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TOKAMAK FUSION TEST REACTOR (TFTR) NEUTRAL
BEAM LINE VACUUM CHAMBER COVER
STRUCTURAL ANALYSIS

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**TOKAMAK FUSION TEST REACTOR (TFTR) NEUTRAL BEAM LINE
VACUUM CHAMBER COVER STRUCTURAL ANALYSIS**

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ABSTRACT

The Tokamak Fusion Test Reactor (TFTR) vacuum chamber cover is sealed by O-rings without the aid of mechanical fasteners. Under vacuum loading and component weights, the edges lifted no more than 0.005 in. (by a SAP4 computer code analysis). This report explains the model used for this investigation and, in addition, shows the maximum deflection expected at the center of the cover is less than 0.047 in. Also, no stresses are expected to exceed 13,700 psi.

INTRODUCTION

Most components of the neutral beam lines of the Tokamak Fusion Test Reactor (TFTR) are enclosed in a large, right-parallel-piped vacuum chamber. The function and rationale for the unorthodox design of this structure are explained in the referenced publication.*

*L. C. Pittenger, et al., "Neutral Beam Injection System for the Tokamak Fusion Test Reactor," Proceedings of the 7th Symposium on Engineering Problems in Fusion Research, Oct. 1977 Conference, p. 555.

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One unusual feature of this chamber is a cover that sits on seals without being mechanically fastened to the lower section of the chamber. Under pressure and other structural loads, the cover tends to lift around the edges. While the seals are designed to tolerate some lift around the edges, we started this investigation to more accurately evaluate seal integrity for several loading conditions. Useful by-products of the analysis are the stresses and bending moments in the structural members.

TOP COVER DESCRIPTION

As shown in Fig. 1, the cover is a reinforced flat plate made of AISI 300 series stainless steel with two large access ports and several stiffeners. For convenience, we affixed a set of coordinate axes with the origin at a point lying at half the width of the panel, the left end of the panel, and in the plane of the bottom panel face. The plate thickness was originally planned to be 0.75 in. but has been changed to 2 in. The access ports are 0.75-in.-thick plate with 2-in.-thick covers. The intersections of the access ports and bottom plate are reinforced by 2.5-in.-thick stiffening rings.

Other reinforcements consist of the fabricated box beam around the perimeter and fabricated T-beams traversing the plate. The box beam, which has cross-sectional dimensions of 9 in. wide by 12 in. high, is built from 0.75-in.-thick plate. The two transverse T-beams are 12 in. high and have 0.75-in. webs and 1.5-in. by 6-in. flanges. The short longitudinal T-beams are also 12 in. high with 0.75-in. webs and 0.75-in. by 6-in. flanges.

Besides supporting the pressure load and its own gravity load, the top panel supports several other components. A calorimeter, weighing 8000 lbf, is suspended from the center of the cover of the smaller access port. The

ion dump, weighing 1076 lbf, is suspended from the large access port cover in two places. A liquid helium Dewar flask sits on the longitudinal T-beams and weighs 3000 lbf. A cryopanel, weighing approximately 6120 lbf, hangs from the top panel along each side of the chamber. Each panel is suspended from four points with the line of suspension about 40 in. from the centerline of the top panel.

MODELING ASSUMPTIONS AND COMPUTATIONAL PROCEDURE

THE MESH

We used the finite element method to approximate the deflections and rotations in a static, linear elastic analysis. Symmetry about the y-z plane allows us to model only half the structure by impressing the proper boundary conditions on nodes in the plane of symmetry. We modeled the structure as 417 thin plate elements joined at 424 nodal points, as shown in Fig. 2. This geometry and associated boundary conditions are input to the SAP4 computer code, which computes the approximate deflections and rotations at each nodal point. The resulting matrix system involves 2441 degrees of freedom.

Due to the size of the grid and limitations on available software, the mesh was generated in several sections and merged by a text editing program. This disjoint generation sequence yielded element orderings resulting in a half-bandwidth of 1848. The size of this matrix system required more contiguous disk storage space than is usually available. Preprocessing of the element connectivity data by the SAPMIN computer code reduced the half-bandwidth to 152. This results in much more efficient

computations due to fewer disk information transfers required for matrix formulation and equation elimination.

BOUNDARY CONDITIONS AND LOAD CASES

Symmetry about a plane allows us to reduce the problem size by half with special consideration for the boundary conditions on nodes in the plane of symmetry. Consider a plane bisecting a beam perpendicular to the longitudinal axis of the beam. Assume the beam is simply supported and loaded symmetrically about the bisecting plane. For small displacements, points in this plane have no axial displacement, and the plane undergoes no rotation. Analogous boundary conditions are impressed on this structural problem. For all load cases considered later, nodes in the plane of symmetry are constrained to zero displacement perpendicular to the plane, and no rotation of the plane is permitted.

The first computations in the analysis yield a solution for the case of only the component and gravity loads discussed earlier without the pressure load. This simulates no-vacuum conditions and determines seal integrity at the beginning of chamber evacuation. The second computation simulates normal operating conditions with gravity loads and a pressure load of 16 lbf/in². This pressure load is excessive as a safety factor.

While we are interested in displacements and stresses throughout the panel, behavior around the outer edge is of central importance. The contact problem between the top panel and the sides of the chamber is nonlinear due to constraint in one direction (one surface contacts another) and no constraint in another (one surface loses contact with another). We attack the problem with an iterative procedure similar to a computational procedure employed in contact problems. Springs are used to constrain all

displacements normal to the contact surface. This problem is solved, and the extension of each spring is considered. If a spring is compressed, indicating the surfaces are in contact, the spring is not removed. However, if a spring is extended, tending to pull two uncontacted surfaces together, the spring is removed, and the computation is repeated. This iterative process is continued until all remaining springs are compressed, and inclusion of any other springs would result in an extended spring. Then the contact surface is defined, and displacements of uncontacted nodes may be used to evaluate seal integrity.

SPRING STIFFNESSES

A satisfactory model for this problem might include the cover and portions of the sides and ends of the chamber that contact the top. However, this problem would be prohibitively large, so we attempt to model the effect of the remainder of the chamber on the cover through the springs around the panel's perimeter.

The problem arises as to what value of spring rate will adequately reflect the effect of the sides on the top. We approach this problem by approximating a spring rate based on uniaxial compression of the sides by the top. In the first series of computations, we set the spring rates to a much higher value to establish an upper bound on the edge displacements. Later, we solve the problem with the derived spring rates. We compare the results of these computations in evaluating seal integrity.

Considering a uniaxial tension test, we see that

$$F = \frac{AE}{L} \delta ,$$

where

F - Force in the member.

A - Cross-sectional area of the member.

E - Young's Modulus.

L - Length of the member.

δ - Change in length L due to load F.

Then $K = AE/L$ is the spring constant for the member. From the design drawings, we choose the following figures to describe the side and end panels:

	<u>Width</u> <u>(in.)</u>	<u>Length</u> <u>(in.)</u>	<u>Area</u> <u>(in.²)</u>	<u>K</u> <u>(lb/in.)</u>
Side panels:	198.0	154.25	234.9 in.*	4.1×10^7
End panels:	118.0	164.0	88.6 in.	1.5×10^7

*Includes area of T-beams.

For the upper bound on spring rates we choose 10^{10} lb/in.

It is clear that better models may be developed for the spring rates along the edges. For example, the spring rates near a corner should be much larger than those in the midsection. However, we choose to base our recommendations on the two rates given here, as the original question concerns seal integrity and not precise edge deflections.

COMPUTATIONAL RESULTS

For this first series of computations, we attempt to establish upper bounds on edge deflections by assuming boundary spring rates of 10^{10} lb/in. Results of interest may be best expressed by referring to a

plot of the finite element mesh of the bottom plate only. This plot, with some selected nodal point numbers, is shown in Fig. 3. We consider first the case of structural loads but no pressure load.

After several spring removal iterations, the contact surface is defined by nodes 1-3, 38-165, and 190-192. The maximum deflection around the perimeter of the top panel is 1.44 mils at node 7. These results indicate that the seal will be intact when no pressure load exists.

We next consider the case of structural loads plus the pressure load to simulate fully evacuated conditions. The resulting contact surface is defined by nodes 1-4, 33-157, and 190-193. The maximum vertical edge deflection is 5.4 mils at node 197. Again the seal should remain intact. We also find that the maximum vertical deflection of the panel is -48.1 mils at node 44. Maximum principal stresses throughout the structure are less than 13,500 psi.

Considering the conservative nature of the spring rate assumption for the preceding calculations and the indications that the seal will be effective, we omit computations for the 10^7 lbf/in. spring rate.

FIGURE CAPTIONS

- FIG. 1. Perspective view of the chamber top panel.
- FIG. 2. Three-dimensional perspective computer plots of the finite
 element mesh for the top panel.
- FIG. 3. Relevant nodal point numbers on the lower surface of the top
 panel.

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Figure 1.

Figure 2.

Figure 3.