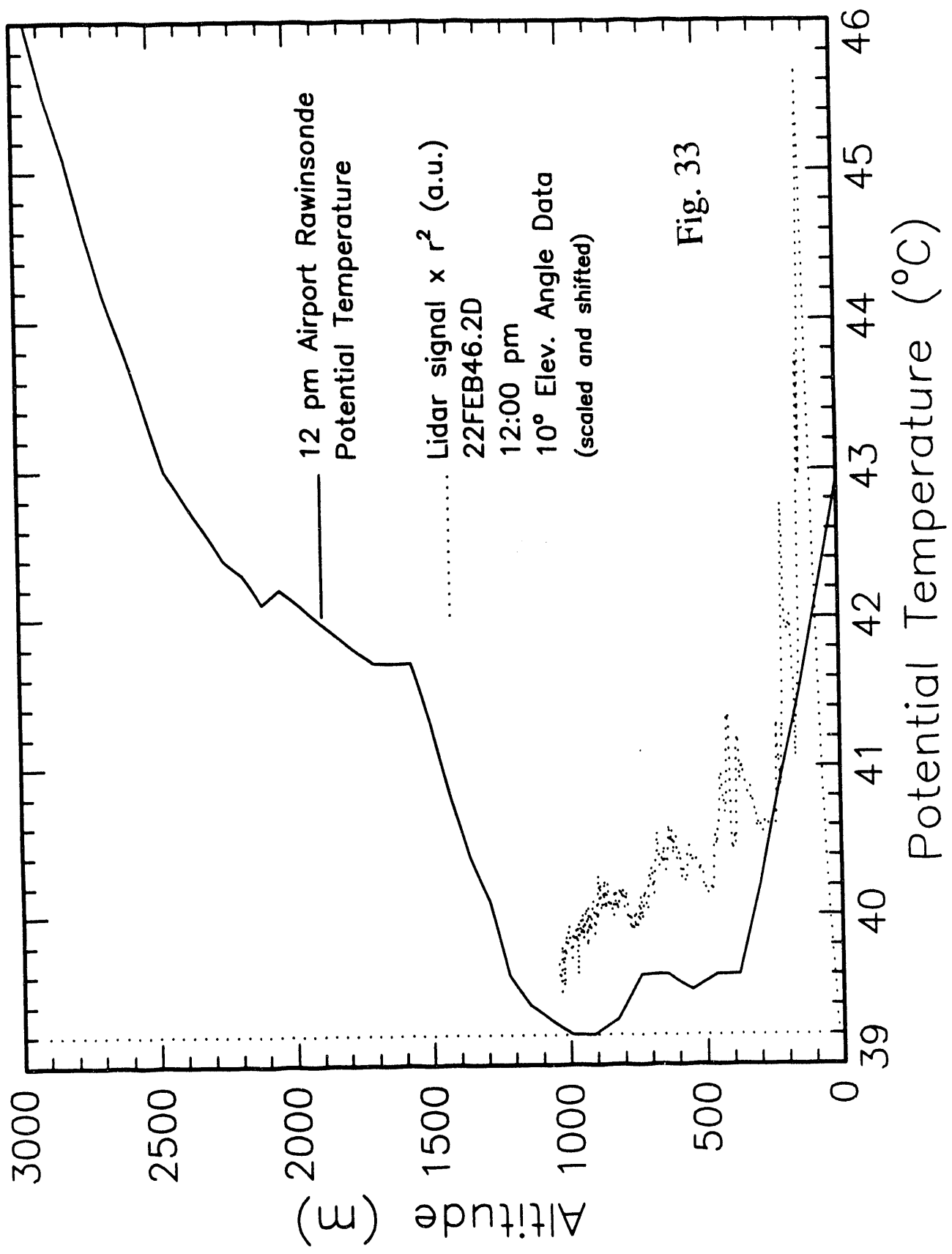


Fig. 33

2-22-1991 11:57 Scans=10 Az: 120.00 Elev: 8.00; Vertical scan/120-8-50x1/250v/0db

### Vertical Scan; File:E\FEB22.91\22FEB46.2D

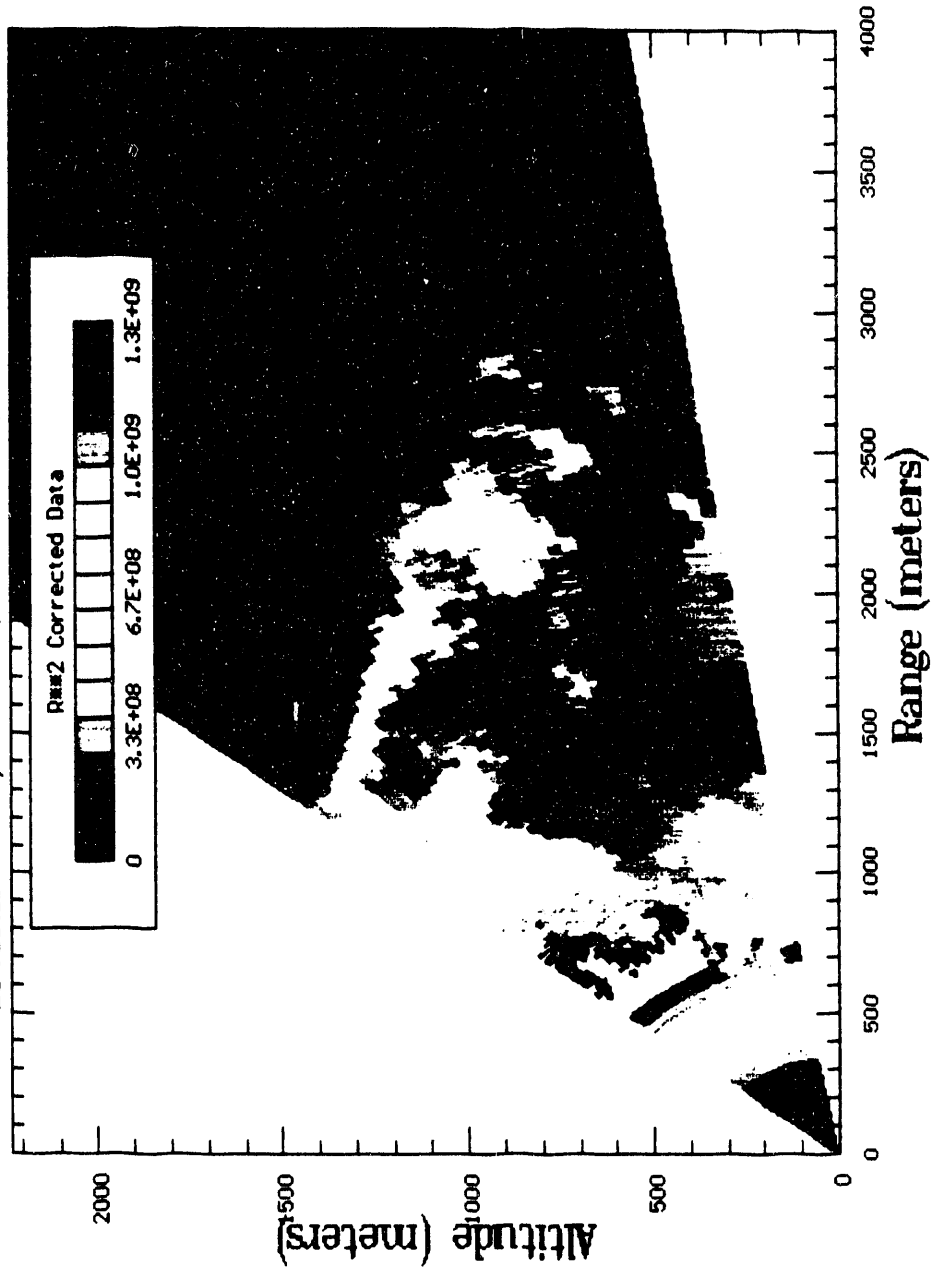
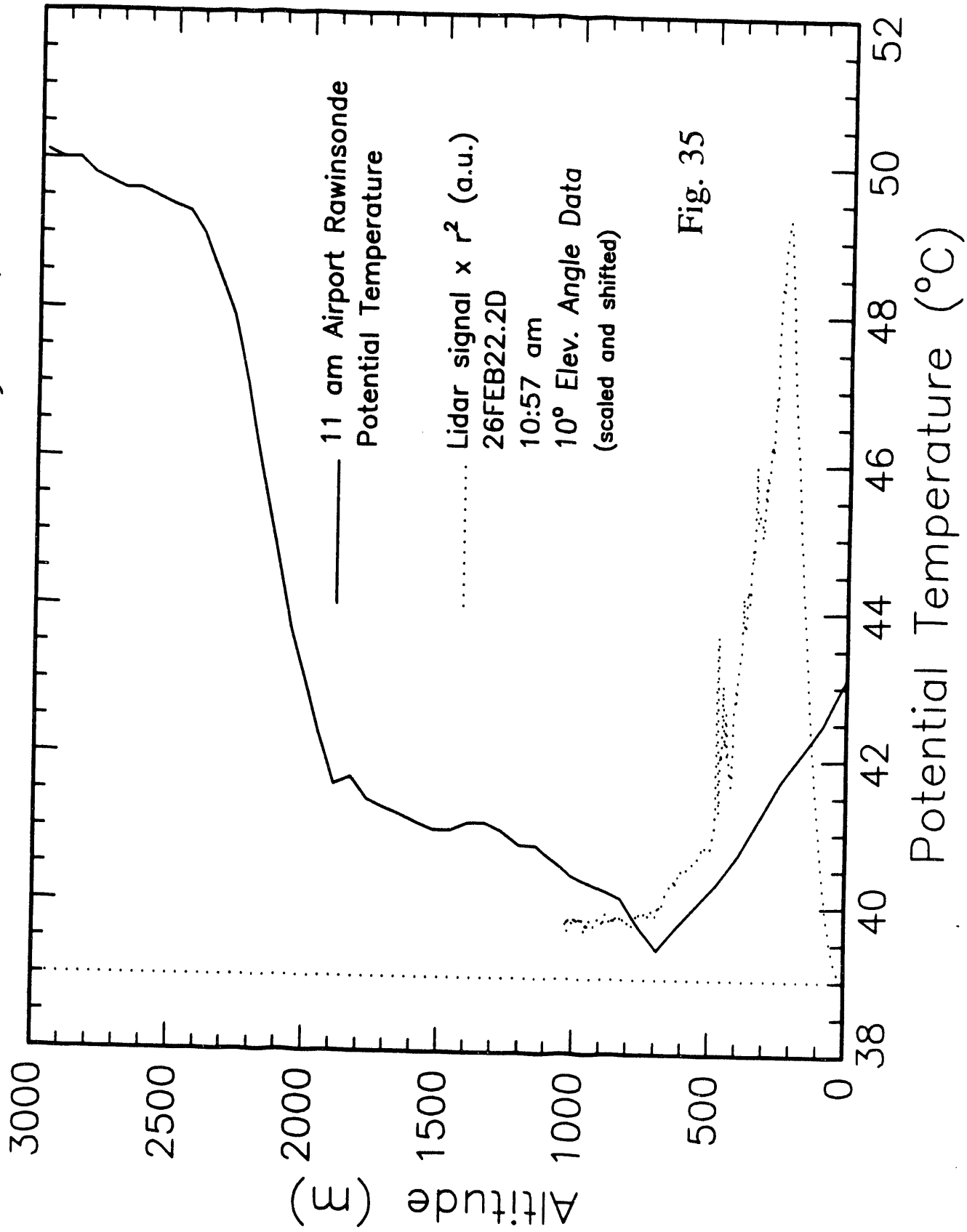


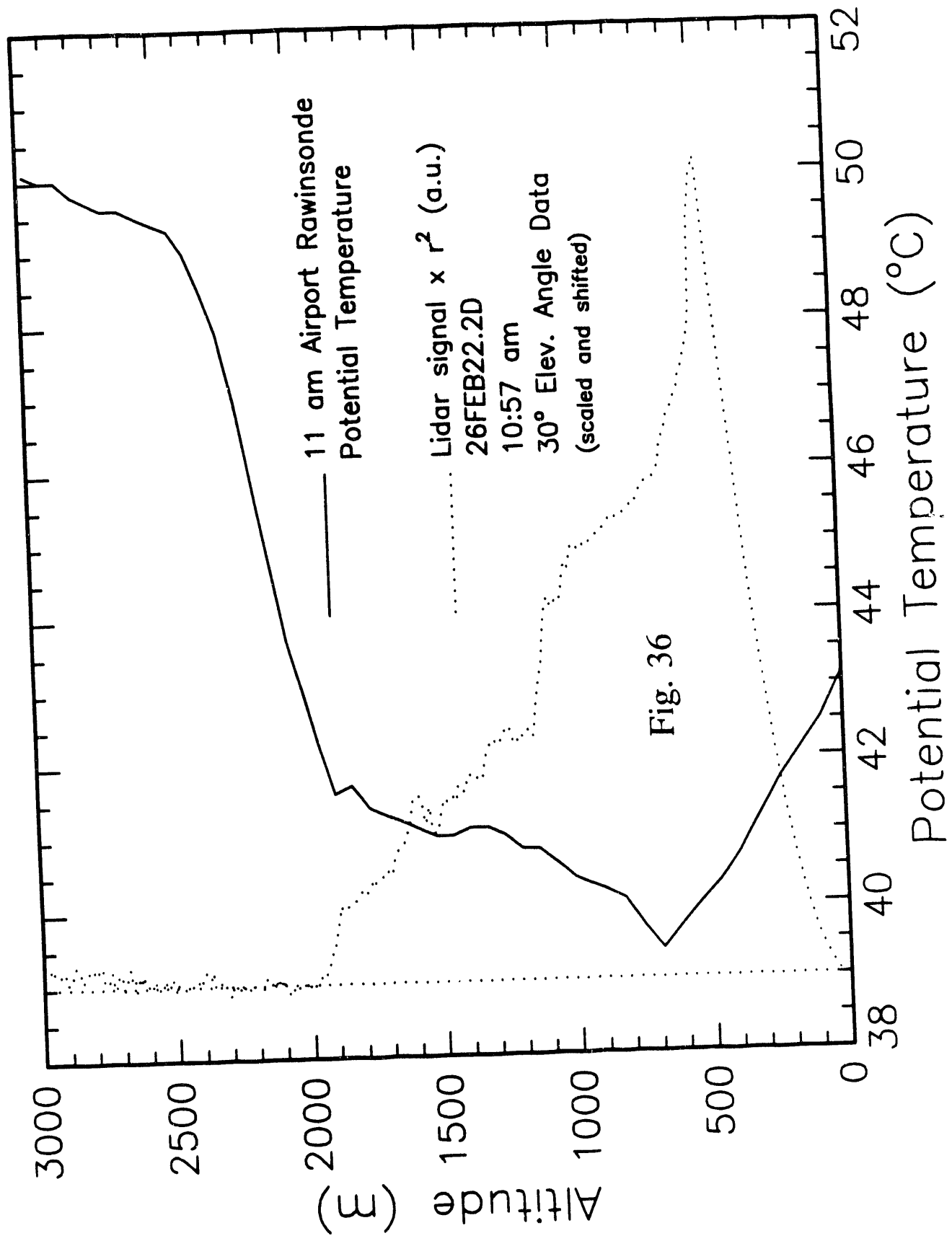
Fig. 34

Mexico City February 26, 1991





Mexico City February 26, 1991



2/26/1991 10:47 Scans=50 Azi: 90.00 Elev: 0.00; vert scan 0-30x.25

Vertical Scan; File:E\FEB26.91\26FEB22.2D

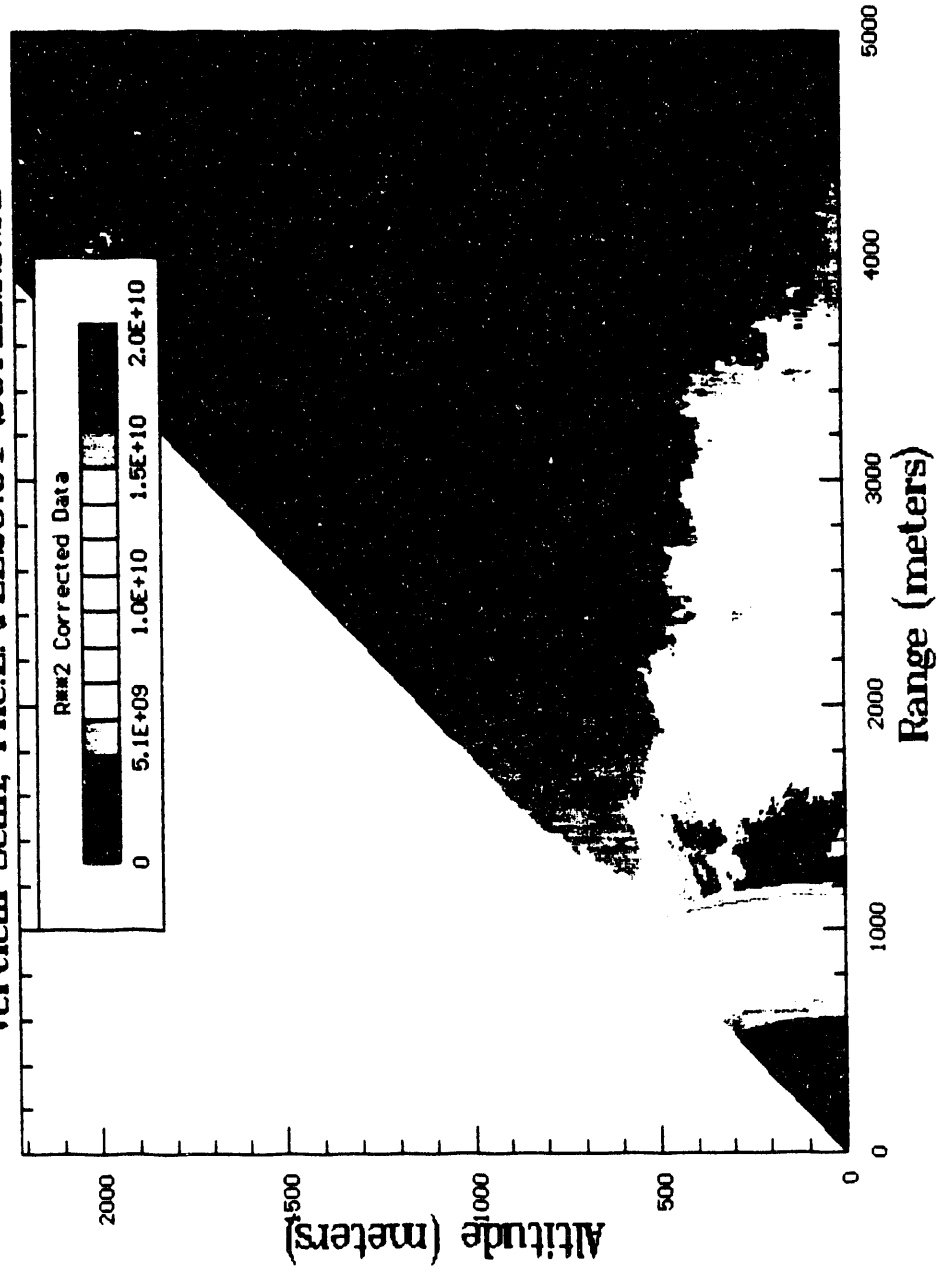


Fig. 37



# **Appendix A**

## **Data Logs**

**Mexico City Project LIDAR Notebook Index**

**THERMO-ELECTRIC POWER PLANT SITE**

**February 16 - 18, 1991**

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
16FEB01	2D	679520	12:17a		54	V	25	90	284	10-50	325	0	n
16FEB02	2D	762060	1:05a		54	V	25	90	284	5-50	325	0	n
16FEB03	2D	844600	1:18a		54	H	50	60-110	254-304	25	325	0	n
16FEB04	2D	679520	1:59a		54	V	50	90	284	10-50	325	0	n
16FEB05	2D	844600	2:10a		54	H	50	60-110	254-304	30	325	0	n
16FEB06	DAT	19076	2:16a		54	dat	100	90	284	10	325	0	n
16FEB07	DAT	19076	2:19a		54	dat	100	90	284	20	325	0	n
16FEB08	DAT	19076	2:20a		54	dat	100	90	284	30	325	0	n
16FEB09	DAT	19076	2:22a		55	dat	100	90	284	40	325	0	n
16FEB10	DAT	19076	2:23a		55	dat	100	90	284	50	325	0	n
16FEB11	DAT	19076	2:25a		55	dat	100	90	284	50	325	0	n
16FEB12	2D	679520	2:44a	2:35a	55	V	100	90	284	10-50	325	0	n
16FEB13	2D	679520	2:57a	2:45a	55	V	100	110	304	10-50	325	0	n
16FEB14	2D	679520	3:37a	3:33a	55	V	50	90	284	10-50	325	0	n
16FEB15	3D	2875084	4:06a	3:44a	55	3D	50	60-110	254-304	10-50	325	0	n
16FEB16	2D	679520	5:01a	5:00a	56	V	25	110	304	10-50	325	0	n
16FEB17	DAT	19076	5:05a	5:06a	56	dat	100	110	304	20	325	0	n
16FEB18	DAT	19076	5:07a	5:08a	56	dat	100	110	304	35	325	0	n
16FEB19	DAT	19076	5:09a	5:11a	56	dat	100	110	304	50	325	0	n
16FEB20	2D	679520	5:18a	5:15a	56	V	25	110	304	10-50	325	0	n
16FEB21	DAT	19076	5:22a	5:24a	56	dat	100	110	304	20	290	0	n
16FEB22	DAT	19076	5:24a	5:25a	56	dat	100	110	304	35	290	0	n
16FEB23	DAT	19076	5:26a	5:27a	56	dat	100	110	304	50	290	0	n
16FEB25	2D	679520	5:33a	5:30a	56	V	25	110	304	10-50	290	0	n
16FEB26	DAT	19076	5:37a	5:38a	56	dat	100	110	304	20	290	0	n
16FEB27	DAT	19076	5:39a	5:40a	56	dat	100	110	304	35	290	0	n
16FEB28	DAT	19076	5:42a	5:42a	56	dat	100	110	304	50	290	0	n
16FEB29	2D	679520	6:01a	6:00a	56	V	25	110	304	10-50	270	0	n
16FEB30	DAT	19076	6:08a	6:10a	56	dat	100	110	304	20	268	0	n
16FEB31	DAT	19076	6:18a		56	dat	100	110	304	20	268	0	n
16FEB32	DAT	19076	9:55a	9:55a	57	dat	10	130	224	30	268	0	n
16FEB33	2D	679520	10:03a	9:58a	57	V	50	130	224	10-50	326	0	n
16FEB34	2D	679520	10:14a	10:10a	57	V	50	60	254	10-50	326	0	n
16FEB35	DAT	19076	10:18a	10:20a	57	dat	100	60	254	20	326	0	n
16FEB36	DAT	19076	10:19a	10:22a	57	dat	100	60	254	35	326	0	n

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
16FEB37	DAT	19076	10:21a	10:23a	57	dat	100	60	254	50	326	0	n
16FEB38	2D	679520	10:49a	10:45a	57	V	50	60	254	10-50	326	0	n
16FEB39	DAT	19076	10:54a	10:56a	57	dat	100	60	254	20	326	0	n
16FEB40	DAT	19076	10:56a	10:58a	57	dat	100	60	254	35	326	0	n
16FEB41	DAT	19076	10:59a	11:00a	57	dat	100	60	254	50	326	0	n
16FEB42	2D	679520	12:44p	12:37p	57	V	50	60	254	10-50	310	0	n
16FEB43	DAT	19076	12:48p	12:47p	57	dat	100	60	254	20	310	0	n
16FEB44	DAT	19076	12:49p	12:50p	57	dat	100	60	254	35	310	0	n
16FEB45	DAT	19076	12:52p	12:54p	57	dat	100	60	254	50	310	0	n
16FEB46	2D	679520	1:02p	12:56p	57	V	50	90	284	10-50	310	0	n
16FEB47	DAT	19076	1:06p	1:03p	57	dat	100	90	284	20	310	0	n
16FEB48	DAT	19076	1:07p	1:06p	57	dat	100	90	284	20	300	0	n
16FEB49	DAT	19076	1:10p	1:12p	57	dat	100	90	284	35	300	0	n
16FEB50	DAT	19076	1:13p	1:15p	57	dat	100	90	284	50	300	0	n
16FEB51	2D	679520	1:27p	1:24p	58	V	50	130	324	10-50	300	0	n
16FEB52	3D	10402732	2:59p	1:53p	58	3D	10	60-120	254-314	10-50	300	0	n
16FEB53	DAT	19076	5:41p			dat	100	60	254	10	270	0	n
16FEB54	2D	1009680	5:50p	5:53p	59	H	50	60-120	254-314	10	300	0	n
16FEB55	2D	679520	6:13p	6:08p	59	V	50	60	254	10-50	300	0	n
16FEB56	2D	679520	6:26p	6:20p	59	V	50	90	284	10-50	300	0	n
16FEB57	2D	679520	6:35p		59	V	50	120	314	10-50	300	0	n
16FEB58	DAT	19076	9:29p	9:30p	60	dat	100	90	284	20	300	0	n
16FEB59	DAT	19076	9:32p	9:32p	60	dat	100	90	284	50	300	0	n
16FEB60	2D	679520	9:43p	9:37p	60	V	50	90	284	10-50	290	0	n
16FEB61	2D	679520	10:03p	9:58p	60	V	50	60	254	10-50	290	0	n
16FEB62	2D	679520	10:28p	10:18p	60	V	50	120	314	10-50	290	0	n
16FEB63	2D	679520	11:34p	11:30p	61	V	50	90	284	10-50	290	0	n
16FEB64	DAT	19076	11:50p		61	dat	50	90	284	50	290	0	n
16FEB65	DAT	19076	11:57p		61	dat	50	90	284	30	290	0	n
16FEB66	DAT	19076	12:01a		61	dat	50	90	284	10	290	0	n
16FEB67	DAT	19076	12:05a		61	dat	50	90	284	10	290	0	n
16FEB68	2D	679520	12:13a		61	V	50	90	284	10-50	150	0	n
16FEB69	2D	679520	12:35a	12:30a	62	V	50	30	224	10-50	290	0	n

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
17FEB70	2D	679520	12:45a		62	V	50	60	254	10-50	290	0	n
17FEB71	2D	679520	12:55a	12:50a	62	V	50	90	284	10-50	290	0	n
17FEB72	2D	679520	1:05a	1:00a	62	V	50	120	314	10-50	290	0	n
17FEB73	2D	679520	2:28a		62	V	50	60	254	10-50	290	0	n
17FEB74	2D	679520	2:39a	2:35a	62	V	50	90	284	10-50	290	0	n
17FEB75	2D	679520	2:54a	2:50a	62	V	50	90	284	10-50	150	0	n
17FEB76	2D	679520	3:05a	3:00a	62	V	50	120	314	10-50	290	0	n
17FEB77	DAT	19076	3:38a	3:30a	62	dat	50	90	284	10	290	0	n
17FEB78	DAT	19076	3:45a		63	dat	50	90	284	50	290	0	n
17FEB79	2D	679520	4:16a	4:12a	63	V	50	90	284	10-50	290	0	n
17FEB80	2D	679520	4:26a	4:22a	63	V	50	60	254	10-50	290	0	n
17FEB81	2D	679520	4:37a	4:33a	63	V	50	120	314	10-50	290	0	n
17FEB82	2D	1009680	4:52a	4:46a	63	H	50	60-120	254	40	290	0	n
17FEB83	2D	1009680	5:03a	4:52a	63	H	50	60-120	254	50	290	0	n
17FEB84	2D	679520	6:21a	6:15a	64	V	50	90	284	10-50	290	0	n
17FEB85	2D	679520	6:29a		64	V	50	90	284	10-50	150	0	n
17FEB86	2D	679520	6:39a	6:35a	64	V	50	60	254	10-50	150	0	n
17FEB87	2D	679520	6:47a	6:44a	64	V	50	60	254	10-50	290	0	n
17FEB88	2D	679520	7:01a	-7:00a	64	V	50	120	314	10-50	290	0	n
17FEB89	2D	679520	7:09a	-7:10a	64	V	50	120	314	10-50	150	0	n
17FEB90	2D	679520	7:47a	7:42a	64	V	50	60	254	10-50	150	0	n
17FEB91	2D	679520	7:55a		64	V	50	60	254	10-50	290	0	n
17FEB92	2D	679520	8:05a	-8:00a	65	V	50	120	314	10-50	290	0	n
17FEB93	2D	679520	8:16a	-8:15a	65	V	50	120	314	10-50	150	0	n
17FEB94	2D	679520	8:25a	8:21a	65	V	50	90	284	10-50	150	0	n
17FEB95	2D	596980	8:36a	8:34a	65	V	50	30	224	15-50	150	0	n
17FEB96	2D	596980	8:46a	8:42a	65	V	50	30	224	15-50	290	0	n
17FEB97	2D	1009680	9:00a	8:42a	65	V	50	30	224	15-50	290	0	n
17FEB98	2D	679520	9:18a	8:55a	65	H	50	60-120	254-314	50	290	0	n
17FEB99	2D	679520	9:32a	9:12a	65	V	50	60	254	10-50	290	0	n
17FEB100	2D	762060	12:48p		66	V	50	120	314	10-50	290	0	n
17FEB101	2D	762060	12:57p	12:35p	66	V	50	110	120	5-50	290	0	n
17FEB102	2D	762060	1:06p	12:50p	66	V	50	120	130	5-50	290	0	n
17FEB105	DAT	19076	7:49p	1:00p	67	dat	50	92	102	10	290	0	n
17FEB106	DAT	19076	8:08p		67	dat	50	90	100	30.5	290	0	n
17FEB107	2D	762060	8:18p		67	V	50	120	130	5-50	290	0	n



File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
17FEB108	2D	596980	8:38p	67	V	50	110	120	3-10	290	0	n	
17FEB109	2D	1570952	8:56p	68	V	50	70	80	3-50	290	0	n	
17FEB110	2D	1570952	9:29p	68	V	20	110	120	3-50	290	0	n	
17FEB111	2D	762060	9:52p	68	V	50	120	130	5-50	290	0	n	
17FEB112	2D	762060	10:04p	69	V	50	120	130	5-50	290	0	n	
17FEB113	2D	762060	10:22p	69	V	50	120	130	5-50	290	0	n	
17FEB114	2D	762060	10:34p	69	V	50	120	130	5-50	290	0	n	
17FEB115	2D	762060	10:48p	69	V	50	120	130	5-50	290	0	n	
17FEB116	2D	762060	11:06p	69	V	50	120	130	5-50	290	0	n	
18FEB01	3D	11261148	12:47a	69	3D	10	60-120	70-130	6-50	290	0	n	
18FEB02	2D	762060	1:09a	69	V	50	80	90	5-50	150	0	n	
18FEB03	2D	762060	6:01a	70	V	50	90	100	5-50	150	0	n	
18FEB04	2D	762060	6:18a	70	V	50	90	100	5-50	150	0	n	
18FEB05	2D	1504920	6:37a	70	V	50	90	100	5-50	150	0	n	
18FEB06	2D	1504920	6:53a	70	V	50	90	100	5-50	150	0	n	
18FEB07	2D	1504920	7:08a	70	V	50	90	100	5-50	150	0	n	
18FEB08	2D	1504920	7:23a	70	V	50	90	100	5-50	150	0	n	
18FEB09	2D	1504920	7:41a	70	V	50	120	130	5-50	150	0	n	
18FEB10	2D	1504920	7:55a	70	V	50	120	130	5-50	150	0	n	
18FEB11	2D	1504920	8:10a	70	V	50	120	130	5-50	150	0	n	
18FEB12	2D	1504920	8:24a	70	V	50	120	130	5-50	150	0	n	
18FEB13	2D	1504920	8:39a	70	V	50	120	130	5-50	150	0	n	
18FEB14	2D	1504920	8:53a	71	V	50	120	130	5-50	150	0	n	
18FEB15	2D	1504920	9:08a	71	V	50	130	140	5-50	150	0	n	
18FEB16	2D	1504920	9:23a	71	V	50	130	140	5-50	150	0	n	
18FEB17	2D	1207900	9:38a	71	V	50	130	140	5-50	150	0	n	

**Mexico City Project LIDAR Notebook Index**

**POLYTECHNIC INSTITUTE (CINVESTAV) SITE**

**February 20 - 23, 1991**

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	IO MHz Filt.
20FEB01	DAT	6788	12:36a		79	dat	50	90	219	10	300	10	y
20FEB02	DAT	6788	12:39a		79	dat	50	90	219	10	300	10	n
20FEB03	2D	175712	12:48a		78	V	50	90	219	10-50	300	10	y
20FEB04	DAT	19076	2:36a	2:30a	80	dat	100	90	219	30	300	10	y
20FEB05	DAT	19076	2:41a	2:46a	80	dat	100	90	219	30	200	10	y
20FEB06	DAT	19076	2:47a	2:47a	80	dat	100	90	219	50	200	10	y
20FEB07	DAT	19076	2:56a	2:56a	81	dat	100	90	219	50	200	20	y
20FEB08	DAT	19076	2:59a	3:00a	81	dat	100	90	219	50	200	10	y
20FEB09	DAT	19076	3:03a	3:01a	81	dat	100	90	219	20	200	10	y
20FEB10	DAT	19076	3:06a	3:05a	81	dat	100	90	219	20	250	20	y
20FEB11	DAT	19076	3:07a	3:07a	81	dat	100	90	219	20	300	20	y
20FEB12	DAT	19076	3:09a	3:09a	81	dat	100	90	219	10	300	20	y
20FEB13	2D	1339840	3:21a	3:11a	81	V	50	90	219	10-50	300	20	y
20FEB14	2D	1339840	3:40a	3:31a	81	V	50	30	159	10-50	300	20	y
20FEB15	2D	1339840	3:54a	3:45a	82	V	50	120	249	10-50	300	20	y
20FEB16	3D	10237652	4:51a	4:07a	82	3D		60-120	189-249	10-50	300	20	y
20FEB17	2D	679520	4:59a	4:55a	82	V	10	90	219	10-50	300	20	y
20FEB18	2D	679520	5:07a	5:03a	83	V	10	90	219	10-50	300	20	y
20FEB19	2D	679520	5:14a	5:15a	83	V	10	75	204	10-50	300	20	y
20FEB20	2D	679520	5:20a	5:19a	83	V	10	60	189	10-50	300	20	y
20FEB21	2D	679520	5:26a	5:22a	83	V	10	105	234	10-50	300	20	y
20FEB22	2D	679520	5:32a	5:28a	83	V	10	120	249	10-50	300	20	y
20FEB23	DAT	19076	6:10a	6:08a	84	dat	1	90	219	10	300	10	y
20FEB24	DAT	19076	6:11a	6:09a	84	dat	10	90	219	10	300	10?	y
20FEB25	2D	1339840	6:20a	6:12a	84	V	10	90	219	10-50	300	10?	y
20FEB26	DAT	19076	6:24a	6:23a	84	dat	10	90	219	10	325	20	y
20FEB27	2D	679520	6:31a	6:25a	84	V	50	90	219	10-50	325	20	y
20FEB28	2D	679520	6:39a	6:33a	85	V	50	90	219	10-50	300	10	y
20FEB29	2D	679520	6:56a	6:50a	85	V	50	90	219	10-50	300	10?	y
20FEB30	2D	679520	7:06a	7:00a	85	V	50	90	219	10-50	300	10?	y
20FEB31	2D	679520	7:18a	7:15a	85	V	50	90	219	10-50	300	10?	y
20FEB32	2D	679520	7:31a	7:26a	85	V	50	90	219	10-50	300	10?	y
20FEB33	2D	679520	7:48a	7:44a	85	V	50	90	219	10-50	300	10?	y
20FEB34	2D	679520	8:01a	7:57a	86	V	50	90	219	10-50	300	10?	y
20FEB35	2D	679520	8:17a	8:13a	86	V	50	90	219	10-50	300	10?	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
20FEB36	2D	679520	8:30a	8:27a	86	V	50	90	219	10-50	300	10?	y
20FEB37	2D	679520	8:46a	8:42a	86	V	50	90	219	10-50	300	10?	y
20FEB38	2D	679520	9:02a	8:57a	86	V	50	90	219	10-50	300	10?	y
20FEB39	2D	679520	9:18a	9:13a	86	V	50	90	219	10-50	300	10?	y
20FEB40	2D	679520	9:32a	9:26a	86	V	50	90	219	10-50	300?	10?	y
20FEB41	2D	679520	9:47a	9:45a	87	V	25	90	219	10-50	300?	10?	y
20FEB42	2D	679520	10:02a	10:03a	87	V	25	90	219	10-50	300?	10?	y
20FEB43	2D	729044	10:16a	10:15a	87	V	25	90	219	7-50	300?	10?	y
20FEB44	2D	729044	10:31a	10:30a	87	V	25	90	219	7-50	300?	10?	y
20FEB45	2D	332976	10:39a	10:37a	87	V	25	161	189	7-50	300?	10?	y
20FEB46	2D	729044	10:47a	10:45a	87	V	25	90	219	7-50	300?	10?	y
20FEB47	2D	696028	10:55a	10:52a	88	V	25	161	189	9-50	300?	10?	y
20FEB48	2D	729044	11:05a	11:01a	88	V	25	90	219	7-50	300?	10?	y
20FEB49	2D	729044	11:25a	11:20a	88	V	25	90	219	7-50	300?	10?	y
20FEB50	2D	729044	11:34a	11:30a	88	V	25	90	219	7-50	300?	10?	y
20FEB51	2D	729044	11:48a	11:45a	88	V	25	90	219	7-50	300?	10?	y
20FEB52	2D	729044	12:03p	12:00a	88	V	25	90	219	7-50	300?	10?	y
20FEB53	2D	1384156	1:50p		88	V	25	161	189	9-50	300?	10?	y
20FEB54	2D	1384156	1:57p		88	V	25	161	189	9-50	300?	10?	y
20FEB55	2D	679520	2:43p	2:42p	88	V	25	161	189	10-50	300?	10?	y
20FEB56	2D	1339840	3:05p	3:00p	89	V	10	161	189	10-50	300?	0	y
20FEB57	2D	1339840	3:16p	3:15p	89	V	10	161	189	10-50	300?	0	y
20FEB58	2D	844600	3:29p	3:30p	89	V	10	161	189	10-50	300?	10?	y
20FEB59	2D	2990640	3:51p	3:40p	89	H	10	45-135	174-264	10	300?	10?	y
20FEB60	2D	679520	4:48p	4:45p	89	V	25	45	174	10-50	300?	10?	y
20FEB61	2D	712536	8:29p		90	V	50	90	219	8-50	300	0	y
20FEB62	2D	712536	8:47p		90	V	50	90	219	8-50	400	0	y
20FEB63	2D	712536	9:10p		91	V	50	90	219	8-50	300	0	y
20FEB64	2D	712536	9:20p		91	V	50	90	219	8-50	400	0	y
20FEB65	2D	712536	9:30p		91	V	50	90	219	8-50	300	0	y
20FEB66	2D	712536	9:39p		91	V	50	90	219	8-50	400	0	y
20FEB67	2D	712536	10:49p		91	V	50	90	219	8-50	300	0	y
20FEB68	2D	712536	10:58p		91	V	50	90	219	8-50	400	0	y
20FEB69	2D	712536	11:07p		91	V	50	90	219	8-50	300	0	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
21FEB01	2D	712536	12:13a		91	V	50	90	219	8-50	300	0	y
21FEB02	2D	712536	12:22a		91	V	50	90	219	8-50	300	0	y
21FEB03	2D	712536	12:33a		91	V	50	60	189	8-50	300	0	y
21FEB04	2D	712536	12:43a		91	V	50	120	249	8-50	300	0	y
21FEB05	3D	10749400	2:12a	1:22a	92	3D	10	60-120	189-249	8-50	275	0?	y
21FEB06	2D	712536	2:32a	2:27a	92	V	50	60	189	8-50	300	6	y
21FEB07	2D	712536	2:41a	2:40a	92	V	50	60	189	8-50	300	6	y
21FEB08	2D	712536	2:51a	2:45a	93	V	50	120	249	8-50	300	6	y
21FEB09	2D	712536	4:17a	4:12a	94	V	10	60	189	8-50	270	6	y
21FEB10	2D	712536	4:26a	4:22a	94	V	10	60	189	8-50	200	20	y
21FEB11	2D	712536	4:33a	4:30a	94	V	10	90	219	10-50	200	20	y
21FEB12	2D	712536	4:40a	4:38a	94	V	10	120	249	10-50	200	20	y
21FEB13	TD	1653492	4:48a	4:48a	94	TD	10	90	219	15	200?	20	y
21FEB14	TD	10732892	5:02a	4:53a	94	TD	10	90	219	15	200?	20	y
21FEB15	TD	10732892	5:14a	5:08a	95	TD	10	90	219	15	200?	20	y
21FEB16	TD	10732892	5:24a	5:21a	95	TD	10	90	219	15	200?	20	y
21FEB17	TD	4756996	5:30a	5:35a	95	TD	10	90	219	15	200?	20	y
21FEB18	TD	6440936	5:36a	5:42a	95	TD	10	90	219	15	200?	20	y
21FEB19	TD	1455396	5:39a	5:51c	95	TD	10	90	219	15	200?	20	y
21FEB20	TD	4146200	5:44a	5:53a	96	TD	10	90	219	15	200?	10	y
21FEB21	TD	10237652	5:55a	6:00a	96	TD	10	90	219	15	200?	16	y
21FEB22	TD	9907492	6:04a	6:12a	96	TD	10	90	219	15	200?	16?	y
21FEB23	TD	2809052	6:08a	6:25a	97	TD	10	90	219	15	200?	16?	y
21FEB24	TD	9957016	6:19a	6:32a	97	TD	10	90	219	15	200?	16?	y
21FEB25	TD	10732892	6:29a	6:42a	97	TD	10	90	219	15	200?	16?	y
21FEB26	2D	712536	7:26a	7:45a	98	V	50	90	219	8-50	200?	16?	y
21FEB27	2D	712536	10:34a	10:31a	99	V	25	90	219	8-50	200?	16?	y
21FEB28	3D	4492868	11:02a	10:45a	99	3D	10	60-90	189-219	8-25	325	6	y
21FEB29	3D	4492868	11:25a	11:07a	99	3D	10	60-90	189-219	8-25	325	6	y
21FEB30	3D	6936052	11:52a	11:35a	99	3D	10	90-110	219-239	8-28	325	6	y
21FEB31	2D	712536	11:59a	12:01p	99	V	25	110	239	8-50	325	6	y
21FEB32	2D	712536	12:07p	12:10p	99	V	25	120	249	8-50	325	6	y
21FEB33	2D	712536	12:17p	12:18p	99	V	25	90	219	8-50	325	6	y
21FEB34	2D	712536	12:40p	12:38p	99	V	25	90	219	8-50	325	6	y
21FEB35	2D	1009680	12:50p	12:46p	99	H	25	60-120	189-249	8	325	0	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	IO MHz Filt.
21FEB36	2D	1009680	12:58p	12:55p	99	H	25	60-120	189-249	8	265	0	y
21FEB37	2D	1191268	1:34p	1:30p	100	H	25	90-161	219	8	265	0	y
21FEB38	2D	1151268	1:42p	1:40p	100	H	25	90-161	219	10	265	0	y
21FEB39	2D	1191268	1:49p	1:50p	100	H	25	90-161	219	12	265	0	y
21FEB40	TD	6985700	2:13p	2:10p	100	TD	10	90	219	7.5	265	0	y
21FEB41	TD	7002084	2:21p	2:25p	100	TD	2	90	219	7.5	265	0	y
21FEB42	TD	7002084	2:25p	2:28p	100	TD	5	90	219	7.5	265	0	y
21FEB43	2D	1405872	2:32p	2:35p	100	V	10	160	189	8-50	265	0	y
22FEB01	DAT	6788	2:56a		104	dat	1	90	219	10			y
22FEB02	2D	184152	3:36a	3:30a	104	V	10	90	219	8-50	250	16	y
22FEB03	2D	184152	3:44a	3:41a	104	V	10	30	159	8-50	250	16	y
22FEB04	2D	184152	3:52a	3:39a	104	V	10	120	249	8-50	250	16	y
22FEB05	2D	712536	4:15a	4:13a	104	V	10	120	249	8-50	250	16	y
22FEB06	2D	712536	4:22a	4:20a	104	V	10	90	219	8-50	250	16	y
22FEB07	2D	712536	4:27a	4:25a	104	V	10	30	159	8-50	250	16	y
22FEB08	2D	712536	4:45a	4:43a	105	V	10	60	189	8-50	250	16	y
22FEB09	2D	712536	4:50a	4:48a	105	V	10	90	219	8-50	250	16	y
22FEB10	2D	712536	4:55a	4:53a	105	V	10	120	249	8-50	250	16	y
22FEB11	2D	712536	5:14a	5:12a	105	V	10	90	219	8-50	250	16	y
22FEB12	2D	712536	5:19a	5:17a	105	V	10	60	189	8-50	250	16	y
22FEB13	2D	712536	5:24a	5:23a	105	V	10	120	249	8-50	250	16	y
22FEB14	2D	712536	5:45a	5:43a	105	V	10	90	219	8-50	250	16	y
22FEB15	2D	712536	5:50a	5:49a	105	V	10	60	189	8-50	250	16	y
22FEB16	2D	712536	5:55a	5:56a	106	V	10	120	249	8-50	250	16	y
22FEB17	DAT	19076	6:07a		106	dat	1	90	219	30	250	16	y
22FEB18	DAT	19076	6:08a		106	dat	10	90	219	30	250	16	y
22FEB19	DAT	19076	6:10a		106	dat	100	90	219	30	250	16	y
22FEB20	2D	712536	6:28a	6:26a	106	V	10	120	249	8-50	250	16	y
22FEB21	2D	712536	6:35a	6:33a	106	V	10	90	219	8-50	250	16	y
22FEB22	TD	4129692	6:41a	6:38a	107	TD	25	90	219	14	250	16	y
22FEB23	2D	712536	6:51a	6:50a	107	V	10	60	189	8-50	250	16	y
22FEB24	2D	712536	7:19a	7:15a	107	V	10	60	189	8-50	250	16	y
22FEB25	2D	712536	7:24a	7:23a	107	V	10	90	219	8-50	250	16	y

File name	File ext.	File size (bytes)	ALR Time	Log Book # Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
22FEB26	2D	712536	7:30a	7:29a	107	V	10	120	249	8-50	250	16	y
22FEB27	2D	712536	7:57a	8:00a	107	V	10	90	219	8-50	250	16	y
22FEB28	2D	712536	8:03a	8:04a	107	V	10	60	189	8-50	250	16	y
22FEB29	2D	712536	8:10a	8:10a	107	V	10	120	249	8-50	250	16	y
22FEB30	2D	712536	8:49a	8:49a	108	V	10	90	219	8-50	250	16	y
22FEB31	2D	712536	8:54a	8:54a	108	V	10	60	189	8-50	250	16	y
22FEB32	2D	712536	9:00a	9:00a	108	V	10	120	249	8-50	250	16	y
22FEB33	DAT	19076	9:22a	9:20a	108	dat	10	90	219	15	250	16	y
22FEB34	2D	1372856	9:28a	9:28a	108	V	10	90	219	9-50	250	16	y
22FEB35	DAT	19076	9:30a	9:30a	108	dat	10	90	219	45	250	16	y
22FEB36	DAT	19076	9:32a	9:32a	108	dat	10	90	219	45	250	16	y
22FEB37	DAT	19076	9:37a	9:37a	108	dat	10	90	219	9	250	16	y
22FEB38	DAT	19076	9:39a	9:39a	108	dat	10	90	219	9	250	16	y
22FEB39	2D	1405872	9:59a	10:00a	108	V	10	90	219	8-50	250	0	y
22FEB40	2D	1405872	10:06a	10:05a	108	V	10	90	219	8-50	250	10	y
22FEB41	3D	5978712	10:41a	10:15a	108	3D	10	60-110	189	8-50	250	10	y
22FEB42	2D	712536	10:49a	11:00a	108	V	10	90	219	8-50	250	10	y
22FEB43	2D	1009680	11:18a	11:20a	108	H	10	60-120	189-249	8	250	16	y
22FEB44	2D	1405872	11:28a	11:30a	108	V	10	80	209	8-50	250	16	y
22FEB45	2D	1405872	11:35a	11:37a	108	V	10	80	209	8-50	250	0	y
22FEB46	2D	712536	12:00p	12:00p	108	V	10	120	249	8-50	250	0	y
22FEB47	2D	712536	12:05p	12:10p	108	V	10	120	249	8-50	250	16	y
22FEB48	2D	712536	12:10p	12:15p	108	V	10	120	249	8-50	290?	16	y
22FEB49	2D	1405872	12:17p	12:20p	109	V	10	120	249	8-50	290	16	y
22FEB50	2D	1405872	12:24p	12:27p	109	V	10	120	249	8-50	290	0	y
22FEB51	2D	679520	12:29p	12:35p	109	H	10	80-120	209-249	8	290	0	y
22FEB52	2D	679520	12:33p	12:38p	109	H	10	80-120	209-249	8	290	16	y
22FEB53	2D	679520	12:37p	12:42p	109	H	10	80-120	209-249	10	290	16	y
22FEB54	2D	679520	12:41p	12:48p	109	H	10	80-120	209-249	10	290	0	y
22FEB55	2D	1009680	1:25p	1:30pp	109	H	10	80-120	209-249	8	290	16	y
22FEB56	2D	1405872	1:39p	1:40p	109	V	10	140	269	8-50	290	16	y
22FEB57	2D	1339840	1:58p	2:00p	109	V	10	160	289	10-50	290	16	y
22FEB58	2D	844600	3:11p	3:08p	110	H	10	40-90	169-219	10	290	16	y
22FEB59	2D	1339840	3:17p	3:17p	110	V	10	40	169	10-50	290	16	y
22FEB60	2D	1339840	3:37p	3:35p	110	V	10	40	169	10-50	310	16	y
22FEB61	2D	1339840	3:43p	3:43p	110	V	10	40	169	10-50	325	16	y

File name	File ext.	File size (bytes)	ALR Time	Log Book # Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
22FEB62	2D	1339840	3:48p	3:50p	110	V	10	40	169	10-50	360	16	y
22FEB63	2D	1339840	4:01p	4:00p	110	V	10	40	169	10-50	370	16	y
22FEB64	2D	1339840	4:16p	4:15p	110	V	10	40	169	10-50	370	16	y
22FEB65	2D	1339840	4:28p	4:30p	111	V	10	40	169	10-50	370	16	y
22FEB66	2D	1339840	4:43p	4:45p	111	V	10	40	169	10-50	370	16	y
22FEB67	2D	1339840	4:47p	4:50p	111	V	10	40	169	10-50	370	0	y
22FEB68	2D	1339840	4:53p	4:55p	111	V	10	40	169	10-50	370	16	y
22FEB69	2D	1339840	5:00p		111	V	10	90	219	10-50	371	0	y
22FEB70	2D	1092344	5:08p	5:10p	111	V	10	90	219	10-50	371	16	y
22FEB71	2D	1339840	5:20p		111	V	10	90	219	10-50	371	0	y
22FEB72	2D	1339840	5:25p		111	V	10	90	219	10-50	371	16	y
22FEB73	2D	1339840	5:30p		111	V	10	90	219	10-50	371	0	y
22FEB74	2D	2000160	5:38p	5:39p	111	H	10	30-90	159-219	10	371	0	y
22FEB75	2D	2000160	5:46p		111	H	10	90-150	219-279	10	371	0	y
22FEB76	2D	2000160	5:55p		111	H	10	90-150	219-279	10	371	16	y
22FEB77	2D	2000160	6:00p		111	H	10	90-150	219	10	371	16	y
22FEB78	2D	1405872	6:27p		112	V	10	90	219	8-50	371	16	y
22FEB79	2D	1405872	6:38p		112	V	10	120	249	8-50	371	16	y
22FEB80	2D	1405872	6:44p	6:48p	112	V	10	120	249	8-50	371	0	y
22FEB81	2D	1405872	6:50p	6:54p	112	V	10	30	159	8-50	371	0	y
22FEB82	2D	1405872	6:55p		112	V	10	30	159	8-50	371	16	y
22FEB83	2D	1405872	7:08p	7:13p	112	V	10	90	219	8-50	371	16	y
22FEB84	2D	1405872	7:25p		112	V	10	90	219	8-50	371	16	y
22FEB85	2D	1405872	7:29p		112	V	10	90	219	8-50	371	16	y
22FEB86	2D	1405872	7:40p		112	V	1	90	219	8-50	371	16	y
22FEB87	2D	1405872	7:47p		113	V	10	90	219	8-50	371	16	y
22FEB88	2D	1405872	7:55p	8:03p	113	V	10	90	219	8-50	371	16	y
22FEB89	2D	1405872	8:00p	8:08p	113	V	10	90	219	8-50	371	16	y
22FEB90	2D	1405872	8:04p	8:13p	113	V	10	90	219	8-50	371	16	y
22FEB91	2D	1405872	8:11p	8:24p	113	V	10	90	219	8-50	371	16	y
22FEB92	2D	927264	8:16p	8:28p	113	V	10	90	219	8-50	371	16	y
22FEB93	2D	1405872	8:29p	8:40p	113	V	10	90	219	8-50	371	16	y
22FEB94	2D	1405872	8:36p	8:49p	113	V	10	90	219	8-50	371	16	y
22FEB95	2D	1405872	8:41p	8:55p	113	V	10	90	219	8-50	371	16	y
22FEB96	2D	1405872	8:46p	9:00p	113	V	10	90	219	8-50	371	16	y
22FEB97	2D	1405872	9:30p	9:45p	113	V	10	90	219	8-50	371	16	y



File name	File ext.	File size (bytes)	ALR Time	Log Book # Time	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	I0 MHz Filt.
22FEB98	2D	1405872	9:35p	9:49p 113	V	10	90	219	8-50	371	16	y
22FEB99	2D	1405872	9:40p	9:54p 113	V	10	90	219	8-50	371	16	y
22FEB100	2D	1405872	10:15p	113	V	10	150	279	8-50	371	16	y
22FEB101	2D	1405872	10:19p	113	V	10	150	279	8-50	371	16	y
22FEB102	2D	1405872	10:27p	114	V	10	30	159	8-50	371	16	y
22FEB103	2D	1405872	10:34p	114	V	10	30	159	8-50	371	16	y
23FEB01	DAT	19076	2:56a	2:56a 115	dat	1	141	48	8	300	16	y
23FEB02	DAT	19076	2:59a	2:58a 115	dat	1	141	48	7	300	16	y
23FEB03	2D	1537936	3:04a	3:00a 115	V	10	141	48	4-50	300	16	y
23FEB04	3D	11442736	3:34a	3:07a 115	3D	10	135-145	42-52	4-20	300	16	y
23FEB05	2D	1207776	3:42a	3:42a 116	V	10	135	42	4-40	300	16	y
23FEB06	2D	1207776	3:47a	3:47a 116	V	10	140	47	4-40	300	16	y
23FEB07	2D	1207776	3:52a	3:54a 116	V	10	145	52	4-40	300	16	y
23FEB08	DAT	19076	4:09a	116	dat	10	50	317	8	300	6	y
23FEB09	2D	1405872	4:17a	4:18a 116	V	10	50	317	8-50	300	6	y
23FEB10	2D	1075712	4:34a	4:37a 116	V	10	40	307	8-40	300	6	y
23FEB11	2D	1075712	4:39a	4:42a 116	V	10	60	327	8-40	300	6	y
23FEB12	2D	712536	4:51a	4:54a 116	V	10	110	17	8-50	300	16	y
23FEB13	2D	712536	4:56a	4:59a 116	V	10	120	27	8-50	300	16	y
23FEB14	2D	712536	5:00a	5:04a 117	V	10	130	37	8-50	300	16	y
23FEB15	2D	712536	5:04a	5:07a 117	V	10	140	47	8-50	300	16	y
23FEB16	2D	712536	5:07a	117	V	10	150	57	8-50	300	16	y
23FEB17	3D	7629388	5:32a	5:15a 117	3D	10	110-150	17-57	8-50	300	16	y
23FEB18	2D	679520	5:44a	5:50a 117	H	10	110-150	17-57	10	300	16	y
23FEB19	2D	1339840	5:48a	5:54a 117	H	10	110-150	17-57	10	300	16	y
23FEB20	2D	1405872	6:13a	6:18a 117	V	10	110	17	8-50	300	16	y
23FEB21	2D	1405872	6:18a	6:24a 117	V	10	120	27	8-50	300	16	y
23FEB22	2D	1405872	6:23a	118	V	10	130	37	8-50	300	16	y
23FEB23	2D	1405872	6:28a	118	V	10	140	47	8-50	300	16	y
23FEB24	2D	1405872	6:33a	118	V	10	150	57	8-50	300	16	y
23FEB25	3D	7629388	6:58a	6:48a 118	3D	10	110-150	17-57	8-50	300	16	y
23FEB26	3D	8669392	7:30a	7:20a 118	3D	10	140-150	47-57	8-50	300	16	y
23FEB27	DAT	19076	8:47a	8:48a 118	dat	100	110	17	8	300	20	y

File name	File ext.	File size (bytes)	ALR Time	Log Book #	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
23FEB28	DAT	19076	8:49a	8:49a	119	dat	100	120	27	8	300	20	y
23FEB29	DAT	19076	8:49a	8:50a	119	dat	100	130	37	8	300	20	y
23FEB30	DAT	19076	8:51a	8:51a	119	dat	100	140	47	8	300	20	y
23FEB31	DAT	19076	8:52a	8:52a	119	dat	100	150	57	8	300	20	y
23FEB32	2D	712536	8:55a	8:54a	119	V	10	150	57	8-50	300	20	y
23FEB33	2D	712536	8:58a	8:57a	119	V	10	140	47	8-50	300	20	y
23FEB34	2D	712536	9:01a	9:00a	119	V	10	130	37	8-50	300	20	y
23FEB35	2D	712536	9:05a	9:04a	119	V	10	120	27	8-50	300	20	y
23FEB36	2D	712536	9:11a	9:10a	119	V	10	110	17	8-50	300	20	y
23FEB37	3D	7629388	9:37a	9:15a	120	V	10	110-150	17-57	8-50	300	16	y
23FEB38	3D	1405872	9:46a	9:45a	120	V	10	110	17	8-50	300	16	y
23FEB39	2D	1504920	9:55a	9:55a	120	V	10	50	317	5-50	300	16	y
23FEB40	2D	1405872	10:02a	10:05a	120	V	10	60	327	8-50	300	16	y
23FEB41	2D	679520	10:10a	10:15a	120	V	10	60	327	8-50	300	16	y
23FEB42	2D	679520	10:13a	10:13a	120	V	10	60	327	8-50	300	16	y
23FEB43	2D	679520	10:16a	10:16a	120	V	10	60	327	8-50	300	16	y
23FEB44	2D	679520	10:20a	10:20a	120	V	10	60	327	8-50	300	16	y
23FEB45	2D	679520	10:23a	10:23a	120	V	10	60	327	8-50	300	16	y
23FEB46	2D	679520	10:26a	10:26a	120	V	10	60	327	8-50	300	16	y
23FEB47	2D	679520	10:29a	10:29a	120	V	10	60	327	8-50	300	16	y
23FEB48	2D	679520	10:33a	10:33a	120	V	10	60	327	8-50	300	16	y
23FEB49	2D	679520	10:36a	10:36a	120	V	10	60	327	8-50	300	16	y
23FEB50	2D	679520	10:39a	10:45a	120	V	10	60	327	8-50	300	16	y
23FEB51	2D	679520	10:42a	10:47a	120	V	10	60	327	8-50	300	16	y
23FEB52	2D	679520	10:45a	10:51a	120	V	10	60	327	8-50	300	16	y
23FEB53	2D	679520	10:48a	10:48a	120	V	10	60	327	8-50	300	16	y
23FEB54	2D	679520	10:52a	10:52a	120	V	10	60	327	8-50	300	16	y
23FEB55	2D	679520	10:55a	11:00a	121	V	10	60	327	8-50	300	16	y
23FEB56	2D	679520	10:58a	11:05a	121	V	10	60	327	8-50	300	16	y
23FEB57	2D	679520	11:01a	11:08a	121	V	10	60	327	8-50	300	16	y
23FEB58	2D	679520	11:04a	11:11a	121	V	10	60	327	8-50	300	16	y
23FEB59	2D	679520	11:08a	11:15a	121	V	10	60	327	8-50	300	16	y
23FEB60	2D	679520	11:12a	11:18a	121	V	10	60	327	8-50	300	16	y
23FEB61	2D	679520	11:15a	11:15a	121	V	10	60	327	8-50	300	16	y
23FEB62	2D	679520	11:18a	11:26a	121	V	10	60	327	8-50	340	16	y
23FEB63	2D	679520	11:21a	11:29a	121	V	10	60	327	8-50	375	16	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
23FEB64	2D	679520	11:24a	11:32a	121	V	10	60	327	8-50	375	16	y
23FEB65	2D	679520	11:28a	11:36a	121	V	10	60	327	8-50	325	16	y
23FEB66	2D	19324	11:31a	12:40p	122	V	10	60	327	8-50	325	16	y
23FEB67	2D	1405872	12:42p	12:47p	122	V	10	60	327	8-50	325	16	y
23FEB68	2D	762060	12:47p	12:47p	122	H	10	30-75	297-342	8	325	16	y
23FEB69	2D	1504920	12:51p	12:50p	122	H	10	30-75	297-342	10	325	16	y
23FEB70	2D	1504920	12:55p	12:55p	122	H	10	30-75	297-342	12	325	16	y
23FEB71	2D	1504920	1:03p	1:04p	122	H	10	110-155	17-62	8	325	16	y
23FEB72	2D	1504920	1:07p	1:07p	122	H	10	110-155	17-62	10	325	16	y
23FEB73	2D	1504920	1:11p	1:12p	122	H	10	110-155	17-62	12	325	16	y
23FEB74	2D	1405872	1:16p	1:16p	122	V	10	145	52	8-50	325	16	y
23FEB75	2D	1405872	1:23p	1:24p	122	V	10	130	37	8-50	325	16	y
23FEB76	2D	1405872	1:35p	1:38p	122	V	10	145	52	8-50	325	0	y
23FEB77	2D	1405872	1:51p	1:54p	122	V	10	135	42	8-50	325	0	y
23FEB78	2D	1405872	1:56p	1:59p	122	V	10	125	32	8-50	325	0	y
23FEB79	2D	1405872	2:01p	2:04p	122	V	10	110	17	8-50	325	0	y
23FEB80	2D	1405872	2:51p	2:52p	122	V	10	110	17	8-50	400	0	y
23FEB81	2D	1405872	2:57p	3:00p	122	V	10	145	52	8-50	400	0	y
23FEB82	2D	1158252	3:10p	3:05p	122	V	10	60	327	8-50	400	0	y
23FEB83	2D	1405872	3:26p	3:27p	123	V	10	60	327	8-50	400	0	y
23FEB84	2D	1405872	3:32p	3:35p	123	V	10	145	52	8-50	400	0	y
23FEB85	2D	1405872	4:10p	4:13p	123	V	10	110	17	8-50	325	16	y
23FEB86	2D	1405872	4:15p	4:19p	123	V	10	110	17	8-50	325	0	y
23FEB87	2D	1405872	4:20p	4:25p	123	V	10	145	52	8-50	325	0	y
23FEB88	2D	1405872	4:24p	4:30p	123	V	10	145	52	8-50	325	16	y
23FEB89	2D	1339840	4:31p	4:35p	123	H	10	110-150	17-57	10	325	16	y
23FEB90	2D	762184	4:49p	4:41p	123	V	10	60	327	10-50	325	16	y
23FEB91	2D	1405872	5:14p	5:20p	125	V	10	60	327	8-50	327	16	y
23FEB92	2D	1405872	5:21p	5:20p	125	V	10	110	17	8-50	327	16	y
23FEB93	2D	1405872	6:02p	6:10p	125	V	10	110	17	8-50	327	16	y
23FEB94	2D	1405872	6:21p	6:20p	125	V	10	60	327	8-50	327	16	y
23FEB95	2D	679520	6:44p	6:45p	125	H	10	110-150	17-57	15	327	16	y
23FEB96	2D	679520	6:56p	6:55p	125	H	10	110-150	17-57	15	327	16	y
23FEB97	2D	1339840	7:10p	7:10p	125	V	10	150	57	10-50	327	16	y
23FEB98	2D	679520	7:34p	7:22p	125	V	10	150	57	10-50	327	16	y
23FEB99	2D	679520	7:55p	7:53p	125	V	10	150	57	10-50	327	16	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
23FEB100	2D	679520	8:12p	8:10p	125	V	10	150	57	10-50	250	16	y
23FEB101	2D	679520	8:18p		126	V	10	60	327	10-50	250	16	y

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**UNAM BOTANICAL GARDENS SITE**

**February 25 - March 1, 1991**

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
25FEB01	DAT	19076	11:04p		128	dat	10	90	40	30			y
25FEB02	DAT	19076	11:10p		128	dat	10	90	40	-1			y
26FEB01	DAT	19076	2:08a		129	dat	100	90	40	5	327	0	y
26FEB02	DAT	19076	2:09a		129	dat	10	90	40	30	327	0	y
26FEB03	DAT	19076	2:11a	2:11a	129	dat	10	90	40	50	327	0	y
26FEB04	2D	844600	2:17a	2:14a	129	V	50	90	40	0-51	400	0	y
26FEB05	2D	2000160	2:40a	2:31a	129	V	50	90	40	0-30	400	0	y
26FEB06	2D	2000160	3:21a	3:06a	129	V	50	90	40	0-30	400	0	y
26FEB07	2D	3849056	4:15a	3:53a	130	H	50	71-129	21-79	0	400	0	y
26FEB08	2D	2000160	4:29a	4:25a	130	V	50	90	40	0-30	400	0	y
26FEB09	2D	2000160	5:03a	5:00a	130	V	50	90	40	0-30	400	0	y
26FEB10	2D	2000160	5:38a	5:30a	130	V	50	90	40	0-30	400	0	y
26FEB11	2D	2000160	6:07a	6:00a	130	V	50	90	40	0-30	400	0	y
26FEB12	2D	2000160	6:34a	6:30a	131	V	50	90	40	0-30	400	0	y
26FEB13	2D	2000160	7:02a	7:01a	131	V	50	90	40	0-30	400	0	y
26FEB14	2D	2000160	7:26a	7:27a	131	V	50	90	40	0-30	400	0	y
26FEB15	2D	2000160	7:55a	7:58a	131	V	50	90	40	0-30	400	0	y
26FEB16	2D	2000160	8:37a	8:29a	131	V	50	90	40	0-30	400	0	y
26FEB17	2D	2000160	9:04a	8:59a	131	V	50	90	40	0-30	400	0	y
26FEB18	2D	2000160	9:35a	9:25a	131	V	50	90	40	0-30	400	0	y
26FEB19	2D	1207900	9:53a	9:49a	131	V	50	90	40	0-30	400	0	y
26FEB20	2D	2000160	10:05a	9:55a	131	V	50	90	40	0-30	400	0	y
26FEB21	2D	2000160	10:32a	10:30a	131	V	50	90	40	0-30	400	0	y
26FEB22	2D	2000160	10:57a	11:00a	131	V	50	90	40	0-30	400	0	y
26FEB23	2D	679520	11:03a		132	V	50	90	40	20-30	400	0	y
26FEB24	DAT	19076	11:05a		132	dat	50	90	40	15.6	400	0	y
26FEB25	DAT	19076	11:05a		132	dat	50	90	40	15.6	400	0	y
26FEB26	2D	2000160	11:26a	11:30a	132	V	50	90	40	0-30	400	0	y
26FEB27	2D	2000160	11:52a	12:00p	132	V	50	90	40	0-30	400	0	y
26FEB28	2D	2000160	12:19p	12:30p	132	V	50	90	40	0-30	400	0	y
26FEB29	2D	2000160	12:44p	12:55p	132	V	50	90	40	0-30	400	0	y
26FEB30	2D	2000160	1:12p	1:30p	132	V	50	90	40	0-30	400	0	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
26FEB31	2D	2000160	1:37p	1:55p	132	V	50	90	40	0-30	400	0	y
26FEB32	2D	1670000	1:43p		133	V	10	90	40	0-50	400	16	y
26FEB33	2D	976664	1:47p		133	H	10	71-129	21-79	0	400	16	y
26FEB34	2D	2000160	2:12p	2:30p	133	V	50	90	40	0-30	400	0	y
26FEB35	2D	2000160	3:08p	3:00p	133	V	50	90	40	0-30	400	0	y
26FEB36	2D	2000160	3:32p	3:30p	133	V	50	90	40	0-30	400	0	y
26FEB37	2D	2000160	4:00p	4:00p	133	V	50	90	40	0-30	400	0	y
26FEB38	2D	2000160	4:35p	4:26p	133	V	50	90	40	0-30	400	0	y
26FEB39	2D	2000160	5:05p	4:56p	133	V	50	90	40	0-30	400	0	y
26FEB40	2D	2000160	5:32p	5:26p	133	V	50	90	40	0-30	400	0	y
26FEB41	2D	2000160	6:04p	6:01p	133	V	50	90	40	0-30	400	0	y
26FEB42	2D	1670000	6:10p		134	V	10	90	40	0-50	400	16	y
26FEB43	2D	1934128	6:17p	6:21p	134	H	10	79-129	21-79	0	400	16	y
26FEB44	2D	2000160	6:28p	6:30p	134	V	50	90	40	0-30	400	16?	y
26FEB45	2D	1670000	6:37p		134	H	20	79-129	21-79	0	400	0	y
26FEB46	2D	2000160	6:54p	7:00p	134	V	50	90	40	0-30	400	0	y
26FEB47	2D	2000160	7:27p	7:30p	134	V	50	90	40	0-30	400	0	y
26FEB48	2D	2000160	7:56p	8:05p	134	V	50	90	40	0-30	400	0	y
26FEB49	2D	2000160	8:19p	8:30p	134	V	50	90	40	0-30	400	0	y
26FEB50	2D	2000160	8:54p	9:04p	134	V	50	90	40	0-30	400	0	y
26FEB51	2D	2000160	9:15p	9:32p	134	V	50	90	40	0-30	400	0	y
26FEB52	2D	2000160	9:39p	10:00p	134	V	50	90	40	0-30	400	0	y
26FEB53	2D	2000160	10:10p	10:30p	134	V	50	90	40	0-30	400	0	y
26FEB54	2D	2000160	10:43p	11:00p	134	V	50	90	40	0-30	400	0	y
26FEB55	2D	1521552	11:11p	11:30p	134	V	50	90	40	0-30	400	0	y
27FEB01	2D	2000160	11:32p	12:00a	135	V	50	90	40	0-30	400	0	y
27FEB02	2D	2000160	12:04a	12:30a	135	V	50	90	40	0-30	400	0	y
27FEB03	2D	2000160	12:30a	1:00a	135	V	50	90	40	0-30	400	0	y
27FEB04	2D	2000160	12:58a	1:30a	135	V	50	90	40	0-30	400	0	y
27FEB05	2D	2000160	1:23a	2:00a	135	V	50	90	40	0-30	400	0	y
27FEB06	2D	2000160	1:52a	2:30a	135	V	50	90	40	0-30	400	0	y
27FEB07	2D	2000160	2:18a	3:00a	135	V	50	90	40	0-30	400	0	y
27FEB08	2D	2000160	2:45a	3:30a	135	V	50	90	40	0-30	400	0	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
27FEB09	2D	2000160	3:12a	4:00a	135	V	50	90	40	0-30	400	0	y
27FEB10	2D	2000160	3:39a	4:30a	135	V	50	90	40	0-30	400	0	y
27FEB11	2D	2000160	4:07a	5:00a	135	V	50	90	40	0-30	400	0	y
27FEB12	2D	2000160	4:24a	5:23a	135	H	25	60-120	10-70	1	400	0	y
27FEB13	2D	2000160	4:41a	5:38a	135	V	50	90	40	0-30	400	0	y
27FEB14	2D	2000160	4:56a	6:00a	135	V	50	90	40	0-30	400	16	y
27FEB15	2D	2000160	5:10a	6:15a	135	V	50	90	40	0-30	400	16	y
27FEB16	2D	2000160	5:30a	6:35a	135	V	50	90	40	0-30	400	0	y
27FEB17	2D	778692	5:42a	7:00a	135	H	25	60-120	10-70	1	400	0	y
27FEB18	2D	2000160	5:58a	7:05a	135	V	50	90	40	0-30	400	0	y
27FEB19	2D	2000160	6:27a	7:33a	136	V	50	90	40	0-30	400	0	y
27FEB20	2D	1009680	6:40a	7:55a	136	H	50	60-120	10-70	1	400	0	y
27FEB21	2D	2000160	6:54a	8:11a	136	V	25	90	40	0-30	400	0	y
27FEB22	2D	1339840	7:06a	8:27a	136	V	25	90	40	0-20	200	0	y
27FEB23	2D	1009680	7:17a	8:27a	136	H	25	60-120	10-70	1	400	0	y
27FEB24	2D	1009680	7:25a	8:47a	136	H	25	60-120	10-70	1	200	0	y
27FEB25	2D	1207776	8:22a	-9:45a	137	V	25	42	352	2-20	400	0	y
27FEB26	2D	1207776	8:47a	10:10a	137	V	25	42	352	2-20	400	0	y
27FEB27	2D	1207776	10:36a	10:30a	137	V	25	42	352	2-20	400	0	y
27FEB28	2D	2528416	10:58a	10:51a	137	V	25	42	352	2-40	400	0	y
27FEB29	2D	2528416	11:32a	11:30a	138	V	25	42	352	2-40	400	0	y
27FEB30	2D	2528416	11:55a	11:50a	138	V	25	42	352	2-40	400	0	y
27FEB31	2D	2666944	12:04p	12:05p	138	H	25	95-115	45-65	0	400	0	y
27FEB32	2D	1351264	12:11p	12:15p	138	H	25	100-120	50-70	1	400	0	y
27FEB33	2D	7403392	12:27p	12:25p	138	H	25	72-128	22-78	0	400	0	y
27FEB34	2D	35168	12:37p	12:45p	138	V	25	42	352	2-40	400	0	y
27FEB35	2D	547456	12:51p	1:07p	139	H	25	39-47	349-357	2	400	0	y
27FEB36	DAT	68212	1:27p	1:45p	139	dat	100	157.6	107.6	1.7	400	0	y
27FEB37	DAT	68212	1:30p	1:50p	139	dat	255	157.6	107.6	1.0	400	0	y
27FEB38	2D	1315572	1:40p	1:50p	139	V	255	157.6	107.6	0.8-3.0	400	0	y
27FEB39	2D	514440	5:09p	5:07p	140	V	10	90	40	0-30	400	0	y
27FEB40	TD	8256692	5:19p	5:15p	140	TD	3	90	40	10	400	0	y
27FEB41	TD	8256692	5:23p	5:20p	140	TD	3	90	40	10	400	0	y
27FEB42	3D	8801456	6:16p	5:55p	140	3D	10	71-81	21-31	0-3	400	0	y
27FEB43	3D	9263680	6:47p	6:24p	140	3D	10	75-125	25-75	0-10	400	0	y
27FEB44	2D	844600	7:34p	7:35p	141	V	50	90	40	0-50	400	0	y



File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
27FEB45	2D	2330320	7:58p	7:50p	141	H	50	20-160	330-110	20	400	0	Y
27FEB46	2D	184280	8:04p	8:15p	141	H	50	110-115	60-65	2	400	0	Y
27FEB47	2D	2330320	8:21p	8:20p	141	H	50	20-160	330-110	30	400	0	Y
27FEB48	2D	844600	8:29p	8:37p	141	V	50	90	40	0-50	400	0	Y
27FEB49	2D	1670000	11:04p	11:15p	142	V	10	90	40	0-50	400	6?	Y
27FEB50	2D	1670000	11:11p		142	V	10	90	40	0-50	400	6	Y
27FEB51	2D	1670000	11:23p		142	V	10	42	352	0-50	400	6	Y
27FEB52	3D	14216080	12:21a		142	3D	10	71-91	21-71	0-40	400	6	Y
28FEB01	2D	1670000	12:29a	12:45a	142	V	10	90	40	0-50	400	6	Y
28FEB02	2D	1670000	12:40a		142	V	10	90	40	0-50	400	6	Y
28FEB03	2D	1636984	12:47a		142	V	10	140	90	1-50	400	6	Y
28FEB04	2D	2825560	1:06a	1:30a	142	H	10	45-140	355-90	3	400	6	Y
28FEB05	2D	1670000	1:20a	1:40a	142	V	10	90	40	0-50	400	6	Y
28FEB06	3D	22882780	2:37a	2:00a	142	3D	10	75-140	25-90	0-10	400	6	Y
28FEB07	2D	1670000	2:44a	3:10a	142	V	10	90	40	0-50	400	6	Y
28FEB08	2D	1670000	2:50a	3:12a	142	V	10	120	70	0-50	400	6	Y
28FEB09	2D	1670000	2:56a	3:18a	142	V	10	60	10	0-50	400	6	Y
28FEB10	2D	1670000	3:23a	3:45a	142	V	10	90	40	0-50	400	6	Y
28FEB11	2D	1670000	3:28a	3:52a	142	V	10	120	70	0-50	400	6	Y
28FEB12	2D	1670000	3:35a	3:59a	143	V	10	60	10	0-50	400	6	Y
28FEB13	2D	1670000	5:01a	5:00a	143	V	10	90	40	0-50	400	6	Y
28FEB14	2D	1670000	5:07a	5:05a	143	V	10	90	40	0-50	400	6	Y
28FEB15	2D	1670000	5:12a	5:10a	143	V	10	90	40	0-50	400	6	Y
28FEB16	2D	1670000	5:18a	5:16a	143	V	10	90	40	0-50	400	6	Y
28FEB17	2D	1670000	5:28a	5:24a	143	V	10	90	40	0-50	400	6	Y
28FEB18	2D	1670000	5:33a	5:32a	143	V	10	90	40	0-50	400	6	Y
28FEB19	2D	1670000	5:39a	5:39a	143	V	10	90	40	0-50	400	6	Y
28FEB20	2D	1670000	5:52a	5:50a	143	V	10	90	40	0-50	400	6	Y
28FEB21	2D	1670000	5:58a	5:58a	143	V	10	90	40	0-50	400	6	Y
28FEB22	2D	1670000	6:03a	6:04a	143	V	10	90	40	0-50	400	6	Y
28FEB23	2D	1670000	6:09a	6:10a	143	V	10	90	40	0-50	400	6	Y
28FEB24	2D	1670000	6:14a	6:15a	143	V	10	90	40	0-50	400	6	Y
28FEB25	2D	1670000	6:19a	6:20a	143	V	10	90	40	0-50	400	6	Y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
28FEB26	2D	762184	6:23a	6:24a	143	V	10	90	40	0-50	400	6	y
28FEB27	2D	1670000	6:31a	6:30a	143	V	10	90	40	0-50	400	6	y
28FEB28	2D	1670000	6:36a	6:35a	143	V	10	90	40	0-50	400	6	y
28FEB29	2D	1670000	6:43a	6:42a	143	V	10	90	40	0-50	400	6	y
28FEB30	2D	1934128	6:50a	6:50a	143	H	10	71-129	21-79	0	400	6	y
28FEB31	2D	1670000	6:56a	7:01a	143	V	10	68	18	0-50	400	6	y
28FEB32	2D	1636984	7:03a	7:09a	144	V	10	42	352	1-50	400	6	y
28FEB33	2D	1636984	7:09a	7:09a	144	V	10	42	352	1-50	400	6	y
28FEB34	2D	1636984	7:16a	7:16a	144	V	10	42	352	1-50	400	6	y
28FEB35	2D	1636984	7:22a	7:22a	144	V	10	42	352	1-50	400	6	y
28FEB36	2D	1636984	7:28a	7:28a	144	V	10	42	352	1-50	400	6	y
28FEB37	2D	1636984	7:34a	7:34a	144	V	10	42	352	1-50	400	6	y
28FEB38	2D	1636984	7:39a	7:39a	144	V	10	42	352	1-50	400	6	y
28FEB39	2D	1636984	7:44a	7:44a	144	V	10	42	352	1-50	400	6	y
28FEB40	2D	1636984	7:50a	7:50a	144	V	10	42	352	1-50	400	6	y
28FEB41	2D	1636984	7:55a	7:55a	144	V	10	42	352	1-50	400	6	y
28FEB42	2D	1636984	8:00a	8:00a	144	V	10	42	352	1-50	400	6	y
28FEB43	2D	1636984	8:25a	8:25a	144	V	10	42	352	1-50	400	6	y
28FEB44	2D	1670000	8:32a	8:32a	144	V	10	80	30	0-50	400	0	y
28FEB45	2D	1670000	8:38a	8:38a	144	V	10	80	30	0-50	400	6	y
28FEB46	2D	861232	8:42a	8:42a	144	V	10	80	30	0-50	400	6	y
28FEB47	2D	943648	11:20a	11:20a	144	H	25	72-128	22-78	0	400	6	y
28FEB48	2D	1670000	11:46a	~11:45a	144	V	25	90	40	0-50	400	6	y
28FEB49	2D	1670000	12:19p	~12:25p	145	V	10	90	40	0-50	400	16	y
28FEB50	2D	943648	12:46p	12:45p	145	H	10	72-128	22-78	0	400	0	y
28FEB51	2D	943648	12:59p	1:00p	145	H	10	72-128	22-78	10	400	0	y
28FEB52	2D	1670000	1:38p	~1:37p	145	V	10	90	40	0-50	400	0	y
28FEB53	2D	943648	4:38p	~4:35p	146	H	10	72-128	22-78	0	400	0	y
28FEB54	2D	1207776	4:49p	4:49p	146	H	10	110-128	60-78	0	400	0	y
28FEB55	2D	613488	5:04p	5:04p	146	H	10	72-90	40	0	400	0	y
28FEB56	2D	1670000	5:21p	5:20p	147	V	10	90	40	0-50	400	0	y
28FEB57	2D	960280	5:38p	5:38p	147	V	10	42	352	2-50	400	0	y
28FEB58	2D	943648	5:50p	~5:45p	147	H	10	72-128	22-78	0	400	0	y
28FEB59	2D	1670000	6:05p	~6:05p	147	V	10	75	25	0-50	400	0	y
28FEB60	2D	1670000	6:21p	~6:20p	147	V	10	75	25	0-50	400	16	y
28FEB61	2D	1670000	6:33p	~6:40p	147	V	10	75	25	0-50	400	0	y

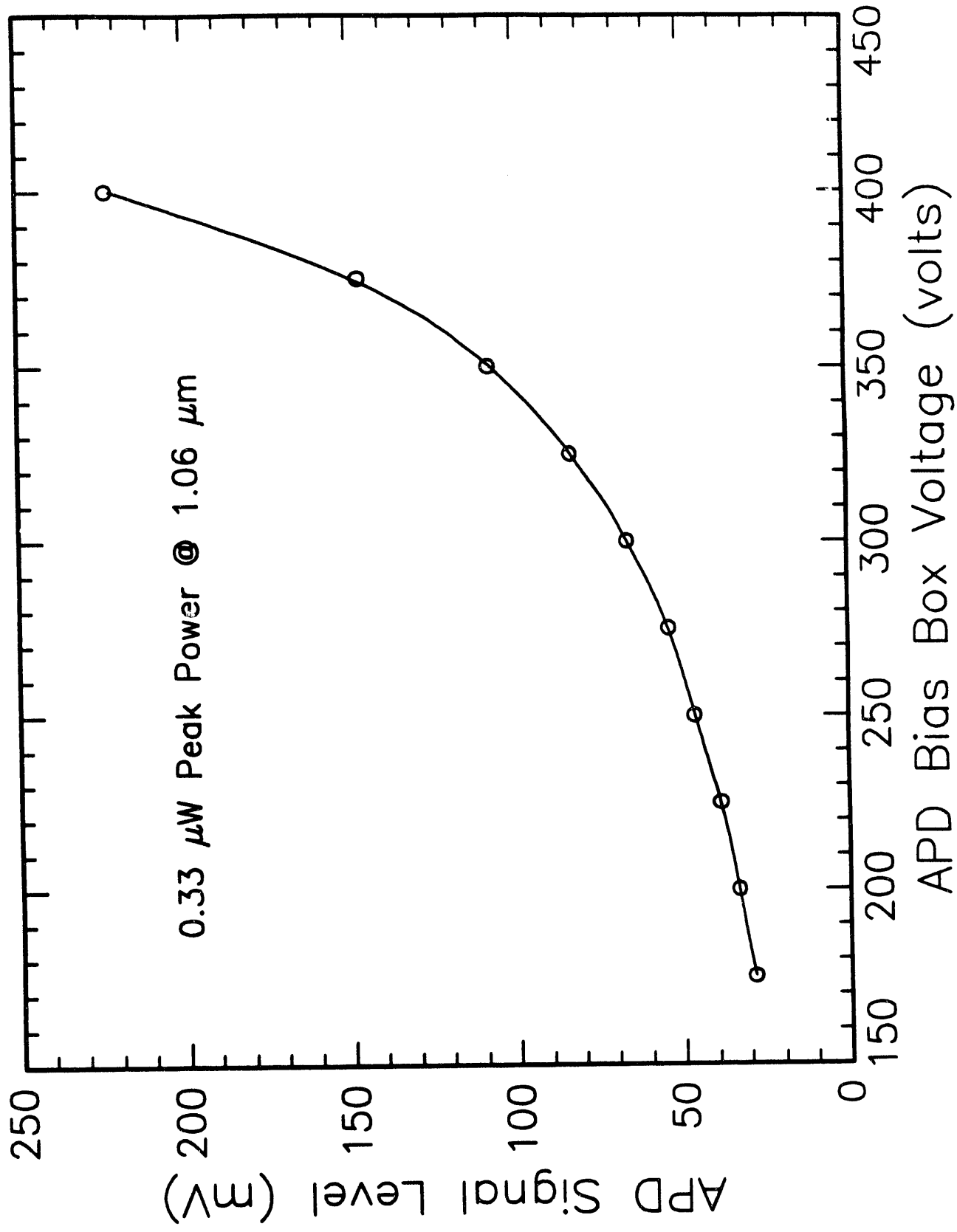
File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
28FEB62	2D	943648	6:49p	-6:50p	147	H	10	72-128	22-78	0	400	0	y
28FEB63	2D	1670000	7:23p		148	V	10	75	25	0-50	300	0	y
28FEB64	2D	1670000	7:43p		148	V	10	75	25	0-50	400	0	y
28FEB65	2D	1670000	7:56p		148	V	10	90	40	0-50	400	0	y
28FEB66	2D	1670000	8:25p	-8:23p	148	V	10	60	10	0-50	400	0	y
28FEB67	2D	1670000	8:38p	-8:40p	148	V	10	90	40	0-50	200	0	y
28FEB68	2D	1670000	10:37p	10:40p	149	V	10	90	40	0-50	400	0	y
28FEB69	2D	1670000	10:44p	10:45p	149	V	10	90	40	0-50	200	0	y
28FEB70	2D	1670000	11:52p	11:55p	149	V	10	90	40	0-50	200	0	y
28FEB71	2D	1670000	11:57p	12:03a	149	V	10	90	40	0-50	400	0	y
1MAR01	2D	1670000	12:45a	12:35a	5	V	50	90	40	0-50	400	0	y
1MAR02	2D	1670000	12:52a	12:50a	5	V	10	90	40	0-50	400	20	y
1MAR03	2D	3783024	1:28a	1:08a	5	H	50	71-128	21-78	0	400	20	y
1MAR04	2D	3783024	1:50a	1:39a	5	H	50	71-128	21-78	0	400	20	y
1MAR05	2D	1670000	2:02a	2:05a	5	V	50	90	40	0-50	400	20	y
1MAR06	2D	1670000	2:37a	2:42a	5	V	50	90	40	0-50	400	20	y
1MAR07	2D	1670000	2:52a	3:04a	5	V	10	90	40	0-50	400	20	y
1MAR08	2D	3849056	3:09a	3:16a	6	H	10	71-129	21-79	0	400	20	y
1MAR09	2D	1670000	3:26a	3:40a	6	V	10	90	40	0-50	400	20	y
1MAR10	2D	1670000	3:38a	3:46a	6	V	50	90	40	0-50	400	0	y
1MAR11	2D	1670000	4:07a	4:18a	6	V	50	90	40	0-50	400	0	y
1MAR12	2D	1670000	4:13a	4:31a	6	V	10	90	40	0-50	400	20	y
1MAR13	2D	3849056	5:28a	5:11a	7	H	50	71-120	21-70	0	400	20	y
1MAR14	2D	976664	5:35a	5:36a	7	H	50	71-129	21-79	0	400	20	y
1MAR15	2D	1670000	5:46a	5:45a	7	V	50	90	40	0-50	400	0?	y
1MAR16	2D	1670000	5:53a	6:00a	7	V	10	90	40	0-50	400	20	y
1MAR17	2D	3783024	6:21a	6:24a	7	H	10	71-129	21-79	0	400	20	y
1MAR18	2D	3783024	6:42a	6:35a	7	H	50	71-128	21-78	0	400	0	y
1MAR19	2D	1670000	6:53a	7:01a	7	V	50	90	40	0-50	400	0	y
1MAR20	2D	1670000	6:59a	7:14a	7	V	10	90	40	0-50	400	20	y
1MAR21	2D	1273808	7:08a	7:27a	8	H	50	71-90	21-40	0	400	0	y
1MAR22	2D	1670000	7:33a	7:45a	8	V	50	90	40	0-50	400	0	y
1MAR23	2D	1670000	7:39a	8:00a	8	V	10	90	40	0-50	400	20	y

File name	File ext.	File size (bytes)	ALR Time	Log Book Time	Pg. #	Scan type	Shot #	Lidar Azimuth (degrees)	True North Azimuth (degrees)	Elevation (degrees)	APD Voltage (Volts)	Signal Atten. (dB)	10 MHz Filt.
1MAR24	2D	1273808	7:50a	8:16a	8	H	50	71-90	21-40	0	400	0	y

## **Appendix B**

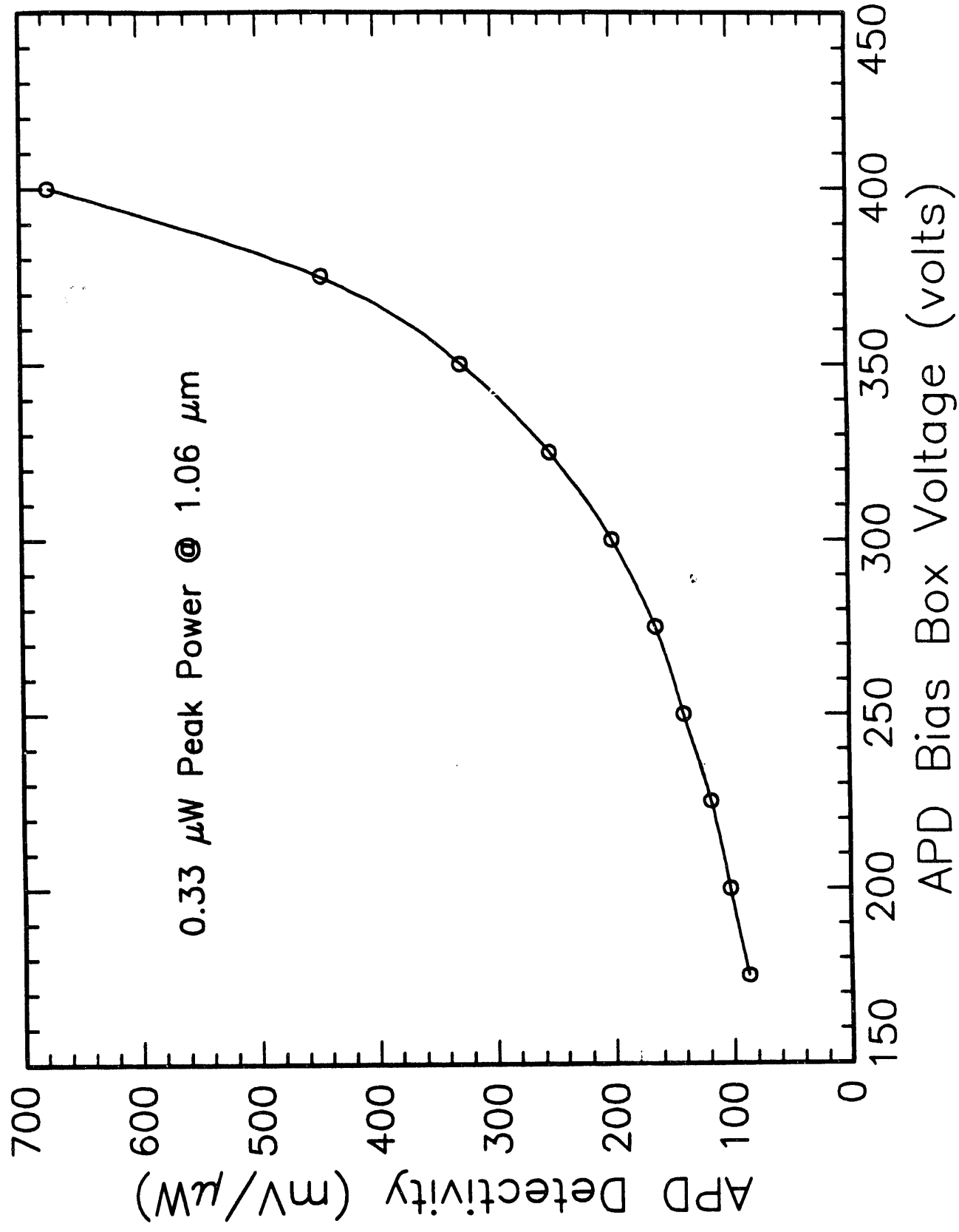
### **APD Sensitivity vs Bias Voltage**

Optical APD #3 at 75 °F



# Optical APD #3 at 75 °F

0.33  $\mu$ W Peak Power @ 1.06  $\mu$ m



# **Appendix C**

**Atmospheric Extinction Effects,  
Systematic and Random Noise in the Data**



Detailed analysis of the lidar data revealed various types of random and systematic noise. Some, but not all, of the noise sources have been identified and are discussed in the material that follows.

The most obvious source of systematic noise occurred during the digitization process. An 8-bit transient digitizer (least significant bit = 2 mV) was used to input the analog APD signals into the computer. The 10 shot average APD random noise level was typically less than 2 mV so that the errors connected with the digitization process are easily visible when the lidar return signal is featureless and slowly changing, leading to a "staircase" appearance in the individual angle traces. Unusually large non-linear behavior was observed in the neighborhood of the 15th digitizer count (i.e. the transition from (00001111 = 15) to (00010000 = 16) which occurs at an input voltage level of about 30 mV (2mV/ count). The APD dc level and digitizer input offset was such that the zero signal level normally occurred at about 13-14 digitizer counts (or about 26-28 mV). Thus, the last 2-4 mV of signal tend to be noticeably corrupted by the digitizer non-linearity, resulting in peculiar signal shapes. An example of this digitizer non-linearity is shown in Fig. C1, which is a single trace composed of a 10 laser shot average extracted from a two-dimensional scan. It shows that as level 15 is approached two things happen : 1) the signal level suddenly drops to level 15 from level 16 instead of executing a smooth transition, and 2) the signal appears to become very smooth while it is close to the 15th level, lacking the randomness that precedes and follows the 15th level. When this type of signal is multiplied by  $r^2$  to eliminate the  $1/r^2$  fall-off, it tends to produce signals like the one shown in Fig. C2. This systematic dip leads to the appearance of what can look like an atmospheric structure in the 2-D vertical and horizontal scans. Since the non-linearity causes a "sag" in the true signal, the  $r^2$  corrected 2-D color plots will show this feature as a sudden decrease in signal which can be erroneously interpreted as a decrease in aerosol concentration (i.e. an area of relatively cleaner air surrounded by dirtier air). An obvious example of this effect is shown in Fig. C3. A more subtle example is shown in Fig. C4, where one might think there is a column of clean air from above reaching down to mix with the dirty air below. The visibility of this digitizer effect in the 2-

D color plots presented in this report depends greatly on the atmospheric situation at the time the data was taken. In general, when the atmosphere is rich with structures, the structures themselves will tend to mask the effect. On the other hand, when the atmosphere is very uniform, with slowly varying spatial aerosol distributions the effect can be quite noticeable, tending to produce radially symmetric features in the 2-D plots. In summary, atmospheric structures that occur close to the 15th digitizer count level are contaminated and should be very carefully interpreted.

A second type of noise that occasionally produced very noticeable effects on the single angle extracted data files was due to the laser system firing circuitry and power supply. A short burst of high-frequency (HF) noise would, from time-to-time, fall within the time period being digitized. This type of noise is not easily seen in the 2-D plots because the bursts occurs at random places along the signals that make up an entire 2-D scan.

The fact that atmospheric extinction has not been removed from the data leads to several systematic effects in the plots. In the color plots, atmospheric attenuation often shows up as a slow fade in the colors being used to depict signal amplitude. This makes it appear as if the lidar truck is always in a zone of higher aerosol concentration than zones at farther ranges. Often the slow fade exhibits a staircase-like appearance which is due to the fact that only 16 colors can be printed and the data has to be binned into the available slots. The slow color fade effect is sometimes obscured by the rich and varied aerosol structures that are found in the atmosphere. Occasionally, the laser beam will pass through an optically thick atmospheric structure, such as a dense plume, that will cause the aerosol signal beyond the plume to appear smaller than the signal at the same elevation at different locations, giving rise to "shadows" in the color plots. An example of the "shadows" phenomenon is shown in Fig. C5. The visibility of the shadows also depends strongly on the exposure level of the color print.

The presence of clouds in the scanned region caused another type of problem in the 2-D color plots. Clouds can produce very large signals in the APD detector. If per chance the elevation angle and the cloud height are such that the cloud return occurs near the end of the file where the baseline calculation is performed, the baseline subtraction operation leads to nonsensical results for that particular scan angle (or group of angles).

An example of this situation is shown in Fig. C6. This problem can be easily remedied by selecting a different region for the baseline subtraction for the affected

angles. Strong returns from clouds also cause the APD detector to ring, giving rise to ripples in the data recorded behind the struck cloud.

Careful examination of the color plots shows that the last color in the color scale (corresponding to the highest signal value) never appears within the plot. This is due to a "bug" in the software so that in fact, only 15 colors are being plotted.

Sometimes the APD voltage and atmospheric conditions were such that the aerosol return signals for ranges as high as 800-1000 m were larger in amplitude than the transient digitizer could accommodate (0.512 V max.) . This signal "saturation" process produces a very smoothly rising signal when the  $r^2$  correction is applied.

22FEB68.2D Angle #60

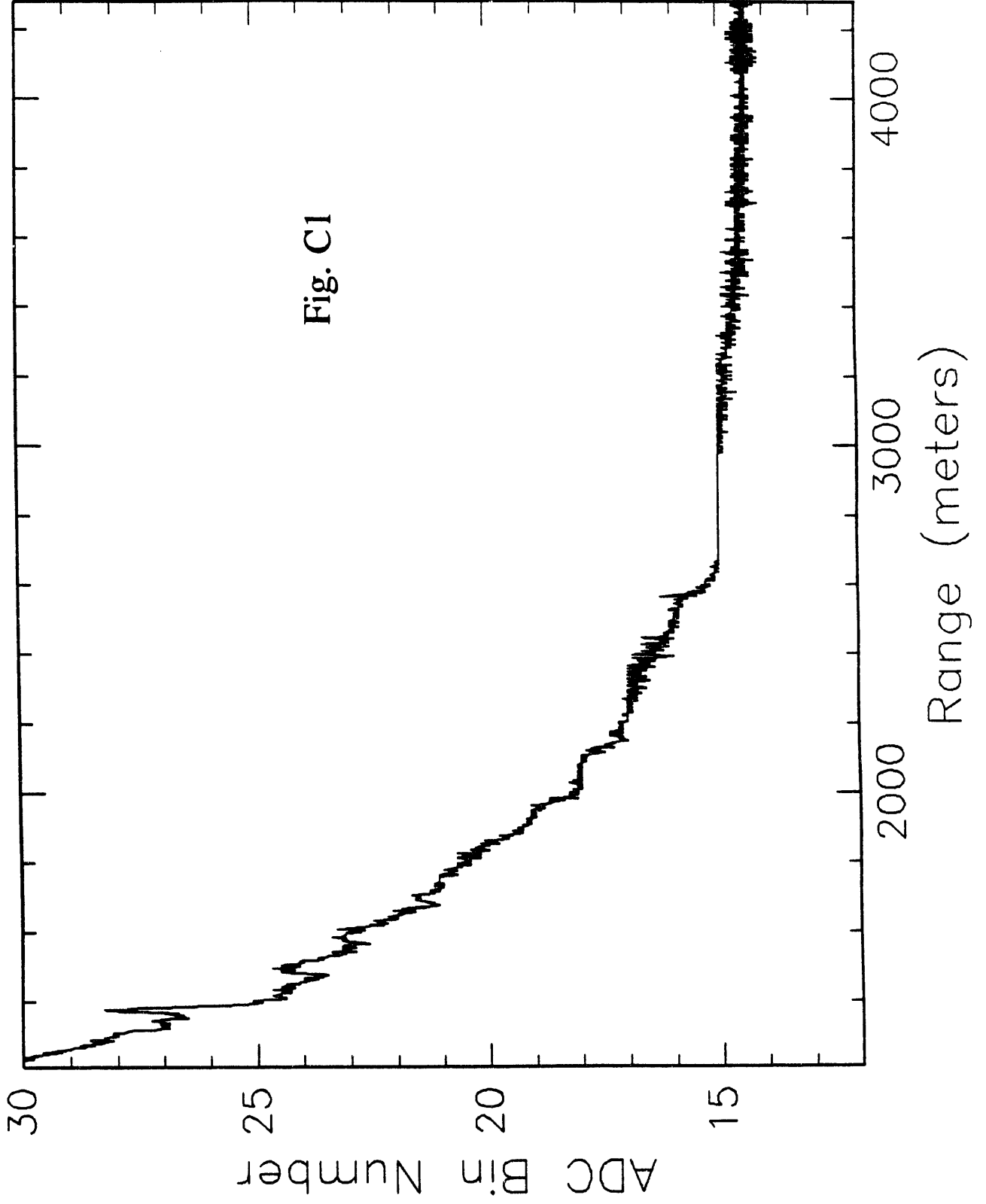
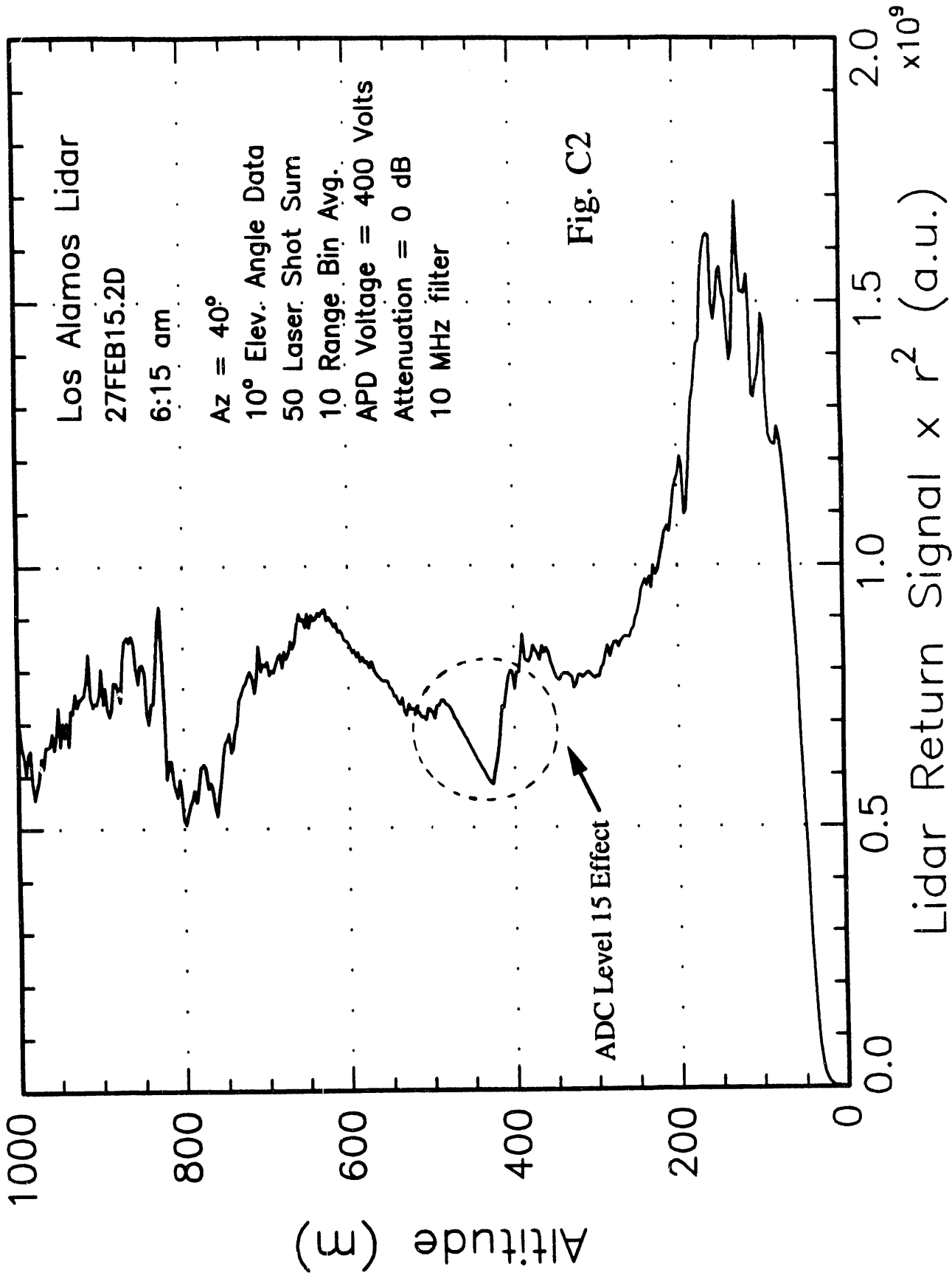


Fig. C1

# UNAM Site February 27, 1991



2/22/1991 11:23 Scans=10 Azi: 80.00 Elev: 8.00; vertical scan/80-8-50x1/250y/16db

Vertical Scan; File:E:\FEB22.91\22FEB4.2D

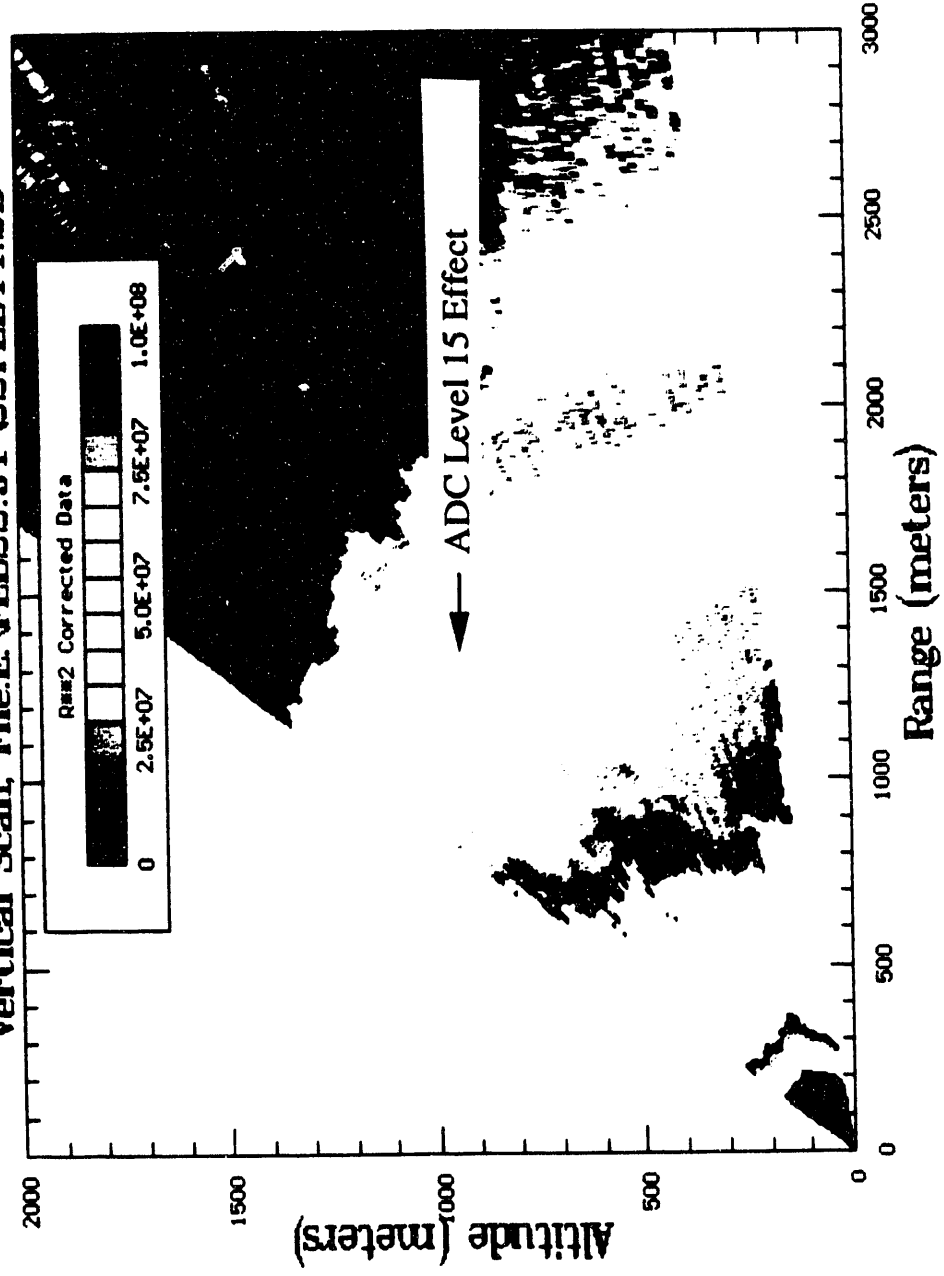


Fig. C3

2/28/1991 19:19 Scans=10 Az: 75.00 Elev: 0.00; Vertical scan 75 az and 0-50 x 0.5, 10 shots

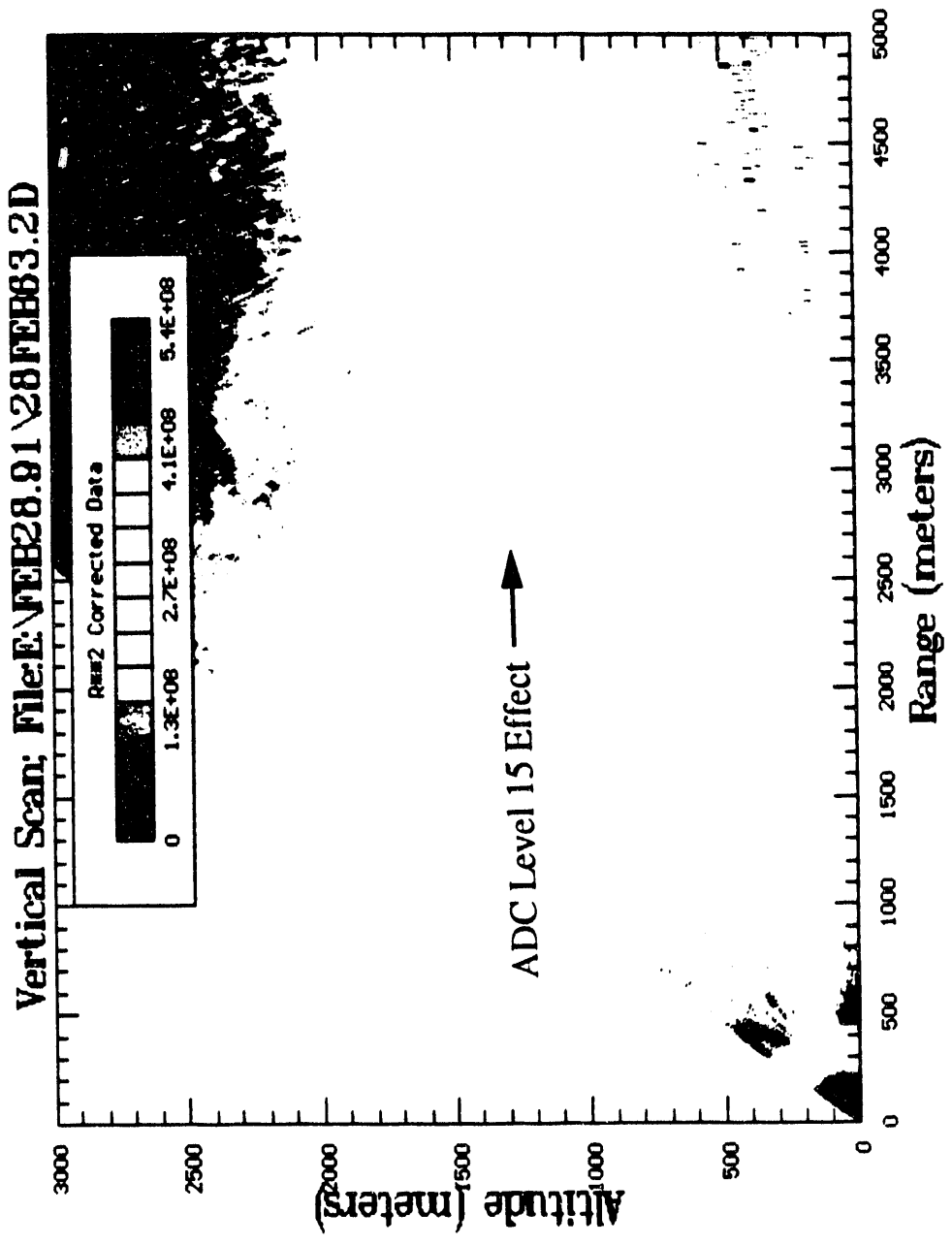


Fig. C4

2/26/1991 9:25 Scans=50 Az: 90.00 Elev: 0.00; vert scan 0-30x.25

### Vertical Scan; File:E\FEB26.91\26FEB18.2D

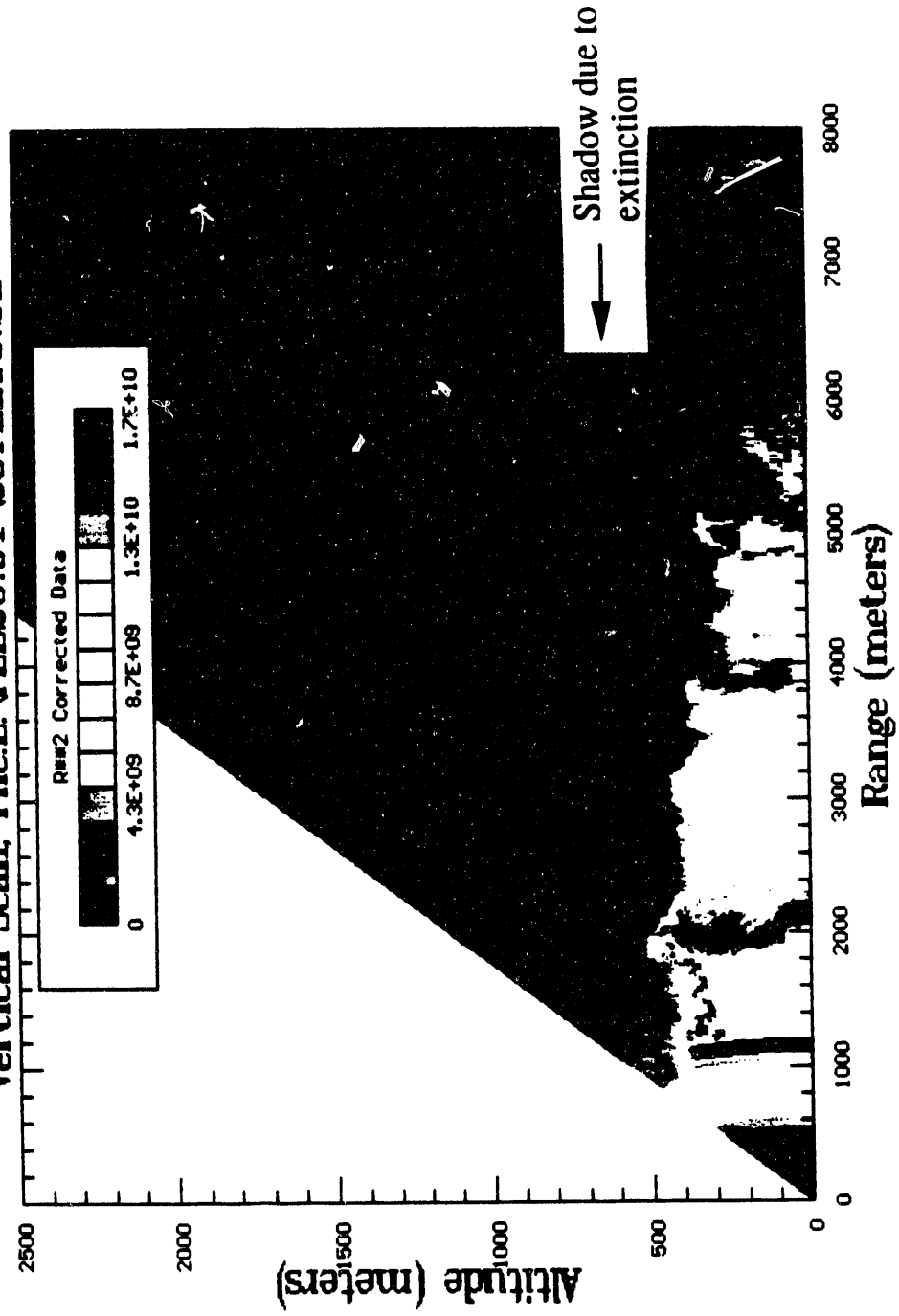


Fig. C5



2/28/1991 2:39 Scans=10 Az: 90.00 Elev: 0.00 Vertical scan 90 az and 0-50 x 0.5, 10 shots

Vertical Scan: File:E:\FEB28.91\28FEB07.2D

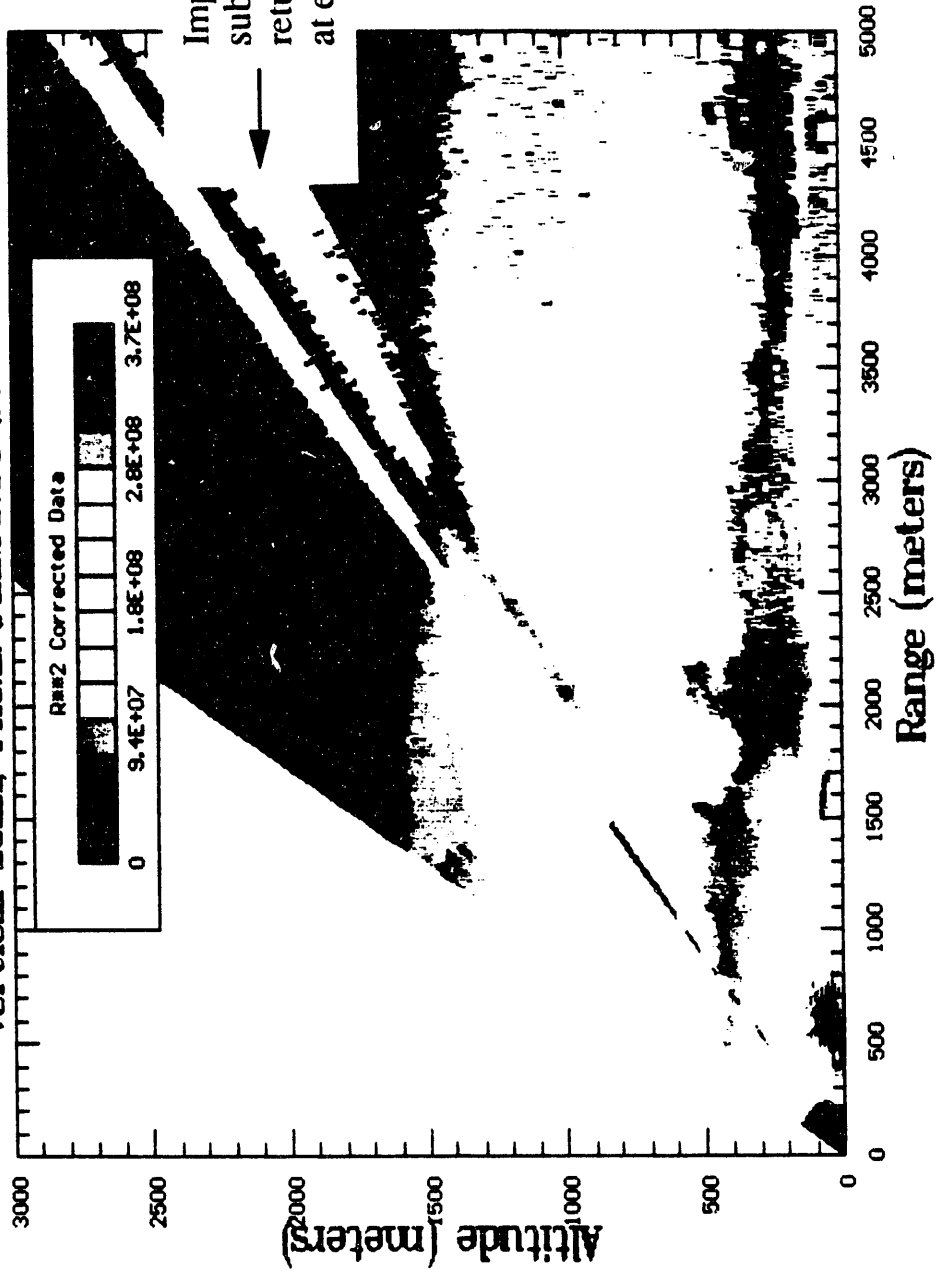
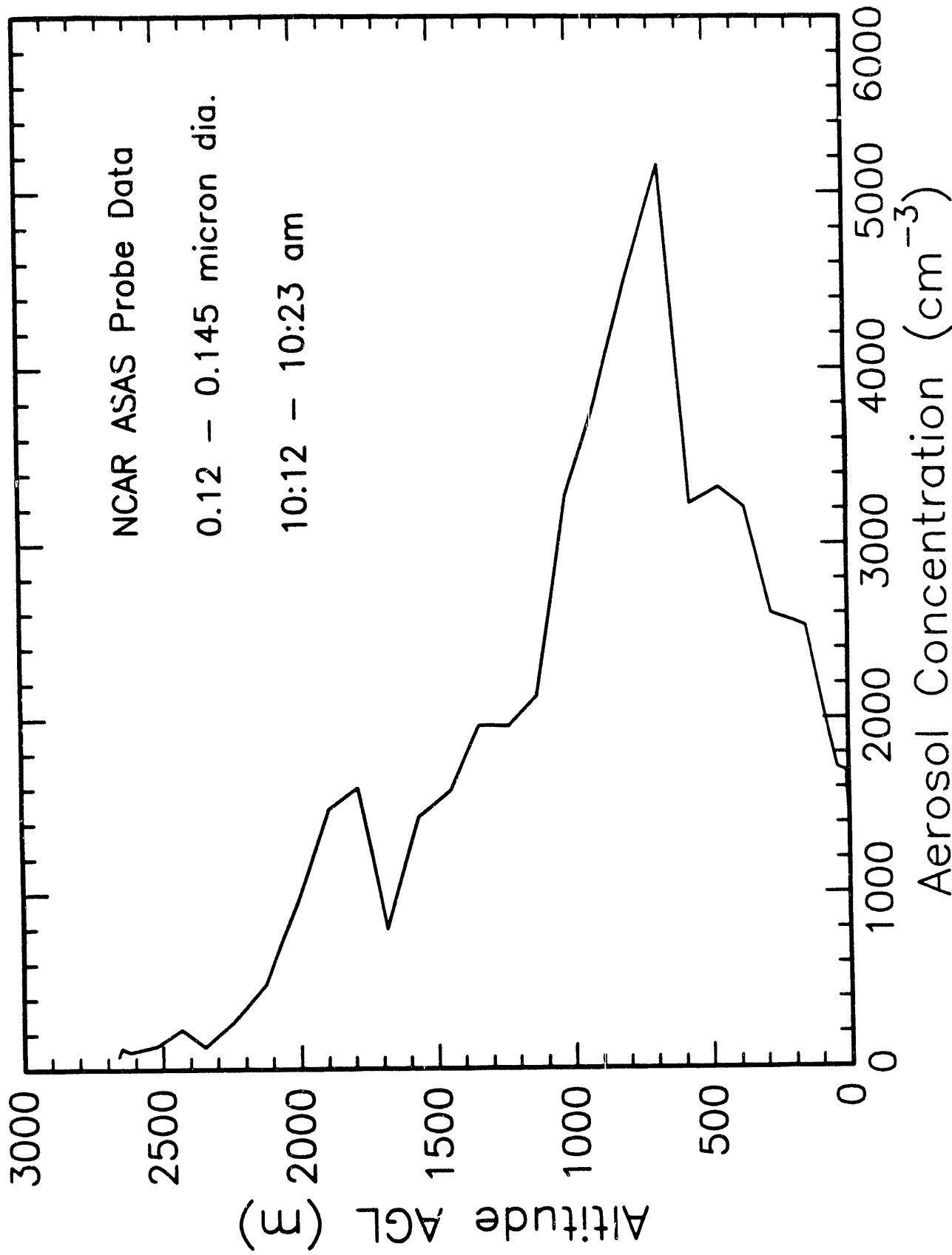


Fig. C6

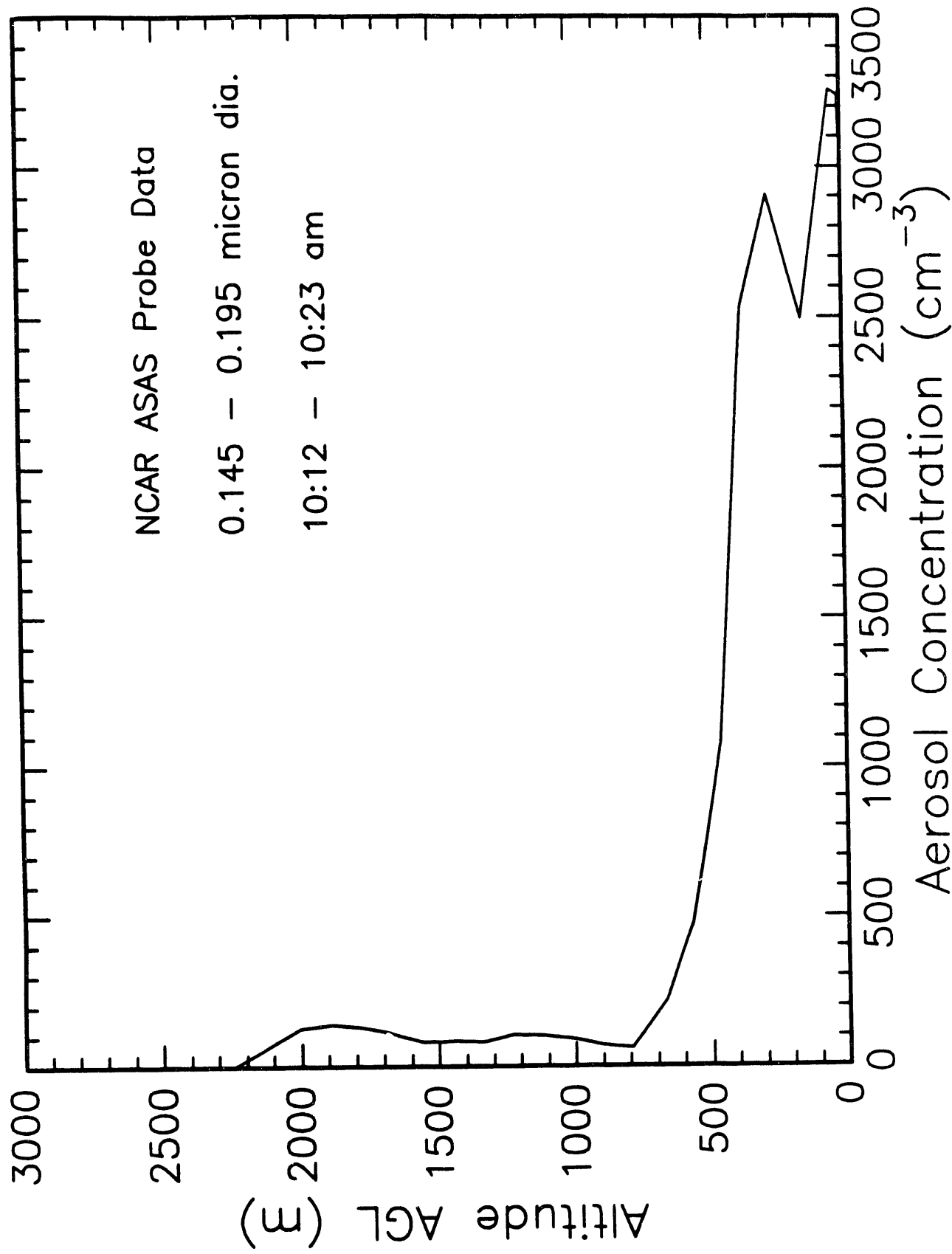
# **Appendix D**

## **NCAR ASAS Aerosol Probe Data**

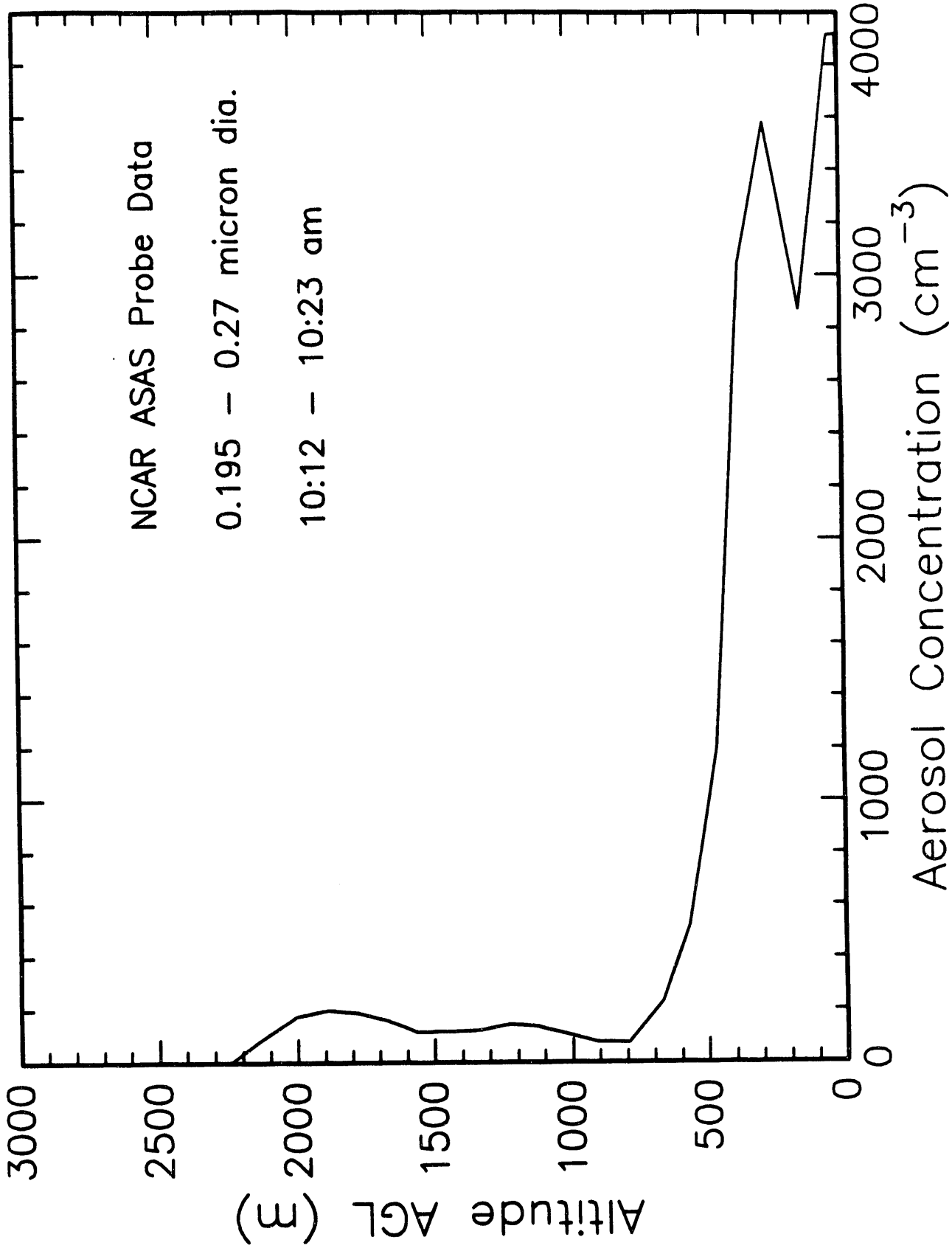
# Mexico City February 22, 1991



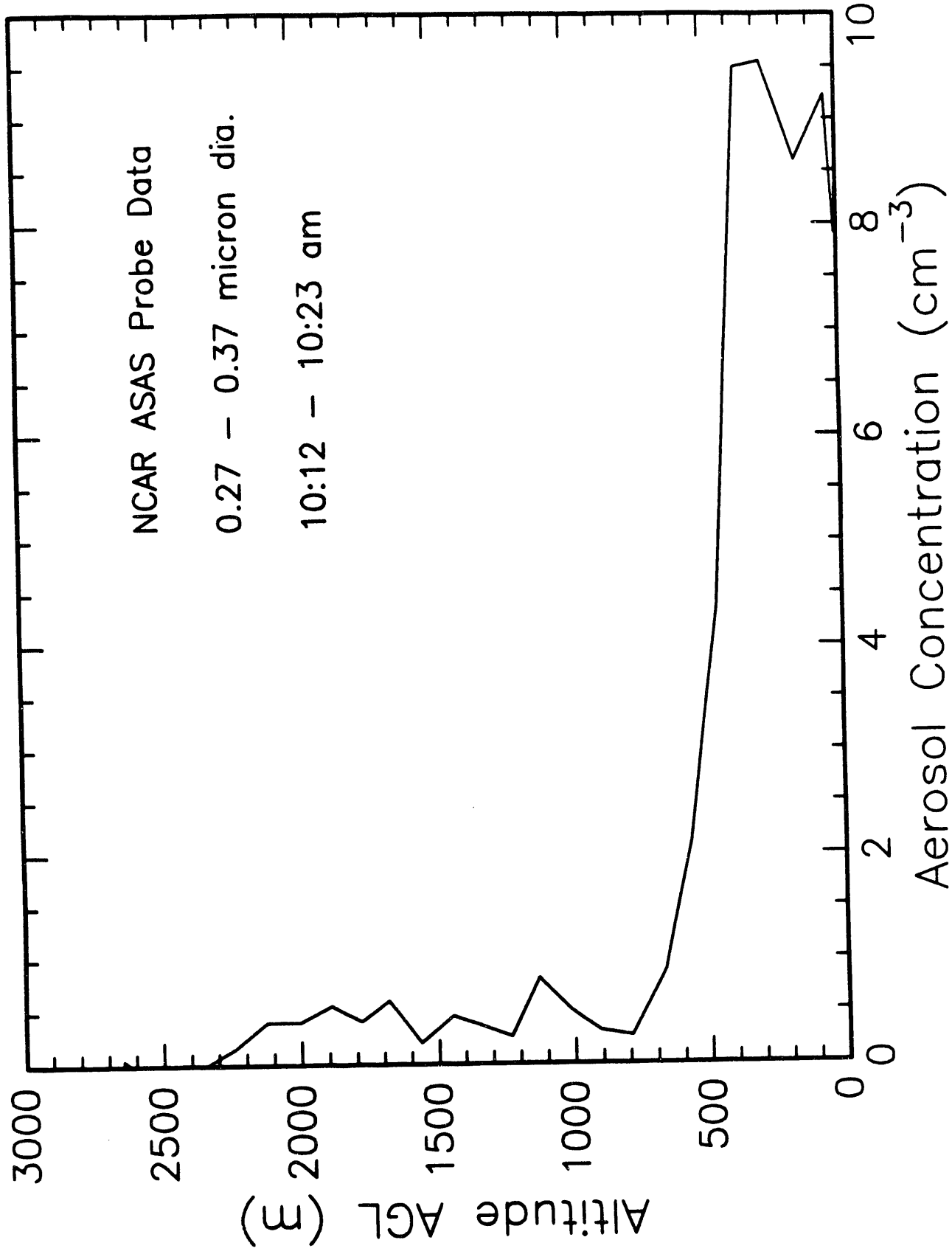
# Mexico City February 22, 1991



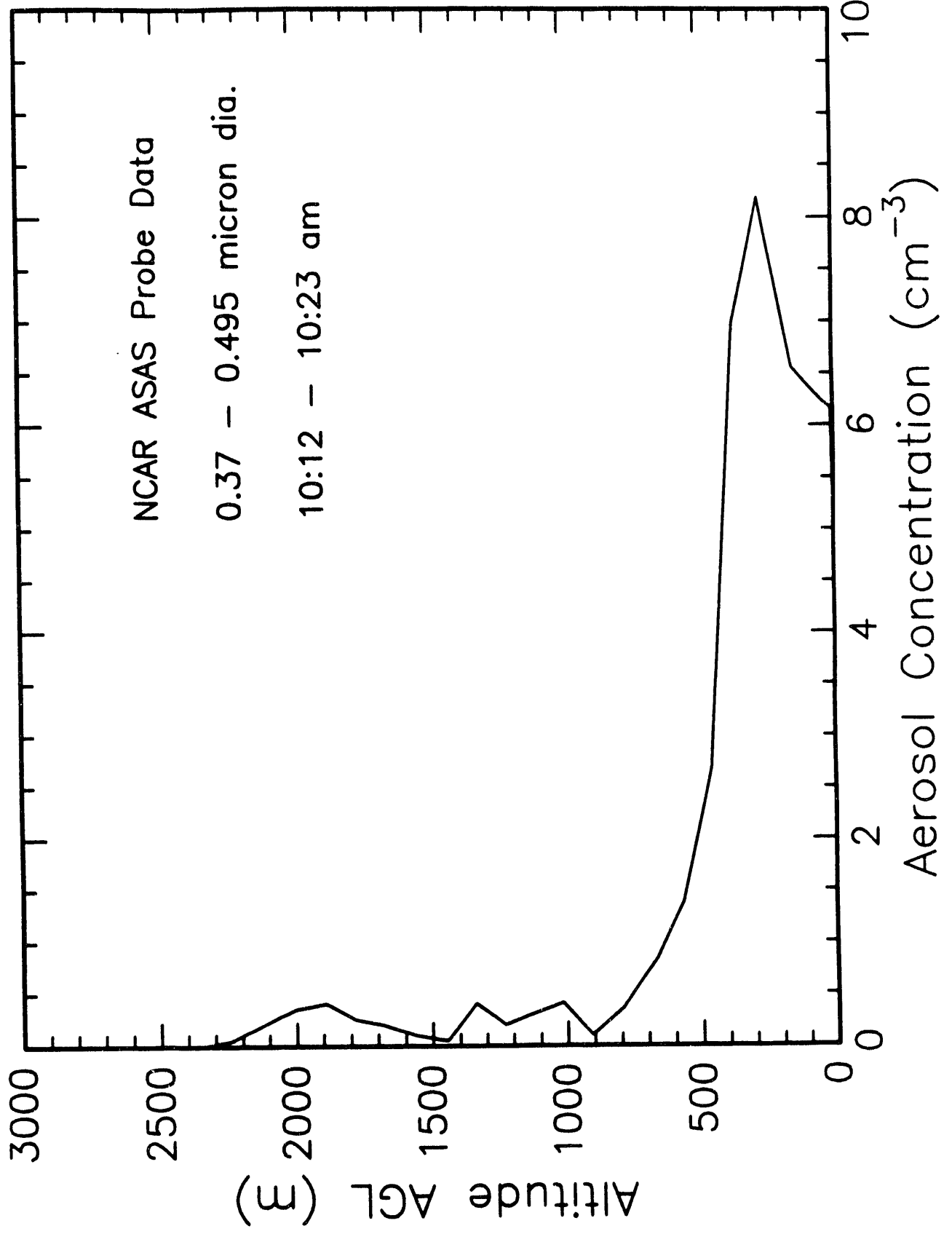
# Mexico City February 22, 1991



# Mexico City February 22, 1991



# Mexico City February 22, 1991

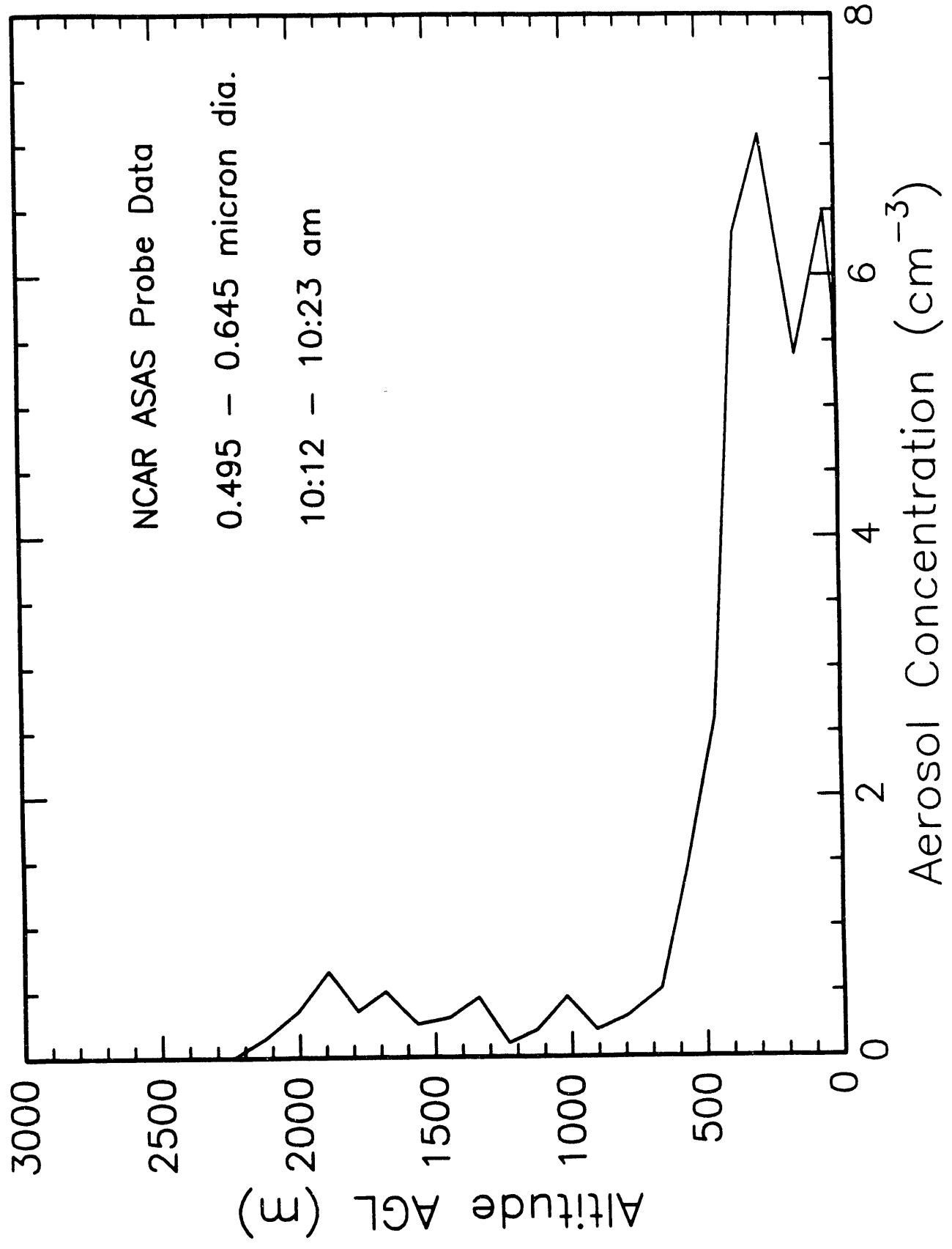


Mexico City February 22, 1991

NCAR ASAS Probe Data

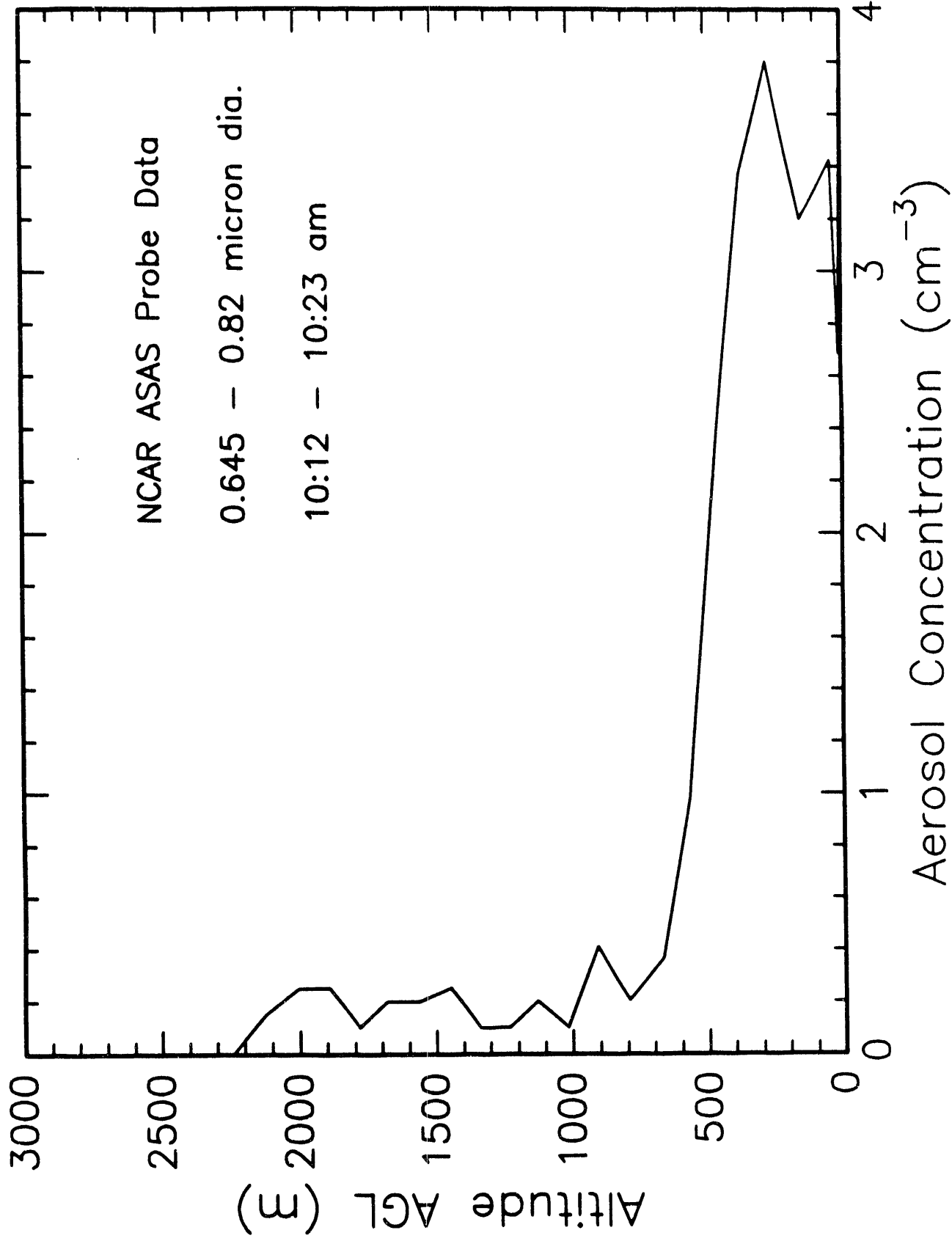
0.495 - 0.645 micron dia.

10:12 - 10:23 am

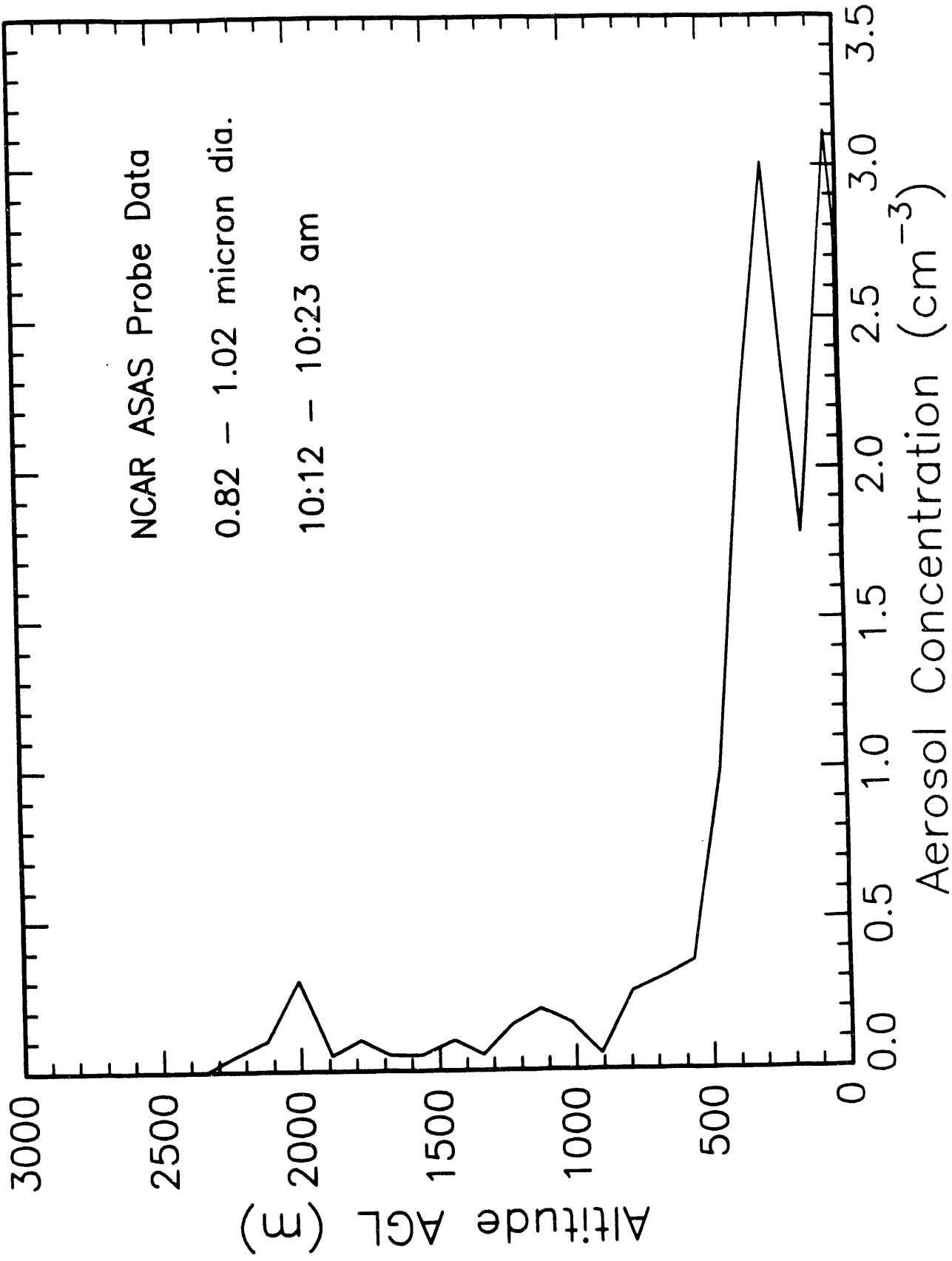




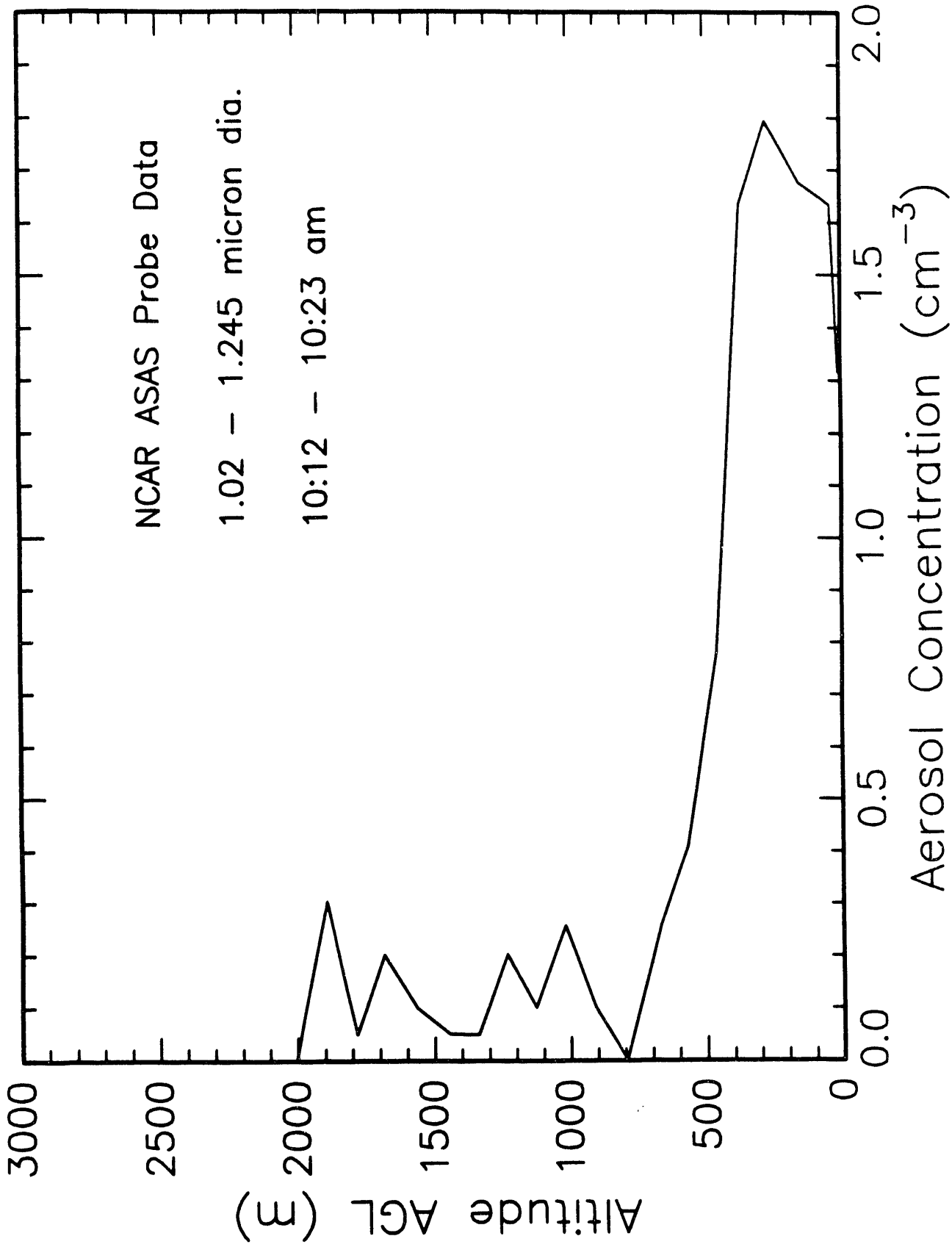
# Mexico City February 22, 1991



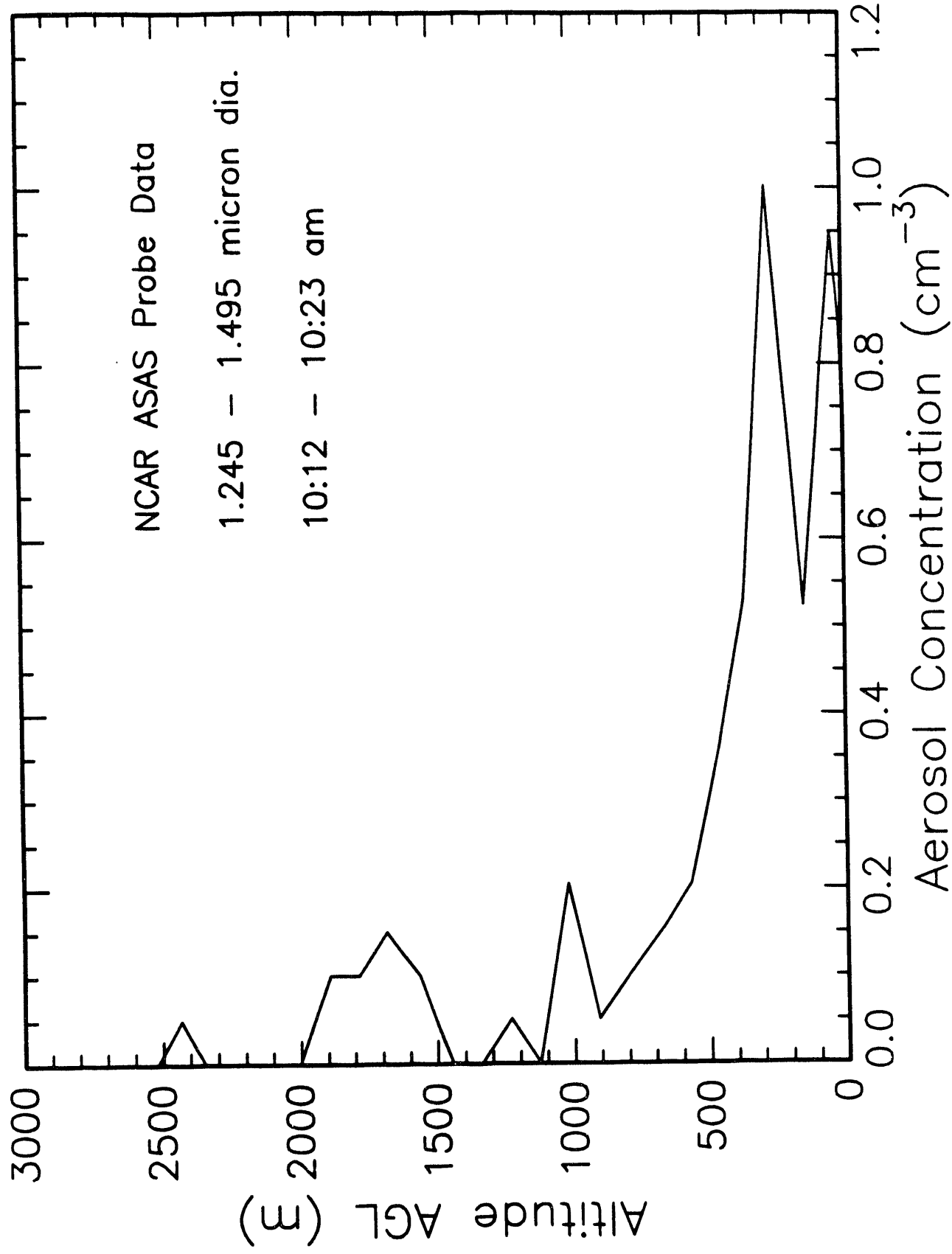
Mexico City February 22, 1991



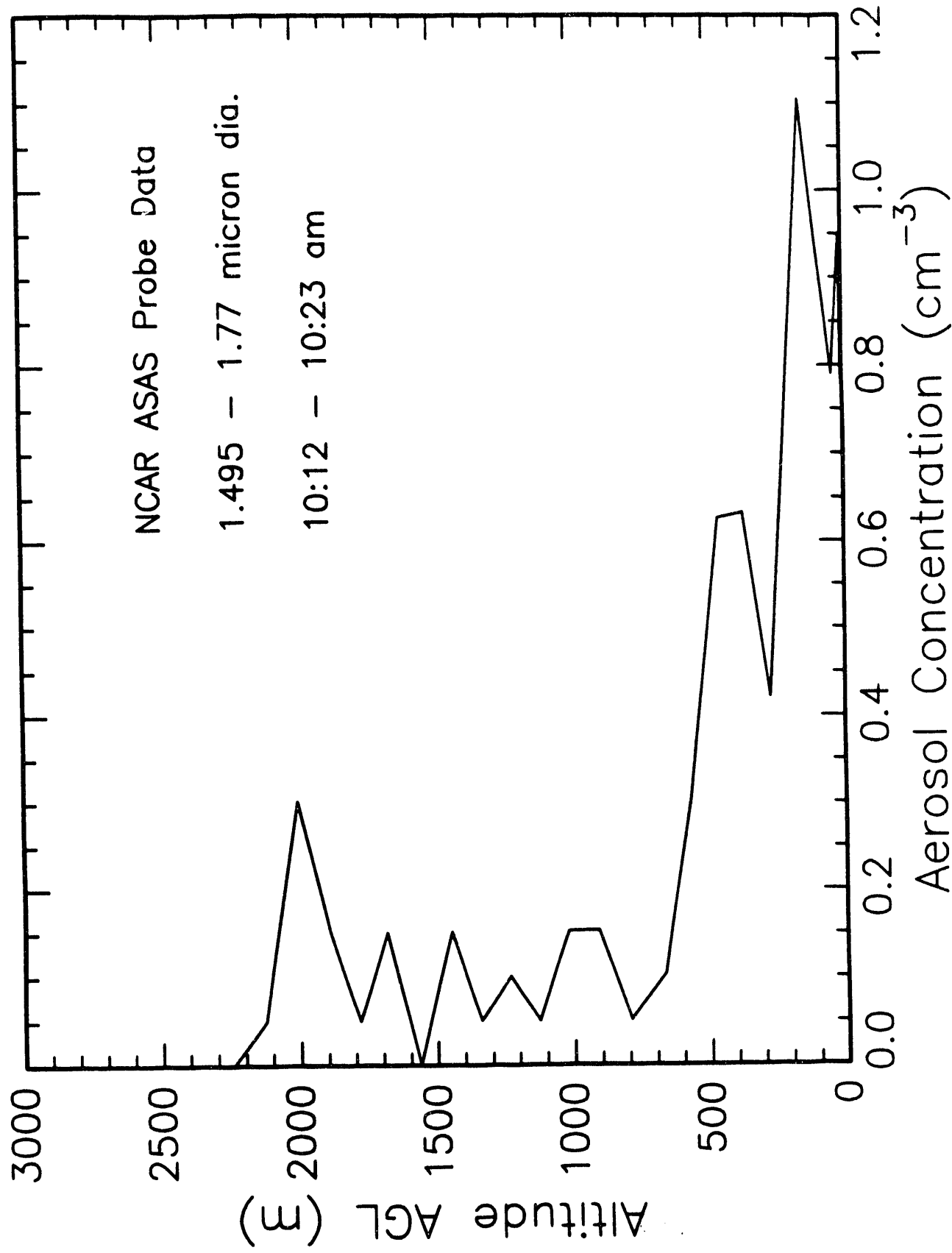
Mexico City February 22, 1991



# Mexico City February 22, 1991

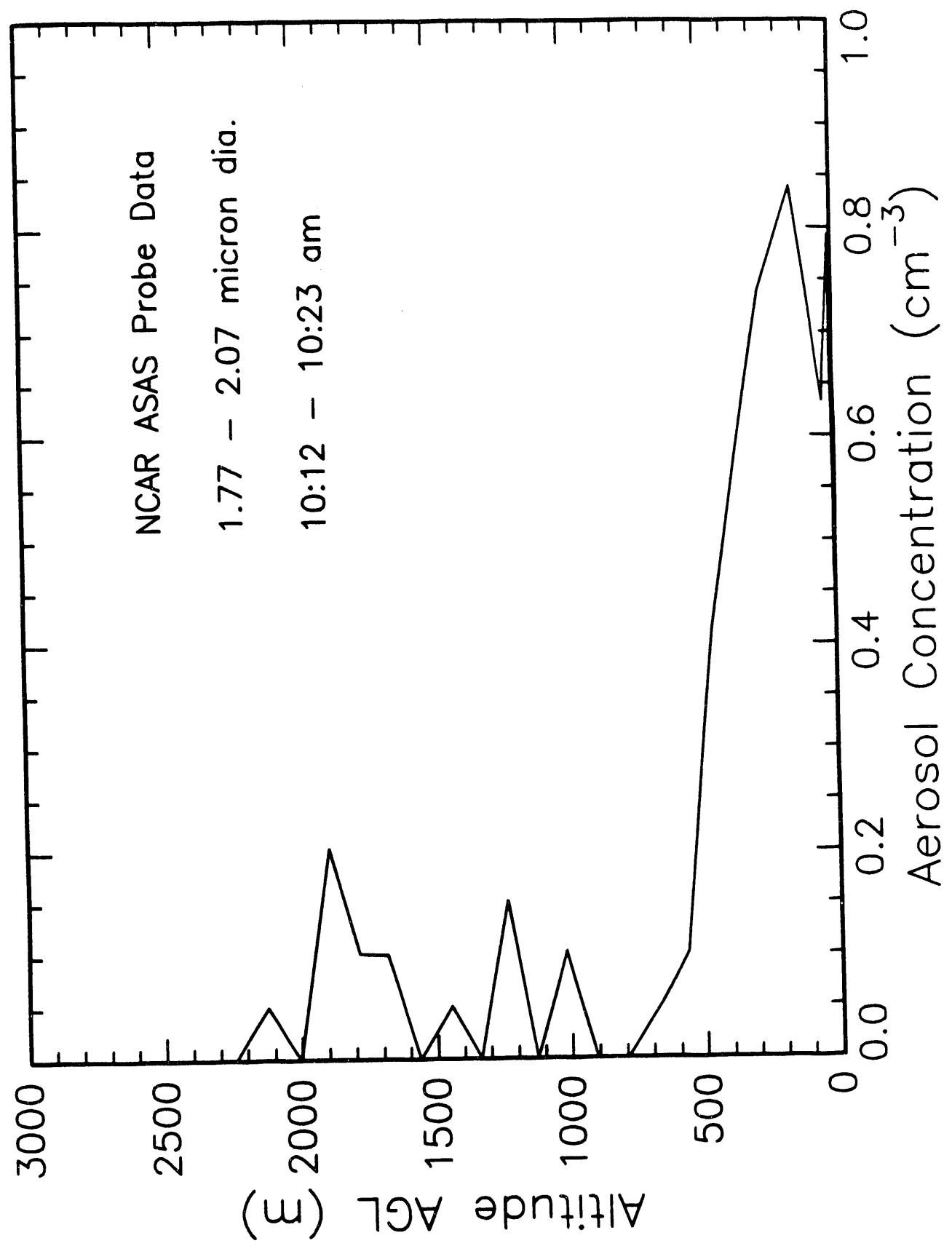


# Mexico City February 22, 1991



Mexico City February 22, 1991

NCAR ASAS Probe Data  
1.77 - 2.07 micron dia.  
10:12 - 10:23 am

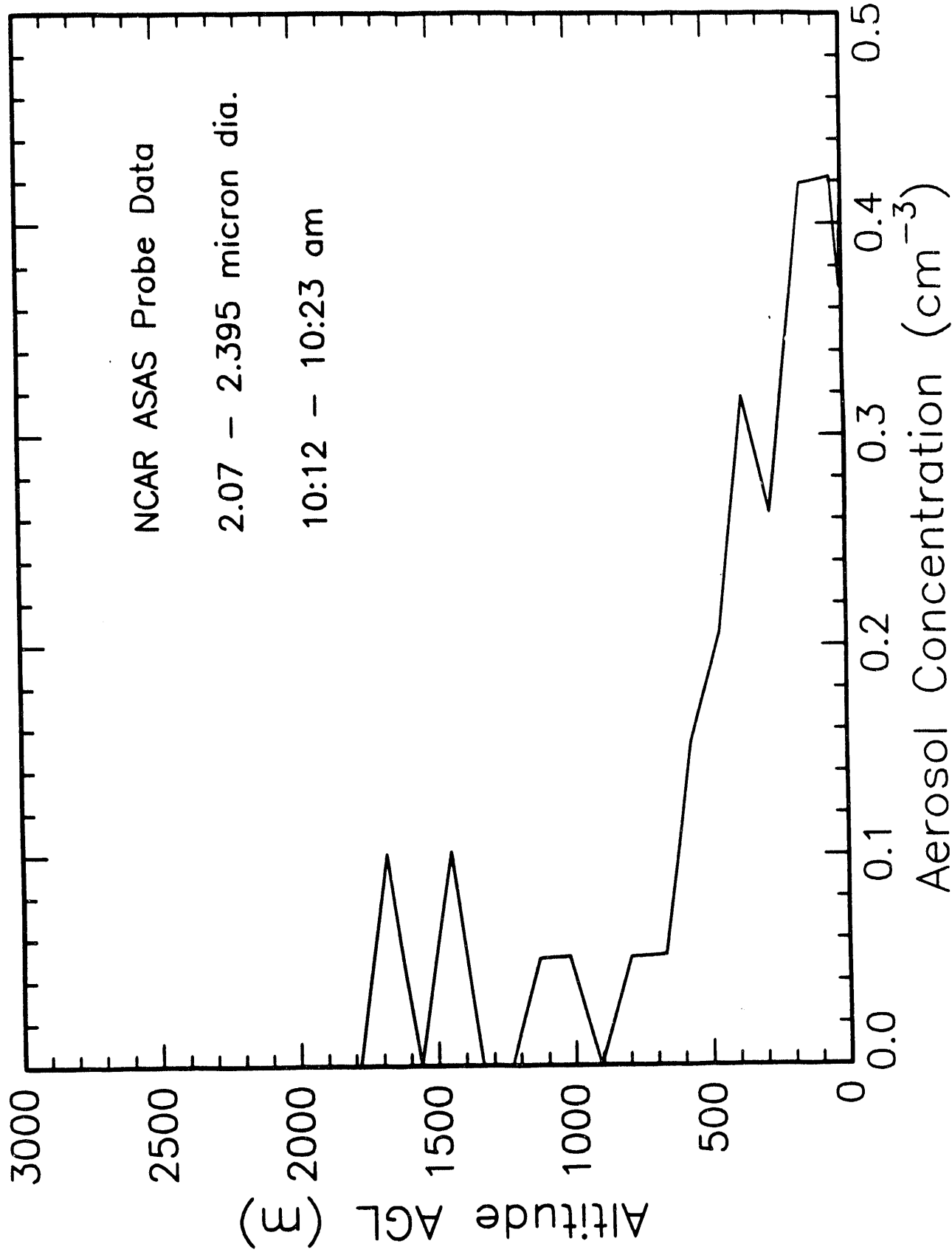


# Mexico City February 22, 1991

NCAR ASAS Probe Data

2.07 - 2.395 micron dia.

10:12 - 10:23 am

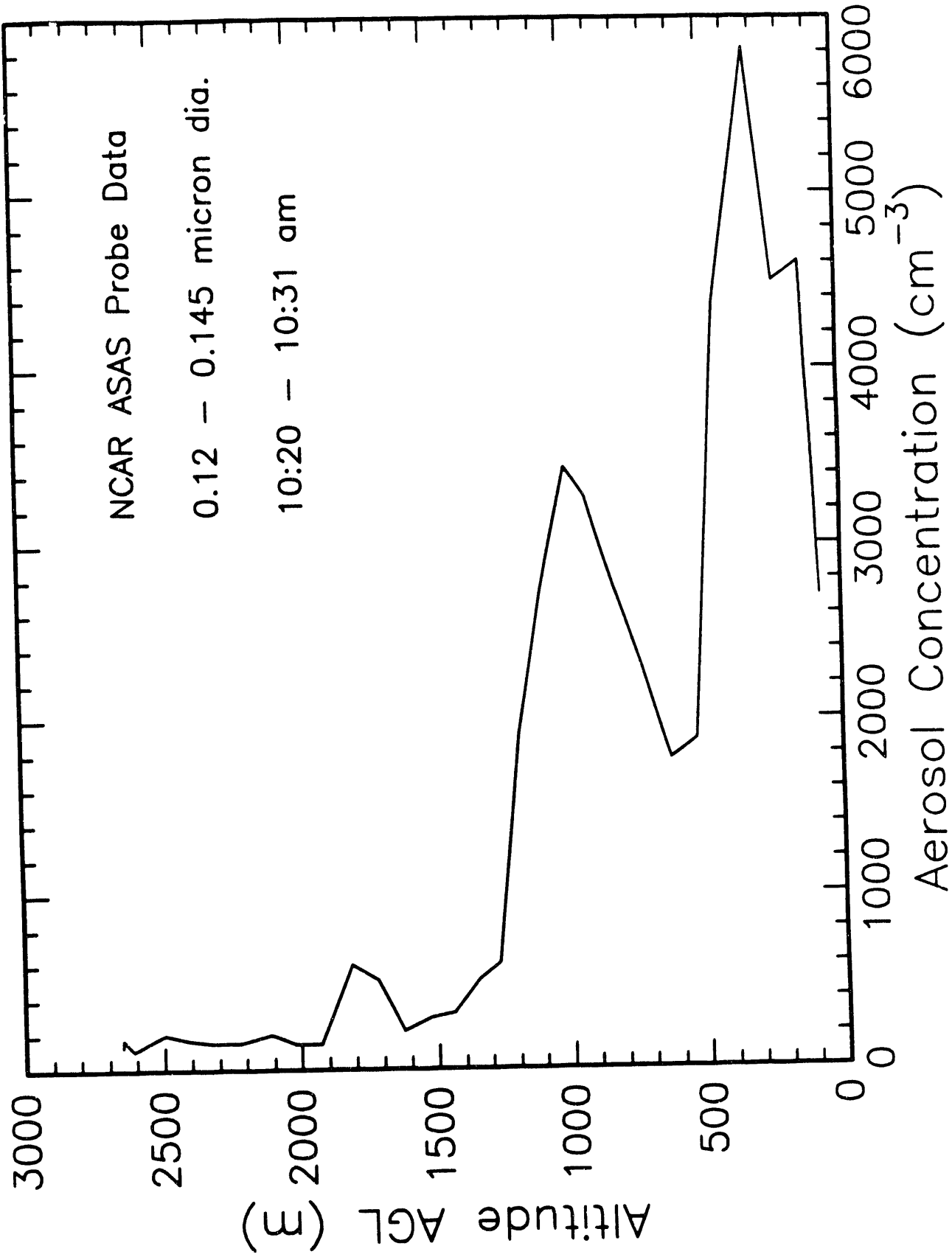




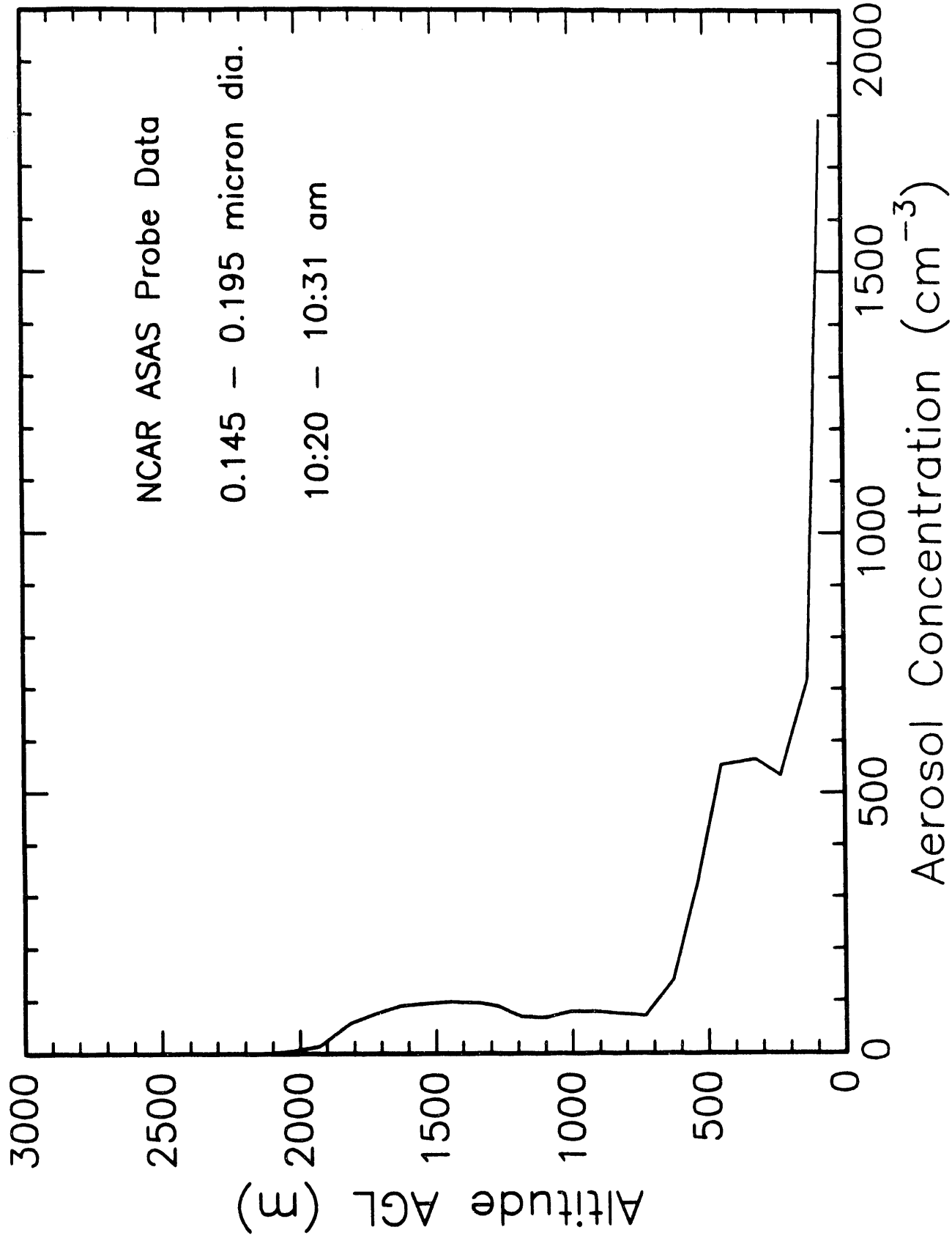




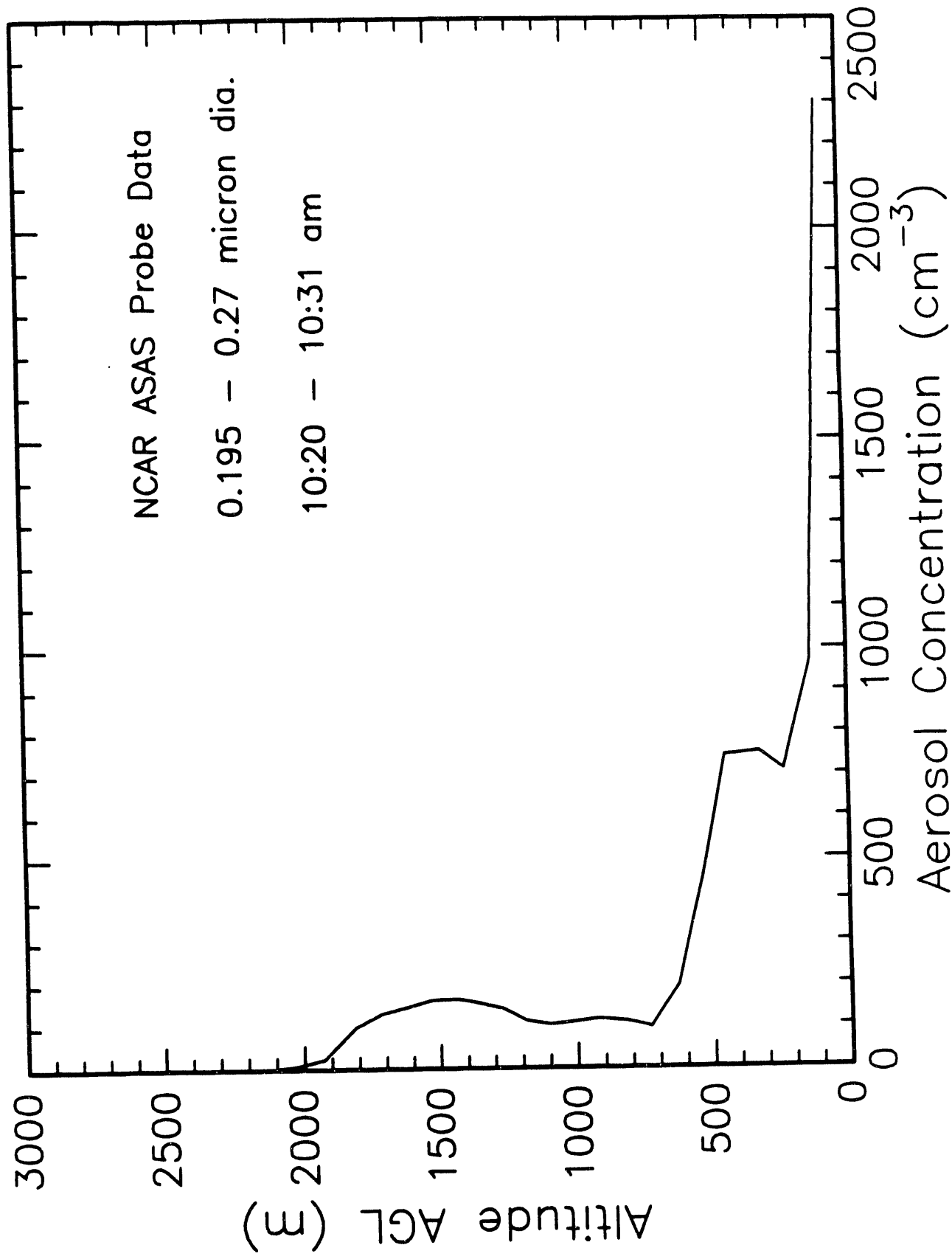
Mexico City February 26, 1991



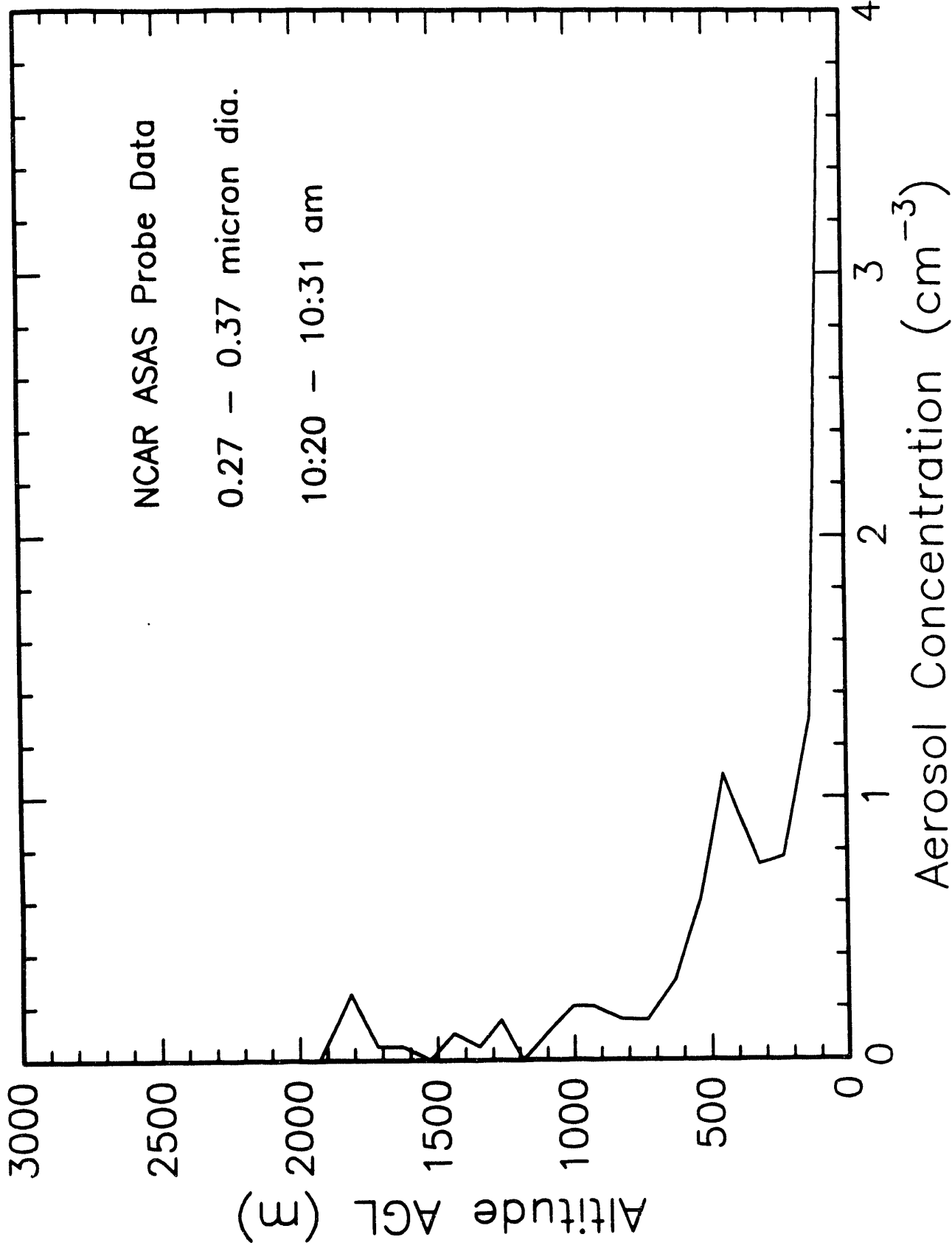
# Mexico City February 26, 1991



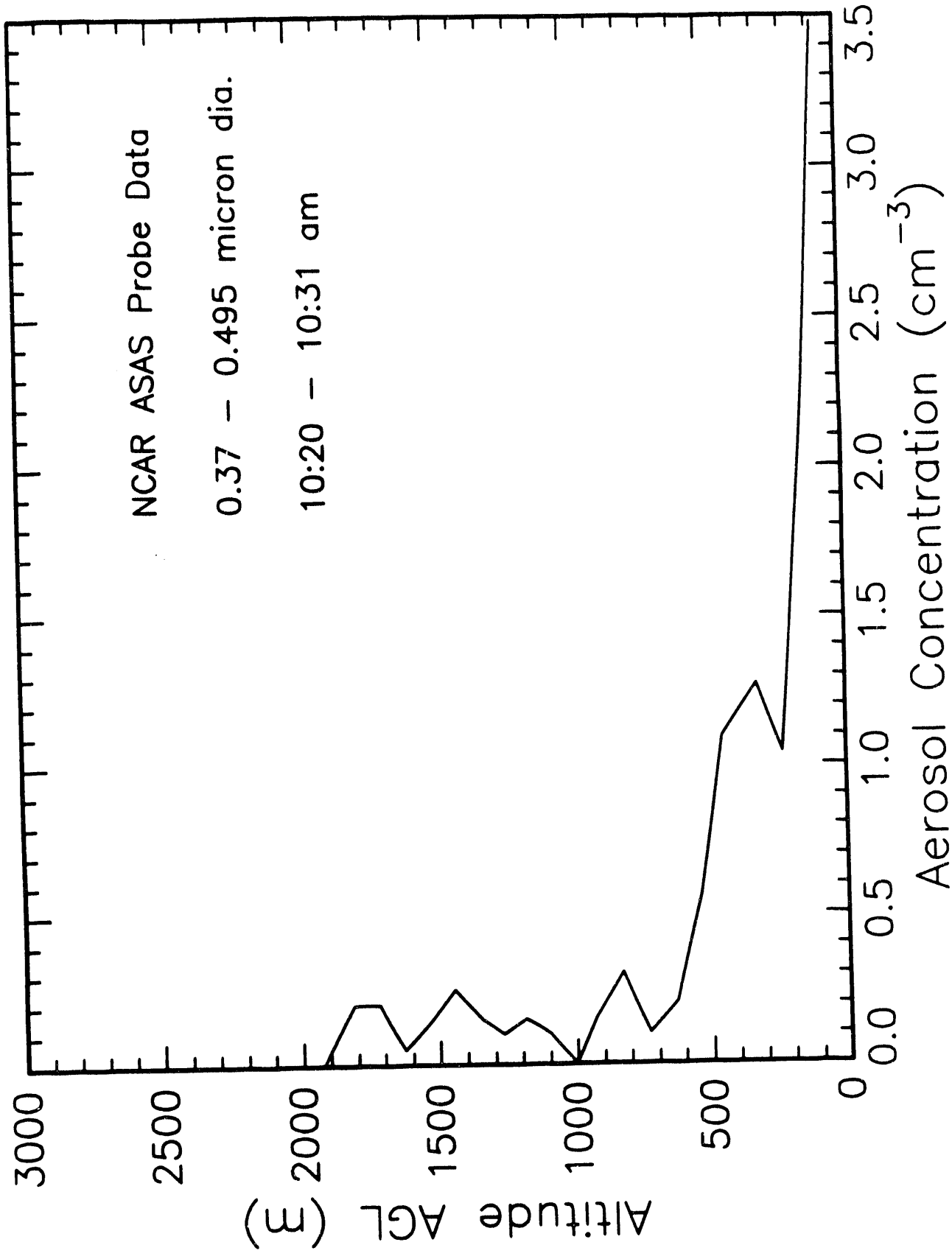
Mexico City February 26, 1991



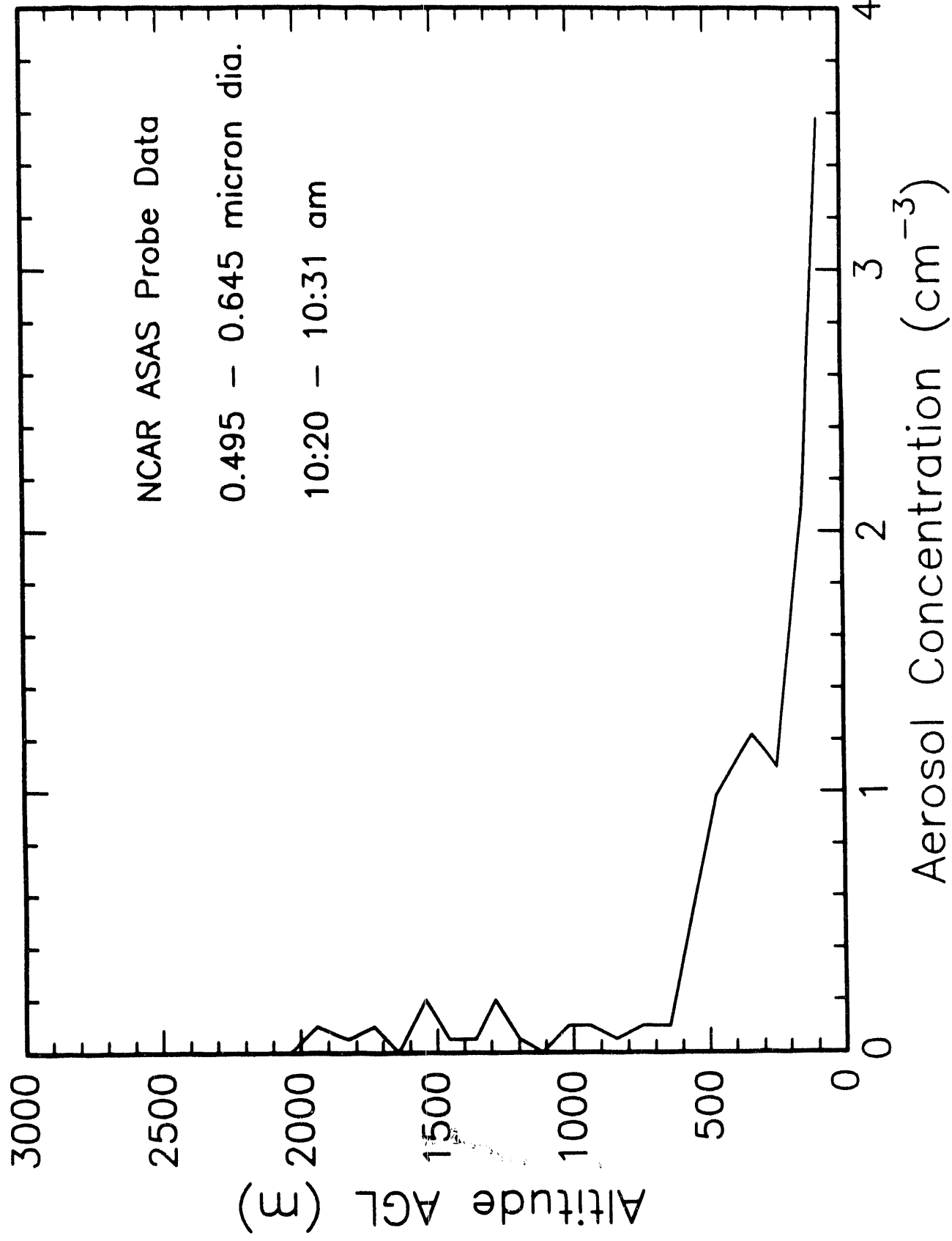
Mexico City February 26, 1991



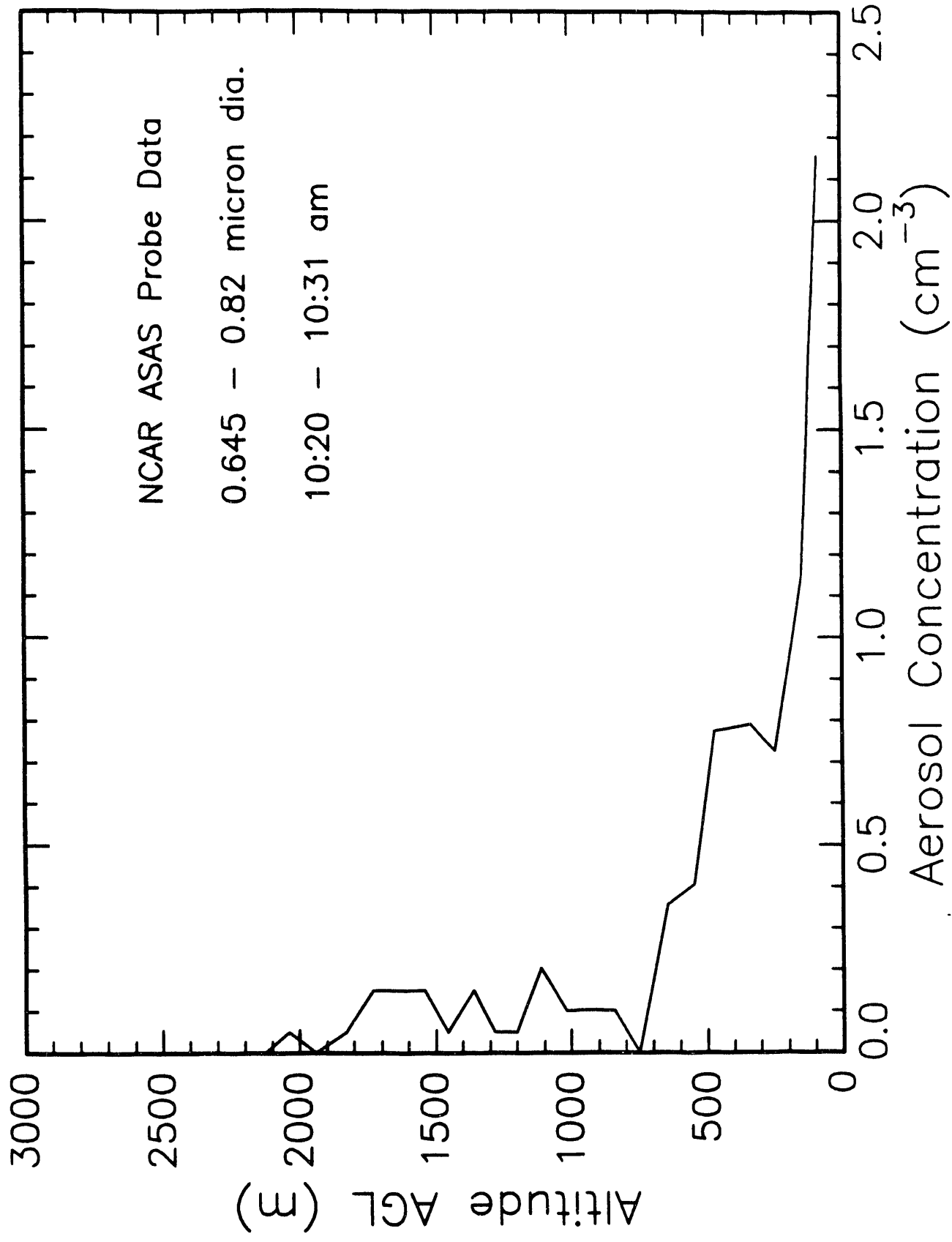
Mexico City February 26, 1991



Mexico City February 26, 1991

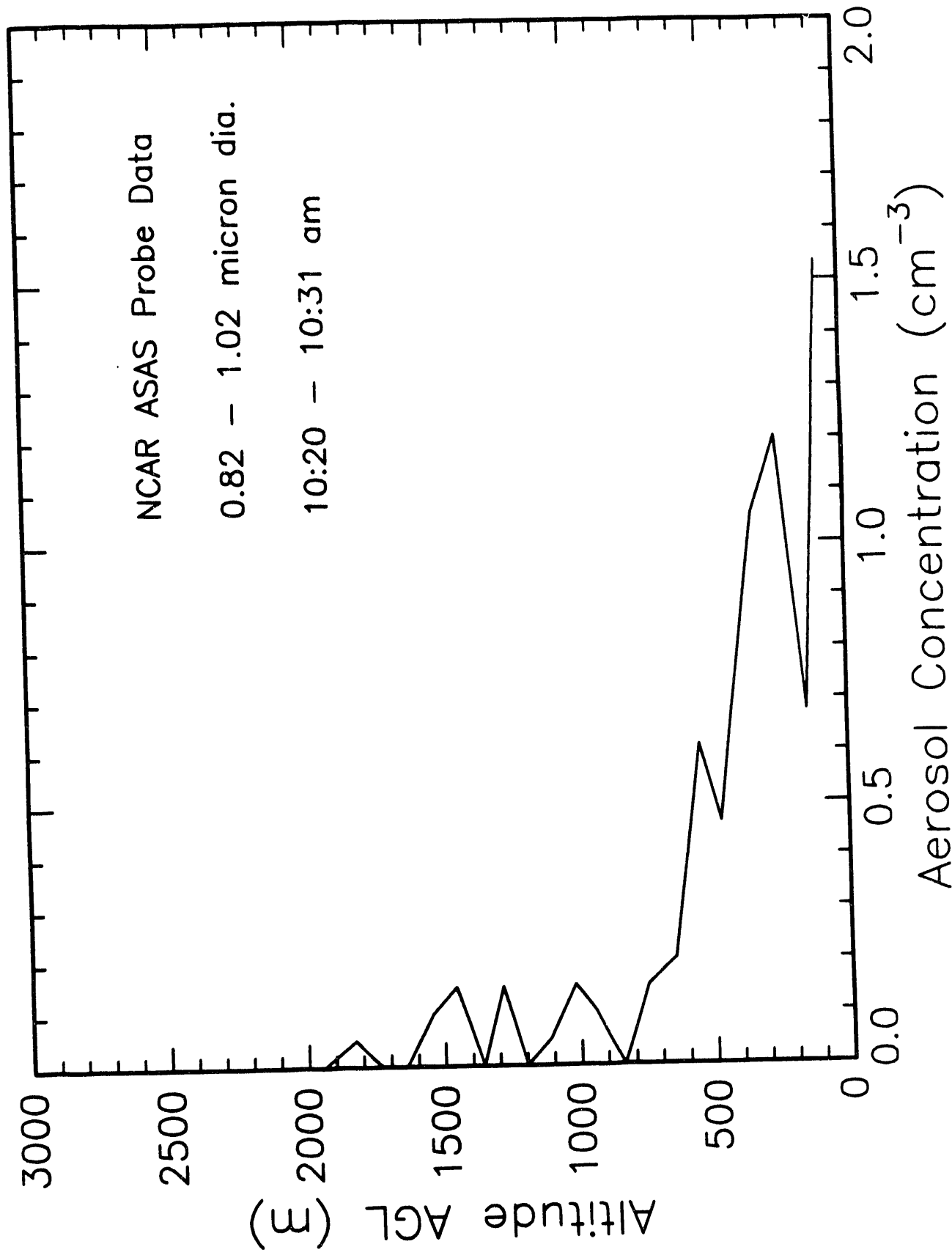


# Mexico City February 26, 1991

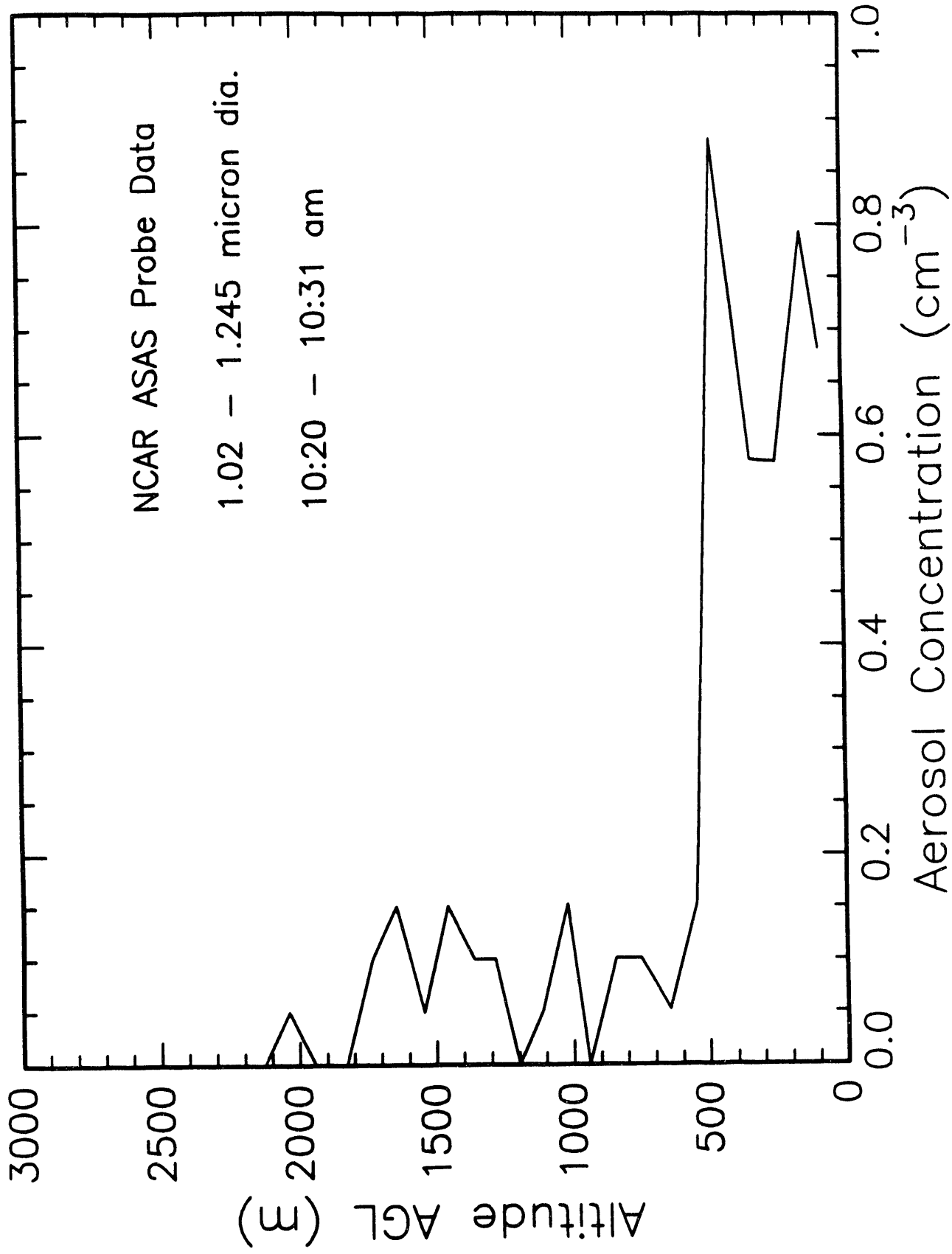




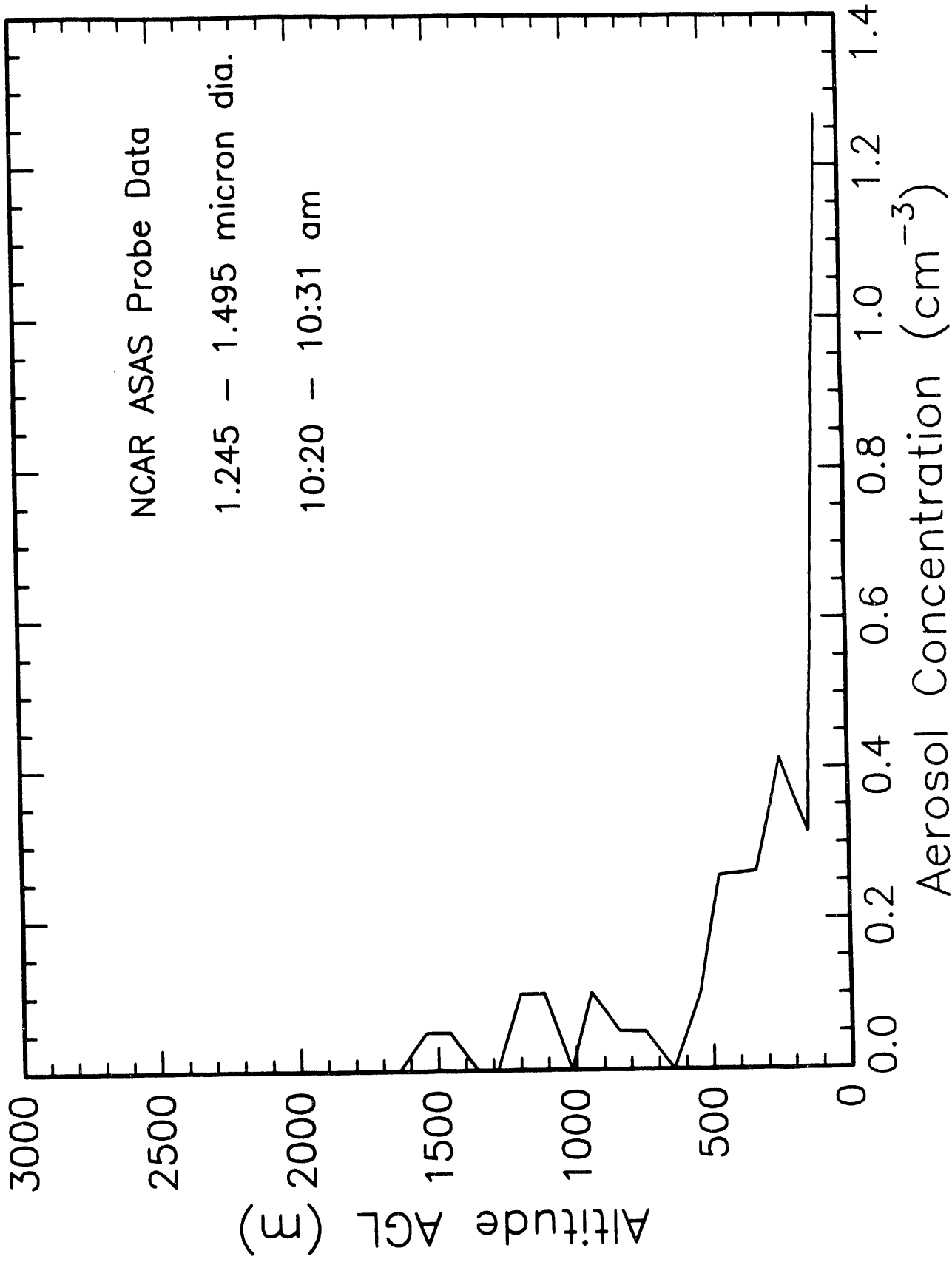
# Mexico City February 26, 1991

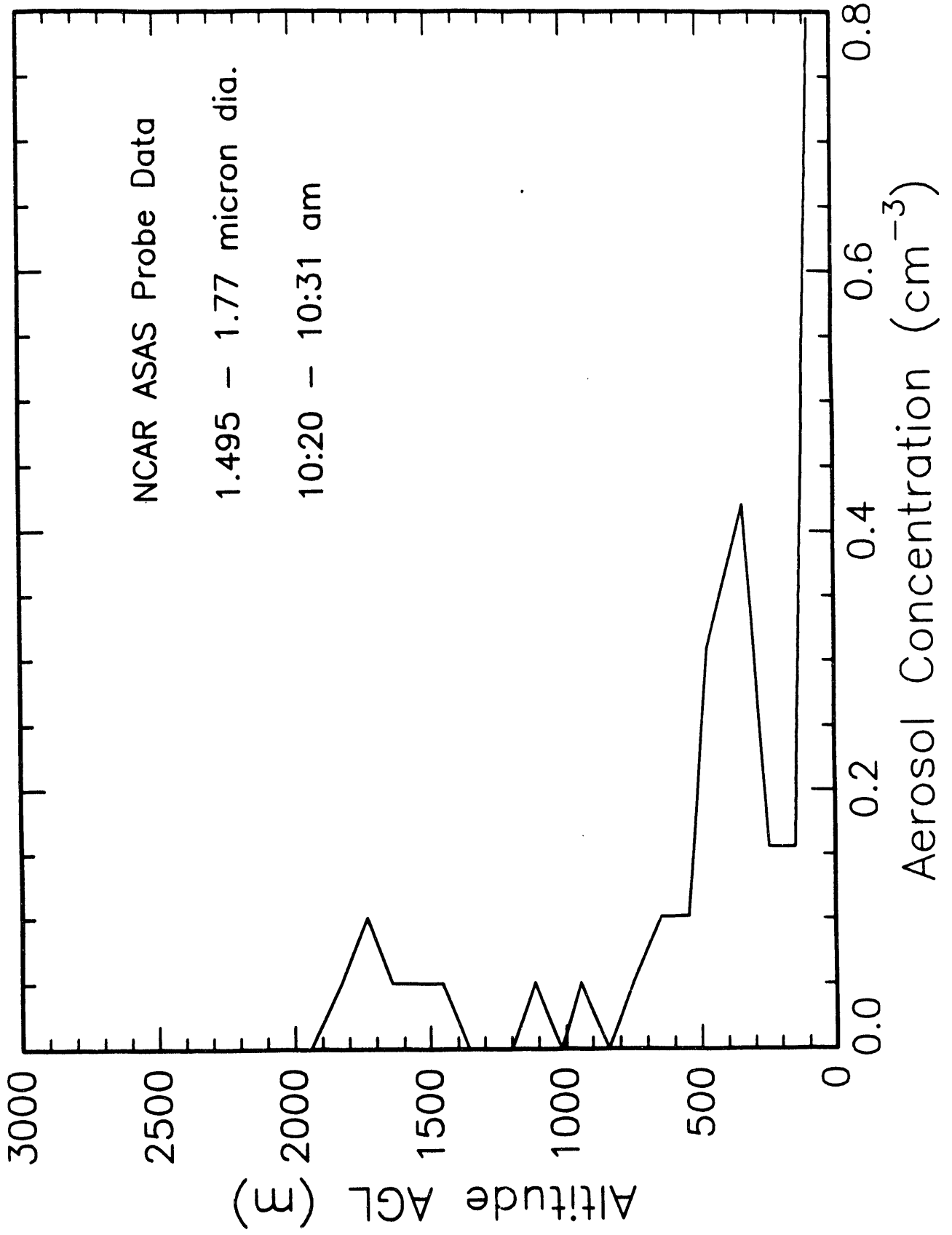


Mexico City February 26, 1991

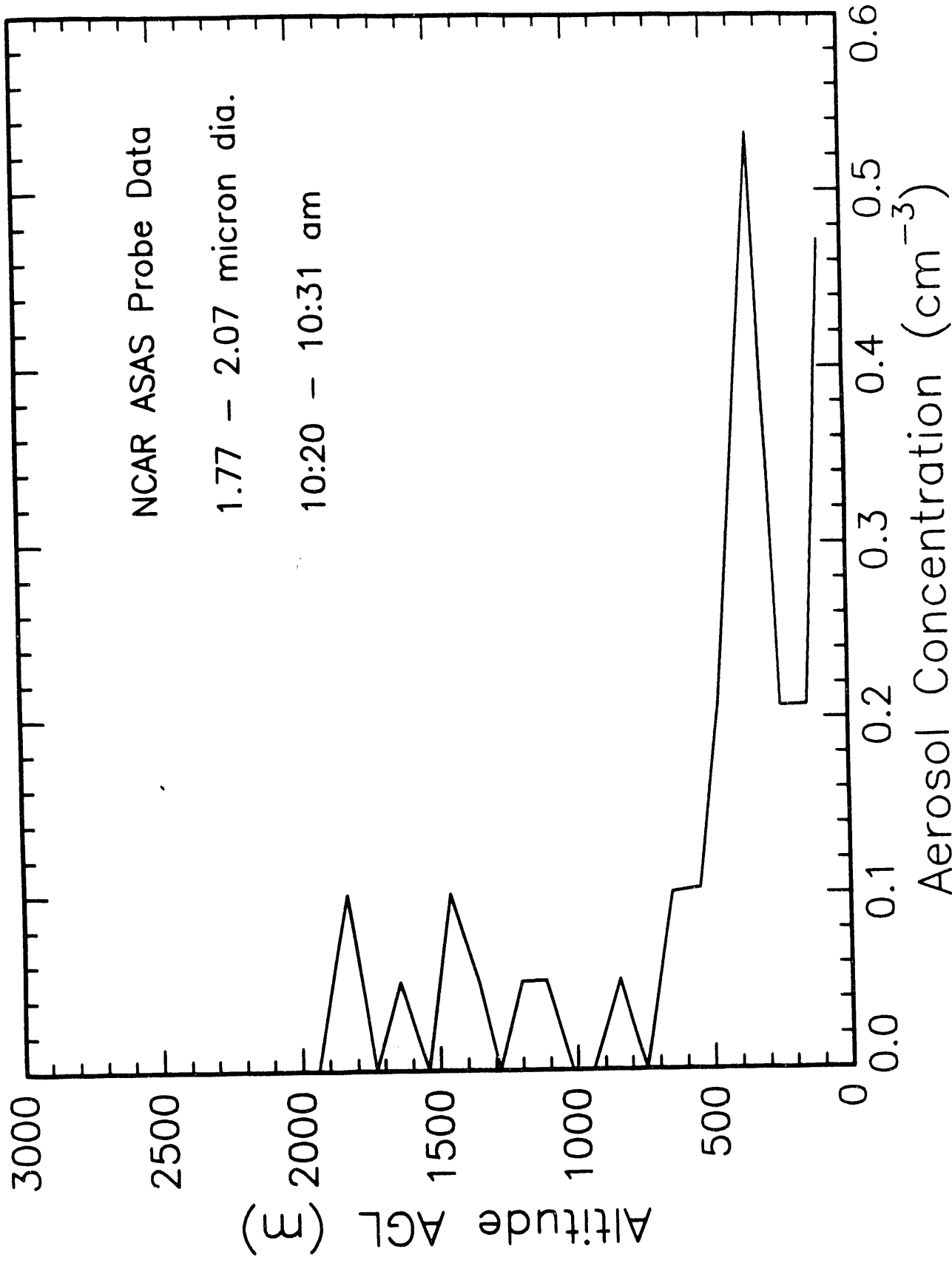


# Mexico City February 26, 1991





# Mexico City February 26, 1991

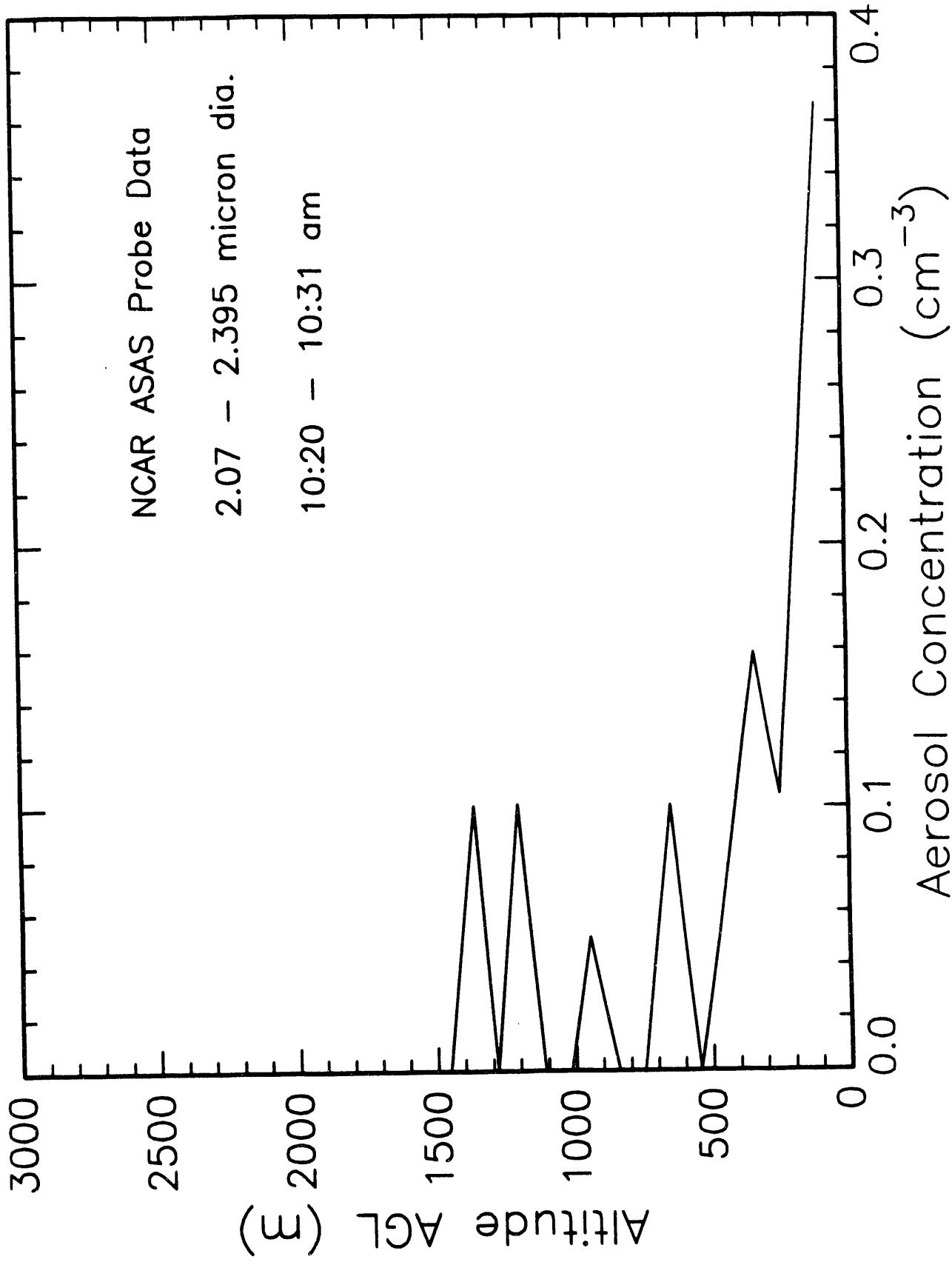


Mexico City February 26, 1991

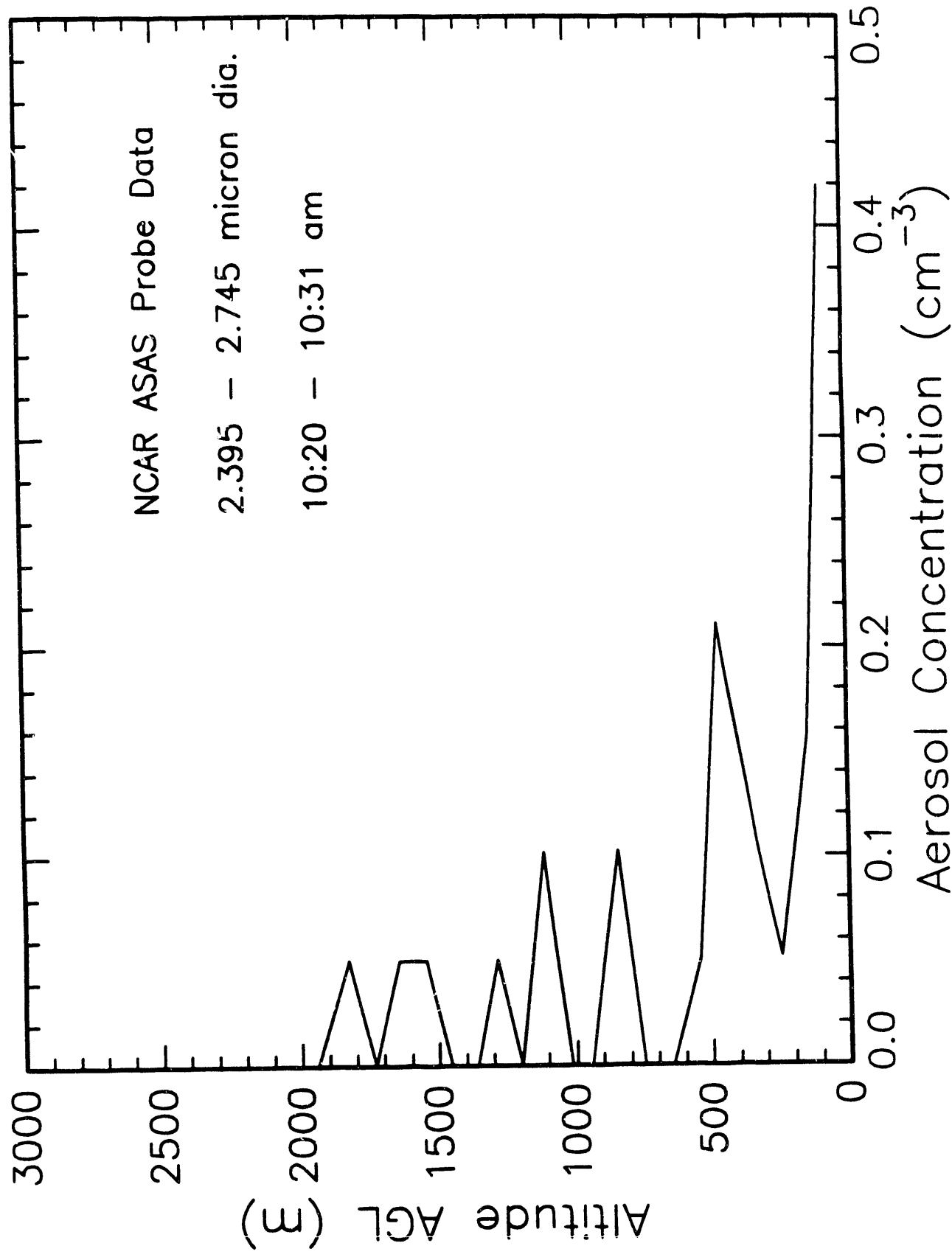
NCAR ASAS Probe Data

2.07 - 2.395 micron dia.

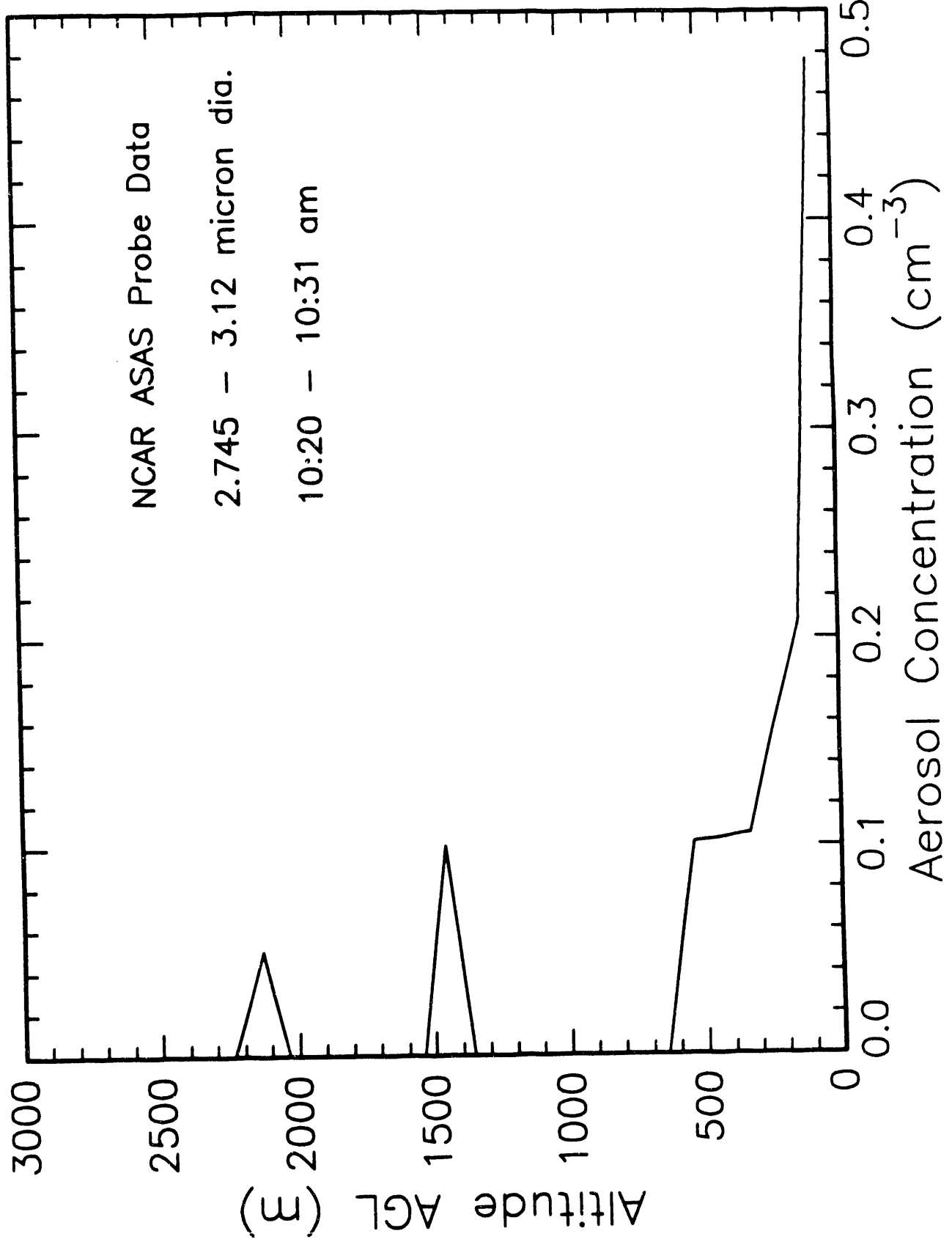
10:20 - 10:31 am



# Mexico City February 26, 1991



Mexico City February 26, 1991







:

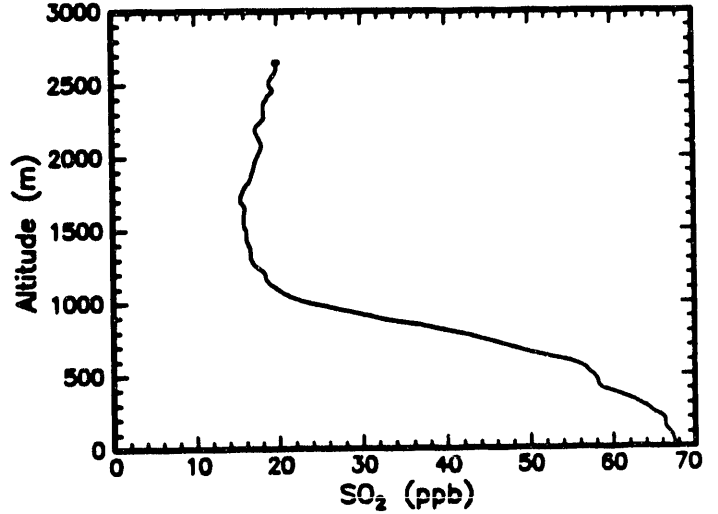
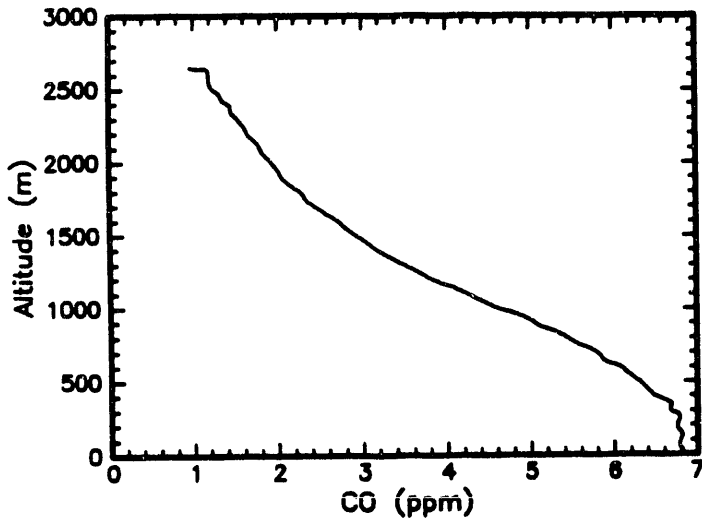
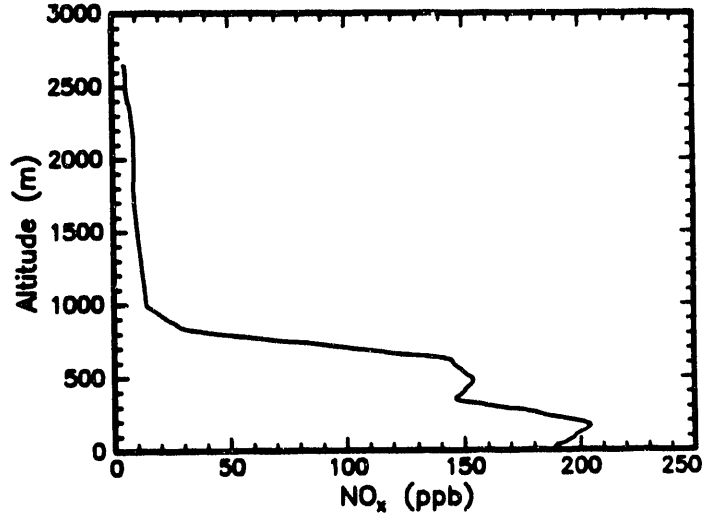
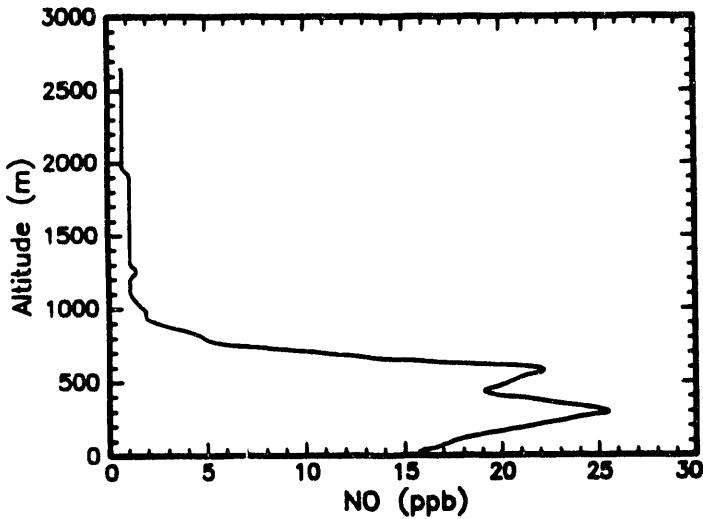
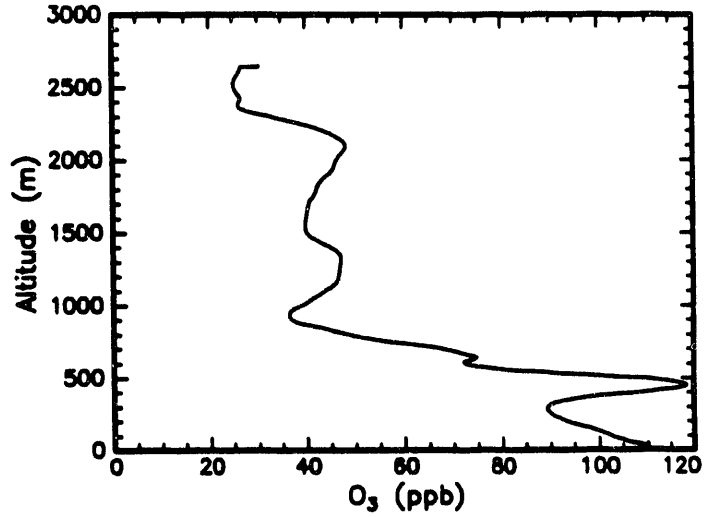
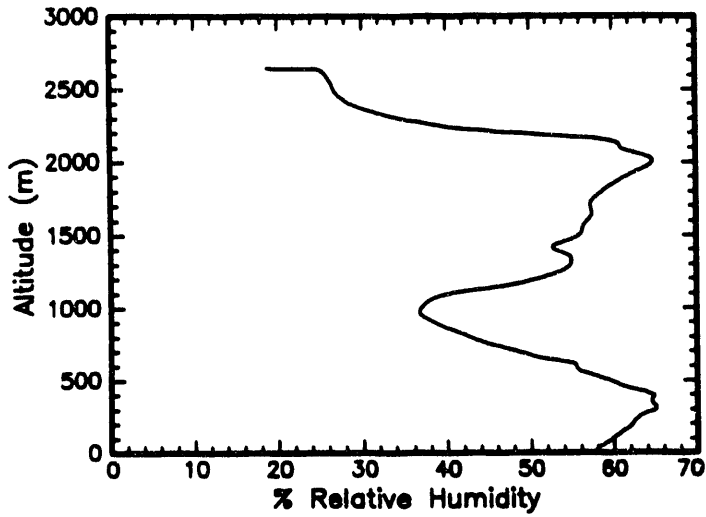
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## **Appendix E**

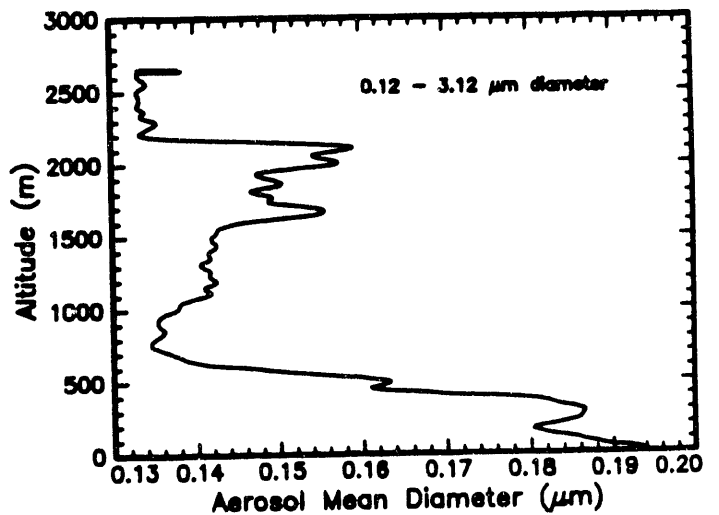
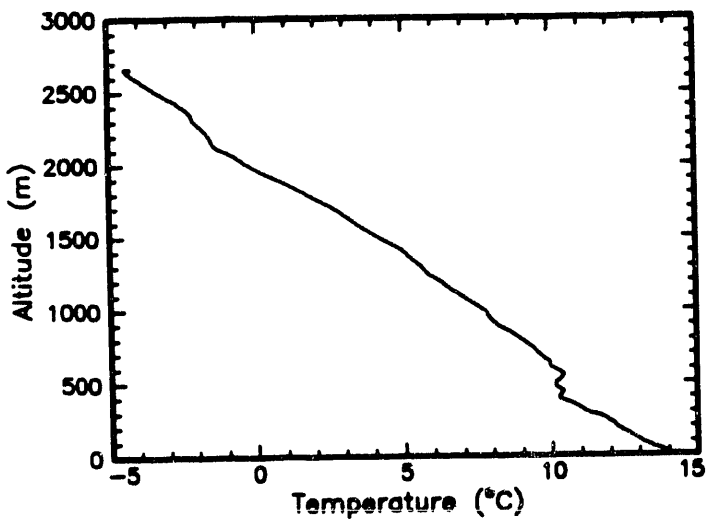
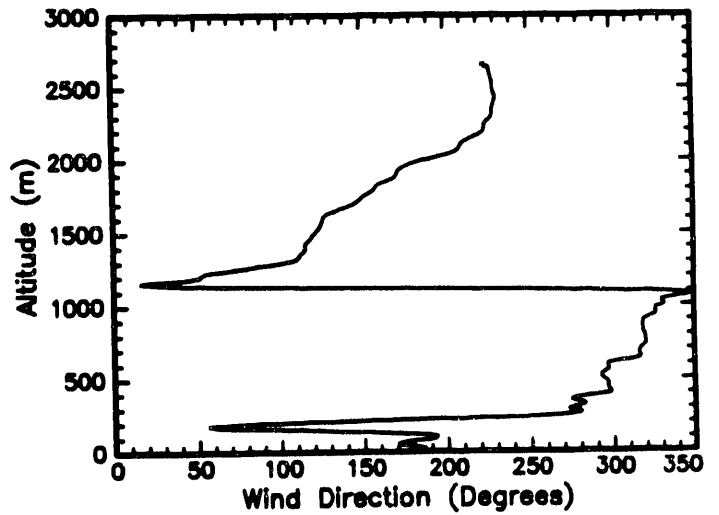
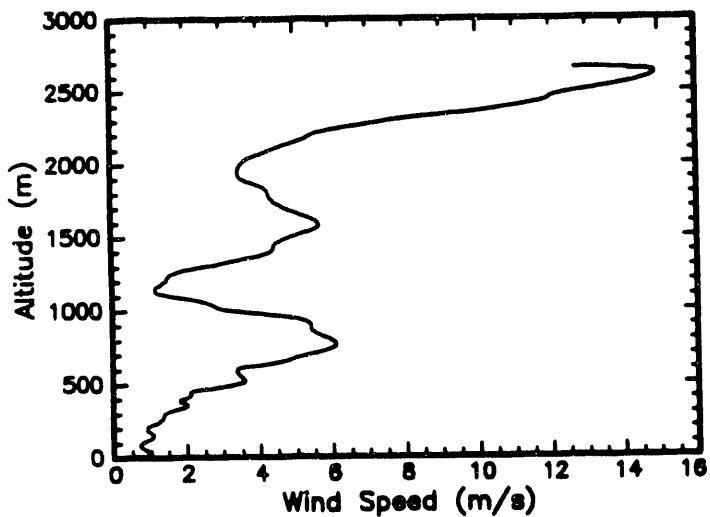
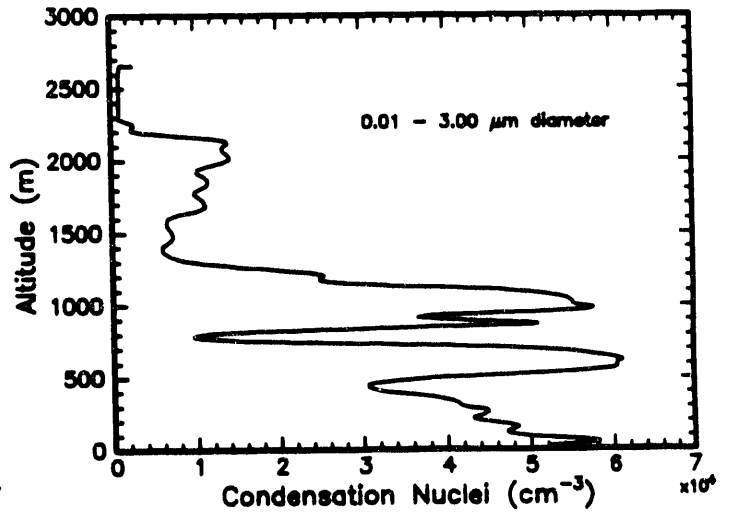
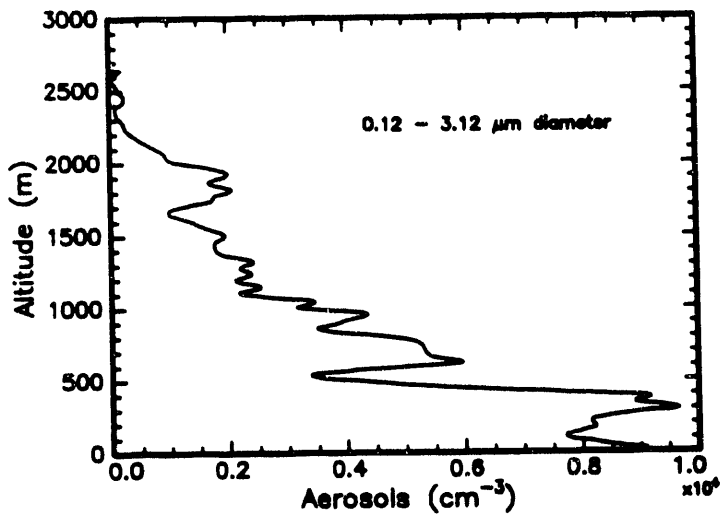
### **NCAR Meteorological and Air Pollutant Ascent Data**

# NCAR Ascent of February 22, 1991

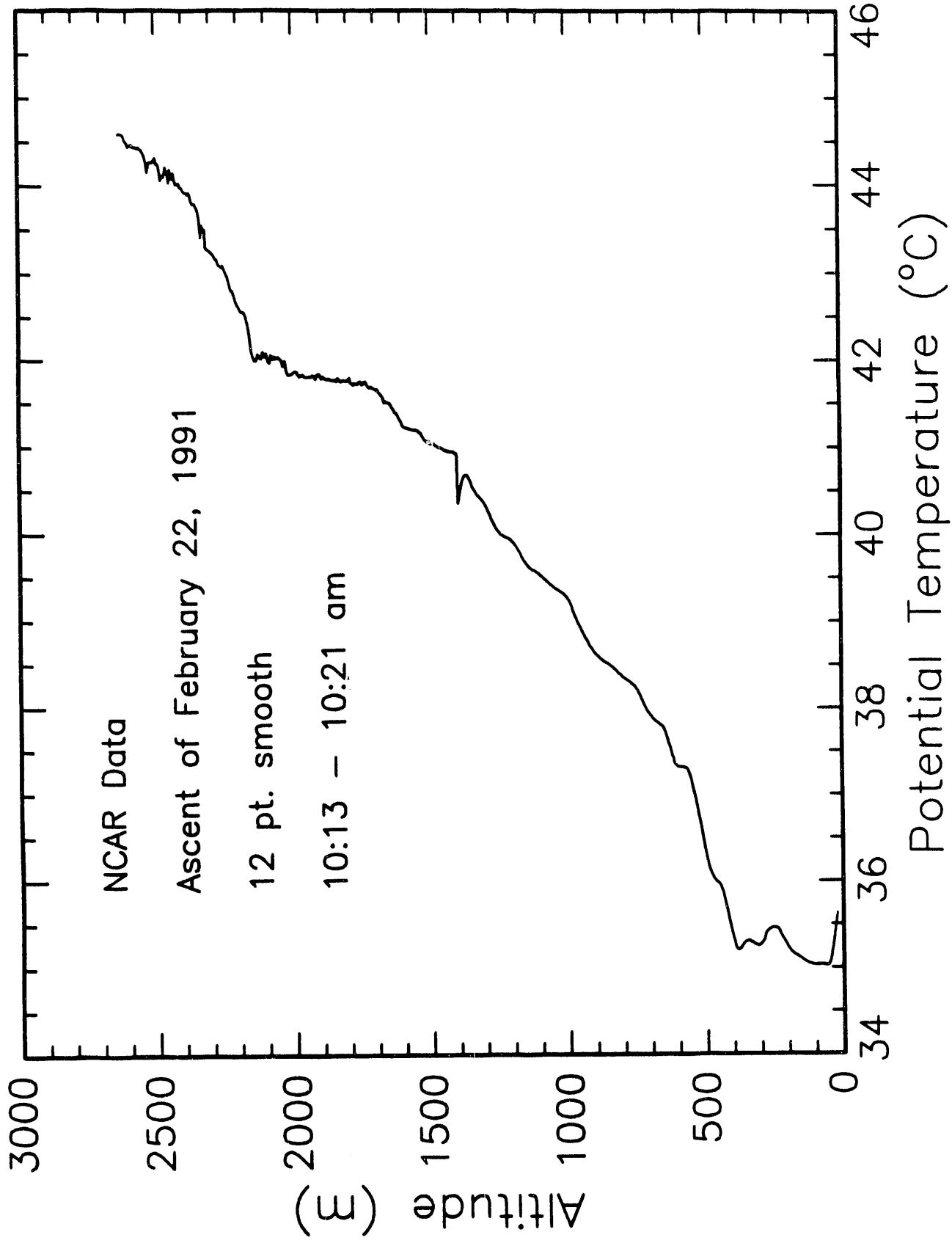
10:13 - 10:22 am



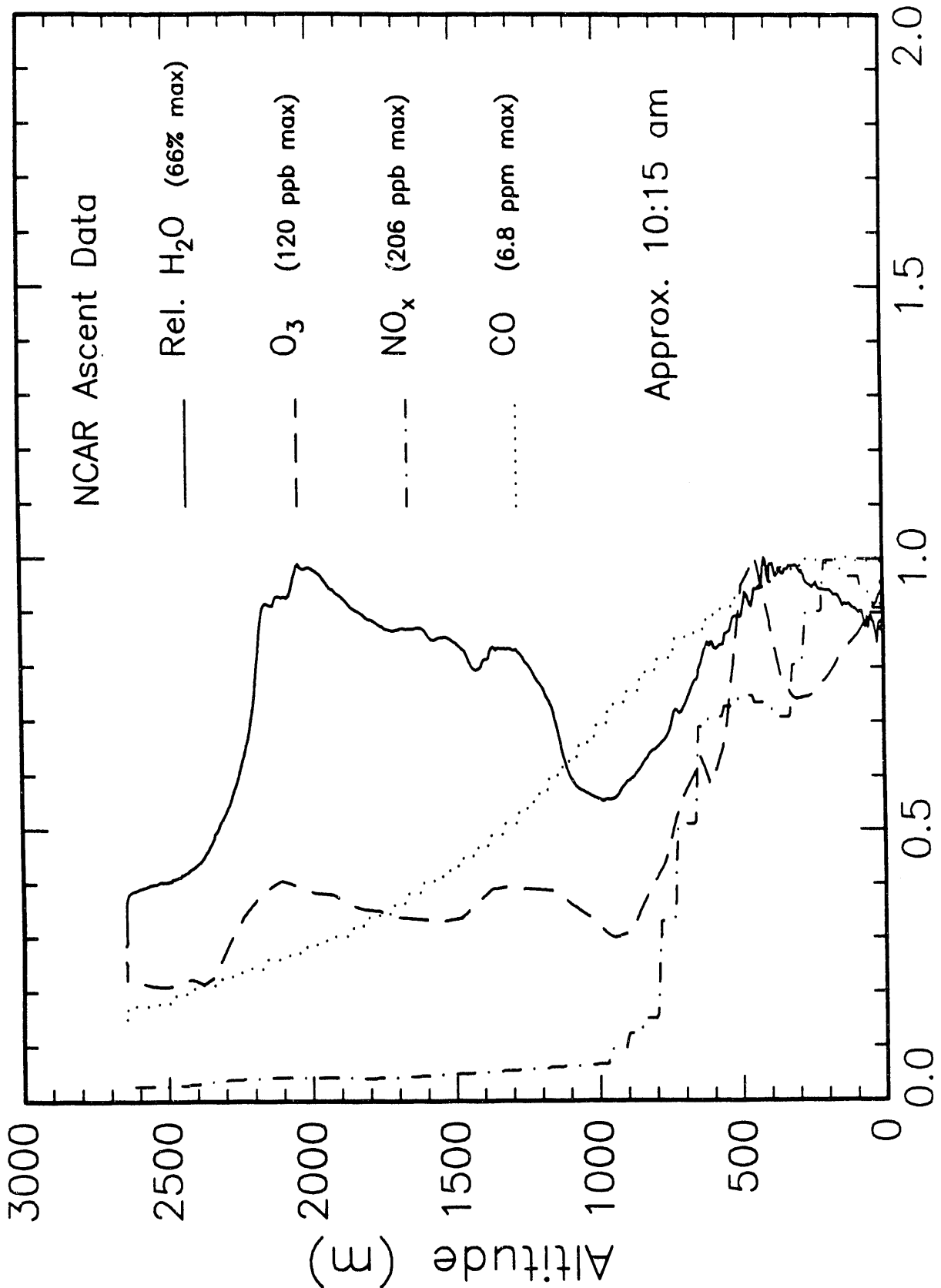
NCAR Ascent of February 22, 1991  
10:13 - 10:22 am



# Mexico City February 22, 1991



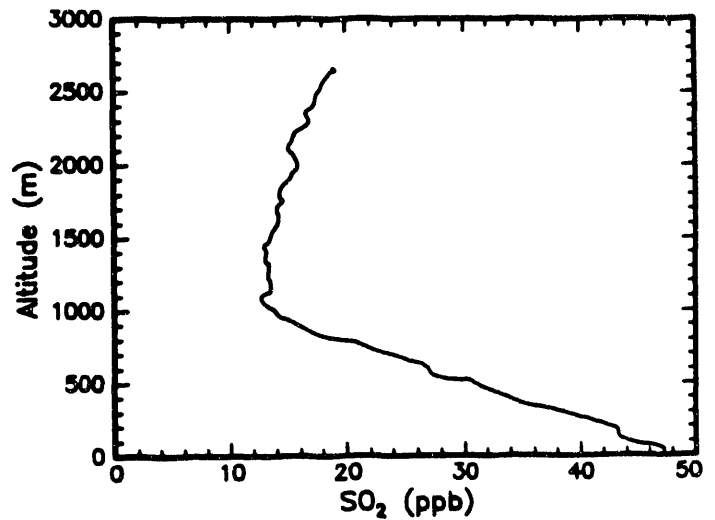
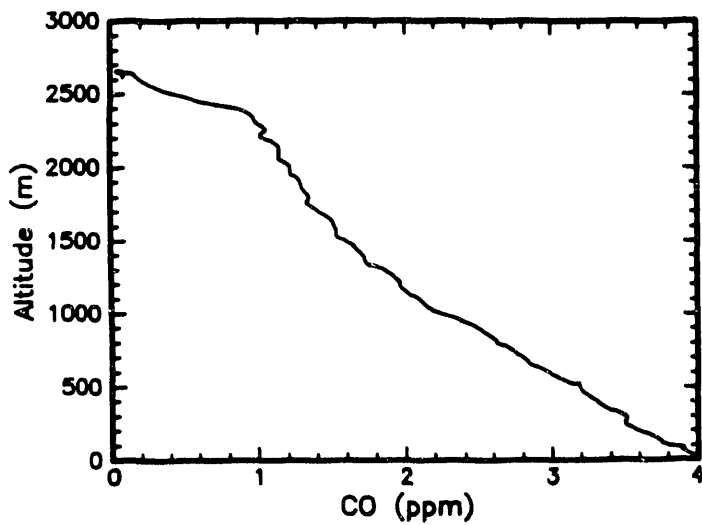
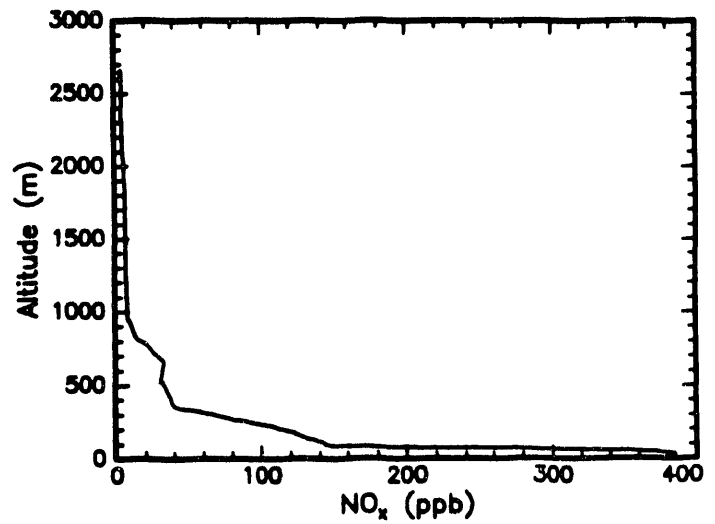
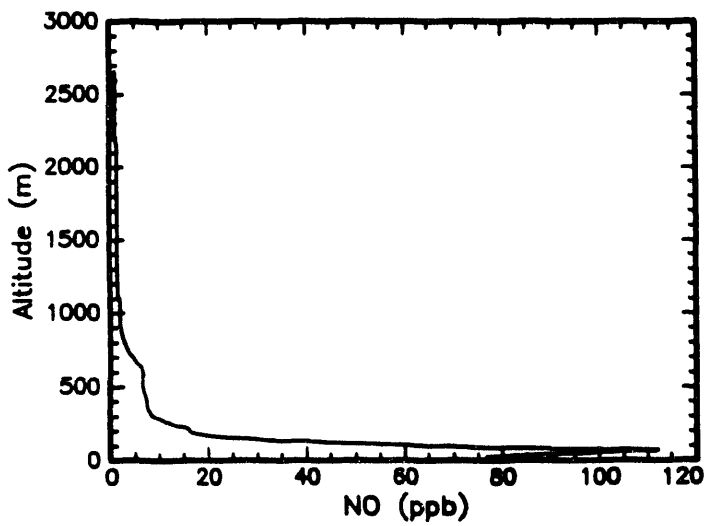
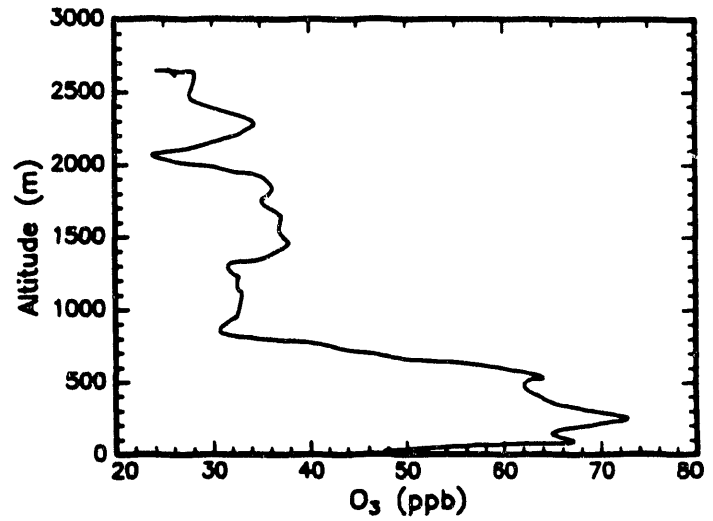
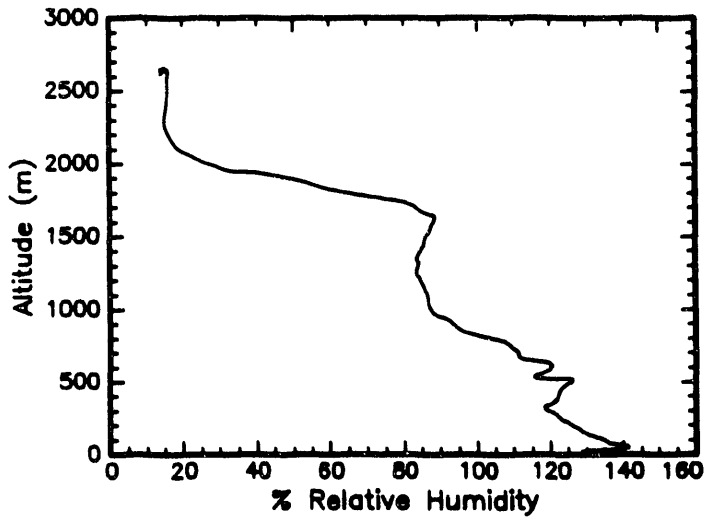
# Mexico City February 22, 1991



Normalized Rel. H<sub>2</sub>O, O<sub>3</sub>, NO<sub>x</sub>, CO

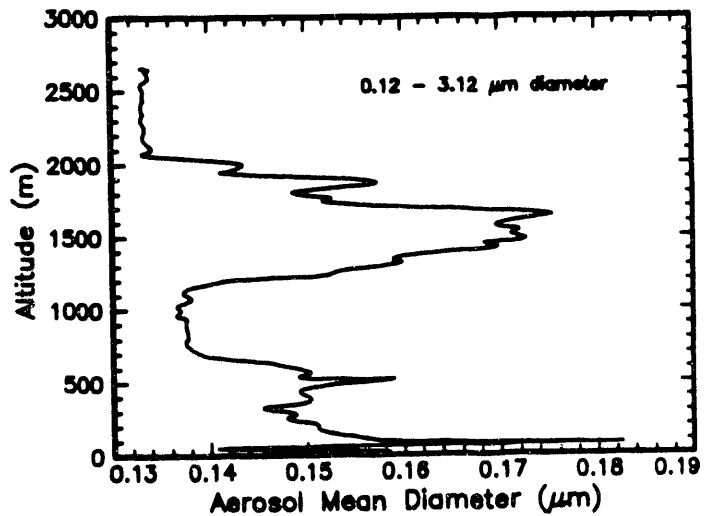
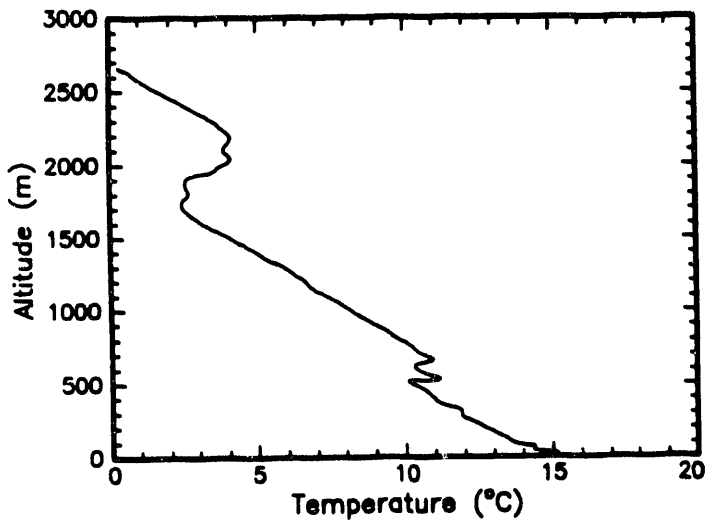
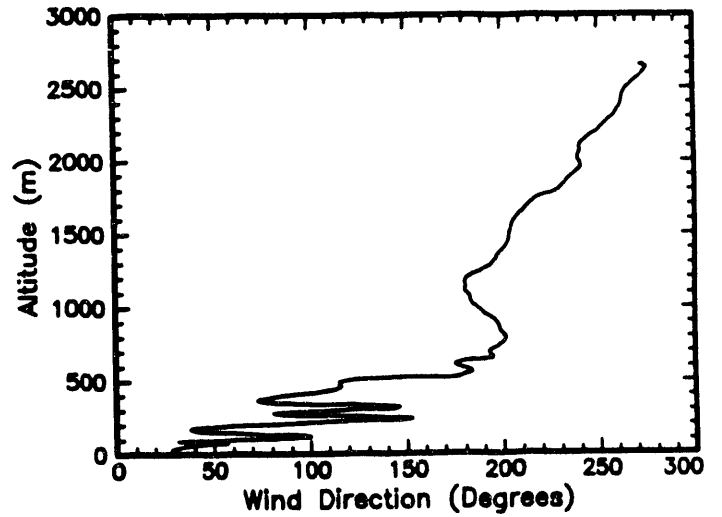
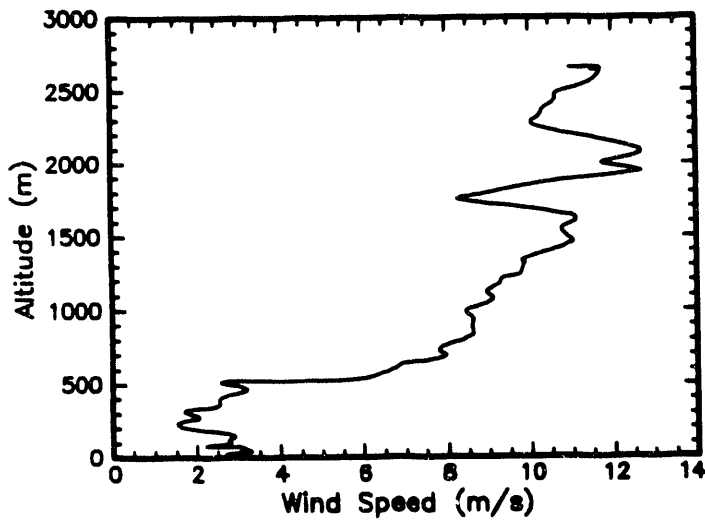
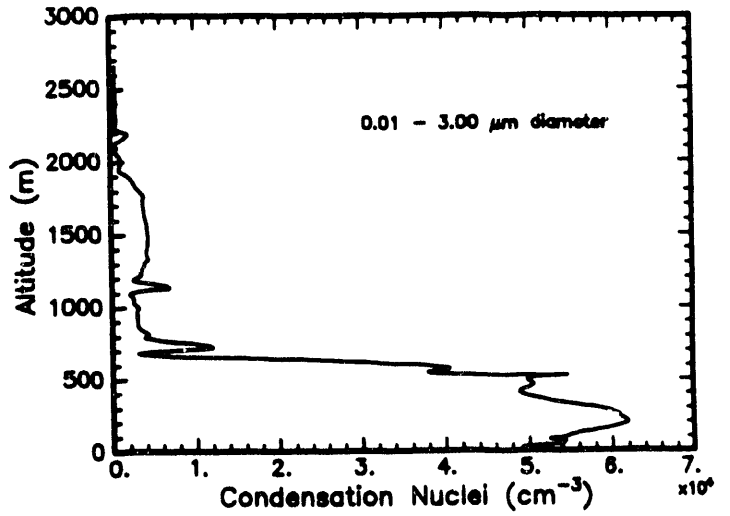
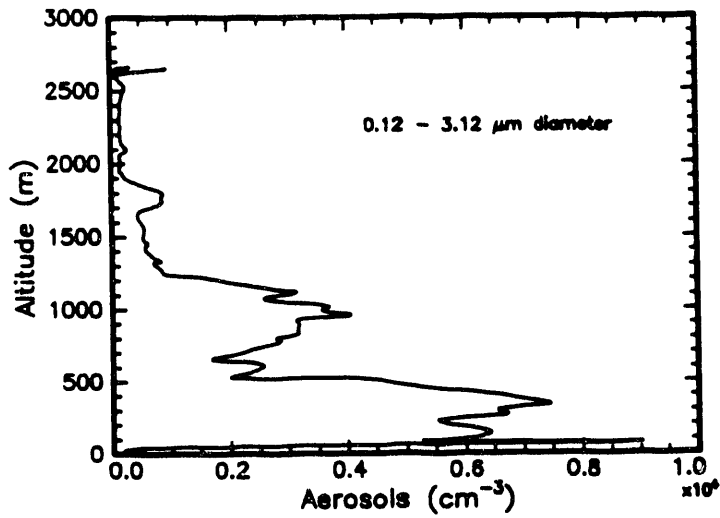
# NCAR Ascent of February 26, 1991

10:20 - 10:31 am



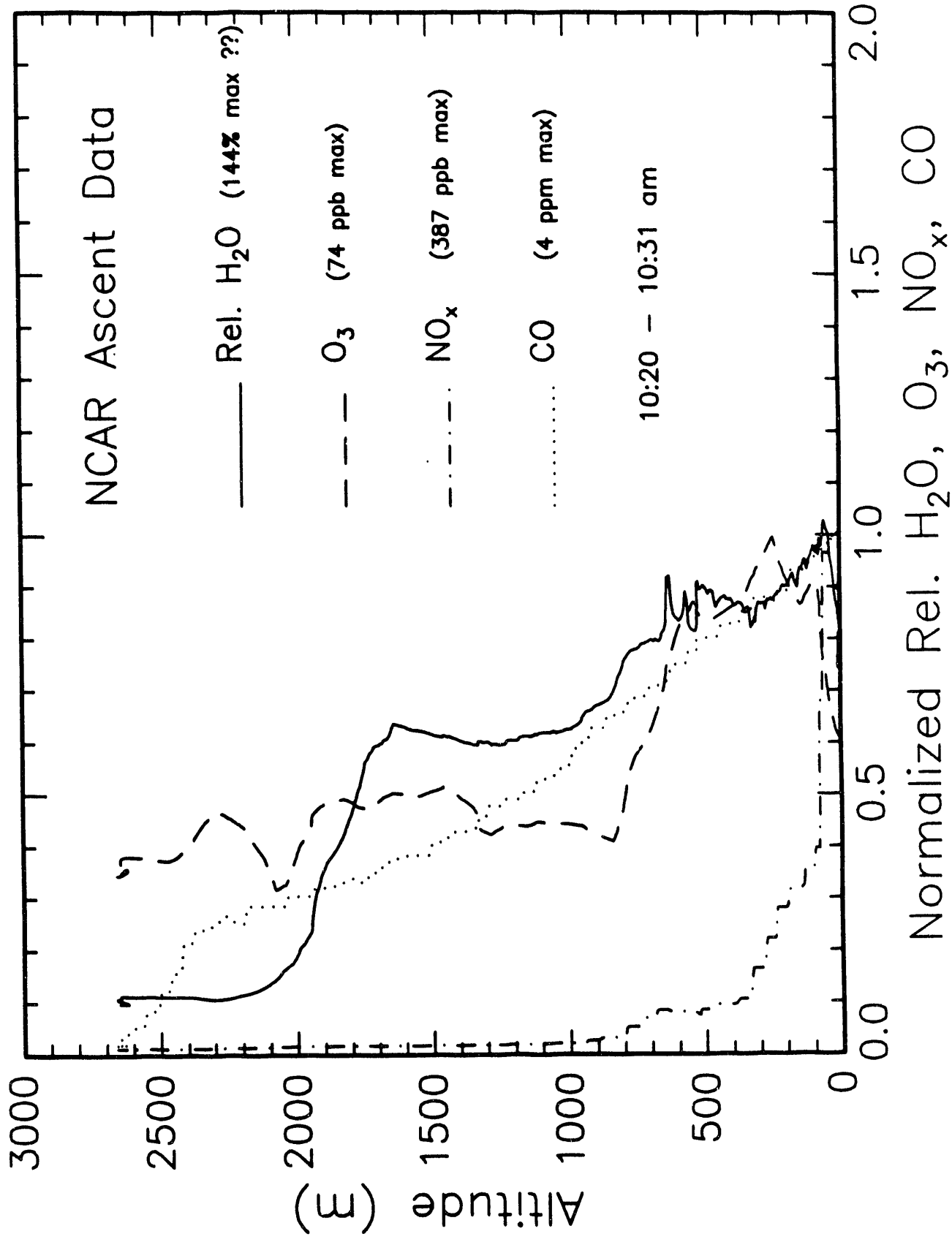
# NCAR Ascent of February 26, 1991

10:20 - 10:31 am

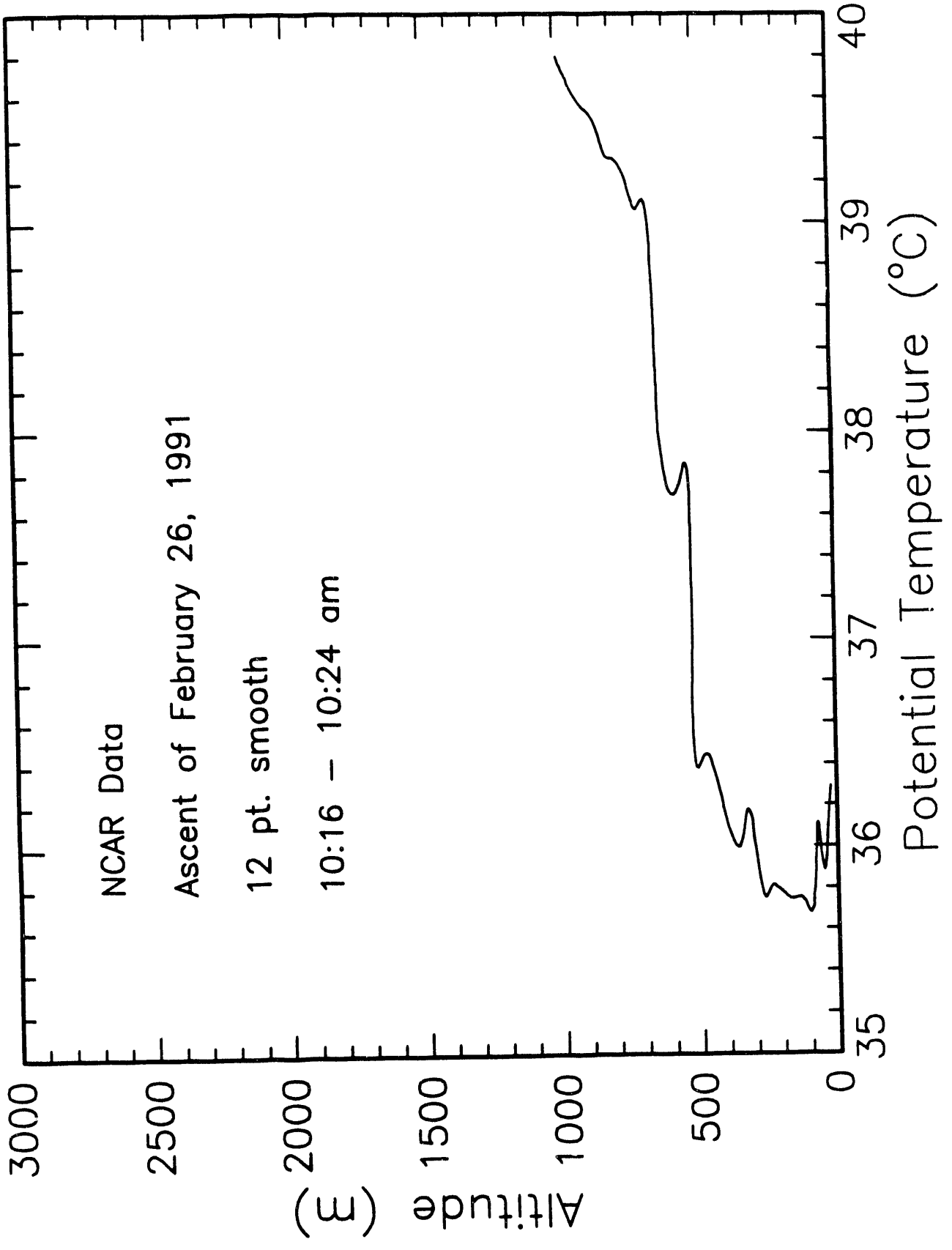




# Mexico City February 26, 1991



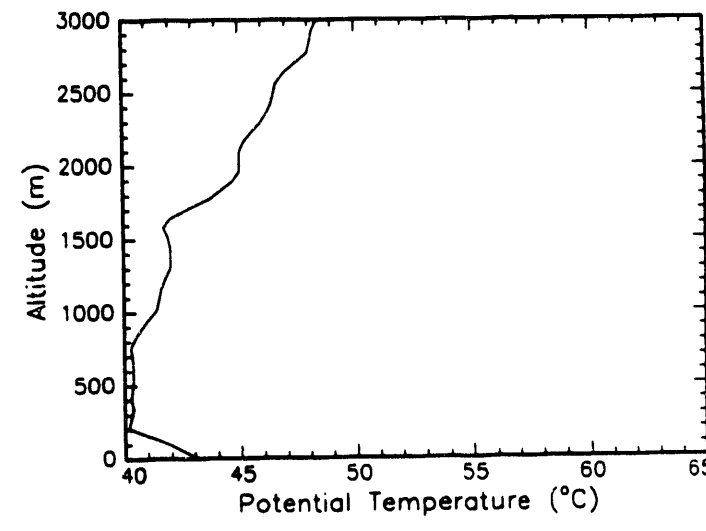
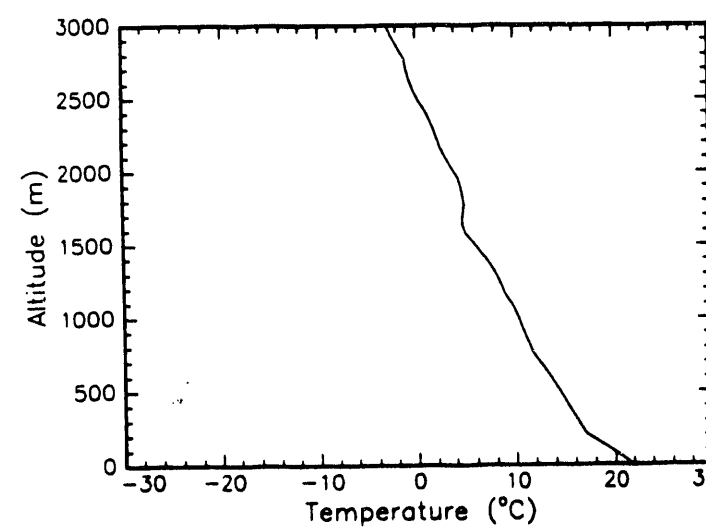
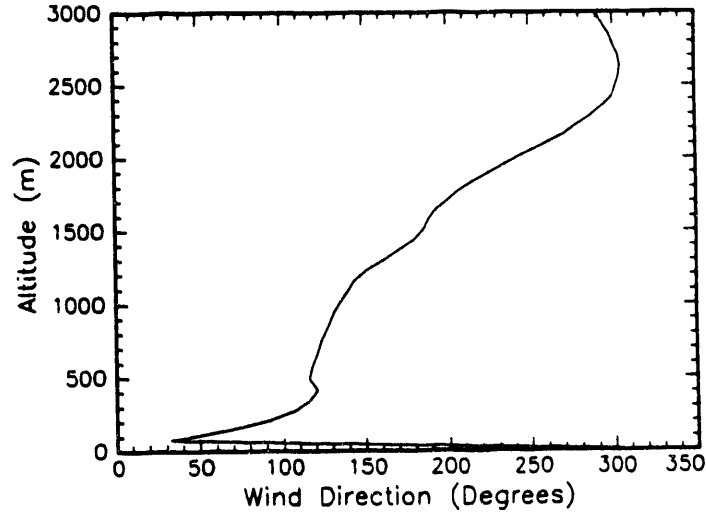
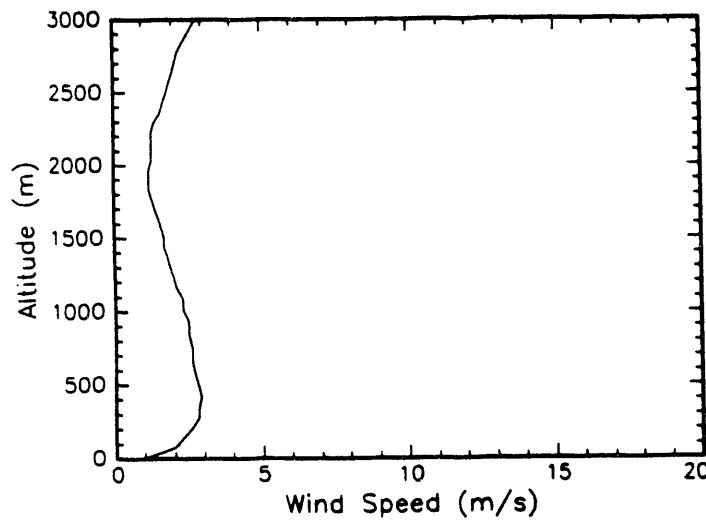
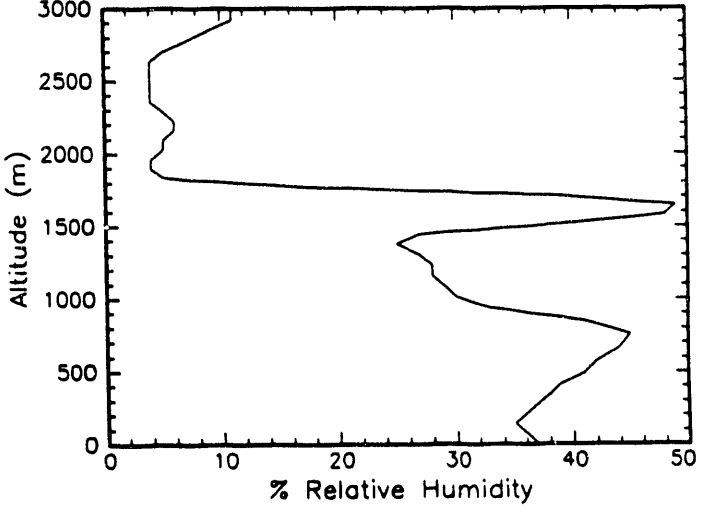
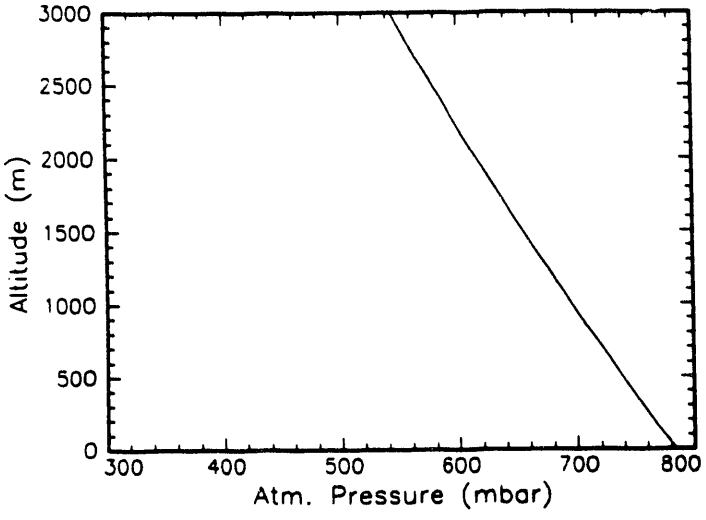
# Mexico City February 26, 1991



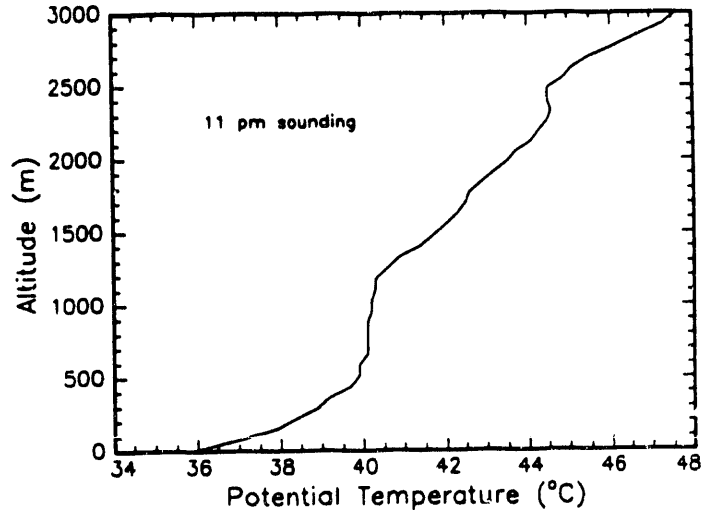
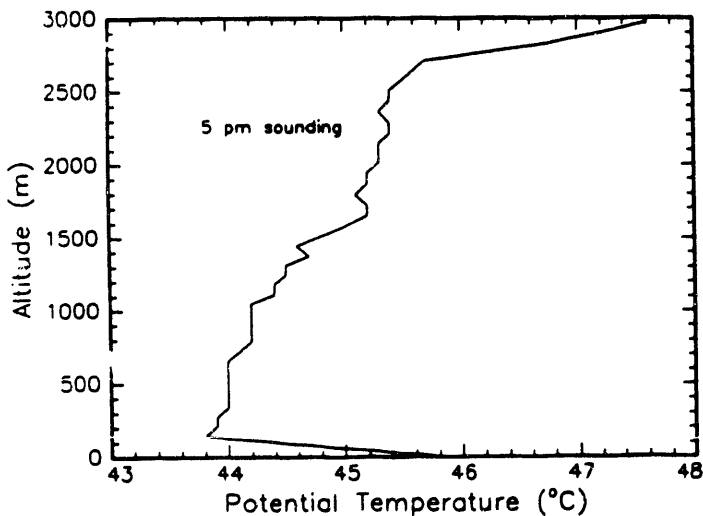
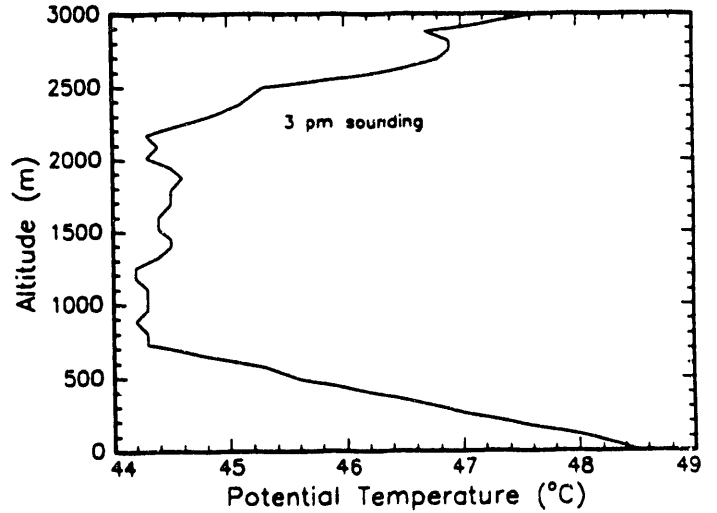
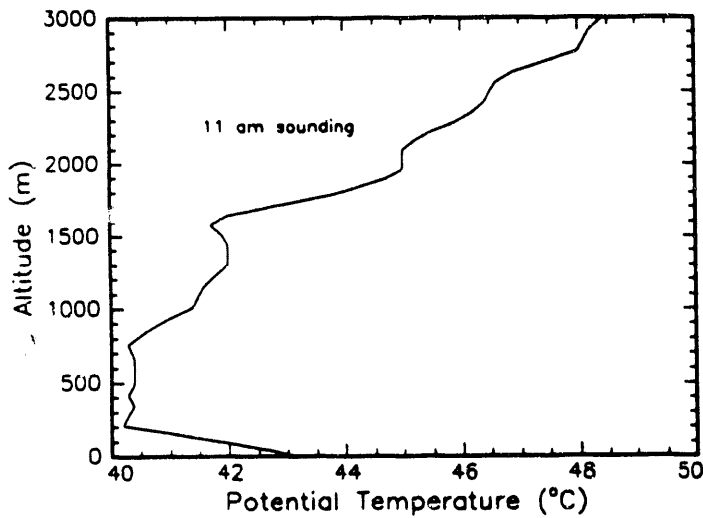
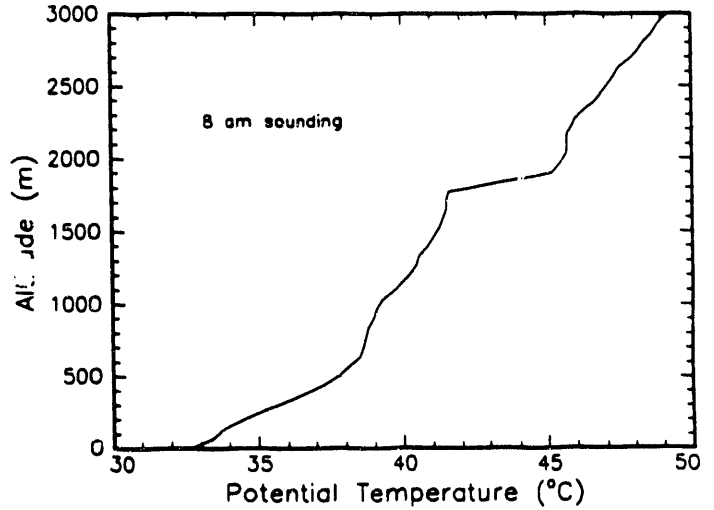
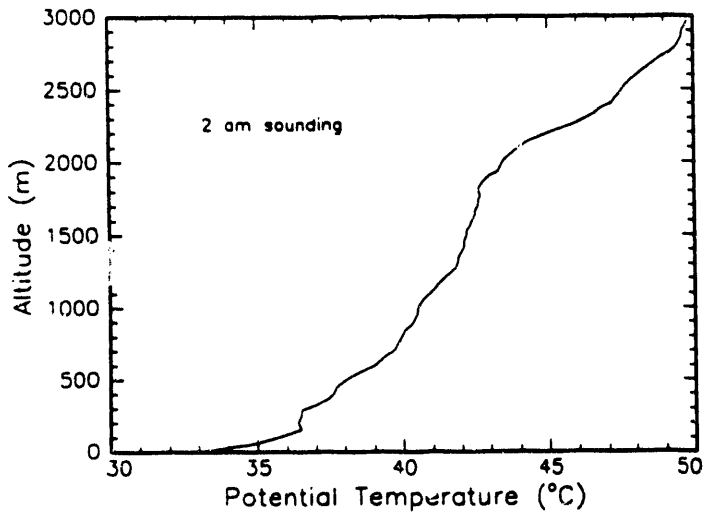
**Appendix F**

**Mexico City Airport Rawinsonde  
Data**

Airport Rawinsonde Sounding February 17, 1991  
11 am

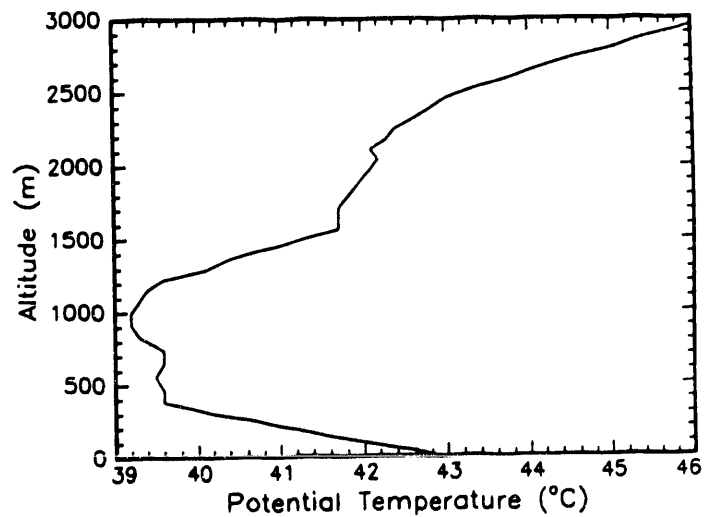
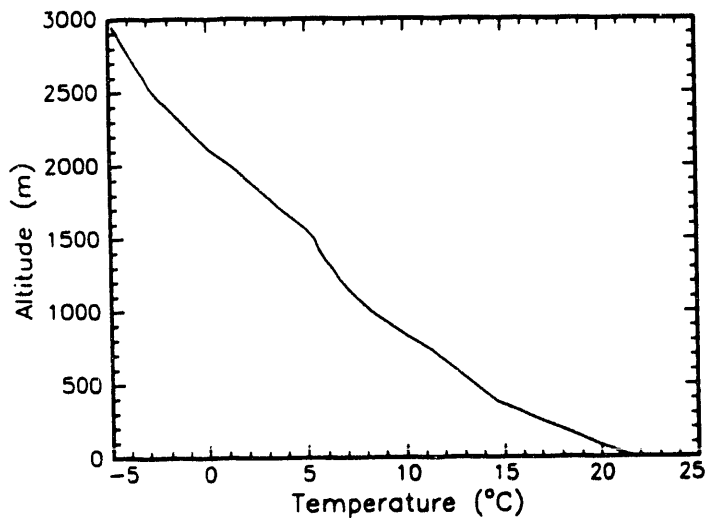
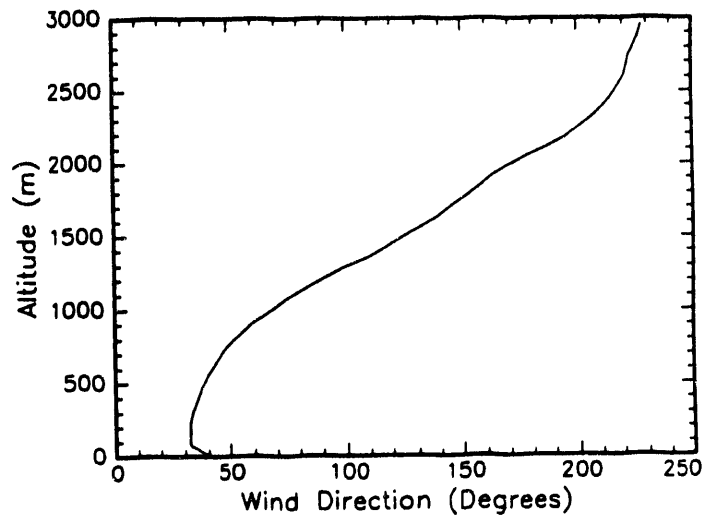
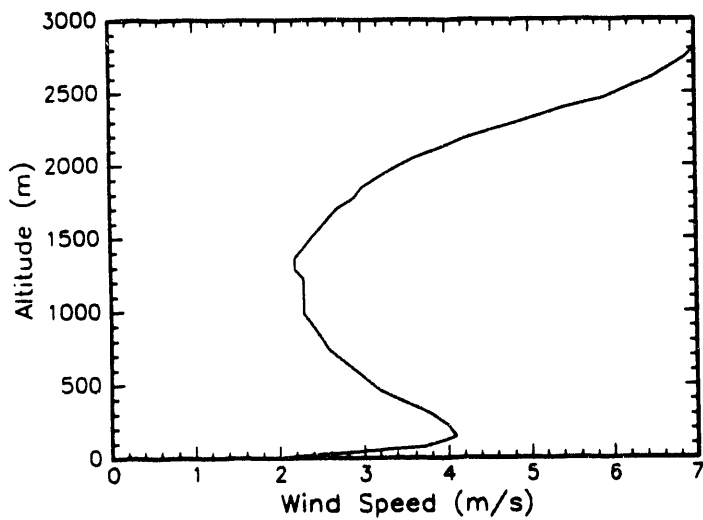
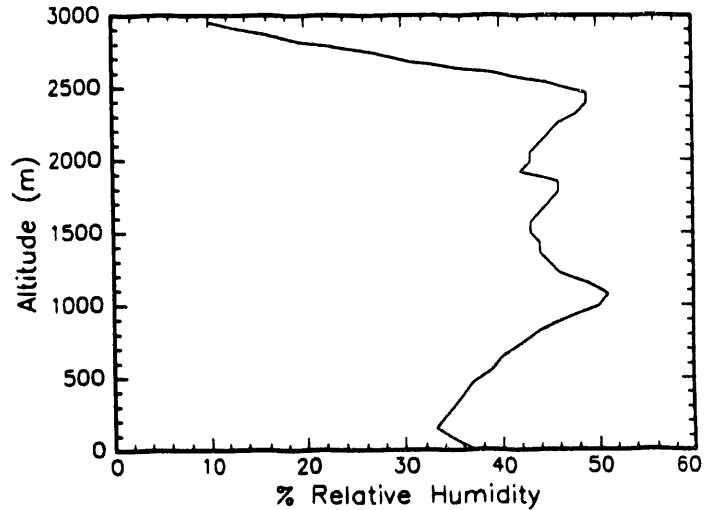
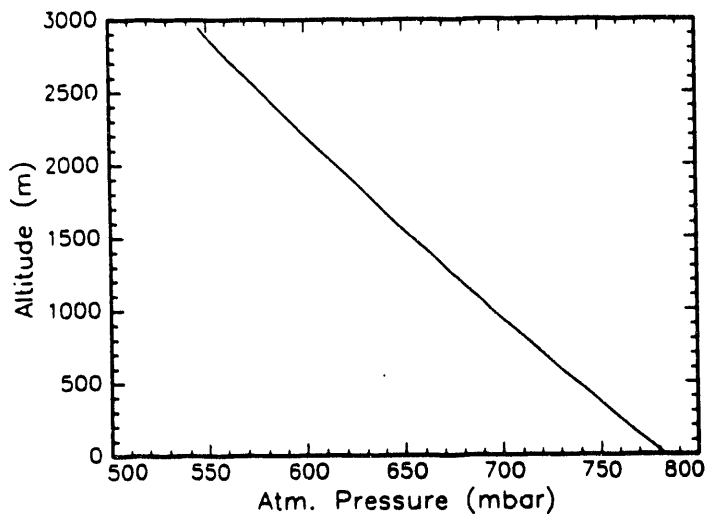


# Airport Rawinsonde of February 17, 1991

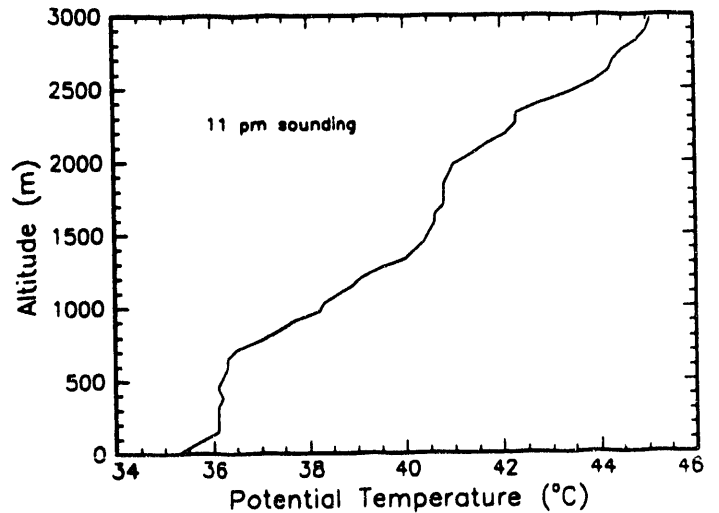
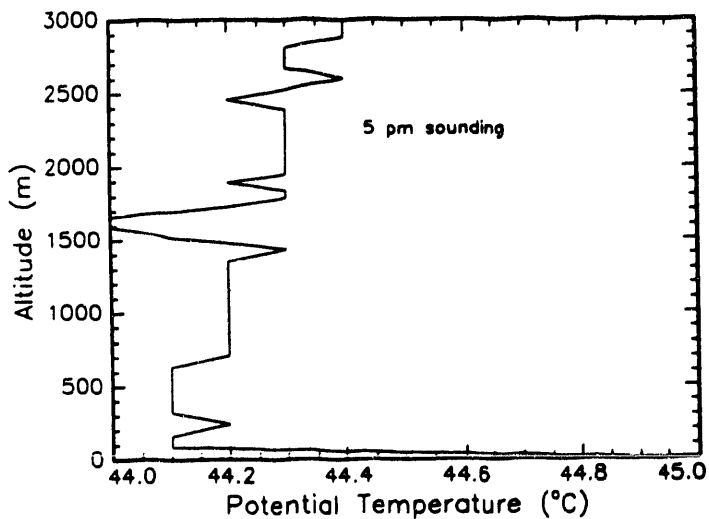
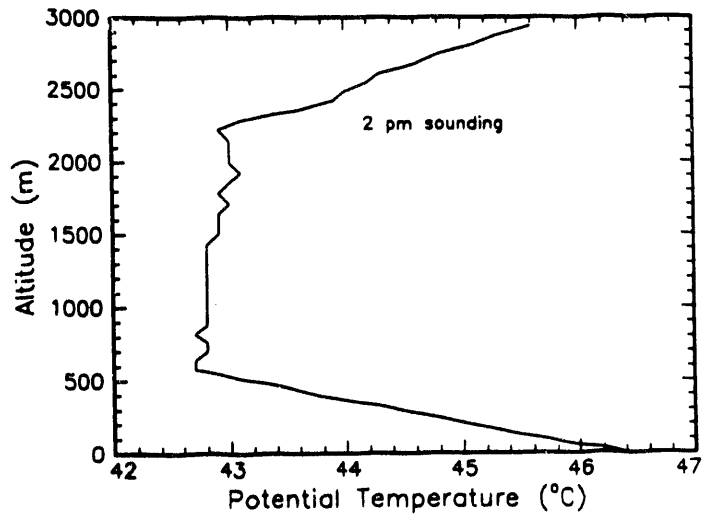
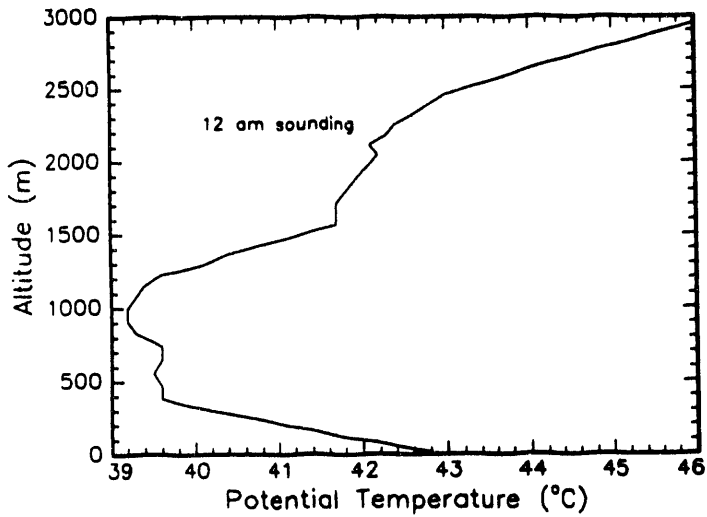
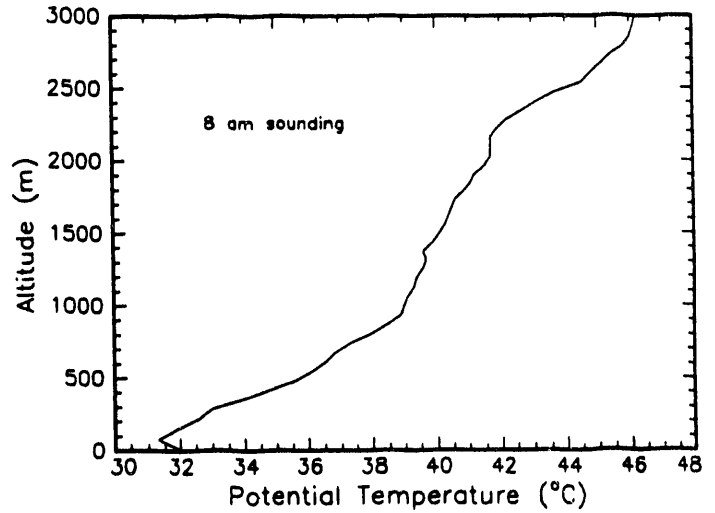
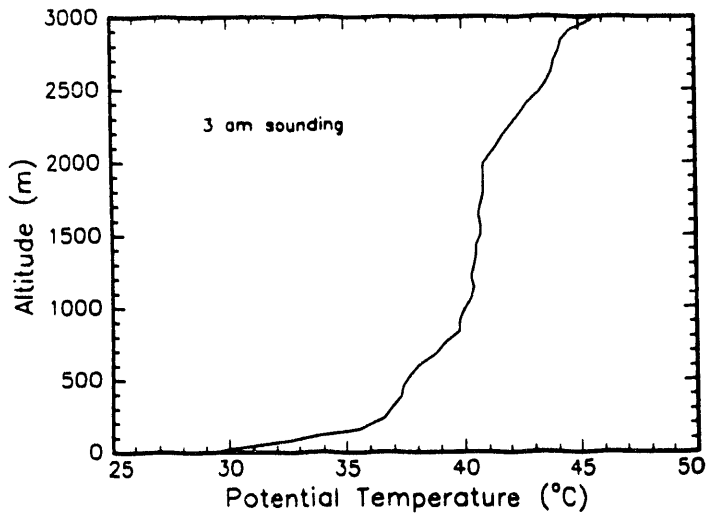


# Airport Rawinsonde Sounding February 22, 1991

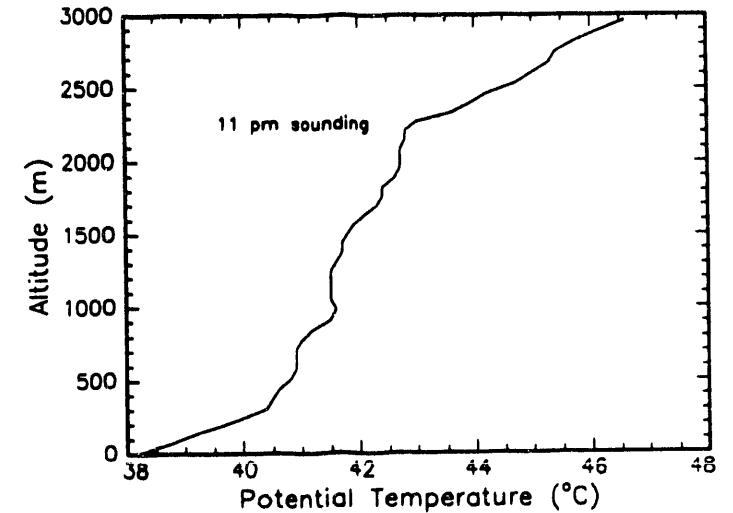
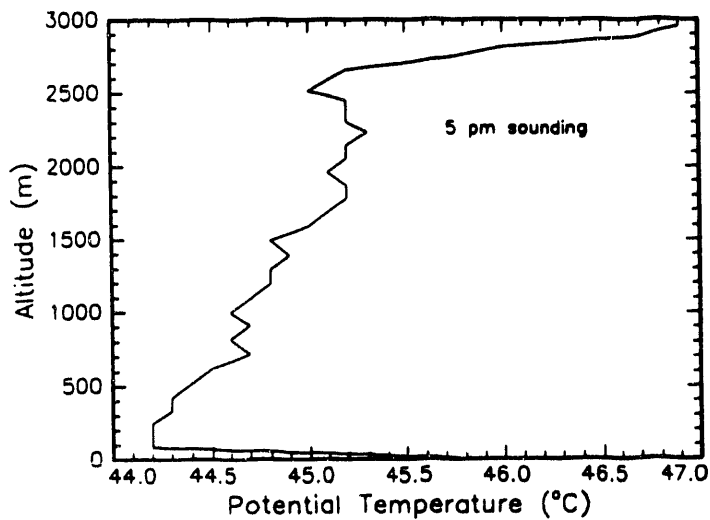
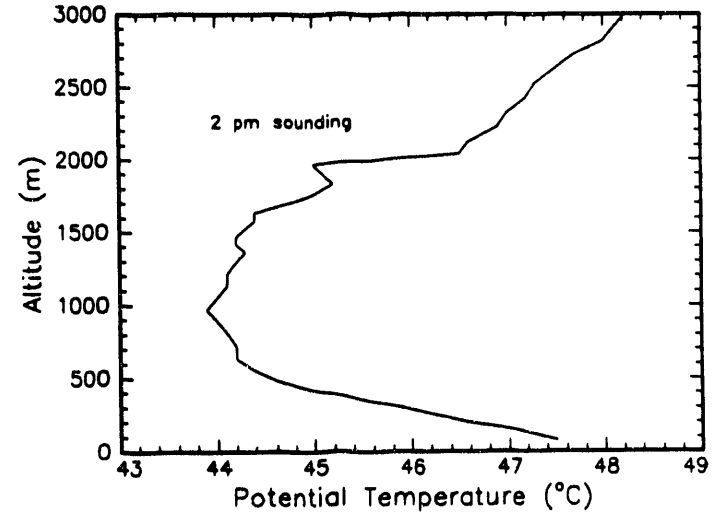
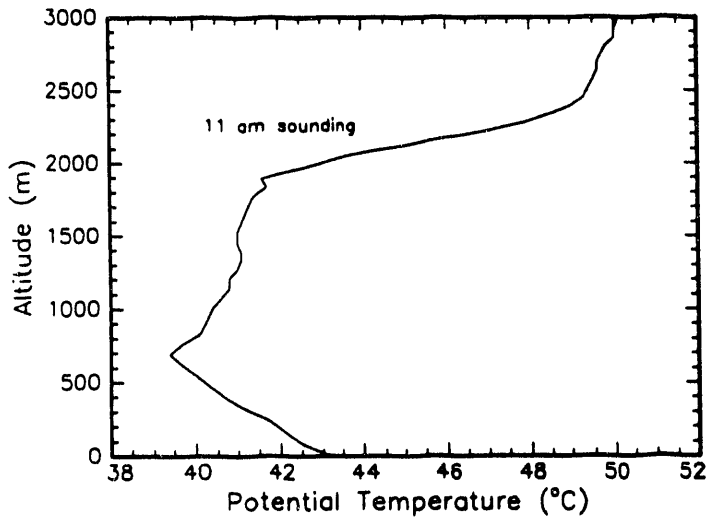
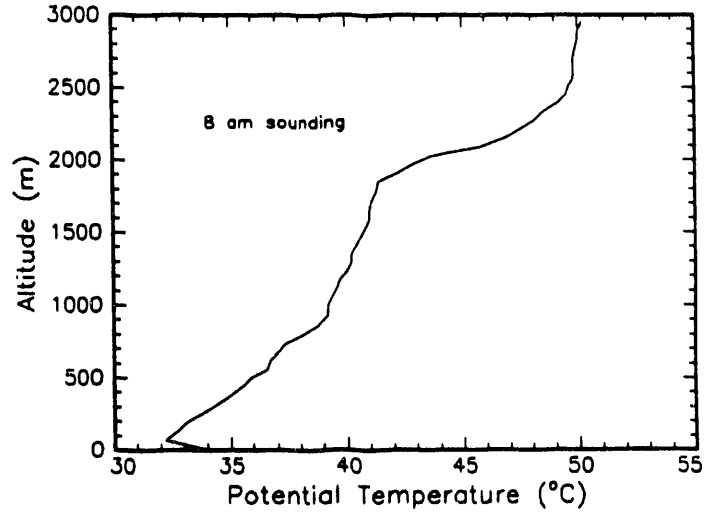
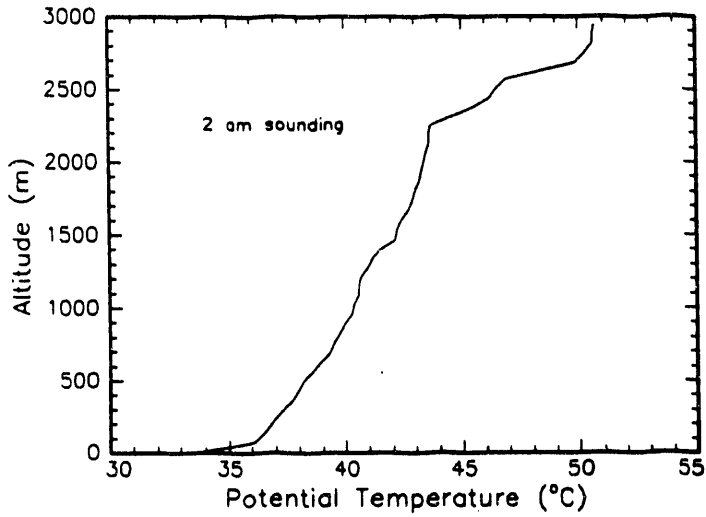
12 pm



# Airport Rawinsonde of February 22, 1991



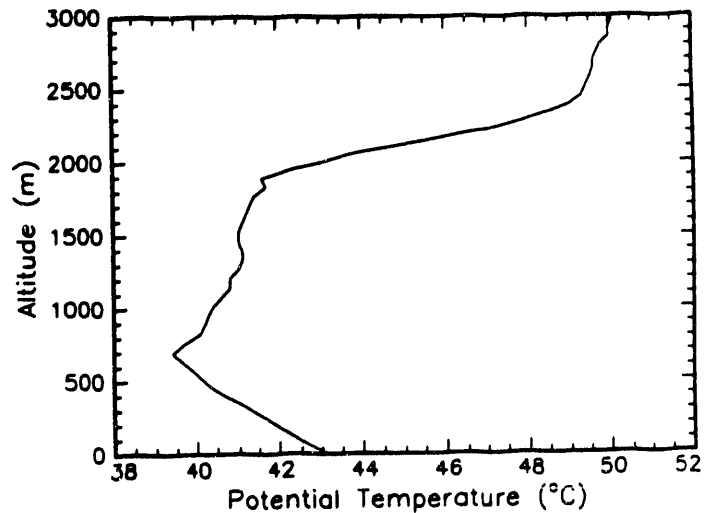
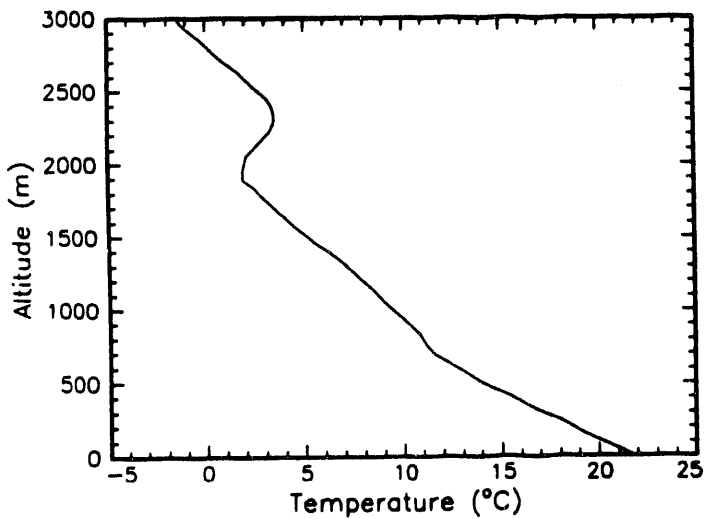
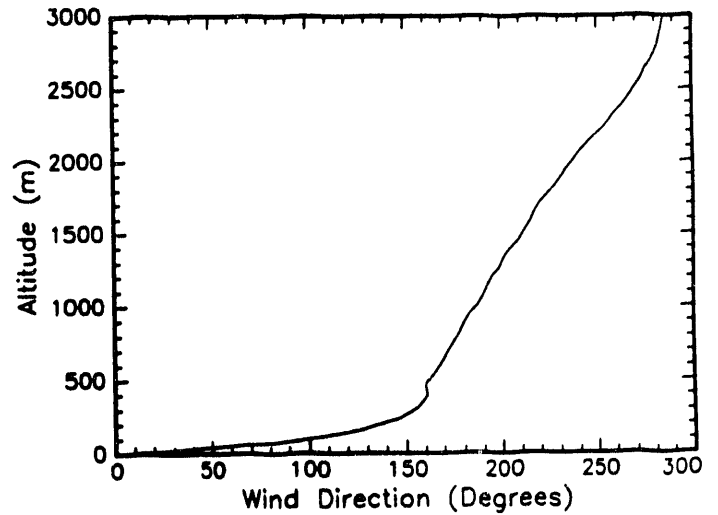
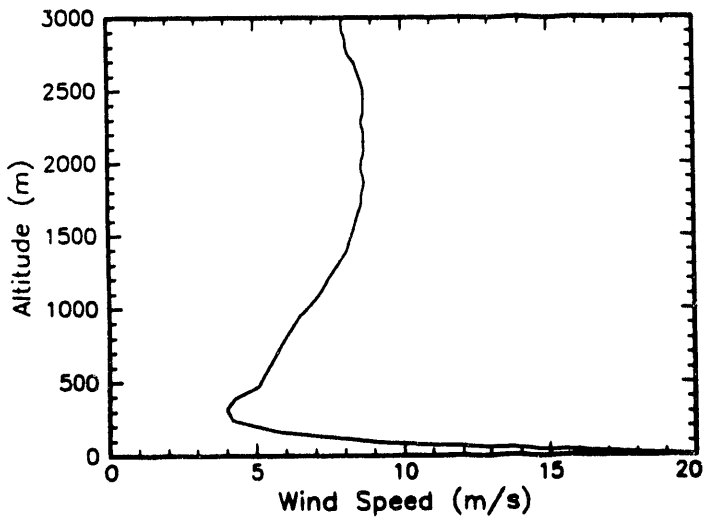
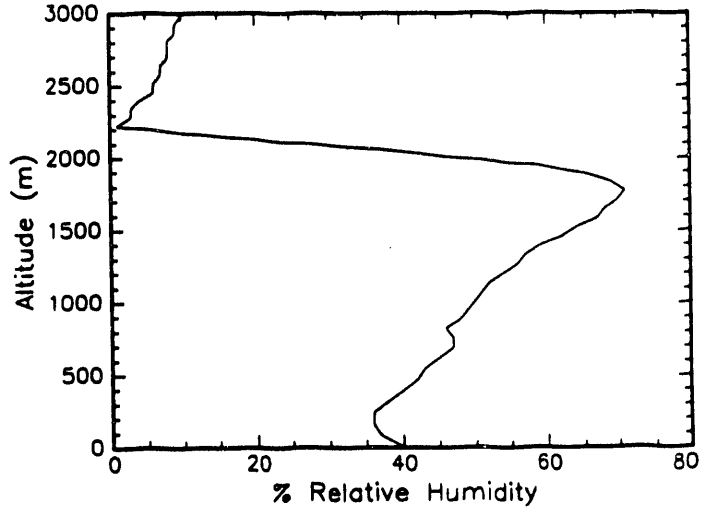
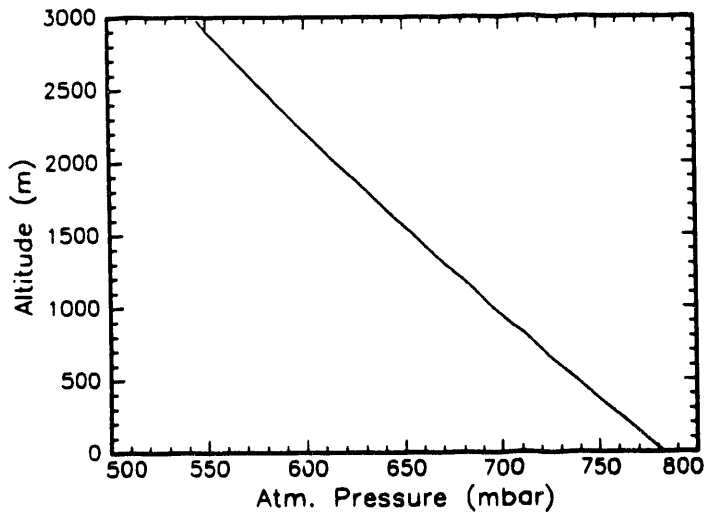
# Airport Rawinsonde of February 26, 1991





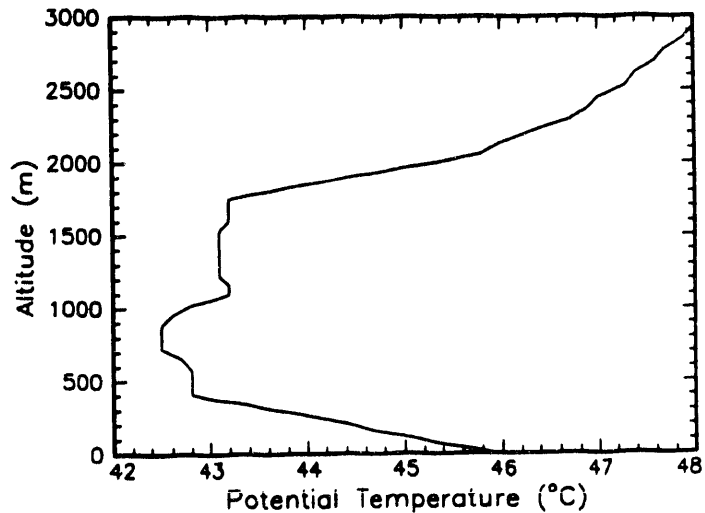
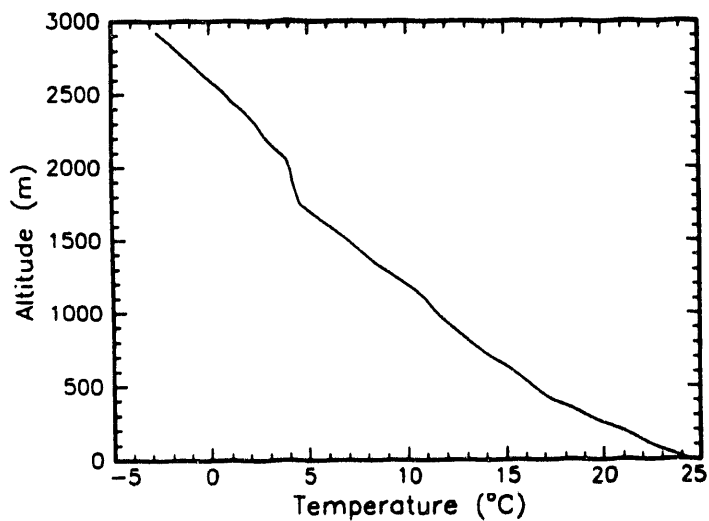
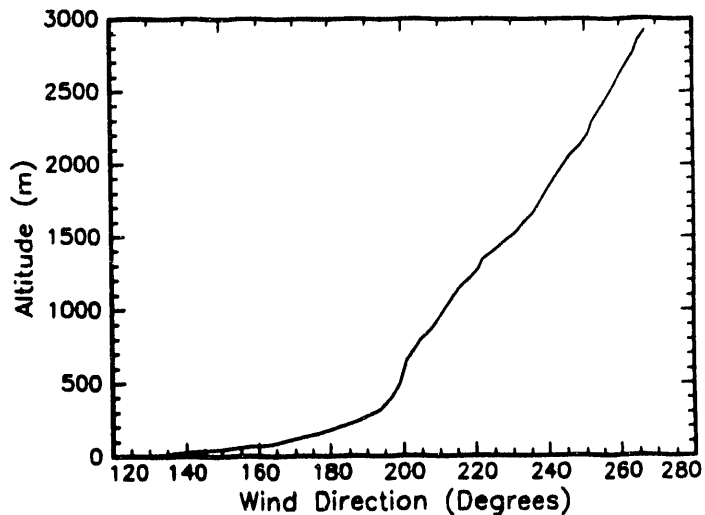
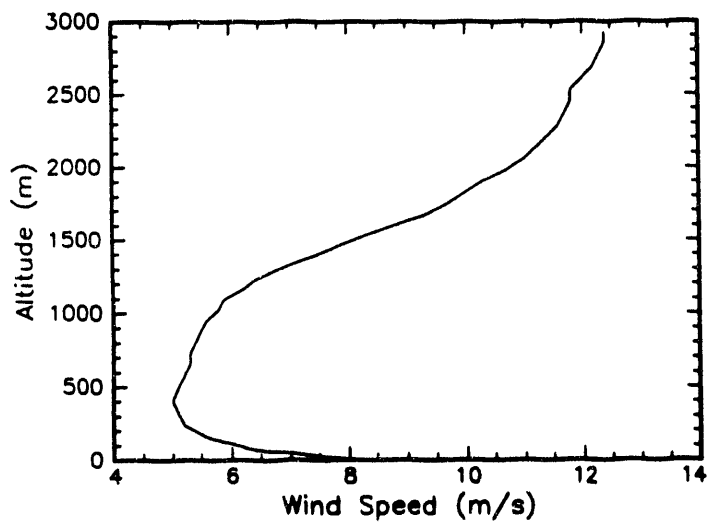
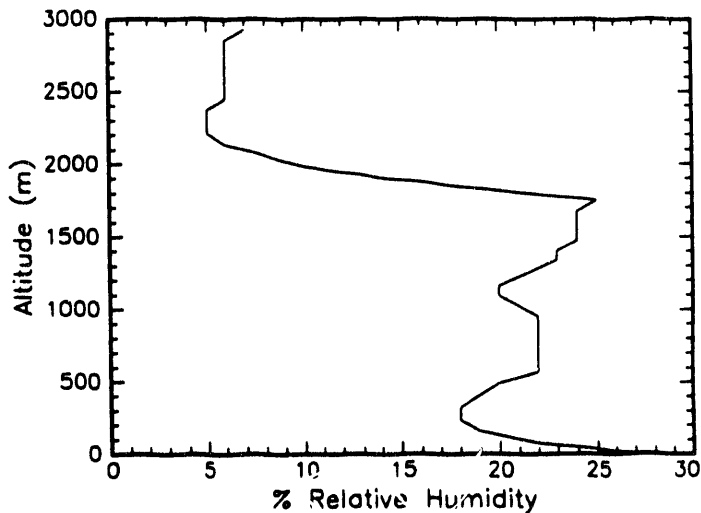
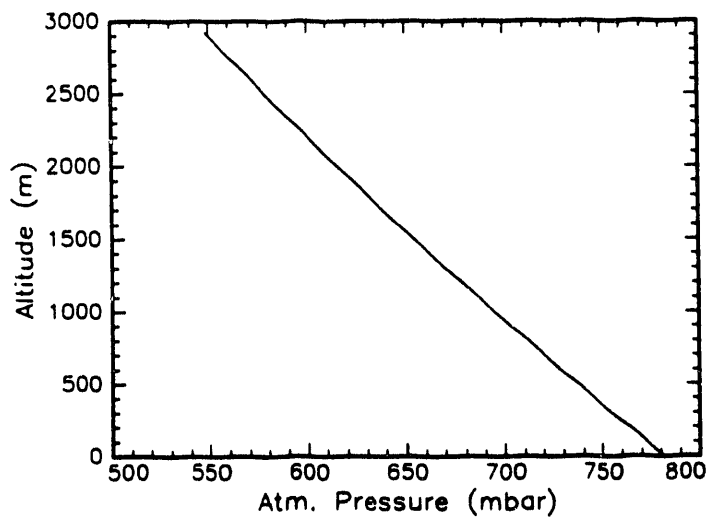
# Airport Rawinsonde Sounding February 26, 1991

11 am

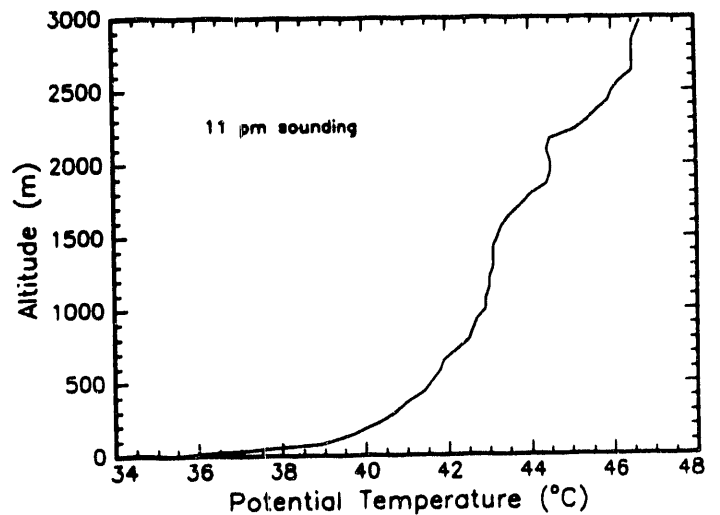
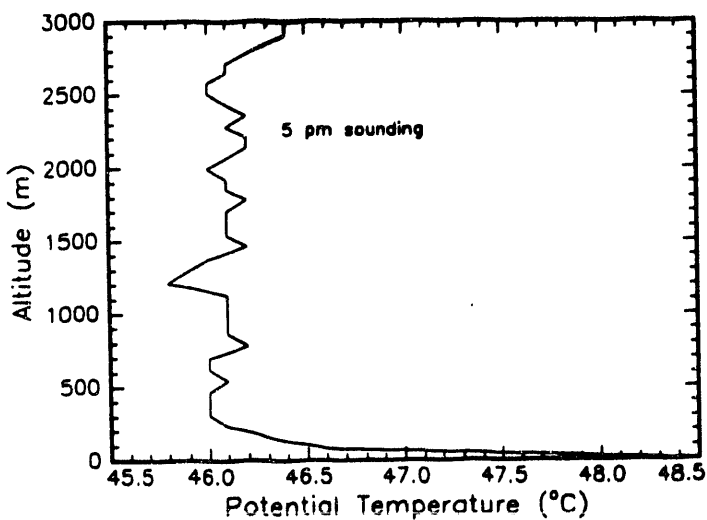
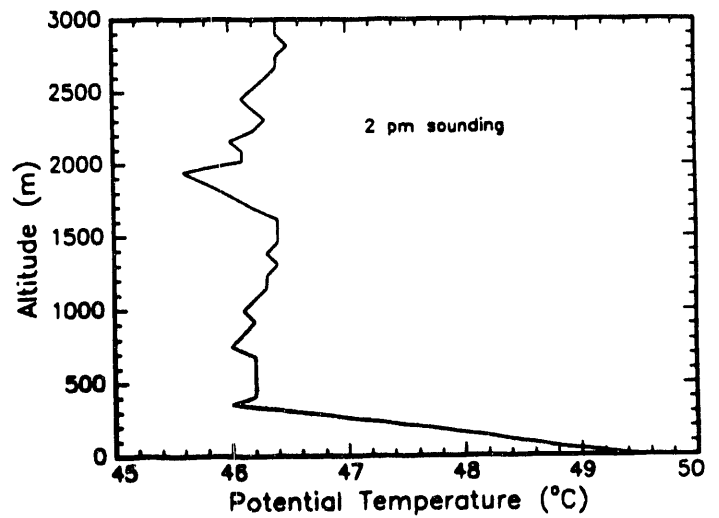
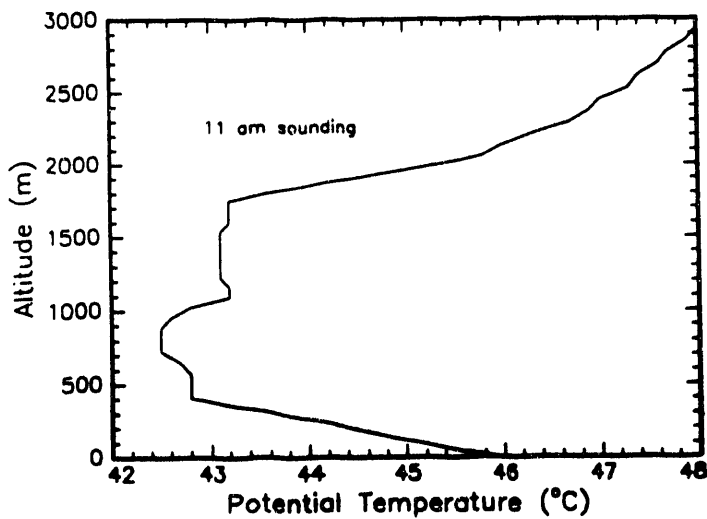
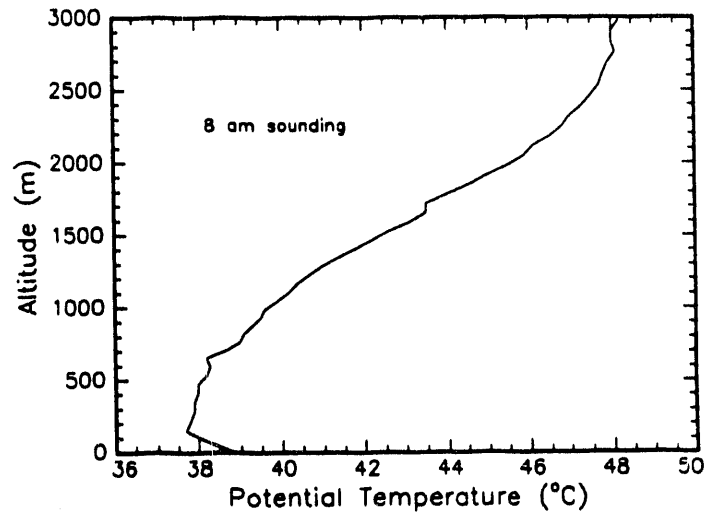
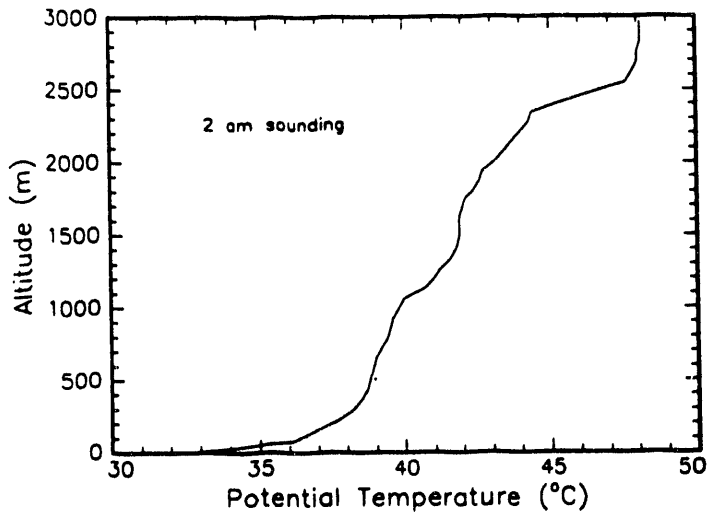


# Airport Rawinsonde Sounding February 27, 1991

11 am

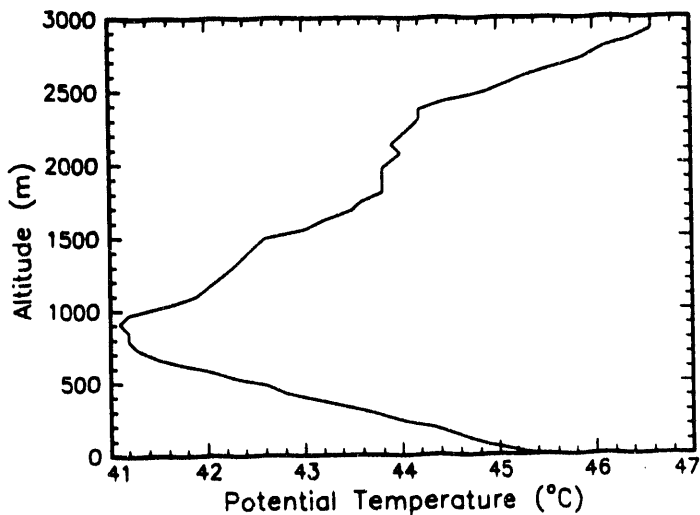
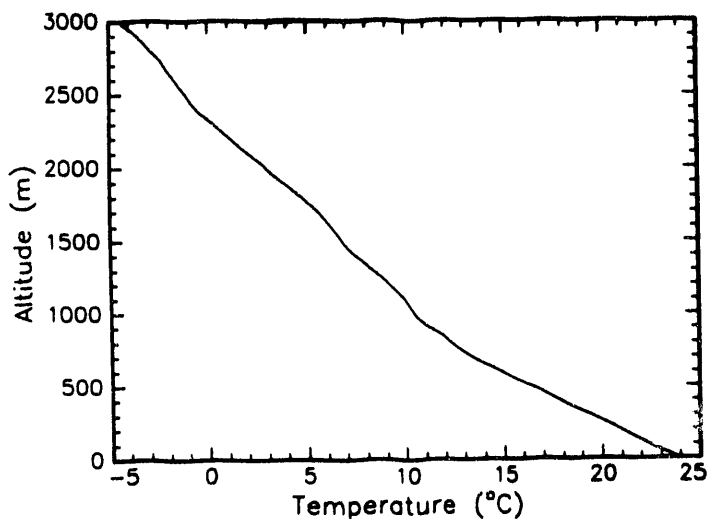
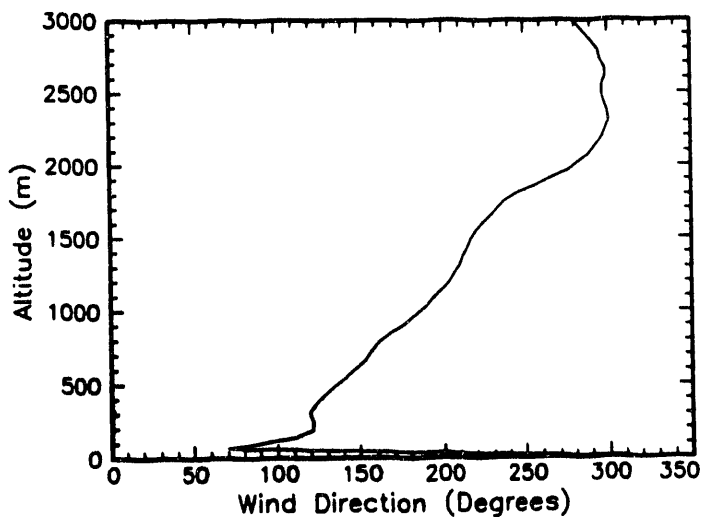
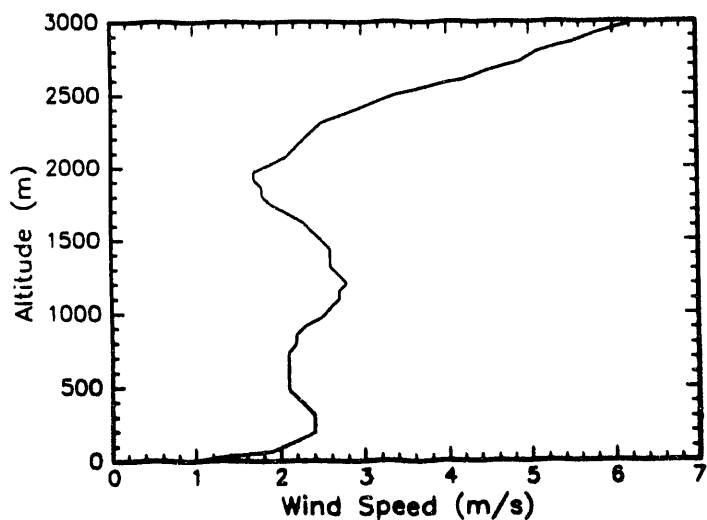
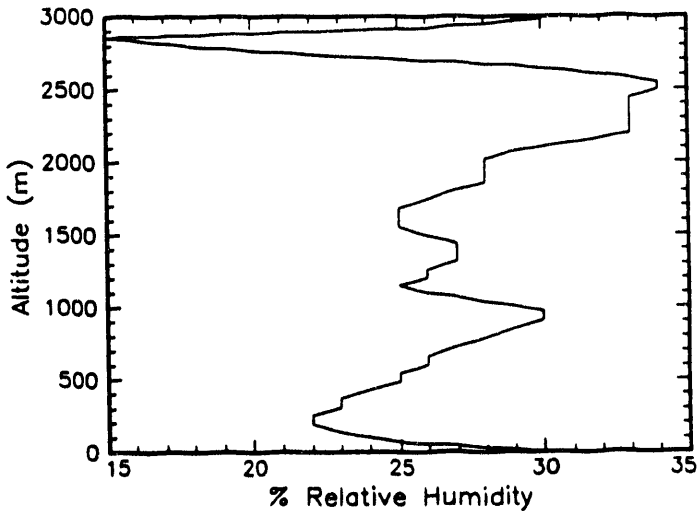
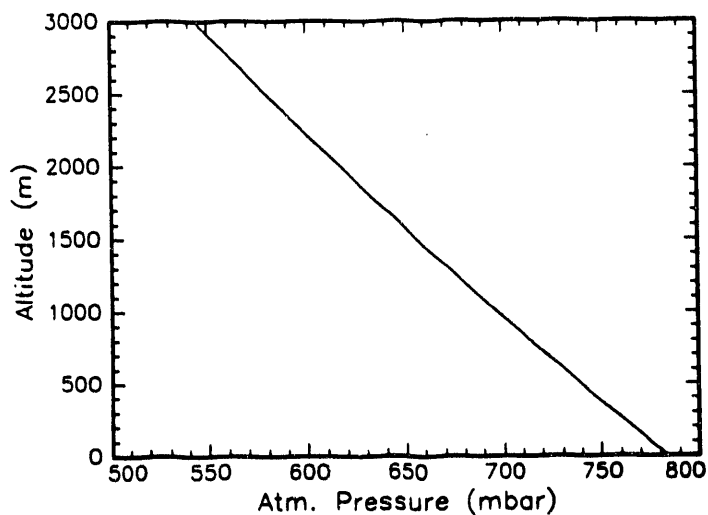


# Airport Rawinsonde of February 27, 1991

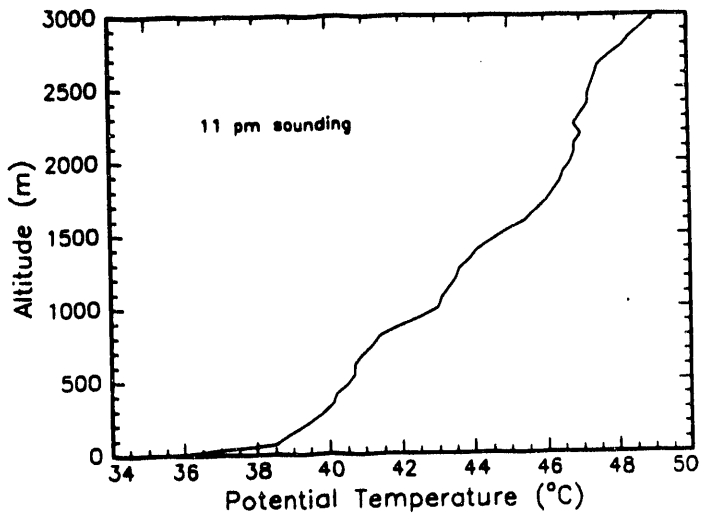
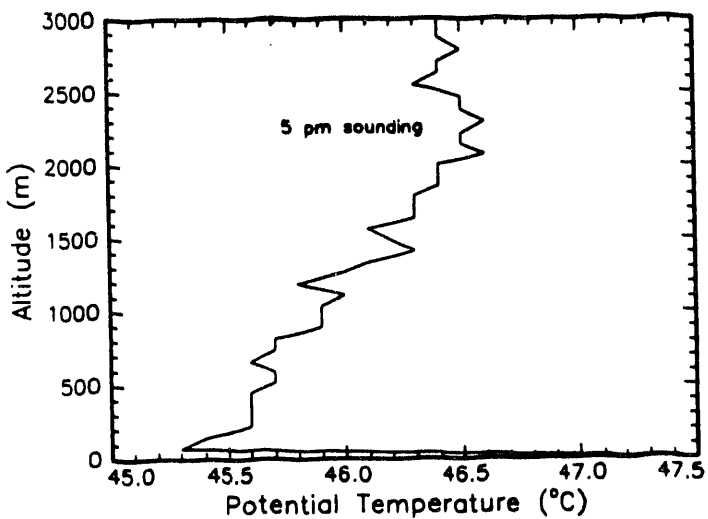
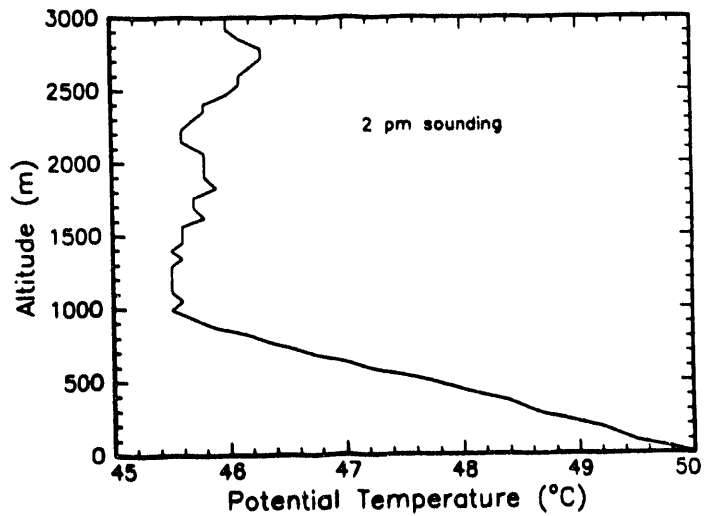
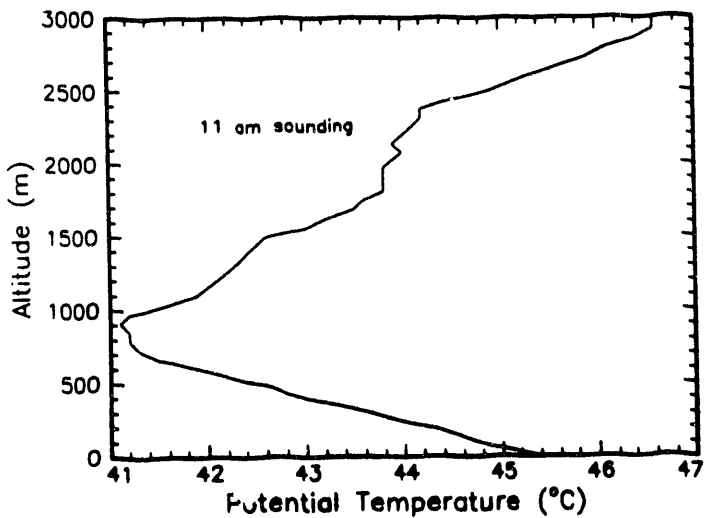
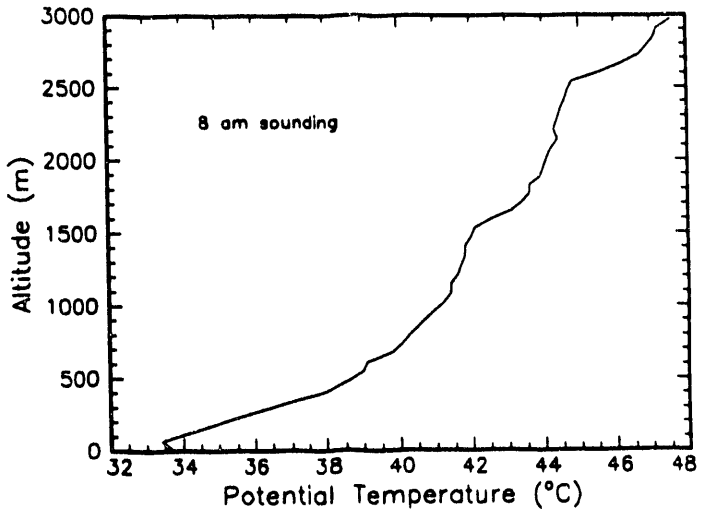
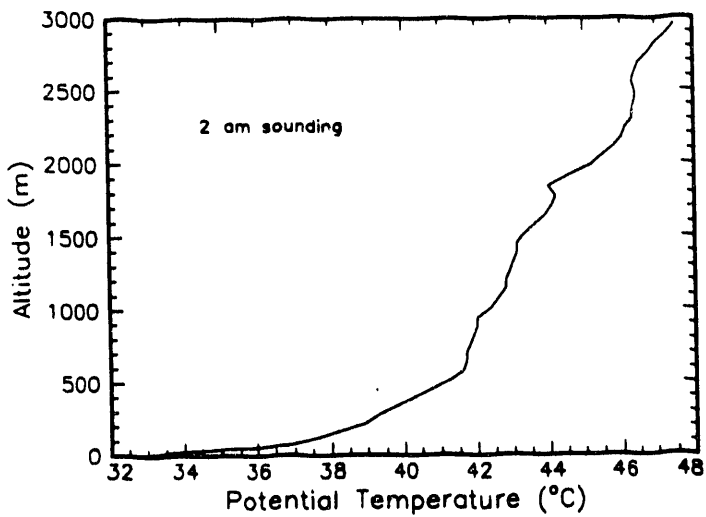


# Airport Rawinsonde Sounding February 28, 1991

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# Airport Rawinsonde of February 28, 1991



**END**

**DATE  
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**10 / 13 / 93**

