REV LTR/CHG NO NUMBER **Rookwell International** SUPPORTING DOCUMENT N266ER000-001 SEE SUMMARY OF CHG DOCUMENT TYPE Engineering Design Report PROGRAM TITLE KEY NOUNS Intermediate-Size Inducer Pump (ISIP) Pump, Inducer, Design DOCUMENT TITLE ORIGINAL ISSUE DATE June 15. 1979 **ISIP Design Report** GO NO S/A NO. PAGE 1 OF 765 TOTAL PAGES 09280 23000 PREPARED BY/DATE DEPT MALL ADDR REL, DATE SECURITY CLASSIFICATION T. J. Boardman 731 LB88 (CHECK ONE BOX ONLY) (CHECK ONE BOX ONLY) IR&D PROGRAM? YES NO 🛛 IF YES, ENTER TPA NO. ERDA DOD BESTRICTED П X Ð DATA UNCL APPROVALS DATE DEFENSE CONF  $\Box$ INFO G. J. Hallinan SECRET AUTHORIZED DATE R. V. Anderson RA CLASSIFIER DISTRIBUTION ABSTRACT MAIL NAME ¥ A DDR This report summarizes the mechanical, structural, and hydrodynamic design of the Intermediate-Size Inducer \* R. V. Anderson (6) LB17 Pump (ISIP). The design was performed under Atomics T. J. Boardman (2) LB08 International's DOE Base Technology Program by the -\* H. Marson LB24 Atomics International and Rocketdyne Divisions of G. W. Mevers LA10 Rockwell International. The pump was designed to C. Dunn LB08 utilize the FFTF prototype pump frame as a test vehicle a \*\* R. Hoshide **JB05** to test the -inducer, impeller, and diffuser plus \* J. E. Wolf 055/AB24 necessary adapter hardware under simulated Large-\*\* E. D. Jackson 055/AC51 Scale Liquid Metal Fast Breeder Reactor service D. E. Davis \*\*! 055/AB48 conditions. The report describes the design-require-G. J. Hallinan \*\* LB39 ments including the purpose and objectives, and discusses those design efforts and considerations made to meet the requirements. Included in the report are appendices showing calculative methods and results. Also included are overall assembly and layout drawings plus some details used as illustrations for discussion of the design results and the results of water tests performed on a model of the inducer. AT03-763F-76026 RESERVED FOR PROPRIETARY/LEGAL NOTICES THIS REPORT MAY NOT BE PUBLISHED WITHOUT THE APPROVAL OF THE PATENT BRANCH, DOE This report was prepared as an account of work sponsored by the United 731-D.263 States Government Neither the U S Government, nor any of its employees nor any of its contractors, subcontractors, or their employees, makes any \*\* Complete document warranty, express or implied, or assumes any legal liability or responwithout Appendices. sibility for the accuracy, completeness or usefulness of any information, \* COMPLETE DOCUMENT apparatus, product or process disclosed, or represents that its use would NO ASTERISK, TITLE PAGE/SUMMARY not infringe privately owned rights. OF CHANGE PAGE ONLY FORM 734-C REV. 11 75 -

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#### 1.0 INTRODUCTION

#### 1.1 PURPOSE

The Intermediate Size Inducer Pump (ISIP) project was initiated to demonstrate, by test, the applicability of axial flow inducers to centrifugal pumps for primary coolant service in large sodium-cooled reactors. This project is the second step in the DOE inducer pump development program which was started at Atomics International with a smaller, "subscale" inducer pump which was designed, fabricated, and tested in water, and is now undergoing endurance tests in sodium. <sup>(1)</sup> Achievement of program objectives is based on utilizing the combined engineering capabilities of Atomics International (AI), a division of Energy Systems Group (ESG), where there has been considerable sodium, reactor, and ASME Code design experience, and of the Rocketdyne Division which has developed the hydrodynamic technology needed to produce inducers that can operate at low suction pressure (high suction specific speed) while meeting Liquid Metal Fast Breeder Reactor (LMFBR) life requirements.

#### 1.2 OBJECTIVES

The principal project objective, as stated in the Task Proposal/ Agreement,<sup>(2)</sup> is the demonstration of the inducer technology through the design of an intermediate-size inducer, impeller, and diffuser system; a system which can be sodium-tested using the Fast Flux Test Facility (FFTF) Prototype Primary Pump as a test vehicle. The design task, therefore, includes hydrodynamic and structural design of the impeller, inducer, and diffuser, plus necessary adapter hardware, to operate inside the existing FFTF Prototype Primary Pump in lieu of the present FFTF Prototype Pump impeller. Because the prototype pump is designated as a plant spare for FFTF, it was necessary that the ISIP design not include any requirements for change or modification of existing hardware that might jeopardize the "spare" status. This



required that the ISIP design be physically and functionally compatible with existing configurations and operating requirements of the prototype pump.

#### 1.3 TECHNICAL BACKGROUND

The advantage of using inducers to permit centrifugal pump operation at lower suction pressures was initially used at Rockwell International, by the Rocketdyne Division, in the development of fuel and oxidizer pumps for rocket engines. In this application, the hydrodynamic goals for inducers were the same as for reactor coolant pumps; i.e., reduction of the suction pressure requirements. However, the design problems were significantly different than those faced in designing a pump for reactor coolant service. For rocket engine applications it was necessary to use extremely high speeds (which result in high centrifugal stresses), in order to reduce the size and weight of the pump to proportions suitable for flight service. Design life requirements were short, measured in minutes or hours, as opposed to life requirements, measured in years for reactor coolant service. Also, for rocket engines, the operating temperatures were very low, in the cryogenic range, and thermal cycles were few, whereas sodium-cooled reactors require temperatures in the order of 1000<sup>0</sup>F and equipment must be capable of withstanding a significant number of thermal cycles over the long (20-40 yr) life.

In the intervening period, between developing inducer pumps for rocket engine application and the present development of similar pumps for reactor coolant service, the Rocketdyne Division developed a commercial line of inducer pumps for use in water jet propulsion systems of hydrofoil craft. The design of those pumps did not have to consider the temperature extremes of cryogenic or reactor service, but had to provide extended life (5,000 to 20,000 hr) free from disabling damage due to



cavitation. In addition to meeting the long life requirements, the physical size of the inducers had to be increased from the small, high-speed units used for rocket engines to sizes slightly larger than that being used for ISIP.

The most recent development in sodium inducer pumps is the Subscale Inducer Pump, a small pump specifically designed for operation with low suction pressures (high suction specific speed) in high temperature sodium. This pump was originally built and tested in water and in sodium under DOE contract. It was later modified and further tested in sodium under contract from ANL. <sup>(1)</sup> As of this date, the Subscale Inducer Pump has successfully completed a 2,000 hr design point endurance test in sodium at  $950^{\circ}$ F, with a suction pressure margin of 200% above the conventionally defined cavitation point (3% reduction in head due to cavitation). The inducer and impeller showed no signs of cavitation as a result of this test.



#### 2.0 REQUIREMENTS

2.1 GENERAL

Initial design requirements for the Intermediate-Size Inducer Pump (ISIP) were based principally on those requirements originally used for the Fast Flux Test Facility (FFTF) Prototype Primary Pump, and were contained in pump specification HWS-1551. (3) Since the ISIP design effort covered only those hydrodynamic elements and adapters used to replace the prototype pump impeller, much of the information given in HWS-1551 was not pertinent to this project. It was assumed that the FFTF Prototype Pump met the requirements of HWS-1551 and that as long as the operating conditions for those parts to be used in the ISIP assembly were not changed, or were not outside of the range of specification requirements, no further analyses of prototype pump parts were needed. Also, because the ISIP was to be used only for testing (as opposed to reactor service), some of the requirements, such as design life and thermal transients, were rewritten in terms of test requirements. These requirements were planned to be identical to those used for Phase B sodium testing of the FFTF Prototype Pump by Energy Technology Engineering Center (ETEC) (then Liquid Metal Engineering Center (LMEC)) in the Sodium Pump Test Facility (SPTF).

#### 2.2 SPECIFICATIONS

In order to permit early initiation of the cooperative design effort to be performed by Atomics International and Rocketdyne, a set of technical requirements<sup>(4)</sup> based on HWS-1551 was developed. The set covered the basic hydrodynamic and structural design requirements, including expected limiting values (upper and lower limits) for those parameters which could not be quantified precisely at the time. Subsequently, a more formal and inclusive design specification was written



(Appendix B). This specification was revised once as a result of design review comments.

#### 2.3 HYDRODYNAMIC DESIGN REQUIREMENTS

Hydrodynamic design requirements, with the exception of suction performance, are basically the same as those used in HWS-1551 for the FFTF Prototype Pump. The principal parameters are shown in Table I, which was extracted from the design specification. Added to the original FFTF Prototype Pump requirements was a requirement for operation at design speed, flow, and temperature, with a net positive suction head (NPSH) of 12.8 ft "without cavitation" as defined in the specification. For both the ISIP and the FFTF Prototype Pump "without cavitation" is defined as operating under this condition; the total head across the pump is not reduced by more than 3%, due to reduced suction pressure from its noncavitating (adequate suction pressure) value. The NPSH at this 3% head reduction condition is designated as the required net positive suction head (NPSHR).

The fluid properties on which the hydrodynamic design is based are those contained in ANL  $7323^{(12)}$  which is the same source document as used for design of the FFTF Prototype Pump. Although later publications of sodium properties may have been available, it was felt that use of these properties, in the design and test evaluation of the ISIP, would provide more consistent comparison between performance characteristics of the ISIP and those of the FFTF Prototype Pump which was tested in the same loop.

#### 2.4 STRUCTURAL DESIGN REQUIREMENTS

The initial structural design requirements given in Reference 4 were established to provide a basis for design initiation. These criteria



.

TABLE I	
HYDRODYNAMIC DESIGN REQUIRE	MENTS
DESIGN POINT	
Flow	14,500 gpm
Head	500 ft
Speed	1,110 rpm
Required NPSH	12.8 ft (max.
MAXIMUM FLOW POINT	
(2-Loop Operation)	
Flow	18,000 gpm
Head	375 ft (min.
Speed	1,110 rpm
Cover Gas Pressure	36 ft Na (min.
Submergence	4 ft (min.
(Overdischarge centerline)	

covered steady state structural design only. The maximum primary membrane stress and the maximum primary membrane plus bending stress were limited to those values which had been previously calculated for the FFTF Prototype Pump impeller (7450 psi and 7730 psi, respectively). Since the ISIP impeller has a similar configuration, it was felt that having the initial design based on these previously successful values would allow a high probability of success in limiting the stresses during thermal transients to values obtained using Code Case N-47 (1592-10) as guidance. These criteria are given in Reference 3.

Unlike many design approaches which require design for specified thermal transients, requirements for structural design of the ISIP components were based on developing a structurally conservative steady state design. This design would have a high probability of meeting the transient requirements, then analyzing the design to determine which, if any, of the specified test thermal transients could not be met within the structural design criteria. The scope of analysis, <sup>(4)</sup> was based on limiting the structural analysis effort to elastic, and simplified inelastic, methods to make this determination.

#### 2.5 MECHANICAL DESIGN REQUIREMENTS

Using the FFTF Prototype Pump frame as a test vehicle dictated a number of physical and functional interface requirements. The requirements were to be included in the ISIP design specification in order to avoid the risk of damage to the pump frame. Other mechanical design requirements were based on developing the original concept arrangement, as depicted in the early proposal, into a fully detailed assembly which would be suitable for reactor coolant service.

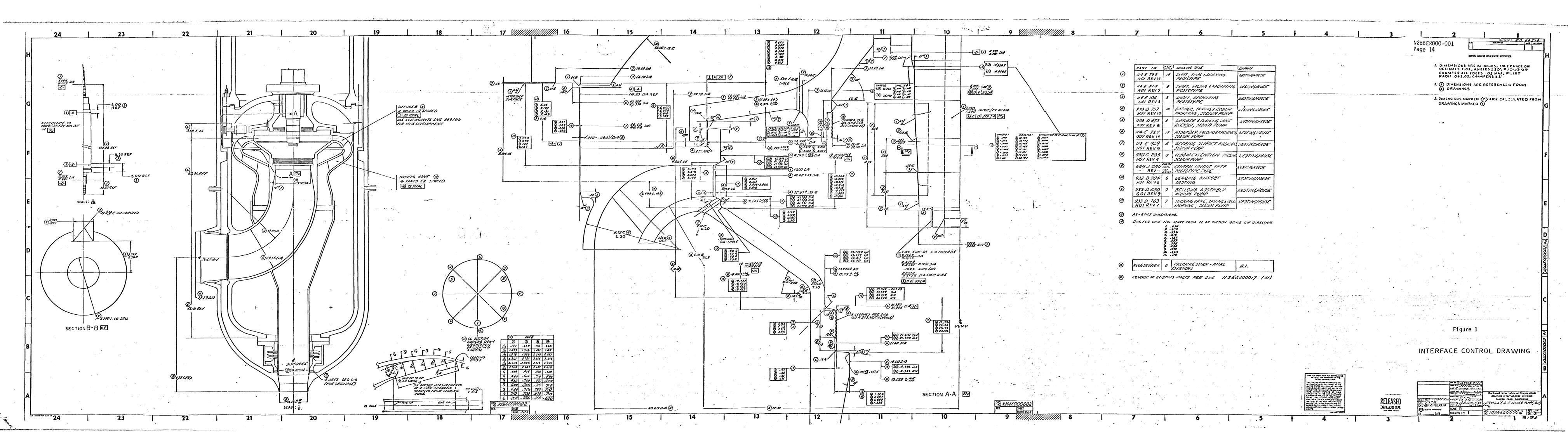
The following changes from the FFTF Prototype Pump design, in physical interface requirements, were implemented with HEDL concurrence. (5)

- Axial Clearance The prototype pump had 3/4 in. axial clearance above and below the impeller. The ISIP design specification requires 1/2 in. axial clearance above and below the impeller.
- b) Radial Clearance The prototype pump has .100 in. radial clearance at the lower (front) labyrinth seal. The ISIP design specification requires that the design provide .015 in. minimum radial clearance margin against rubbing under the combined effects of eccentricity, thermal distortion, and .025 in. radial movement at the lower labyrinth seal and the inducer blade tips.

Other physical interfaces with the prototype pump frame are defined on the interface control drawing (ICD) (Figure 1), which includes "asbuilt" measurements from the prototype pump components, and on the rework drawing which defines modifications in the prototype pump parts made to accommodate ISIP components.

Functionally, design of the ISIP components was to provide for necessary internal circulation, and to avoid excess loads on the prototype pump components. To alleviate the effects of thermal transients, the ISIP design had to maintain the provision for circulation of 50 gpm, up through the hollow lower end of the prototype shaft, to the radial holes above the impeller. The ISIP impeller/inducer design had to provide recirculation capability to maintain the pressure at the lower end of the sodium bearing below 18 psi. This requirement was necessary to assure adequate flow over the lower bearing sill.

The specification requires axial loads to be limited to within 70,000 lb upward thrust and 40,000 lb downward thrust. That is within the thrust bearing capability - rotor weight considered. These axial





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thrust limits must be met under the effect of a 10% difference in static head between the upper (back) and lower (front) shrouds of the impeller; a requirement based on changes in axial thrust which have been noted on many pumps. This includes water tests of the prototype pump when flow is throttled significantly below the design value.

Other mechanical design requirements included provision of methods of venting and draining the ISIP components (these features were already included in the design of the prototype pump), and provision for attachment of lifting and handling tools. The specification anticipated that some new tools or modification of the existing prototype pump tools might be required. Lifting tools were to conform to the requirements of RDT F8-6T<sup>(6)</sup> and support stands were to conform to the Uniform Building Code requirements for this region.

#### 2.6 MATERIALS AND PROCESSES

Materials and processes required for use on the ISIP were selected to be compatible with those materials presently in the FFTF Prototype Pump. All forged parts were to be made from Type 304 forgings, as was the prototype pump. Also, like the prototype pump, the impeller was to be fabricated from CF8, the chemically equivalent cast material to 304. Unlike the prototype, threaded fasteners in the ISIP were to be made from ASME SA-638, Grade 660, commercially known as A286. This alloy was chosen because of its reduced tendency to gall against stainless steel and its compatibility with the thermal expansion coefficient of stainless steel. This nickel alloy also has the advantage of a higher strength than Type 304. The piston ring which is used to restrict leakage from the impeller discharge to the inducer inlet, was to be made from a precipitation hardened nickel alloy, ASME SA-637, Grade 718, commercially known as Inconel alloy 718.



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The specification also required that the major parts be given a supplemental heat treatment as a part of the fabrication process to develop dimensional stability. The purpose of this requirement was to avoid, or minimize, the effects of material densification during extended exposure to high temperatures. These effects were identified as having contributed to the sodium bearing failure during Phase A testing of the prototype pump.



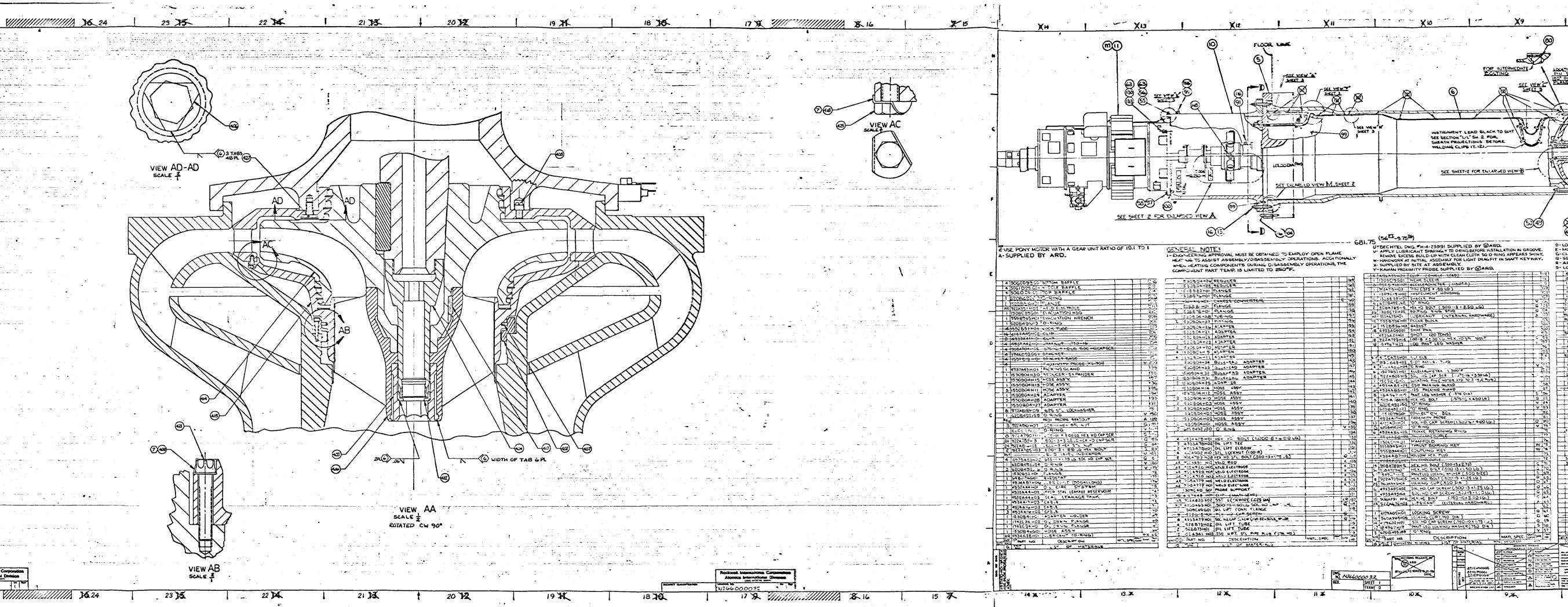
#### 3.0 PRESENT DESIGN

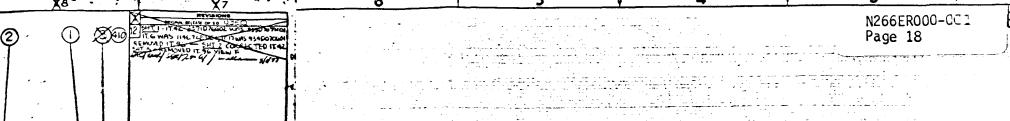
#### 3.1 DESCRIPTION

The final design of the Intermediate-Size Inducer Pump (ISIP) is shown in Figure 2. This figure was taken from general assembly Drawing N266000032 which is the top level drawing showing all ISIP components. The drawing includes components from the Fast Flux Test Facility (FFTF) Prototype Pump and those new components provided by Rockwell. The material list provides entry to the drawing tree. This permits identification of all lower level drawings of subassemblies and individual components. The ISIP general assembly drawing was produced by modifying a copy of the original FFTF Prototype Pump general assembly Drawing 114E829. Using lines and cross-hatching over information from the prototype pump assembly drawing which does not apply to the ISIP assembly, permits easy identification of those items which were changed for the ISIP configuration. The "find numbers" (equivalent to the prototype pump piece numbers) in the parts list for the new ISIP components start with No. 400. This permits easy distinction from the original piece numbers which end with No. 216.

Detailed information concerning principal dimensions and fits for the ISIP hydrodynamic components is shown in Figure 3 which was taken from the detail layout Drawing N266R000015. Fits and clearances at interfaces with original prototype pump components shown on the layout, are based on design dimensions for the prototype pump parts. Actual fits and clearances may be slightly different when considering the present "as built" dimensions for the prototype pump parts shown in Figure 1. Differences between design dimensions and "as built" dimensions for prototype pump components are probably a result of previously operating the prototype pump at elevated temperatures during sodium tests at the Sodium Pump Test Facility (SPTF). Following the tests,

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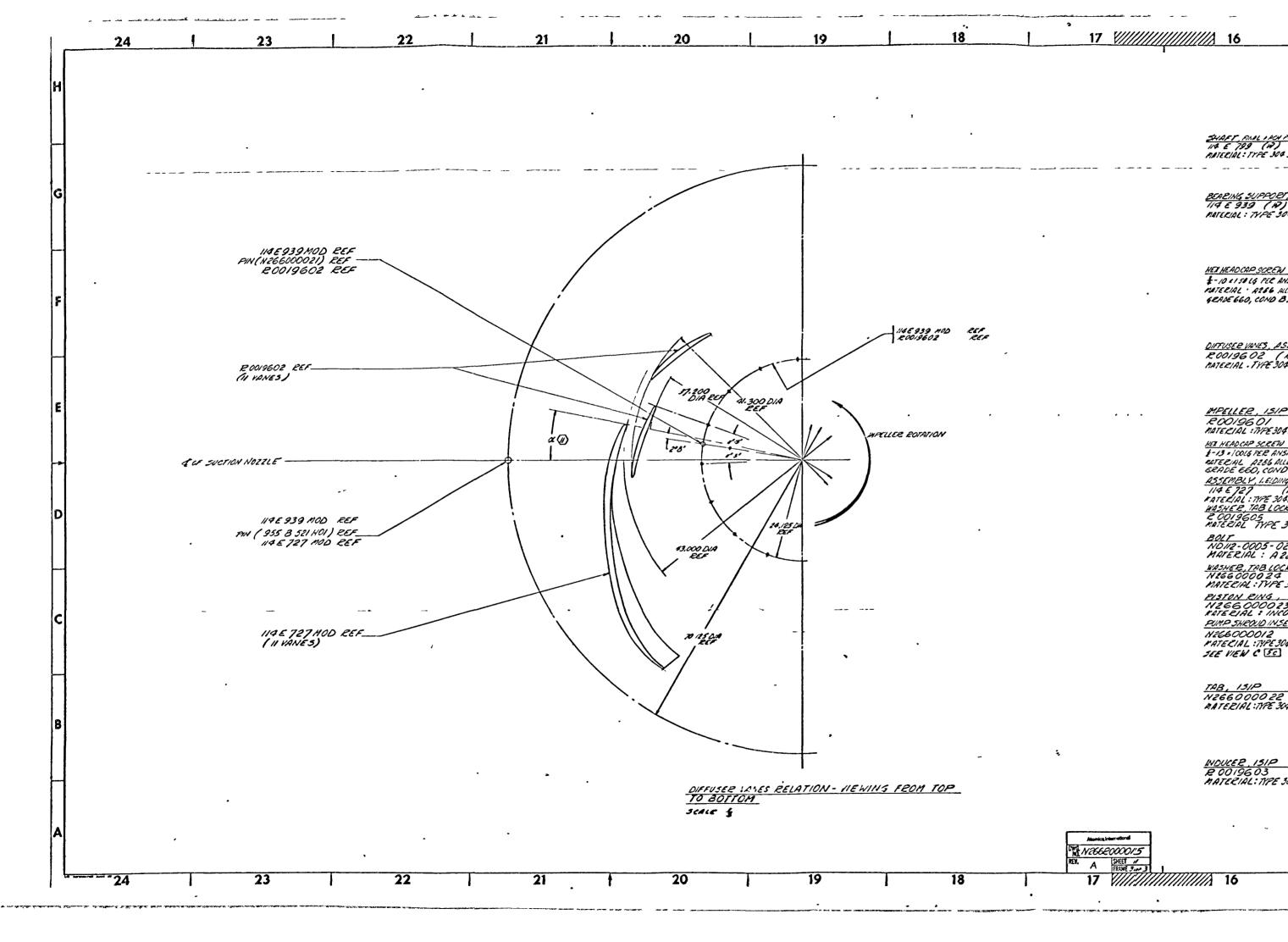
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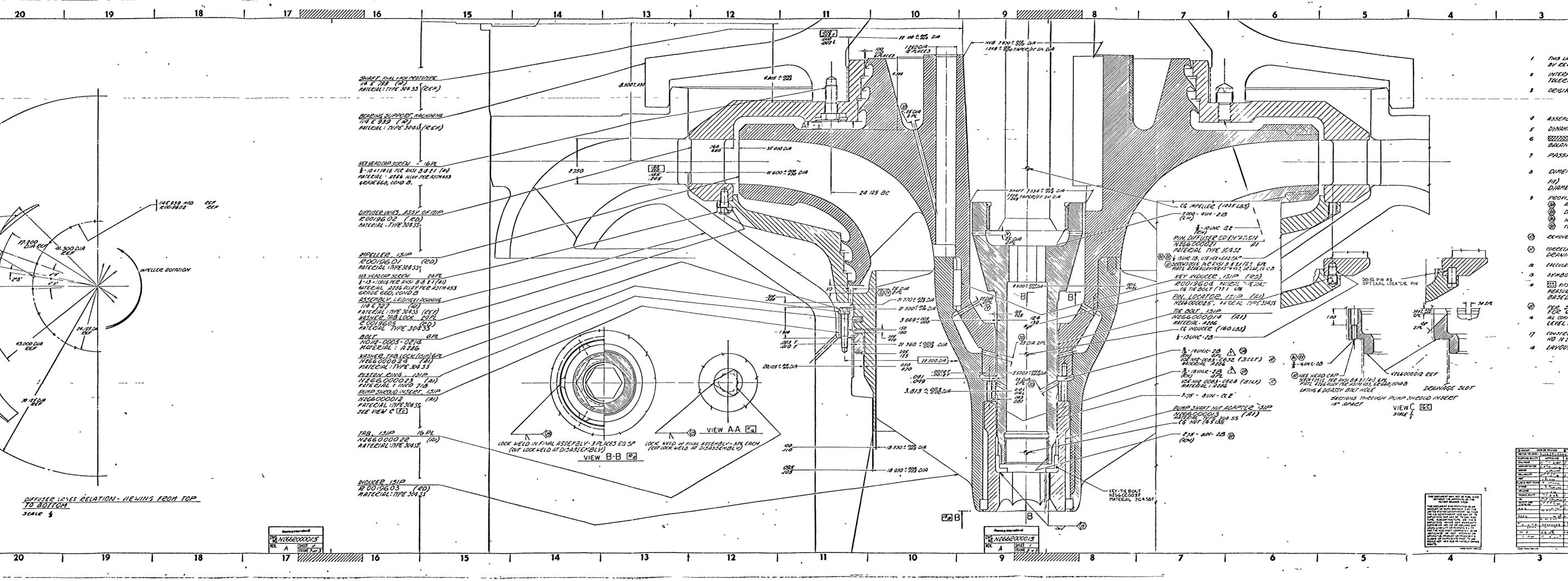
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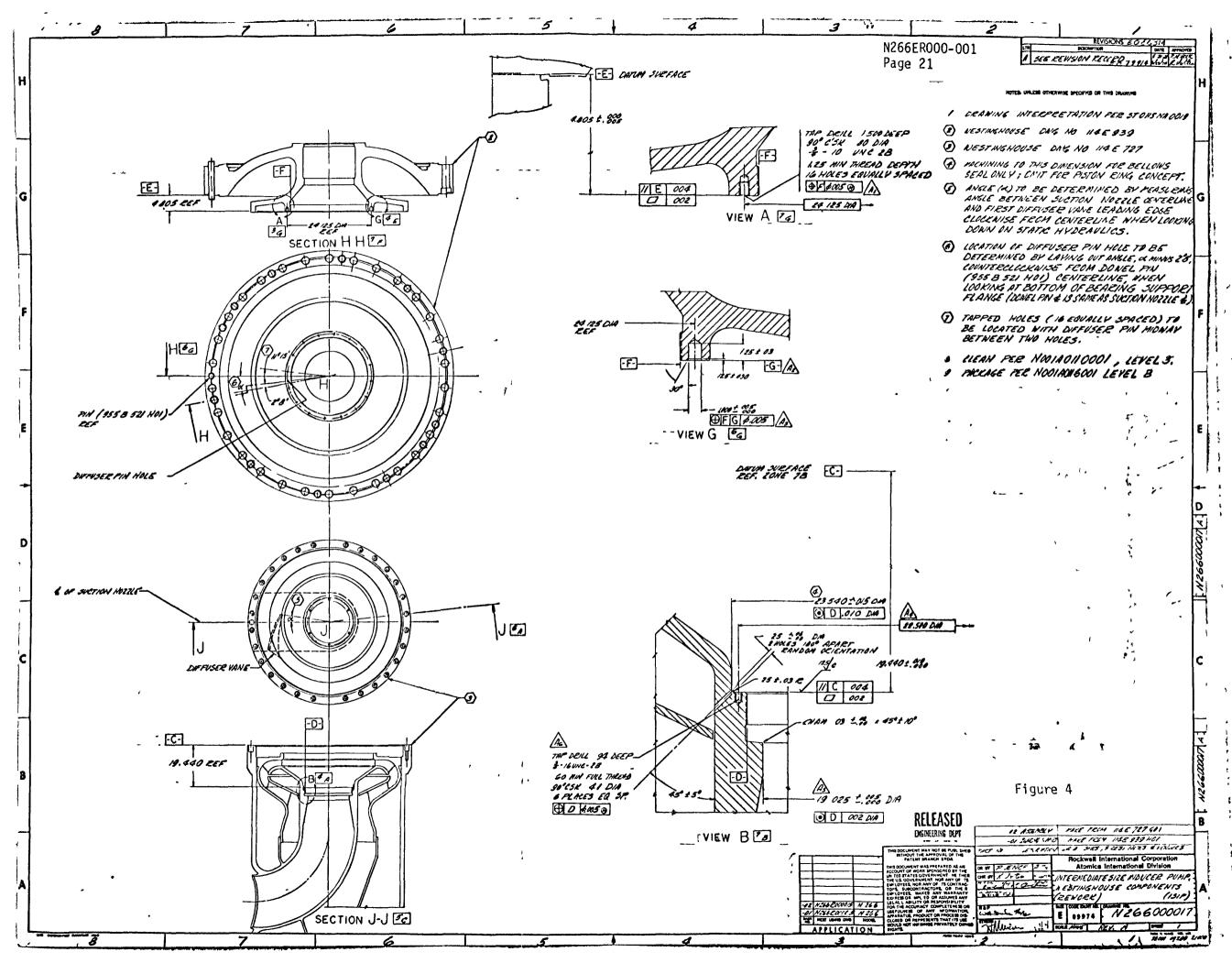
there was evidence of some material densification due to exposure to high temperatures, which could have caused small dimensional changes.

#### 3.2 MECHANICAL DESIGN

Basically, mechanical design of the ISIP is very similar to that of the FFTF Prototype Pump. For the ISIP, the prototype impeller and impeller nut are replaced by the ISIP impeller/inducer assembly, the tie-bolt, and the nut adapter. The ISIP diffuser assembly mounts on the lower side of the prototype bearing support flange and functions both as an adapter-diffuser, between the ISIP impeller outlet and the prototype diffuser inlet, and as a support for the inducer tunnel which is part of the diffuser shroud. A shroud insert is installed into the lower labyrinth seal of the prototype static hydraulics. This insert has a hard-surfaced cylindrical bore against which the piston ring, mounted on the ISIP diffuser shroud, rides to restrict leakage toward the inducer inlet while permitting radial and axial motion as needed to accommodate tolerance stackups, and as might occur during thermal transients.

#### 3.2.1 Protoype Pump Part Modifications

Mounting of the ISIP diffuser assembly onto the prototype bearing support flange and installation of the shroud insert into the prototype static hydraulics required some modification of the bearing support flange and of the static hydraulics. These modifications are shown in Figure 4, taken from N266000017. All of the modification work, except drilling of the two drain holes in the static hydraulics, were to be performed by the Westinghouse-Sunnyvale plant. Design of the modifications was coordinated with HEDL to assure that the changes would not affect the "spare" status of the prototype parts, and with Westinghouse-Sunnyvale to assure that the modifications were within the capability of the existing machine tools.



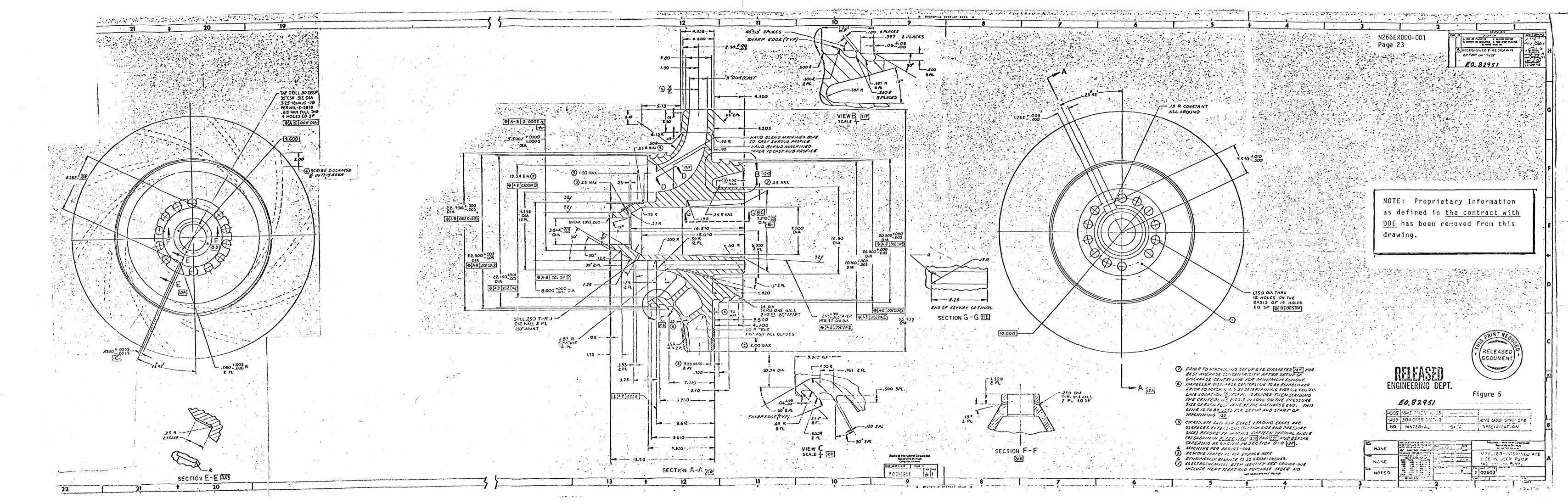


#### 3.2.2 Impeller

The ISIP impeller, Figure 5, was designed to have the same fit with the prototype pump shaft as the prototype impeller, and the same assembly criteria was to be used, i.e., an interference fit to be achieved by advancing the impeller .025 in. further along the shaft taper than its cold set position. This criteria results in a .0026 in. diametral interference fit in the approximately 8 in. mean diameter of the tapered bore (1/8 in. taper on diameter per foot of length). The taper fit and tolerances permit using hot  $(180^{\circ}F)$  water to heat the impeller before mounting to achieve the design interference. The 12 1.25 in. diameter holes through the impeller hub are designed to channel the recirculating internal flow from the upper (back) labyrinth, and from the lower end of the sodium bearing, back to the eye of the impeller. The total 669 gpm flow had to be accommodated while maintaining the pressure between the hub and the bearing no more than 18 psi above suction pressure (see Figure 2 of Appendix C). The pressure criteria was provided by HEDL to assure adequate flow out of the pump hydrostatic bearing pocket, across the lower sill of the pocket.

The impeller design provides additional material at both (upper and lower) ends of the hub and near the tips of the two shrouds for dynamic balancing. Balancing of the impeller and inducer was accomplished under ESG Specification N4007,  $^{(13)}$  which requires the impeller and inducer to be balanced individually; then an assembly check balance performed after the inducer is mounted on the lower end of the impeller hub. Because the impeller is a sand casting, subject to core shifts during the casting process, it was necessary that a liberal amount of material be available for removal during balancing operations.

Alignment for the inducer, which mounts on the lower end of the impeller hub, is provided by the 5.5007 in. diameter and 8.600 in.





diameter cylindrical surfaces on the impeller hub, and by the shoulder which is machined perpendicular to the axis of the impeller bore within .0005 in. The 5.5007 in. diameter was designed for an interference fit with the inducer bore. After installation in the ISIP, the upper end of the inducer hub is held against the square shoulder on the impeller by the tie-bolt and nut.

Considerable discussion was given to design of the impeller labyrinth seals. The original labyrinth seals on the prototype pump had a series of annular grooves in the stationary member running in close proximity (0.100) to a cylindrical surface on the impeller. The grooves were 1/8 in. deep and the lands between the grooves had a 1/8 in. pitch (Ref. 7). The nominal radial clearance was .050 in. at the rear (upper) labyrinth, and .100 in. at the front (lower) labyrinth. To minimize leakage through the labyrinth seals, it was decided to combine several features which were not included in the prototype pump. First, a stepped labyrinth design was used to help break up the velocity carryover effect from fluid leaving one stage of the labyrinth before it reached the next stage. Second, the pitch and groove depth between labyrinth stages was drastically increased from a 0.125 in. depth to 0.5 in., and from a 0.125 in. pitch to 1.25 in. (1.4 in. for the upper labyrinth). Thereby, the path length between lands was increased, and the cross-section area available for velocity dispersion, and associated momentum destruction, was also increased. Third, the form of the land and groove was specially designed to deflect a part of the fluid jet leaving one land down into the pocket, then redirecting it back against the fluid entering that pocket. The intent of this action is to destroy fluid momentum by taking a part of the velocity stream and directing it back against itself. The tooth form of the labyrinth and its effectiveness, particularly for relatively large radial clearances, had been reported in the technical literature referred to in the Engineering responses to the design review report (see Attachment III in Appendix D). Calculations indicated that this labyrinth

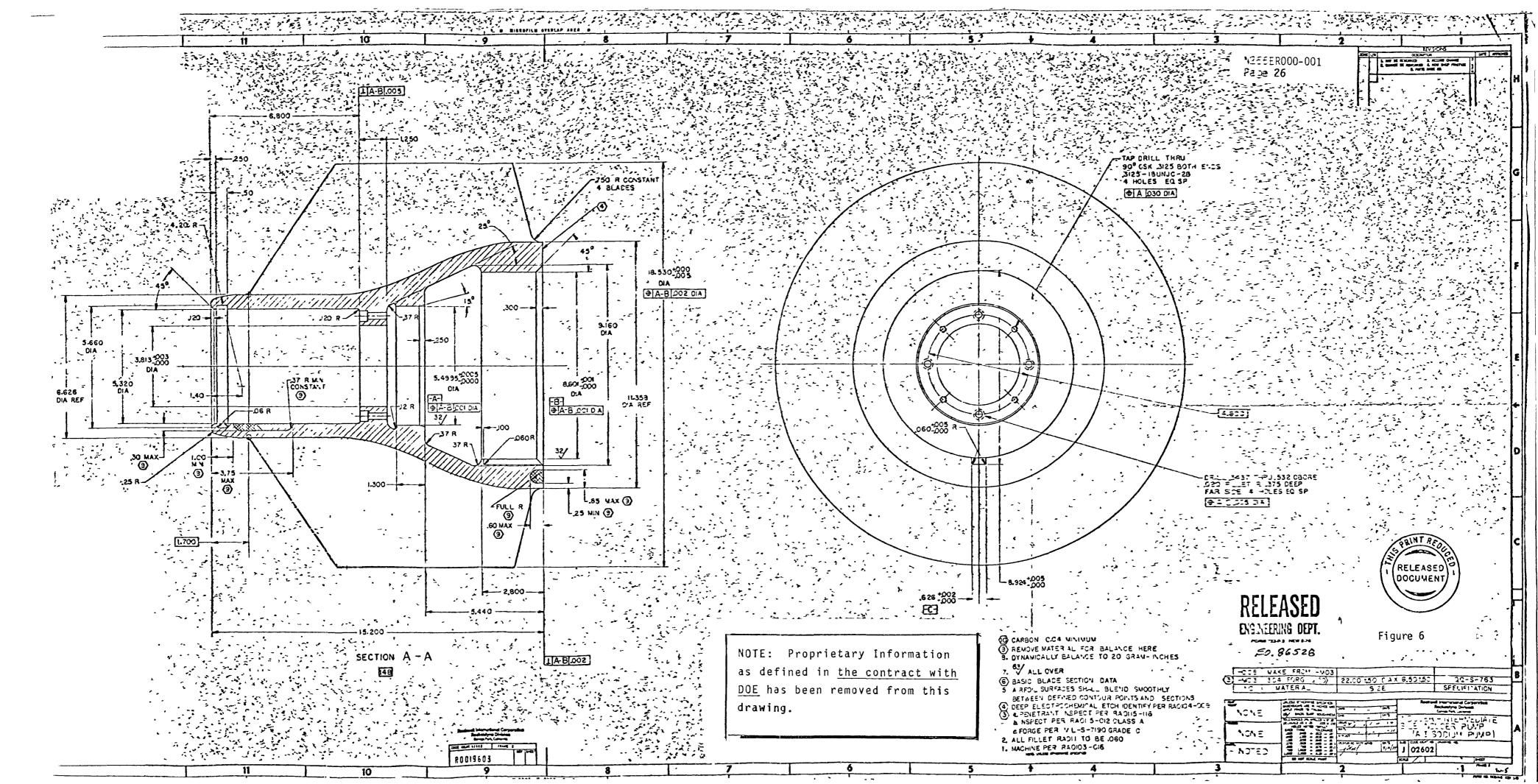


design would be more effective in limiting internal leakages than the more conventional straight labyrinth, under the required radial clearances.

#### 3.2.3 Inducer

Mechanical design of the inducer, Figure 6, was concerned principally with the internal surfaces of the bore, where provisions for mounting and for transmitting torque had to be provided. External surfaces of the hub and blade surface coordinates were dictated by hydrodynamic considerations. Blade thicknesses and blade-to-hub fillets were based on compromise between ideal hydrodynamic and structural conditions, with structural given as much dominance as practical, without undue detractions from hydrodynamic performance. Practically, this approach results in the leading edges and outer portions of the blade being controlled almost entirely by hydrodynamic requirements, while the inner portions, including the root, and trailing edges being controlled mostly by structural requirements (exclusive of the general blade shape).

Internal to the hub, the inducer design includes two internal bores at 5.4995 and 8.601 in. diameters, to match the 5.5007 and 8.600 in. diameters on the impeller hub. This arrangement provides for an interference fit at the smaller diameter, near the axial center of the inducer blades, and a close tolerance clearance fit at the upper (back) end of the inducer to react against transverse moments. These moments could occur if pressure distribution around the inducer is not exactly symmetrical. Like the taper fit between the impeller and the shaft, the fit between the inducer and the impeller is designed to permit the use of hot  $(180^{\circ}F)$  water. Hot water is used to heat the inducer before mounting it on the impeller, to achieve the design interference. A 5/8 in. square key transmits torque from the impeller hub to drive the inducer during operation.



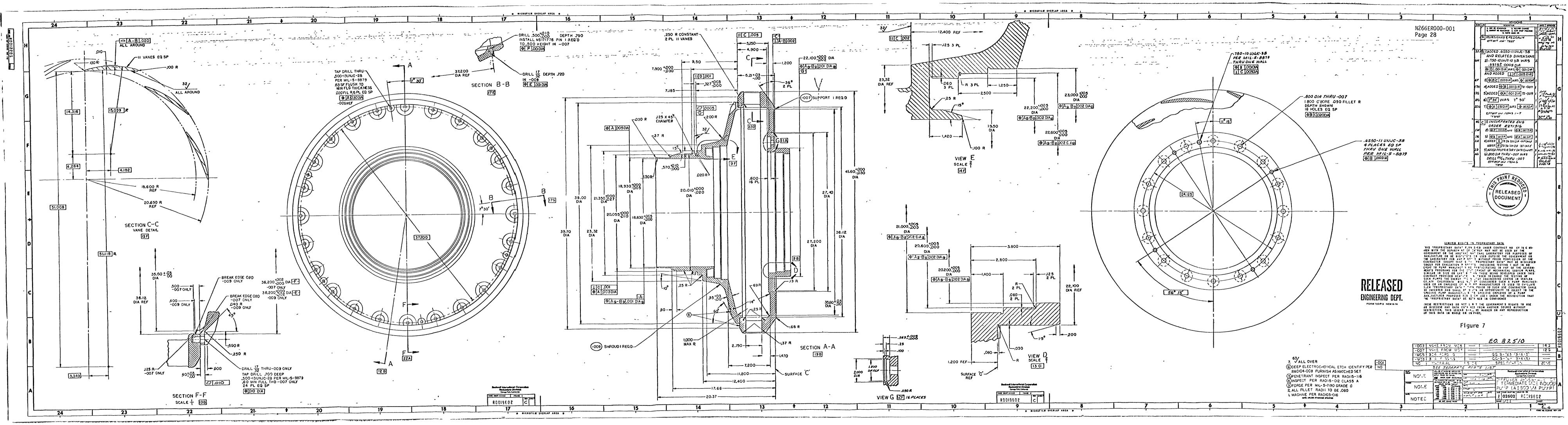
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The internal flange of the inducer has four tapped holes and four clearance holes which are aligned with tapped holes in the impeller hub. The four tapped holes permit the use of jacking screws in removing the inducer from the impeller. The clearance holes permit temporary assembly bolts to be installed, holding the two parts together safely for handling during operations, such as during dynamic balancing. All eight tapped holes (four in the inducer and four in the impeller) provide connection for the lifting tool used to hoist the impeller/inducer assembly during pump assembly.

#### 3.2.4 Diffuser Assembly

The diffuser assembly, Figure 7, serves a number of purposes in adapting the ISIP impeller and inducer to the existing FFTF Prototype Pump parts. First, the diffuser provides structural support for the stationary vanes designed to guide fluid leaving the ISIP impeller to the existing prototype diffuser. Second, the diffuser assembly serves as the stationary member of the upper and lower labyrinth seals for the impeller. Third, the assembly provides structural support for the inducer tunnel. The labyrinth seals are designed to operate with close running tolerances (nom. .050 in.), therefore, the diffuser must maintain concentricity at these locations. The lower end of the diffuser shroud forms the inducer tunnel, a cylindrical bore which, like the labyrinth seals, has a .050 in. running clearance and must be maintained concentric with the rotating element. The diffuser tunnel outside diameter, although stationary, has a .050 nominal clearance with the prototype pump parts, and must be maintained concentric with those parts during normal operation.

The diffuser shroud is designed for an interference fit at its mounting on the diffuser vanes, as are the diffuser vanes designed for an interference fit with the upper labyrinth bore in the prototype pump





bearing flange. Both fits are provided with tapped holes to permit use of jacking bolts during disassembly. The interference fits are designed to be accomplished using dry ice  $(-110^{\circ}F)$  to chill the male portion of the fit to a temperature approximately  $100^{\circ}F$  below ambient temperature.

Mounting the diffuser to the bearing support flange and the diffuser shroud to the diffuser using interference fits reduced the maximum eccentricity at the lower labyrinth and at the inducer tips from what might have been encountered if these parts were fixed to the diffuser shroud of the prototype pump. The .050 in. radial clearance with the prototype pump outside the inducer tunnel, combined with the .050 in. radial clearance inside the inducer tunnel permits the Hanford Engineering Development Laboratory (HEDL) required transverse motion of the prototype pump parts at the lower labyrinth, even under the most adverse tolerance stackup while still adequate margin against rubbing at the inducer blade tips or the lower labyrinth seal. (See Paragraph 3.2.9.2 for a detailed discussion of radial clearances.)

#### 3.2.5 Tie-Bolt and Shaft Adapter Nut

The tie-bolt serves as an extension to the existing prototype pump shaft and as the principal tension member in holding the impeller/ inducer assembly on the shaft. The upper end of the tie-bolt connects to the 5 in. thread at the lower end of the shaft (where the shaft nut is installed in the prototype pump design) and provides a 3.75 in. thread at the lower end of the tie-bolt where the shaft adapter nut is installed to clamp the inducer/impeller assembly onto the shaft taper. The hole through the center of the tie-bolt provides passageway for the calculated 50 gpm flow, up through the shaft to a region above the sodium bearing, to control temperature differences during thermal transients. Provision for flow through the shaft was a feature designed into the prototype pump. Despite the slight increase in flow resistance



offered by addition of the tie-bolt, the flow rate is not expected to be affected significantly.

In addition to holding the impeller/inducer on the shaft, the tiebolt is also part of the puller tool used to remove the impeller/inducer from the shaft during disassembly. For this application, the tie-bolt is unscrewed from the 5 in. thread on the shaft end and the puller tool attached to the 3.75 in. thread on the tie bolt. The pull is against the internal shoulder of the impeller hub. Also, during assembly and disassembly, the modified guide plate which is used to clamp the bearing support flange to the shaft assembly, is connected to the shaft assembly through the 2.75 in. internal thread at the lower end of the tie-bolt.

Material for the tie-bolt is A286 (ASME SA-638, Grade 660), and is used to minimize the risk of thread galling. The thermal expansion coefficient of this material is comparable to that of Type 304 stainless steel, but is slightly lower. Therefore, as the pump temperature rises during service, it is expected that the tension in the tie-bolt will increase. To compensate for this effect, the tightening torque for the shaft nut adapter is specified as 100 ft/lb, instead of the 450 ft/lb used in mounting the prototype impeller on the shaft. This torque is expected to provide adequate tension at the minimum operating temperature  $(400^{\circ}F)$ . The impeller/inducer is held in place this way under the influence of axial thrust, while still not causing an overstressed condition due to differential thermal expansion at the maximum temperature of  $1050^{\circ}F$ . The 13,300 in.-lb hydrodynamic moment on the inducer is reacted at the 5.5 and 8.6 in. diameter turns at the lower end of the impeller hub.

The shaft nut adapter is a sleeve-type nut with an internal hex, which mounts on the 2.75 in. thread of the tie-bolt. The lower end of the nut has six lugs, two of which are lock welded to the lower end of

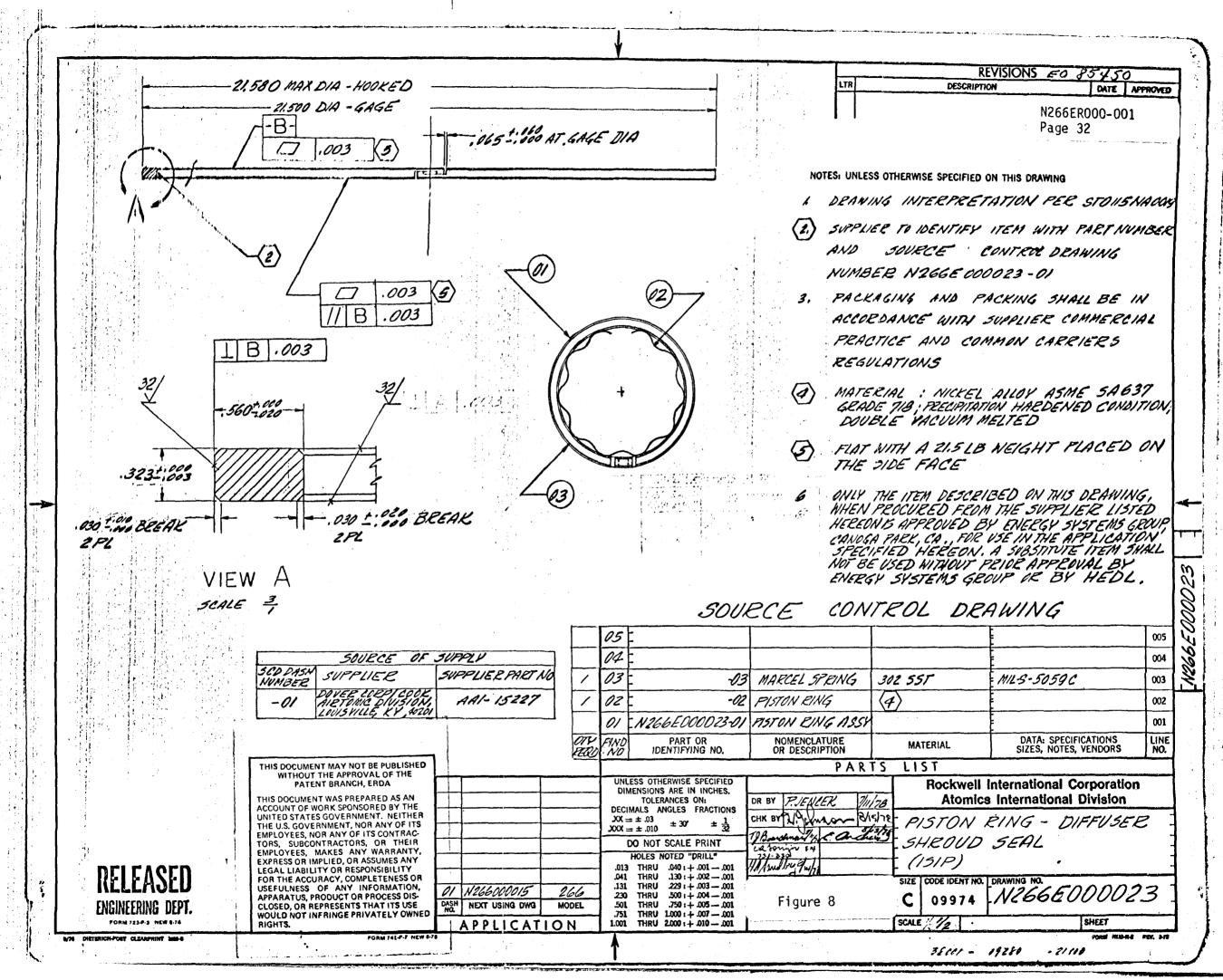


the inducer hub at assembly (the remaining four lugs are for subsequent assemblies, if required). Lock welding the nut to the inducer hub prevents the nut from turning (relative to the shaft). However, it is not a positive lock against the tie-bolt turning, despite the difference between the 5 in. thread pitch and the 3.75 in. thread pitch (four threads/in. vs eight threads/in.). Therefore, two "L" shaped locking keys are included in the assembly. The keys are installed into keyways at the lower end of the tie-bolt before the nut is installed. Then they are lock welded to the inside of the nut. Since both the nut and keys are Type 304 stainless steel, the lock weld does not involve dissimilar materials.

#### 3.2.6 Piston Ring Gland

The piston ring gland is compromised of a piston ring assembly, Figure 8, installed in a groove in the ISIP diffuser shroud, and the shroud insert which is installed in the prototype pump static hydraulics, as shown in Figure 3. The static hydraulics were modified to accept the shroud insert by machining a controlled tolerance recess (23.450 in. diameter) and mounting seat, and providing six 3/4-in. tapped holes for the mounting bolts as shown in Figure 4. Also, two 1/4-in.-diameter drain holes were provided, to drain the groove which would exist between the outside diameter of the shroud insert and the prototype pump shroud. Concentricity of the shroud insert, within the static hydraulics, is maintained by an interference fit between the shroud insert and the lower labyrinth grooves of the prototype pump. Like the diffuser parts, the interference fit is designed to permit the use of dry ice to cool the insert  $100^{\circ}$ F below ambient before installation. Tapped holes are provided in the insert to permit use of jacking bolts at disassembly.

Design of the piston ring gland was based on three basic criteria:





- 1) Limiting the leakage through the gland. Eighty-five gpm at 177 psi differential pressure was specified.
- 2) Limiting the axial load against the ISIP diffuser shroud, due to sliding friction, which might occur as a result of relative motion during thermal transients. A friction factor of 0.5 was assumed for this application.
- 3) Avoiding possible "hangup" which might fracture the ring during assembly for the most adverse misalignment conditions. Since this is a blind assembly under heavy load, failure of the ring during assembly might not be identified.

The ring itself was a purchased item with limiting groove dimensions and lead-in taper dimensions provided to the supplier. The supplier's recommendation to use a centering spring under the piston ring simplified the lead-in taper design aim; to prevent the ring from catching on the shroud insert and breaking during pump assembly. The calculated maximum permissible eccentricity between the ring and inducer shroud is .09 in., considering all adverse tolerances. Also included in the supplier's design is an end-hook arrangement to limit expansion of the ring prior to pump assembly.

To reduce the risk of galling, the base of the shroud insert, where the piston ring seats, has a hard-surface overlay (Stellite). The ring is made from a precipitation hardened material, Inconel 718, and has chamfered corners.

Conservative estimates of leakage through the piston ring, considering the effective radial gap to be 1/2 the diametral tolerance of the Shroud Insert, and the axial gap to be 1/2 the required flatness of the ring, yield a calculated value of 90.9 gpm vs the specified 85 gpm. This calculated estimate also considers no fluid friction losses in the gap, only a 0.5 velocity head entrance loss and a 1.0 velocity heat exit loss. The 90.9 gpm estimate was judged sufficiently close to the 85 gpm requirement for acceptance of the ring design (see Appendix A).

#### 3.2.7 Rotordynamics

Rotordynamic analysis of the shaft assembly was performed to assure that substitution of the ISIP impeller/inducer assembly for the original prototype impeller would not result in a critical speed problem during operation. To perform the analysis an analytical "stick" model of the shaft assembly was made. The model was similar to the one in Reference 8 which was used to analyze the prototype rotor assembly. Calculations were also made using a finite element dynamics computer program. Verification of the modeling technique and program operation was done by - first running a model of the prototype shaft in the finite element program - then checking the results against those reported in Reference 8 for the prototype pump. The results of the verification run and the ISIP analysis are reported in Appendix E. The two programs (the program used by Atomics International, and the program used by Westinghouse) for prototype pump design showed close agreement for the verification. The critical speed for the ISIP configuration was slightly higher than that predicted for the prototype pump. Since no critical speed problems were encountered during sodium tests of the prototype pump, it was concluded that shaft critical speed problems would be unlikely in the ISIP.

#### 3.2.8 Vibration

Previous vibration problems had been encountered during sodium testing of the prototype pump; therefore, this was a concern in the ISIP design. The previous problem had been due to excitation by turbulent



vortices which were generated by flow through the upper (back) labyrinth. The vortex shedding frequency resonated in the chamber above the impeller and excited a harmonic of the impeller labyrinth seal. Such occurrences are practically impossible to predict. However, the ISIP design includes changes in configuration which were made in an effort to avoid repetition of the problem. The upper (back) labyrinth ring on the impeller has a tapered cross-section, making it less susceptible to excitation by a single frequency. Calculation of the natural frequencies of the inducer blades and of the impeller did not show frequencies in a range where excitation could be anticipated. (Actual measurement of natural frequencies was specified as part of the preassembly data recording requirements.)

### 3.2.9 <u>Clearances and Tolerance Stackup</u>

### 3.2.9.1 Axial Clearances

The ISIP was designed to use basically the same procedures for axial positioning of the impeller, with respect to the diffuser, as the FFTF Prototype Pump. Mounting details for installation of the impeller onto the existing tapered shaft have the same dimensional relationship, including tolerances, between taper bore in the hub and impeller discharge centerline, as the prototype pump. Because the ISIP diffuser is mounted on the bearing support flange and not in the static hydraulics like the prototype, initial axial positioning of the shaft assembly, which involves alignment between the ISIP diffuser inlet centerline and the impeller discharge centerline, can be set and verified more readily than could be on the prototype pump before installing the upper assembly on the static hydraulics.

The ISIP design provides 1/2 in. axial clearance above and below the impeller, as opposed to the 3/4 in. provided in the prototype pump.



The reduction in axial clearance was made to minimize disk friction losses from the impeller shrouds and with HEDL concurrence that 1/2 in. would be acceptable based on the existing shaft, oil bearing, and SP/SC design. The largest differential change in axial length was calculated to be 0.043 in., occurring when the pump speed is suddenly reduced from high speed, with all sodium pumped from the shaft tunnel, to low speed, when sodium suddenly flows back up in the shaft tunnel (see Appendix A).

### 3.2.9.2 Radial Clearances

The nominal radial clearance at the lower labyrinth seal of the FFTF Prototype Pump impeller was 0.100 in. The nominal radial clearance at the lower labyrinth seal of the ISIP impeller is 0.050 in. The radial clearance at the ISIP inducer blade tips is also 0.050 in. Both the FFTF and ISIP impellers have a 0.050-in. radial clearance at the upper labyrinth seal. Soon after the start of design, AI requested HEDL approval of the 0.050-in. ISIP impeller lower labyrinth seal radial clearance. At that time, the ISIP inducer tunnel and lower labyrinth seal (both a part of the diffuser shroud) were guided by a seal sleeve in the static hydraulics as shown in Figure A-1 of Appendix A. The clearance between the sleeve and the ISIP inducer tunnel was only enough for assembly. In response to the AI request, HEDL stated that at least a 0.065-in. radial clearance would be necessary. This necessary clearance was based on a 0.025-in. allowance for stackup of tolerances, a 0.025-in. allowance for thermal distortion (occurring as lateral motion at the top of the Prototype Pump suction elbow), and a 0.015-in. margin against rubbing.

Re-evaluation of the hydrodynamic design showed that the 0.050-in. inducer blade tip radial clearance was the maximum permissible for proper operation of the ISIP. Therefore, to provide a 0.015-in. margin as requested by HEDL, the ISIP was redesigned to provide the configuration shown in Figure A-2 of Appendix A. This configuration maintains



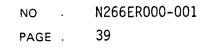
the 0.050-in. rotating clearances at the ISIP impeller lower labyrinth seal and inducer blade tips. The design introduces an additional 0.050-in. stationary radial gap behind the inducer tunnel (part of the diffuser shroud) and the Prototype Pump static hydraulics. Recirculation flow through this gap is restricted by a piston ring seal which can accommodate more than 0.050 in. radial motion.

Based on this design (Figure A-2), the radial tolerance stackup analyses were performed (Appendix F). These analyses showed, that under the most adverse stackup of tolerances at assembly, a 0.012-in. minimum radial clearance would exist at the inducer blade tips, at room temperature (Condition 5, Dimension J). The corresponding minimum stationary radial gap behind the inducer tunnel would be 0.0255 in. (Condition 5, Dimension 0). These were calculated with the shaft bearing journals against opposite sides of the upper (oil) and lower (sodium) bearings. The condition includes the effects of looseness at rabbet fits, perpendicularity, and concentricity for all stationary and rotating parts from the oil bearing to the inducer.

As previously stated, the tolerance stackup analyses assumed contact at opposite sides of the oil and sodium bearings to establish the minimum inducer tip clearance of 0.012 in. In actuality, with the pump operating, the specified minimum sodium bearing film thickness is 0.005 in. (this is continuously monitored during operation). Taking account of the amount of rotor overhang, this translates to an increase of 0.0054 in. on the calculated minimum radial clearance at the inducer tip, providing a calculated minimum clearance of 0.0174 in. (0.012 + 0.0054) during operation. The minimum calculated stationary radial gap behind the diffuser tunnel is not affected by bearing film thickness and remains at 0.0255 in. The minimum calculated clearances were compared to the required clearance values from HEDL. The HEDL allowance for tolerance stackup was 0.025 in., and this tolerance stackup was accounted for by the stackup analyses which were based on design tolerances for each individual part. The HEDL value for thermal distortion (lateral movement at the top of the suction elbow) was 0.025 in., which can be accommodated by the stationary gap of 0.0255 in. behind the inducer tunnel. The HEDL value for margin against rubbing, after accounting for tolerance stackup and thermal distortion, was 0.015 in., which is met by the calculated minimum clearance at the inducer tip of 0.0174 in.

In addition to considering the foregoing margin requirement provided by HEDL, a more detailed evaluation was made which considers local thermal distortions in addition to the 0.025-in. lateral movement at the top of the suction elbow. Referring to Table 1 of the transient structural analysis and deformation studies (Appendix I), Transient Events E-208 and E-203 cause the greatest reductions in inducer tip clearance (Location E) and inducer tunnel stationary clearance (Location F) due to local distortions. The inducer tip clearance at the Location E is the most critical running clearance on the ISIP rotor.

For Transient E-208, local distortions cause the stationary gap behind the inducer tunnel to increase by 0.0131 in., changing the minimum stationary clearance from 0.0255 in. to 0.0386 in., which is more than the 0.025-in. lateral motion at the top of the suction elbow. At the same time, the minimum inducer tip clearance is reduced by 0.0037 in. from 0.0174 in. to 0.0137 in., which is more than twice the 0.0054-in. allowance at the inducer tip for minimum sodium bearing film thickness. It is, therefore, concluded that no rubbing would occur for this transient at the inducer tips. Rockwell International Energy Systems Group



For Transient E-203, the minimum stationary gap is reduced by 0.0061 in. from 0.0255 in. to 0.0194 in. A lateral motion of 0.025 in. at the top of the suction elbow could cause a lateral motion of 0.0056 in. (0.025-0.0194) at the inducer tunnel. At the same time, the minimum inducer tip clearance (without lateral motion of the tunnel) is increased by 0.0029 in. from 0.0174 in. to 0.0203 in. Subtracting the 0.0056 in. lateral motion of the inducer tunnel from this minimum clearance leaves a minimum clearance of 0.0147 in., which is also more than twice the 0.0054 in. allowance at the inducer tip for minimum sodium bearing film thickness. Therefore, it is also concluded that for this transient no rubbing would occur at the inducer tips.

NOTE: The minimum clearances utilized above are based on the worst tolerance stackup as calculated from the dimensions of individual parts in the ISIP assembly. The actual stackup as subsequently measured during Assembly Procedures AP-39-PP-036 and AP-39-PP-043 resulted in a 0.037-in. minimum clearance at the inducer tips (versus a calculated 0.012 in.) and a 0.054-in. minimum clearance behind the inducer tunnel (vs a calculated 0.0255 in.).

#### 3.3 HYDRODYNAMIC DESIGN

Hydrodynamic design of the ISIP components was based on meeting the same noncavitating performance requirements as the FFTF Prototype Pump, which were also included in the ISIP design specification (Appendix B). The following is a list of the basic requirements:



Design Point: Flow 14,500 gpm Head 500 ft Speed 1,100 rpm

Maximum Flow Point: Flow 18,000 gpm Head 375 ft (minimum) Speed 1,110 rpm

In addition to the above requirements, the ISIP is also designed to have a required net positive suction head (NPSHR) of not more than 12.8 ft when operating at design flow and speed, and to be capable of operating at 200% margin above the required net positive suction head for 2,000 hours without any visual effect of damage due to cavitation damage. The present margin is defined as:

% Margin =  $\left(\frac{\text{NPSHA}}{\text{NPSHR}} - 1\right)$  100

where: NPSHR = Required NPSH NPSHA = Available NPSH

Refer to Paragraph 2.3 for definition of NPSHR.

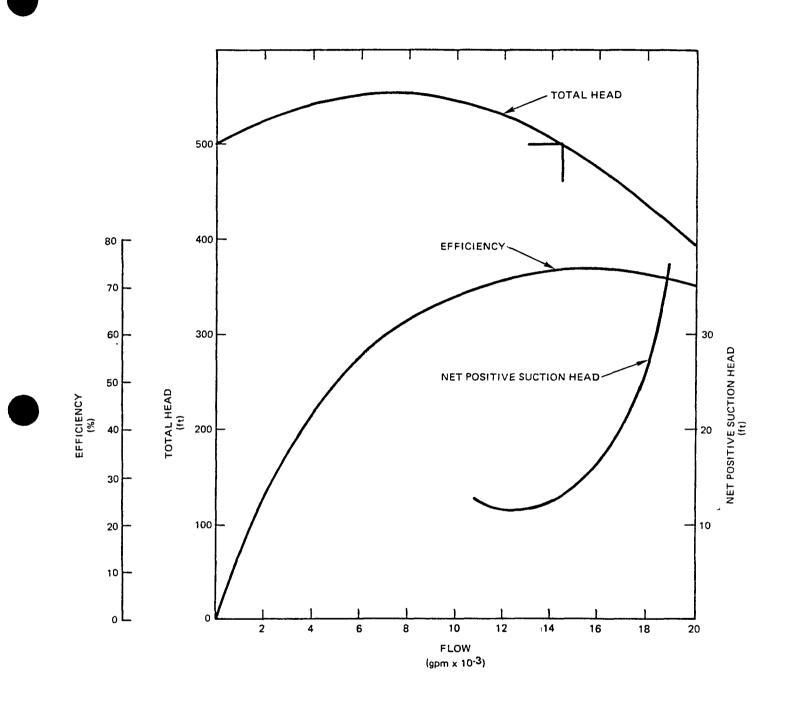
Three hydrodynamic elements are included in the ISIP design: impeller, inducer, and diffuser. These elements are to be installed in the impeller cavity of the prototype pump. An existing hydrodynamic element, the prototype pump diffuser, will remain in the pump and its characteristics will also contribute to the overall hydrodynamic performance. The hydrodynamic design process (not unlike other design efforts) was necessarily an iterative one, especially in the early stages, consisting of assuming or selecting certain parameters or



configuration features and calculating their impact and compatibility with other features. This report covers basically the final step, or steps of this process.

Initial steps in the hydrodynamic design effort consisted of sizing the impeller (determining its tip diameter) to verify the feasibility of the conceptual design, which included an intermediate (ISIP) diffuser between the impeller discharge and the prototype pump diffuser inlet, and evaluating the internal recirculation flows to predict actual flow rates through each of the various hydrodynamic elements. The diameter of the inducer was limited to about 19 in. by the existing inlet configuration of the prototype pump (see Figure 2). The outlet diameter of the ISIP diffuser was limited to about 41.75 in. by the inside diameter of the existing prototype diffuser. Calculation of the internal recirculation flows is presented in N266TI000003 (Appendix C). This report shows the internal flows originally calculated for the FFTF Prototype Pump design, and the changes in those flows resulting from the ISIP design. Using these flow rates and the head requirements from the design specification, calculation of the impeller tip diameter was completed. Final, detail hydrodynamic calculations were performed by the Rocketdyne Division using computer programs containing both theoretical and empirical relations developed through design and test of numerous, similar configurations. For detail description of the final hydrodynamic design process and calculated results, see the hydrodynamic design report, Appendix G. This report describes the design criteria and identifies the computer programs used for hydrodynamic analysis. It also includes tables and curves of calculated performance parameters such as overall performance, blade loadings, and internal losses. Figure 9 shows a composite of the expected head, efficiency, and NPSHR characteristics at 1,110 rpm. The following subparagraphs discuss the initial calculations used to establish design feasibility prior to submitting the problem for computer analysis.

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#### 3.3.1 Impeller

The first step in the impeller design effort was to establish a practical impeller discharge diameter and blade trailing edge configuration which would permit reducing the impeller diameter sufficiently, from that of the prototype impeller, to permit installation of a varied intermediate (ISIP) diffuser between the ISIP impeller discharge and the existing prototype diffuser inlet. The ISIP diffuser was needed to extend the permissible range of flow variation toward the low-flow regime, and to provide better control of clearances between the inducer and the inducer tunnel. Radial tolerance stackup and possible transverse movement of the existing inlet structure in the prototype pump would not permit adequate control of clearances.

Based on an assumed head rise efficiency for the pump (not including efficiency losses due to internal recirculation), the required Euler head ( $H_e$ ), or head rise for the rotating vane system (impeller plus inducer), was calculated. The impeller tip diameter and blade discharge angle, as determined from this head, is not appreciably affected by the head rise through the inducer in the ISIP configuration.

The Euler head is proportional to the product of the impeller tip velocity  $(U_2)$  and the tangential component of the absolute fluid velocity leaving the impeller  $(C_{U2})$ . With the selected (through design iteration)

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tip diameter of 35.4 in. and the specified rotating speed of 1,100 rpm, the tangential fluid velocity component is calculated by use of the Euler equation:

 $H_{e} = C_{u2}U_{2}/g \qquad \text{where:} \qquad C_{u2} = \tan g. \text{ absolute fluid} \\ \text{vel. (ft/sec)} \\ g = gravitational \text{ constant} \\ (ft/sec^{2}) \\ \vdots \\ C_{u2} = g H_{e}/U_{2} \qquad U_{2} = \text{ impeller tip velocity} \\ (ft/sec) \\ = (171.4 \text{ based on } 35.4\text{-in.} \\ \text{diameter at 1,110 rpm}) \\ = 32.2 (625)/171.4 \\ C_{u2} = 117.4 \text{ ft/sec} \end{cases}$ 

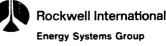
The prototype pump impeller had a blade tip diameter of 38.6 in. and produced the same net head rise with approximately the same pump head rise efficiency. For this initial calculation, losses were not assumed to vary significantly between the prototype pump and the ISIP pump design; therefore, reduction of the ISIP impeller diameter to 35.4 in. required increasing the head coefficient above that used for the prototype pump impeller design. The methods by which the head coefficient for a radial discharge impeller may be increased have been publicized in various texts on impeller design and become apparent by examination of the discharge velocity triangle and the Euler head equation (refer to impeller blade calcuations in Appendix A). These methods principally consist of:

1) Increasing the angle of the impeller blade ( $\beta_2$ ) in the region of the impeller tip (blade trailing edge).

2) Increasing the number of impeller blades to provide better flow guidance, forcing the angle of the relative flow into better conformance with the blade angle in the tip region.

Both of these techniques were used in the design of the ISIP impeller. The blade discharge angle was increased by about ten degrees (approximately from  $20^{\circ}$  to  $30^{\circ}$ ), and the number of blades at the discharge was increased from six to 10. Five of the 10 blades were designed as partial blades to avoid excessive blockage of through flow area in the eye, due to the total vane thickness. The blade width (B<sub>2</sub>) at the ISIP impeller discharge was increased from 2.40 in. to 2.75 in. to match the width at the diffuser inlet (both ISIP and prototype pump diffusers) in an effort to minimize turbulent losses when the fluid travels from one vane system to the next.

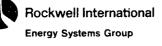
Impeller blade calculation results show a blade discharge angle of  $31.5^{\circ}$  (Appendix A). The calculation method was based on theoretical considerations as presented in the text of Reference 9. The method consists of calculating a correction for the discharge velocity triangle based on the exit geometry using the method derived by Stodola. The Stodola correction was put in the form which includes a coefficient, nominally equal to 1.0 for impellers with vane overlap but for which further modification is available based on published theoretical work by Busemann. Considering the tangential component of the absolute discharge velocity  $(C_{u2})$ , necessary to produce the required Euler head (H<sub>2</sub>), the "maximum usable" velocity triangle correction ( $\Delta \nu$ <sub>SA</sub>) was calculated for various blade discharge angles. These correction values were then compared to calculated corrections ( $\Delta 
u_{
m SA}$ ) predicted from the theoretical methods in the text. Plotting the results of two, the calculations, with the discharge angle as the independent variable, yields a solution at the intersection of the two curves where the



"maximum usable" correction equals the predicted correction. The solution, although not exact, indicated that the hydrodynamic requirements would result in a practical impeller discharge configuration which could be fabricated, and not be outside the range of experience at Rocketdyne or commercial pump manufacturers.

These initial calculations were based on frictionless flow through the impeller since, at the time, head losses through the pump were lumped under one assumed head-rise efficiency  $(7_h)$ . Also, the Stodola coefficient, as determined by Busemann, is based on blades with a logarithmic spiral (constant blade angle). The foregoing calculations are approximate, but no refinement was attempted, since the quantitative effects of impeller discharge geometry does not readily lend itself to theoretical analysis. Instead, at Rocketdyne, as at other pump designers, empirical data built up from published information and from the design organization's own past experience is normally relied upon. For the ISIP, detail calculations were made using two company developed computer programs developed through design and test evaluation of numerous impellers.

Initial calculation of the inlet angle for the impeller blades was based on accepting the flow leaving the inducer blade system with a minimum amount of entry losses (see Appendix A). Using an inducer Euler head ( $H_{ei}$ ), assumed as 12% of the total head rise through the rotor, the tangential component of the absolute velocity leaving the inducer ( $C_{u2i}$ ) can be calculated from the Euler equation. With the tip diameter limited by the existing prototype pump inlet configuration, the inducer exit hub diameter was first determined using company data from inducers with similar hydrodynamic characteristics. The impeller inlet hub diameter was set equal to the inducer hub outlet diameter, thereby establishing the through flow area and permitting calculation of the meridinal approach velocity to the impeller. For initial evaluation, fluid and



blade velocities at the tip, or outer periphery, are the principal concern because they are usually most critical to the design. Subsequent detail calculations considering radial equilibrium and axial velocity distribution for various steam tubes are performed by the computer program to determine impeller inlet blade angle variation between the tip and the hub.

As can be seen from the blade inlet calculations in Appendix A, use of an inducer aids in suppressing cavitation in the impeller, not only by generation of static pressure, but also by providing prewhirl which reduces the relative velocity of the fluid entering the impeller vane system. Proper prediction of this velocity angle and magnitude permits lower entry shock losses for the impeller than would be achievable without an inducer. Results of the calculations show the relative angle of the fluid approaching the blade ( $\beta_1$ ) as 28 degrees. To minimize entry losses, the impeller leading edge is set at this angle plus a slight positive correction to account for the increase in meridinal velocity ( $C_{m1}$ ) due to vane blockage.

It was previously mentioned that the Busemann value for the Stodola correction coefficient was based on blades assumed to have a constant angle (logarithmic spiral). Comparison of the calculated blade inlet angle of 28 degrees (plus a small positive correction) to the discharge angle of 31.5 degrees shows that this was a reasonably accurate assumption for the ISIP impeller.

Final calculations, as presented in the hydrodynamic design report (Table 1 of Appendix G), predict a 9% head margin for the impeller. During conventional development of impeller designs, which include water tests of full-size impellers or scale models, some adjustment in the pump head (either decrease or increase) can be made by decreasing the impeller diameter or underfilling the impeller vane tips. For the ISIP



impeller, no water testing is scheduled, therefore, pump head may be subject to some error due to the lack of opportunity to "fine tune" the impeller discharge geometry on the basis of test results.

### 3.3.2 Inducer

The inducer is a high specific speed, axial flow runner, characterized by a low head rise, compared to the flow and speed. There is considerably more theoretical and empirical data available for axial flow runners than for radial flow runners, where blade shapes and solidity (length to spacing rates) effects, as applied to the function of generating head, are concerned. However, in addition to the obvious objective of head generation to suppress impeller cavitation, the following two objectives must also be met for inducer applications requiring long life, such as for primary sodium pumps.

- The inducer itself must operate with low suction pressure (low NPSH) without (gross) cavitation, to the extent that head rise in the inducer or in the following impeller would be impaired.
- 2) Any local cavitation, which might occur near the low suction pressure limit must be handled in a way that prevents collapse of cavitation bubbles which would cause material damage on the surface of the inducer or the following impeller.

To achieve the above objectives, Rocketdyne makes heavy use of empirical data compiled from the results of testing previous successful designs. In addition to information from previous designs, a thorough knowledge of how the thermodynamic and transport properties of fluids affect the cavitation problem also had to be developed. Finally,



knowledge of the effects of varying various local details such as clearances, contours, and vane-edge shapes, which might be varied in any one design, had to be developed, specifically in application to the hydrodynamic runner. The procedures for applying this information have largely been put into computer programs to minimize calculative time requirements. Since the problems are seldom straightforward (implicit) many iterations are required for a solution. Also, for any particular design, optimizations, requiring repitition of the iteration process, are also required. (See Appendix G for detail description of the inducer design.)

Achievement of the first objective, performance at low suction pressures, is met through the design of the vane shapes and hub profile. The design must ensure that entry losses are minimized and momentum is imparted to the fluid by the blades in a manner which does not result in pressures low enough to cause cavitation on the low-pressure (suction) side of the blade. Pressure distributions, due to rotational fields and influence of adjacent vanes, are among the design considerations.

The second objective, avoidance of material damage due to local cavitation, involves:

- . Predicting transport paths from the point of generation to the point of collapse in the free stream
- . Predicting possible bubble formation in local areas, such as the blade leading edges, where there are high fluid accelerations with local static reductions
- Predicting possible bubble formation in clearance areas where there is likely to be high fluid shear rates and flow separation.

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The inducer profile is shown in Figure 6, with some of the features resulting from the design effort required to install an inducer in the existing prototype configuration. For the blade tips, the nominal inlet diameter of 19 in. in the prototype pump was reduced to 18.53 in. to provide room for the inducer tunnel (low end of the ISIP diffuser) to extend down into the 19-in. inlet bore of the remachined prototype inlet (see Figure 3). The nominal 0.050-in. radial gap between the inducer blade tips and the bore of the diffuser tunnel was calculated for this blade shape. The purpose of this allowance was to carry any bubbles which might form in flow through the gap, away from the blade surface and into the fluid stream between blades before collapse. The leading edge configuration provides a low loss entry into the vane system, with the blade "rake" imparting slight prewhirl to the fluid before reaching the blade tip leading edge.

The inducer inlet hub diameter was a compromise selection between having optimum hydrodynamic performance and providing adequate area for the 50-gpm through-the-shaft flow to the top of the bearing (see Figures 1 and 2 of Appendix C), plus room for inducer mounting hardware. The increased exit hub diameter provides some increase in head for the hub-side stream tube by virtue of its larger (than the inlet hub) tangential velocity, making a more uniform head profile across the exit radius.

Approximate velocity triangle calculations for the inducer are shown in Appendix A. These figures indicate that the change in blade angle is low, approximately 11 degrees over the length of the blade, making the inducer blades appear somewhat like a constant angle helix. The calculations are approximate, similar to the sizing calculations for the impeller. Actual vane angles and hub profile are performed in detail and optimized with the computer programs, considering local fluid velocities, accelerations, and blade pressure differences. The high



solidity blading permits low local blade loading and avoids the risk of flow separation within the blade system.

### 3.3.3 Impeller/Inducer Assembly

Two hydrodynamic requirements had been established for the impeller/ inducer assembly; these were regarding limits for the hydrodynamic radial and axial thrust loads which have to be supported by the pump bearing. The radial load requirement was a qualitative one, stating that symmetry should be used where feasible to minimize radial loads. The ISIP impeller and diffuser are designed with polar symmetry. The only existing hydrodynamic asymmetry in the ISIP design is in the existing suction elbow. However, through test experience, it is known that hydrodynamic radial loads will occur due to eccentricities resulting from manufacturing and assembly tolerances, bearing characteristics, and flow phenomena. The radial loads due to flow phenomena are most pronounced at low (throttled) flows when flow angles are markedly different from vane angles. In such cases, an asymmetrical flow and pressure distribution pattern is possible. The estimated maximum radial thrust for the impeller given in Appendix G is 800 lb. For the inducer there is an estimated transverse moment (normal to the shaft axis), due to asymmetrical axial pressure gradients of 13,300 in.-lb. If acting in the same line, the combined radial load at the sodium bearing could be 984 1b (see Appendix A).

Control of axial thrust generated by the impeller/inducer assembly is achieved by sizing the labyrinth seals to provide thrust within the specification limits. Inputs for the thrust calculations include momentum change through the assembly (axial components only), radial pressure distribution along the lower (front) and upper (back) shrouds, and the radial pressure distribution between the upper (back) labyrinth and the shaft. For configurations such as the shroud, an assumption



that the fluid rotates at about half the angular velocity of the impeller is usually adequate; for other configurations, such as between the upper labyrinth and shaft where the rotating surface area is relatively large compared to the stationary area, higher fluid rotational velocities are justified for use in the calculations.

# 3.3.4 <u>Diffuser</u>

With a new pump design, one diffuser would normally be considered adequate for conversion of impeller discharge velocity into pressure. However, for the ISIP, being installed into an existing configuration, there were two considerations as to why the intermediate (ISIP) diffuser was included in the hydrodynamic design: hydrodynamic performance at low (throttled) flow conditions, and structural support at the inducer tunnel.

Performance tests of the Westinghouse Prototype Pump (with its existing diffuser) showed unstable, and high, radial loads when the discharge flow was throttled below about 80% of its design value at constant speed  $(Q/N \cong 11)$ . The result was evidenced in the performance of the hydrostatic sodium bearing during which the position of the journal within the bearing would start to vary, both in angle from a fixed reference and offset from the bearing center, until the minimum film thickness would start to decrease below minimum permissible operating value, which was 25% of the available radial clearance, approximately 0.005 in.. Rocketdyne attributed this instability to flow separation (similar to stalling) in the curved diffusion passageways of the prototype diffuser when the inlet flow angle was changed from its design value by throttling. In an effort to permit a wider range of operation, the ISIP diffuser was designed to provide fluid flow to the prototype diffuser at a nearly constant angle. Not having curved diffusion passageways, the ISIP diffuser is expected to be less sensitive to variations of the inlet flow angle which occur during throttling.



The structure that supports the lower labyrinth seal of the prototype pump permits too much lateral motion to use for support of the diffuser tunnel.

Proper operation of the inducer requires that the inducer blade tip-to-inducer tunnel bore radial clearance be maintained at .050 in. (nominal) within close tolerance. Therefore, the inducer tunnel was designed as part of the ISIP diffuser shroud which is supported from the pump bearing support structure through the 11 ISIP diffuser vanes. This mechanical arrangement permitted maintaining the blade radial clearance independent of motion at the prototype lower labyrinth. Otherwise, attaching the diffuser tunnel to the stationary member of the prototype lower labyrinth would have required a greater clearance, as evidenced by the 0.100 in. radial clearance for the prototype lower labyrinth as opposed to the 0.050 in. radial in the upper labyrinth, which is a part of the bearing support flange (see 2.9.3 for discussion of radial clearances).

The ISIP diffuser has 11 vanes, as has the prototype diffuser. The vanes are installed so the wake from the trailing edge of the ISIP diffuser vanes will feed into the middle of the channels of the prototype diffuser throats. The staggering of vanes was chosen to minimize the potential for boundary layer buildup through the prototype diffuser passageways. Like the ISIP impeller, the width of the ISIP diffuser was maintained equal to the prototype diffuser inlet width (2.75 in.) to minimize flow losses.

#### 3.4 STRUCTURAL DESIGN

### 3.4.1 <u>Steady-State Analysis</u>

Analyses of the structural integrity of ISIP components were performed in two parts. The first part was the steady-state structural



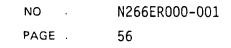
analysis based on steady-state operation at design temperature. At the time of the steady-state analysis, the design temperature was specified as 1050<sup>0</sup>F, and the structural design criteria were those given in the technical requirements document (Ref. 4). The work was performed using computer models of the components as shown in the design layout drawing (Figure 3). Other input data included the mechanical loadings due to pressure distributions around the various components. The data were based on results from the hydrodynamic analysis, centrifugal forces due to rotation, and assembly loads resulting from shrink fits. The impellerto-shaft fit was the most intensive in this category. The results are reported in the steady-state stress report of Appendix H. The results show that the steady-state design criteria are met. It should be noted that in view of these results, the reported margins are with respect to the design criteria of Reference 4 which also have margin included to allow for additional stresses to be imposed during thermal transients. For hydrodynamic loadings resulting from other than design point operation, the steady-state design criteria could be relaxed some to reduce the margins since all thermal transients are scheduled to be run at design speed and flow. No effort was made to revise the steady-state structural analysis and calculated stress margins after the specified test temperature was reduced from  $1050^{\circ}F$  to  $950^{\circ}F$ , since the effect was to increase the allowable stresses by about 15%, which would have increased the calculated margins above already acceptable values.

## 3.4.2 Thermal Transient Analysis

Structural response of the ISIP during thermal transients was analyzed by first calculating the temperature distribution throughout the lower end of the structure, which would occur during the test thermal transients; then, on the basis of selecting most adverse temperature distributions, calculating the resulting thermal stresses. The calculated temperature distributions were also used to calculate thermal distortions which affect internal fits and running clearances. Results of the thermal stress and distortion calculations are given in Appendix I. These are based on the temperature distortions calculated in Appendix J. In order to verify the adequacy of the ISIP thermal model, it was first used to calculate temperatures from the previous prototype pump tests, using actual test input temperatures. The calculated temperatures were then compared to temperatures measured during the tests. The results of this verification study is given in Appendix K.

In addition to transient structural analysis of the ISIP components, an investigation of the adjacent, existing prototype components was made; particularly of the bearing support flange. The investigation was made to determine whether they would be subjected to more severe transient conditions during ISIP tests, than they had previously withstood successfully during transient tests of the prototype pump, and for which they had been previously analyzed. The results, as shown in Appendix I, show that the prototype pump parts will not be subjected to more severe conditions during ISIP tests than were encountered during prototype pump tests. Therefore, no further structural evaluation was made.





#### 4.0 DESIGN VERIFICATION

Final verification of the ISIP design will be through meeting the hydrodynamic and cavitation performance criteria of the specification, as evidenced by sodium test results and post-test inspection. To gain confidence that the ISIP will meet these ultimate objectives, a number of checks were made during the design and fabrication process. These checks can be divided into three categories: reviews, feature tests, and assembly checks.

#### 4.1 REVIEWS

Due to the developmental nature of the ISIP project, the design was subject to continuous review, generally informal, throughout its progress. In addition to this continuous surveillance, three more structured reviews were held, the last of which included customer participation. For the structured reviews, a review board was selected from persons within the Energy Systems Group and the Rocketdyne Division. Those chosen are knowledgeable in specific areas of design, fabrication, and testing, and if possible, have not had part in generating the information to be reviewed.

The initial review was held on December 8, 1977, for the purpose of determining the adequacy of the conceptual design layout drawing and technical requirements. This review was designated as an "Engineering Review" since the board's function was to provide recommendations and questions for consideration as the design progressed. No engineering response to these recommendations and questions was required.

The second review was held on April 10, 1978, and designated as a "Preliminary Design Review." Its purpose was to review the preliminary design, as represented by the design layout drawing, and the pump specification. The review also served to define those items for which



additional work was required prior to the final (customer) design review to be held before fabrication.

The third review was held on May 10, 1978 and was designated as a "Customer Design Review." The review board included members from Argonne National Laboratory (ANL), who represented the interests of the customer (DOE), and from Hanford Engineering Development Laboratory (HEDL), who represented the test vehicle owner. The Rockwell members included persons skilled in the areas of materials, structural and thermal analyses, hydrodynamics, mechanical design, test, quality assurance, and manufacturing. The design layout drawing and pump specifications were reviewed along with supporting documentation, including material specifications and analytical reports. The review resulted in a number of action items and recommendations which were subsequently resolved with the board members by the Engineering Department. A copy of the completed review report is included as Appendix D. The issue shown (Change No. 1) includes a statement, on the cover page, to the effect that all action items were answered satisfactorily, and is signed by the chairman and the administrator of the review board. Final release of the layout drawing, Figure 3, includes a decal adjacent to the title block with approval signatures by the review board members.

An additional review to be performed is the test readiness review, which will be held approximately one week prior to rotation. The purpose of this review is to verify that both the pump assembly and the test facility are ready for the initiation of testing.

#### 4.2 FEATURE TESTS

Feature tests are used to verify that specific design features will perform as expected, prior to the completion of the pump assembly. For the ISIP, one feature test was performed. This was a test series to



verify that hydrodynamic design of the inducer was adequate. These tests were run on a 6-in. diameter scale model of the inducer in the water tunnel test loop at the Rocketdyne Division, where the inducer was designed and fabricated. The tests consisted of measuring the cavitation performance (variation of inducer head with net positive suction head) of the model inducer in water, and running simulated life tests to assess the capability for long-term operation in sodium at 200% NPSH margin without cavitation damage. Model tests were run ranging from 80% to 130% of the design flow, with NPSH margins from zero percent to 258%. A surface coating of "Magic Marker Type A" ink, as was used for previous model tests of the subscale inducer, was applied to the blades for the simulated life tests. The life tests were evaluated under the assumption that if dye removal occurs as a result of cavitation effects during water tests, there is almost a certainty that cavitation effects will eventually occur during operation in sodium under similar conditions. The converse is also assumed. The tests were run for both concentric and eccentric positioning of the inducer tunnel. Test results, as reported in Appendices L and M, show that the inducer has good life expectancy with respect to the design requirements when operating at rated condition (14,500 gpm, 1,110 rpm, 950°F) with 200% NPSH margin.

NOTE: Due to the proprietary nature of some information contained in the original issue of Appendices L and M, those pages containing proprietary information (i.e., inducer blade surface coordinates, inducer leading edge trim, inducer trailing edge trim, and impeller leading edge trim) have been deleted from the appendices.



#### 4.3 ASSEMBLY CHECKS

Assembly checks verify the design, manufacturing, and often a portion of the assembly procedures with respect to fits, clearances, and tolerances. Those checks are over and above the normal dimensional inspection, and generally relate to functionability. For the ISIP, four assembly checks were included. The first was to verify that the 1-in. total axial clearance between the impeller and diffuser shroud was actually provided prior to pump assembly. Measurements made prior to assembly, using the actual parts, showed that 0.999-in. clearance was available. The second assembly check was to verify that the fits and lead-in tapers of the design were adequate to align the diffuser shroud to the static hydraulics, without interference or damage to the thin lower end of the diffuser shroud. That check was also to verify that the piston ring would compress without damage during assembly of the upper internals (SP/SC sodium bearing assembly, oil bearing assembly, and shaft assembly) to the static hydraulics. The ring cannot be seen as it starts into the static hydraulics, nor is there any "feel" due to the weight of the upper internals (approximately 45 tons). The initial check, using the diffuser assembly mounted on the bearing support flange, showed no problem with piston ring compression or diffuser shroud alignment.

The third assembly check was the shaft alignmnent check, designed to verify that assembly of the upper internals had been accomplished satisfactorily within the calculated tolerance stackup limits. Measurements taken of the inducer blade-to-inducer tunnel shroud clearance showed a minimum measured clearance of .037 in. vs a calculated worst condition of .012 in. (Appendix F). Radial eccentricity of the inducer with respect to the axis of the shaft journal bearings was .005 in. vs a calculated maximum value of .007 in., and eccentricity of the diffuser shroud around the inducer was .003 in. vs a calculated maximum value of .0075 in.



### 5.0 TEST PLANS

Testing of the Intermediate-Size Inducer Pump (ISIP) is to be performed in the Sodium Pump Test Facility (SPTF) at the Energy Technology Engineering Center (ETEC) where sodium tests were run on the Fast Flux Test Facility (FFTF) Prototype Pump. The prototype pump tank, which will also be used for the ISIP, is still installed in the SPTF test loop. Pump assembly and disassembly, also considered a part of testing, is to be performed by ETEC in the Component Handling and Cleaning Facility (CHCF) which is adjacent to the SPTF. Special tools required for assembly will be principally the same tools as used for assembling the prototype pump. Some modifications of the prototype tools and new tools specially designed to fit ISIP components were provided by Atomics International.

As originally planned, testing of the ISIP in SPTF would repeat most of the Phase B tests previously performed on the prototype pump with basically the same instrumentation. In addition to utilizing existing facilities, this approach has the advantage of permitting comparative evaluation of two different types of pumps, one with an inducer and one without, without introducing questions of test setup or facility differences when evaluating the results.

An Approval-in-Principle (AIP) was prepared and submitted to Department of Energy for approval of the tests to be run by ETEC (Ref. 10). Next, a Request for Test (RFT) was prepared (Ref. 11) giving detail requirements for tests to be performed in the ISIP. In addition to the tests previously performed on the FFTF Prototype Pump during Phase B tests at SPTF, the RFT also included an interim disassembly and inspection, to be performed after determining NPSH requirements at various flows. These tests were to be followed by a 2000 hr design point endurance test at 200% NPSH margin, then a 300 hr off-design



endurance test to be run at runout loop impedance but reduced pump speed to match the design flow, and finally the series of thermal transient tests which had been run on the FFTF prototype pump.

The NPSH value corresponding to 200% margin would be based on the measurement NPSH required at design flow and speed (14,500 gpm and 1,110 rpm) to limit the overall head drop, due to cavitation, to 3%. For the off-design endurance test, the NPSH would remain the same as for the 200% margin at design condition, but the flow impedance of the test loop would be decreased to that defined by the runout flow condition (18,000 gpm at 1,110 rpm). The pump speed would be decreased to 894 rpm to maintain the 14,500 gpm flow rate. Based on results from water tests of an inducer model, the NPSH margin for this off-design condition is expected to be approximately 89%.

The Request for Test was subsequently revised to delete those tests which, although important for the FFTF Prototype Pump, would add little information concerning the ISIP design. Tests deleted included the onehour NPSH demonstration test which was based on FFTF plant requirements, the 8-hr post NPSH test endurance run which would be covered by the 2000-hr endurance run, two low-rate  $(0.4^{\circ}F/sec)$  thermal transients which would retest the prototype pump structure but not the ISIP components, and one up transient which was basically a repeat of a similar transient at lower temperatures. Also deleted was the interim disassembly and inspection. The maximum test temperature was reduced from 1050°F to 950<sup>0</sup>F which obviated those tests designed to monitor pump operation from  $950^{\circ}$ F to  $1050^{\circ}$ F, and those  $1050^{\circ}$ F tests which were a repeat of the  $950^{\circ}$ F tests. When the test request was originally written, water test results of the ISIP inducer model were not yet available. These results later showed that inducer performance in the specified operating range was expected to be very good (see Appendices L and M). Test results from the subscale inducer model also indicated that the water test results



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were valid for predicting good suction performance in sodium, as later confirmed by sodium tests of that pump. These test results provided the confidence level needed for the AI recommendation to delete the interim disassembly and inspection from the ISIP test plans.



6.0 REFERENCES

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- ESG-DOE-13265, "Task Proposal/Agreement," SA033, dated March 15, 1979
- 3. HWS-1551, Rev. 1, "Specification LMFBR Low-Capacity Prototype Pump and FFTF Primary Pump," dated January 1974, including Modifications to RDT-E3-2T dated January 1974 and Addenda through 1P dated May 24, 1977
- 4. N266TI000001, "Intermediate-Size Inducer Pump Technical Requirements," dated January 20, 1978
- HEDL Letter 7850652 dated February 10, 1978 (1906AT), W. J. McShane (HEDL) to Director, FFTF-PO, "HEDL Approval of AI ISI Bearing Drain Methodology and Labyrinth Clearances.
- 6. RDT F 8-6T, "Hoisting and Rigging of Critical Components and Related Equipment"
- 7. Westinghouse Drawing 160A243, "Standard Labyrinth Seal Grooves"
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- 10. AI Letter 78AT-2187, R. V. Anderson (AI) to Director, DOE-SAN "Intermediate-Size Inducer Pump (ISIP), Revised Request for Approval-In-Principle (AIP)," dated March 7, 1978
- 11. N266RFT000001, "Sodium Testing of Intermediate-Size Inducer Pump in SPTF at ETEC" by J. O. Pfouts
- ANL-7323, "Thermophysical Properties of Sodium," by G. H. Golden and J. V. Tokar, Argonne National Laboratory, Argonne, Illinois, August 1967
- N40007, "Intermediate-Size Inducer Pump (ISIP) Impeller/Inducer Dynamic Balance," October 9, 1978



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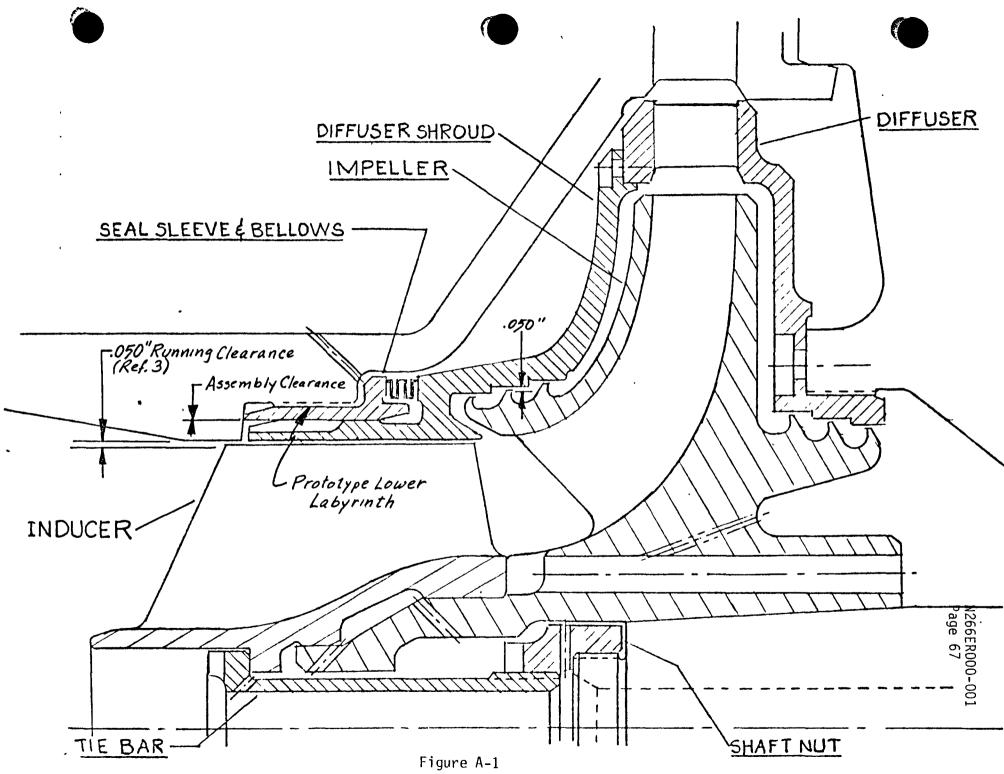
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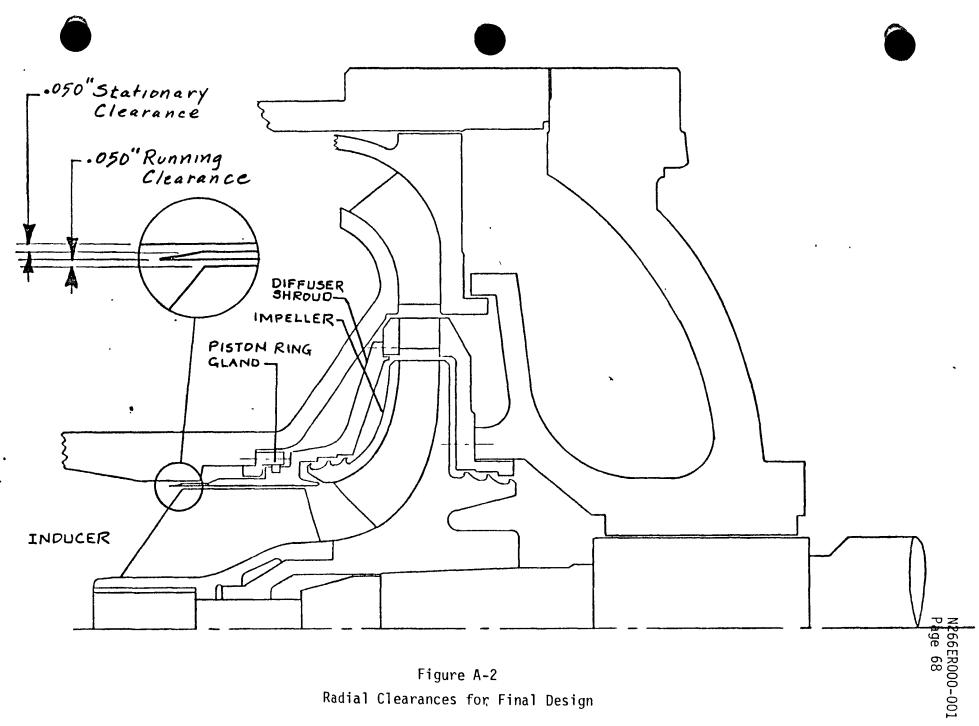


RADIAL CLEARANCES

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Radial Clearances for Initial Design



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Radial Clearances for Final Design



# PISTON RING LEAKAGE ESTIMATE

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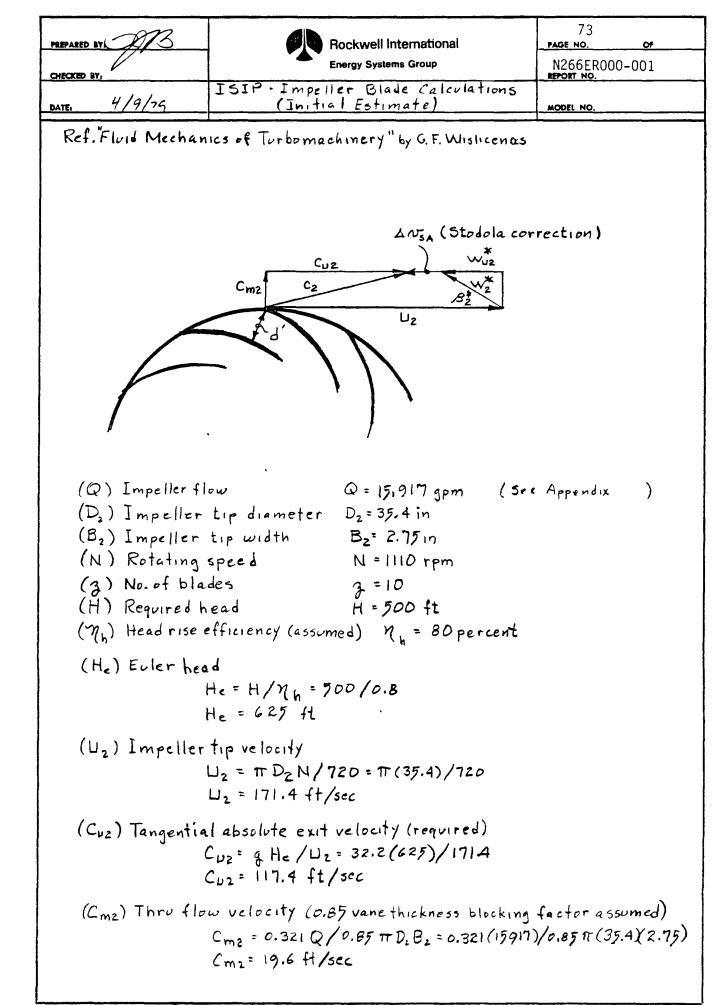
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## IMPELLER BLADE CALCULATIONS



PREPARED BY		I International stems Group			74 <u>3e no</u> 266ER0 Ort no.	<del>or</del> 00-001	
DATE: 4/9/75	ISIP - Impeller Bla (Initial Est,		tions		DEL NO.		
	ANGLE CALCULATIO	N	Param	eters f	or 10 bla	ade imp	enet
d'=	$\frac{\pi D_2}{3} \sin \beta_2^*$ Ref. See	$\beta_2^* \rightarrow$	20°	30"	40°	<u>50°</u>	<u>60'</u>
	$\frac{d}{10} \operatorname{Ref. Sec}_{2}^{+} \operatorname{Ref. Sec}_{2}^{+}$	d'>	3-80	5.56	7.14	8.52	9.63
(At2) Discharge H		A <sub>t</sub> ₂ →	10.46	15.29	19.66	23.43	26.48
<b>.</b>	charge vzlocity(fictitious						
w <sub>2</sub> <sup>*</sup> = -	<u>321 Q</u> 3 Azz Ref. Sec Eq	::s 33 È 36 . (162)	17.84	22 41	25.00		
-	$321(15917)/10 \cdot A_{22}$ ft/se	-	48.04	55.41	23.99	21.81	19.29
$(W_{U2})$ langential r $W_{U2}^{*}$ =	elative discharge veloci W2 cos B2 tt/sec		45.90	28.93	19.91	14.02	9.65
$(\Delta N_{SA}')$ Maximum u	suable Stadola correction	1					
$\Delta N_{SA}^{-} = (1$	$J_2 - C_{U2} - W_{U2}^*$ ft/sec	ANSA ->	8.10	25.06	34.09	39.9B	44.35
(K <sub>SA</sub> ) Stodola corre Busemannis	theoretical results)						
		27 K <sub>sa</sub>	1-19	0.96	0.84	0.7B	0.75
(ANSA) Predicted S							
$\Delta N_{SA} = K_{S}$	$AU_2 \frac{\pi \sin B_2^*}{3}$ Ref. E	(329)	21.02	25.05	20.00	22.7	24.07
	.4 Tr Ksn sin Bz It/sec		<i>~1,12</i> ≣	27.07	29.01	52.17	54.97
<del>6</del> 0 C	. 1	1					
\$50° (ANJ		/					
40	11						
X 36	Laus M.	AK,USABLE)					
5 20°	20 30	10					
SOLUTION: B2	ODOUA CORRECTION AA	sh ft/sec)					
	<u> </u>						
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CHECKED BY. DATE: 4/9/79	ISIP - Impeller Blac (Initial Est		REPORT NO.
BLADE ANGLE	INLET CALCULATION	NS	
(D,) Eye dia			
	19 in	Set by exis	ting in let diameter
(dh) Hub dia dh=	11.36 in	Based on iv Siging	nducer outlet hub
(Hei) Inducer	r Euler head		
	= .12 He = .12 (625) = 75 ft	head for si	aximum inducer ze and speed limit (i) denotes inducer
(U,) Impeller	inlet tangential veloc	.ity	
	= $\pi D_1 N / 720$ = $\pi (19)(1110) / 720$ = 92 ft/sec NOTE: $U_1 \simeq U_{21}$ (induc	er tip velocity)	
(Cui) Tangentia	il fluid velocity approach	ing impellet	
$C_{\nu_1}$	= Cuzi = g Hci/Uzi		
	= 32.2(75)/92 = 26.24 fl/sec		
(Cmi) Meridoni	al (thro-flow) velocit	'y approaching im	peller
· · · · · ·	= .321 Q/Ae = .321 (15917)/.785(1 : 28.0 ft/sec	Where Ae 9²-11.36²)	= Eye area
	approach angle = tan-' Cm1/(U1-Cu = tan-' 28.0/(92-26		
(W,) Relative	= 23° approach velocity = Cm, /sin B,		
$\omega_{i}$	= 28/sin 23° = 71.4 ft/sec		

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## INDUCER BLADE CALCULATIONS

77 PREPARED BY, **Rockwell International** PAGE NO. Atomics International Division N266ER000-001 CHECKED BY ISIP- Inducer Blade Calculations (Initial Estimate) DATE MODEL NO. (A.) Inlet Flow Area  $A_{1} = (D_{1}^{2} - D_{b_{1}}^{2}) \pi / 4$ Where: A, = Inlet Flow Area (in2) D: = Inducer Tunnel bore (in)  $=(18.63^2-6.63^2)\pi/4$ Dhi = Inducer mlet hub OD(in) A. = 238 In2 (Cmi) Axial fluid velocity (approaching inducer)  $C_{m_1} = 0.321 Q / A_1$ (gpm) Where: Q= Inducer flow = 0.321 (14600/238) (= 14600 gpm from App. ) Cm1 = 19.68 ft/see (11/sec) Cmi=Axial inhet vel. (U, ) Blade top velocity at inlet U, = TT D4 N/720 Where: U, = Tang. velot blade tip (ft/sec) Dz = Blade tip dia = TT (18. 53 X1110)/720 (In) N = Rotating speed (tpm) U, : 89.75 ft/sec (B) Fluid inlet angle, relative to blade tip B, = arc tan (Cm, /U,) Where: B, = Reliangle at white (deg) = arc fan (19.68/89.15) B. = 12.36° Cm2

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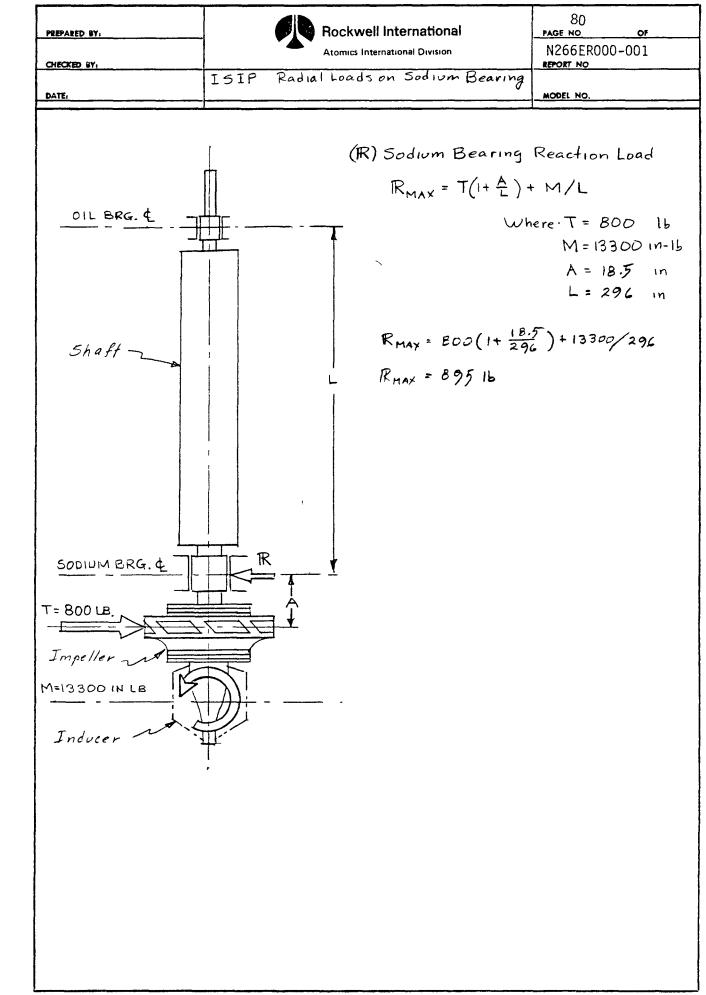
78 **Rockwell International** PREPARED BY PAGE NO. OF N266ER000-001 Atomics International Division CHECKED BY ISIP - Inducer Blade Calculations (Initial Estimate MODEL NO. DATE (Cuz) Tangential fluid velocity at exit Cuz= gHei/Uz Where Cut Tang. abs. exit vel. (11/sec) Hei = Inducer head (ff)= 32.2 (75)/89.75 (See imp. inlet calculation) Uz = Blade tip vel. @ exit (Al/sec) (= L),) Cu2= 26.91 NOTE: This value differs slightly from the 26.24 ft/sec velocity calculated for the impeller inlet velocity triangle due to the slight difference in assumed inducer diameters (18.53 vs 19 in.) (A2) Exit flow area  $A_2 = (D_1^2 - D_{h_2}^2) \pi / 4$ Where: Az = Exit flow area  $(n^2)$ D.= Inducer exit hub OD (in) = (18.63-11.362) TT/4 A,= 17/ 102 (Cm2) Arial fluid velocity (leaving inducer) Cm2 = 0.321 Q/A2 Where. Cm = Axial exit vel. (ff/ser) = C.321 (14600)171 Cm1 = 27.35 (B) Fluid exit angle relative to blade tip B2= arctan [Cm2/(U2-CW2)] Where: B2= Rehangle at exit (deg) = ore tan [17.35/(89.15-26.91)] B: 23.52°  $C_2$ Cmz  $C_{\mu 2}$ 



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#### RADIAL LOADS ON SODIUM BEARING

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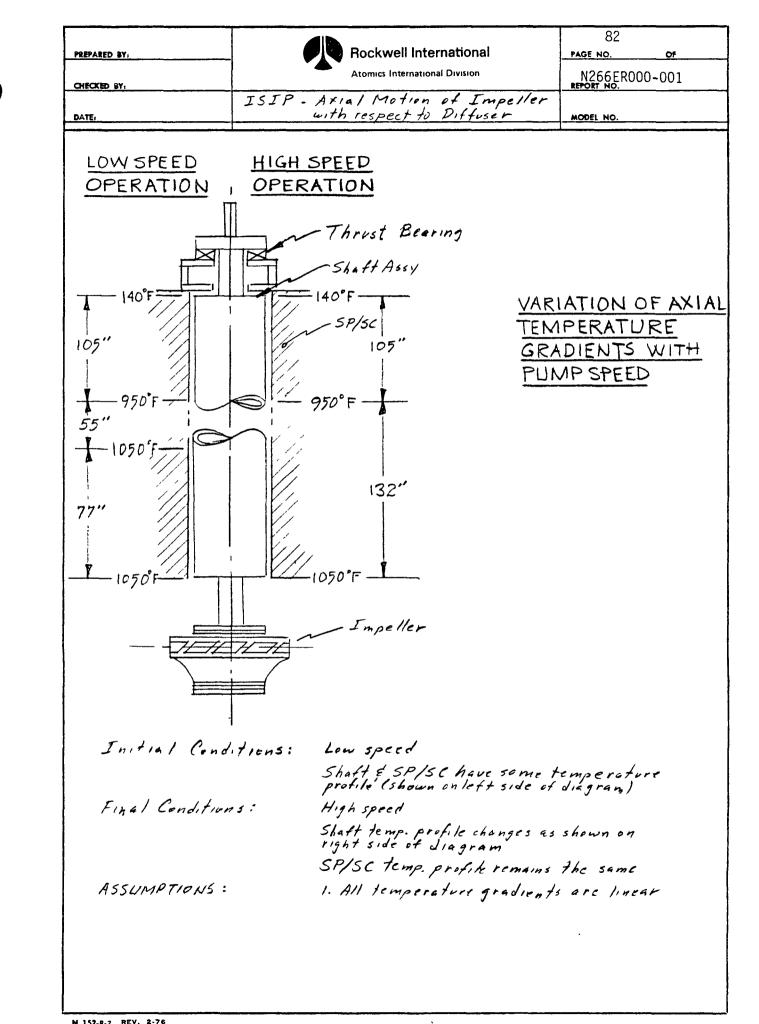
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### AXIAL MOTION OF IMPELLER WITH RESPECT TO DIFFUSER





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#### APPENDIX B

## DESIGN SPECIFICATION - PUMP, SODIUM, INDUCER, INTERMEDIATE SIZE (ISIP) (IMPELLER/INDUCER/DIFFUSER RETROFIT)

ESG Document N266ST310001

- 1 N266ER000-001 Page 85 **Rockwell International** Atomics International Division PREPARED BY NUMBER N266ST310001 R Taradise AMEND REV DESIGN В D.R. Paradise Specs. & Stds. Engineer SPECIFICATION TYPE COMPONENT DATE TOTAL PAGES 5-22-79 91299 E.O. .44 TITLE PUMP, SODIUM, INDUCER, INTERMEDIATE SIZE (ISIP) (IMPELLER/INDUCER/DIFFUSER RETROFIT) APPROVALS R. Wachlen I L.R. Woehler, Sr., Manager Anderson Project Manager Specifications & Standards E. D. andun Boardman E. Andrews Project Engineer Quality Assurance THIS REPORT MAY NOT T PUBLISHED WITHOUT THE APPROVAL OF THE "ATENT BRANCH, DOE This report was prepared as an account of work sponsored by the United States Government, Neither the U.S. Government, nor any of its employees nor any of its contractors, subcontractors, or their emproyees, makes any ENGINEERING DEPT warranty, express or implied, or assumes any legal hability or responsibility for the accuracy, completend or a section, instantion, FORM 723-P-3 NEW 8-74 apparatus, product or process disclosed, or represents line as would not infringe privately owned rights.

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#### SUMMARY OF CHANGES

This Summary of Changes delineates the changes which constitute Revision B. The outside margins have been marked to indicate where changes, deletions, or additions from the previous issue have been made.

Revision B changes were made to bring this specification in line with Request for Test (N266RFT000001) Rev. C. changes.

- Page Paragraph Title-Description of Change
- 3-1 3.1.1.3 Radial Clearance In the first sentence, following word "clearance" deleted statement "but in no case shall the radial clearance be less than 0.050 inch using the most adverse tolerance stackup." Added new second sentence beginning with "At least...and ending with transient tests."
- 3-2 3.2.2.1 Operating Life In the second sentence added word "design" preceding operating and after 4000 hours deleted words "minimum, at conditions described in 4.45" and substituted words beginning "of which 3000 hours...and ending with 1110 rpm."
- 3-2 3.2.2.2 <u>Flow/Speed Ratio</u> (was titled System Resistance) System resistance was defined in terms of flow/speed ratio instead of specific speed.
- 3-14 Figure 3-1A <u>Pump Main Motor Operation Envelope</u>. System resistance lines were redefined (see paragraph 3.2.2.2 above).
- 4-3 4.4.5 Performance Testing Extensive test changes made to first and third paragraphs. Added new second paragraph.
- 4-4 4.4.5.1 Determination of NPSHR In first sentence (950 F) was (1050 F), and deleted 14,000 gpm. In subparagraph b, second sentence, added "(Elevation at the lower end of the inducer blade tip)."
- 4-4 4.4.5.2 Determination of Suction Capability at Runout Flow Deleted entire paragraph.
- 4-4 4.4.5.3 Test Success Criteria Renumbered paragraph to 4.4.5.2.

4-5 Figure 4-1 NPSHR Determination Added explanatory words "97% of initial head".

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Page	Paragraph	Title-Description of Change	

4-6	TABLE 4-I	Test Sequence Deleted previous sequence numbers/test
&		descriptions 14, 15, 16, 17, 19 and 23. Added new test
4-7		descriptions for sequence numbers 15 and 16. Deleted
		from sequence numbers 17 through 19, thermal transients
		201, 205 and 206.

4-8	TABLE 4-II	Test Thermal	Transients	Deleted	events	201,	205 and 20	)6.



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# Rockwell International

## Atomics International Division

#### SPECIFICATION FOR PUMP, SODIUM, INDUCER, INTERMEDIATE SIZE (ISIP)

1. <u>SCOPE</u> This specification defines the requirements for the Intermediate-Size Inducer Pump, (also referred to herein as the ISIP) which is to be made by replacing the impeller of the FFTF Prototype Pump with a new inducer, impeller, diffuser, seal, and necessary adapter hardware. Subsequent testing requirements of the complete pump assembly are included.

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2. DOCUMENTS					
2.1 Applicable Documents					
<u>American Society of Mechanical</u>	Engineers (AS)	<u>4E)</u>			
ASME Boiler and Pressure V including Summer 1977 Adde		77 Editio	n,		
ANSI/ASME BPV-III-NCA	Division 1 au Nuclear Power Components; ( Requirements	Plant	on 2		
ANSI/ASME BPV-III-1-NB	Class 1 Compo	onents			
ASME SA-182	Specification Rolled Alloy- Flanges, Ford Valves and Pa Temperature S	-Steel Pi ged Fitti arts for	pe ngs, and		
ASME SA-351	Specification Steel Casting Temperature S	gs For Hi			
ASME SA-453	Specification Materials, H: 50 to 85 KSI with Expansion Comparable to	igh Tempe Yield St on Coeffi	rature, rength, cients		
ASME SA-637	Specification Precipitation Alloy Bars, I High-Temperat	n Hardeni Forging S	tock For		
ASME SA-638	Specification Precipitation Base Superal Forgings, and for High-Temp	h Hardeni loy Bars, d Forging	Stock		
Code Case N-47(1592-10)	Class 1 Compo Temperature S		evated		

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N266E000002 Interface Control Drawing (ICD), "Intermediate-Size Inducer Pump"

#### **Specification**

N001A0110001 Cleaning and Cleanness

N001A0116001 Packaging and Packing for Shipping and Storage; dated 27 April 1977

N266RFT000001 Sodium Testing of Intermediate Size Inducer Pump in SPTF at LMEC

November 1975

MW1-08061-000

Department of Energy, Nuclear Power Development Division

RDT\_Standards

RDT F 2-2	Quality Assurance Program Requirements, August 1973, including Amendments 1 through 4
RDT F 8-6T	Hoisting and Rigging of Critical Components and Related Equipment with

#### Argonne National Laboratory (ANL)

ANL-7273

Thermophysical Properties of Sodium

Amendments 1 through 3

General Weld Procedure: dated

#### International Conference of Building Officials

UBC-1976 Edition Uniform Building Code

.



Atomics International Division

Westinghouse\_Electric\_Corporation

Hws-1551	LMFBR Low Capacity Prototype Pump FFTF Primary Pump, Rev. 1, January 1974, including addendum 1P (June 1977)
WDTRS 25.14, Rev. 18	Sodium Testing of the FFTF Prototype Pump
WEMD 114E829, Rev. 12	General Assembly, Prototype Sodium Pump

#### American National Standards

ANSI B46.1-1962 (R1971) Surface Texture

2.2 Other Documents (See 6.3).

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#### 3. <u>REQUIREMENTS</u>

3.1 Item Definition The FFTF Prototype Pump's original construction requirements are defined in document HWS-1551. The basic pump frame for the ISIP is from the FFTF Prototype Pump. This specification defines the design, fabrication, assembly and test for utilizing this pump frame with a new inducer/impeller/diffuser and necessary adapter hardware in place of the original impeller. For a complete description of the FFTF Prototype Pump, refer to referenced Document a., (CMM-051-00-005, hereinafter referred to as OMM).

3.1.1 Interface Definition The physical interface of the ISIP components are defined by ICD N266E000002. Changes in the interface shall be minimized wherein the pump shall be capable of being restored to its original configuration.

3.1.1.1 Impeller Mounting Mounting of the inducer/impeller on the existing taper at the lower end of the pump shaft shall be designed for controlled advance onto the taper such that the stress criteria of Table 3-III are not exceeded.

3.1.1.2 Axial Clearance At least one-half inch axial clearance shall be provided by the design above and below all rotating members.

3.1.1.3 Radial Clearance Radial clearance at the wear rings and at the inducer vane tips shall be based on assembly stackup of tolerances for the parts determining the clearance. At least 0.015 inch margin shall be provided against rubbing when the pump is operating with the most adverse radial tolerance stackup and is concurrently subject to distortion resulting from thermal transient tests.

#### 3.1.1.4 Tool Interfaces

- The inducer, impeller, adapter diffuser, and other a. new parts (weighing in excess of 10 pounds) designated for installation into the existing pump frame, shall be designed to permit lifting and handling in accordance with the requirements of RDT F 8-6. In addition, the parts shall be designed to interface with the special assembly tools as part of the assembly procedure described in the specially addended version of the OMM.
- b. Tool interface requirements shall be met by designing the parts to interface with existing,



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modified, or new special assembly tools (refer to 3.4.6).

c. The bearing support flange (approximate weight 10,000 pounds) shall be positioned and supported from the impeller (or shaft) during upending and installation of the shield plug/support cylinder (SP/SC) over the shaft. During installation, the shaft assembly shall be supported from the lower end.

#### 3.2 <u>Performance</u>

3.2.1 <u>Hydrodynamic Design Point</u> The hydraulic design conditions for which the pump shall be designed shall be in accordance with Table 3-I.

3.2.2 <u>Range of Operation</u> The range of operation for which the inducer and impeller and associated components shall be designed is presented in Table 3-II, which also includes the design point, and is depicted in Figures 3-1A and 3-1B.

3.2.2.1 <u>Operating Life</u> The inducer and impeller shall be designed for testing over the operating ranges depicted in Figures 3-1A, 3-1B and under the suction conditions (NPSHA) given in 3.2.2.3. The design operating test time shall total 4,000 hours, minimum, of which 3000 hours shall be at design temperature and speed, and 1000 hours shall be at temperatures of 400F, 600F and 800F at speeds between 500 to 1110 rpm.

3.2.2.2 Flow/Speed Ratio The system resistance (R) curves shown on Figure 3-lA represent coincident curves of constant flow/speed (Q/N) ratio for the pump. The following table defines specified flow/speed ratios corresponding to the various system resistance designations:

System Resistance Designation (R)	R-0	R-1	R-2	R-3	R-4.	R-5	R-6
Flow/Speed Ratio (Q/N	0.0	6.576	8.243	9.459	13.063	16.216	22.400

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3.2.2.3 <u>Net_Positive_Suction_Head_Availaple</u>	The ne	t positive			

3.2.2.3 <u>Net Positive Suction Head Available</u> The net positive suction head available (NPSHA) to the pump varies with output flow rate at 1050F in accordance with the following relationship:

NPSHA =  $56.5126 - 1.125 \times 10^{-8}Q^2$  (ft)

- Where: NPSHA = Net Positive Suction Head at pump inlet nozzle, minus the elevation difference, in feet, from the inducer inlet elevation down to the inlet nozzle centerline. (ft)
  - Q = Output volumetric flow rate (qpm)
  - (NOTE: Inducer inlet flow may be slightly higher than pump outlet flow due to internal leakage.)

#### 3.2.3 <u>Suction Performance</u>

3.2.3.1 <u>Design Flow NPSH</u> The pump shall be designed to operate with a net positive suction head of 12.8 feet, or less, at design speed, flow and temperature and with less than 3 percent reduction of head due to cavitation (refer to Explanation note 6.4a).

3.2.3.2 <u>Runout Flow NPSH</u> The pump shall be designed to operate at 18,000 gpm at design speed and temperature, with less than 3 percent reduction in head due to cavitation, when the suction conditions correspond to minimum submergence (refer to Explanation note 6.4b).

3.3 <u>Design Requirements</u>

3.3.1 <u>Stress Criteria</u> All parts (except instrumentation) shall be designed and analysed to meet the structural design criteria of Table 3-III.

3.3.1.1 <u>Steady-State Conditions</u> A reduction of the structural design criteria in Table 3-III shall be determined and the reduced criteria used for design under steady-state temperature conditions.

3.3.1.2 <u>Thermal Transients</u> The design shall be analyzed to identify which of the test thermal transients described in Table 4-II may be run without exceeding the structural design criteria of Table 3-III. The pump shall be analyzed subsequently to determine which thermal transients, listed in

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HWS-1551, the pump could withstand without exceeding the structural design criteria of Table 3-III.

The foregoing analysis shall be limited to use of elastic and simplified inelastic methods. Those areas where inelastic analysis would be required shall be identified.

#### 3.3.2 <u>Mechanical Load Criteria</u>

3.3.2.1 <u>Unbalanced Rotating Loads</u> The impeller and inducer design shall include provisions to permit dynamic balancing of the inducer-impeller assembly within 3.5 inch-ounces at each balance plane when mounted on a balance spindle.

3.3.2.2 <u>Radial Thrust Loads</u> Design of the inducer, impeller, and diffuser adapter shall be such that polar symmetry is maintained.

3.3.2.3 <u>Axial Thrust Loads</u> The wear ring diameters shall be designed to maintain axial thrust between the limits of 70,000 pcunds upward and 40,000 pounds downward over the operating range of the pump. Axial thrust calculations shall consider the possibility of at least ten percent difference between the static head at the tip of the lower (front) shroud and static head at the tip of the upper (back) shroud. Balance piston arrangements based on variation of axial clearances shall not be used to balance axial thrust.

3.3.3 <u>Design for Recirculating Flows</u> The design shall include internal passageways to permit ducting flow from the lower end of the hydrostatic bearing and recirculating flow from the back wear ring of the impeller, to a low pressure region of the inducer/impeller assembly. Flow from the bearing will be 100 gpm at design conditions. To minimize distortion under thermal transient conditions, passageways shall be symmetrical about the pump axis. At design operating conditions, passageways shall be sized to maintain the static pressure below the hydrostatic bearing to less than 18 psi above the inducer inlet pressure.

3.3.4 <u>Drainability and Venting</u> All internal parts shall be designed for self draining and venting. The use of drain heles and vent holes at specific locations shall be acceptable providing flow through these holes is considered in the hydrodynamic design. Concurrent draining and venting through the same holes shall not be permitted.

3.3.5 <u>Threaded Fasteners</u> All internal threaded fasteners shall be positively locked to prevent loosening (friction

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locks are not acceptable), and the head of the fastener shall be trapped to prevent entry into the fluid stream in the event of failure of the fastener shank. Unless otherwise specifically required, threads shall be the coarse thread series (UNC) and shall have a nominal diameter of one-half inch or greater. Mating surfaces of internal and external threads shall be of different materials.

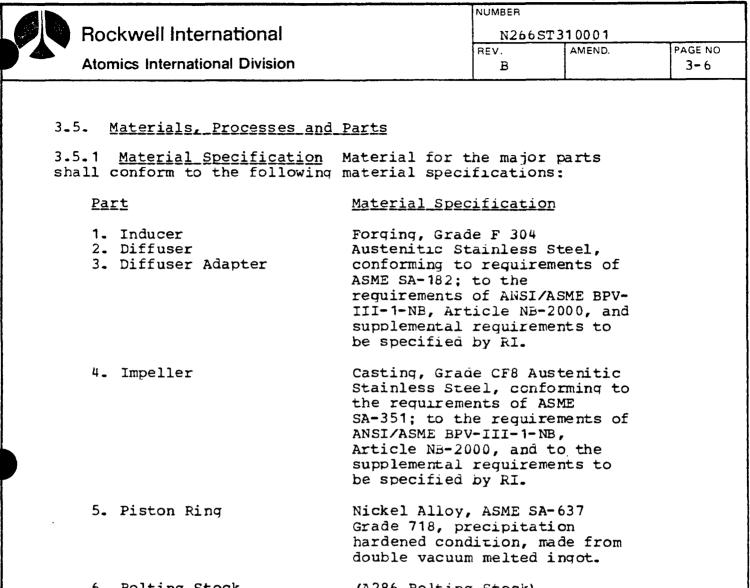
3.3.6 Special Tool Design Special tools, or equipment to permit adapting existing special tools to the ISIP, shall be provided as required to permit handling and assembly of the pump internals. The design, fabrication, and proof testing of all lifting tools shall conform to the requirements of RDT F 806 for tackle. Support stands and similar static equipment shall meet the requirements of the Uniform Building Code for this region. Tool surfaces designed to contact the stainless steel pump parts shall be corrosion resistant. Stainless steel, nickel plate, chrome plate or nylon are chemically suitable contact surface materials. The design of the special tools shall permit assembly of the ISIP as described in the OMM (refer to 6.3a).

3.3.7 Critical Speed The calculated critical speed of the rotating assembly, including the ISIP inducer and impeller, shall not be more than 5 percent below the calculated critical speed for the FFTF Prototype Pump.

3.3.8 <u>Direction of Rotation</u> The inducer and impeller shall be designed to rotate counterclockwise when viewed from the pump drive end (top).

Natural Resonant Vibration The ISIP components 3.3.9 (inducer/impeller, diffuser and diffuser shroud) shall be designed to avoid resonant vibration while under the influence of flow induced pressure pulses (such as the vortex shedding frequency of labyrinth seals) and mechanically induced pressure pulses (such as primary rotating and impeller-todiffuser blade passing frequency).

3.4 Identification and Marking Identification and marking of parts shall be according to applicable detail design drawings.



6. Bolting Stock (A286 Bolting Stock) (Threaded fasteners, shaft keys, etc.)
6. Bolting Stock (A286 Bolting Stock) Conforming to ASME SA-638, Grade 660, Type 2 or ASME SA-453, Grade 660, Class B.

3.5.2 <u>Fluid Properties</u> The thermophysical properties of sodium to be used for this design and subsequent test evaluation shall be according to ANL-7323.

#### 3.5.3 Fabrication Procedures

a. Equipment Protection Extreme care shall be exercised to protect all surfaces from contamination during fabrication, handling, testing, and storage. Precautions necessary to ensure such protection shall be incorporated in the detailed component or fabrication procedure. Detailed procedures for cleanness control, in-



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process cleaning, and final cleaning of all parts, components, and assemblies shall be utilized.

b. Supplemental Heat Treatment After rough machining and prior to final machining, the inducer, impeller, diffuser, and adapter shall be given a supplemental heat treatment in order to develop dimensional stability.

These heat treated parts shall be subsequently protected from moisture which can promote intergrannular attack or stress corrosion. Contaminates to be avoided include oxidizing agents (such as nitric acid), halide environments (such as salt air or fluorides from weld fluxes or smoke) and caustic solutions (such as hydroxides).

- c. Surface Finish The definitions, measurement and designation of surface finishes shall be in accordance with ANSI B46.1.
- d. Lock Welds All lock weld (bolt capture) joints shall be in accordance with MW1-08061-000. Tock welds shall be visually examined under 5X magnification for evidence of cracks.
- Special Processes Any nonstandard fabrication e. processes employed shall be identified and a procedure for their application specified. Examples of nonstandard processes are electrodischarge or electrochemical machining and electron beam welding.
- f. <u>Cleaning</u> All cleaning shall be in accordance with the requirements of RI Specification N001A0110001. Final cleaned surfaces shall meet the requirements for cleanness Level 3. All cleaning procedures shall be submitted and approved by RI.
- Lubricant/Coolant A lubricant/coolant may be q. employed during machining operations provided it does not contaminate any crevice or inacessible area that cannot be subsequently cleaned, and provided the lubricant is removed after completion of all operations. Lubricants used on austenitic stainless steel shall have a sulfur or chloride content of less than 5,000 ppm.



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h. <u>Thread Lubricant</u> Thread lubricants shall be used during assembly. The following lubricants, or equivalent shall be specified on assembly drawings.

#### <u>Type</u>

Never-Seez Pure Nickel . Special, Nuclear Grade	Never-Seez Compound Corporation, Broadview, Ill.					
N-5000 Nuclear Grade	Fel-Pro Incorporated,					
Fel-Pro	Skokie, Ill.					



TABLE 3-I

#### HIDRODYNAMIC DESIGN POINT

Flow Rate	14,500 gpm
Total Head Across Pump	500 ft
Shaft Speed	1,110 rpm
*Minimum Submergence (above impeller discharge centerline)	4 ft
**Minimum Cover Gas Pressure (at minimum submergence)	36 ft Na absolute (at 1050F)
Fluid	Sodium
Fluid Inlet Temperature	1050F
Fluid Density	50.97 lb/ft3

\*Refer to 3.2.2 for normal operating conditions.

\*\*Resulting NPSH is approximately 41.3 ft, referred to inducer inlet elevation. This value includes pump inlet velocity head, but does not include internal suction elbow losses.

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	TABLE 3-II							
	PERFORMANCE REQUIREMENTS							
	FERFORMANCE REQUIREMENTS							
1	Design flow rate, gpm		14500					
2	Total head at design flow rate, ft.		500					
3	Design speed, rpm		1110					
4	Minimum sodium level above impeller							
	discharge centerline, ft.		4					
5	Minimum cover gas pressure at minimum sod level, ft of sodium absolute, 1050F	Lum	36	PAGE NO 3-10 4500 500 1110 4 36 ote 1 1400 te 2 (max) 8000 375 1050 350 11 te 5				
6	Maximum required NPSH at design flow rate,	ft.	Note 1					
7	Maximum required NPSH at runout flow rate,	ft.	Note 1					
8	Flow rate, at pony motor speed, qpm (maxim	REV.         AMEND.         PAGE NO 3-10           14500         500           500         1110           4         4           odium         36           ce, ft.         Note 1           ce, ft.         Note 1           ce, ft.         Note 1           ce, ft.         Note 1           scimum         1400           Note 2         5 (max)           18000         375           4)         1050           ft.         11           Note 5         11						
9	Total head at shutoff, ft. (maximum)		AMEND. PAGE NO 3-10 14500 500 1110 4 36 Note 1 Note 1 1400 Note 1 1400 Note 2 5 (max) 18000 375 1050 350 11 Note 5					
10	Total head (at pony motor speed) ft. (see	Note 3)	5 (max)					
11	Runout flow rate, gpm		18000					
12	Runout head, ft. (minimum)		375					
13	Maximum inlet temperature, F (See Note 4)		1050					
14	Minimum inlet temperature, F		350					
15	Allowable change of free-surface level, ft		11					
16	Performance rangeability N		Note 5					
17	Maximum shaft horsepower (shp) at design speed (1100 rpm) and design flow (14,500 g with 400F sodium	Jbw)	2500					
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NOTES:

1. The minimum available NPSH at a flow of 18,000 qpm shall be that corresponding to minimum cover gas

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pressure occuring concurrently with minimum sodium level. The pump shall not lose more than 3 percent head due to cavitation under these conditions and over the range of operation as specified in 3.2.2.

- 2. The pump shall have a stable (negative slope) headcapacity curve between flows of 8,000 to 18,000 gpm at design speed. A runout head of greater than 375 ft. is specified to assure smooth, stable operation at runout.
- 3. At pony motor operation, the maximum allowable head shall be 5 ft. A design objective at pony motor speed is to meet 4 ft. head at a low of 1,100 to 1,450 gpm.
- 4. For the maximum outlet temperature, the heat input from the pump shall be taken into account.
- 5. The pump shall be capable of continuous operation between the boundaries shown on Figure 3-1A.

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	STRUCTURAL D LIMITS FOR DES IMPELI	IGN	OF	THE	E IS	SIP	IN					
. <u>HIC</u>	H_TEMPERATURE_CRITE	RIA	<u>{≧8</u>	<u>00</u>	<u>F)</u> ,							
	Use Code Case N-47	(1592	2-10)	) (a	s au	iida	nce	)				
A.1 <u>P</u> 1	imary Stress Limits											
.1.1	<u>Design_Condition</u>											
	Design Pressure + D Load (includes seis			nd +	D€	esi	gn	Mec	han:	ical		
	P <sub>M</sub> ≤ S <sub>o</sub>											
	$P_{M} + P_{b} \leq 1.5S$	0										
.1.2	Normal_Operating_Co	ndit	tior	<u>15</u>								
	Pressure + Mechanic	al 1	Load	ls +	De	ad	We	igh	t			
	P <sub>M</sub> ≤ S <sub>Mt</sub>											
	P <sub>L</sub> + P <sub>b</sub> ≤ kS <sub>Mt</sub>											
	$\begin{array}{ccc} P_{L} + \underline{P}_{L} \leq S_{t} \\ K_{t} \end{array}$											
.2 <u>S</u> €	<u>condary Stress Limi</u>	ts										
.2.1	Strain_Accumulation	<u>Lir</u>	<u>nits</u>	Ē								
	Average Inelas	tic	Str	ain	1 ≤					mate	erial	
	or											
	$X + Y \leq S_a/S_y$											
	$S_a = 1.25 S_t$ (	maxi	imun	a te	empe	era	tur	e f	or '	104 ł	nours)	
		aver							~	•		
	$S_{y} = \text{Yield at}$ $\frac{\mathbb{I}_{MAX} + \mathbb{I}}{2}$		aye	e te	mpe	era	tur	eo	î cy	vcTe		

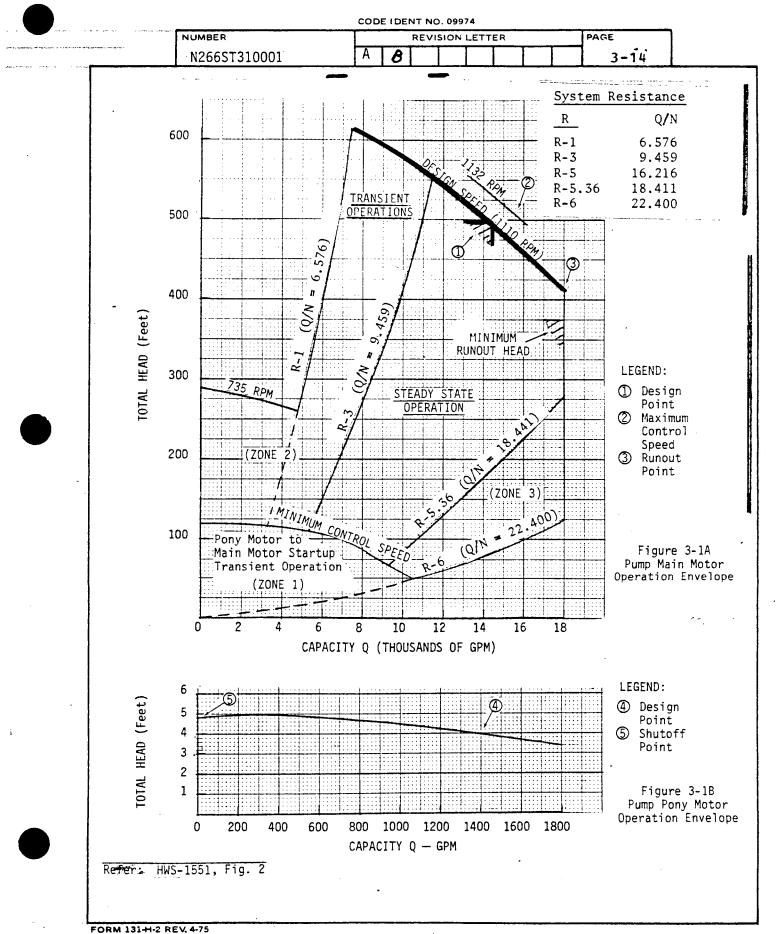
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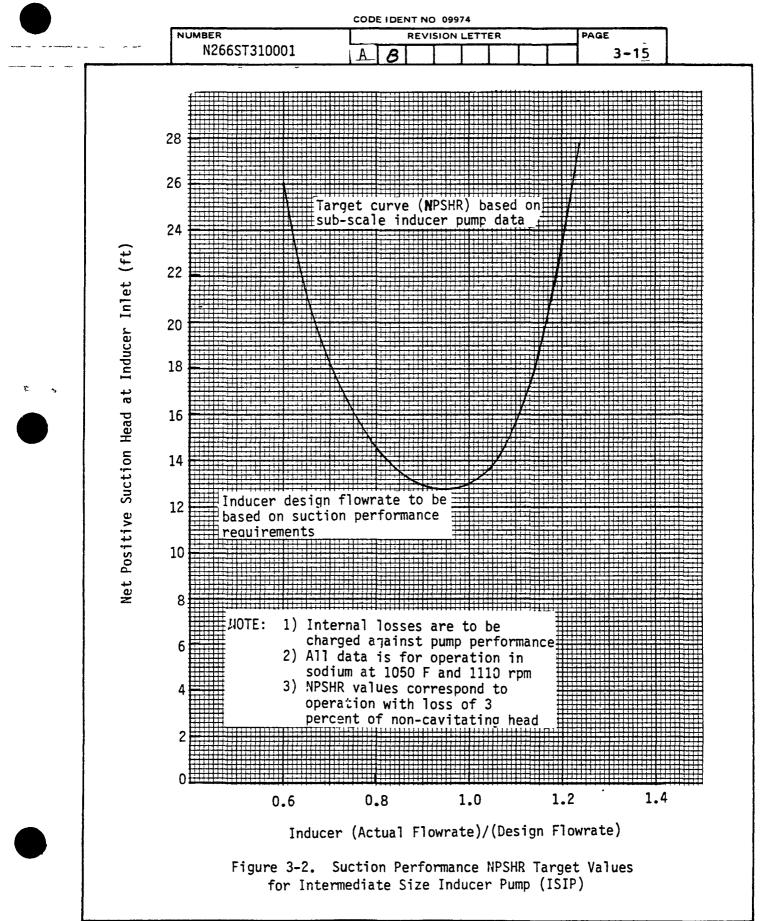
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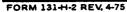
# **Rockwell International Corporation Atomics International Division** CODE IDENT NO 09974 REVISION LETTER PAGE NUMBER 3-13 N266ST310001 B A TAELE 3-III STRUCTURAL DESIGN CRITERIA STRESS LIMITS FOR DESIGN OF THE ISIP INDUCER, IMPELLER, AND DIFFUSER (continued) $X + Y \leq 1$ $T_{M_1N} \leq \text{temperature at which } S_M = S_t \text{ at } 10^5 \text{ hours}$ A.2.2 Creep Fatigue Limits $\begin{array}{ccc} \Sigma \underline{b} & + & \Sigma \underline{t} & \leq & 0.6 \\ Na & & Td \end{array}$ Figure 3-3 shall be used as the design fatigue curve for pressure or other high-cycle oscillations. B. LOW TEMPERATURE CRITERIA (<800°F) Section III, Subsection NB (as guidance) B.1 Primary + Secondary Stress Limits B.1.1 Design Condition Design Pressure + Design Dead Weight + Design Mechanical Load (include seismic) $P_M \leq S_M$ $P_L + P_b \leq 1.5 S_M$ B.1.2 Normal Operating Condition Pressure + Thermal + Mechanical Load + Dead Weight $P_L + P_h + Q \leq 3S_M$

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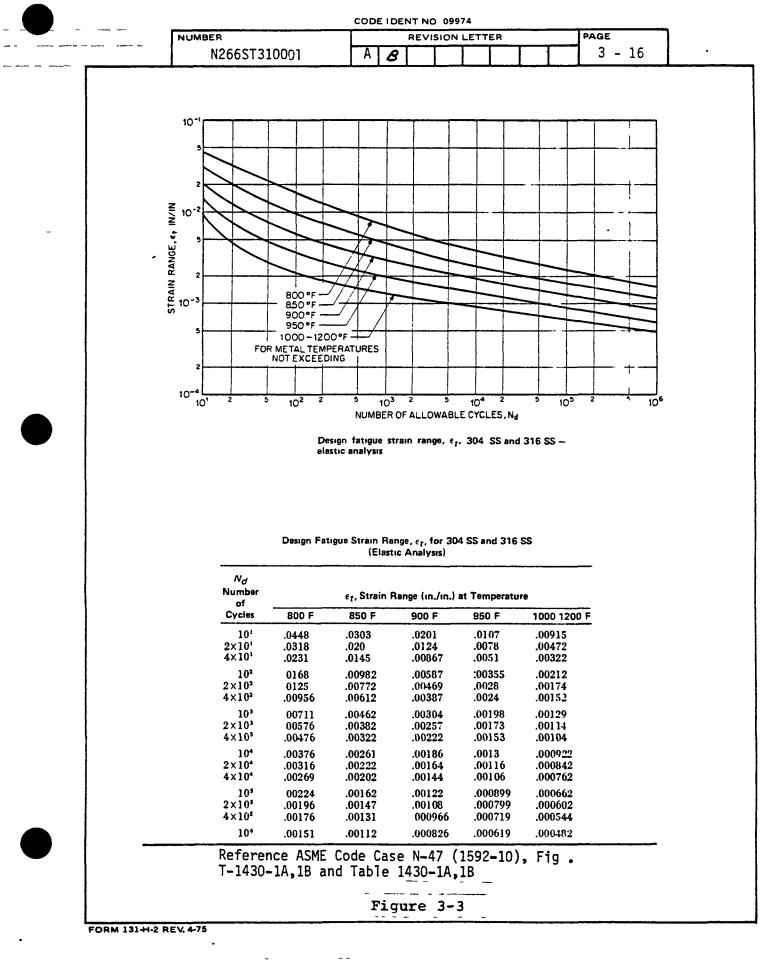


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### 4. QUALITY ASSURANCE PROVISIONS

4.1 Quality Assurance Program A quality assurance program shall be established and maintained meeting the requirements of RDT F 2-2, Section 1, Section 2 (except 2.5.1), Section 3 (except 3.3.5 and 3.9), Section 4 (except 4.12), and Section 5 (except 5.3, 5.9 and 5.14).

4.2 <u>Design Verification</u> Compliance with the design requirements of Section 3 of this specification, shall be demonstrated by analysis and accepted procedures (refer to Table, Appendix 20) and assessed by an independent formal design review.

### 4.3 <u>Quality Examination</u>

4.3.1 <u>Visual and Dimensional Examination</u> All fabricated parts shall be subjected to a visual examination and a dimensional check to verify compliance with drawings and applicable specifications.

### 4.3.2 Special Measurements and Recordings

4.3.2.1 <u>Inducer/Impeller Surface Measurements</u> Prior to initial assembly and after post-test cleaning, coordinates of the inducer blade surfaces shall be measured and recorded in accordance with inspection requirements to be provided in the addendum to the OMM (refer to 6.2.3). In addition to measurement of inducer blade, surface coordinates, photographs and cast replicas of the inducer and impeller blade surfaces, including those regions near the leading and trailing edges, shall be taken before and after the test and maintained as test records.

4.3.2.2 <u>Natural Resonant Vibration Measurement</u> The natural vibration frequencies of the individual ISIP components (inducer, impeller, diffuser and diffuser shroud) shall be measured and recorded prior to assembly to conform to requirement 3.3.9.

4.3.2.3 <u>Fit and Clearance Measurements</u> The assembly fit of the bearing support assembly, diffuser, diffuser shroud, shroud insert and static hydraulics shall be physically checked. The check shall include measurement and recording of minimum and maximum clearances between the shroud lower end (inducer tunnel) and the bore at the suction elbow upper end. In addition, the radial play (looseness) between the bearing support and static hydraulics shall be measured.

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### 4.4. <u>Test Requirements</u>

4.4.1 <u>Test Scope</u> Testing is considered to start with the recording of the receipt of inspection data and to continue through assembly, installation, performance testing, removal, cleaning, and post-test inspection. All information regarding the condition or performance of the pump and its auxiliaries, whether or not the information concerns the inducer, shall be considered as test data.

4.4.2 <u>Assembly and Installation</u> Pump parts shall be received, inspected, and assembled in accordance with the addended OMM by the testing organization. Following assembly of the internals, the internal subassembly shall be installed in the pump tank, then installation of the motor and connection of auxiliaries completed. Assembly and installation shall be performed in accordance with specific procedures in accordance with OMM requirements.

4.4.2.1 <u>Special Tools</u> In addition to the operating equipment, there is a set of special tools used for assembly and disassembly of the pump. These tools are "pump peculiar," designed specifically to meet pump reguirements. Other general purpose and "facility peculiar" tools are not included.

For complete description of the special tools, refer to the OMM.

4.4.3 <u>Instrumentation and Controls</u> Instrumentation to be used for sodium testing of the ISIP shall be the same, or equivalent to, instrumentation used for testing the prototype FFTF pump during Phase B tests, with the exception of the midshaft bearing and MTI probes which will be deleted. The complete list of instrumentation is described in N266RFT000001.

4.4.3.1 <u>Internal Instrumentation</u> Internal instrumentation, consisting of thermocouples, accelerometers, and proximity probes, and including necessary clips and penetration seals, will be supplied by RI for installation by the ETEC testing organization.

4.4.3.2 <u>External Instrumentation Controls and Equipment</u> External instrumentation, controls and auxiliary equipment (4.4) shall be supplied by the ETEC testing organization.

4.4.4 <u>Auxiliary Equipment</u> Auxiliary equipment requirements, in addition to the liquid rheostat shall include:

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- a. The liquid rheostat control cabinet (C201A).
- An alarm/monitor control cabinet (C999 sometimes referred to as (C201B) which includes an annunciator panel, lube oil and motor temperature indicators and which functions as an interface junction between the pump and the facility control system.
- c. An oil lubrication system to provide oil circulation, cooling and filtration for the upper, oil lubricated bearings. Includes indicators of temperature, pressure, and level to monitor performance of the oil lubrication system.

4.4.5 <u>Performance Testing</u> After all equipment has been installed and preoperational checkouts completed per the OMM, pump performance tests shall be performed. The performance test shall repeat those selected tests performed during Phase B testing of the prototype pump including a locked rotor impedance test (refer to WDTRS 25.14) in accordance with the Request for Test (refer to 6.2.2) and detail test procedures to be prepared by the ETEC test organization. The maximum test temperature shall be 950F. The sequence of tests shown in Table 4-I shall be used. Temperature ranges and rates for thermal transient testing shall be as listed in Table 4-II.

For the cavitation performance tests, the suction pressure shall be reduced to the point of 3.0 percent reduction in total head across the pump at 14,500, 16,000, and 18,000 gpm.

After cavitation performance testing, a 2,000 hour design pcint endurance test at 950F, 14,500 gpm and full speed shall be conducted with a 200 percent NPSH margin over the value determined for a 3 percent reduction in non-cavitating head. Following the design point endurance test, a 300 hour offdesign endurance test shall be run at 950F, 14,500 gpm and speed of 894 rpm with the same NPSH as was used for the design pcint endurance test.

Percent NPSH margin shall be calculated using the following equation:

%M = 100 (NPSHT/NPSHR - 1)

Where: %M = Percent NPSH margin

NPSHT = NPSH to be provided to the pump during the test

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NPSHR = NPSH required to limit pump head reduction to 3% of the non-cavitating head under the same speed, flow and temperature conditions. (test value)

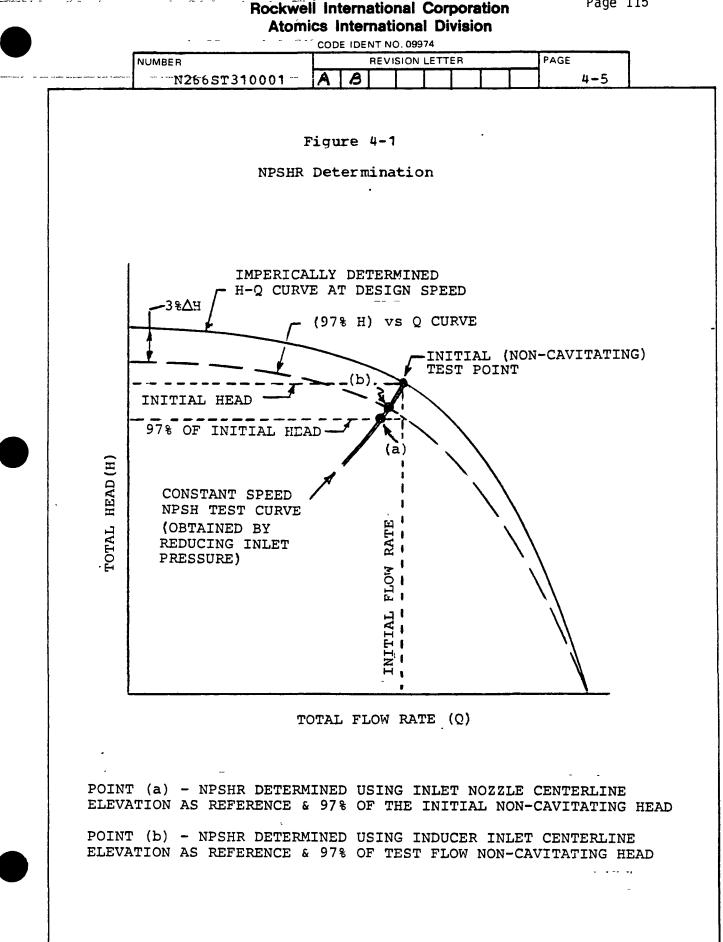
4.4.5.1 <u>Determination of NPSHR</u> Pump tests to determine the net positive suction head required (NPSHR) to limit the cavitation head loss to 3 percent, shall be performed at design speed (1110 rpm) and design temperature (950F) at initial measured flow rates of 14,500, 16,000 and 18,000 gpm. The tests shall be run with fixed (constant) flow impedance. The NPSHR shall be reported for each initial measured flow by two methods (refer to Figure 4-1):

- a. <u>Inlet Nozzle Centerline Elevation as Reference</u> NPSHR shall be determined at the measured flow corresponding to a 3 percent head drop (point (a) of Figure 4-1) below the initial (non-cavitating) head at the initial flow. NPSH shall be referenced to the inlet nozzle centerline (refer to Explanation 6.4c).
- b. Inducer Inlet Centerline Elevation as Reference NPSHR shall be determined at the measured flow corresponding to a 3 percent head drop (point (b) of Figure 4-1) at the actual (not initial) flow (refer to Explanation 6.4d). NPSH shall be referenced to the inducer inlet elevation (elevation at the lower end of the inducer blade tip).

4.4.5.2 <u>Test Success Criteria</u> Verification of design shall be by inspection of the impeller and inducer after testing. The criteria for success shall be the absence of visual evidence of material damage (which can be attributed to cavitation) when reviewed with the unaided eye.

4.4.6 <u>Cleaning and Disassembly</u> Removal from the pump tank, cleaning and disassembly of the ISIP shall be performed in accordance with the addended OMM using detail procedures prepared by the test organization. During removal, the pump internals shall be maintained in an inert atmosphere until cleaned. The alcohol cleaning process shall be used. Following general cleaning, disassembly and spot cleaning (as required) shall be completed. All disassembled parts shall be inspected and inspection data recorded on special data forms provided in the addended OMM.

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				<u> </u>	<b>.</b>	
		TABLE	l la T			
		TEST SE	QUENCE			
	equence	Test Identification				
]	Number	(WDTRS 25.14)	Test Des	cription		
	1.	7.2.1	Pump Assembly	and Insta	allation	
	2.	7.2.2	Auxiliary Sys	tem Check		
	3.	7.2.3	Preheat and S	odium Fill	L	
	4.	7-2-4	Initial Start During Wettin		eration	
	5.	7.2.5.4	Pony Motor Fl	ow Scan		
	6.	7.2.5.5	Main Motor (R	4) Speed S	Scan	
	7.	-	500 rpm Flow	Scan(1)		
	8.	7.2.7.1	700F Checkout			
	9.	7.2.7.2	750F Checkout Endurance Tes		l Scan &	
	10_	7.2.7.4	800F Checkout			
	11.	7.2.7.5	850F Checkout	and Speed	l Scan	
	12.	7.2.7.8	900F Checkout		-	
	13.	7.2.8.1	950F Checkout Endurance Tes		l Scans &	1
	14.	7.2.11.B	Cavitation Pe	rformance	_	1
	15.	-	2000 Hour Des Test at 200%			1

(1) Test needs to be based on results of Pony Motor Flow Scan.

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		<u> </u>			
		SEQUENCE			
		tinued)			
Sequence	Test Identification				
Number	(WDTRS 25.14)	Test Des	scription	1	
16.	-	3000 Hour Off Test at Reduc			
17_	7.2.7.3	Low-Temperatu Transients 20			
18.	7.2.7.6	Mid-Temperatu Transient 204		al	
19.	7.2.7.6	High-Temperat Transients 20			

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### TABLE 4-II

TEST THERMAL TRANSIENTS

Event	Initial(2)(3) Speed/Flow (1) (rpm/gpm)	Initial Temp. (F)	Final Temp. (F)	Temp. Change (F)	Trans Rate (F/sec)	Main Drive Trip	Soak Time (hr)
202	1,110/14,500	750	600	- 150	-1.5	No	6
203	1,110/14,500	500	650	+150	+1.5	No	6
204	1,110/14,500	850	650	-200	-2.0	No	8
207	1,110/14,500	1050	720	-330	-1.2	No	12
208	1,110/14,500	1050	825	-225	-2.0	No	9
210	1,110/14,500	1050	900	-150	-3.0	No	6

(1) Reference WDTRS 25.14.

- (2) Initial speed and flow is shown at the beginning of the thermal transient.
- (3) All thermal transient events shall be run with constant speed and discharge throttle valve settings, and with a constant sodium level within facility level control limits.

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5. <u>PACKAGING AND PACKING</u> Finished component castings, forgings and machined parts shall be packaged and packed in accordance with the requirements of RI Specification N001A0116001. Packaging to Level A shall be required to maintain a dry argon purge gas environment during shipment and storage. Packing to Level B applies using wood packing crates.

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### 6. DOCUMENTS, DATA, AND REPORTS

6.1 <u>Drawings</u> Drawing requirements for the ISIP shall include the following:

- a. General Assembly Drawing
- b. Engineering Layout Drawing
- c. "Spot" Layout Drawings (as required)
- d. Detail Drawings
- e. Interface Control Drawing

6.1.1 <u>General Assembly Drawing</u> The general assembly drawing shall be the top level drawing for the ISIP, through which access to all other drawings can be attained. This drawing shall be a modified or addended version of the existing Westinghouse Drawing 114E829 for the FFTF Prototype Pump.

6.1.2 Engineering Layout Drawing The engineering layout drawing shall be a cross-section assembly drawing showing assembled dimensions, tolerances, and clearances for the inducer/impeller and its hydrodynamic surroundings. This drawing shall have sufficient dimensional data and auxiliary views to permit engineering stress and thermal analysis. The layout drawing shall be maintained in an up-to-date status as new or revised dimensional data is received.

6.1.3 <u>Spot Layout Drawings</u> Spot layout drawings shall be prepared as required to show assembled dimensional information in local regions. These drawings shall be for temporary use in providing up-to-date engineering information as the design develops and as supplements to the overall layout drawing between update periods.

6.1.4 <u>Detail Drawings</u> Detail drawings shall be prepared for each new part showing all the requirements for fabricating and inspecting the part.

6.1.5 <u>Interface Control Drawing</u> An interface control drawing shall show all dimensional and functional interface data required for the design of new parts. The source of all data shall be referenced on the drawing.

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### 6.2 Documentation

6.2.1 <u>Reports</u> The following reports shall be prepared to record and support the design, analysis, and test effort:

- a. Hydrodynamic design report
- b. Steady-state stress analysis report
- c. Final design report, including thermal transient analysis
- d. Interim test reports
- e. Final test report, including post-test inspection
- f. Status reports, weekly and monthly, to report project status with relation to established milestones, recent accomplishments, and problem areas.

6.2.2 <u>Request for Test</u> A Request for Test shall be prepared in accordance with requirements of the test facility, describing all those tests to be run and the sequence of testing to be used. In addition, the Request for Test shall define restrictive limits, non-test operation of the pump, and data recording and reporting requirements. The Request for Test shall contain sufficient detail to permit preparation of test procedures by the testing organization. The Request for Test shall include the requirement for determination of locked rotor impedance of the pump.

6.2.3 <u>Operations and Maintenance Manual (OMM) Addendum</u> An addendum shall be prepared for the existing OMM (refer to document a.) to cover assembly, disassembly, and inspection of those new parts used to construct the ISIP from the existing prototype pump. The addendum shall include graphic material and detail instructions for the use of special tools at least to the extent presently provided in the existing manual.

# 6.3 <u>Reference Documents</u>

 a. OMM-051-00-005, Rev. 2, Westinghouse Electric Corporation Electro-Mechanical Division (WARD), "Operation and Maintenance Manual, Liguid Metal Coolant Pump, Model LMP-1, for the Fast Flux Test Facility (Prototype and Primary) Contract E(45-1)-2170."



- b. 77,LMEC-DRF-2476, letter from R.E. Fenton (LMEC) to T.A. Mangelsdorf (HEDL), "FFTF Prototype Pump -Phase B - Minimum NPSH Demonstration at Runout Flow and Pump Cavitation Performance at Selected Flowrates," July 19, 1977.
- c. Engineering Memorandum 4438, Westinghouse Electric Corporation, E-M Division, "Stress Analysis of the FFTF Impeller, FFTF Primary Pump," S.O. U360, August 31, 1972, by R.J. Oleyar.
- d. FRA-152-3, Draft for RDT F 9-1, "Interim Supplementary Structural Criteria for Elevated Temperature," A.L. Snow, November 6, 1970.

#### 6.4 Notes

a. Explanation of 3.2.3.1.

The criterion for NPSH is defined as the total (static plus velocity) head available to the pump at the inlet nozzle\*, referred to the elevation of the inducer inlet, less the vapor head of the sodium, all expressed in feet of sodium at design temperature. Suction performance will be the prinicpal criteria to be used for evaluating the inducer/impeller assembly relative to a conventional impeller. Target values for the net positive suction head required (NPSHR) to limit the head loss to 3 percent cavitation are shown in Figure 3-2.

\*Subtract the elevation difference between the inducer inlet and the pump inlet centerline.

b. Explanation of 3.2.3.2.

Minimum submergence comprises 4 feet above the impeller discharge centerline concurrent with a minimum cover gas pressure of 36 feet absolute of sodium at 1050F. Corresponding conditions for this criterion are defined as having the sum of the submergence and absolute cover gas head equal to 40 feet.



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c. Explanation of 4.4.5.1a.

NPSHR, corresponding to method defined in 4.4.5.1a was reported in Reference Document b in 6.3.

d. Explanation of 4.4.5.1b.

This NPSHR valve will require determination of an imperical equation to represent the non-cavitating H-Q characteristic.

6.5 <u>Data Submittal</u> Data on subcontract purchase items (i.e., castings, forgings, and other machined parts), shall be submitted as defined in Appendix 10 and as specified in the applicable Procurement specification and purchase order. A supplier data list (SDRL) shall be prepared, as applicable, for each procurement specification.



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# APPENDIX 10

DATA SUBMITTAL REQUIREMENTS

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### APPENDIX 10 DATA SUBMITTAL REQUIREMENTS

10.1 <u>INTRODUCTION</u> This appendix establishes the requirement for data to be submitted to RI. It is comprised of two major elements: a set of general requirements which apply to all data items; a Supplier Data Requirements List (SDRI) \* which lists all of the data items required and provides the schedule and submittal requirements.

### 10.2 <u>GENERAL REQUIREMENTS</u>

### 10.2.1 Document Identification Requirements

10.2.1.1 <u>Title</u> Each document submitted shall bear a title which is descriptive of the contents and which distinguishes it from other similar documents.

10.2.1.2 <u>Numbering</u> All documents shall be numbered. The Supplier's document numbering system may be used provided that it prohibits the use of the same number on more than one document. The document number shall appear on each page of the document. The Supplier's drawing numbering system shall meet the following minimum requirements:

- a. The document number shall not exceed 15 characters. These characters may include numbers, letters, and dashes, with the following limitations:
  - (1) Letters I, O, and Q snall not be used.
  - (2) Letters shall be upper case (capitals).
  - (3) Numbers shall be whole Arabic (1, 2, 3, etc.) numerals. Fractional, decimal, and Roman numerals shall not be used.
  - (4) Blank spaces are not permitted.

Each page of multisheet documents shall be numbered. The first page shall indicate the total number of pages.

\*SDRL to be provided in applicable procurement document.

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10.2.1.3 <u>Revisions</u> The supplier's document revision system shall include a requirement for advancing the revision letter or number each time the document is revised and reissued.

10.2.1.4 <u>Identification</u> The first page of the document shall show the supplier's name and address (city and state are required, street address is optional), the document title, document number, current revision letter or number, and date.

# 10.2.2 Document Legibility and Reproducibility

10.2.2.1 <u>Clarity</u> All documents submitted shall be of sufficient clarity such that, when reproduced, lines, numbers, letters, and characters of the reproductions will be clearly legible and readable.

10.2.2.2 <u>Reproducible Copies</u> When reproducible copies of drawings are ordered, they shall be direct reading black-onwhite translucents. Sepias are not acceptable. Reproducibles shall be of such quality that when microfilmed, copies made from the microfilm meet the requirements of Paragraph 10.2.2.1.

10.2.2.3 <u>Subtier Documents</u> All documents forwarded from subtier suppliers shall comply with these same requirements.

10.2.3 <u>Contractual Due Dates</u> When the due date specified in the SDRL occurs on Saturday, Sunday, or a noliday, the due date becomes the subsequent working day. Unless otherwise specified, all schedules are expressed in calendar days.

#### 10.2.4 Preparation for Shipment

10.2.4.1 <u>Transmittal Letter</u> The supplier shall submit all data under a transmittal letter (or equivalent) which includes the following:

- a. RI Purchase Order number
- b. Purchase Order line item number
- c. SDRL line item number. (If the document satisfies more than one item number, then all applicable line item numbers will be listed.)
- d. Supplier document identification number, title, and revision or date



- e. Quantity and type (reproducible or nonreproducible) of data transmitted
- f. Action required (e.g., RI approval, review, or for information)

10.2.4.2 <u>Method of Transmittal</u> All reproducibles of "B" (11 in. by 17 in.) and larger sized drawings shall be shipped rolled (unfolded) inside mailing tubes. All prints of "B" and larger size drawings shall be folded to 8-1/2 in. by 11 in. and shipped flat. All "A" (8-1/2 in. by 11 in.) size documents shall be shipped flat.

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	••• ['	NUMBER N266ST310001	AB		N LETTER		-1	age 20-1
			APPI	NDIX 20				-
		TABLE	20-1. DESIG		ATION METH	OD		
=			1	Vorif	ication Me	thod		<u> </u>
~ P	aragraph	Requirement		Drawing	1	Tolerance		Comment
_			Analysis	Review	Checking	Stackup	Test	
3	3.1.1.1	Impeller Mounting						Procedure in
								OMM Addendum (6)
	3.1.1.2	Axial Clearance			X	X		
	3.1.1.3	Radial Clearance			X	X		RDT F 8-6
3	3.1.1.4(a)	Tool Interfaces		X	X			Stress Signoff
	(b)			x	x			
	(c)			x	x			
3	3.2.1	Hydrodynamic Design Point	x					Analysis (1)
3	3.2.2	Range of Operation	х.					Analysis (1)
3	3.2.2.1	Operating Life	X					Analysis (1,3) Report (2)
3	3.2.3.1	Design Flow NPSH	X				x	Analysis (1) Test (4.4.5.1) (4)
3	3.2.3.2	Runout Flow NPSH					x	Test (4.4.5 ) (4)
3	3.3.1	Stress Criteria	x					Analysis (3)
3	3.3.1.1	Steady State Conditions	x					Analysis (3)
3	3.3.1.2	Thermal Transients r	×					Analysis (5)
3	3.3.2.1	Unbalanced Rotating Loads		x	x			
3	3.3.2.2	Radial Thrust Loads	x	x	X			(a) Analysis (1) (b) Test Org & Insp
3	3.3.2.3	Axial Thrust Loads	x	X	x			Analysis (1,3)
3	3.3.3	Design for Recirculating Flows	x	x	x			Report (2)
3	3.3.4	Drainability and Venting	x	x	x			
3	3.3.5	Threaded Fasteners		x	x			
3	3.3.6	Special Tool Design	ļ	Х	x			OMM Addendum (6)
3	3.3.7	Critical Speed	x					
3	3.3.8	Direction of Rotation		x	x			
3	3.3.9	Natural Resonant Vibration	x				X	4.3.2.2
3	3.4	Identification and Marking		X	x			Procurement Spec
3	3.5.1	Material Specification		x	x			Procurement Spec's
3	3.5.2	Fluid Properties	x					Analysis, Reports (1,4
3	3.5.3	Fabrication Procedures		x				Procurement Spec's
Ē	Reference	Documents			• ···· • · · · · · · · · · · ·	-	4	· · · · · · · · · · · · · · · · · · ·
	(2)De (3)S (4)F	ydrodynamic Analysis Report (Est. ssign Report (Est. Complete Dec.) H tructural Analysis Report (Est. Co inal Test Report (Est. Complete De est Transient Identification, TI (	by AI mplete 4/7/7 ec. 1980) by	'8) by Roc AI	ketdyne			

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# APPENDIX C

RECIRCULATING FLOW ANALYSES OF INTERMEDIATE SIZE INDUCER PUMP

ESG Document N266TI000003

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	,			N266ER000-001 Page 132
Γ	Rockwell International		NUMBER	REV LTR/CHG NO.
	Atomics International Division	PORTING DOCUMENT	N266TI000003	SEE SUMMARY OF CHG
Y	ROGRAM TITLE		DOCUMENT TYPE Technical Inform	
	Intermediate- Size Indu	er Pump	KEY NOUNS	
┢	DOCUMENT TITLE		Inducer Pump	~~ + ·
	Recirculating Flow Anal	vses of Intermediate	ORIGINAL ISSUE DATE April 20, 1978	
	Size Inducer Pump (ISIF		GO NO. S/A NO.	PAGE 1 OF
			00200 22000	TOTAL PAGES 17
	PREPARED BY/DATE	DEPT MAIL ADDR	09280 23000	REL. DATE 4-21-788K
	R. K. Hoshide RLHall	d 4/20/78731 JB05	SECURITY CL (CHECK ONE BOX ONLY)	ASSIFICATION (CHECK ONE BOX ONLY)
- <u>(</u> -	IR&D PROGRAM? YES NO		ERDA DOD	
1	APPROVALS	DATE Alinaky 4/20/28		DEFENSE
	L. Stabinsky		SECRET	INFO.
	T. J. Boardman	Dourdmon 4/20/78	AUTHORIZED CLASSIFIER	DATE
1	DISTRIBUTION	ABSTRACT		
F	K NAME MAI	IR .		
	T.J. Boardman(17)LB C. Dunn LB R. K. Hoshide JB0	flow analyses for the I (ISIP), from which the pump were obtained. labyrinth seals, which slanted and rounded ri design features should seal leakages and also characteristics. RESERVED FOR PROPRIETARY/LEGA	ntermediate-Size primary flowrate The front and reas incorperate stepp bs were checked. minimize the imp provide excellent	Inducer Pump s through the r impeller bed pockets with These seal beller labyrinth shutoff head
- L '	COMPLETE DOCUMENT IO ASTERISK, TITLE PAGE/SUMMAR OF CHANGE PAGE ONLY	This report was prepared as an States Government. Neither the nor any of its contractors, sub warranty, express or implied, sibility for the accuracy, comp apparatus, product or process not infringe privately owned r	E PATENT BRANCH account of work spons U. S. Government, nor a contractors, or their emp or assumes any legal leteness or usefulness disclosed, or represents	H, ERDA ored by the United ny of its employees oloyees, makes any liability or respon- of any information,

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### N266TI00003

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Recirculating Flow Analyses of Intermediate Size Inducer Pump (ISIP)

- Refs:
- (1) AI Drawing, "Intermediate-Size Inducer Pump Layout, ISIP," Drawing N266R000015, Issue 1, March 16, 1978
- (2) Allen, H. G., "Hydraulics Design Report FFTF Primary Pump," Engr. Memo 4476, Westinghouse Electric Corporation, Electro-Mechanical Div., Cheswick, Pennsylvania, January 15, 1973
- (3) Crane, "Flow of Fluids Through Valves, Fittings, and Pipe," Technical Paper 410, Crane Company, New York, N.Y., 1976
- (4) Internal Letter, "Pump Impeller Labyrinth Seal Study," DDR-712-3012, Isaacson, J., Rocketdyne Division, Rockwell International, Canoga Park, California, December 4, 1957
- (5) Crewdson, E., "Water-Ring Self-Primary Pumps," Vol. 170, No. 13, Institution of Mechanical Engineers, Westminster, South Wales, 1956

### INTRODUCTION

Recirculating flows of the ISIP were analyzed, and the calculations are shown in Appendix A. Secondary flow paths were first obtained before the primary flow rates through the pump were obtained. Analyses were also conducted to check the impeller labyrinth seal design and the drain and vent hole leakages.

#### SUMMARY

Recirculation flow rates were obtained and are shown in Figures 1 and 2. From these recirculation flows, the primary flow rates through the pump were obtained and are also shown in Figures 1 and 2.

The impeller labyrinth seal design incorporates good design features which are stepped pockets with slanted and rounded ribs. These features are especially helpful in minimizing the leakage flows for this large clearance seal application.

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### DISCUSSION

The ISIP layout drawing (Reference 1) was used to determine the various recirculation flow paths through the pump. Recirculation flows which remained the same from the previous pump design were obtained from Reference 2 and are shown in Figure 1.

Secondary flow paths were first obtained and are summarized below:

- 1.  $Q_1$ , leakage between suction nozzle outlet cone and inlet to suction elbow = 160 gpm.
- 2.  $Q_2$ , leakage through inlet static seal = 85 gpm.
- 3.  $Q_2$ , flow through drive shaft = 50 gpm.
- 4.  $Q_A$ , leakage through front impeller labyrinth seal = 648 gpm.
- 5.  $Q_{\rm F}$ , leakage through rear impeller labyrinth seal = 569 gpm.
- 6.  $Q_c$ , flow through hydrostatic bearing = 200 gpm.
- 7.  $Q_7$ , leakage through the diffuser and radial bearing housing = 131 gpm.
- 8.  $Q_{o}$ , leakage through discharge bellows static seal = 10 gpm.
- 9.  $Q_0$ , leakage through impeller return holes = 669 gpm.

These recirculation flow calculations are shown in the appendix, and the flows are shown in Figures 1 and 2. Friction factors used were obtained from Crane (Reference 3).

Impeller labyrinth seal leakage rates were checked using previous Rocketdyne empirical data (Reference 4) and results obtained from E. Jackson (addendum to Reference 5). The seal flow coefficient obtained for both front and rear labyrinth seals was 0.428 which is realistic for the present design. These labyrinth seal designs incorporate the step configuration from Reference 4 and the slanted rounded backs of the ribs from Reference 5. These features should minimize these leakages and also provide excellent shutoff head characteristics.

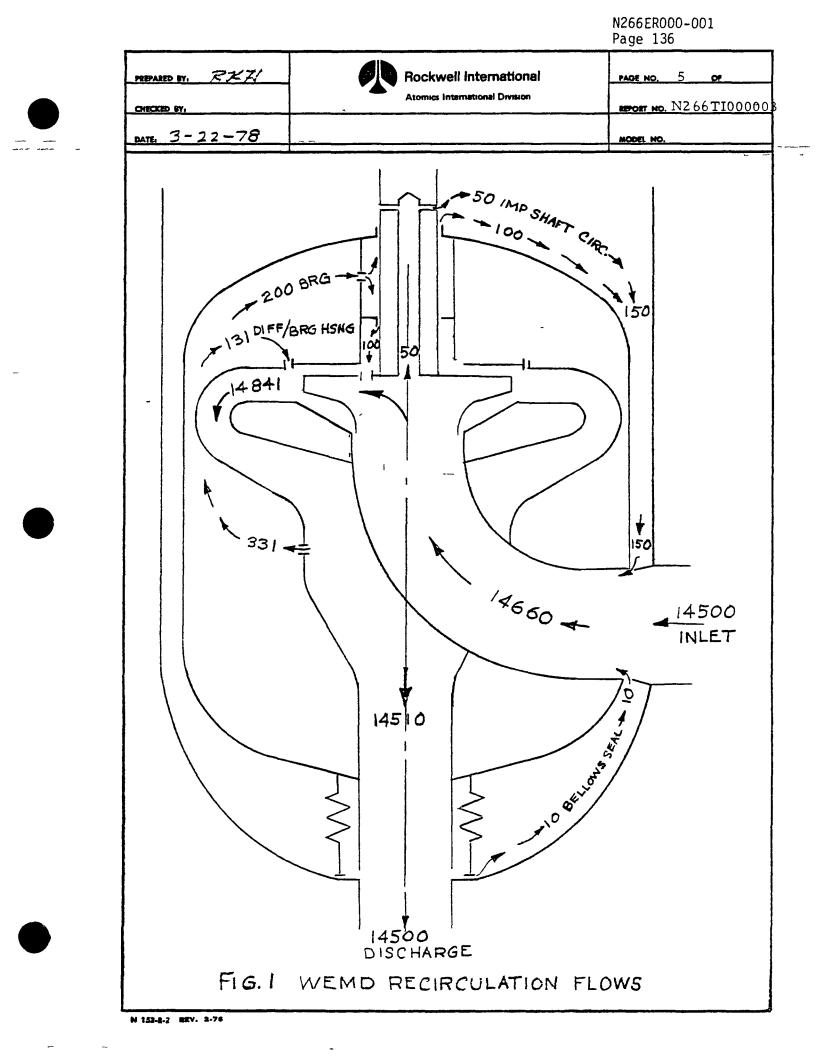
The shaft extension does not affect the flow rate through the drive shaft. Only a small decrease (less than 1/2 gpm), which includes the vent/drain holes contribution, is realized and was neglected for this analysis.

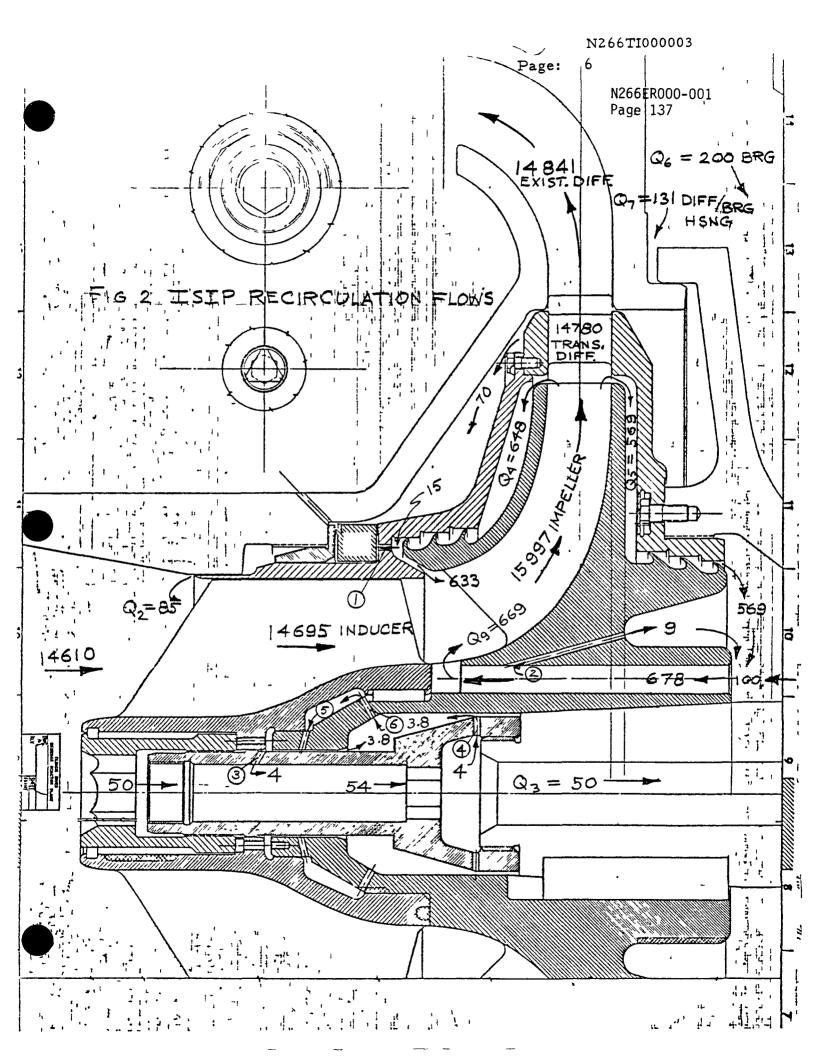
From this recirculation flow analysis, the following primary flow rates through the pump were obtained:

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- 1. Q disch., discharge flow rate = 14,500 gpm.
- 2. Q inlet, inlet flow rate = 14,500 gpm.
- 3. Q suct. el., suction elbow flow rate = 14,660 gpm.
- 4. Q ind., flow through inducer = 14,695 gpm.
- 5. Q imp., flow through impeller = 15,997 gpm.
- 6. Q trans. diff., flow through transition diffuser = 14,780 gpm.
- 7. Q exist. diff., flow through existing diffuser = 14,841 gpm.





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PREPARED BY, RXH	Rockwell International Atomics International Division	PAGE NO 7 OF
DATE: 3-22-78	APPENDIX A - FLOW ANALYSES	MODEL NO
I. THIS F. PRIMARY F. <u>A. THE</u> <u>AS FOLL</u> <i>I.</i> Q <i>I.</i> Q	OW ANALYSES INCLUDES: N OWS, 2) LABYRINTH SEAL, DRAIN, & V SECONDARY FLOW PATHS OWS: LEAKAGE BETWEEN SUCTI OUTLET CONE AND INLET ELBOW. LEAKAGE THROUGH INLES LEAKAGE THROUGH PRIVE SH LEAKAGE THROUGH FRONT ŽABYRINTH SEAL. LEAKAGE THROUGH REAR LABYRINTH SEAL. FLOW THROUGH HYDROSTA LEAKAGE THROUGH HYDROSTA LEAKAGE THROUGH THE DIF	SECONDARY & SECONDARY & ARE DEFINE ON NOZELE TO SUCTION T STATIC SEAL AFT. MPELLER IMPELLER IMPELLER TIC BEARING FUSER AND VG.
<u>FLOWRATES</u> 1. G 2. Q	LEAKAGE THROUGH DISCHA STATIC SEAL.	RGE BELLOW R RETURN <u>G PRIMARY</u> E OWRATE

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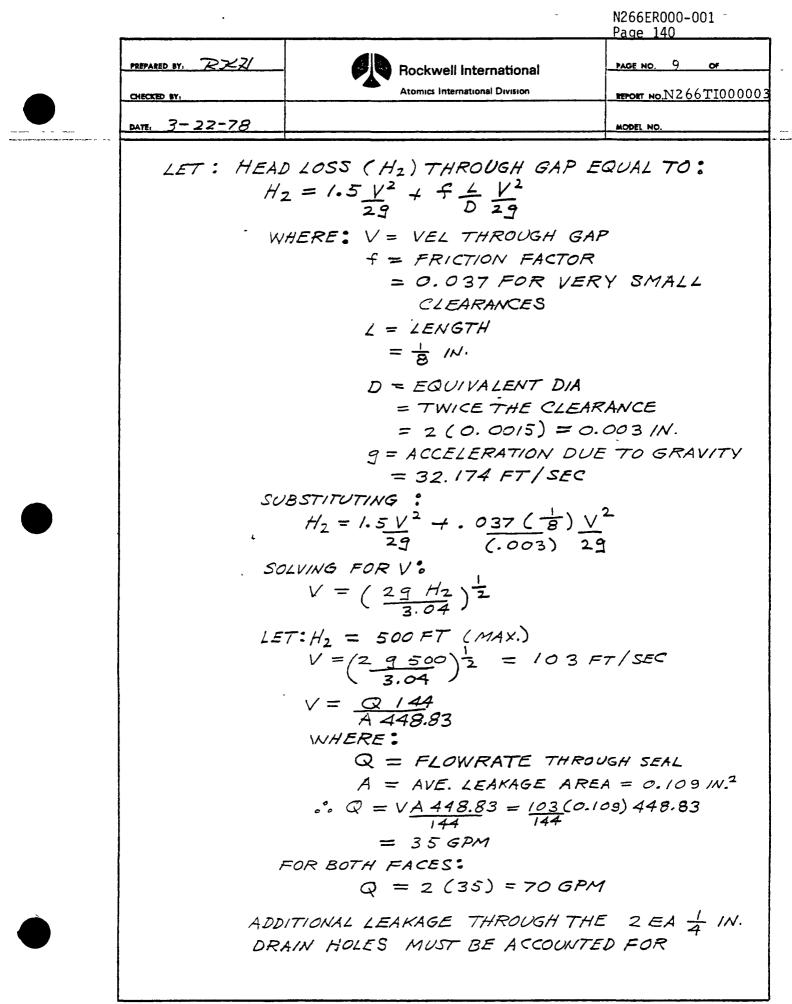
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PREPARED BY: RXX	Rockwell International	PAGE NO 8 OF
CHECKED BY	Atomics International Division	REPORT NO N266TI00
DATE; 3-22-78		MODEL NO.
6. Q <i>tra</i>	NS. DIFF. = FLOW THROUGH DIFFLISSER	TRANSITION
7. QEXIST	$= Q_{IMP} - Q_{4} - Q_{5}$ $= FLOW THROUGH$ $= Q_{TRANS, DIFF.} + Q_{5}$	EXISTING DIFFUS
8. QDIS	SCH. = $Q_{EXIST. DIFF.} - G$ = $14,500 GPM.$	
C. THIS SECO.	NDARY FLOW ANALYSES	ARE AS FOLLOWS
	ROSTATIC BEARING	
	SAME AS WEMD REPORT	(REF.2)
	$Q_6 = \underline{200  GPM} \checkmark$	
2. Q7 DIFI	EUSER AND RADIAL BEAR	RING HOUSING
	SAME AS WEMD REPORT	(REF. 2 )
	$Q_7 = \underline{131 GPM} \blacktriangleleft$	<u></u>
3. OB DIS	CHARGE BELLOWS STATI	C SEAL
	SAME AS WEMD REPORT	
	$Q_{\mathcal{B}} = \underline{IO \ GPM} \blacktriangleleft$	
4 OA FRI	ONT IMPELLER LABYRINT	SFAI
	FROM ROCKETDYNE DIV.	
,	6633 CANOGA AVE, CANOG	
C	₹4 = <u>648 GPM</u> -	- 
5 Or RF	AR IMPELLER LABYRINT	H SEAL
	FROM ROCKETDYNE DIV.	
	6633 CANOGA AVE, CANO	
~ (	Q5 = 569 GPM -	-
GIVEN	T STATIC SEAL MEAN SEAL DIA. = 23.	2 IN.
~ , , ,	$FACE WIDTH = \frac{1}{8} IN$	
	ě	
DED	CLEARANCE = O TO 3 A SEAL:	1125, SAY 1.5 MIL
	AREA = TT (MEAN DIA) CI	FARANCE
	$= \pi (23.2) (.0015)$	

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		N266ER000-001
	······································	Page 141
PREPARED BY, RXX	- Rockwell International	PAGE NO 10 OF
CHECKED BY	Atomics International Division	REPORT NO. N266TI0000
DATE: 3-22-78		MODEL NO.
	35.8 - 15.1 = 20.7 PSID	
A =	$\frac{2\pi}{4(144)}(\frac{1}{4})^2 = 0.000682$	e7 <sup>2</sup>
	-	_
HEA	$10 \ 2055 = 1.5 \ V^2 + f \ \frac{L}{D} = \frac{1}{29}$	
		- 7
	$E_{7}:f = 0.037$	1
0 -	$V = \left(\frac{29 \ \Delta H}{1.587}\right)^{\frac{1}{2}} = \left(\frac{29 \ (2)}{(1.58)}\right)^{\frac{1}{2}}$	0.7) 144 2
		÷ (
$\sim$	HERE: C = DENSITY = 50.971 LB/	/3
Ħ	= 50.977 LB/ V = 48.7 FT/SEC	
0.0	V = 48.7 F7/3ec	
ANI	Q = VA 488.83 = 48.7	- /
	= 14.9 GPM, SAY 13	SGPM
0°. TO	TAL INLET STATIC SEAL	LEAKAGE IS:
	Q2 = 70 + 15 = 85 GP	M -
CH	ECK ON REYNOLD'S NO. (R	?e )
$\mathcal{P}_{-}$	$= \rho V d$	- •
	$= \frac{OVd}{m}$	
И	WHERE: d = DIA., FT	
	$\mathcal{M} = \forall ISCOSITY$ $= 0.522   LB   F$	THR
SUI	STITUTING:	
	$R_{\rm c} = 50.97/(48.7) \cdot \frac{25}{12} (360)$	$o) = 3.5 \times 10^{5}$
	0.522/	
	$LET: \frac{e}{d} = 0.0001 = 0.00$	04
	4	•
	FROM CRANE (REF. 3)	
	f = 0.0173	$3) \cdot 59 V^2$
	$\mathcal{S} \cdot \Delta H = 1.5 \frac{V^2}{29} + (0.017)$	4 29
	$V = \begin{pmatrix} 29 & \Delta H \\ 1.54 \end{pmatrix}^{\frac{1}{2}} = \begin{pmatrix} 29 & (20.7) \\ 1.54 \end{pmatrix}^{\frac{1}{2}}$	
	$\left(\frac{1}{1.54}\right)$ $\left(\frac{1}{1.54}\right)$	50.971)
	Q = 49.4(0.000682)448.8	3 = 15 GPM
i i i i i i i i i i i i i i i i i i i		

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10-11 April 10-24

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	-	N266ER000-001 Page 142
prepared by, RXX	Rockwell International	PAGE NO 11 OF
CHECKED BY:	Atomics International Division	REPORT NON266T100000
DATE: 3-22-78		MODEL NO
7. Q3 DRI	VE SHAFT	
	THE WEMD REPORT ( R	EF.2)
	= 49.8  GPM	
	ISE THE ISIP DESIGN H	IAS AN ADDITIONAL
SHAFT	FEXTENSION, THE ADDITIC	DNAL PRESSURE
1	AND ACCOMPANYING DECI	
RATE	WAS CHECKED AS FOLLO	ows:
I FT	: d = 1.95 IN. (DISTANC.	F ACROSS FLATS)
<i>ິ</i> ເ	$A = \frac{\pi}{\pi} (1.95)^2 = 0.0$	0207FT
	4(144)	-
LE	T: Q = 49.8 GPM	
0	$\circ V = Q = 49.8$	
	$V = \frac{Q}{A  448.83} = \frac{49.8}{(0.0207)}$	448.83
	= 5.36 FT/SEC	
Re =	= 50.971 (5.36) <u>1.95</u> (	(3600)
	/2	
	0.522/	
	$= 3.07 \times 10^{5}$	
e	$= \frac{0.001}{1.95} = 0.0005$	
व	1.95	
FRO	OM CRANE	
	f = 0.0182	
$\Delta H =$	$7.5 \left(\frac{5.36}{29}\right)^2 + \frac{0.0182(13)}{1.95(2)}$	3,9)(5,36)
		5)
	= 0.73 FT	
Q	$= K \sqrt{\Delta H}, \ OR: K = \frac{O}{\sqrt{\Delta H}}$	- 、
	ROM WEMD (REF. 2)	
	$K = \frac{49.8}{1000} = 7.054$	
	V49.84	
5. Q	3 = 7.054 V 49.8473 =	= 49.44 GPM
	·	
DEC	CREASE IN FLOW = 49.8-	45.44 PM (NEGLIGIBLE)
0 /		···· (/VZGZ/G/DZE)
0.24	$T Q_3 = 50GPM -$	

1.459 19.900

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	Rockwell International Atomics International Division	HAGENO 1
CHECKED BY,		REPORT NO.N2
DATE: 3-22-78		MODEL NO
B. Q. SUCT	TON NOZZLE OUTLET CONE AN	D INLET T
	TON ELBOW	
	$Q_3 + \frac{1}{2}Q_6 + Q_8$	
=	$50 + \frac{1}{2}(200) + 10$	
=	<u>160 GPM</u>	
· <u> </u>	PELLER RETURN HOLES	
Q9 =	$Q_5 + \frac{1}{2} Q_6$	
-	569 + - (200)	
	*	
	<u>669 GPM</u> -	
D. IMPELLER	LABYRINTH SEAL CHECK	
FROM	ROCKETDYNE DIV., ROCKWELL	INT.
· ·	= 648 GPM	
	= 569 GPM	
2,00	4 = DELTA PRESSURE (STATIC) LABYRINTH SEAL	ALROSS
	= 129.7 - 35.8 = 93.8 P.	51D
ΔP.	S = DELTA PRESSURE (STATI	(C) ACROSS
	LABYRINTH SEAL	_
	= 126.9 - 39.7 = 87.2  PS	
	ONT SEAL AVE. DIA.= 22.5 EAR SEAL AVE. DIA.= 20.45	
	AMETRAL CL. = 0. 100 TO	
	$VE  DIAMETRAL \ CL = 0.10$	
	RONT CASING DIA. = 22.5+	
•	EAR CASING DIA. = 20.45+0	
	NT SEAL CL. AREA = (22.605	-
170	= 0.0258	4(
	= 0.0258	83F7 4
REA	$= 0.0258$ $R SEAL CL. AREA = (20.605^2 - 2)$	$2.5 \int \frac{\pi}{4(144)}$
	= 0.02348 F	72

		N266ER000-001
REPARED BY, RXX		Page 144 PAGE NO 13 OF
	Rockwell International	PAGE NO 13 OF
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ATE: 3-22-78		MODEL NO
- 3/	(	
	$SEC = KA (29 \Delta H)^{1/2}$	
OR K =	= Q 1 A (29AH) 1/2 448.83	
	$I = \Delta P \left( \frac{144}{50.97} \right)$	
	E: K = SEAL FLOW COEFFIC	IENT
° K	FOR FRONT SEAL = 648	
	0.02583(29)	(93.9)/ <u>44</u> 50.971) <sup>2</sup> 44
	= 0.428	
K	EAR DEAR SEAL - 569	. 1
	FOR REAR SEAL = <u>569</u> 0.02348(29(	87.2)144 12 448
	= 0.428	50,971J
$R_{P} =$		
	dh VP u	
WHERE	e dh = <u>4 (CLAREA)</u> WETTED PERIMETE	R
	$V = \frac{Q_L}{A(44883)}, FT/SEC$	
	M = VISCOSITY	
	= 0,5221 LB/FT HR	
FRONT	SEAL WETTED PERIMETER =	<u>TT ( 22.605 + 22</u>
		12 1.81 FT
REAR :	SEAL WETTED PERIMETER = II	
		·74 FT
S. FRONT	SEAL Ro = 4(0.02583) 648	- 1 50.9
	11.81 (0.02383	3)448.83
	<u>//.8/ (0.02583</u> 0.522/ <u>1</u> 360	0
	$= 1.72 \times 10^{5}$	
REAR	SEALRe = 4 (569) (50.971) (	3600) = 1.66×1
	10.74 (448.83)(	
THE KV.	ALUES FOR BOTH SEALS ARE	OF REALISTIC
VALUES BASE	D ON PREVIOUS ROCKETDYNE DA	TA (REF. 4) AN

N 152-8-2 REV 2-76

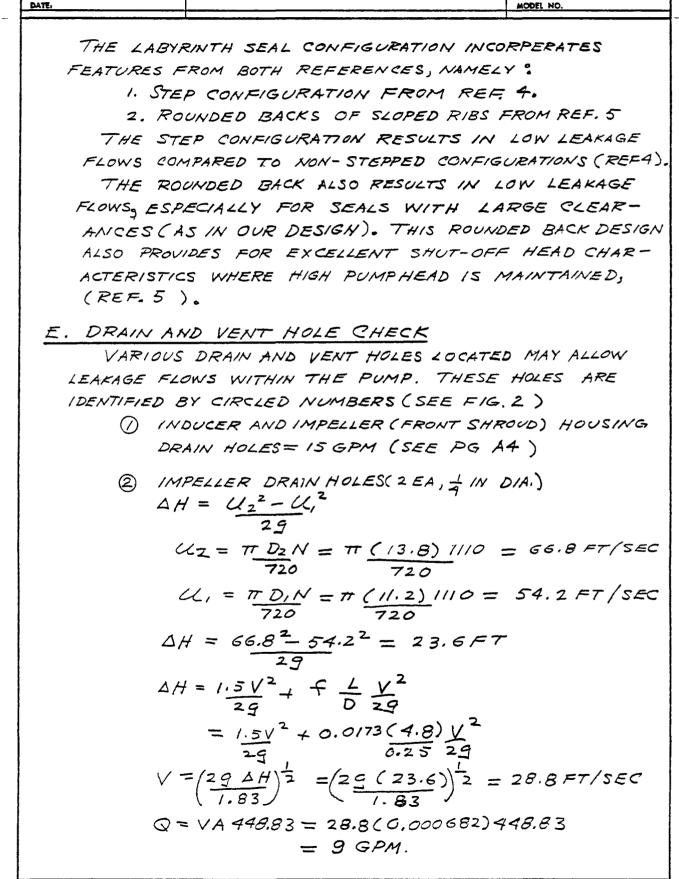
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			N266ER000-001
	PREPARED BY, RXX		Page 146 PAGE NO. 15 OF
	PREPARED BY: RRA	Rockwell International	PAGE NO. 15 OF
	CHECKED IV.	Atomics International Division	REPORT NO.N266TI000003
	DATE: 3-22-78		MODEL NO.
Pygge, sampleyt (printing), frendliger, gan			
	3 DRAIN HOL	LES IN SHAFT EXTENSION (2	$(EA_{*}, \frac{1}{4}, N, D/A_{*})$
	$\mathcal{U}_2 = \frac{T}{720}$	(3.6)/110 = 17.4 FT/SEC	
	$\mathcal{U}_{i} = \overline{\mathcal{T}}_{i}$	(2.4) 1110 = 11.6 FT/SEC	
	1 120		
		$\frac{4^2 - 11.6^2}{29} = 2.6 FT$	
	A VENT HOLD	ES IN SHAFT EXTENSION (2)	EA, 1 IN. DIA.)
	$\mathcal{U}_2 = \frac{\pi}{2}$	6.6) 1110 = 32 FT/SEC	
	$\mathcal{L}_{1} = \pi \mathcal{L}_{2}$	(5.0) 1110 = 24.2 FT/SEC	
	1 720	7	
	417 = 34	$\frac{2-24.2^2}{29} = 6.8FT$	
	5 DRAIN HOLE	S IN IMPELLER HUB ( ZEA., 4	- IN. DIA.)
	-	5.3) 1110 = 25.8 FT/SEC	
_	/20	(3.7) / / / 0 = 17.9 FT/SEC	
	$\Delta H = 2$	$\frac{5.8^2 - 17.9^2}{29} = 5.4 FT$	
	G VENT HOLD	ES IN IMPELLER HUB ( 2 EA,	1 IN. DIA.)
	$\mathcal{U}_2 = \pi$	(8.2)/110 = 39.7 FT/SEC	•
		720 (6.5) 1110 = 31.5 FT/SEC	
		720	
		$\frac{9.7^2 - 31.5^2}{29} = 9.1FT$	
	REFERING T	- - FIG. 2 ДН 3 IS AC	TING AGAINST
		DH S IS ACTING AGAI	•
	· AH (4) - AH	$(3) = 6.8 - 2.6 = 4.2 F_{1}^{2}$	$\tau$
	÷	$\sqrt{5} = 9.1 - 5.4 = 3.7 F$	
	-	•	
		$= 1.5V^{2} + 0.0173(.75)V^{2} = \frac{1.5V^{2}}{.25}V^{2} = \frac{1.5V^{2}}{.25}V^{2$	- +• /
	V ④ =/	$\left(\frac{2q(4.2)}{5}\right)^{\frac{1}{2}} = 13.2 FT/$	'SEC
		. /•55 •	
	Q = /	3.2 (0.000682) <b>4</b> 48.83	= 4 GPM
	L		

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N 152-8-2 REV. 2-76

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		N266ER000-001
DATE: 3-22-78	Rockwell International Atomics International Division	page no 16 of report noN266TI00000
	<u>ک</u>	MODEL NO.
	$\frac{5V^{2} + 0.0173(.98)}{.25}\frac{V^{2}}{.29} = \frac{29}{.25}\frac{1}{.29} = \frac{29}{.1568} = \frac{12.3 \text{ FT/S}}{1.568}$	
Q 6 =	/2.3(0.000682) <b>448.8</b> 3=	3,8 GPM.
Q 3 Q 4 Q 5 Q 6	ULATION FLOWS ARE: = 4 GPM = 4 GPM = 3.8 GPM G. 2 FOR FLOW DIRECTION	oN
	AN ADDITIONAL 4 GPM F. EXTENSION, Q3 FLOWRA	
	OF Q3 FLOW THROUGH D	
Re = 5 FROM	$Q' = 49.8 + 4 = 53.8 GA$ $V' = 53.8 = 5$ $0.0207(448.83)$ $50.971(5.79) \frac{1.95}{12}(3600)$ $0.5221$ $CRANE, f = 0.0182$ $(5.79)^{2} + 0.0182(13.9)$ $29 = 1.95(29)$ $= 0.85 FT$	.79 FT / SEC $) = 3.3 \times / 0^{5}$ $) (5.79)^{2}$
	7.054 ( SEE PG. A5)	
c. Q =	$7.054 \sqrt{49.8485} = 4$	19.37 GPM
DEC	REASE IN FLOW = 49,84- = 0,47 G	49.37 SPM (NEGLIGIBLE
°° - L.	$ET:Q_3 = \underline{50  GPM}$	

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40-00 -00-00 FT

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1			N266ER000-001 Page 148
	PREPARED BY, RZH	Rockwell International Atomics International Division	<u>PAGE NO 17 OF</u> REPORT NON266TI000003
	DATE: 3-22-78		MODEL NO.
·• ··· ···	G. PRIMARY FLO	WRATES THROUGH P	UMP
		ARA B , PAGES AI AND . IG FLOWRATES ARE OB:	
		SCH = 14, 500 GPM -	
	2.Q/N	LET = 14,500 GPM -	
	3. Q Sc	NCT. EL. = QINLET + QI	11 (() ( ) ) / -
		= 14,500 + 160 =	
	4. QINL	$P_{0} = Q_{SUCT, EL} + Q_{2} - Q_{3} \\ = 14,660 + 85 - 50$	
		$= \underline{14, 695 \text{ GPM}} \rightarrow$	
	5. QIMP	$R = Q_{IND} + Q_g + Q_4 - 15$	
		= 14695 + 669 + 648	-/5
		= <u>15,997 GPM</u>	

 $= \underline{14, 841 \text{ GPM}} = \underline{14,$ 

= 14,841 - 200 - 131 - 10 = 14,500 GPM -

N 152-8-2 REV. 2-76



APPENDIX D

CUSTOMER DESIGN REVIEW INTERMEDIATE SIZE INDUCER PUMP (ISIP)

ESG Document N266DRR000003

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FORM 719-P REV. 7-78

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	Rockwell international Atomics International Division	SUPP	ORTING DOCUMENT	NUMBER N266DRR		REV LTR/CH	
PROG	RAM TITLE	~		DOCUMENT 1 Design	Review Re	port -	
I	ntermediate-Size	Inducer	Pump (ISIP)	KEY NOUNS Inducer			
	JMENT TITLE			ORIGINAL IS			
	ustomer Design R nducer Pump	eview ir	itermediate-Size	May 12			
	·			GO NO.	S/A NO.	PAGE 1 OF TOTAL PAGES	
PREP	ARED BY/DATE		DEPT MAIL ADDR	09280	23000	REL. DATE	
, C,	E. Sternburg		5/10/78 731 LB26			ASSIFICATION	50
04	Sternburg			(CHECK ONE	BOX ONLY)	CHECK ONE BOX C	
	OVALS	NO X	IF YES, ENTER TPA NO DATE	UNCL	ERDA DOD	RESTRICTED DATA	
	. E. Glasgow			CONF. SECRET		DEFENSE INFO.	
-	- 5 - L	1mg	m 5/12/78	AUTHORIZE	<u> </u>	l D4	ATE
_	S. Q. Coglu		-12-78	CLASSIFIER			
	DISTRUEUTION	MAIL	ABSTRACT				
*	NAME	ADDR	This report document customer design revi				
* R. * F	. V. Anderson	LB17	Inducer Pump (ISIP).	The mee	ting was	held on	
	. G. Andrews	KB45	May 9, 1978, and res				
*  K.	. W. Atz . A. Birg	T486 LB39	10 recommendations.	The desi	gn was gi	ven a	
~ Ю. к IT	. J. Boardman	LB39	conditional approval				
*  R	. J. Bremner	LB39 LB49	completion of the ac	tion item	s and rec	commendations.	
* n	. O. Cipra	LB49 LB35					
* 10.	. Dunn	LB35 LB39					
* 1	E. Glasgow	LB39					
* G.		LB26					
* R.		JB05					
* E.		55-AC51	ОШАГ				
* P.	G. Jencek	LB49	0 16-17-78 CHA!				
* A.	. T. Marsik	KB43	( that all all	ACTION	ITEMS F	ELEASED	
*  C.	P. Messina	LB03	- a number of the	THIS D	RR HAVS	- BEEN	
* Н.	M. Minami	LB30	25 Stan - SATIO	2700700	(*** ******* 14 */ -7 ***		
* E.	M. Mouradian	LB351		SFACTOR	LI FUNC	WYERED	
* þ.	. M. Nishizaka	LB35	10/1/78 AND	ARE NO	W ON FI	LE IN	
* P.	R. Paradise	NB14	ENG!	NEERING	DATA.		
*  K.	Rothe				9,E 10-	18-72	
* M.		55-AC14	-	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		- <b></b>	
* C.	F. Sternburg	LB26					
* D.		55-AB24					_
* þ.		55-AC51	RESERVED FOR PROPRIETARY/LEGA				
· N.	K. Doshier	KB43	THIS REPORT MAY NOT	BE PUBL	ISHED W	ITHOUT THE	
	A. Marrazzo	T482	APPROVAL OF THE	PATENT	BRANCH,	ERDA	
• <b>R</b> .	E. Schnurstein	LB11	This report was prepared as an a	account of w	ork sponsor	cd by the United	
۴ ۵.	Q. Torrijos	LB26	States Government, Nuther the U	5 Governm	ent, nor any	of its employees	
			nor any of its contractors, subce	ritractors, cr	their cmplo	yees, makes any	
{			warranty, express or implied, o	r assumes a	ny legal li	ability or respon-	
1 7	/31-X.1/bjm		sibility for the accuracy, comple	teness or us	sefulness of	any information,	
	JI-A. I/ UJIII		apparatus, product or process di	sclosed, or r	epresents th	nat its use would	
	OMPLETE DOCUMENT		not infringe privately owned rig	nts.			
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FORM 734-C REV. 11-75

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DESIGN	REVIEW REPC	ORT	DRR-	N266DRR0000	003
ROGRAMISIP		REVIEW	ATF May	10, 1978	
EVIEWED DOCUMENT NO S	ee Page 4				
DCUMENT TITLECus	tomer Design Review,	, Intermediate-	Size Ind	ucer Pump	
	INCEPTUAL			FINAL	
_	ECIAL EXPLAIN Custon			-	
	. –	DISAPPROVED-RE		SEE REMAR	KS
	NDITIONALLY APPROVED Do impletion of all action items	ocument(s) reviewed to I	be approved up	ion the satisfactory	
	ems will require a written answer	or a copy of a released	EO indicating	completion for the	DRB Files
	DESIGN REVI				
Name and Dept	Review Responsibility	Name and D	)ept	Review Resp	onsibility
. E. Glasgow 731	Chairman	R. W. Atz	720	Test	
C. F. Sternburg 731	Administrator	R. J. Bremne	er 731	Mechanical	Design
	M&P	R. Karr		ANL	
J. M. Nishizaka 731	Stress	G. Jacobson		HEDL	
. M. Mouradian 731	Thermal/Hydraulics				
G. Andrews 755	QA				<u>.</u>
. T. Marsik 784	Manufacturing				
K. Rothe	Hydrodynamics				
UESTS A	I	Rocketdyn	<u>e</u>	ANL	
R. V. Anderson*	P. Jeneck	E. D. Jackson		R. Jaross	
「. J. Boardman* (PE ₹. K. Hoshide*	) G. Hallinan H. Minami*	J. E. Wolf* J. M. Zorad	(PE)	HEDL	
). 0. Cipra*	N. Marrazzo	M. Sasaki*		M. Young	
C. Dunn	D. Paradise R. Schnurstein			DOE	
N. K. Doshier *Presenter	C. Torrijos			K. Absher	
riesenter	DEN	MARKS		J. Nulton	
	11	in and			

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Rockwell International

## DESIGN REVIEW REPORT

# **DRR** - N266DRR000003

REVIEWED DOCUMENT NO. Page 4

Atomics International Division

SUMMARY

The purpose of the meeting was to review the intermediate-size inducer pump preliminary design as described in the documents listed on Page 4 of this report.

The intent of the review was to have the DRB assess that the preliminary design, as described during the presentation by the various disciplines, met all the requirements as depicted in Specification N266ST310001 and that these requirements were reflected in the design.

The Chairman requested that written comments be submitted by the Board Members on the critique of the data package, as indicated on the IL sent to the DRB.

The design review meeting was opened on May 9, 1978, by the Chairman, and after a brief introductory statement, the meeting was turned over to the responsible engineers for their presentations. During the course of the presentations, questions and concerns that were not satisfactorily resolved at the meeting resulted in action items. Those written comments by the DRB that did not result in action items are listed as recommendations.

The meeting was concluded by granting "Conditional Approval" to the design, subject to the satisfactory completion of the action items and recommendations.

All action items shall be resolved within 30 days from the date of the design review. Responses to the recommendations are due within 15 days of the design review. Responses to the action items and recommendations shall be forwarded to the Board Chairman and the Administrator by IL. Procedures of EMP 5-3, Design Reviews, apply.

Page 4

Atomics International Division

# DESIGN\_REVIEW REPORT

DRR- N266DRR000003

REVIEWED DOCUMENT NO.\_

SUMMARY

## CUSTOMER DESIGN REVIEW INTERMEDIATE-SIZE INDUCER PUMP DATA PCKAGE

Review Items

N266R000015 Design Layout Drawing N266ST310001 Pump Specification

Supporting Documents

N266E000002 Interface Control Drawings
N266SK00017 Rework Sketch for Static Hydraulics and Bearing Support Flange
N266TI000002 Pump Shaft Rotodynamics
N266TI000003 Recirculating Flow Analyses
N266B0160001 Specification, CF8 Castings
N266B0160002 Specification, 304 Forging
R/H 8113-3630 Hydrodynamic Design Report
Steady-State Stress Analysis Summary Assembly Outline Procedure



DE	SIGN REVIEW REPORT	DRR- N26	6DRR000003
	NT NO. Page 4		
	SUMMARY Agenda	<u>,</u>	
	Intermediate-Size Induc Customer Design Rev		
Place:	Conference Room 1		
Time: Attendee	8:10 a.m., May 9, 1978 es: AI, Rocketdyne, ANL, and HEDL		
Attended	es. Al, Nocketayne, Ant, and heat		Approximate Time
Ι.	Introduction	L. Glasgow	8:55 a.m.
II.	Project Description and Goals	R. V. Anderson	8:20 a.m.
III.	Design Approach	T. J. Boardman	8:30 a.m.
IV.	Description of Hydrodynamics Components	J. Wolf	8:55 a.m.
۷.	Hydrodynamic Design Description	E. D. Jackson	9:15 a.m.
VI.	Systems Analysis Recirculation Flow Analysis	R. K. Hoshide	10:00 a.m.
VII.	Stress Analysis	H. Minami	10:20 a.m.
VIII.	Stress Analysis Rotordynamics	D. O. Cipra	10:30 a.m.
IX.	Stress Analysis Steady State	M. Sasaki	10:45 a.m.
х.	DRB Review of Documentation	Board	11:15 a.m.
XI.	Review of Board Poll and Con- tingent Sign-Off		

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Rockwell International

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	DESIGN REVIEW REPORT	DRRN266DRI	·····
No	Description	Assigned to	Completion Date
	The following comments are <u>action items</u> to the responsible designers and project offic agreed. A written response to the Chairman a copy to each Board Member is required in 30 days stating what action was taken.	e	
1.	Specification N266T310001	L Boardman/	6 /0 /79
1.	Paragraph 3.1.1: Exhibit evidence that HED agrees with the requirements of this paragrand the meaning of "minimized."		6/9/78
2.	Paragraph 3.2.2.1: Add an equation as a fon note. Add a paragraph defining NPSH margin the verification section.		6/9/78
3.	Paragraph 3.2: Add the requirement to dete the locked rotor impedance of the pump.	rmine Boardman/ Paradise	6/9/78
4.	Paragraph 3.2.2.1: Provide an inspection p to include visual observation and replicas the leading and trailing edges of the induce and impeller.	of Paradise	6/9/78
5.	Paragraph 3.2.3.1: Identify the requirement that goes into this paragraph.	t Boardman	6/9/78

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	DESIGN REVIEW REPORT	DRRN266DRI	R000003
	ACTION ASSIGNMENTS		
No.	Description	Assigned to	Completion Date
6.	Paragraph 3.3.1: Add a parenthetical quantit stating that the stress report shall be signe by the manager of the stress group.	•	6/9/78
7.	Paragraph 3.3.2: Add a paragraph to specify the requirements for vibration stiffness of t AI diffuser and inducer tunnel.		6/9/78
8.	Compare the structural design requirements of the FFTF pump with those of the ISIP.	Boardman	6/9/78
9.	Paragraph 3.5.1, Part 5: Replace "bellows seal" with "piston ring" which fits into the bellows seal area. Modify the specification remove "bellows."	Boardman/ Paradise to	6/9/78
10.	Examine the impact of material dilation.	Friske/ Nishizaka	6/9/78
11.	Paragraph 3.5.3b: Remove the word "maximum" from the first sentence.	Paradise	6/9/78
12.	Paragraph 3.5.3b: Separate this paragraph in a heat treatment paragraph and a sensitizatio protection paragraph.		6/9/78
13.	Paragraph 3.5.3e: Remove the first sentence.	Paradise	6/9/78
14.	Paragraph 3.5.3e: Lock welding should be to the Code requirements.	Friske/ Paradise	6/9/78

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	ACTION ASSIGNMENTS		R000003
No			
No.	Description	Assigned to	Completion Date
15.	Table 3-II: Callout the efficiency requirements.	Boardman/ Paradise	6/9/78
16.	Table 3-II, Note 1: Reword to say that the pump shall not lose more than 3% head at the specified flow.	Boardman/ Paradise	6/9/78
17.	Table 3-II, Note 2: Correct "design objectives' to specific requirements.	Boardman/ Paradise	6/9/78
18.	Paragraph 4.1: Add the locked rotor test to this list.	Boardman/ Paradise	6/9/78
19.	Paragraph 4.2: Change the word "verified" to "assessed."	Paradise	6/9/78
20.	Paragraph 4.4.3" Reword this paragraph to add the deletion of the MTI probes.	Paradise	6/9/78
	Drawing Layout N266R000015		
21.	Add to the general notes: Construct to the requirements of the ASME BPV Section III, Class 1.	Boardman	6/9/78
22.	Material callout should be added to the Jence drawing.		6/9/78
23.	Correct the weld symbols on the lock welds.	Friske/ Jencek	6/9/78
24.	Add "Revision 2" to the specification number in Note 4.	Paradise	6/9/78

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	DESIGN REVIEW REPORT	DR	<b>R –</b> N266DF	R000003
	ACTION ASSIGNMENTS	•		
No.	Description		Assigned to	Completion Date
25.	Prepare a radial tolerance analysis and com it to the FFTF pump tolerance analysis.	npare	Boardman/ Jencek	6/9/78
26.	Clear up the clearance of N266R000015 Layou Sheet 2.	Jt	Boardman/ Jencek	6/9/78
27.	Check the edges of the different assemblies during assembly operations. Add to the QA section "to check the clearances between th inlet elbow and the diffuser tunnel."		Boardman/ Paradise	6/9/78
	Support Documents			
28.	Examine the torsional vibration criteria wirespect to the blade passing frequency plus other excitations.		Nishizaka/ Cipra	6/9/78

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Form 733-X-4 Rev. 7-75

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Page 10

·	RECOMMENDATIONS		
No	Description	Assigned to	Completion Dat
	The following comments are <u>recommendations</u> requiring a written response. If accepted, they become action items. Normally, responses to recommendations should be made within 15 days	5.	
	Specification N266T310001		
1.	Paragraph 3.1.1.1: Look into the need of blueing to check the fit defined in this para-graph.	Andrews/ Doshier	5/25/78
2.	Paragraph 3.2.1: Put down all of the terms involved in the NPSH.	Boardman/ Paradise	5/25/78
3.	Paragraph 3.2.2.1: Move the verification section from the requirement section back to the verification section.	Boardman	5/25/78
4.	Paragraph 3.3.5: The specification should require that steps be taken to reduce the possibility of galling of the threaded fasteners.	Boardman	5/25/78
5.	Paragraph 3.5.1, Part 5: Justify aluminization of the piston ring seal compared to the use of stellite or other hard facing techniques.	Boardman	5/25/78
6.	Paragraph 3.5.3c: Review the requirements of this paragraph.	Boardman	5/25/78

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-		RECOMMENDATIONS	<u></u>	
-	No	Description	Assigned to	Completion Date
-		Drawing Layout N266R000015		
	7.	Supply data to justify the saw tooth design.	Boardman	5/25/78
	8.	Examine the natural frequency of the pump blading.	Boardman	5/25/78
		Support Documents		
	9.	Make sure the impeller and the threads are dry after heating in water.	Boardman	5/25/78
	10.	Examine the impact of the fact that the shaft is stepped at the taper.	Nishizaka	5/25/78

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Form 733-X-4 Rev. 7-75

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| Internal Letter                                                                                                                                                                             | Page 161                                            |
|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------|
|                                                                                                                                                                                             | Rockwell International                              |
| Da'e .                                                                                                                                                                                      | NC N266DRR000003                                    |
| TO ', C arm + Arms                                                                                                                                                                          | FRCI.1 Nam Organization In fina Aggless Profes      |
| Design Review Board Members                                                                                                                                                                 | - L. E. Glasgow<br>- 731, 071-LB39                  |
|                                                                                                                                                                                             | . 1372                                              |
| Customer Design Review<br>Intermediate-Size Induce                                                                                                                                          | er Pump                                             |
| The Design Review Board approve design of the <u>Intermediate-Size</u>                                                                                                                      | e Inducer Pump (ISIP)<br>as presented in the design |
| review meeting of <u>May 9, 1978</u><br>documents:                                                                                                                                          | and as exhibited in the following                   |
| See Page 4                                                                                                                                                                                  | · · · · · · · · · · · · · · · · · · ·               |
| ••••••••••••••••••••••••••••••••••••••                                                                                                                                                      |                                                     |
|                                                                                                                                                                                             |                                                     |
| Design                                                                                                                                                                                      |                                                     |
| NOD I VIIIII                                                                                                                                                                                |                                                     |
| M&P (: P. Mixsu.                                                                                                                                                                            | in the state -                                      |
| Stress <u>- 1 111.</u>                                                                                                                                                                      | - <u>' · · · · · · · · · · · · · · · · · · </u>     |
| Stress <u> </u>                                                                                                                                                                             | ······································              |
| Stress 7 111.<br>Thermal/Hyd Econd M                                                                                                                                                        |                                                     |
| Stress <u>7</u> 1)].<br>Thermal/Hyd <u>Ecoud</u> M<br>Reliability/Maintainability<br>Quality Assurance <u>Cours</u>                                                                         |                                                     |
| Stress <u>7</u> 1)].<br>Thermal/Hyd <u>Ecoud</u> M<br>Reliability/Maintainability<br>Quality Assurance <u>Cours</u>                                                                         | na J. an drews                                      |
| Stress <u>7</u> <u>111</u><br>Thermal/Hyd <u>Ecoud</u> <u>M</u><br>Reliability/Maintainability<br>Quality Assurance <u>Cause</u><br>Manufacturing <u>Q.7</u> <u>M</u>                       | na J. an drews                                      |
| Stress <u>if</u> <u>III</u> .<br>Thermal/Hyd <u>Ecoud</u> <u>M</u><br>Reliability/Maintainability<br>Quality Assurance <u>Cause</u><br>Manufacturing <u>U.N.M</u><br>Test <u>Robert W.C</u> | na J. an drews                                      |
| Stress <u>if</u> <u>if</u><br>Thermal/Hyd <u>Eined</u> <u>M</u><br>Reliability/Maintainability<br>Quality Assurance <u>Cause</u><br>Manufacturing <u>U.N.M.</u><br>Test <u>Robert W.C</u>   | and J. an drew                                      |
| Stress <u>if</u> <u>III</u> .<br>Thermal/Hyd <u>Ecoud</u> <u>M</u><br>Reliability/Maintainability<br>Quality Assurance <u>Cause</u><br>Manufacturing <u>U.N.M</u><br>Test <u>Robert W.C</u> | and J. an drew                                      |
| Stress <u>if</u> <u>III</u> .<br>Thermal/Hyd <u>Ecoud</u> <u>M</u><br>Reliability/Maintainability<br>Quality Assurance <u>Cause</u><br>Manufacturing <u>U.N.M</u><br>Test <u>Robert W.C</u> | and J. an drews                                     |

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ATTACHMENT I

N266DRR000003 Page 13 CHANGE I

L. E. Glasoow 731. 071-LB39

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T. J. Poardnan 731, 071-LB39

1759

Intermediate-Size Inducer Pump (ISIP)

N266DRR000003, Customer Design Review, Intermediate-Size Ref: Inducer Pump

Attached is a list of the steps planned by Project Engineering for resolution of the action items and recommendations listed in the referenced report for the pump layout drawing (N266R000015) and for the supporting documents. Please indicate whether additional effort, other than implementation, is required for resolution.

Response to the action items and recommendations against the specification was transmitted under separate IL.

T. J. Boardman

jdj:525

Attachment

- cc: G. Hallinan
  - R. Anderson
  - C. Dunn
  - P. Jencek
  - W. Friske
  - J. Page
  - C. Torrijos
  - R. Schnurstein
  - J. Wolf (Rocketdyne) -

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- D. Paradise
- L. Noehler
- C. Sternburg (12)

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N266 DRR000003 Page 14 Change 1 It to L. . . . May 25, 1978

DRR Action Items for Layout Drawing N266R000015

- 21. <u>Comment</u>: Add to the general notes: Construct to the requirements of the ASME BPV Section III, Class 1.
  - <u>Response</u>: A note will be added to the drawing covering this requirement.
- 22. Comment: Material callout should be added to the drawing.
  - Response: Material callouts for each part will be added to the layout drawing. Basically, the impeller will be CF8; all other points will be 304 forgings excepting the threaded fasteners and the tie bolt which will be A286.
- 23. Comment: Correct the weld symbols on the lock welds.
  - <u>Response</u>: The lock weld symbols will be changed to show single V full penetration joints.
- 24. Comment: Add "Revision 2" to the specification number in Note 4.

Response: The note will be changed to designate, "OMM-051-00-005, Revision 2, Addendum 1".

- 25. <u>Comment</u>: Prepare a radial tolerance analysis and compare it to the FFTF pump tolerance analysis.
  - Response: A comparative radial tolerance analysis will be prepared for the region of concern. That is from the hydrostatic bearing down to the lower end of the rotor assembly.
- 26. Comment: Clear up the clearance of N266R000015, Layout Sheet 2.

Response: The information shown on Sheet 2 during the design review will be transferred to the original layout (Sheet 1) with all pertinent clearances shown. The layout will then be issued as Revision A.

- 27. <u>Comment</u>: Check the edges of the different assemblies during assembly operations. Add to the QA section, "to check the clearances between the inlet elbow and the diffuser tunnel".
  - Response: Checks, measurements, and other assembly monitoring functions will be specified in the OMM Addendum where

### N266DRR000003 Page 15 Change 1

pump assembly chrections will be written. These, in turn, will be described step-by-step in the detail assembly procedures to be written by ETEC and approved by AI. Assembly procedures include a signoff requirement for each step and provide forms for recording measurements. Completed assembly procedures become a part of test data.

- 7. Comment: Supply data to justify the saw tooth design.
  - <u>Response</u>: This comment resulted from a review meeting discussion concerning the ISIP labyrinth seal tooth spacing and the cavitation potential resulting from using three teeth widely spaced as opposed to closely spaced teeth in the prototype design.

The prototype pump front (lower) labyrinth is a "straight" (not staggered) type having a radial clearance of .100 in. (.050 in. for the back labyrinth) and a tooth spacing of .125 in. The tooth form is tapered (29 deg.) with a zero slant angle and a groove depth of .125 in. (reference WEMD Drawing 160A243). Thus, the tooth spacing, radial clearance, and groove depth (tooth height) were all of the same order of magnitude. The ISIP has a staggered (stepped) labyrinth with a radial clearance of .050 in. and a tooth spacing of approximately 1.0 in. The tooth form has a curved back (downstream side), is slanted against the direction of flow, and has a groove depth (tooth height) of 0.5 in. The ratio of radial clearance to tooth spacing is 0.1 as is the ratio of radial clearance to tooth height. The stepped arrangement and the low clearance-to-spacing ratio help minimize the velocity carryover effect, enabling each tooth to act more like an independent restriction with zero approach velocity, thus increasing the friction factor as shown in Figure 4 of Reference 1. (a) The low clearance-to-tooth height ratio permits rapid expansion of the fluid stream after crossing the tooth, encouraging the formation of turbulent eddies (a loss effect).

Figure 7 of Reference 2<sup>(b)</sup> illustrates the increased leakage effect of reducing tooth (blade) spacing for a fixed clearance, despite increasing the number of teeth. While the quantitative data of this reference

<sup>(</sup>a) Reference 1: W. Zabriskie and B. Sternlicht, "Labyrinth Seal Leakage Analysis," ASME Paper 58 A-118, Transactions of the ASME, Journal of Basic Engineering (contributed for the November 30-December 5, 1958, Annual Meeting, New York, New York)

<sup>(</sup>b) Reference 2: F. E. Heffner, "A General Method for Correlating Labyrinth-Seal Leak-Rate Data" Transactions of the ASME, Journal of Basic Engineering, June 1960 (Pages 265-275)

### N266DRR000003 Page 16 Change 1

may not be directly applicable due to differences in tooth form and fluid compressibility (the reference was written for compressible flow), the proportional trends are shown to be consistent for low-pressure ratios (which correspond to low-pressure ratio function  $\emptyset$ ) where compressibility effects are minor.

The effects of slanting the tooth profile against the direction of flow is also illustrated in Figure 4 of Reference 1, (a) showing that the friction factor for the slanted configuration is higher than for the nonslanted type.

Effects of the rounded back tooth form were presented in the review meeting by R. Hoshide. This data, plus additional data developed by General Motors for similar profiles, is being assembled and will be transmitted to the review board. The data shows the increased effectiveness of that particular profile.

In order to assess the potential for cavitation, the cavitation number will be evaluated at the minimum pressure following the last (third) labyrinth tooth for both the front (lower) and rear (upper) labyrinths. This data will be presented to the review board with the aforementioned profile data.

- 8. Comment: Examine the natural frequency of the pump blading.
  - Response: The natural frequency of the impeller and diffuser blading will be examined and compared to known exciting frequencies. As a sand casting with draft to be added by the foundry, results for the impeller are expected to be qualitative at best. However, since the impeller blades are supported on each side, as were the prototype impeller blades, they are expected to have a fairly high natural frequency which would be difficult to excite.

<sup>(</sup>a) Reference 1: W. Zabriskie and B. Sternlicht, "Labyrinth Seal Leakage Analysis," ASME Paper 58 A-118, Transactions of the ASME, Journal of Basic Engineering (contributed for the November 30-December 5, 1958, Annual Meeting, New York, New York)

DRR Action Items for Support Documents

28. <u>Comment</u>: Examine the torsional vibration criteria with respect to the blade passing frequency plus other excitations.

Response: The torsional vibration criterion as stated in Paragraph 3.3.2.9 of RDT E 3-2T reads "The first torsional and lateral critical speeds shall not be less than 125" of the design speed or as specified in the Ordering Data." The HWS 1551 ordering data does not modify this requirement.

> For both the prototype pump and the ISIP, the design speed corresponds to a frequency of 18.5 Hz. Using the AI model, both pumps have a torsional frequency more than 142% above the design speed (26.69 Hz for ISIP and 26.34 Hz for the prototype); therefore, the rotating speed will not excite the torsional frequency.

> The ISIP has ten impeller discharge vanes and eleven diffuser vanes, potentially generating pulses at 185 Hz, 2035 Hz, and 1850 Hz at design speed. At reduced speeds, these pulses will match the torsional critical frequency at 160 rpm, 14.5 rpm, and 16 rpm, none of which are in the steady-state operating range of the pump (94 rpm plus 400 to 1132 rpm). The 160 rpm will occur during the startup transient between pony motor speed (94 rpm) and minimum main motor speed (400 rpm) but will be for very short duration due to motor acceleration, and at low energy level due to the low speed. Other torsional excitation due to motor windings and rotor/starter slot combinations in the motor will remain unchanged. Therefore, no torsional vibration problems are predicted.

> Similar to the ISIP, the prototype pump blade frequency matched the torsional critical frequency at 263 rpm which also occurred during startup transients. No vibration problems were observed during startups while sodium testing at SPTF.

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N266DRR000003 Page 18 Change 1

DRR Recommendations for Support Documents

- 9. <u>Comment</u>: Make sure the impeller and the threads are dry after heating in water.
  - Response: A requirement for drying the threads will be included in the OMM Addendum for assembling ISIP and in the ETEC assembly procedure, requiring specific signoff by the operator. Based on prototype pump assembly experience, the assembly temperature (~180°F) will greatly enhance drying for exposed tapped holes.
- 10. <u>Comment</u>: Examine the impact of the fact that the shaft is stepped at the taper.
  - Response: The impact of the relief in the middle of the shaft taper will be examined by Rocketdyne (Sasaki) as part of the steady-state stress analysis.

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Cir	May 26, 1978	ATTACH MENT II		NZGGDRR000003 Page 19 Change 1
TO L. E. Glasgow 731, 071-LB39		Lt O		Boardman 171-LB39
		· ·	1759	N266ER000-001 Page 168

Intermediate Size Inducer Pump (ISIP)

Ref: N266DRR000003 Customer Design Review Intermediate Size Inducer Pump

Attached is a list of the steps planned by Project Engineering for resolution of the action items and recommendations listed in the referenced report for the pump specification (N266ST310001). Please indicate whether additional effort, other than implementation, are required for resolution.

Response to the action items and recommendations against the layout drawing and supporting documents will be covered under a separate IL.

T.J. Boardman

jew:4/1

Attachments

- cc: R. Anderson
  - C. Dunn
    - W. Friske
    - C. Hallinan
    - R. Hoshide
  - P. Jencek
  - J. Page
  - D. Paradise
  - R. Schnurstein
  - C. Torrijos
  - L. Woechler
  - J. Wolf (Rocketdyne)
  - C. Sternburg (12)

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Attachment 1 IL to L. E. Glasgow May 26, 1978 N266DRR000003 Page 20 Change 1

#### I. DRR ACTION ITEMS FOR N266ST3100001

1. <u>Comment</u> - Paragraph 3.1.1: Exhibit evidence that HEDL agrees with the requirements of this paragraph and the meaning of "minimized."

<u>Response</u> - HEDL agreement with the requirements of this paragraph will be evidenced by HEDL approval of AI Drawing N266000017, "Intermediate Size Inducer Pump, Westinghouse Components (Rework)" which shows interface changes to be made on the FFTF pump parts. A statement will be added to 3.1.1 to the effect that all such changes shall be approved by HEDL prior to implementation.

2. <u>Comment</u> - Paragraph 3.2.2.1: Add an equation as a footnote. Add a paragraph defining NPSH margin to the verification section.

Response - The equation referred to was an equation for NPSH margin.

A period will be put after the second line in the second paragraph then reference to Paragraph 4.4.5 will be made.

Test requirements and an equation for NPSH margin will be added to Paragraph 4.4.5.

The equation will not be in a footnote since it will be part of a requirement (method of determining margin for this test) not an explanatory note.

3. <u>Comment</u> - Paragraph 3.2: Add the requirement to determine the locked rotor impedance of the pump.

<u>Response</u> - This requirement will be added to the test requirements under Paragraph 6.2 instead of under Performance in 3.2, since there is no specified locked rotor resistance requirement for design or verification.

4. <u>Comment</u> - Paragraph 3.2.2.1: Provide an inspection plan to include visual observation and replicas of the leading and trailing edges of the inducer and impeller. See insert for 3.2.2.1 and 4.3.1.

<u>Response</u> - Requirements for pre- and post-test inspection including measurement, visual observation, and replicas will be included under 4.3.1.

5. <u>Comment</u> - Paragraph 3.2.3.1: Identify the requirement that goes into this paragraph.

### N266DRR000003 Page 21 Change 1

<u>Response</u> - Paragraph 3.2.3.1 and 3.2.3.2 are being rewritten to specify the 12.8 ft NPSH requirement given in the Hydrodynamic Design Report (R/H 8113-3630) distributed as a supporting document for the design review.

6. <u>Comment</u> - Paragraph 3.3.1: Add a parenthetical quantity stating that the stress report shall be signed by the manager of the stress group.

<u>Response</u> - The stress report requires signature by manager of the stress <u>unit</u> and by the project engineer, as indicated in Table 1 on Page 10 of N266RPA000001 for this project.

7. <u>Comment</u> - Paragraph 3.3.2: Add a paragraph to specify the requirements for vibration stiffness of the AI diffuser and inducer tunnel.

<u>Response</u> - A paragraph stating that the pump shall be designed such that no malfunction or damage shall result from vibration will be added, similar to that in Paragraph 3.3.5.4 of Ammendment 2 to RDT E 3-2T.

8. <u>Comment</u> - Compare the structural design requirements of the FFTF pump with those of the ISIP.

<u>Response</u> - Comparison of the structural design requirements has been made. Attachment 2 summarizes the results of this comparison. Generally, with a few additions (such as the vibration requirement), the ISIP requirements are comparable to those for FFTF when the limited life and noncritical function (test as opposed to primary system cooling) are considered.

9. <u>Comment</u> - Paragraph 3.5.1, Part 5: Replace "bellows seal" with "piston ring" which fits into the bellows seal area. Modify the specification to remove "bellows."

Response - These changes will be made to the specification.

10. <u>Comment</u> - Examine the impact of material dilation.

Response - It is presumed that this should be "material densification."

The impact of this phenomenon has been examined and the results of the examination are summarized in Attachment 3. Since information on this subject is severely limited, the results and conclusions represent our best judgement based on available data.

11. <u>Comment</u> - Paragraph 3.5.3b: Remove the word "maximum" from the first sentence.

Response - The word "maximum" will be removed.



# N266DRR000003 Page 22 Change 1

12. <u>Comment</u> - Paragraph 3.5.3b: Separate this paragraph into a heat treatment paragraph and a sensitization protection paragraph.

<u>Response</u> - The two subjects will be separated into two grammatical paragraphs, both under 3.5.3b. The requirement is for heat treatment, which will be in the first paragraph. A result will be sensitization, which will be addressed in the second paragraph in terms of handling precautions to be followed. M&P, with Project Engineering concurrence, does not want these requirements under different paragraph numbers because one is a direct consequence of the other, therefore, the requirements should remain associated.

13. Comment - Paragraph 3.5.3e: Remove the first sentence.

<u>Response</u> - This paragraph will be revised to cover lock welding only and will specify AI requirements equivalent to those specified for lock welds on the FFTF prototype pump (See <u>W</u> EMD Drawing 114E829). The AI requirements were previously approved by HEDL for use in the pump.

The revision will implement removal of the first sentence.

14. <u>Comment</u> - Paragraph 3.5.3e: Lock welding should be to the Code requirements.

<u>Response</u> - See response for Action Item 13. Design of the locking devices will be based on using RDT M 6-2T as a guide.

15. Comment - Table 3-II: Callout the efficiency requirements.

<u>Response</u> - Efficiency requirements will be implied by specifying maximum shaft horsepower (equal to rated motor horsepower.)

16. <u>Comment</u> - Table 3-II, Note 1: Reword to say that the pump shall not lose more than 3% head at the specified flow.

Response - The note will be reworded as indicated.

17. <u>Comment</u> - Table 3-II, Note 2: Correct "design objectives" to specific requirements.

<u>Response</u> - Note 2 will be revised to require a negative slope between 8,000 and 18,000 gpm, corresponding to the estimated performance curve in the Hydrodynamic Design Report. The shutoff head goal will be deleted on the same basis.

These were originally requirements set for the FFTF prototype pump for operation in the FFTF plant. Since the ISIP is essentially a retrofit design to put the inducer and impeller in the same cavity as the prototype pump impeller, the same dimensional design flexibility needed to achieve those requirements is no longer available. Also the primary purpose of ISIP is for suction performance tests, as opposed to plant operation.

### N266DRR000003 Page 23 Change 1

- 18. <u>Comment</u> Paragraph 4.1: Add the locked rotor test to this list. <u>Response</u> - A locked rotor test will be specified under 6.2.2. (see Action Item 7).
- 19. Comment Paragraph 4.2: Change the word "verified" to "assessed."

Response - This change will be made to the specification.

20. <u>Comment</u> - Paragraph 4.4.3: Reword this paragraph to add the deletion of the MTI probes.

Response - The MTI probes will be added to those excepted instruments.

II. DRR RECOMMENDATIONS FOR N266ST310001

1. <u>Comment</u> - Paragraph 3.1.1.1: Look into the need of blueing to check the fit defined in this paragraph.

<u>Response</u> - The ISIP impeller bore will be machined to the same dimensions and tolerances as the FFTF impellers, which are interchangeable; therefore, a specification requirement for blueing should not be required in the specification (nor was it required in HWS-1551 or RDT E 3-2T.) However, like <u>W</u> EMD, AI will add this requirement to the assembly procedure as a precaution and final check on the fit.

 <u>Comment</u> - Paragraph 3.2.1: Put down all of the terms involved in the NPSH.

<u>Response</u> - NPSH may be expressed in terms of a number of different variables, usually depending on those which can be measured. Instead of putting down the "terms," a word description will be provided allowing the use of engineer flexibility to select those measurable variables which can be combined to provide the correct value.

3. <u>Comment</u> - Paragraph 3.2.2.1: Move the verification section from the requirement section back to the verification section.

<u>Response</u> - This will be accomplished as part of the revision under Action Items 2 and 4.

4. <u>Comment</u> - Paragraph 3.3.5: The specification should require that steps be taken to reduce the possibility of galling of the threaded fasteners.

<u>Response</u> - The specification will include a requirement for mating surfaces of internal and external threads to be different materials and for thread lubricants to be used at assembly.

5. <u>Comment</u> - Paragraph 3.5.1, Part 5: Justify aluminization of the piston ring seal compared to the use of stellite or other hard facing techniques.



### N266DRR000003 Page 24 Change

<u>Response</u> - Present plans are to aluminize the bore of the Type 304 steel cylinder. The piston ring will be made of Inco 718. This material combination has been discussed with the AI M&P Department, LMEC, and HEDL. Inco 718 against an aluminzed surface has been tested in sodium at HEDL and found to have resonable wear resistance. The thickness of the hard surface will be approximately 3-4 mils, of which approximately half will build up on the surface. Based on HEDL information, the expected friction coeffecient is between 0.2 and 0.5. Stellite was not selected because of its high local heat input and the potential effects of its lower thermal expansion coefficient during thermal transients.

6. <u>Comment</u> - Paragraph 3.5.3c: Review the requirements of this paragraph.

<u>Response</u> - This paragraph will be reviewed carefully and revised as appropriate. From an initial reading, the intent of the paragraph is not clear, despite the fact that the requiremen' is explicit.

jew:4/2-6

N266DRR000003 Page 25 Change 1 Attachment 2 IL to L. E. Glasgow May 26, 1978

### COMPARISON OF STRUCTURAL DESIGN REQUIREMENTS OF FFTF PUMP WITH THOSE OF ISIP

- References: (1) RDT E 3-2T Centrifugal Free-Surface Sodium Pump with Electrical Drive, May 1971; including Amendment 1, February 1972, and Ammendment 2, June 1974.
  - (2) HWS-1551 LMFBR Low Capacity Prototype Pump--FFTF Primary Pump, Revision 1, January 1974, including Addendum 1P, June 1977.
  - (3) N266ST310001 Pump, Sodium, Inducer, Intermediate Size (ISIP.)

Structural design requirements for the FFTF pump are to be found under Paragraph 3.3.5, <u>Structural Design</u>, and its subparagraphs in both the RDT standard (Reference 1) and the ordering data (Reference 2.) Structural design requirements for the ISIP may be found under Paragraph 3.3, Design Requirements, in the pump sepcification (Reference 3.)

### 1. Allowable Stresses

a. RDT E 3-2T Ammendment 1, Paragraph 3.3.5.1

Allowable stresses are to be in accordance with the Code, supplemented by Code Case 1331 and RDT F 9-1.

b. N266ST310001, Paragraph 3.3.1 (refers to Table 3-III)

Table 3-III uses allowable stresses extracted from the Code and Code Case 1592-10 as guidance for high temperature ( 800°F) application.

Code Case 1592 is an outcome of the initial high-temperature criteria developed on the FFTF program under RDT F 9-1 for application of Code Case 1331.

### 2. Earthquakes

a. RDT E 3-2T, Paragraphs 3.3.5.2 and 3.4.4

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Requires pump to be designed to seismic criteria specified in ordering data.

b. HWS-1551, Appendix A

States seismic design loads (JABE-WADCO-O2) and performance requirements under various load categories (OBE, DBE, etc.)

c. N266ST310001

Since ISIP has no operational requirements during or after an earthquake, OBE and DBE type requirements are not applicable for the ISIP components. In the event of an earthquake, the pump can be stopped and the system drained immediately under an emergency operating procedure. The FFTF structure has already been analyzed by Westinghouse. The impeller/inducer assembly mass is of the same order of magnitude, but slightly lighter than the FFTF pump impeller, therefore, no additional loads will be applied to the pump shaft. The diffuser and shroud assembly will be checked against Uniform Building Code (UBC) requirements for this area, under a requirement to be added to the specification.

- 3. Vibration
  - a. RDT E 3-2T, Paragraph 3.3.5.4

Requires that design avoid damage or malfunction due to internally or externally excited vibration.

b. N266ST310001, Paragraph 3.3.2

An equivalent requirement is being added under Action Item 7 from the design review.

- 4. Thermal Stresses and Deflections
  - a. RDT E 3-2T, Paragraph 3.3.5.5

Requires analysis for transient induced stresses and deflections.

b. N266ST31001

Requires test transient effects to be analysed and results evaluated against Code criteria to determine permissable transients. Recirculation (internal) flows and calcualted temperature distributions will be compared to the FFTF pump to determine whether additional deflection analyses are warranted.

- 5. Residual Stresses
  - a. RDT E 3-2T, Paragraph 3.3.5.6
    - Requires design to prevent damage or malfunction due to residual stresses or to utilize stress relief processes to relieve residual stresses.

b.

N266DRR000003 Page 27 Change 1

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Requires heat treatment to achieve dimensional stability.

- 6. Creep
  - a. RDT E 3-2T, Paragraph 3.3.5.7

N266ST310001, Paragraph 3.5.3(b)

Requires design to central or limited accumulated creep within limits required for staisfactory operation.

b. N266ST310001, Paragraph 3.3.1 (refers to Table 3-III)

Specifies creep-fatigue and strain accumulation limits.

c. N266ST310001, Paragraph 3.5.3(b)

Requires heat-treatment to achieve dimensional stability.

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N2GCDRR000003 Page 28 Change 1 Attachment 3 IL to L. E. Glasgow May 26, 1978

### EXAMINATION OF THE IMPACT OF MATERIAL DENSIFICATION ON ISIP COMPONENTS

The stainless steel internal components of the ISIP will be given a supplemental heat treatment intended to promote dimensional stability during subsequent sodium pump service. This heat treatment is designed to accelerate metallurgical transformations in the microstructure which increases the density and results in dimensional shrinkage of the component. Westinghouse reported that one FFTF sodium pump casting exhibited a density increase of 0.16% after the stabilizing heat treatment with no change during subsequent heating at 1050°F for 1,000 hr. HEDL is currently conducting a series of tests on cast CF-8 specimens to further evaluate the effectiveness of the heat treatment. The HEDL tests also indicate an increase in density, up to about 0.15%, following the heat treatment. In subsequent heating at 1050°F, a small additional increase in density of about 0.02% was also indicated during the first 500 hr, but there were no significant changes during continued exposures. To date, the HEDL specimens have completed more than 4,500-hr exposure time.

The above data indicate that the supplemental heat treatment does promote densification. Since the components will be final machined after the heat treatment, any further increase in density during sodium service should be minimal with no significant dimensional change.

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га . тс	June 7, 1978 ATTACHMENT	Page Chan	29
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-	Intermediate-Size Inducer Pump (ISIP)	1759	N266ER000-001 Page 178
Ref:	(1) IL dated May 25, 1978, Boardman to	o Glasgow,	"Inter-

- mediate-Size Inducer Pump (ISIP)
  - (2) N266DRR000003, Customer Design Review, Intermediate-Size Inducer Pump

Reference 1 was prepared in response to the action items and recommendations listed in Reference 2 for the design layout drawing (N266R000015) and for the supporting documents. The response to Recommendation 7 stated that the potential for cavitation in the labyrinth would be evaluated separately and transmitted to the review board with copies of the data used to determine the labyrinth profile.

Attached is AI's assessment of the cavitation potential which, based on the cavitation number, is not expected to present a problem. Also attached are copies of the two references upon which the profile and performance estimates were based. Please have this information transmitted to the Rockwell members of the review board as completion of Recommendation 7. Copies will be transmitted to non-Rockwell members of the board by the Program Office.

andmon

T. J. Boardman

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Attachments

cc w/attachment:

cc w/attachment and references for attachments:

- G. Hallinan
- C. Dunn
- P. Jencek
- P. Ferry
- J. Page
- C. Torrijos
- R. Schnurstein
- J. Wolf
- D. Paradise
- L. Woehler
- R. Hoshide

- R. V. Anderson (7)
- C. Sternburg (10)

N2CCDRROGOOO3 Page 30 Change 1 Attachment IL to L. E. Glasgow June 7, 1978

Subject: Summary of Intermediate Size Inducer Pump (ISIP) Impeller Labyrinth Seal Design and Evaluation of Cavitation Potential

Ref:

- (1) Crewdson, E., "Water-Ring Self-Priming Pumps,"
   Vol. 170, No. 13, Institution of Mechanical Engineers,
   Westminster, South Wales, 1956
  - (2) Stocker, H. L., "Advanced Labyrinth Seal Design Performance for High Pressure Ratio Gas Turbines," ASME Publication 75-WA/GT-22, New York, New York, 1975

#### INTRODUCTION

Because the impeller front and rear labyrinth seal configurations were changed from the original Westinghouse design, a briefing on the new seal design was presented at the ISIP Customer Design Review held at Atomics International on May 9, 1978. Charts 1 through 4 were presented at the briefing. A summary sheet on the important seal design parameters is also attached along with the two applicable references (References 1 and 2).

#### SUMMARY

Test results from E. A. Jackson showed that use of slanted round backed teeth gave the highest resistance to flow through the leakage passage. Shutoff pump head was 1-1/2 times higher when compared to the slanted flat topped teeth design. Flow had little tendency to enter the pocket in the flat topped design.

Test results from H. L. Stocker showed that increased internal seal cavity turbulence resulted in lower leakage compared to the baseline seal. Leakage rates were reduced from 10 to 29 percent during static tests. Comparable leakage rates from 11 to 25 percent reduction were obtained under rotating conditions. Results of the dynamic tests showed little effect on the leakage rates through the seal.

#### DISCUSSION

#### <u>General</u>

Impeller labyrinth seal leakages (front and rear) are important in any pump design. Leakage of these seals are recirculated through the impeller and results in efficiency penalties. This leakage can also affect the

N266DRR000003 CHANCE ! Page 31

head-flow curve under throttled conditions and especially the shutoff head. Rockwell experience has shown that standard straight circular groove labyrinth seal designs are very poor in reducing leakage of impeller labyrinth seals especially when the clearance gets large. Stepped configurations have shown to be much more effective (about 50% greater resistance) than the standard straight circular groove design.

#### Test Results of E. A. Jackson

Charts 1 through 4 were presented at the Customer Design Review and summarize the data obtained by E. A. Jackson (Addendum to Reference 1). Three different experimental test programs (stationary model, pump experiments, and large-scale model) were conducted to develop the form of teeth which offered the greatest resistance to water flow through a clearance gap.

Stationary model test results for the slanted flat topped and slanted round backed teeth are shown in Chart 2. Note that the round backed design gave the highest resistance to flow through the passage.

Pump experiments (Chart 3) demonstrated that with the slanted round backed design, 1-1/2 times more head was developed at shutoff. The slope of the head-flow curve remained negative and smooth. This characteristic is very desirable for large-scale breeder reactor (LSBR) sodium pumps. Reduction of leakage through the impeller labyrinth seals, especially during throttled conditions, will help maintain the desired negative slope pump characteristic.

Large-scale model tests (Chart 4) showed that flow had little tendency to enter the pocket in the flat topped design while flow tended to follow the round backed teeth. The rate of circulation was nearly twice that of the flat topped teeth. Based on previous Rockwell experience and from the results of E. A. Jackson (Reference 1), the ISIP impeller labyrinth seal design was obtained.

#### Test Results of H. L. Stocker

H. L. Stocker (Reference 2) conducted water tunnel studies, static air rig, and dynamic air rig tests with various labyrinth seal designs. All designs (nine each) were of the stepped configuration and many had slanted round backed teeth.

Water tunnel flow visualization tests were used as a preliminary evaluation of the turbulence generated by the candidate configurations. Results of these tests showed that increased internal seal cavity turbulence resulted in lower leakage compared to the baseline seal.

Static air rig test results demonstrated that leakage over a standard <u>step</u> seal was reduced from 10 to 29 percent with flow going from a larger diameter to a smaller diameter (as in our design).

Testing under rotating conditions up to 786 ft/sec resulted in lower leakage compared to the baseline seal from 11 to 25 percent. Results of

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the dynamic tests showed little effect on the flow parameter characteristic of the seals and that the seals tested produced zero to 3.2 percent increase over the static flow parameter. This magnitude of change was within the accuracy of the test data.

#### ISIP Seal Design

Impeller labyrinth seal design parameters were obtained from the hydrodynamic analysis and are listed on Chart 5 for both front and rear seals. Note that since the front labyrinth seal leakage discharges between the inducer exit and impeller inlet, the static pressure is 35.8 psia. This pressure is high and should prevent cavitation. Also, the maximum fluid velocity through the labyrinth is only 56 ft/sec (low). The rear labyrinth seal leakage discharges into a zone where the static pressure is 39.7 rsia. Again, this pressure is high and should prevent cavitation. Maximum fluid velocity through the labyrinth is also low at 54 ft/sec. For the front labyrinth, the minimum local cavitation number\* across the last labyrinth blade would be 2.2 at 1050F if no flow contraction is assumed, as would be expected with the rounded backs. Since the rear labyrinth discharges to a higher pressure, 39.7 psia vs 35.8 psia, the last labyrinth blade would have a higher cavitation number. From this hydrodynamic analysis, cavitation is not anticipated to be a problem at either front or rear impeller labyrinth seal locations or in the zones where the leakage flows are discharged.

\*

$$K = \frac{P - P_v}{1/2PV^2}$$

Where:

- K = cavitation number
- P = static pressure
- P, = vapor pressure
- P = fluid mass density
- V = fluid velocity

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## CHART 1

JACKSON, E.A., "EXPERIMENTS TO DETERMINE THE BEST SHAPE AND NUMBER OF VANES FOR A GGE PUMP RUNNER," ADDENDUM TO CREWDSON, E., "WATER-RING SELF-PRIMING PUMPS," THE INSTITUTION OF MECHANICAL ENGINEERS, VOL. 170, NO. 13, WESTMINSTER, SOUTH WALES, 1956

OBJECTIVE – DEVELOP THE FORM OF TEETH WHICH OFFERED THE GREATEST RESISTANCE TO WATER FLOW

- EXPERIMENTAL TESTING
  - STATIONARY MODEL
  - PUMP EXPERIMENTS
  - LARGE-SCALE MODEL

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CHART 2 STATIONARY MODEL TESTS

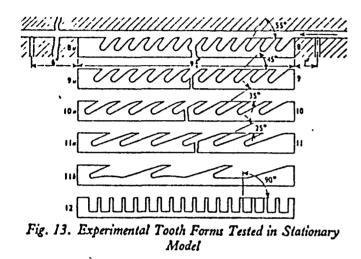
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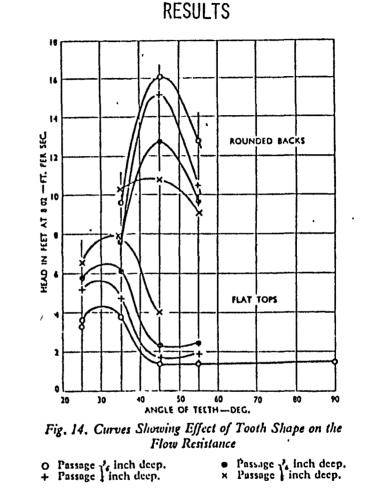
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ROUND	FLAT
BACKED	TOPPED
TEETH	TEETH



- FLAT TOPPED TEETH HIGHEST RESISTANCE TO FLOW WITH MINIMUM CLEARANCE
- ROUND BACKED TEETH HIGHEST RESISTANCE TO FLOW WITH MAXIMUM CLEARANCE

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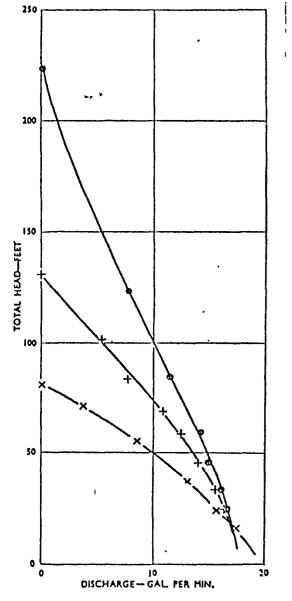


Fig. 15. Performance Curves for Three Types of Pump Runner

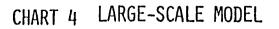
- Vanes 35 deg., rounded backs.
  Vanes 35 deg., flat tops.
  × Vanes 90 deg., flat tops.

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- ROUND BACKED TEETH 1-1/2 TIMES MORE HEAD AT SHUTOFF
- 90° VANE CONFIGURATION HEAD DEVELOPED WAS CONSIDERABLY LOWER THAN FOR INCLINED VANES

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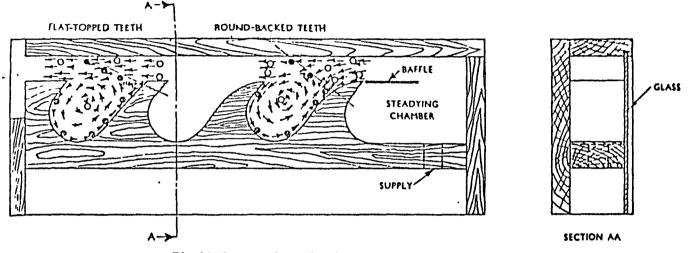


Fig. 16. Large-scale Model of Water-ring Self-priming Pump

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- Regions of high pressure. Regions of low pressure. Approximate line of maximum pressure downstream of tooth.

Length and directions of arrows represent approximate velocity and direction of flow.

- FLAT TOPPED TEETH
  - FLOW HAD LITTLE TENDENCY TO ENTER POCKET
- ROUND BACKED TEETH
  - FLOW TENDED TO FOLLOW ROUND BACKED TEETH .
  - RATE OF CIRCULATION NEARLY TWICE THAT OF FLAT TOPPED . TEETH

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# CHART 5 ISIP IMPELLER LABYRINTH SEAL DESIGN PARAMETERS

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	IMPELLER LAE	YRINTH
DESIGN PARAMETER	FRONT	REAR
LEAKAGE FLOW RATE, GPM	648	569
SEAL DELTA PRESSURE, PSID	93.8	87.2
DISCHARGE STATIC PRESSURE, PSIA	35.8	39.7
SEAL SPEED, FPS	109	99
AVERAGE DIAMETER, IN.	22.5	20.5
AVERAGE DIAMETRICAL CLEARANCE IN.	0.105	0,105
AVERAGE FLOW THROUGH AREA, IN. <sup>2</sup>	3.72	3,38
AVERAGE FLUID VELOCITY, FPS	56	54

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	Intermediate-Size Inducer Pu	mp Design Rev	view Action Items
Ref:	N266DRR000003, Customer Desi	an Review Int	termediate-Size

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The Design Review Board Members have reviewed the action item responses and the updated referenced documents and concur with the implementation of the action items and responses to the recommendations. Approval of this IL by the board members listed below denotes that they concur with the responses to the design review action items.

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Design Review Chairman

Design Review Administrator

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June 19, 1978	N266DRR000003 Page 39 Change 1
Design Review Board Members	L. E. Glasgow 731, 071-LB39
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Intermediate-Size Inducer Pump Design Review Action Items

Ref: N266DRR000003, Customer Design Review Intermediate-Size Inducer Pump

The Design Review Board Hembers have reviewed the action item responses and the updated referenced documents and concur with the implementation of the action items and responses to the recommendations for the Equipment Specification (N266ST310001). Approval of this letter by the board members listed below denotes that they concur with the responses to the design review action items for this document. This form is for signature by non-Rockwell board members. A similar Internal Letter form will be signed by Rockwell board members.

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Design Review Chairman Charles H. Stern Design Review Administrator



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Intermediate-Size Inducer Pump Design Review Action Items

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Argonne National Laboratory

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Hanford Engineering Development Laboratory

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G. Jacobson

Design Review Chairman - Design Review Administrator

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Intermediate-Size Inducer Pump Design Review Action Items

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N266DRR000003, Customer Design Review Intermediate-Size Inducer Pump

The Design Review Board Members have reviewed the action item responses and the updated referenced documents and concur with the implementation of the action items and responses to the recommendations for the ISIP Design Layout, (N266R000015, D2 release). Approval of this letter by the board members listed below denotes that they concur with the responses to the design review action items for this document. This form is for signature by non-Rockwell board members. A similar Internal Letter form will be signed by Rockwell board members.

Argonne National Laboratory

R. Karr

Hanford Engineering Development Laboratory

Design Review Chairman

Design Review Administrator



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## APPENDIX E

## ROTORDYNAMICS OF THE INTERMEDIATE SIZE INDUCER PUMP (ISIP)

ESG Document N266TI000002

Pages A2 thru A23 and B2 thru B93 (computer printout) have been removed from this document for brevity.

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#### INTRODUCTION

The purpose of this report is to document the rotordynamic analysis of the Intermediate Size Inducer pump (ISIP). This study was performed to determine the rotordynamic effect of installing the AI-designed inducer/impeller subassembly in the existing FFTF primary pump. The pump shaft during this conversion was left unchanged, and, therefore, the dynamic finite element shaft model of the original FFTF pump was remodeled using the proposed inducer/impeller mass and stiffness properties.

### SUMMARY

The rotordynamic analysis performed indicates that the ISIP rotating assembly exhibits little change in frequency when compared to that of the FFTF primary pump. This is because the change of effective mass (both translational and rotational) of the hydraulic assembly is practically negligible compared to the overall mass of the rotating assembly.

The first lateral critical shaft speed was found to be 22.1 Hz (121% of the shaft operating speed), and the critical torsional speed was found to be 26.7 Hz (147% of the shaft operating speed).

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#### DISCUSSION

#### Method of Analysis

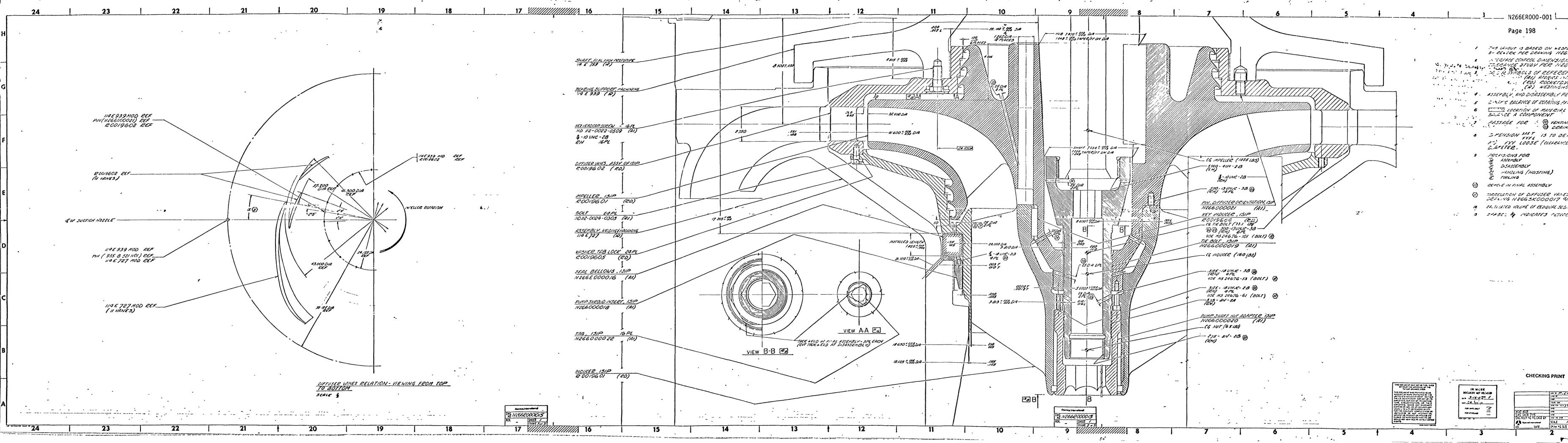
The FFTF pump rotor with the inducer/impeller was modeled using the finite element program SAPV (Reference 1). Since the pump shaft is left unchanged, with only the rotating hydraulic assembly being changed, the basic computer rotordynamic model developed for the FFTF pump (Reference 2) was used. The mass properties of the rotating assembly were calculated based on a preliminary drawing of the inducer/impeller (see Figure 1). The calculated mass properties are presented in Table 1.

TABLE 1. COMPUTED MASS DATA FOR INDUCER/IMPELLER

Item	Weight (1b)	Polar Moment_of Inertia (lb-sec <sup>2</sup> -in.)	Diametrical Moment of Inertia (1b-sec-in.)
Inducer	160.	26.6	18.4
Impeller	1025.	500.	376.

#### Analytic Model

The SAPV ISIP rotordynamic model is presented in Figure 2. The shaft portion of the model is left unchanged from the Westinghouse FFTF primary pump rotordynamic analysis (Reference 2). The computer listing of the Westinghouse model was provided in their report and was used as input data in AI's model. To verify that the model was accurate, the initial FFTF configuration was dynamically analyzed and compared to the FFTF results. The first lateral frequency calculated was 2.5% lower than the Westinghouse

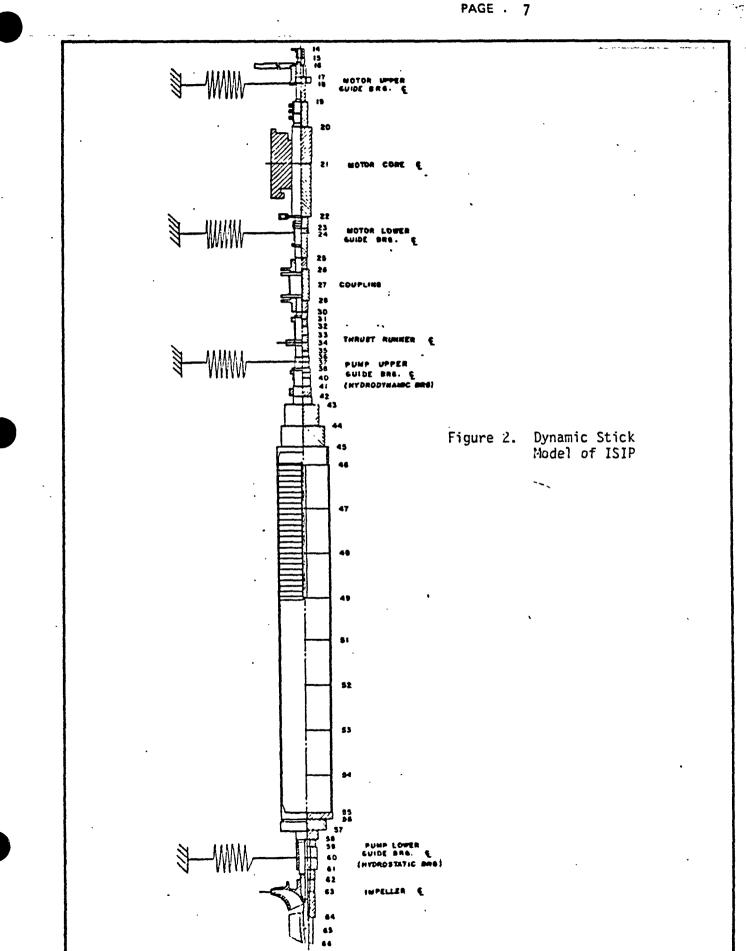


N266T1000002 Page 198 I THE LATOUT IS BASED ON WESTANGHOUSE COMPONENTS MODIFIED BY REALER PER DEAWING 112665×000017 (AI) (A) ATOMICS INTERNATIONAL (A) WESTINGHOL SE ELECTRIC CERTON A. ASSERTLY AND DISASSEMBLY FER OMM-051-00-005 ADDENDUMI. S - 2-MAN'E BALANCE OF ROTATING PARTS PER SPEC N2665T 270000 (A) LOCATION OF MATERIAL AVAILABLE FOR MACHINING TO PASSAGE FOR DEVENTING S DEFINING S DEFINION MART IS TO BEREAD: MATIGHT/MILLERELENCE F) YYY LOOSE (MEARANCE FIT); FITS ARE GIVEN PER S.AMETER. -ENDLING (HOISTING) MELELATION OF DIFFUSER VAMES TO BE ESTABLISHED PER ZEALING NEEGSKOOOOIT SIN 5,6 & 7. CELLISTED VOLUME OF RESIDUAL SOLIM IN UNDRAINED POCKETS 4821N3 STABCE & INDICATES CERUEE OF SEAVITY - , • CHECKING PRINT FIGURE 1 
 Image: State State

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N266ER000-001 Page 199 NO H266T1000002

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results. The model was also checked for accuracy, and no "bugs" were found to exist. This difference in the two frequencies is considered to be within the allowable tolerance between two different finite element programs. The torsional frequency was found to be high by 9% when compared to the FFTF results.

In the real sense, the pump shaft is a free-free system in the torsional direction, and SAPV is unable to solve this problem. In order to make the model stable, a relatively soft torsional spring is added to the motor rotor. This first frequency is a fictitious type mode with the shaft acting as a rigid body and does not affect the true shaft torsional frequency. This was verified by lowering the torsion springrate and noting an insignificant change in the true torsional frequency.

#### Results of Analysis

The significant natural frequencies and their descriptions are presented in Table 2. The results show the ISIP first critical shaft frequency of 22.13 Hz (1,328 rpm). The plotted mode shape is presented in Appendix A. This speed is 121% of the running speed of the pump. Note that there exists some discrepancy between the frequencies obtained from the AI model of the FFTF primary pump and the Westinghouse model. However, the change in frequencies when the inducer/impeller is used is small, suggesting that the installation will have little effect on operating dynamics. The torsional frequency of the ISIP will be higher (as noted in Table 2) because of the lower radius of gyration of the ISIP inducer/impeller.

## TABLE 2. ISIP CRITICAL SHAFT FREQUENCIES AND MODE DESCRIPTIONS

+

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Mode	Calcul	lated Natural F	requencies (Hz)	
	ISIP	FFTF (AI Model)	FFTF (Westinghouse Hodel)	Mode Description
1	.28	.28		*Fictitious Rigid Body Mode
2	22.14	22.14	22.87	First Pump Shaft Lateral Frequency (Critical shaft speed)
3	25.08	25.08	25.36	Motor Shaft First Lateral Frequency
4	26.69	26.34	23.95	Motor/Pump Shaft Torsional Frequency

\* Required to make the SAPV model stable in the torsional direction

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#### CONCLUSIONS

Based on the observation that little change (less than 2%) in frequency is noted with the inducer/impeller hydraulic assembly in place of the existing impeller on the FFTF primary pump, the following conclusion is made: Assuming an inducer/impeller balancing procedure consistent with the procedure used on the original FFTF pump impeller, there will be a minimal effect on the mechanical vibrational response of the ISIP.

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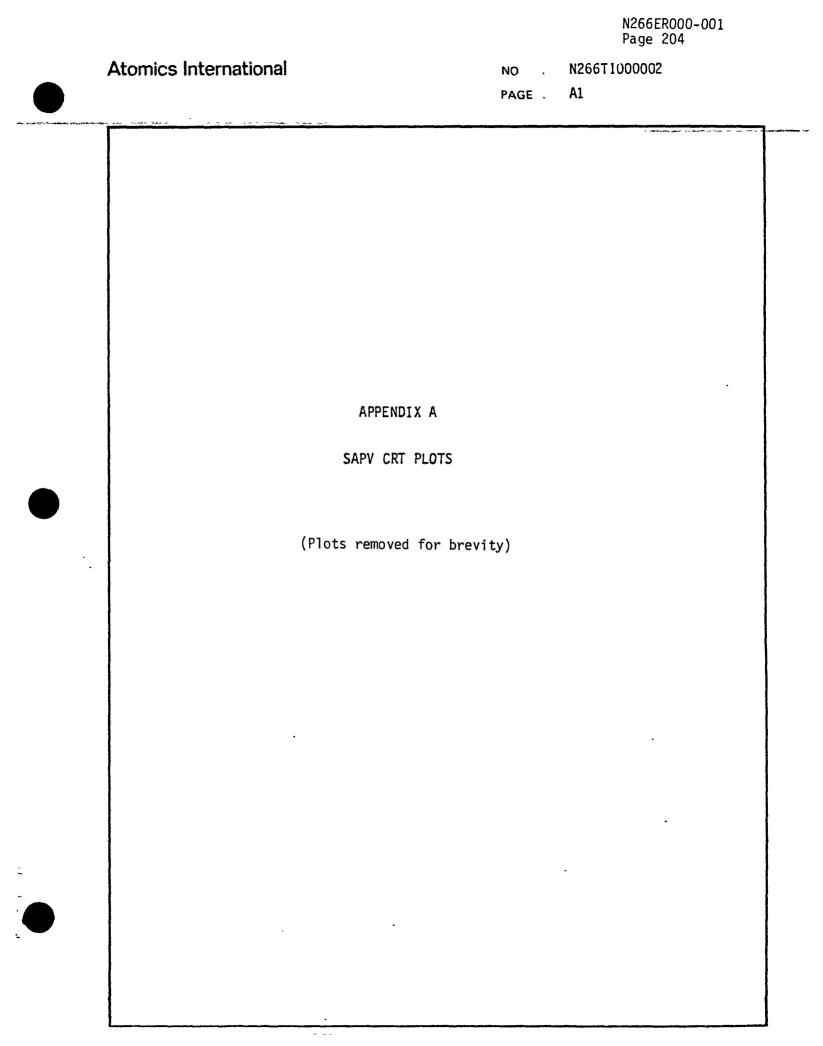
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### REFERENCES

- SAPV, "Structural Analysis Program," E. Wilson, University of California, Berkeley, California, USC Version - 1976
- "FFTF Primary Pump Rotor Dynamics Analysis," Engineering Memorandum No. 4708, Revision 2, by L. C. McNutt, Westinghouse Electric Corporation, Electro-Mechanical Division, Cheswick, Pennsylvania, February 9, 1977



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NO . N266T1000002 PAGE . B1

APPENDIX B

SAPV COMPUTER OUTPUT

(Computer printout removed for brevity)



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## APPENDIX F

## RADIAL TOLERANCE STACKUP - ISIP

ESG Document N266TI000004

Rockwell International Atomics International Division	DRTING DOCUMENT	NUMBER N266T1000004	REV LTR/CHG NO. A SEE SUMMARY OF CHG
PROGRAM TITLE Intermediate-Size Indu DOCUMENT TITLE Radial Tolerance Stack PREPARED BY/DATE M. Grisham M? Sou	ABSTRACT ABS	CHECK ONE BOX ON DOE D UNCL D CONF D SECRET D AUTHORIZED CLASSIFIER Vsis for the Int as been performe learances betwee ents at room tem emperatures to t a part of the t ated radial clea the four condit r all fits and t r maximum parall ces of static/hy eller assembly r maximum parall ces, and maximum nents for worst condit	PAGE 1 OF 35 TOTAL PAGES REL. DATE 5-10-79 RK CLASSIFICATION LY) (CHECK ONE BOX ONLY) RESTRICTED DATA DEFENSE INFO DATE DATE DATE
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REV	SUMMARY OF CHANGE	APPROVALS AND DATE
A	Page 16 was deleted. It is no longer a controlling fact. The possible .002 offset between the diffuser and diffuser shroud was added to tolerance Stackup.	m Brisham Rollins 5-10-29
	For condition 4, possible tilt of inducer was change to .0080 from .0045. Condition 5 was added.	
		Rel.Date:5-10-79 BK
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-		CONTENTS
		Page
	I.	INTRODUCTION 3
	II.	APPLICABLE DRAWINGS 4
	III.	SUMMARY
	IV.	COMPUTATION
		A. Condition 1 7
		B. Condition 2 14
	l	C. Condition 3 19
		D. Condition 4



#### INTRODUCTION Ι.

NO

The existing FFTF primary sodium pump is used in the hot leg of the reactor heat transport system. It is designed to pump liquid sodium at 1050°F temperature, with the low 350°F temperature of transient slugs. The flow rate is 14,500 gpm, with total head of 500 ft. The FFTF prototype sodium pump was fabricated by Westinghouse (EMD) and initially tested in the sodium test facility (SPTF) in the Energy Technology Engineering Center (ETEC). To build the Intermediate-Size Inducer Pump (ISIP), the prototype sodium pump is to be modified by HEDL to facilitate interchangeable installation of an inducer type pump, engineered and fabricated by Rockwell International. The rework involves modification of the Westinghouse bearing support flange for a closer control of axial dimension and of normality, and of the static hydraulics for a control of axial size and flatness. All rework is to be performed per AI Drawing N266000017.

This analysis was performed to demonstrate that the radial clearances of assembly will be adequate to prevent rubbing. Evaluation of the results was by magnitude of the calculated minimum clearances and comparison of these values for those in the FFTF Prototype Pump which was tested under similar conditions in SPTF without evidence of rubbing. Completion of this analysis completes the Engineering response for Action Item No. 25 in the ISIP design review report (N22DRR000003).

The computed radial clearances for selected location are performed for four conditions with progressively compounding effects.



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## II. APPLICABLE DRAWINGS

Item	Drawing Number	Revision	Title
1	114E799	14	Shaft, Final Machining Prototype
2	114E939	8	Bearing, Support Machining, Sodium Pump
3	114E727	14	Assembly, Welding and Machining, Sodium Pump
4	115E116	7	Bearing Assembly
5	R0019601	NC	Impeller - Intermediate-Size Inducer Pump (AI Sodium Pump)
6	R0019602	NC	Diffuser/Vanes - Assembly of Intermediate-Size Inducer Pump (AI Sodium Pump)
7	R0019603	NC	Inducer - Intermediate-Size Inducer Pump (AI Sodium Pump)
8	N266000012	D1	Pump Shroud Insert - ISIP
9	N266000017	D2	Intermediate Size Inducer Pump, Westinghouse Components Rework Sketch (ISIP)

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Rockwell International Energy Systems Group NO . N266TI000004 PAGE . 5

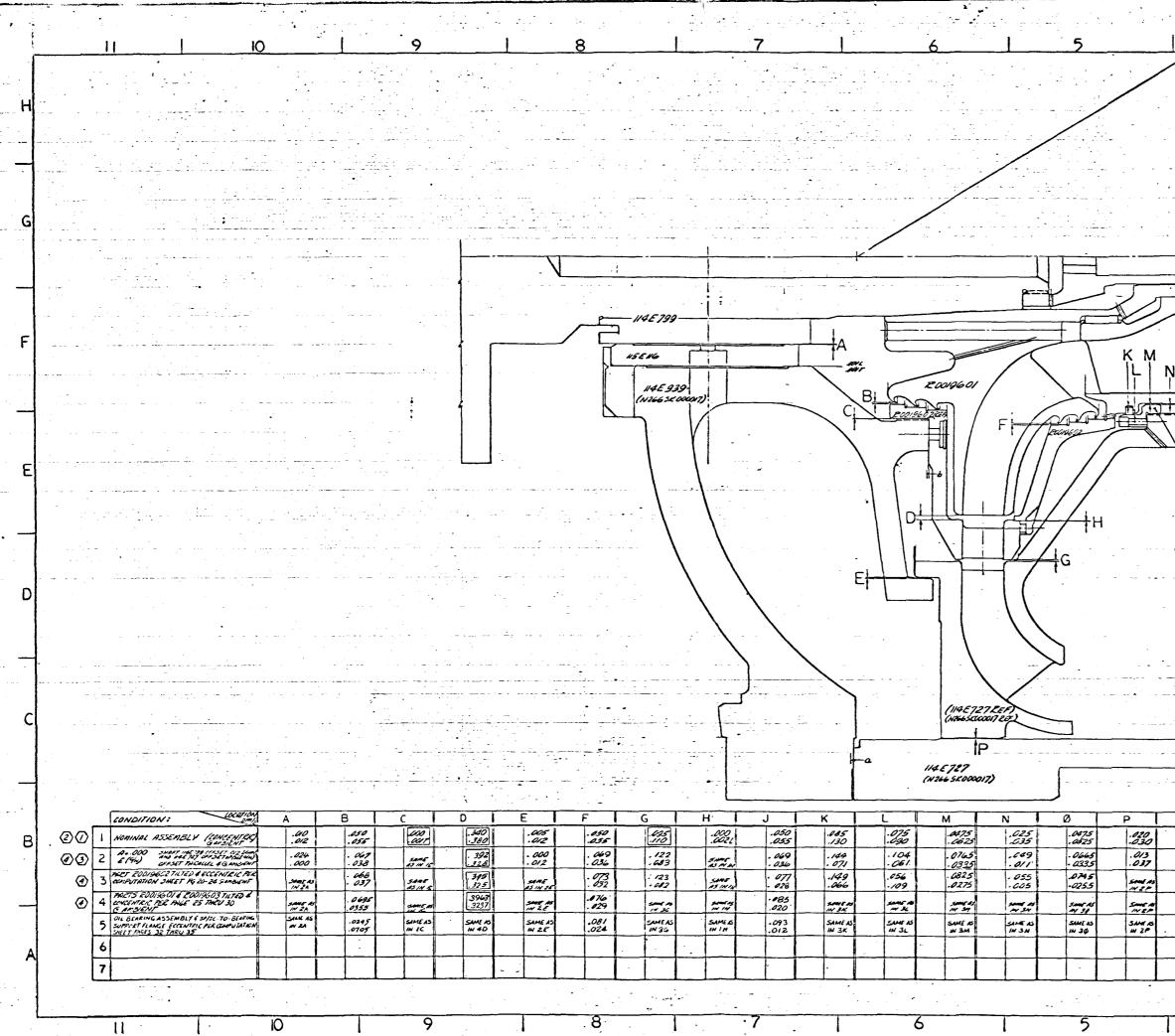
#### III. SUMMARY

The computations of radial clearances indicate a minimum gap .012 in. wide between rotating component R0019603 (inducer) and stationary R0019602 (diffuser assembly) in Location "J" of Condition 4, at ambient temperature.

Although mathematically this condition is possible, the stackup of multiple adverse coincidences in maximum values is improbable and represents a hydrostatic bearing failure mode by film depletion expressed in Condition 2. Due to R0019603 rotation, the value "J" in Condition 4 is extreme in one location only, as defined by the plane of maximum tilt of Part R0019602.

All values of radial gaps, in specific locations and under cited conditions, are summarized on Page 6.

Computation of radial gap values are to be found on Pages 7 through 32.



N266ER000-001 Page 213 REVISIONS DATE DIMENSIONS XXX INDICATE MIN-MAX VALUES PER RADIUS BASED ON DEAMING TOLERANCES
 DIMENSIONS XXX INDICATE MIN-MAX VALUES PER RADIUS BASED ON AVERAGE OF MEASURED (\*AS BUILT?) SIZES 3 ANA WOICATES & SIZE OF LADIAL GAP ON OPPOSITE SIDE BASED ANN WAX SIZES OF CONDITION 1. THE CLARIFICATION OF MOVEMENTS SEE NOTE IN COMPUTATION SHEETS 2 001960 N266 0000 12 R S U V Atomics International Division RADIAL STACK UP- 151P -PAGE 6 09974 N266T1000004 HITEFINDIS APPLICAT 4 3 stori fite para ÷

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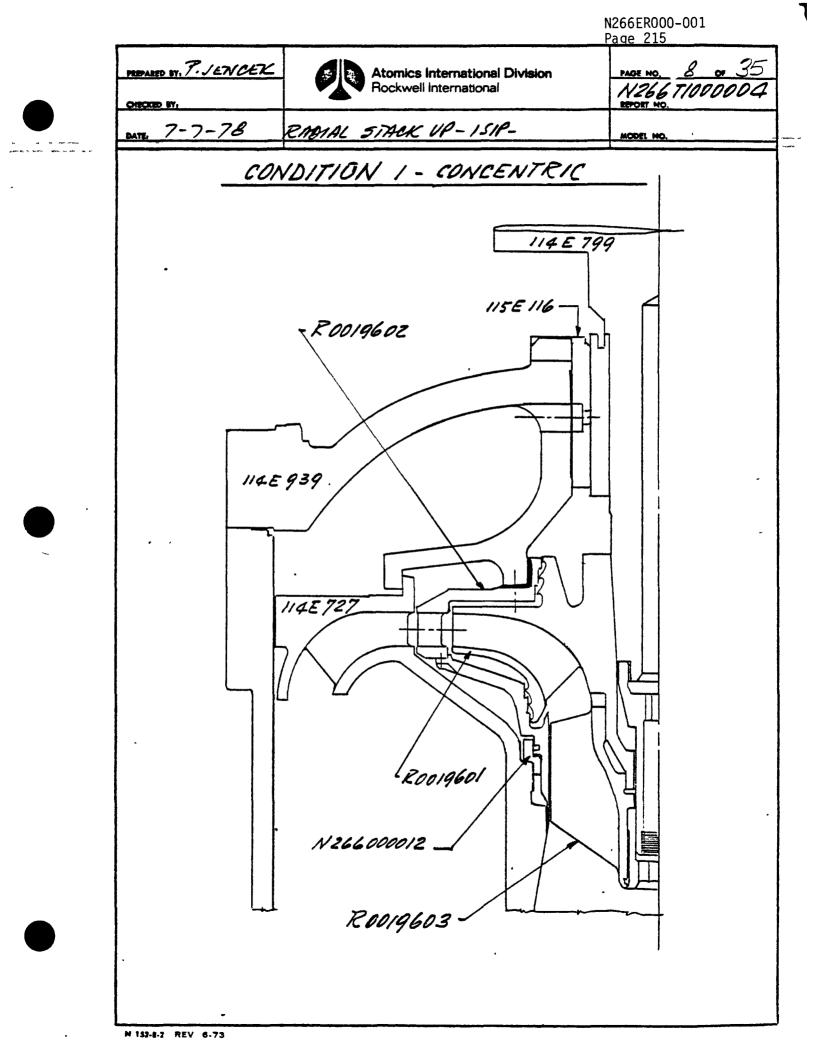
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#### IV. COMPUTATION

A. CONDITION 1

All parts are concentric, and axes are parallel. This is an ideal condition. Clearance values are nominal.

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## B. CONDITION 2

- The shaft moves parallel within the bearing by .012 in. for metal - to metal contact. During the pump operation, this represents an entry into the failure phase.
- 2) The static hydraulic moves parallel by .012 against bearing support in the opposite direction of shaft movement.
- 3) Parts 114E939, 115E116, and R0019602 are thus approached from both sides to decrease radial clearances for same values as radial clearances increase 180° apart.
- 4) The diffuser shroud moves Parallel by .002 relative to the diffuser.

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C. CONDITION 3

Due to normalcy and parallelism tolerances of Parts 114E939 and 114E727, Part R0019602 is tilted. The origin of tilt is approximately at elevation of interface between Parts 114E939 and 114E727.

Radial clearances are calculated by use of variable correction value as a function of distance from the tilt origin.

The resulting radial clearances of Condition 3 are compounded values including those of Condition 2.

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D. CONDITION 4

This condition compounds the effect of tilts, originating in concentricity tolerance callouts of Parts 114E799, R0019602, R0019603 on the radial stackup of values of Condition 3. Considered are:

- Concentricities of the shaft taper to the axis of shaft rotation (male taper).
- 2) Concentricity of the impeller taper ends (female taper).
- 3) Concentricity and diametrical clearance of two (male) impeller pilots and normalcy of impeller interface plane against the inducer - extrapolated and related to axis of rotation.
- 4) Concentricity of two (female) pilots and normalcy tolerance of mating plane for the inducer interfacing with the impeller - extrapolated to lower end of the full inducer vane diameter and related to axis of rotation.
- 5) Item 4 is then related to tilted Part R0019602 from Condition 3.

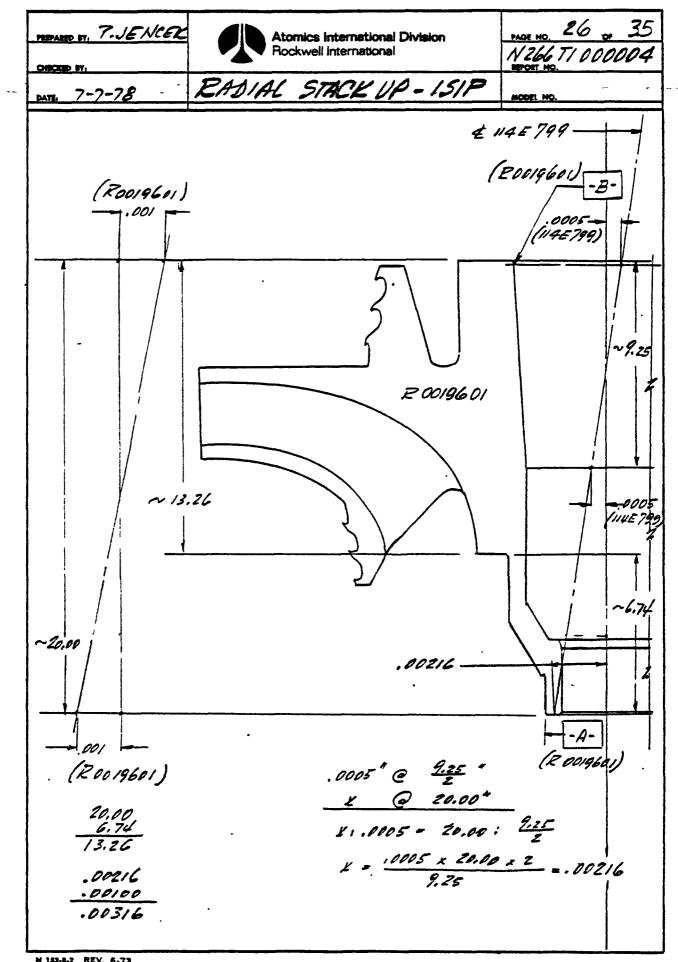
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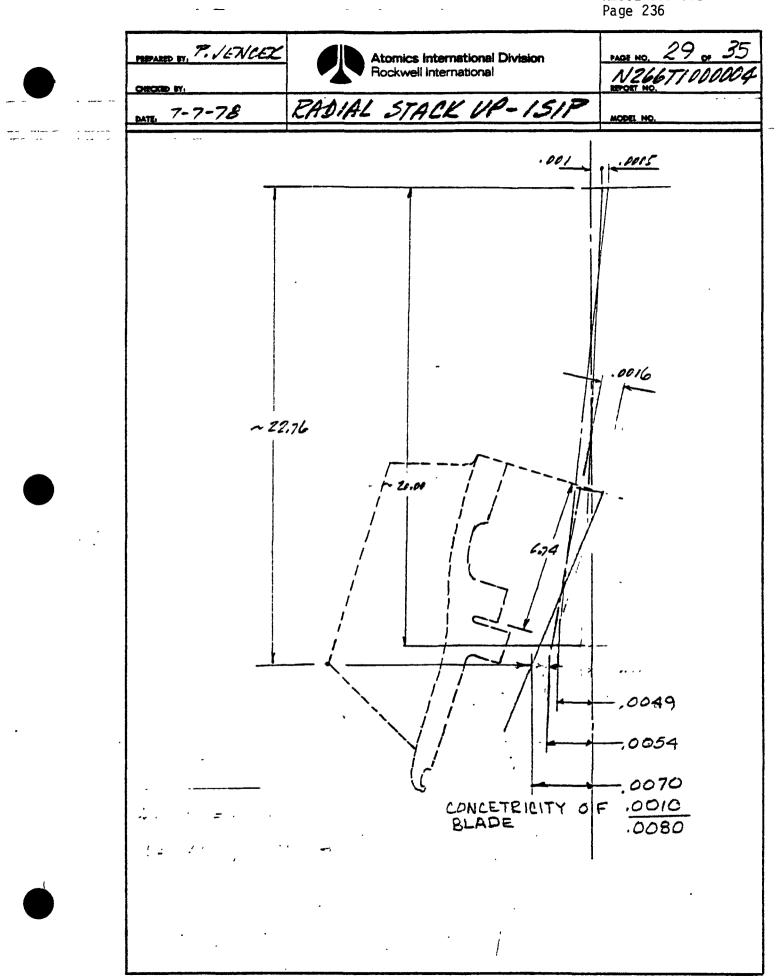
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28 35 PREPARED WY. P.JENKET **Atomics International Division Rockwell International** N266TI 000004 RADIAL STACK VP-ISIP MTE. 7-7-78 NODEL NO (RO019601) --- 1.00025 5.68 5.68 1.00125 ±.001. .003/4 -*B*-001 .003 E 20019603 Roc19601, 7.24 ~6.74 LOPSE) (=) :0005/R 20019603 E0019603 . OC15/R LONC (1.71¢) .001 .002 5.68 00162.00Z .00/25 7.24 <u>,0025</u> <u>-</u> 11.358 <u>7.29</u>0 NOTE: COMPOSITE NORMALCY TOLERANCE OF PARTS RODIAGOI & R. COIG603 . DOITS ALLOWS THE INDUCER TO TILT, AS CAUSED BY THE COMPINED LOO SERESS & CONCENTRICITY TOLEN FRICE IN PILOT B, WITH THE FULCEUM OF TILT IN PILOT A (INTERF, FIT



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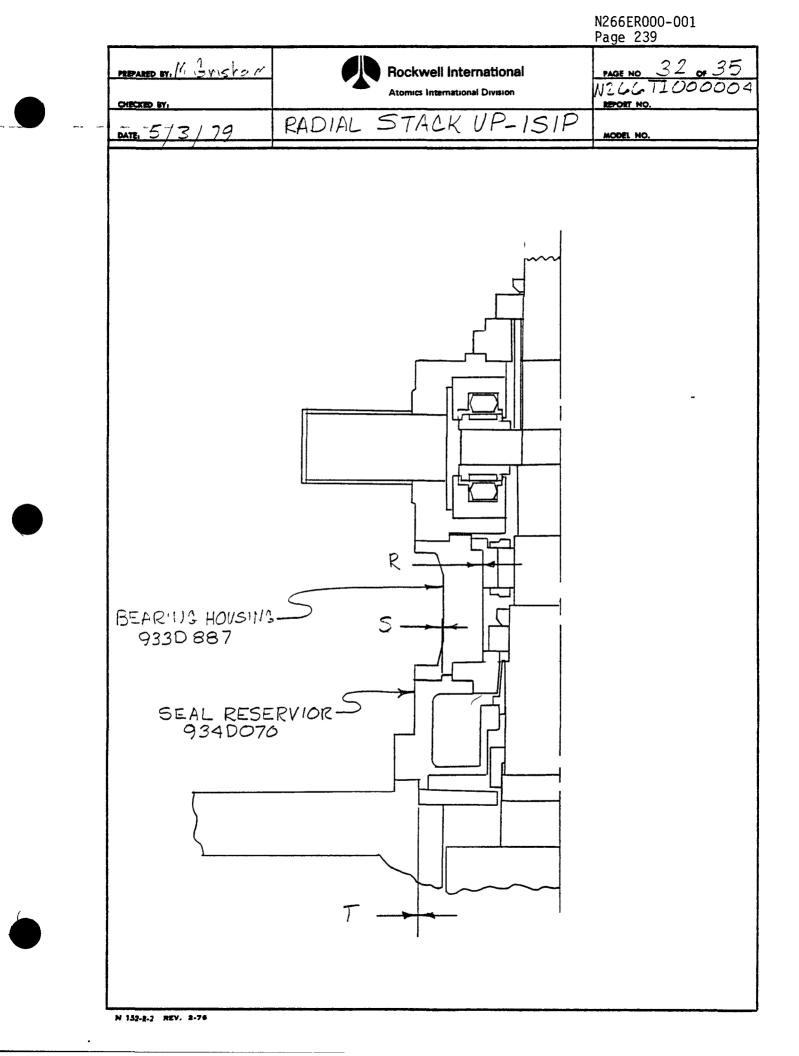
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Rockwell International Energy Systems Group NO · N266TI000004 PAGE · 31

# CONDITION 5

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APPENDIX G

# HYDRODYNAMIC DESIGN REPORT

Rocketdyne Document R/H 8113-3630 (Assigned ESG Document number is N266ER000-002)

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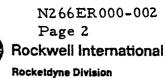
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FORM 734-C REV. 11-75



R/H 8113-3630 -----26 April 1978

HYDRODYNAMIC DESIGN REPORT INTERMEDIATE SIZE INDUCER PUMP FOR SODIUM OPERATION

CONTRACT EY-76-C-03-0824

Prepared for

ATOMICS INTERNATIONAL DIVISION ROCKWELL INTERNATIONAL CORPORATION

Prepared by:

E. D. Jackson Manager Hydrodynamic Unit Rocketdyne

J. A. King Member Technical Staff Hydrodynamic Unit Rocketdyne

F. C. O'Hern Member Technical Staff Hydrodynamic Unit Rocketdyne

Approved by:

E. D./Jackson Manager Hydrodynamic Unit Rocketdyne

D. E. Davis Program Manager Advanced Programs Rocketdyne

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#### INTRODUCTION

The Intermediate-Size Inducer Pump (I.S.I.P.) was designed to operate in the existing FFTF pump housing and to achieve the required pump head rise at the same speed and flow as the existing pump. The existing pump consists of four basic hydrodynamic elements:

- 1. Inlet Elbow
- 2. Centrifugal Impeller
- 3. Vaned Diffuser
- 4. Discharge Housing

All of these elements except the centrifugal impeller were to be retained in an unmodified form for the I.S.I.P. design. The centrifugal impeller was to be replaced with a new design consisting of both an inducer and centrifugal impeller. The objective is to demonstrate the capability of designing an inducer pump for long life in sodium operation so that the advantages of the inducer pump can be realized in future sodium pump applications. These advantages consist primarily in the smaller envelope size and lower weight realized as a result of the better suction performance capability of the inducer. These advantages result in significant cost savings and ease of fabrication and handling for the very large pumps required in many of the reactor coolant loop systems.

The vaned diffuser in the existing design attempts to diffuse the flow while turning it which typically limits the stable range of operation. Tests of the existing pump have demonstrated instability at a flow of approximately seventy percent of the design flow. The I.S.I.P. design must use this same diffuser, therefore to attempt to extend the stable operating range, Rocketdyne has chosen to design the centrifugal impeller to a smaller outer diameter to leave sufficient space to add an intermediate vaned diffuser upstream of the existing diffuser. This new diffuser would be designed to operate over a wider flow range and should provide a wider range of stable operation for the overall pump.

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Thus, the I.S.I.P. design consists of three new hydrodynamic elements:

- 1. Inducer
- 2. Centrifugal Impeller
- 3. Intermediate Vaned Diffuser

This report describes the hydrodynamic design features of each of these. The report also discusses the design rationale and methods of analysis. Following this, the hydrodynamic performance of the design is presented and compared with the design specification.

The specified sodium characteristics used in the design are:

Fluid Inlet Temperature = 1050<sup>0</sup> F Fluid Specific Weight = 50.97 lb/ft<sup>3</sup>

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#### SUMMARY

An inducer pump has been designed to fit within the existing housing of the FFTF facility. The new design consists of three primary hydrodynamic components: An inducer, centrifugal impeller, and intermediate vaned diffuser. The hydrodynamic design of each component has been based on the design procedures and analytical techniques developed over a twenty-five year period and proven to be accurate by detailed comparison with test data.

The design has been shown to meet the specified requirements in every area where an analytical prediction of the performance can be made. The head-rise and efficiency of the pump have design margins so that the calculated values actually exceed requirements over the full range of operation. The suction performance of the design provides a very large margin at the operating NPSH value which is the major advantage of using the inducer pump. The suction performance margin at off-design is estimated to be adequate for suction performance, but may not be as large as desired for life considerations. Testing of a model inducer is required to verify the suction performance at off-design and to evaluate the life potential. Operation of an impeller pump with similar margins would also require test verification of the life potential.

The design has incorporated features that provide for long life at the design point. These features have been established based on proven performance of commerical waterjet pumps designed by Rocketdyne. Each of the major design parameters contributing to long life fall within the range of previously verified designs except for a somewhat larger tip clearance. Analysis has indicated that the tip clearance is acceptable.

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## DESIGN DESCRIPTION .

#### Inducer

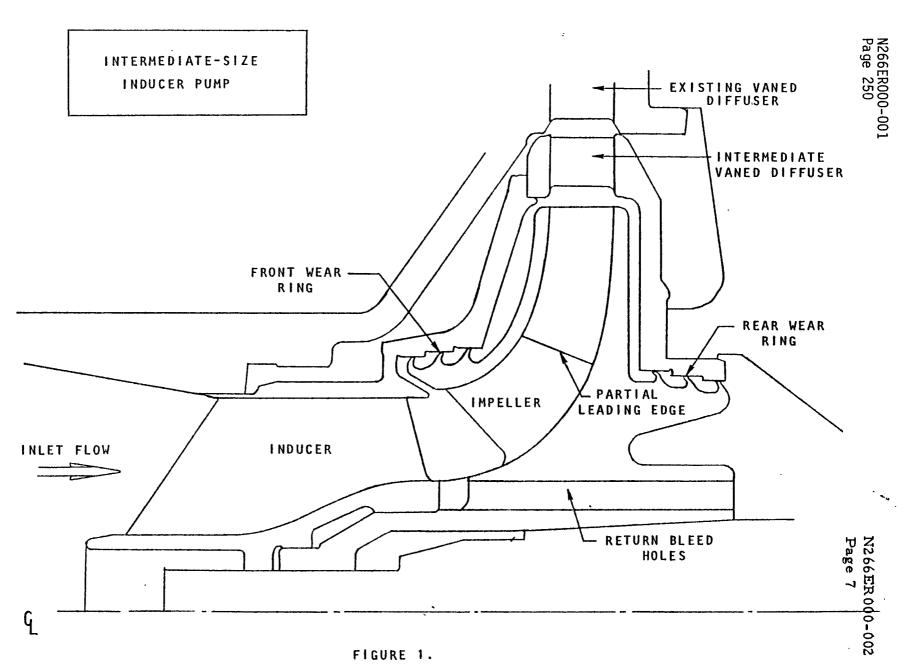
Figure 1 shows a layout of the pump configuration indicating the various hydrodynamic components to be discussed. The inducer design was based on the same design practices established and demonstrated by the successful waterjet inducer designs at Rocketdyne.

The inducer was designed with four blades to minimize the potential of tip vortex collapse on the blade surface and thereby eliminate collapse damage. The four-bladed design also provides minimum potential for radial loads for any NPSH margin provided to the inducer. The envelope of the pump was sufficient to handle the required length of the inducer using only four full blades without any partial blades. Elimination of the partials ', improves confidence in achieving the long life required.

The inducer tip diameter was designed to be 18.53 inches, an unshrouded tip configuration being used to achieve cavitation collapse in the fluid passages and not on the blade material. The tip diameter was dictated by three factors:

- 1. The existing housing outer diameter.
- 2. The required operating clearance of 0.050 in. radial.
- 3. The need to provide a smooth wall contour over the inducer tip.

The longer length of the four-bladed inducer requires it to extend beyond the point where the leading edge of the existing impeller was located. As a result, if the existing housing were used without a liner over the tip of the inducer, a circumferential slot would occur over the inducer and could create cavitating vorticees which could cause hardware damage. Thus, a liner was added to eliminate any slot over the inducer itself.





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The required tip clearance is set by the rotor dynamics of the pump in the facility. This clearance is somewhat larger than values commonly achievable in waterjet practice. However, the effect of the larger clearance was included in both the performance and life analyses. To further avoid any potential for rubbing at the tip, the blade was designed for zero cant angle so that any blade movement would not decrease the operating clearance.

The hub contour was selected to optimize the performance and match the required impeller inlet design. The hub diameter at the inlet is 6.626 in. giving a hub/tip diameter ratio of 0.358. This inlet diameter is selected to achieve the desired suction performance and to maintain the flow co-efficient in the region where confidence in long life is high. The discharge hub diameter is 11.358 in. and is selected for optimum efficiency of the inducer-impeller combination. The contour shape of the hub from inlet-to-discharge is based on established procedures optimized for achieving the proper head-rise distribution along the stream surfaces through the inducer.

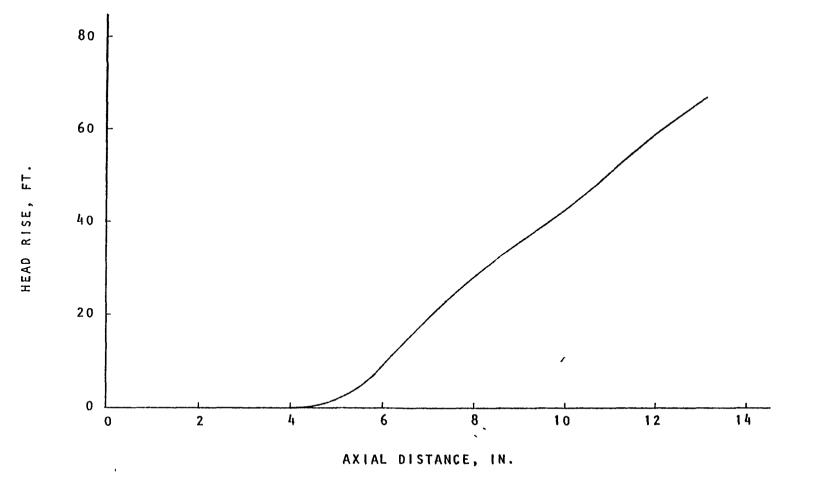
The blade design includes such factors as leading edge blade angles, blade camber distribution, blade thickness distribution, leading-edge and trailing-edge sweep and blade solidities. These values are selected based on previous commerical experience, and in each case the I.S.I.P. values are consistent with waterjet design experience at Rocketdyne. The blade design is of primary importance in achieving

- 1. The optimum suction performance capability
- 2. The long-life with no detrimental blade damage
- 3. The required head and maximum efficiency

One of the results desired in the design is a head-rise distribution through the inducer that is monotonically increasing at a somewhat uniform rate. Figure 2 shows the result achieved in the I.S.I.P. inducer design



ISIP INDUCER PREDICTED HEAD RISE THROUGH INDUCER (BASED ON R3DP) Q = 14600 GPM N = 1110 RPM



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FIGURE 2.

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indicating its agreement with this design criterion. It is also desirable to achieve a relatively uniform head distribution at the inducer discharge and impeller inlet. Figure 3 indicates that this was accomplished.

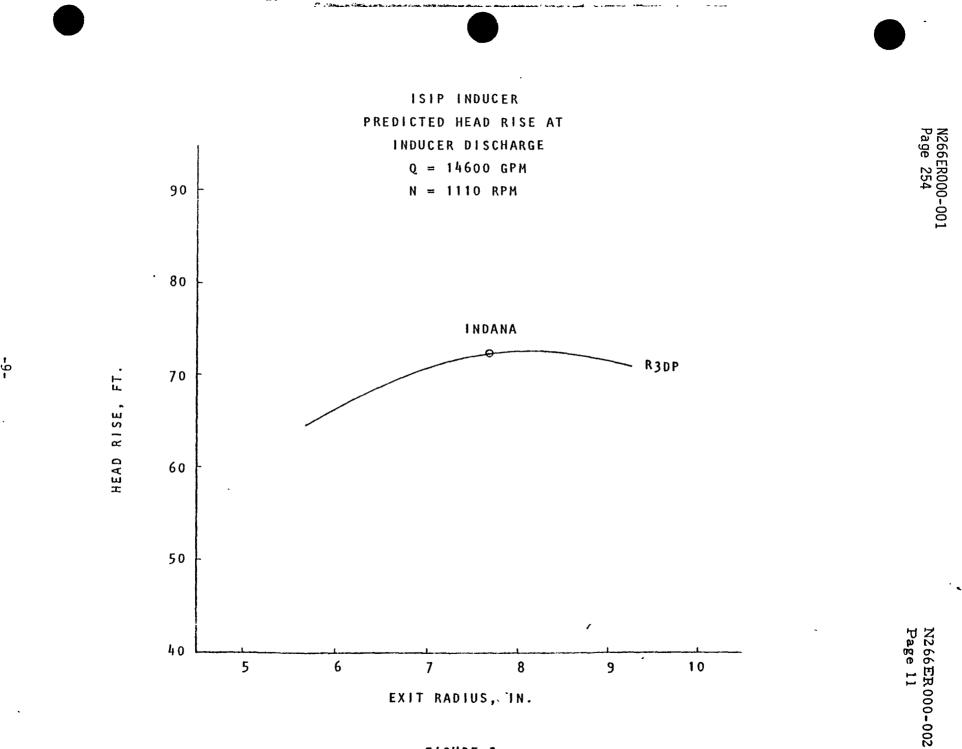
Five Rocketdyne computer programs were used in the hydrodynamic design and analysis of the inducer. The first was the nonisentropic radial equilibrium program (NISRE) which calculates the head-rise and meridional velocity leaving the inducer at all radii for a fixed (radial) blade. This was used in the preliminary design portion of the analysis to obtain the desired moderate blade loading.

After the blade meanline was calculated, an initial blade thickness was assigned on the basis of past experience. The entire inducer geometry was then input into the three-dimensional analysis program. This program (unlike the NISRE) takes into account the curvature of the walls before, within, and following the inducer as well as the blade contours. It calculates the local static pressures on the suction and pressure sides of the blades at all stations and at all radii. These pressures are used to determine where the blade will cavitate and where the cavity will collapse. They are also used by Stress to determine the blade loadings from which the final blade thickness is determined. The program also calculates the head-rise at each streamline and the relative velocities entering the centrifugal impeller. These are used to determine the desired blade angles at this station.

The third program used was the blade leading edge loading program which calculates the loading on the leading edge wedge. This loading was combined with that of the three-dimensional analysis program and given to Stress. The combined loads at the design point are shown on Figure 4.

The fourth program predicts the jet stopping distance of a cavity progressing across the passage from the suction side of the blade to the pressure side. If the cavity travels as far as the pressure side of the next blade before collapsing, it might cause damage on that blade.

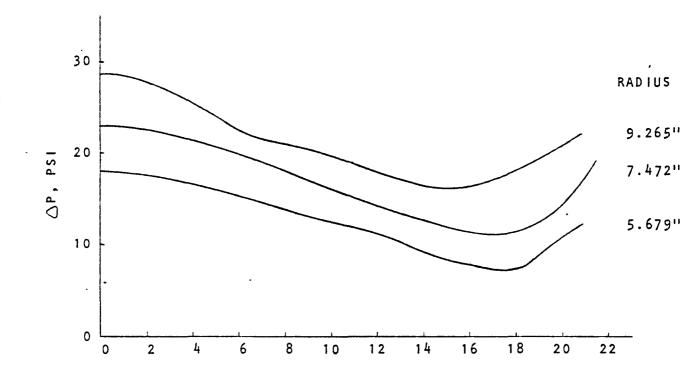
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ISIP FOUR-BLADED INDUCER BLADE LOADING Q = 14600 GPM N = 1110 RPM



BLADE LENGTH, IN.

# FIGURE 4.

The fifth program is the "INDANA" program which is used to calculate the inducer head and efficiency over the full operating range. The calculated performance for I.S.I.P. is presented later in the report in the performance section.

#### Impeller

The impeller is a shrouded radial-discharge centrifugal-type impeller designed to generate the required head-rise. The impeller has five full blades and five additional partial blades at the discharge. The location of the leading edge of the partials is shown schematically on Figure 1. The number of blades is chosen to optimize the efficiency and generate the required head at the design point. The transition from four inducer blades to five inlet impeller blades is not uncommon in optimum design practice and creates no detrimental effects.

The inlet diameters and blade angles were set based on flow conditions at the inducer discharge. The diameters are essentially a continuation of the inducer discharge diameters. The flow angles at the impeller blade leading edge are a result of an extropolation from the inducer discharge using continuity of flow and constant angular momentum. The eye diameter is 19.0 inches and inlet hub diameter is 11.36 inches. The eye diameter is slightly larger than the inducer diameter to accommodate the additional wear ring leakage flow.

The inlet section of the blades are designed for no cavitation, and therefore no cavitation damage and long life are assured. This is made possible by the inclusion of the upstream inducer which provides sufficient headrise to eliminate impeller cavitation either on the blade or in the vorticees generated in the wear ring return flow.

The discharge width of 2.75 inches was set equal to the first diffuser width which in turn was set equal to that of the existing diffuser.

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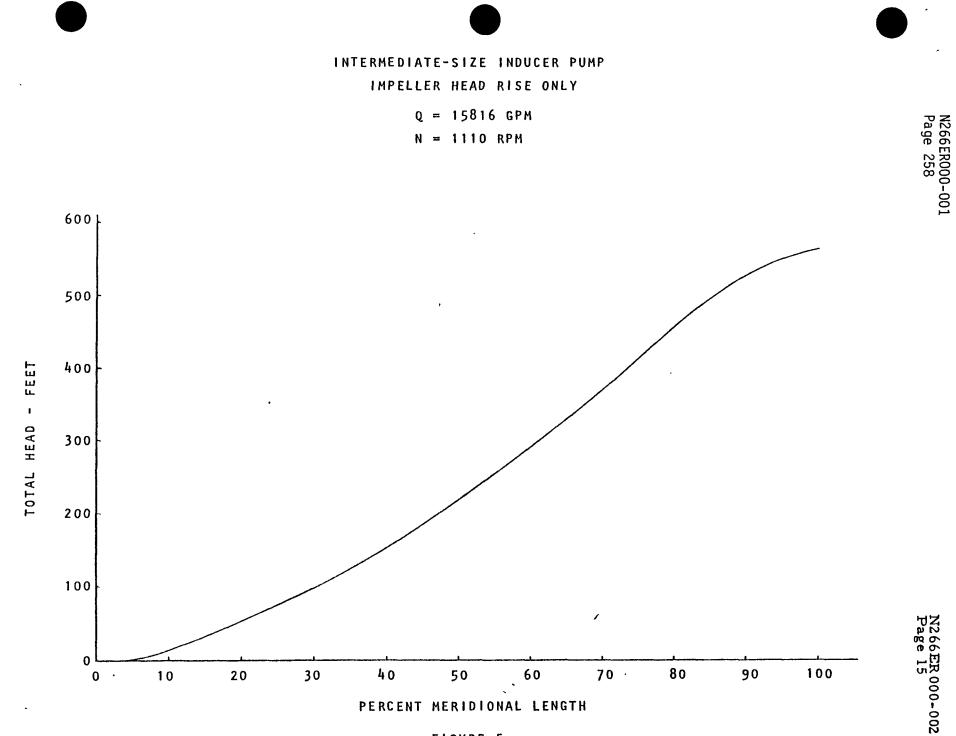
This width is wider than required for this operating condition and probably results in a somewhat lower efficiency. However, the I.S.I.P. design must match the existing diffuser in the existing housing, and a mismatch on the width could be a larger efficiency penalty than using the existing width. The discharge diameter of 35.40 inches, number of blades, and blade angle were balanced in such a way to allow room for another diffuser and still generate the required head. This was based on previous Rocketdyne pump experience developed in the design and test of numerous centrifugal impellers used in the turbopumps of the engines for the national space program.

The shroud and hub contour shapes and the blade camber distributions are selected to achieve a uniform loading and head generation distribution. Figure 5 presents the average head-rise at the design point generated through the impeller as a function of meridional length. Similar pressure loading curves at lower flows were generated to assure structural integrity at off design. Figure 6 presents the blade load distribution generated for the Stress department to determine blade stresses.

Two computer programs are used in the impeller design and analysis effort. The quasi-three-dimensional analysis program "VELDIS" was used to analyze the local velocity and pressure field throughout the impeller bladed section. This program provides the design verification that no detrimental regions of back flow or cavitation are occurring in the impeller. The output from the program also provides the head distribution and blade loads previously presented in Figures 5 and 6. The second program is an overall pump performance prediction program that performs a detailed calculation of the various losses that can occur in the pumping elements as well as in the diffusers. This program was used to calculate the head and efficiency over the full operating range, and the results are presented in a later section.

## Intermediate Vaned Diffuser

A short, ring diffuser was added between the impeller and the existing

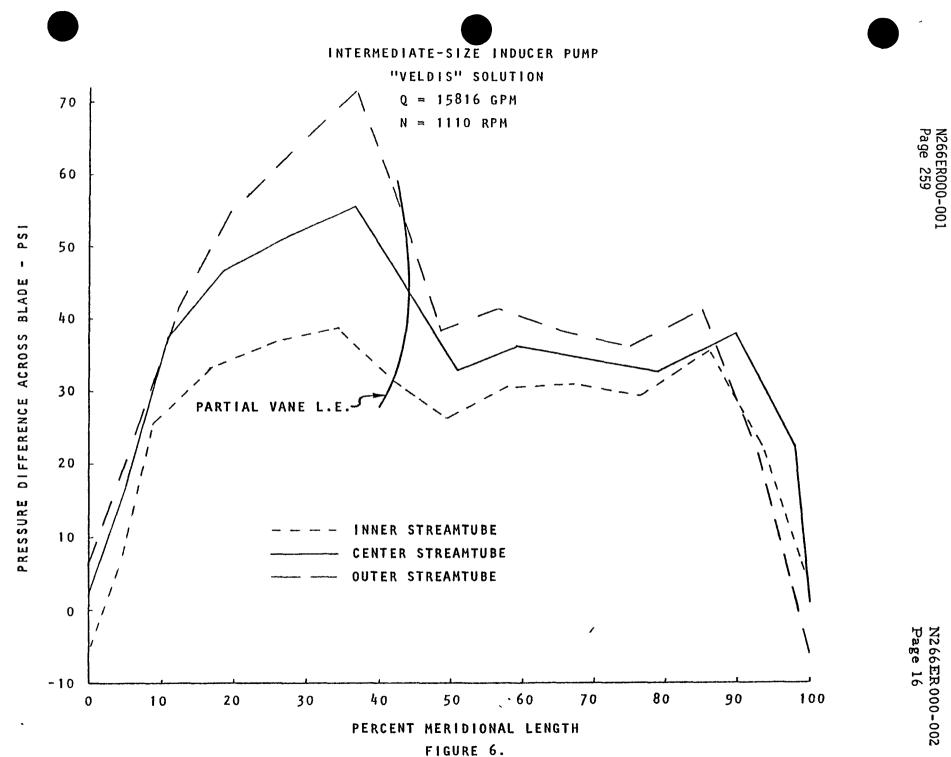




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diffuser in an attempt to increase the stable flow range of operation. This diffuser will provide a flow into the Westinghouse diffuser with a smaller angular variation over the flow range than would be available directly from the impeller.

The discharge width and number of vanes were set to provide a match of the inlet flow angles to the vanes of the Westinghouse diffuser. The eleven vanes of the intermediate diffuser are staggered between the eleven vanes of the existing diffuser to minimize boundary layer build up and separation with its attendant loss in efficiency. The diameters of the intermediate diffuser are 37.2 in. at the inlet and 42.0 in. at the discharge. The discharge diameter was set by the housing geometry and the inlet diameter was set by the impeller diameter, allowing sufficient clearance to avoid cavitation or fatigue damage to the impeller or diffuser.

The vane profile is a double-circular-arc design with a 7.4 percent ', thickness. The profile and thickness were selected consistent with good hydrodynamic practice and to control the hydrodynamic loading on the vanes to meet the required structural integrity.

The inlet vane angle was set to match the flow from the impeller at the design flow and the discharge angle was set to provide a flow matching the inlet vane angle of the Westinghouse diffuser. The required vane angles and diameters combine to give a solidity that provides the required diffusion.

The diffuser was designed using the same methods developed for the space program centrifugal pump designs. These design techniques have been proven based on tests over an extensive flow range. The losses associated with the flow through the diffuser were calculated using the same centrifugal pump loss program discussed in the impeller section.



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### HYDRODYNAMIC PERFORMANCE

### Design Point

The specification design point required an overall head-rise of 500 feet flange-to-flange while pumping a delivered flow of 14500 gpm of sodium at a rotational speed of 1110 rpm. The I.S.I.P. calculated head-rise at these conditions is 546 feet providing a nine percent margin in meeting the required 500 feet. The projected efficiency of the pump at the design point is 74 percent giving a required power of 2037 Hp. This quoted efficiency also has a margin, based on calculations, of four percent.

The program used for the analysis has been quite successful in the prediction of performance on other pumps. This program was developed over the past twenty-five years and checked out by consistently comparing predicted results with pump internal data collected in various test facilities. The program calculates the Euler head-rise for each of the rotating elements and the losses that affect both head-rise and power in each of the components. Table 1 presents the respective head and loss values for each of the components at the design point indicating the margin in the design head-rise. The head can easily be reduced to exactly 500 feet, if required, by trimming the impeller. The calculations for the Westinghouse diffuser system were performed with the available information for the design, but they contain a degree of uncertainity due to the lack of more specific design information.

### Range of Operation

The pump is required to operate over a relatively large flow range. The maximum flow at the design speed is 18,000 gpm at which point the head-rise must exceed 375 feet. The minimum flow is not specified, but it was desired to achieve a stable operation for flows lower than that achieved with the Westinghouse design.

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# TABLE 1

# DESIGN POINT PERFORMANCE CALCULATIONS

DELIVERED FLOW = 14,500 GPM SPEED = 1110 RPM

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COMPONENT	EULER HEAD	LOSSES	CUMULATIVE DEVELOPED HEAD
INDUCER	79.2	7.2	72 FT.
IMPELLER	630.0	63.0	639
INTERMEDIATE DIFFUSER	-	17.0	622
WESTINGHOUSE DIFFUSER	-	43.0	579
DISCHARGE SYSTEM	-	33.0	546 FT.
DESIGN MARGIN = 46 FT. ( 9%)			

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The predicted overall head and efficiency are shown in Figure 7 assuming that the margin shown by the calculations is not realized in actual operation. The head-rise at the 18,000 gpm flow is projected to be 470 feet well in excess of the 375-foot minimum value. The negative slope of the head-flow curve is predicted to extend down to 8000 gpm. The existing pump was reported to have a stability problem between 10,000 and 12,000 gpm, and the vaned diffuser is expected to be the primary cause of the instability. The additional diffuser designed by Rocketdyne should help to extend the stable flow range, but the stable range cannot be guaranteed because the same Westinghouse diffuser is being used.

Figure 8 presents the head and efficiency of the inducer portion of the pump. This head must be sufficient to keep the impeller out of the cavitation region which causes head fall-off.

### Pony Motor Operation

The specification required that at the pony motor speed of 94 rpm, the head-rise was not to exceed five feet of head. Figure 9 presents the scaled head-rise over the required flow range. The maximum head is four feet which is within the specification requirement.

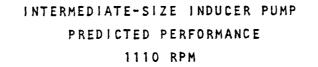
### Life Requirements

The specification requires a 20 year life at the design point and a worstcase, off-design life of 250 hours at 18,000 gpm and design speed of 1110 rpm. The inducer design incorporates the long-life design features established and verified through Rocketdyne's waterjet pump experience. The significant parameters that affect the life of the machine have all been chosen to fall within the range of those parameters actually used in the waterjets. This includes such parameters as the leading edge sweep, flow coefficient, incidence angle, inlet blade angle distribution, cant angle, and tip thickness. The one parameter which was slightly outside

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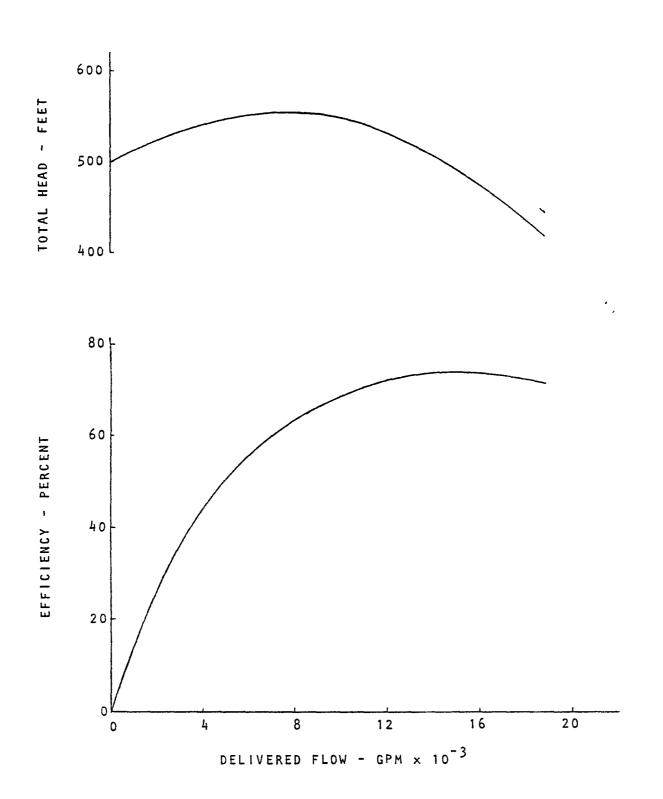


FIGURE 7.

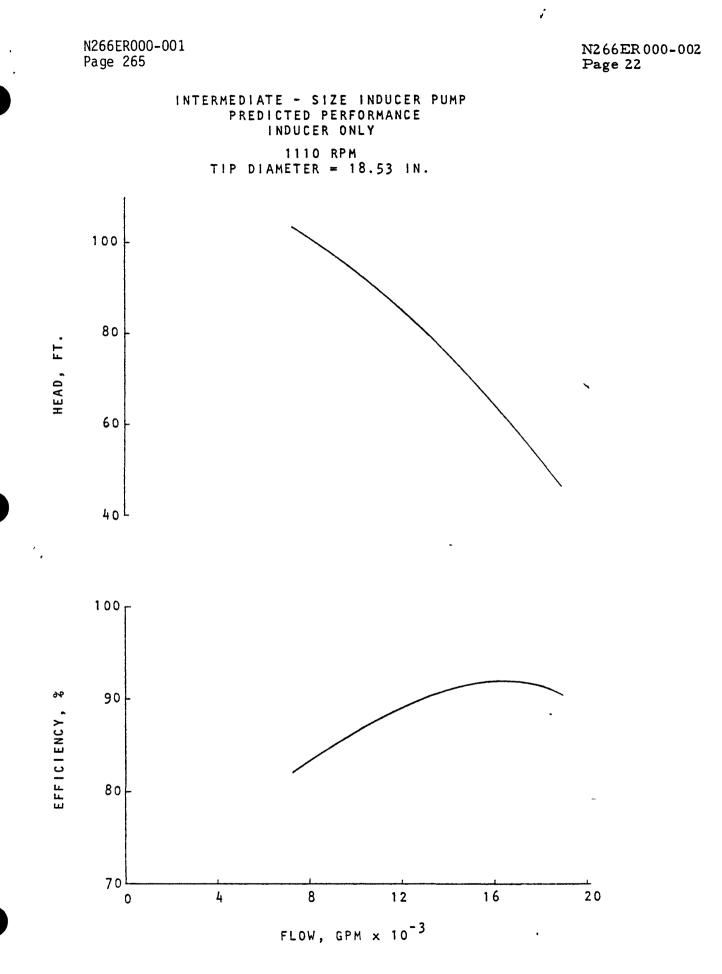


FIGURE 8.

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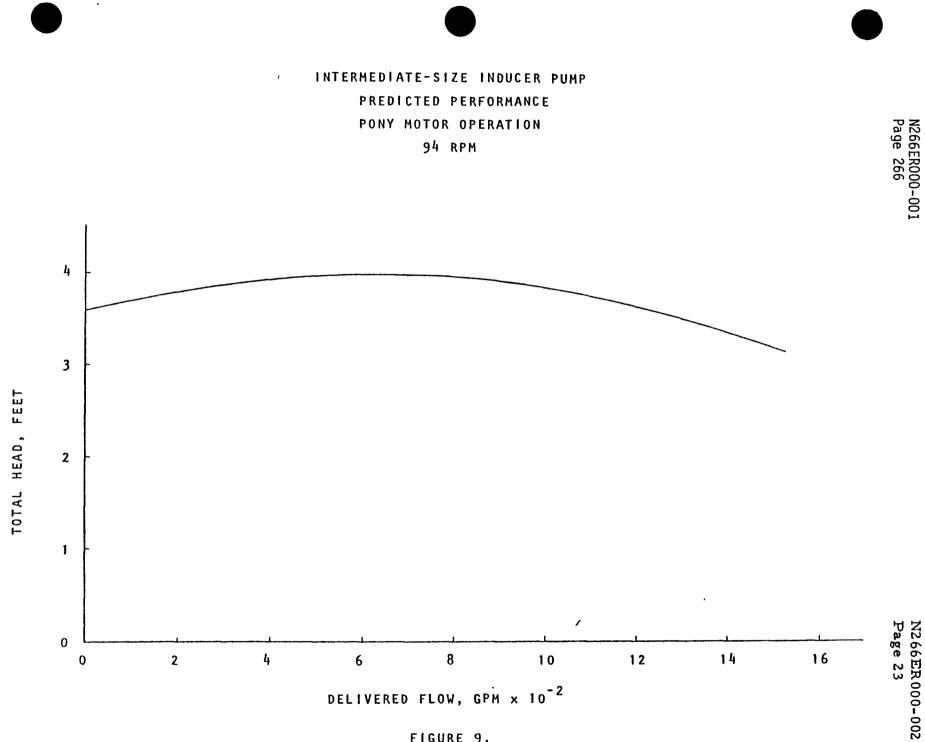


FIGURE 9.

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the waterjet experience range was the tip-clearance-to-blade-height ratio. However, Rocketdyne does have an analytical program for predicting the influence of this clearance on the potential damage due to the tip vortex cavity. This analytical program has been correlated with waterjet life test results. The analysis indicates that the selected four-bladed design will be able to operate with long life at the required operating clearance.

Other features incorporated to maximize the life include designing for zero cant angle of the blade to prevent a detrimental minimum tip clearance in case of blade bending, elimination of the slot over the inducer to prevent generation of slot-edge vortex cavitation, and increasing the blade thickness at the tip to the maximum value consistent with good hydrodynamic suction performance. This latter feature was included to provide more structural integrity to the blade to minimize blade movement in the high temperature sodium environment.

The maximum flow of 18,000 gpm represents a 24 percent increase in flow over the design point. At such a large off-design condition any rotating component, inducer or impeller, would experience some cavitation damage if the NPSH margin is low. The NPSH margin required to prevent such damage for the I.S.I.P. design must be determined from water tests of model hardware. Such testing does provide a very economical approach to the problem and yields the required technological data for assessing the design in the very early stages of the overall program. This provides the opportunity for hardware modifications, if necessary, before fabricating any full-size hardware.

### Suction Performance

The available NPSH provided to the inducer at the design flow is 47 feet. At 18,000 gpm this value drops to 40 feet. Rocketdyne's I.S.I.P design is capable of achieving a predicted required NPSH of 12.8 feet at the design flow. This capability is based on the assumption that the required

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suction performance is the same in sodium as in water. Since both fluids have a very low vapor pressure, the thermodynamic suppression head effects should be negligible so that the above assumption is valid.

Rocketdyne's ability to meet this predicted performance is based on an extensive background of designing and testing high suction performance inducers. More recently, the capability of the subscale sodium inducer demonstrated the ability to achieve the predicted performance. The design features which are required to achieve these results have been designed into the I.S.I.P. consistent with previous Rocketdyne experience. No design compromises were required due to the sodium operation or other pump features with one exception. The outer diameter of the inducer was reduced, raising the required NPSH, to provide a smooth liner over the inducer and eliminate the slot over the inducer present in the existing housing.

The suction performance at off-design conditions is more difficult to predict. Based on the subscale sodium inducer the ratio of breakdown NPSH at 1.24 times design flow (18,000 gpm) compared to that at the design point (14,500 gpm) was 2.26. Using this ratio, the I.S.I.P. required NPSH at the maximum flow would be 29 feet giving a margin of 38 percent. This is an adequate margin for suction performance but is relatively low for achieving life. An inducer or impeller operating with such small margin at this off-design value would be expected to experience damage, and the life then depends on the damage rate compared to the off-design life requirement. At 250 hours of life over a 20 year period, the inducer could be expected to maintain its performance capability even though some damage occurred.

The presence of the inducer provides sufficient head-rise at the impeller inlet to keep the impeller from experiencing cavitation performance loss. The maximum required suction specific speed of the impeller is only approximately 5200 at the off-design flow of 18,000 gpm. At the design flow, it will be significantly less than this.

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# Radial Loads

The specification requires that the design incorporate polar symmetry to minimize radial loads. Such polar symmetry was incorporated in the design. The radial loads are also minimized by the incorporation of a four-bladed inducer, use of a lower impeller diameter than used in the existing pump, use of a more stable vaned diffuser system, and the complete polar symmetry of the existing diffuser discharge. The maximum radial loads to be experienced would occur at the lower flows. The radial loads should be less for the Rocketdyne design than the existing design, but for purposes of analysis a not-to-exceed maximum load was estimated at a low flow of 8000 gpm. These not-to-exceed estimates were:

> Impeller: 800 pounds Inducer: 13,300 in-1b moment

The impeller load is based on an estimate of six percent of the axial thrust acting as a radial thrust. The inducer moment is based on tests of three-bladed inducers which are more likely to experience radial loads. However, the inducer radial load would not be expected to occur at the NPSH margins expected for the I.S.I.P. design.

# Axial Thrust Control

The specification required that the axial thrust not exceed 70,000 pounds in the upward direction and 40,000 pounds downward. It also required that these thrust values be met with an assumed variation of the impeller discharge static pressure of ten percent from front shroud to rear shroud. The axial thrust control was to be achieved without use of a balance piston.

Figure 10 presents the nominal axial thrust for the I.S.I.P. design. The nominal thrust is less than 13,000 pounds at all operating conditions.

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INTERMEDIATE-SIZE INDUCER PUMP N = 1110 RPM INDUCER INLET PRESSURE = 16.64 PSIA TOTAL 12 BLEED HOLES 1.25 IN. BLEED HOLE DIAMETER

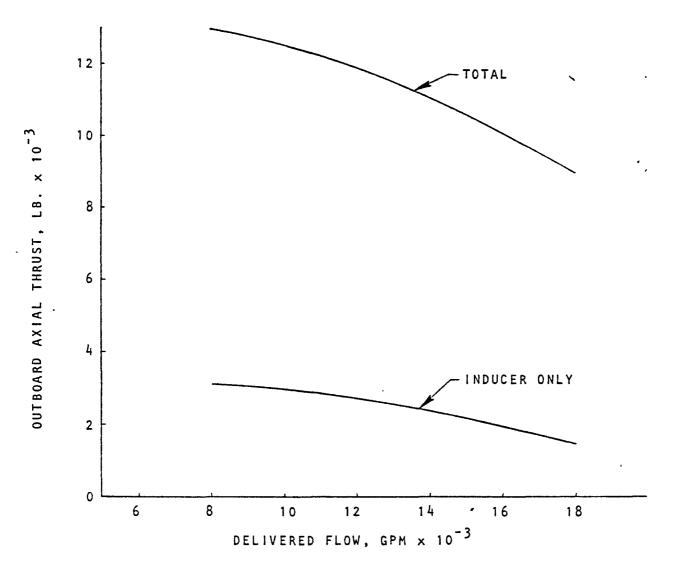


FIGURE 10.

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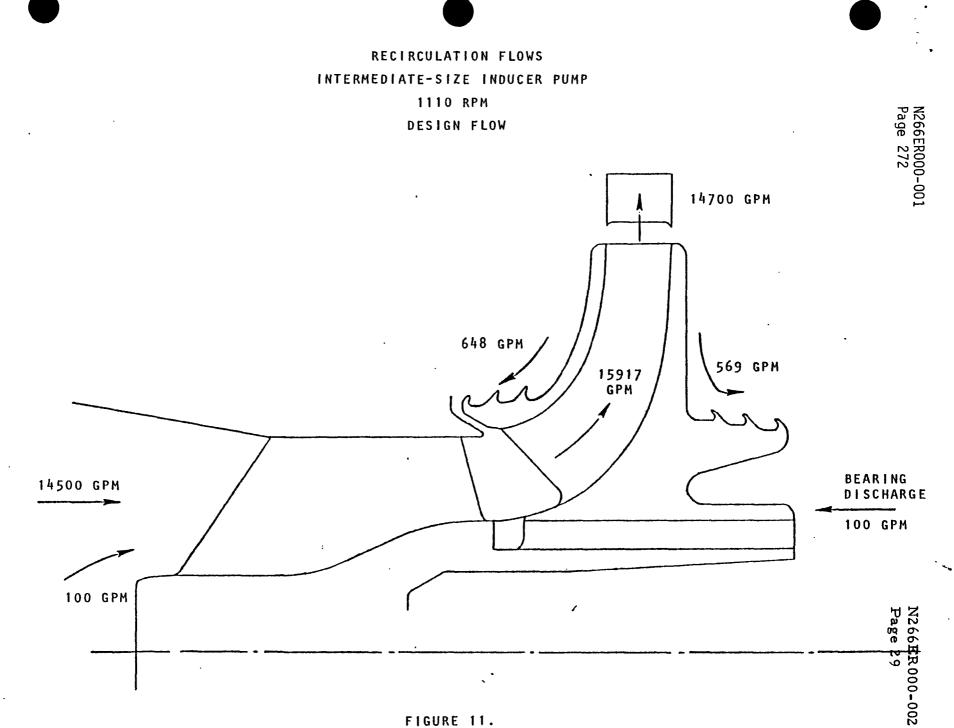
With the additional assumption of the ten percent variation in static pressure the following maximum conditions were obtained:

- 1. Maximum thrust equals 24,800 pounds downward at 8000 gpm.
- 2. Maximum thrust equals 7,200 pounds upward at 18000 gpm.

Case one assumes the rear shroud pressure is higher by ten percent and case two assumes the front shroud pressure is higher. This ten percent variation in static pressure is believed to be higher than will be experienced in the pump, but the thrust values are all well within the limits specified, and no balance piston system is required.

### Recirculating Flows

The specification originally required that the hydrostatic bearing discharge pressure was not to exceed 10 psi above the inducer inlet pressure at the design point. To achieve this goal would require that the bearing discharge flow be ducted back to the inducer inlet. However, because the pump must be fitted into the existing housing, the impeller rear wear ring flow would also have to be dumped into the inducer inlet, or at least a portion of it if another rotating seal were added. Rocketdyne did not like this concept because dumping any significant amount of fluid into the inducer inlet could be detrimental to the suction performance capability. A simpler approach was analyzed and is shown in Figure 11. The bearing discharge flow and rear wear ring flow are collected and dumped into the impeller inlet rather than the inducer inlet. The impeller has the tolerance required to accept the flow without any degradation in overall suction performance. Using this approach gives a bearing discharge pressure that is 13 psi above the inducer inlet pressure rather than the 10 psi originally specified. It was agreed at Atomics International to change the specification to approve the Rocketdyne design.



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Figure 12 shows the differential pressure of the bearing discharge pressure minus inducer inlet pressure as a function of flowrate. The curve results are based on usage of twelve bleed holes at a diameter of 1.25 inches. The total flowrate through the impeller includes the bearing flow, rear wear ring flow, and front wear ring flow. The wear rings are located to achieve the axial thrust results previously presented. The flow through the wear rings is minimized by using properly designed stepped-labyrinth seals.

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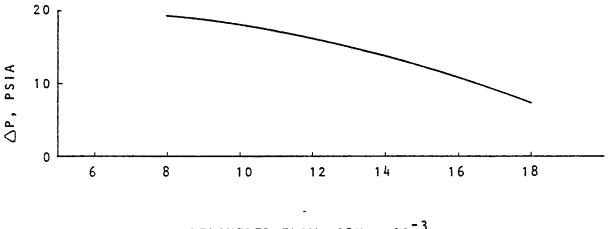
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INTERMEDIATE-SIZE INDUCER PUMP N = 1110 RPM INDUCER INLET PRESSURE = 16.64 PSIA TOTAL 12 BLEED HOLES 1.25 IN. BLEED HOLE DIAMETER

 $\triangle P$  = BRG. DISCH. STATIC PRESS. - INDUCER INLET STATIC PR.



DELIVERED FLOW, GPM  $\times$  10<sup>-3</sup>

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### CONCLUSIONS

The hydrodynamic design has been based on techniques developed and proven over the past twenty-five year period. The analytical tools used are the most advanced available and have been checked out by correlation with available test data. The confidence in achieving the design performance predictions is, therefore, very high.

The design has been shown to meet the specification requirements in all cases where analytical predictions can be made. In fact, design margins have been included in all of these cases to provide additional confidence in meeting the predicted values. Two areas need verification through testing, regardless of whether an inducer pump or an impeller-only design is incorporated. The first is the suction performance margin at the highest flow condition. The quoted margin of 38 percent is expected to be representative but requires test support. The second area is the life characteristics of the design. All of the design features are based on proven designs for long life waterjet pumps at the design point. Life at the off-design flow requires test evaluation.



# APPENDIX H

# STEADY-STATE STRUCTURAL ANALYSIS (PUMP INTERNALS)

ESG Document N266SR000001

Figures 1 thru 29 (except Figure 9) have been removed from this document because they contain proprietary information, as defined by DOE contract.

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# AI INTERMEDIATE-SIZE INDUCER PUMP STRUCTURAL SUMMARY

### Introduction

In accordance with the Statement of Work per Intermediate-Size Inducer Pump, IDWA N-1289, Ref. 1, a steady-state stress analysis has been performed on the inducer, impeller, diffuser assembly and the shaft extension bolt. The components are structurally adequate for the steady-state operation. The method of analysis and the results are summarized in this summary report.

### Design Criteria

The design criteria used in the analysis was established by Atomics International (AI) and is set forth in Ref. 2. The AI allowable stress limits are lower than those allowed by the ASME Boiler and Pressure Vessel Code to leave margin for thermal transient stresses. The AI allowable stress limits for 304 stainless steel at 1050°F are:

- 1. Primary membrane stress  $(P_M) = 7450 \text{ psi}$ .
- 2. Local membrane plus bending  $(P_1 + P_R) = 7730$  psi.

However, two specific exceptions were granted by AI to cover the two locations where the  $(P_L + P_B)$  stresses exceeded the recommended allowables. The two locations are the forward fillet radius in the inside diameter of the inducer hub and the diffuser vane. The calculated inducer fillet stress was 9630 psi. An increase in the allowable stress to 11200 psi was granted for the inducer, Ref. 3. The calculated diffuser vane stress was 8410 psi and the allowable stress was increased to 9000 psi, Ref. 4.

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The design criteria for A286 material used in the shaft extension bolt is set forth in Ref. 4. The recommended allowable stresses at 1050°F are 15000 psi for  $(P_M)$  and 20000 psi for  $(P_1 + P_B)$ .

### **Operating Conditions**

• The pump components were analyzed for steady-state operation at the following operating points.

- 1. Steady-state design point.
- 2. Steady-state maximum pressure condition.
- 3. Steady-state maximum power condition.
- 4. Transient maximum operating pressure condition.

Table 1 lists the speed, flowrate and the temperature of the above four operating points.

The pump components were analyzed based on operating points or combination of operating points which produced the maximum load condition. These loads were treated as steady-state loads.

#### Inducer

The inducer blade and hub were analyzed under steady-state operating conditions in order to determine their structural adequacy and compliance with the AI steady-state structural criteria (Ref. 1).

### Inducer Blade

The inducer blade was analyzed to:

1. Determine stresses at the blade-hub intersection.

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### 2. Determine stresses throughout the blade.

The analysis of step 1. assumes that the blade acts as a series of wedge-shaped cantilever beams under a combined loading of:

- a. Pressure bending moment.
- b. Centrifugal radial force.
- c. Centrifugal bending moment for canted blades.

Bending and membrane stresses are determined at the root of each wedge-shaped beam and then correction factors are applied in order to account for:

- a. the blade twist due to the helix angle;
- b. the tangential load carrying capability of the blade (disk effect);
- c. the distribution of moment at the hub due to plate behavior of the blade.

Under step 2. a finite element computer program was used to calculate stresses and deflections throughout the blade. The blade was modeled as a grid of elastic, triangular plate elements of linearly varying thickness with  $\Delta p$  pressure and centrifugal loads.

The  $\Delta p$  pressure load used in the analysis is a composite of the maximum pressure differences for flowrates at a speed of 1110 RPM. Pressures for 8000 GPM control over the first onethird to one-half of the blade length while pressures for 14500 GPM control for the remainder of the blade. The  $\Delta p$  pressure distribution contours plots are shown in Figure 1. All centrifugal forces are at 1110 RPM.

Results of the inducer blade analysis are summarized in Figure 2. The operating conditions corresponding to the most severe blade loading, the resulting stress intensities, stress intensity contour plots, material, allowable  $(P_L + P_B)$  stress and design margins are shown. The stress intensities shown are located on the blade pressure surface where tension from centrifugal loading and pressure bending combine to produce the most severe stress condition. The maximum stress intensity in the blade is 5.60 KSI and occurs at the blade-hub intersection at a location corresponding to the start of the full blade height. This maximum stress intensity results in a design margin of:

D. M. =  $\frac{7.73}{5.60}$  - 1 = .38

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Figures 3 through 6 are stress contour plots of the radial, tangential, shear in radial and tangential plane and maximum shear on the blade pressure side. Figure 7 is a contour plot of blade deflection in the axial direction.

### Inducer Hub

The inducer hub was analyzed using a finite element computer program for axisymmetric solids. In addition, the hub was analyzed for the non-axisymmetric loads. The non-axisymmetric load analysis consisted of hand calculation using the theories of plates and shells. The results from the non-axisymmetric analysis were superimposed on the results from the finite element analysis.

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The inducer hub was evaluated under the following loads:

I. Axisymmetric loads

- 1. Pressure loads on the inner and outer surface.
- 2. Axial load during operation which includes the effect of initial preload and operating thrust.
- 3. Centrifugal loading due to rotation of the hub and the blades.

II. Non-axisymmetric loads

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- Bending of the hub due to blade bending at the blade-hub sector intersection.
- 2. Couple on the hub from the key.

• . . •

3. Bending of the hub due to a hydrodynamic couple.

The pressure loads are shown in Figure 8. The 695 psia shown in Figure 8 represents axial load in terms of pressure.

The maximum loading condition on the inducer hub results in the stress intensity contours shown in Figure 9. The maximum stress intensity in the hub occurs in the fillet radius joining the hub inlet section and the retaining nut bearing flange. The close spacing of the contours indicates a highly localized stress concentration effect at a gross structural discontinuity. The maximum stress intensity in the hub of 9.63 KSI is due to combined axisymmetric and non-axisymmetric loads and results in a design margin of .16. It should be noted that in the inlet region of the inducer hub, provision has been made for the removal of material for balancing purposes. If the maximum material were removed, the maximum stress intensity

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at the balance groove surface will be equal to the maximum allowable stress intensity of 7.73 KSI. The Figure 9 also summarizes the operating conditions, material, and design criteria. Figures 10 through 29 are stress contour plots of the radial, axial, tangential, shear in radial and axial plane, and maximum shear for the axisymmetric loads.

### Impeller

Compliance of the impeller design with the AI stress criteria was determined through:

- 1. hand analysis of the impeller full and partial vanes;
- 2. a two dimensional, axisymmetric finite element
  - \_ analysis of the hub and shroud.

## Impeller Vanes

The impeller vanes were analyzed as fixed-ended beams of constant thickness and unit width connecting the outer shroud to the hub. Loading for each beam was assumed to be:

- 1. A uniform pressure difference across the vane width.
- 2. Centrifugal loading due to rotation of the vane.

A typical vane section with the pressure and centrifugal loadings is shown in Figure 30. The pressure distribution imposed on the vanes is shown in Figure 31. The maximum stress intensities as well as the corresponding design margins and wrap angle locations in the full and partial vanes are:

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	S <sub>MAX</sub> Wrap Angle <u>KSI D. M.</u>				
Full Vanes	90 <sup>0</sup>	2.41	2.21		
Partial Vanes	10°	1.08	6,16		

It should be noted that for the impeller vanes, the wrap angle is measured from the trailing edge which is the reverse of the convention used for the inducer blade.

Impeller Hub and Shroud

The impeller hub and shroud were analyzed for the following loads:

. .

- I. Axisymmetric loads
  - 1. Fluid pressures.
  - Axial load during operation from the effect of initial preload and operating thrust.
  - 3. Centrifugal loading due to rotation of the hub and shroud as well as the impeller vanes.
  - Shrink fit corresponding to a maximum radial interference of .0013 inches between the impeller hub and pump shaft.

II. Non-axisymmetric loads

- 1. Couple on the hub from the shear keys.
- 2. Bearing at the impeller keyway.

For axisymmetric loads, the hub and shroud were analyzed using a finite element computer code for axisymmetric solids. The basic finite element model is modified in the bleed hole and vane regions to account for a reduced tangential (hoop) continuity.

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In the vane region the model is further modified to account for material distribution and vane orientation. Such modifications are made in an attempt to simulate the vane behavior in as much as this behavior affects the stress distribution in the impeller hub and shroud. As a result, stresses in the vane region from the finite element model are not true stresses. In order to simulate the impeller-shaft elastic interaction the finite element model also includes a portion of the existing shaft.

Figure 32 shows the impeller profile and the maximum loadings imposed upon it under steady-state operating conditions. The resulting stress intensity contours from the finite element model are shown in Figure 33. The maximum stress intensity of 7.48 KSI occurs in the hub at the hub-shaft interface and results in a design margin of .03.

Figure 34 shows the stress intensity contours on the hub profile resulting from the shrink fit of the impeller onto the stepped, tapered shaft. The shrink fit procedure involves sliding the impeller onto the shaft until contact is made and then removing and heating the impeller. The impeller is then replaced on the shaft to a position .025 inches axially beyond the original contact point and allowed to cool. This results in a maximum radial interference of .0013 inches.

Figures 35 through 59 are stress contour plots in the impeller hub and shroud of the following stresses: radial, axial, tangential, shear in axial and radial plane, and maximum shear for the axisymmetric loads. 

#### Diffuser Assembly

The transition diffuser assembly was analyzed using a twodimensional finite element computer program. The loading is primarily a pressure differential across the diffuser thickness and the local effects of the mounting and connecting bolt loads. In the diffuser vane region of the computer model, allowance is made to account for the lack of tangential (hoop) continuity and the actual vane geometry in an attempt to simulate the correct vane behavior. For this reason, stresses in the vane region from the finite element model are used only to determine the membrane loads and bending moments imposed on the vanes. Figure 60 shows the operating conditions corresponding to the maximum diffuser pressure load and the pressure distribution imposed upon the diffuser assembly. Figure 61 summarizes the result of the diffuser assembly analysis. The operating condition, material, allowable stress intensities, stress contour plots and design margin at various locations of the diffuser assembly are shown. The maximum stress intensity of 8.41 KSI occurs in the diffuser vanes and is shown in Figure 62.

Figures 63 through 102 are stress contour plots of the radial, axial, tangential, shear in radial and axial plane, and maximum shear for the axisymmetric pressure loads.

# Shaft Extension

The shaft extension was examined using appropriate hand analyses based on shell and ring theory. It should be noted that the shaft material is A286 steel while the inducer, impeller, and diffuser materials are all 304 stainless steels.

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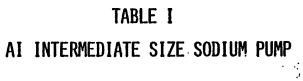
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The shaft extension maximum load operating conditions as well as the resulting stress intensities and design margins at various locations are listed in Figure 103. The maximum stress intensity of 15.6 KSI with a design margin of .28 occurs at a fillet, (location A), as a result of combined axial membrane tension and bending due to eccentricity of the axial load.

#### References

- 1. Intermediate-Size Inducer Pump IDWA N-1289.
- AI Letter 77AT-10423, R. V. Anderson (AI) to R. E. Davis (Rocketdyne), Intermediate-Size Inducer Pump, IDWA N-1289, Revision A, dated November 11, 1977.
- AI Letter, T. Boardman (AI) to J. Wolf (Rocketdyne), Intermediate-Size Inducer Pump (ISIP) Structural Design Criteria, dated May 17, 1978.
- 4. AI Letter, T. J. Boardman (AI) to J. E. Wolf (Rocketdyne), Intermediate-Size Inducer Pump (ISIP), IDWA N-1289 Allowable Stress Values, dated April 19, 1978.

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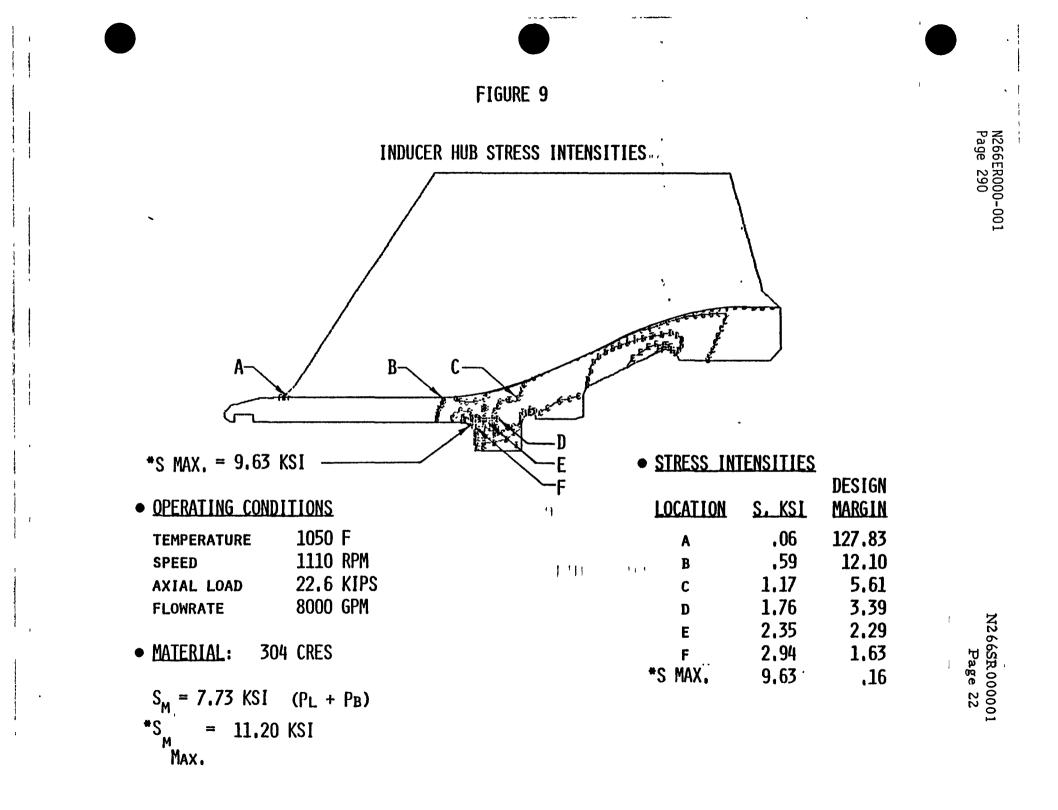
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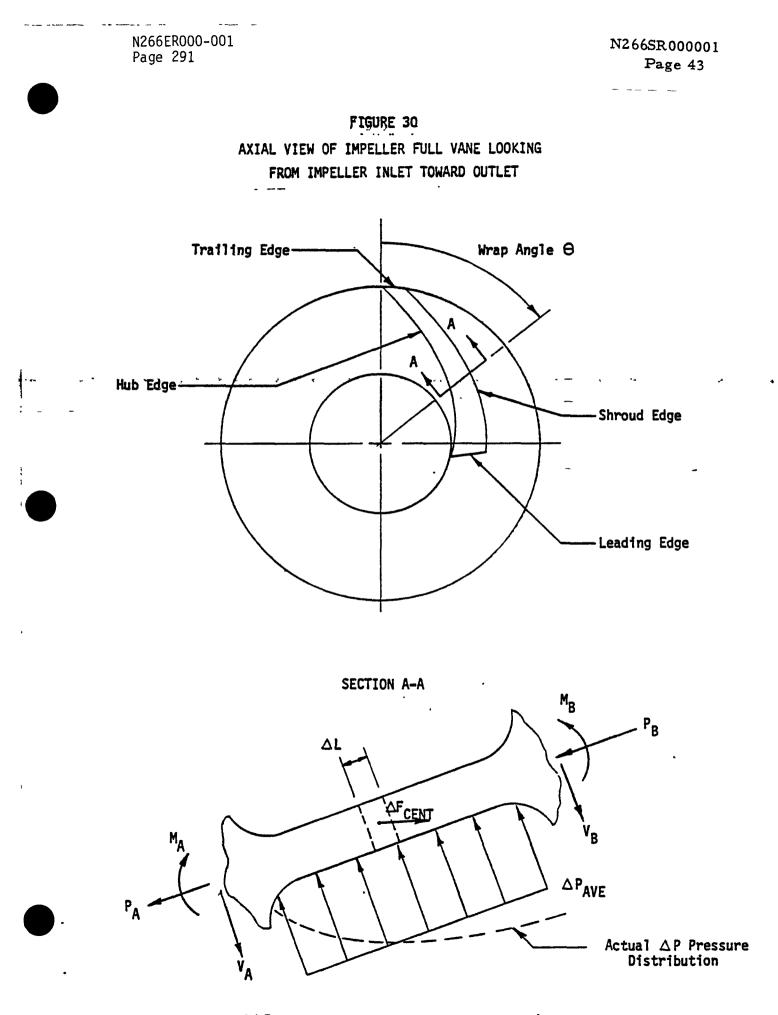
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			1110	1110	1110
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	CDM	1/1500	11750	10000	0000
• FLOWRATE	GPM	14500	11750	18000	8000
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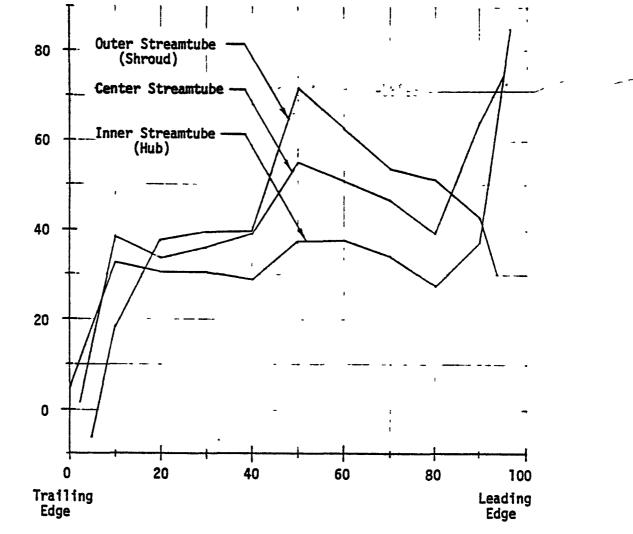
Pressure Differential Across Vane, PSI

N266SR000001 Page 44

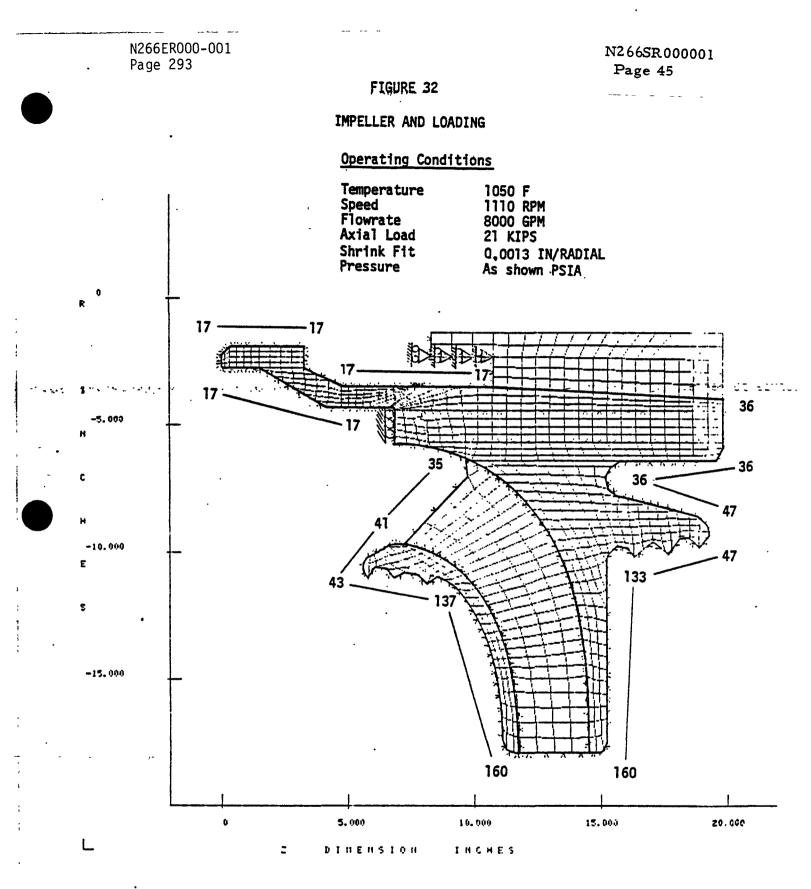
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## FIGURE 31

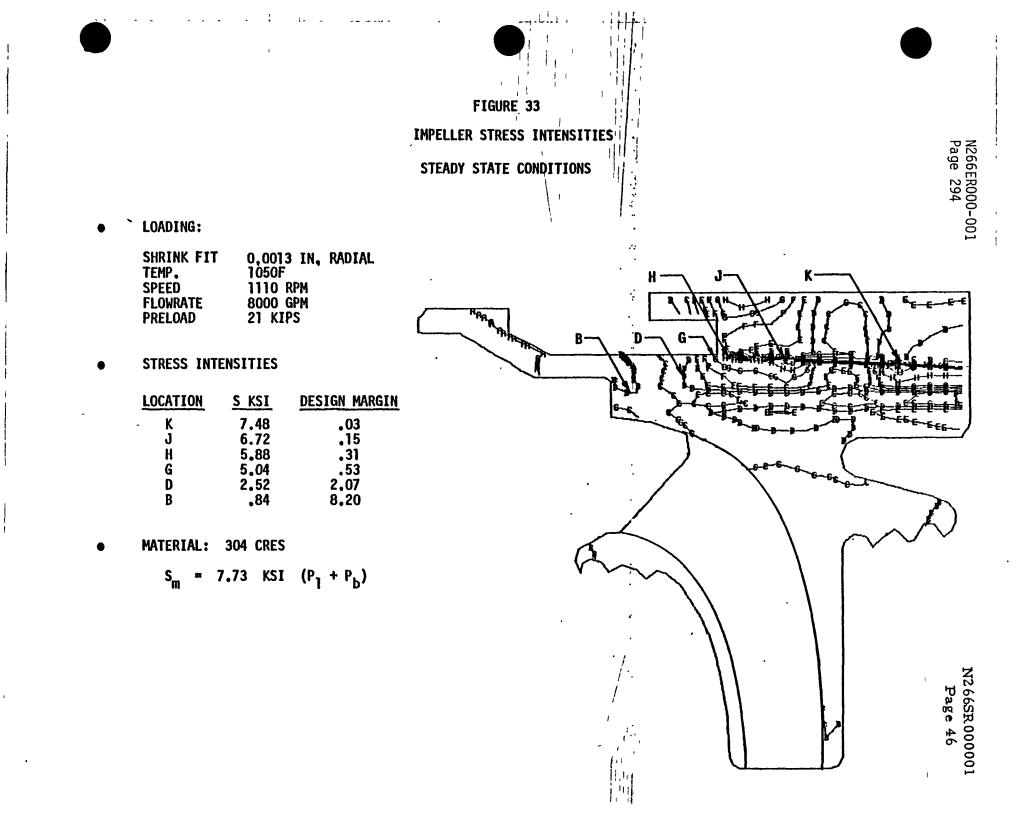
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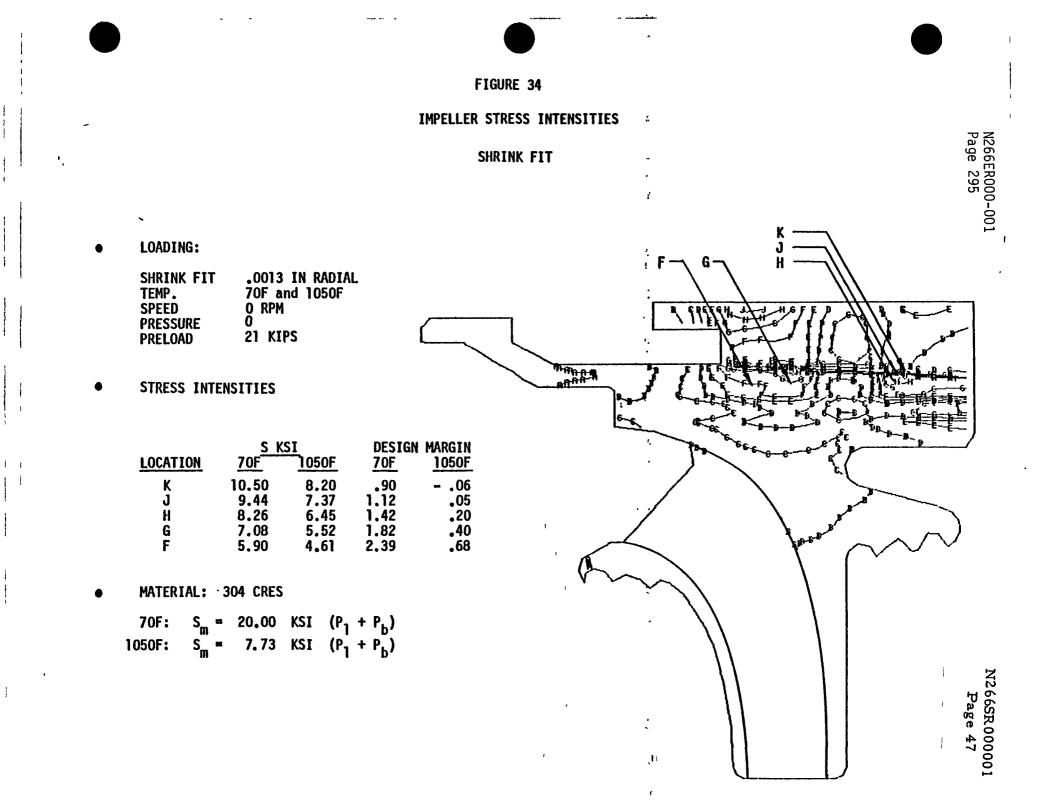
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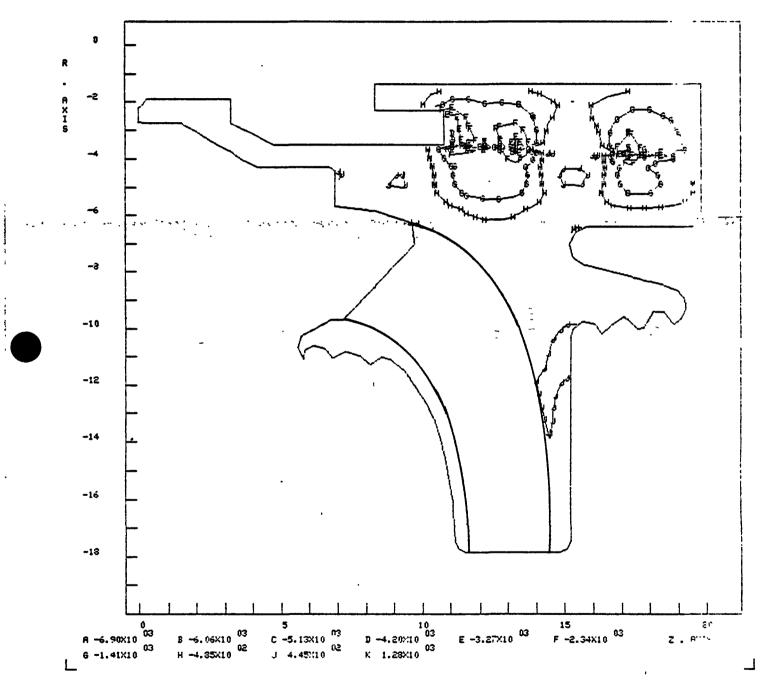
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#### FIGURE 35

AI INTERMEDIATE SODIUM PUMP IMPELLER AXISYMMETRIC ANALYSIS SIGMA-P IS PLOTTED

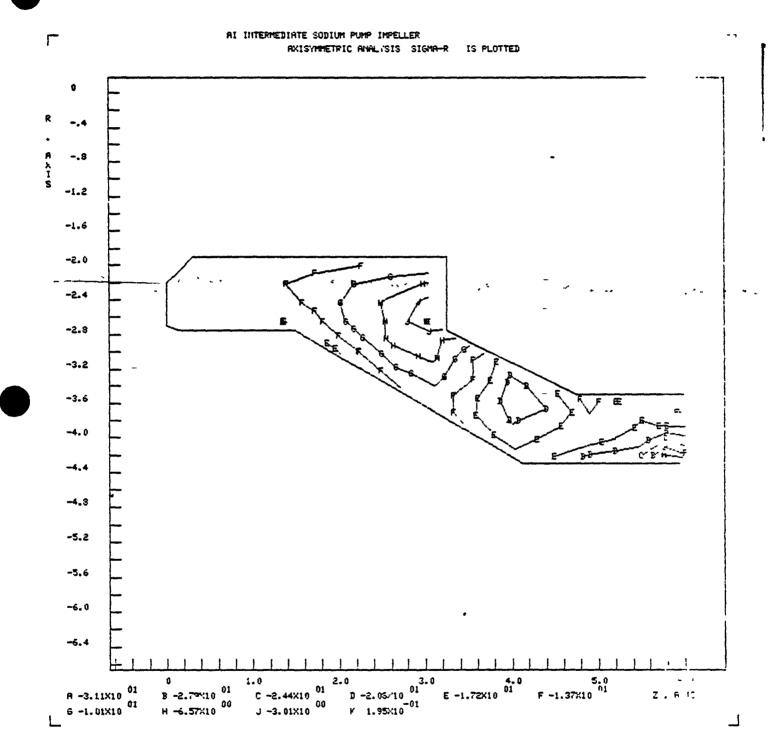


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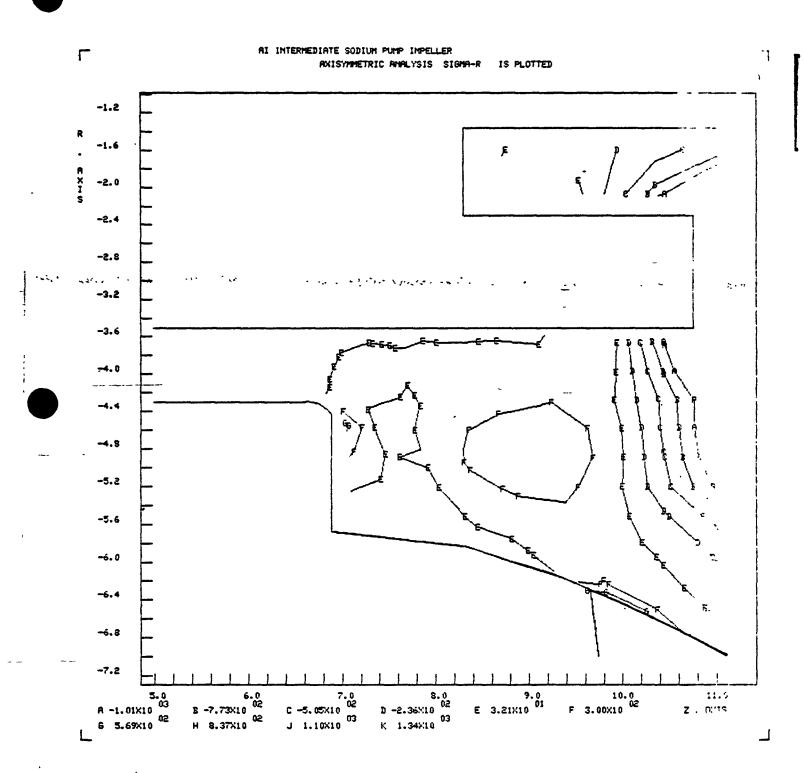
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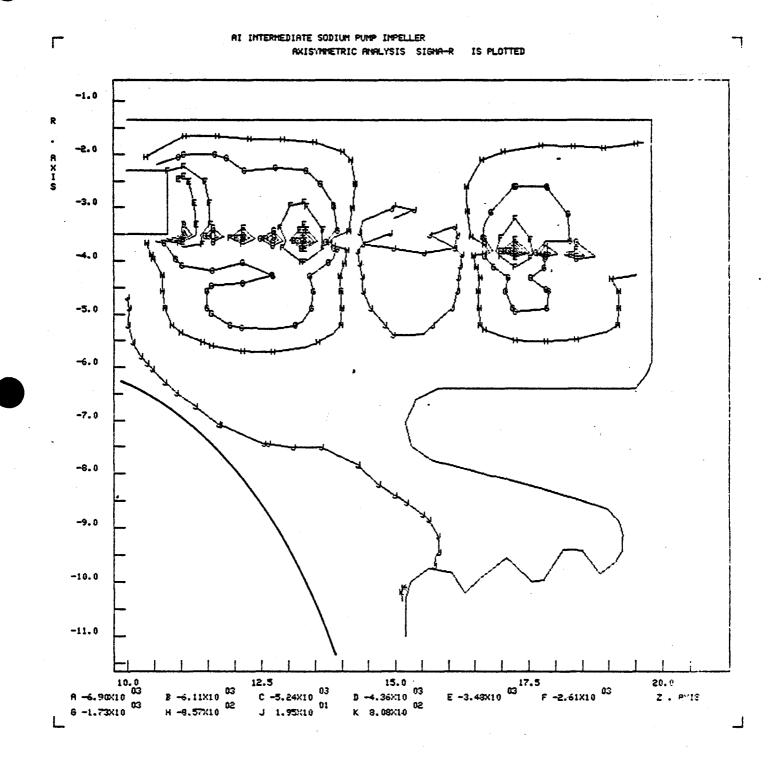
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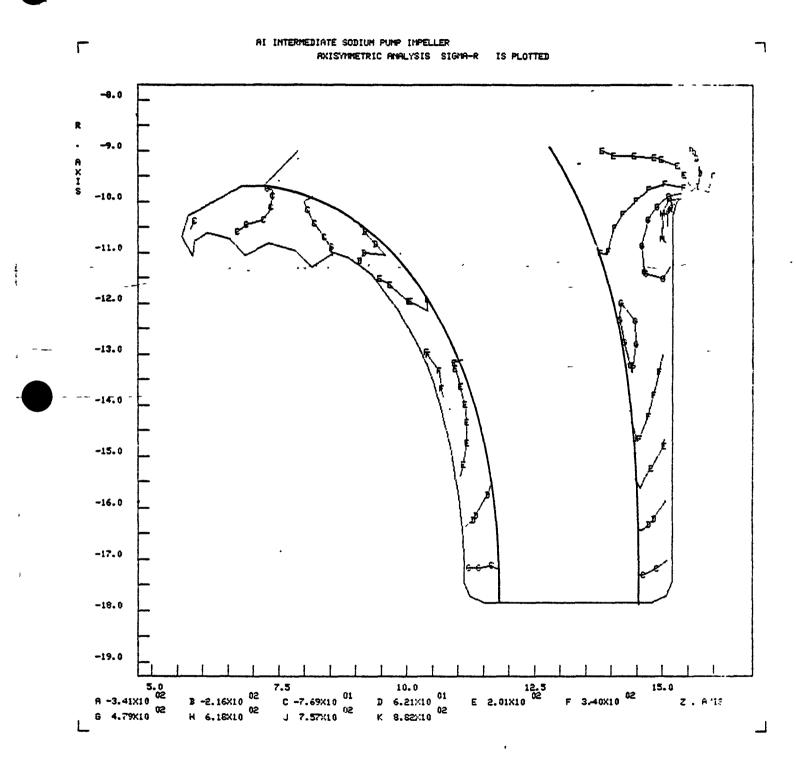
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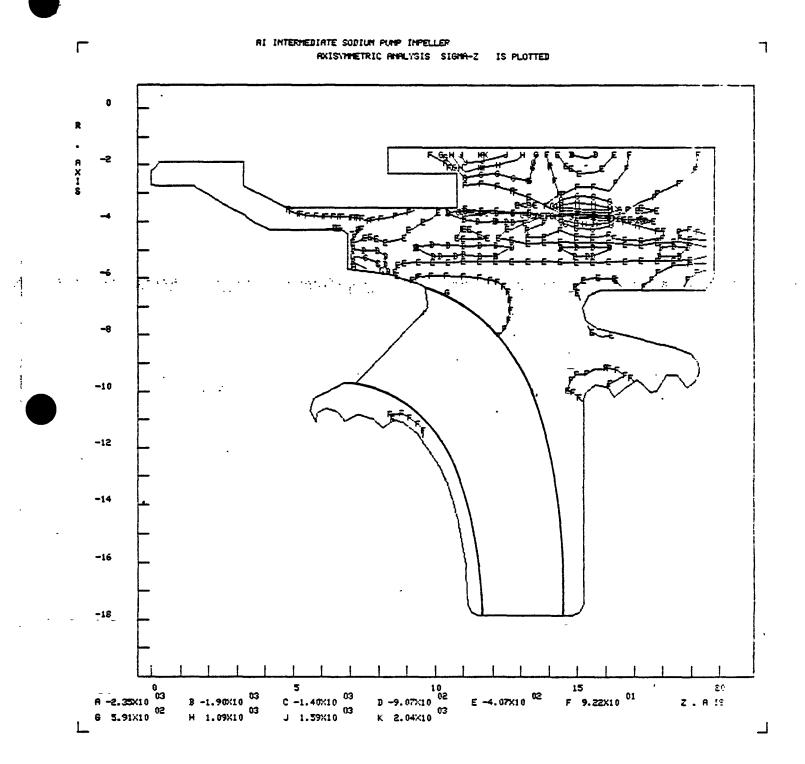
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## FIGURE 40



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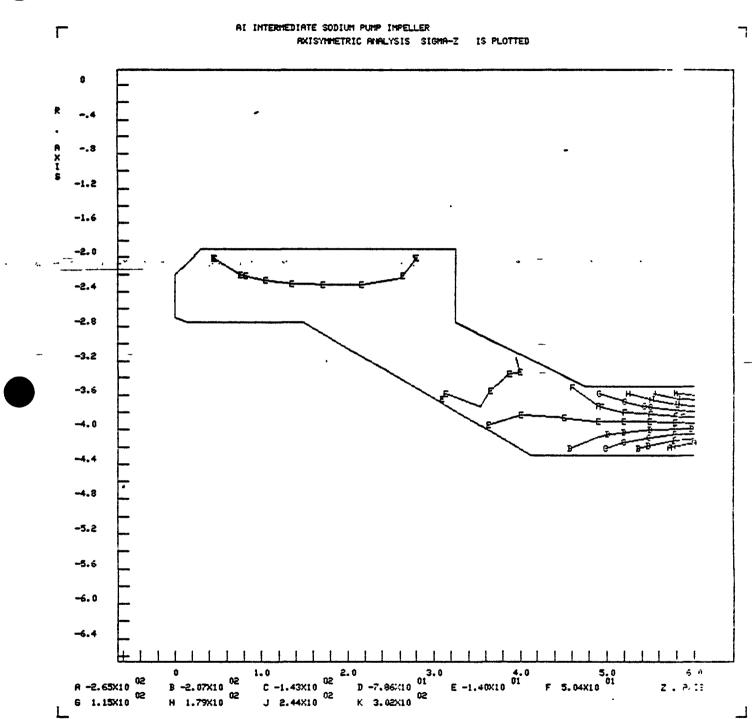
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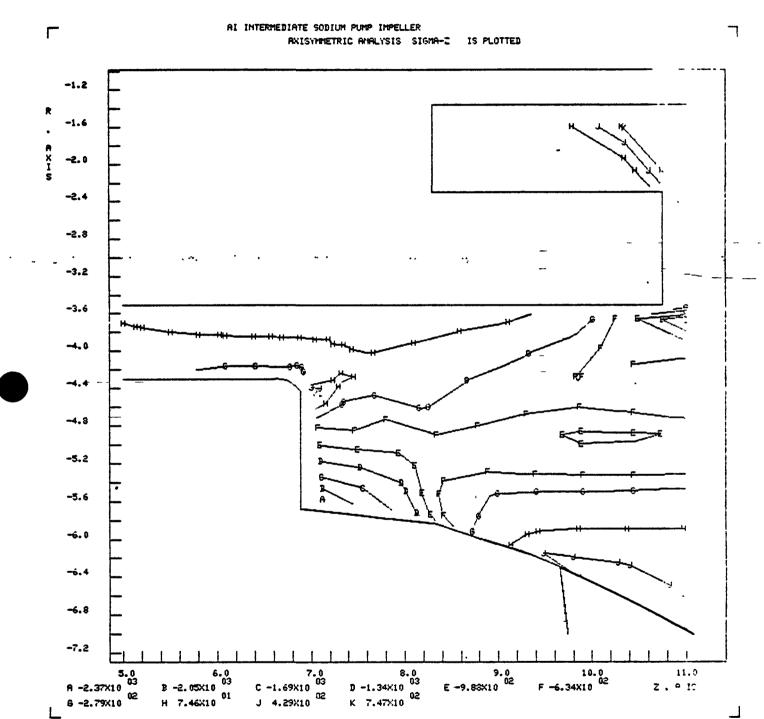


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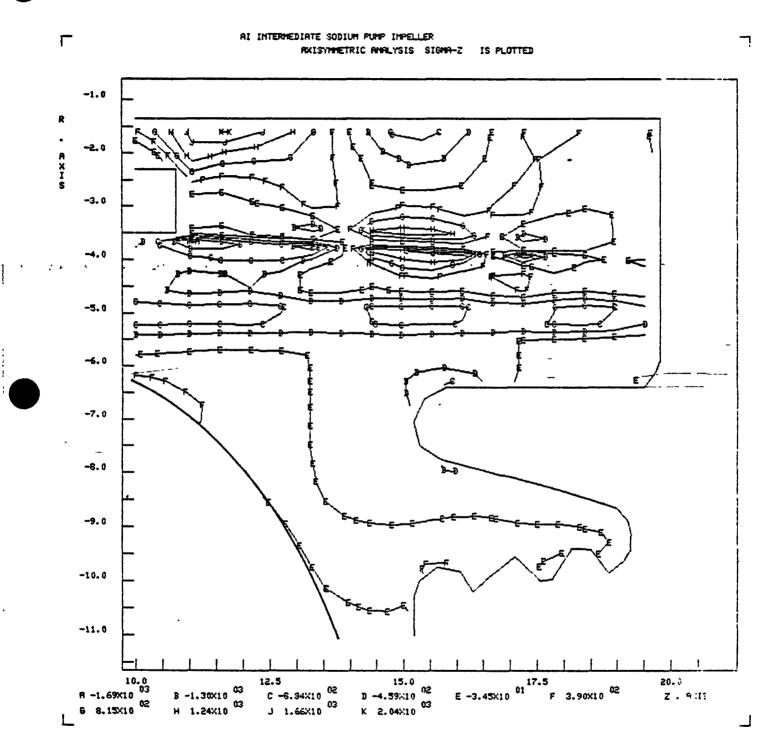
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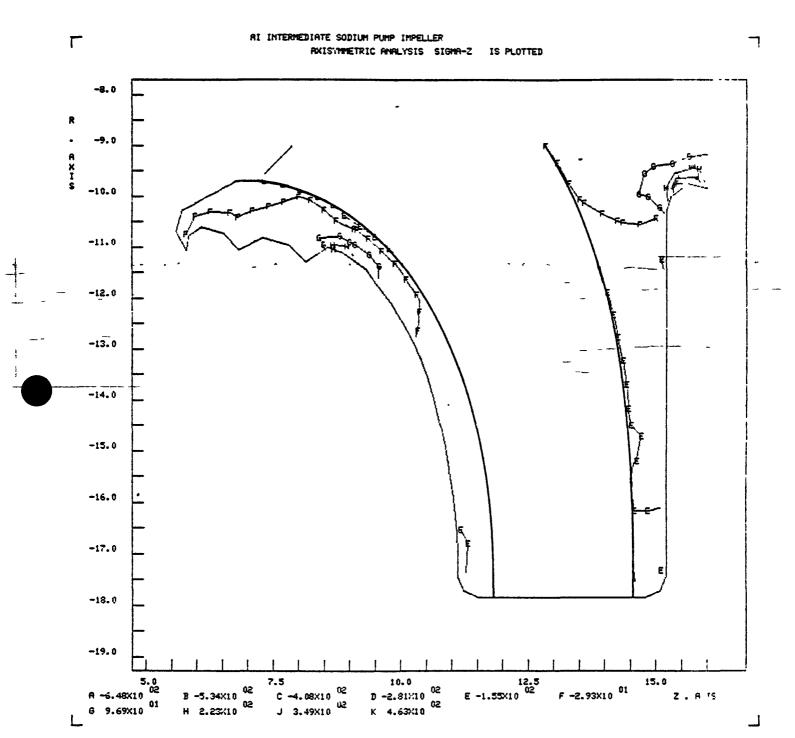


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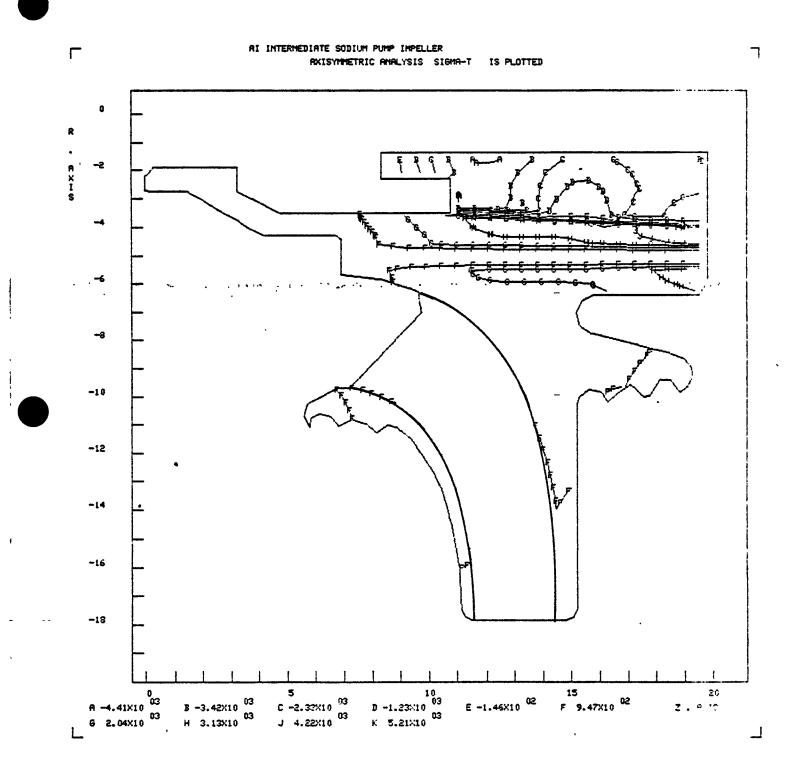
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#### FIGURE 44



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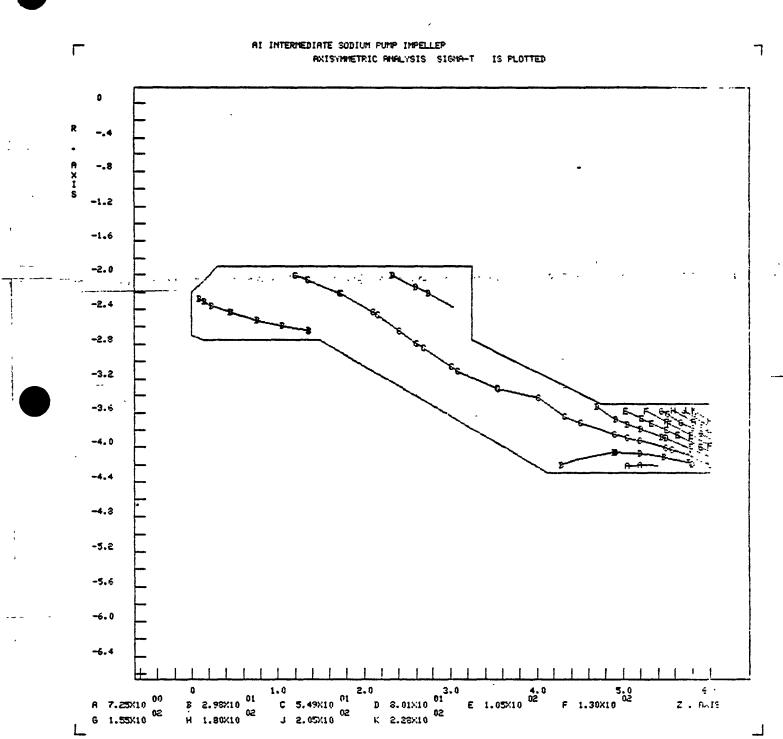
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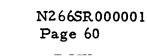
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#### FIGURE 46



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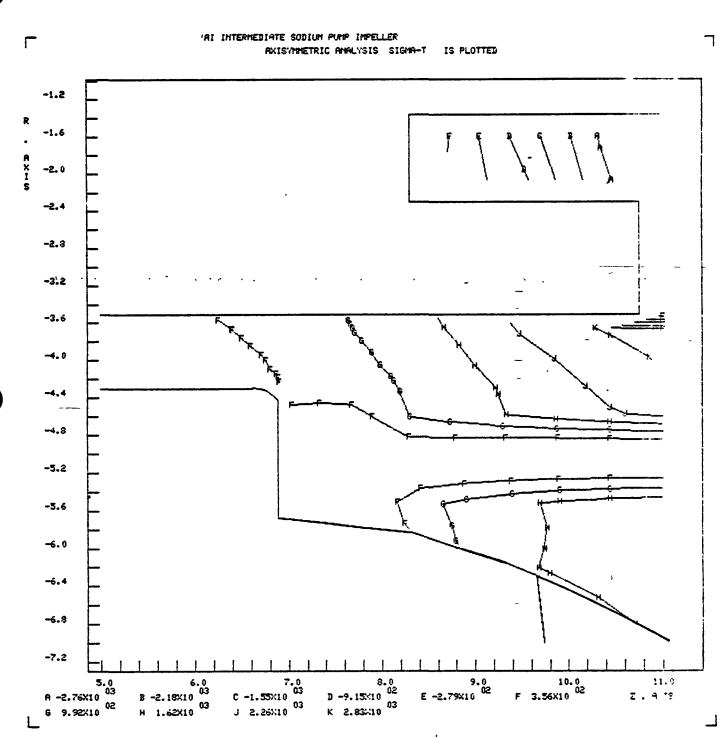
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FIGURE 47

N266ER000-001

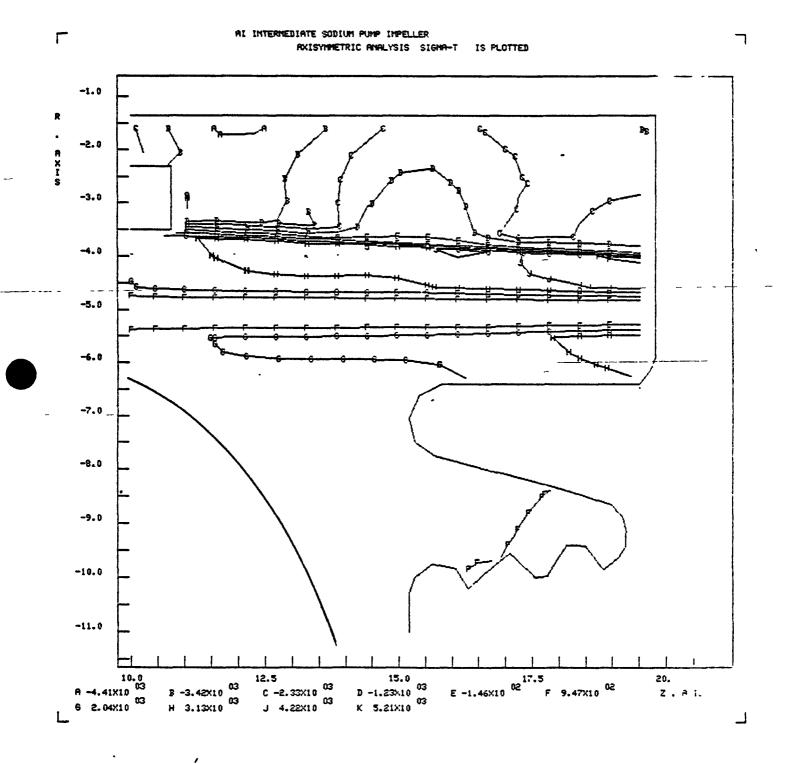
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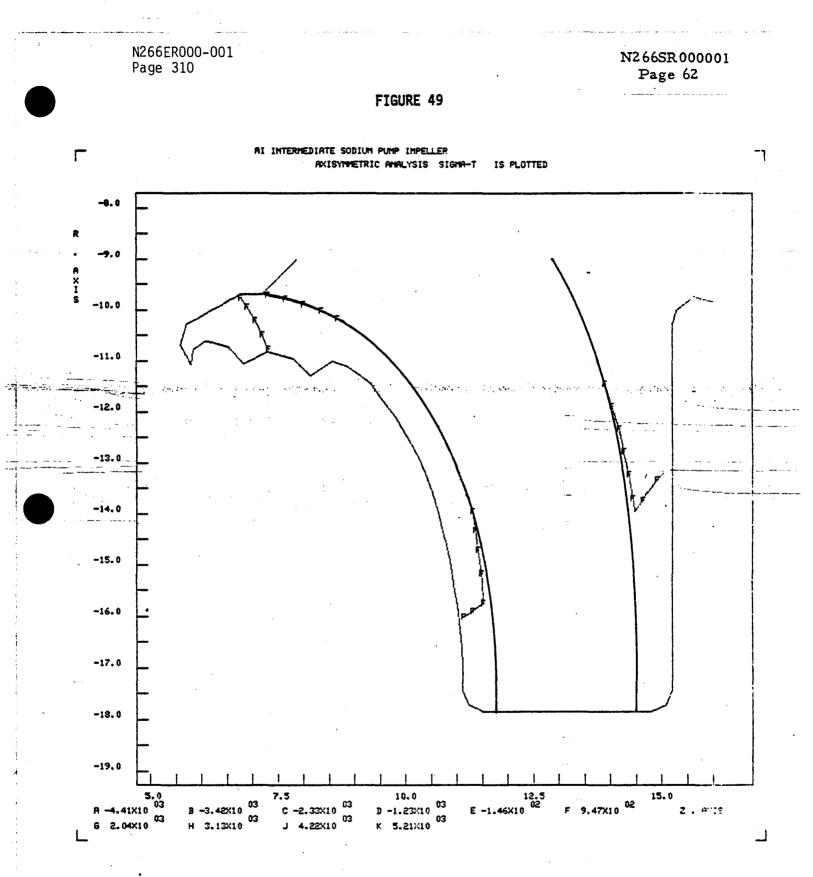
Page 308



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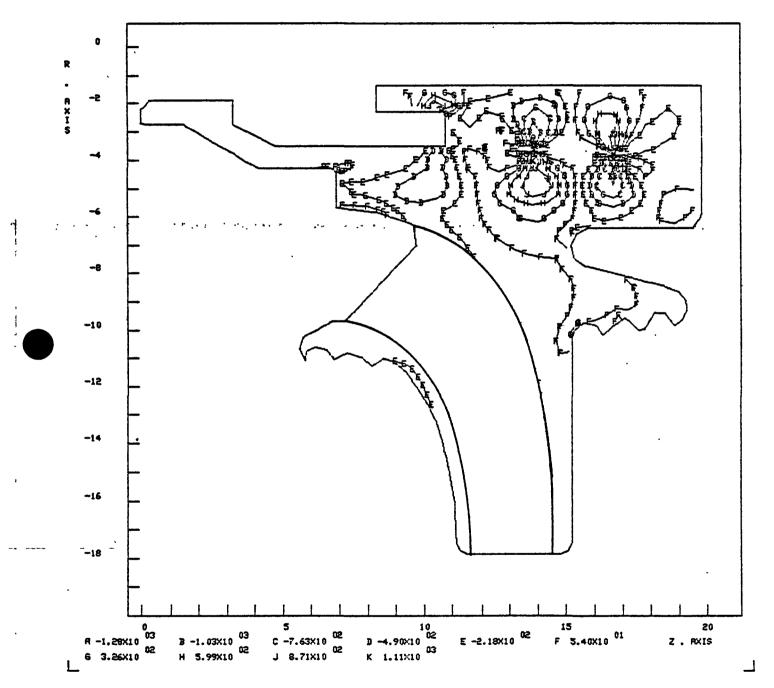
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## N266SR000001 Page 63

#### FIGURE 50

#### AI INTERMEDIATE SODIUM PUMP IMPELLER AXISYMMETRIC ANALYSIS SIGMA-RZ IS PLOTTED -

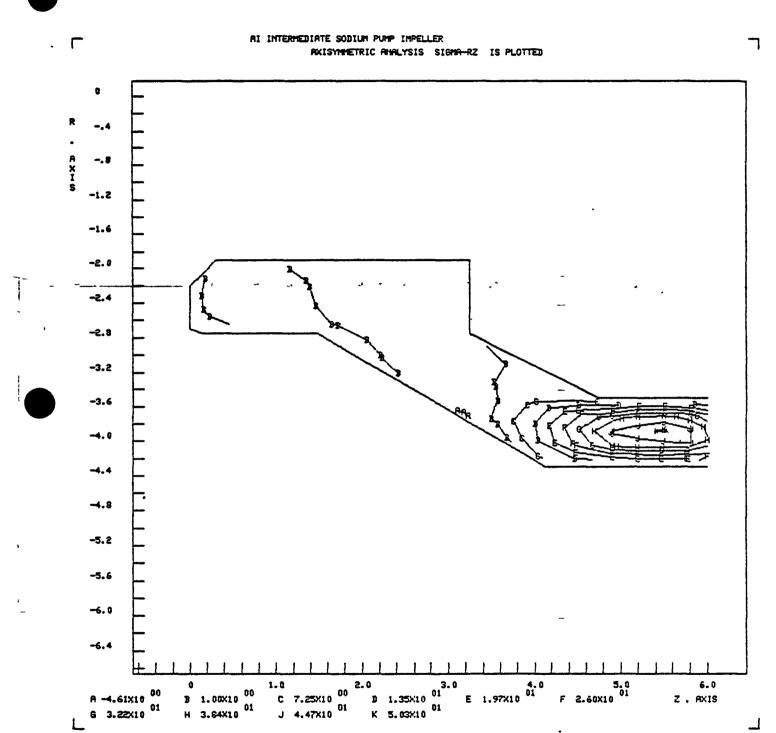


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### N266SR000001 Page 65

## FIGURE 52

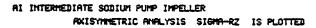
AI INTERMEDIATE SODIUM PUMP IMPELLER Г AXISYMMETRIC ANALYSIS SIGNA-RZ IS PLOTTED -1.Z -1.6 A X I S -2.0 2 -2.4 -2.8 -3.2 -3.6 -4.0 -4.8 -5.2 -5.6 --6.0 ළු -6.4 -6.8 -7.2 5.0 A -7.37X10 6 4.76X10 7.0 C -3.46X10 J 8.37X10 8.0 D -1.40×10 K 1.07×10 6.0 S0 9.0 E 6.47X10 10.0 F 2.70X10 11.0 B -5.52X10 Z. RXIS H 6.81X10 02 1

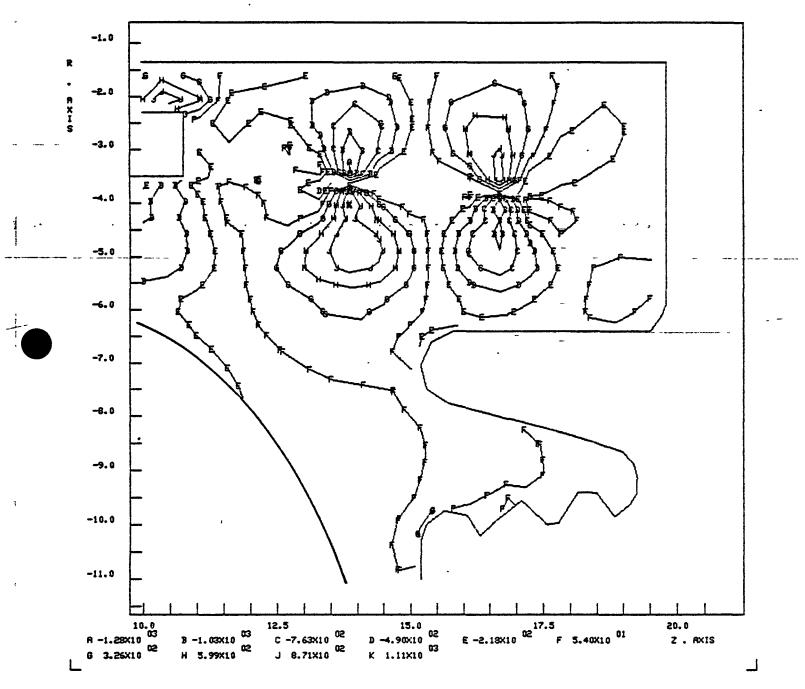
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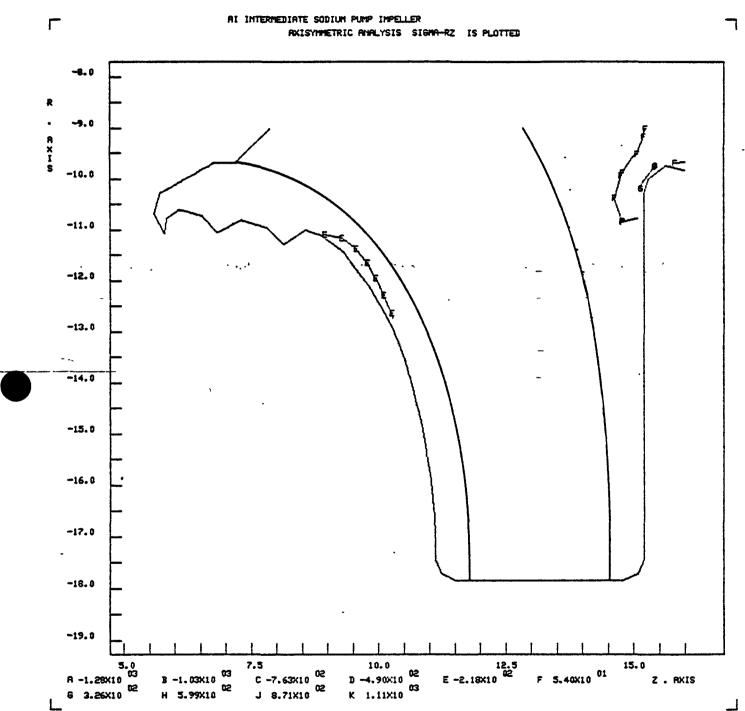
## FIGURE 53

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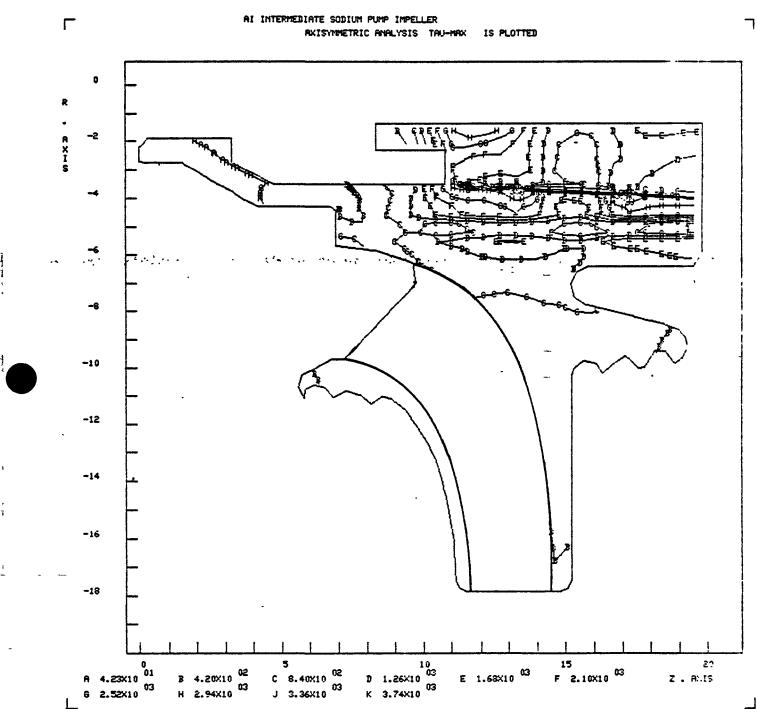




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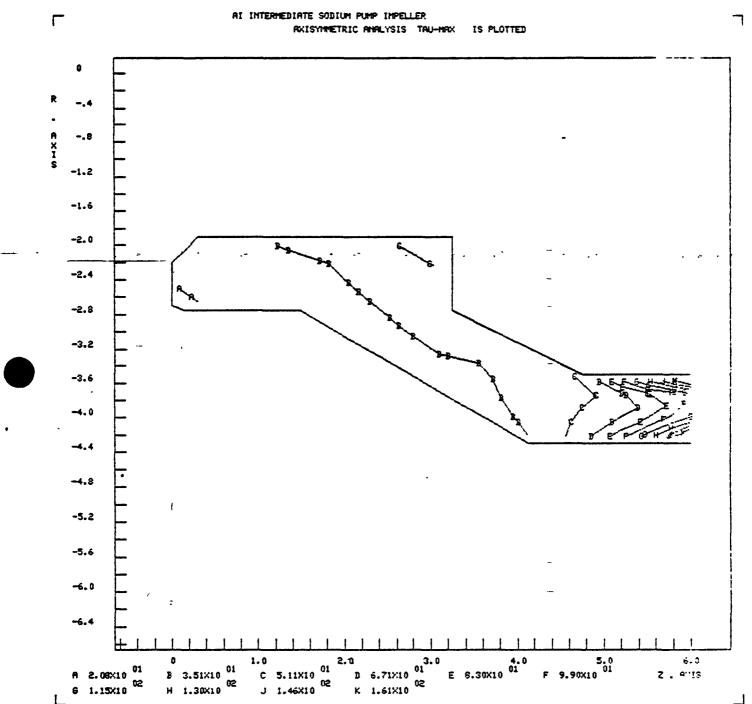


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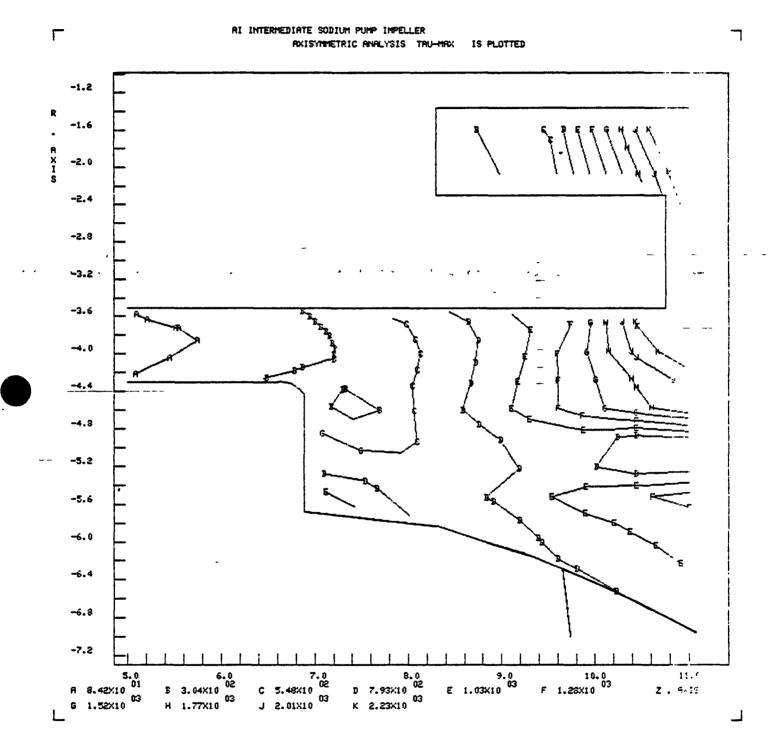


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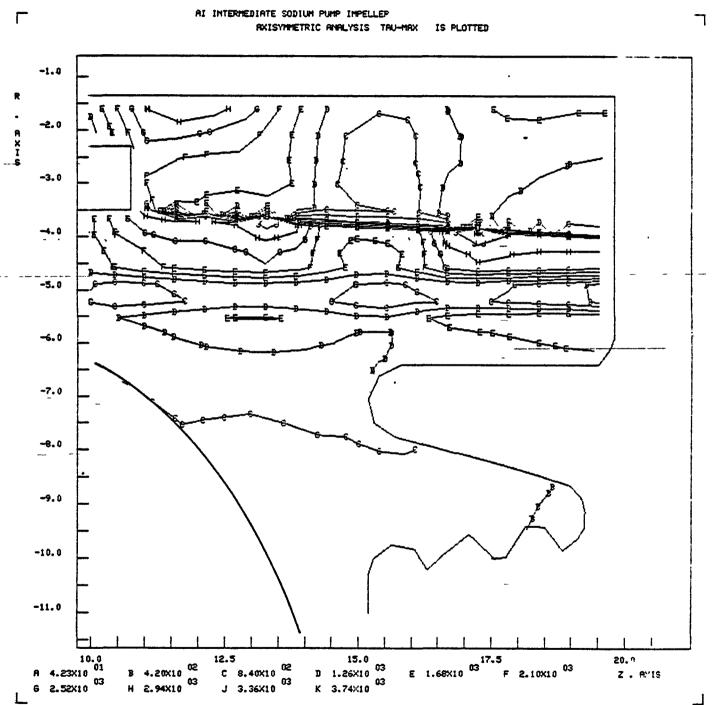
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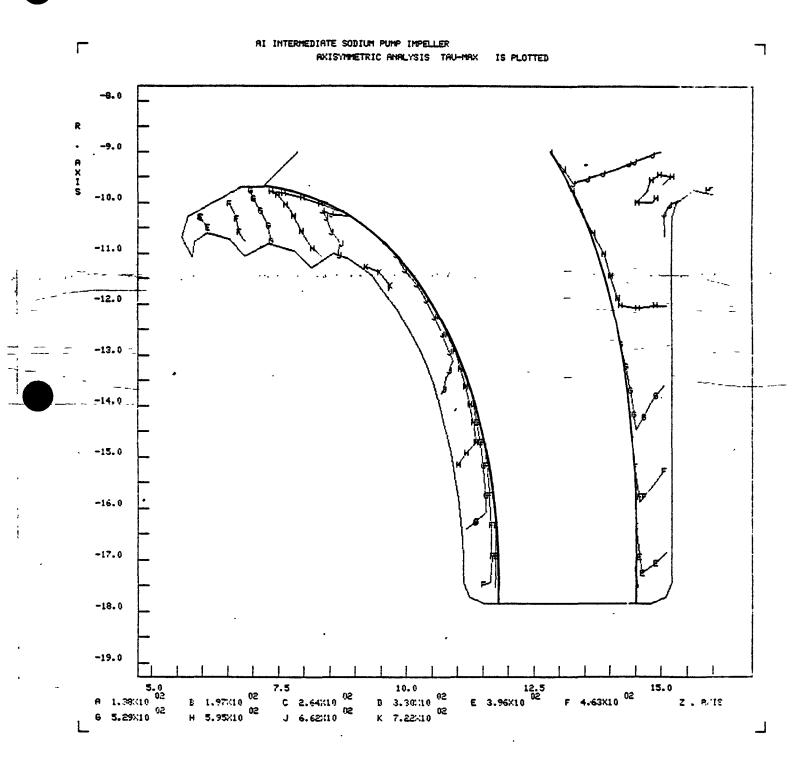


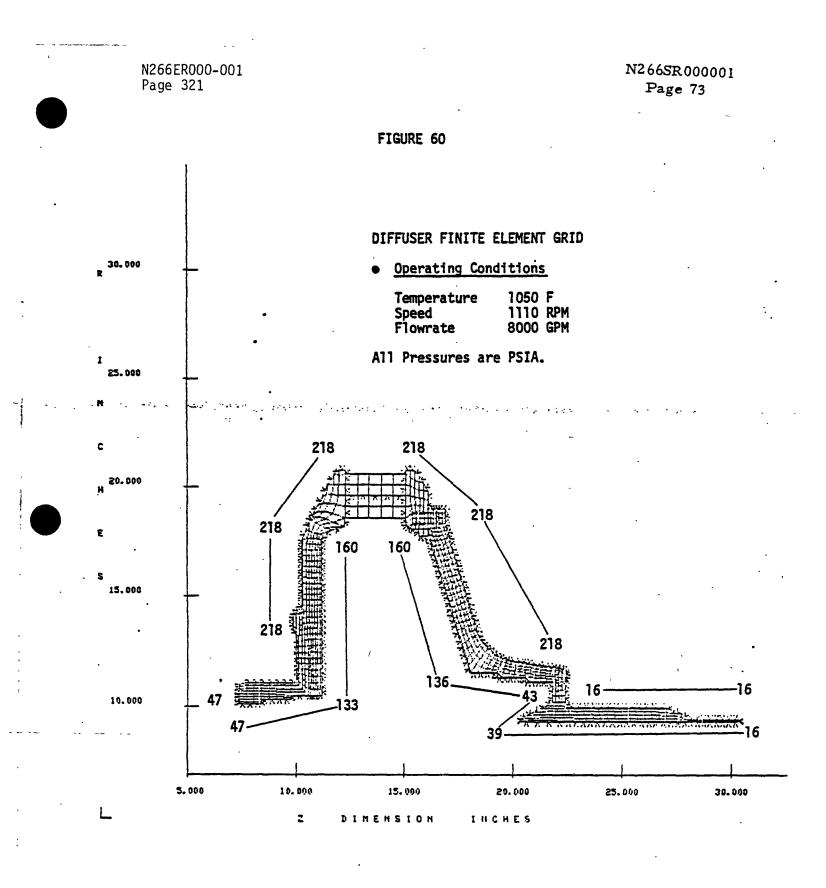
N266SR000001 Page 71



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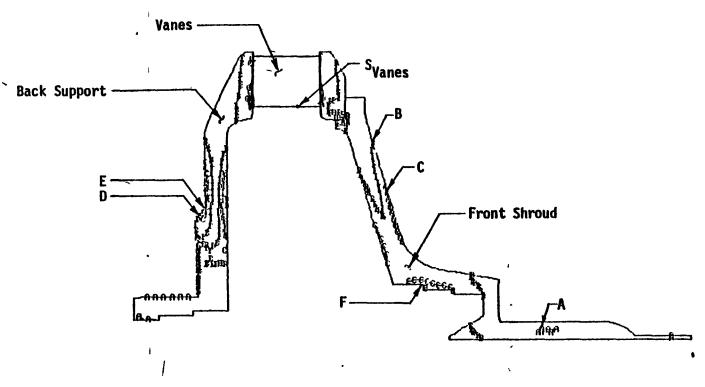
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**DIFFUSER STRESS INTENSITIES** 



Operating Conditions

Temperature	1050 F
Speed	1110 RPM
Flowrate	8000 GPM

• <u>Material:</u> 304 CRES

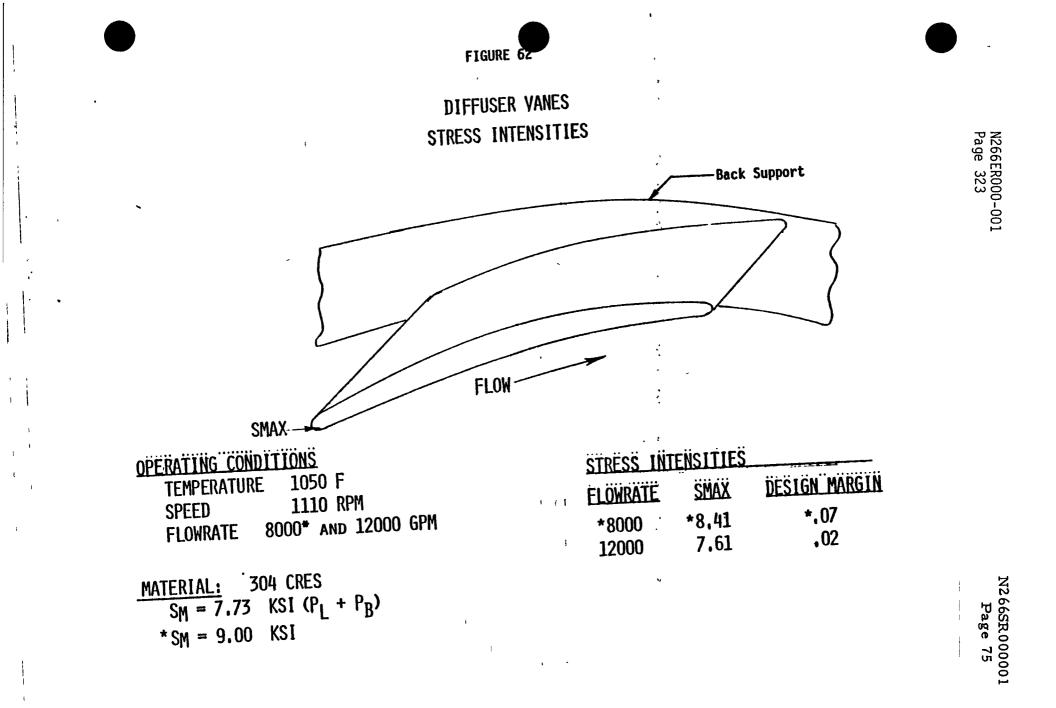
1

 $S_{M} = 7.73 \text{ KSI } (P_{L} + P_{B})$ \* $S_{M} = 9.00 \text{ KSI}$ 

Stress Inte	ensities_	
Location	<u>s, ksi</u>	Design <u>Margin</u>
Α	.14	54.21
В	1.37	4.64
C	2.74	1.82
D	4.11	<b>.88</b>
Ε	5.48	.41
*F	7.36	.22
*S <sub>Vanes</sub>	8.41	.07

N266SR000001 P**a**ge 74

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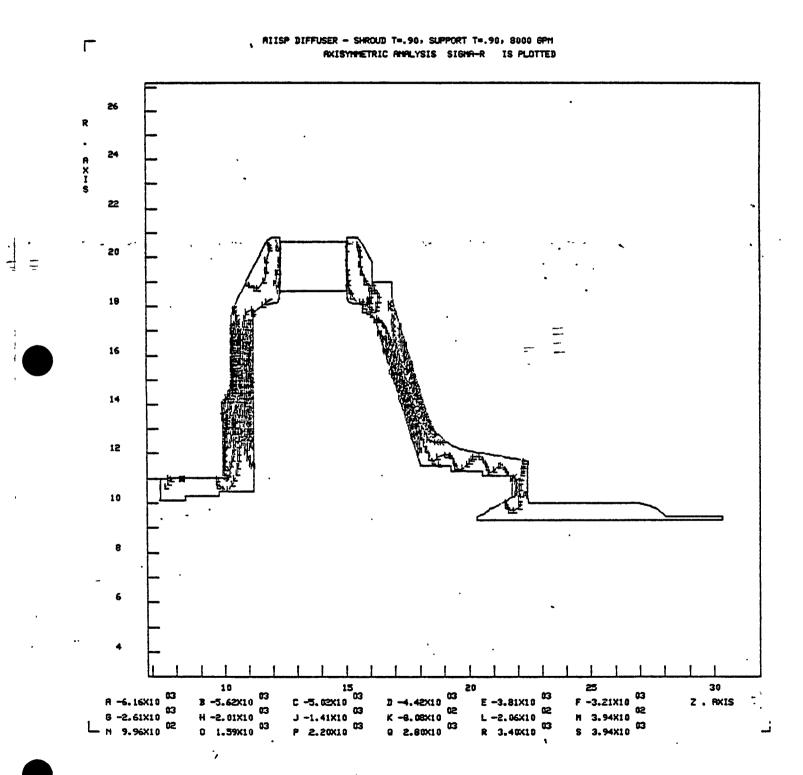
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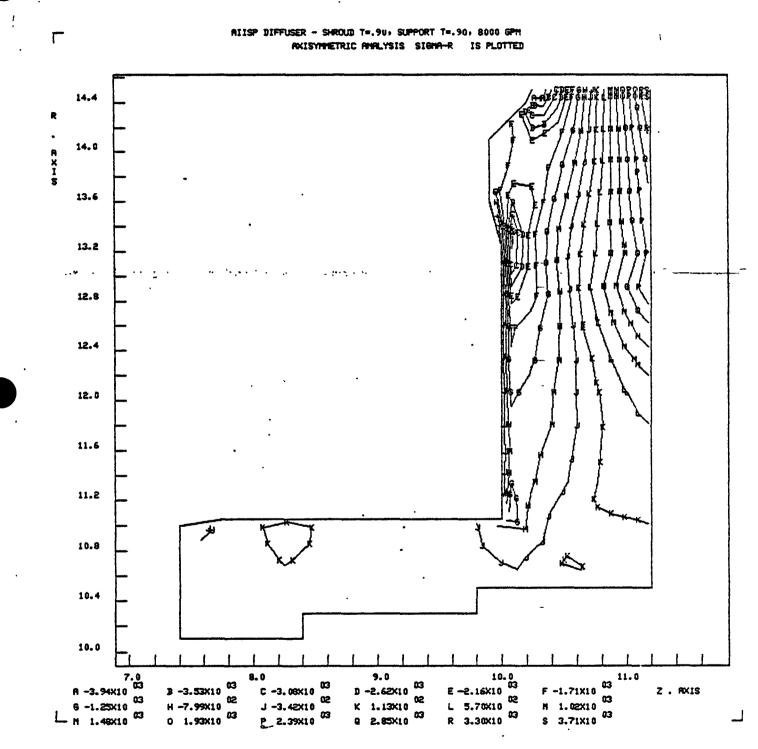
N266SR000001 Page 76

## FIGURE 63



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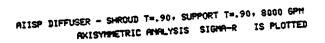
N266SR000001 Page 77

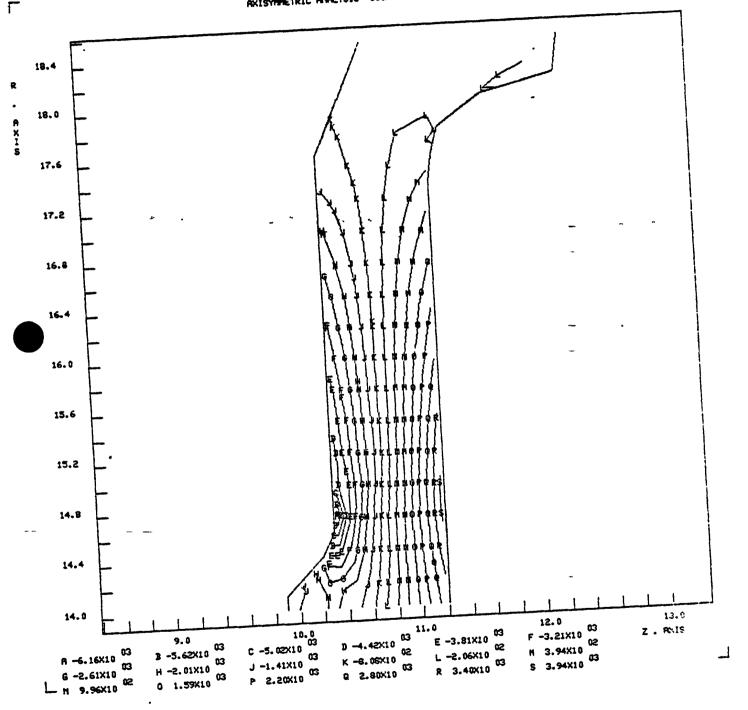


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FIGURE 65





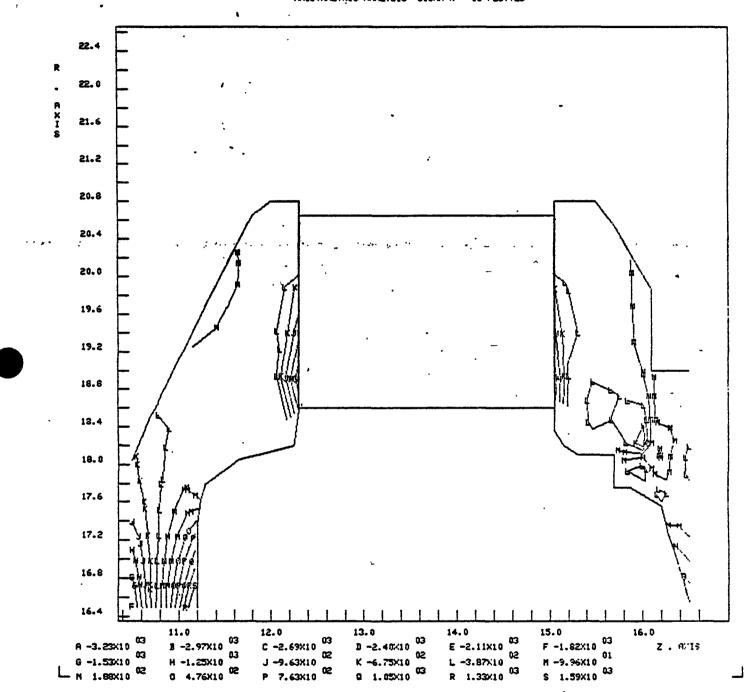
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## N266SR000001 Page 79

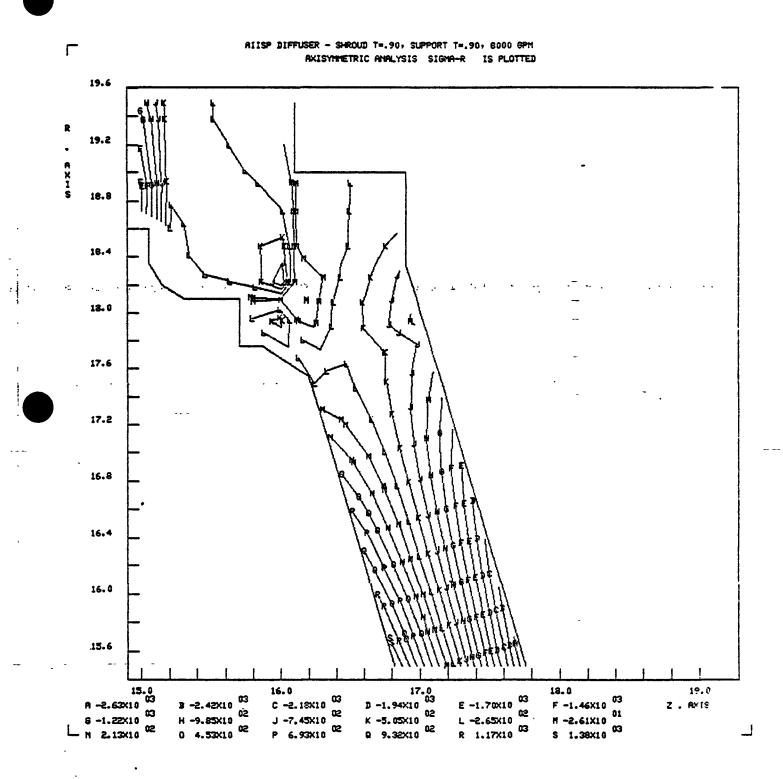
## FIGURE 66

#### ALISP DIFFUSER - SHROUD T=.90, SUPPORT T=.90, 8000 GPM RXISYMMETRIC ANALYSIS SIGMA-R IS PLOTTED

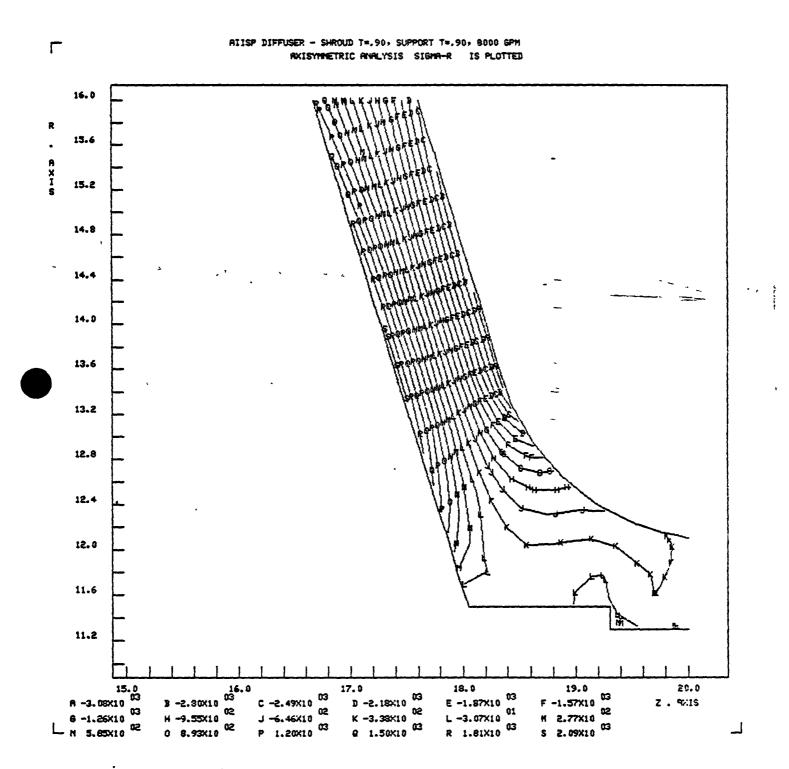


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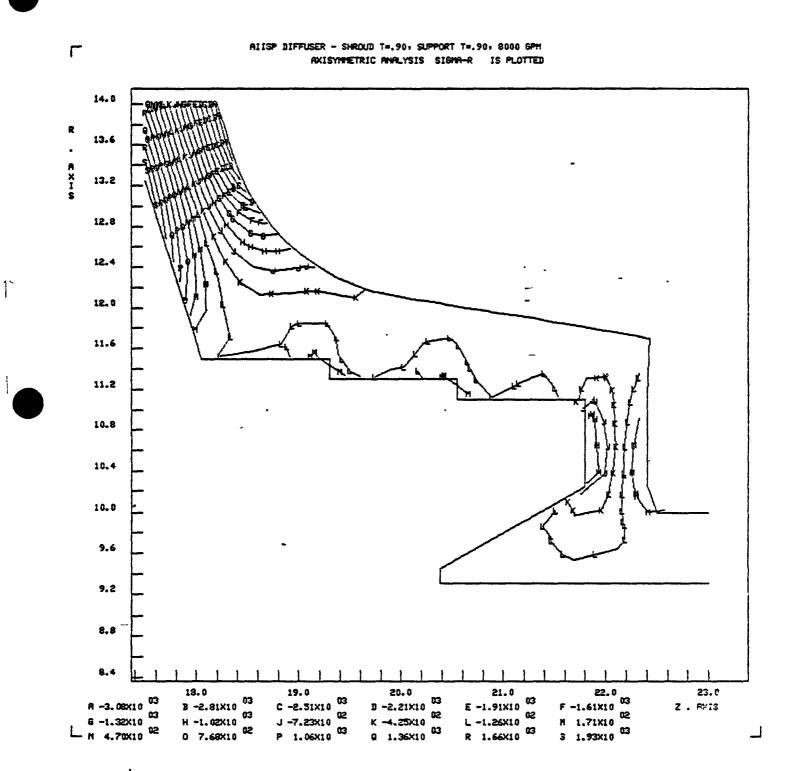


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### FIGURE 69

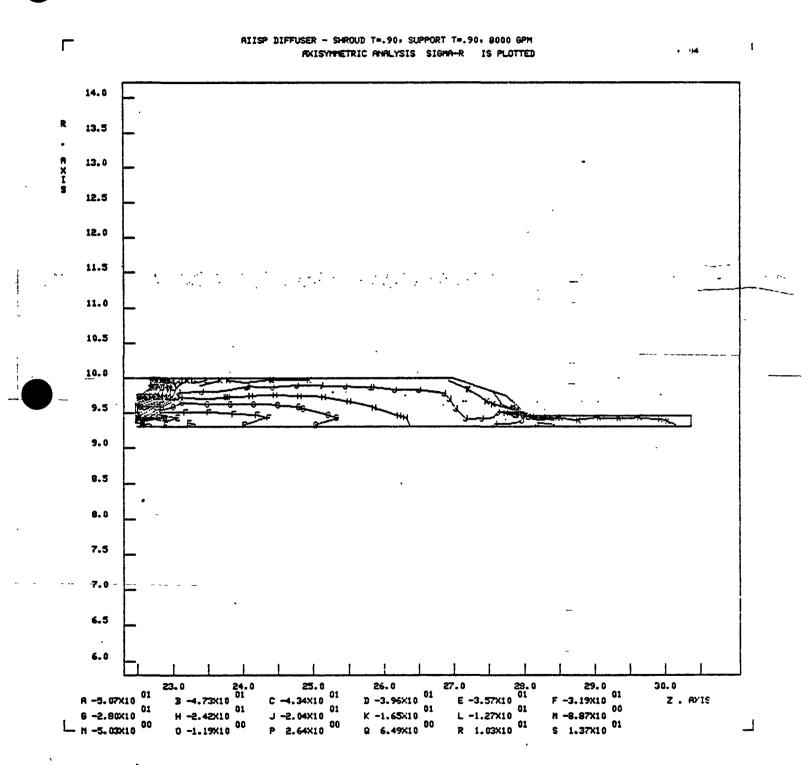


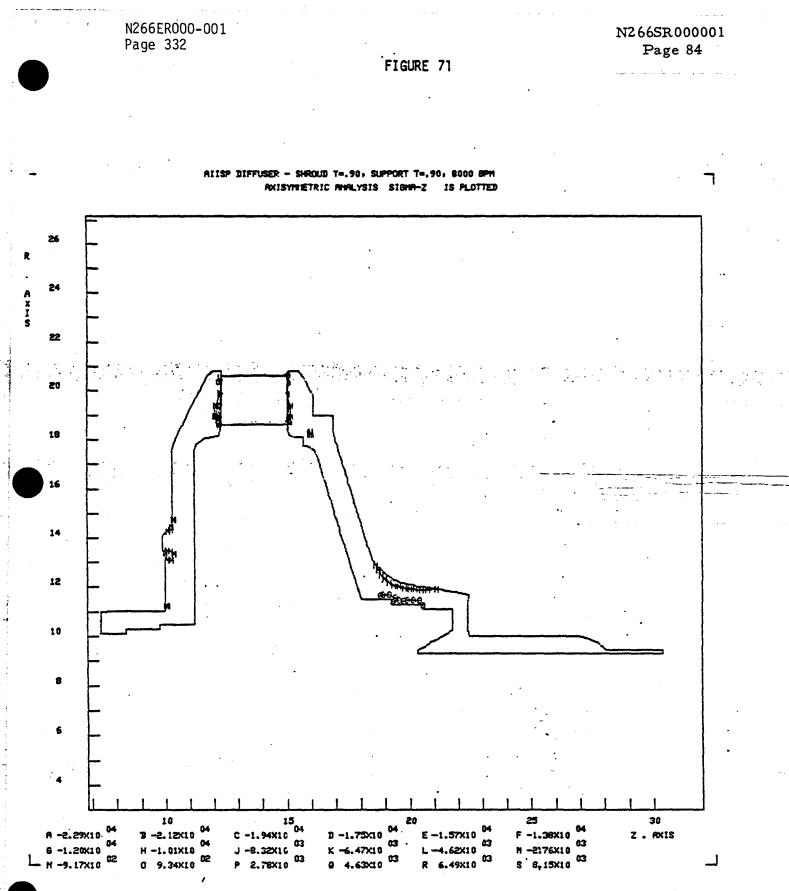
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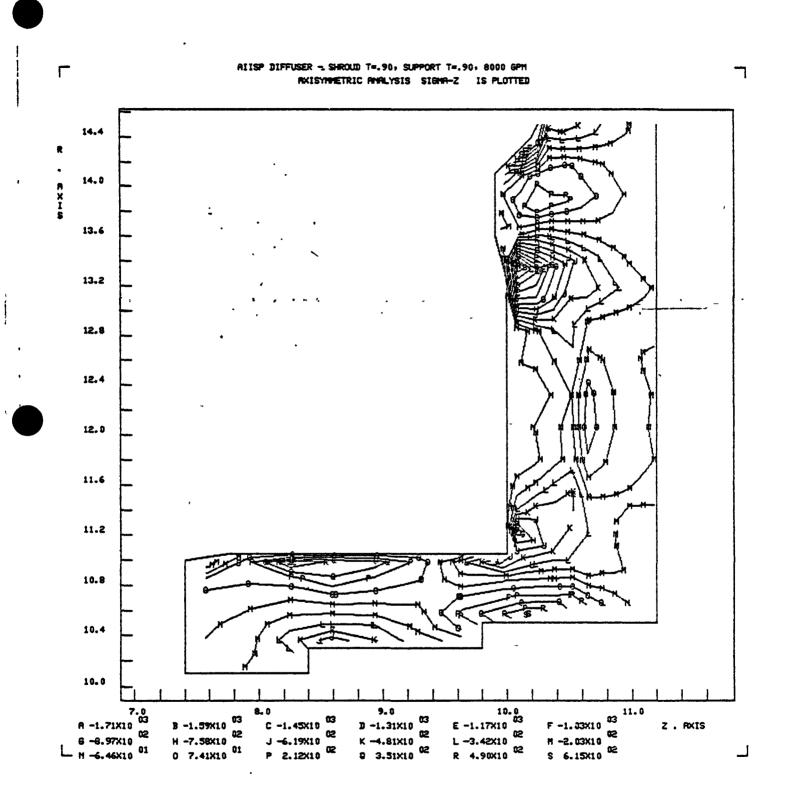
#### FIGURE 70

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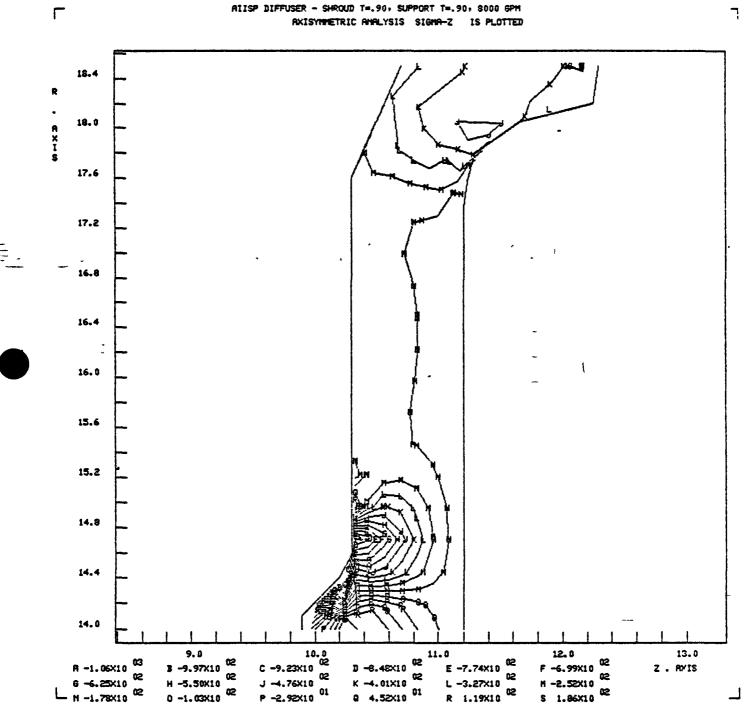
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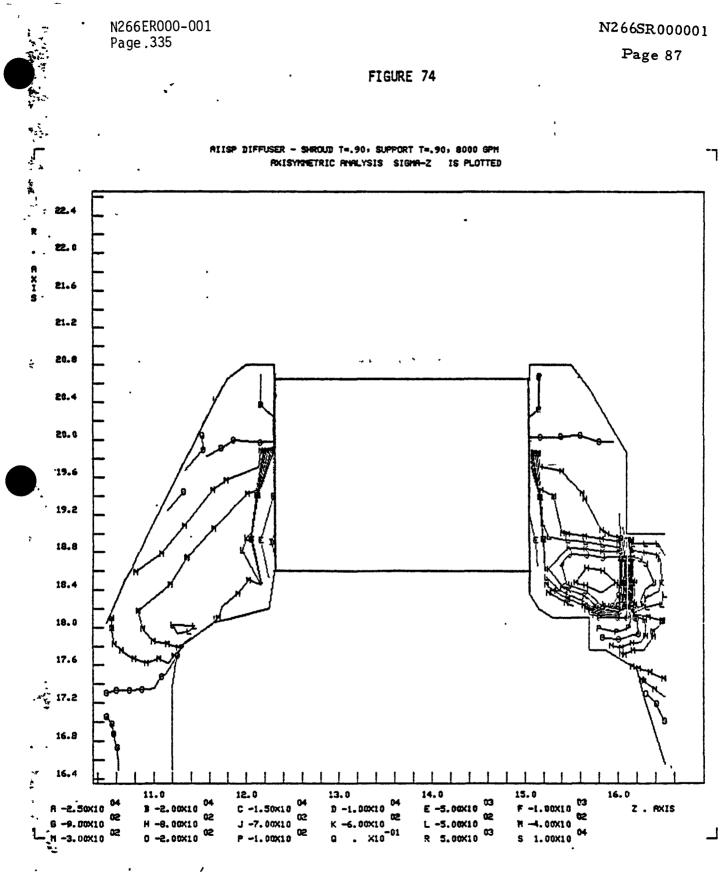


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FIGURE 73

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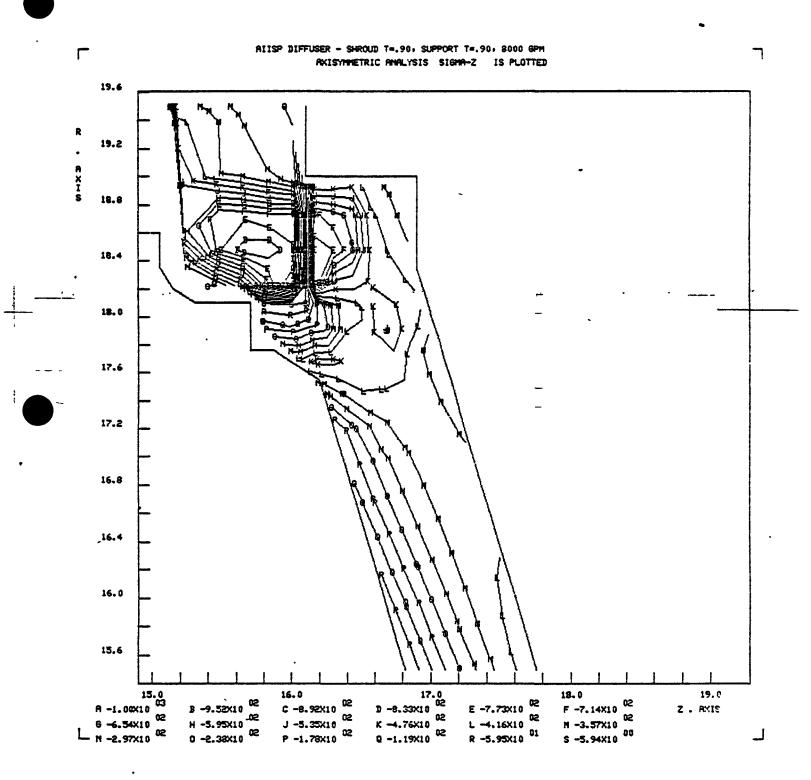




1.

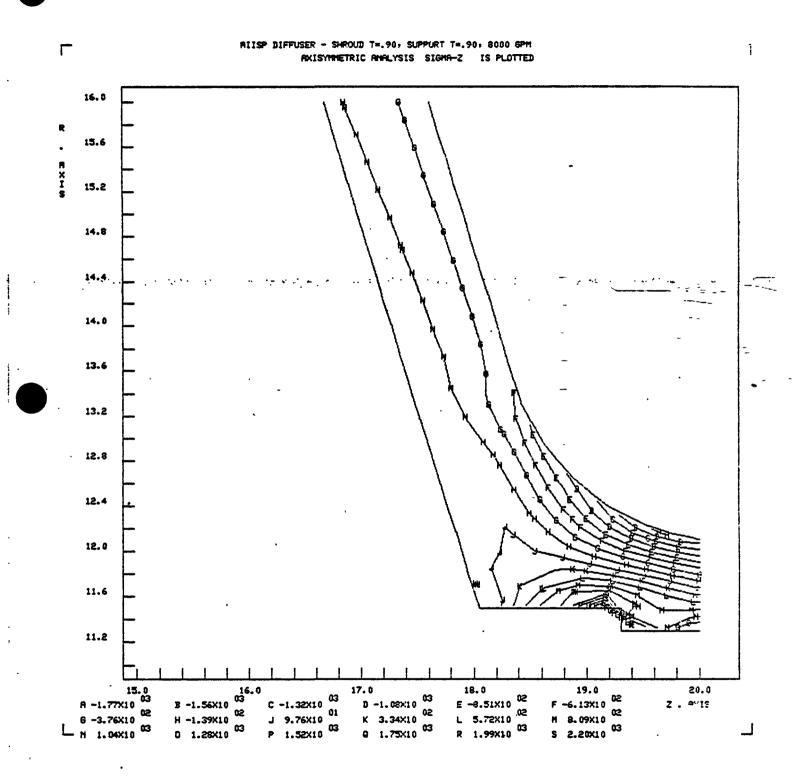
## N266SR000001

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## N266SR000001

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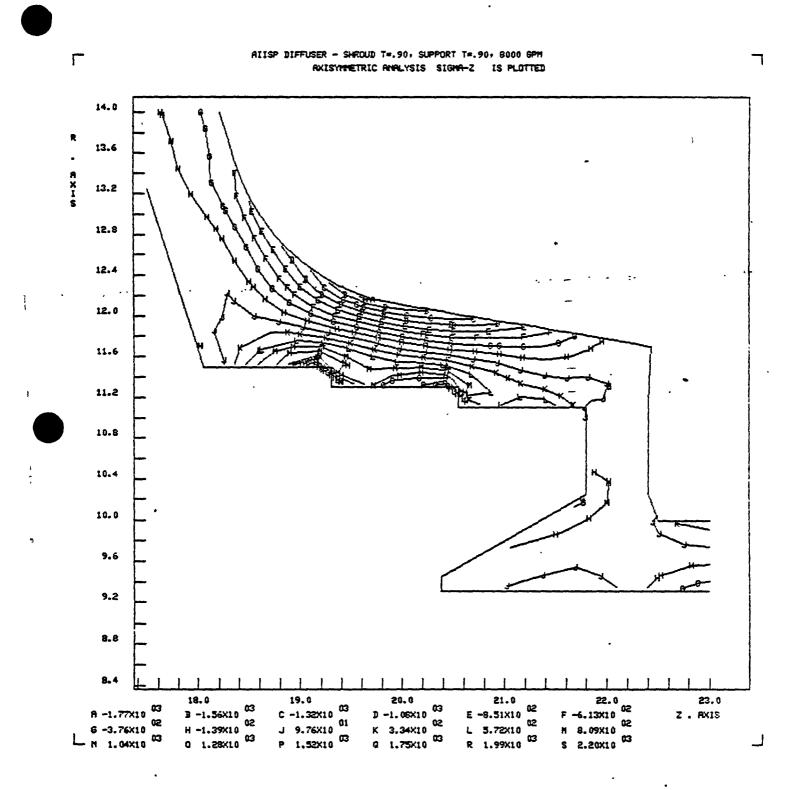


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FIGURE 77



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ALISP DIFFUSEP - SHROUD T=.90, SUPPORT T=.90, 8000 GPM Γ AXISYNMETRIC ANALYSIS SIGNA-Z IS PLOTTED 14.0 13.5 A X I S 13.0 12.5 12.0 11.5 11.0 10.5 10.0 9.5 9.0 8.5 8.0 7.5 7.0 6.5 6.0 24.0 B -5.17X10 H -1 28.0 E -3.20X10 L 7 23.0 30.0 25.0 26.0 27.0 29.0 C -4.51X10 02 D -3.85×10 <sup>02</sup> F -2.54X10 02 A -5.76×10 Z . AXIS 6 -1.88×10 H -1.22X10 02 J -5.68X10 K 8.95×10 00 L 7.47X10 01 H 1.40×10 02 P 3.38X10 02 L N 2.06X10 02 0 2.72X10 02 Q 4.03X10 02 R 4.69X10 02 S 5.28×10 02

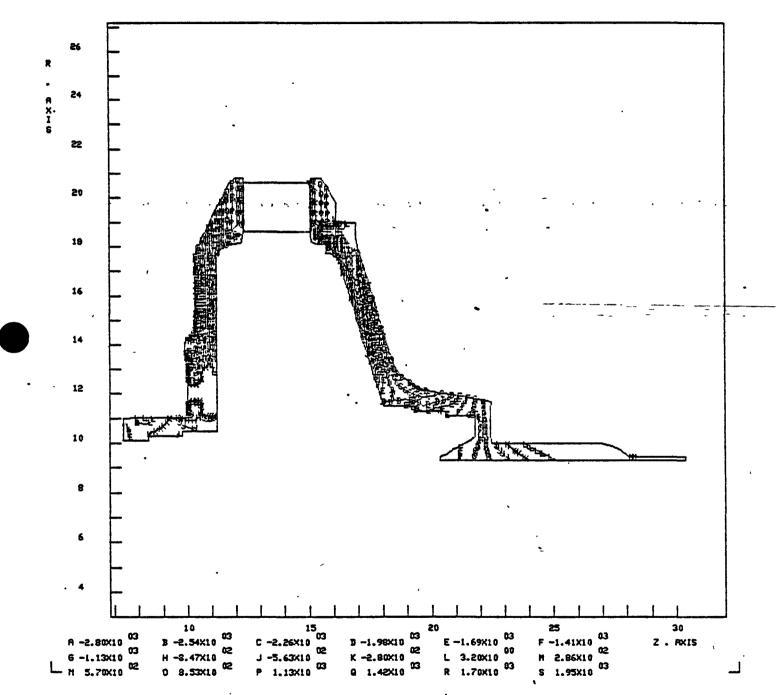
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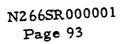
## N266SR000001 Page 92

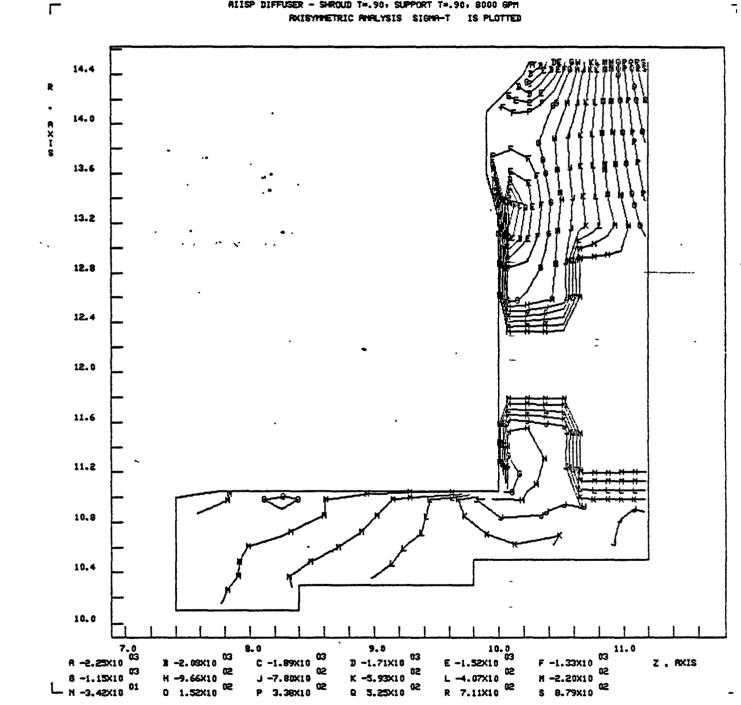
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FIGURE 79

#### ALISP DIFFUSER - SHROUD T=.90, SUPPORT T=.90, 8000 GPM AXISYMMETRIC ANALYSIS SIGNA-T IS PLOTTED







ALISP DIFFUSER - SHROUD T=. 90, SUPPORT T=. 90, 8000 GPM

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• AXIS

18.4

18.0

17.6

17.2

16.8

16-4

16.0

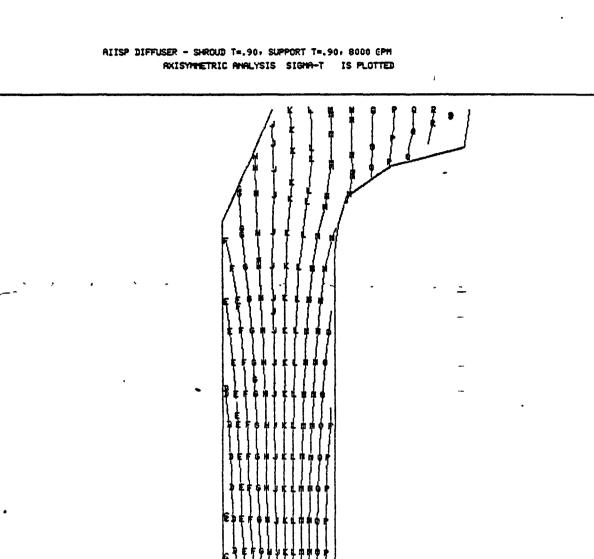
15.6

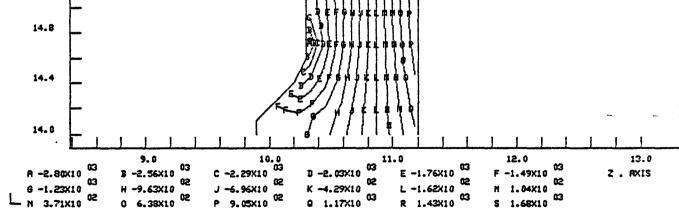
15.2

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FIGURE 81





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AXIS

22.4

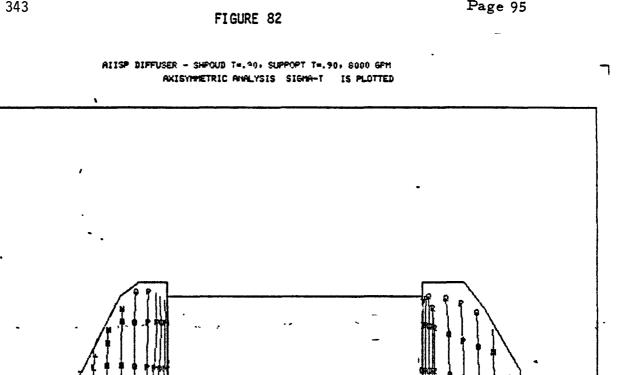
22.0

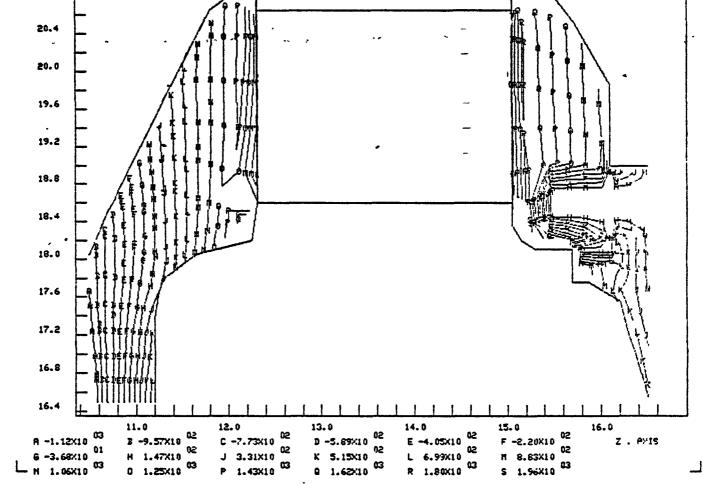
21.6

21.2

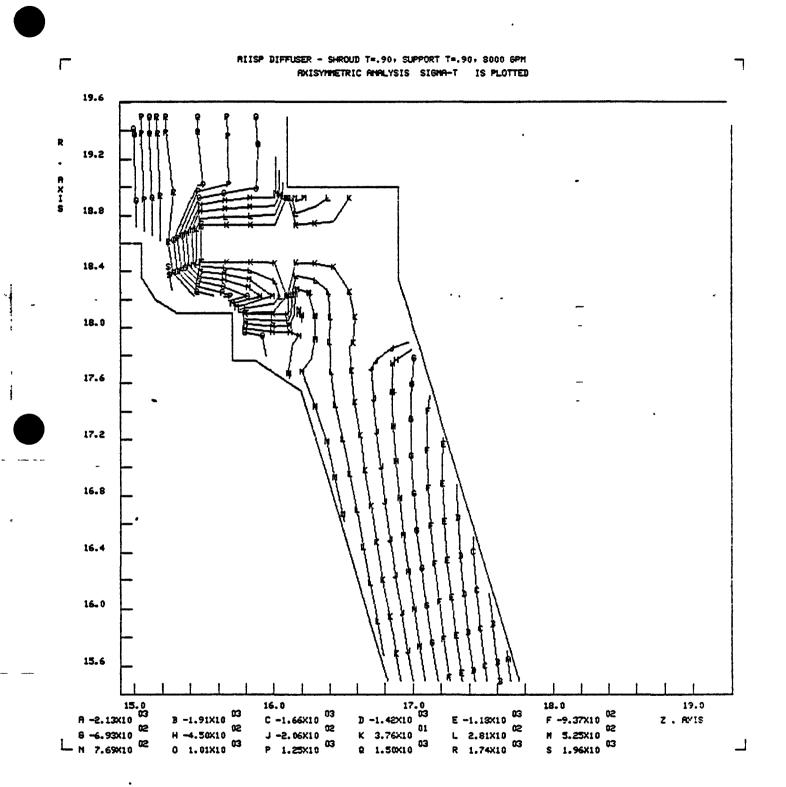
20.8

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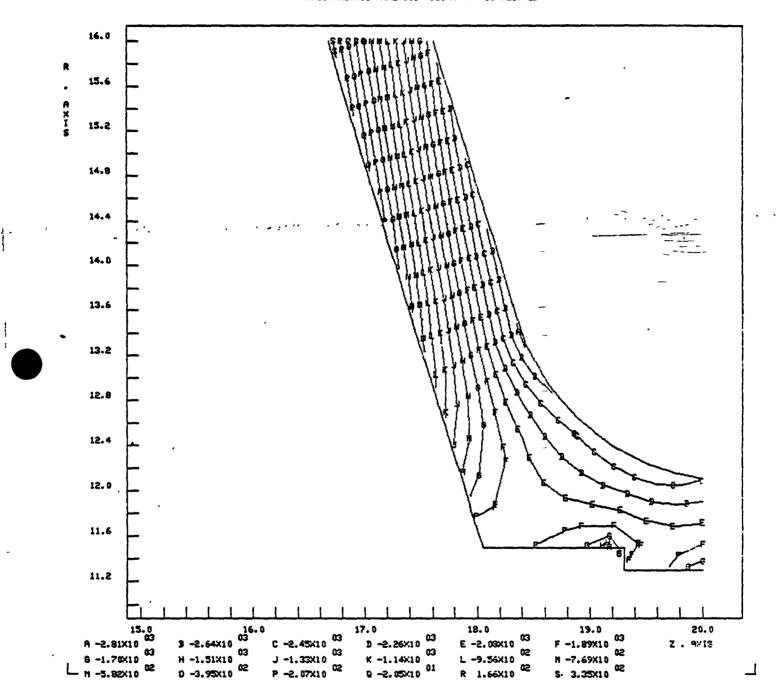


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#### FIGURE 84

RIISP DIFFUSER - SHROUD T=.90, SUPPORT T=.90, 8000 GPM AXISYNNETRIC ANALYSIS SIGNA-T IS PLOTTED

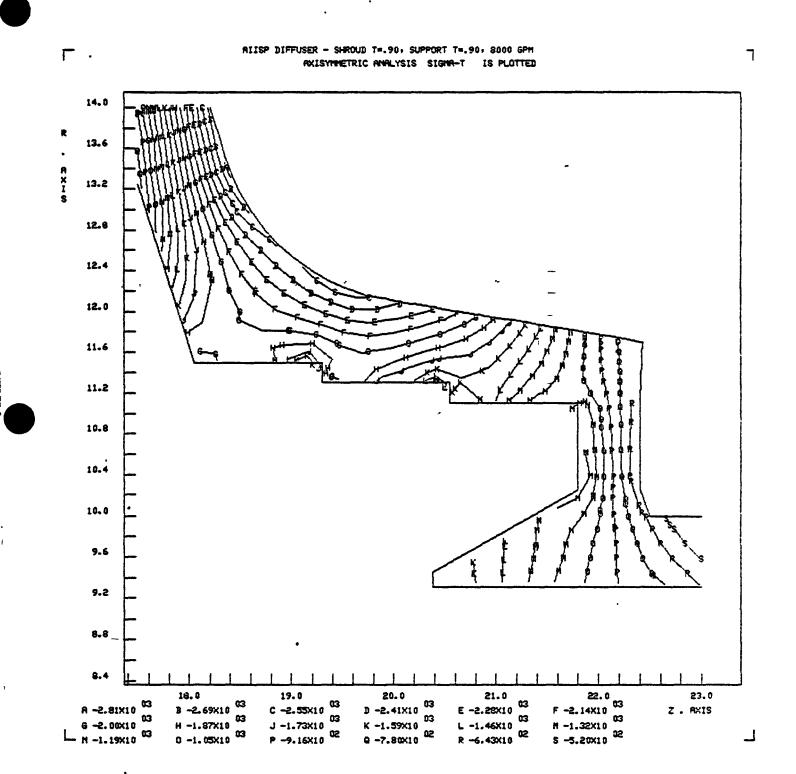


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### FIGURE 85

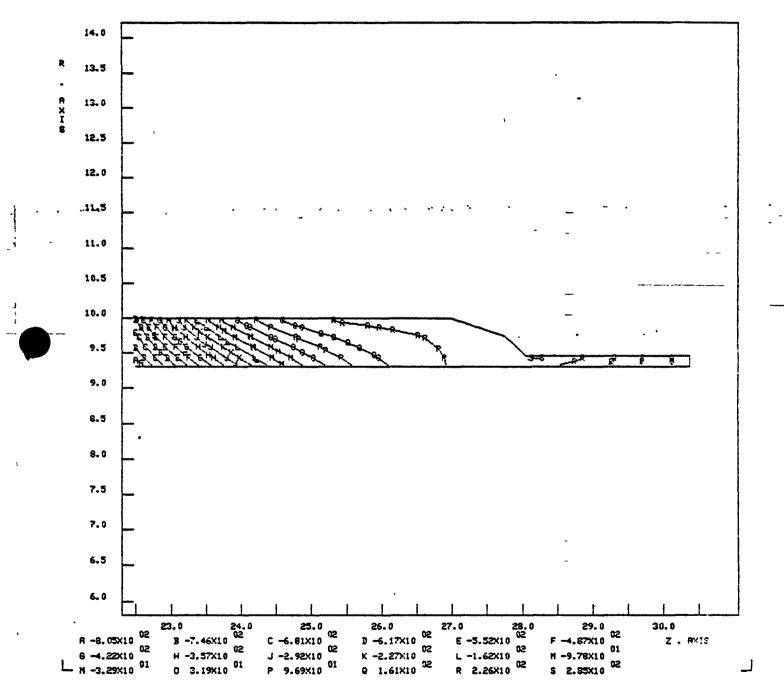


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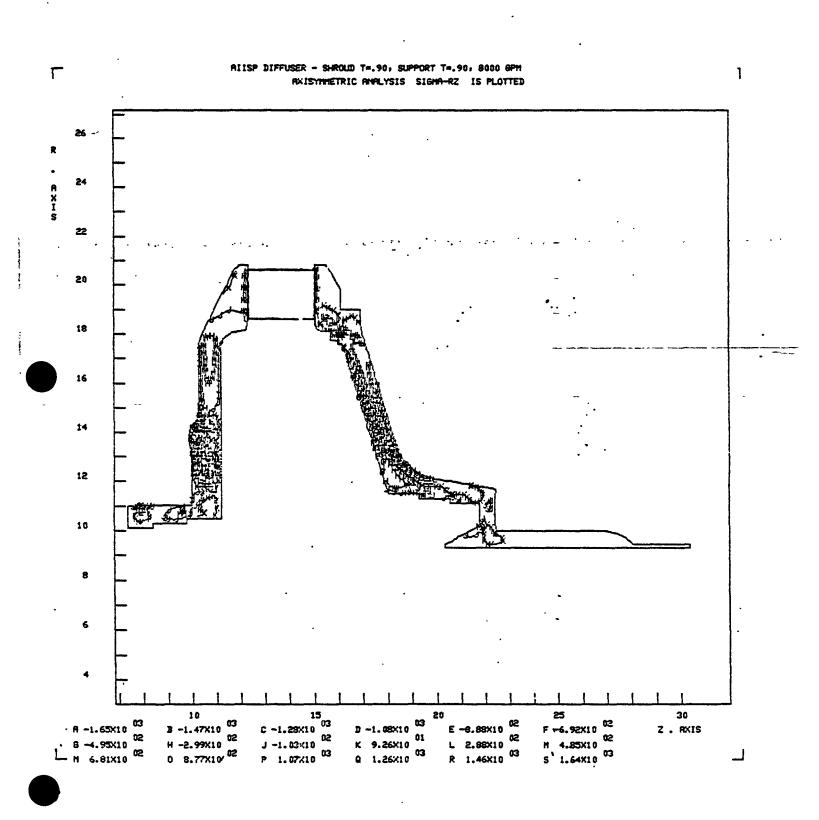
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## FIGURE 86

#### ALISP DIFFUSER - SHROUD T=.90, SUPPORT T=.90, 8000 GPM RXISYMMETRIC ANALYSIS SIGNA-T IS PLOTTED



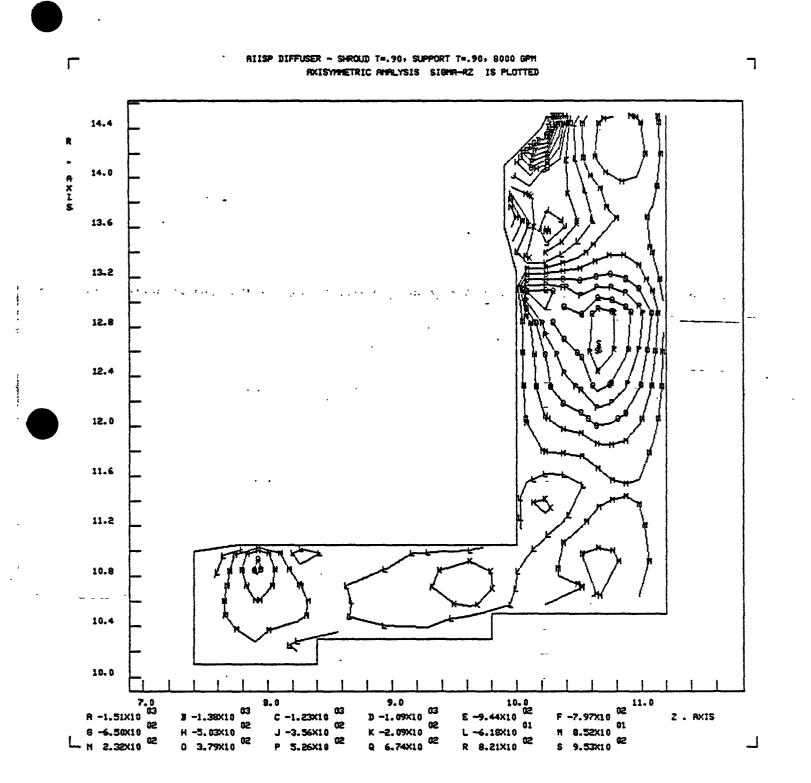
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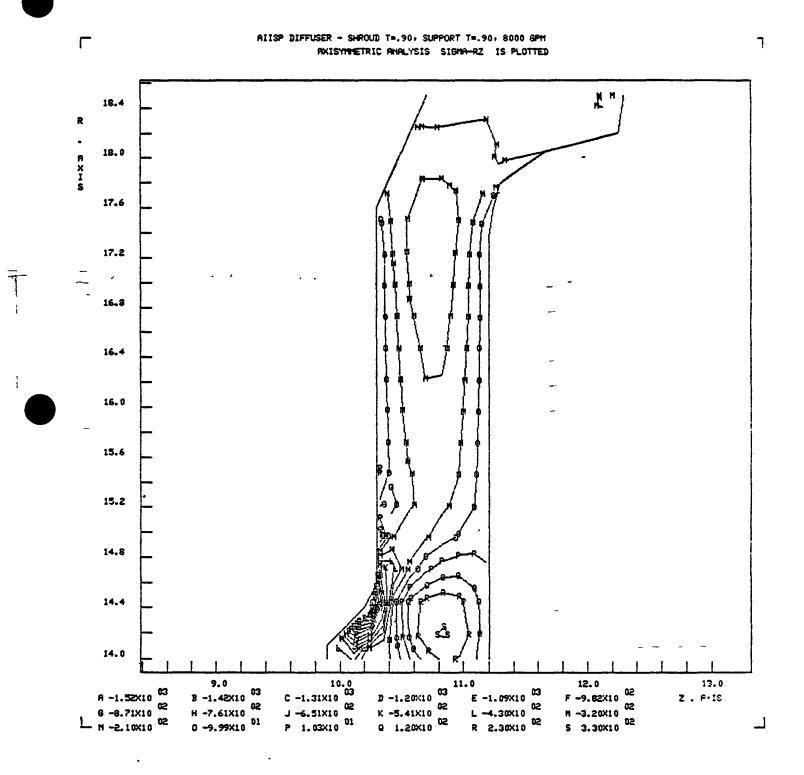
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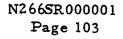
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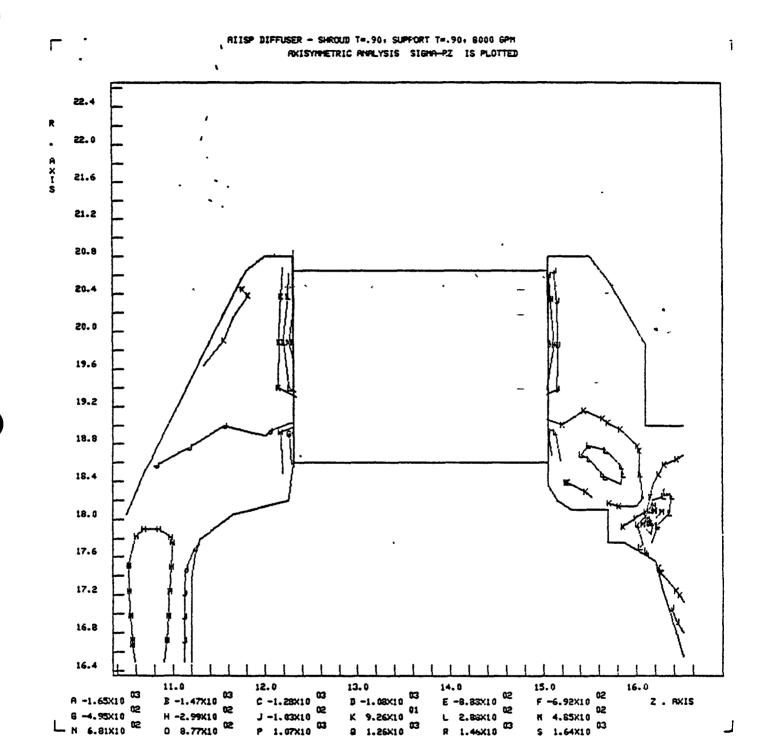


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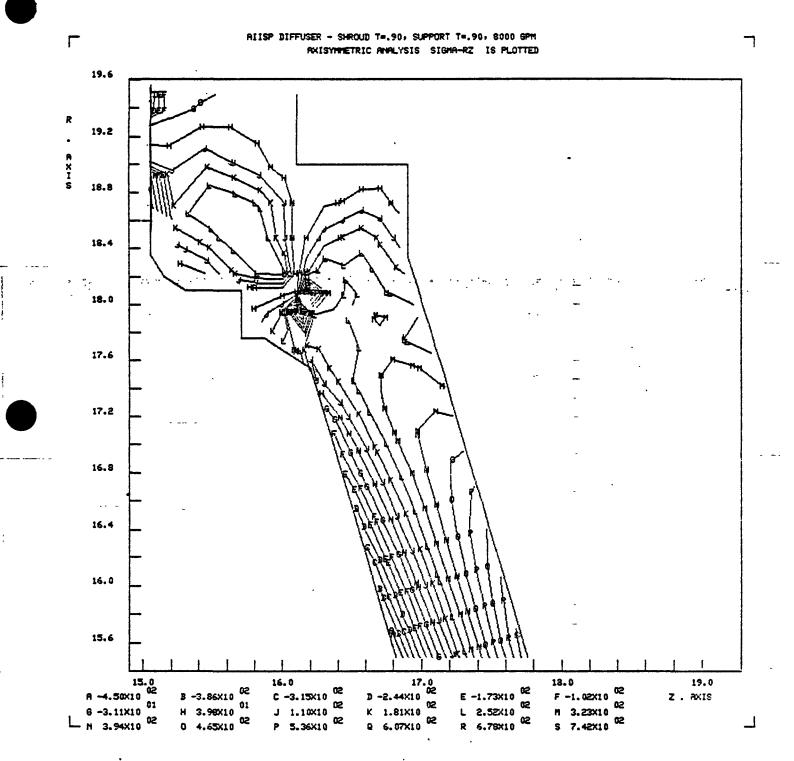
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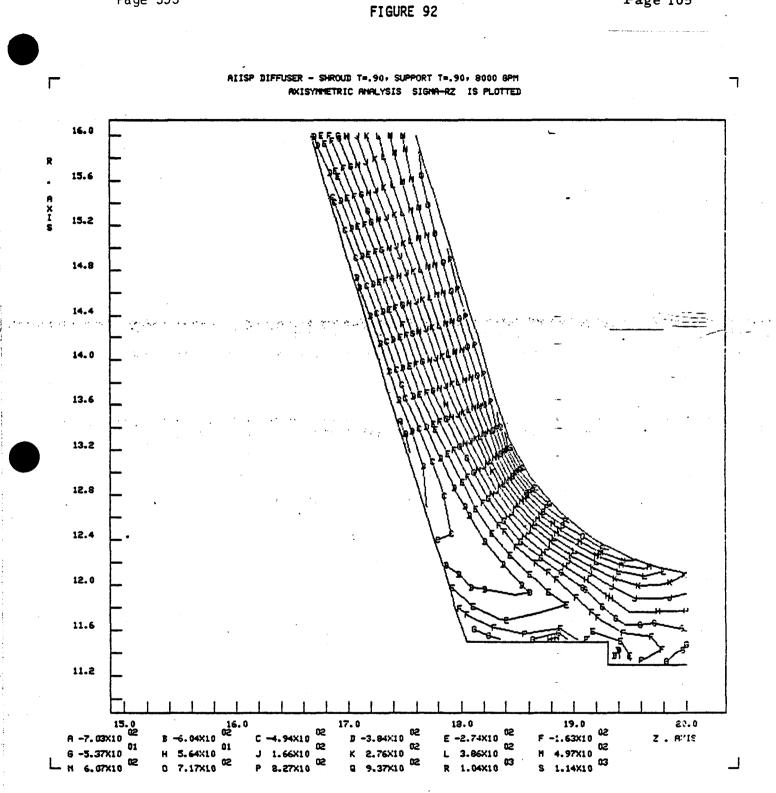




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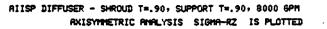
## N266SR000001 Page 106

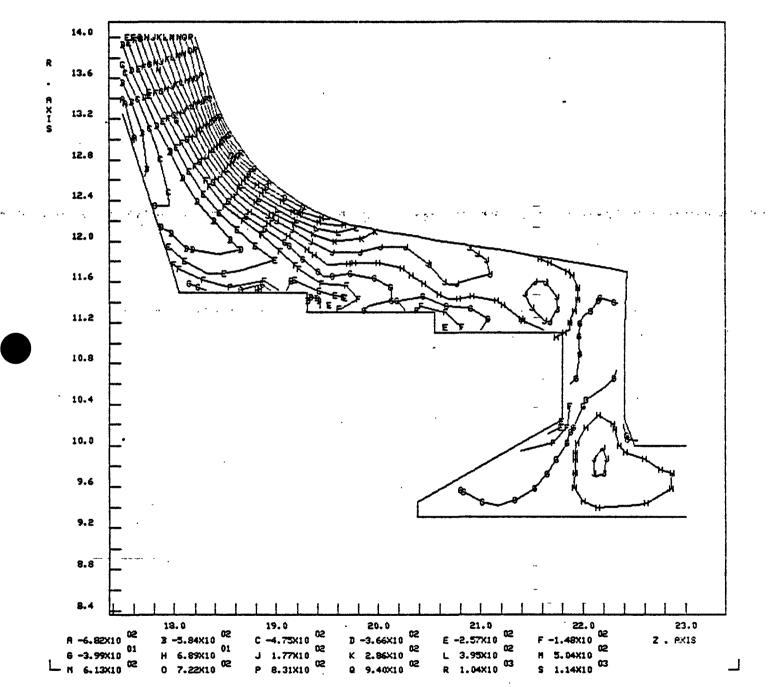
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#### FIGURE 93

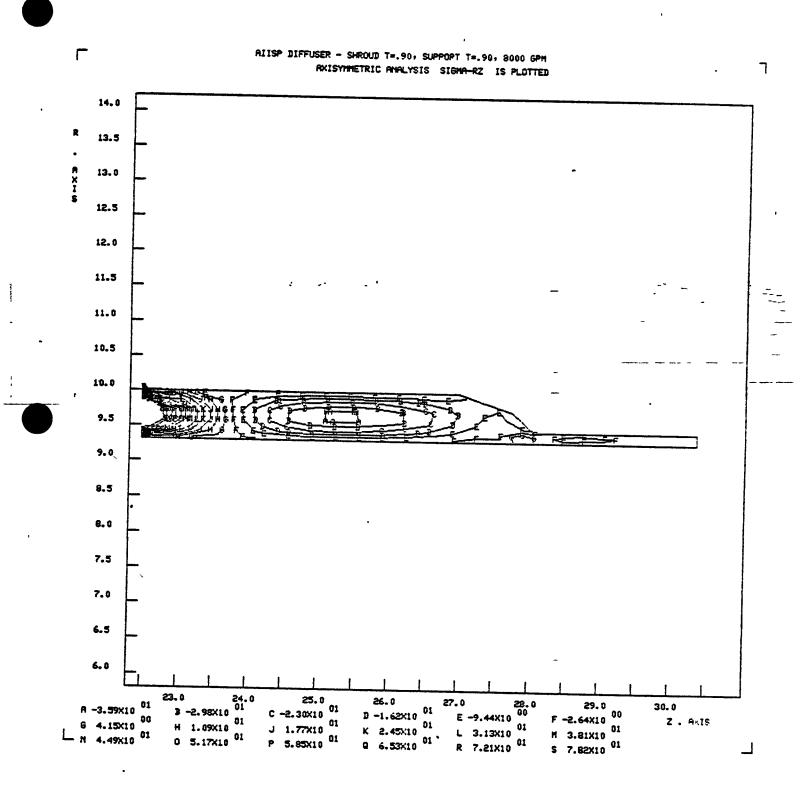




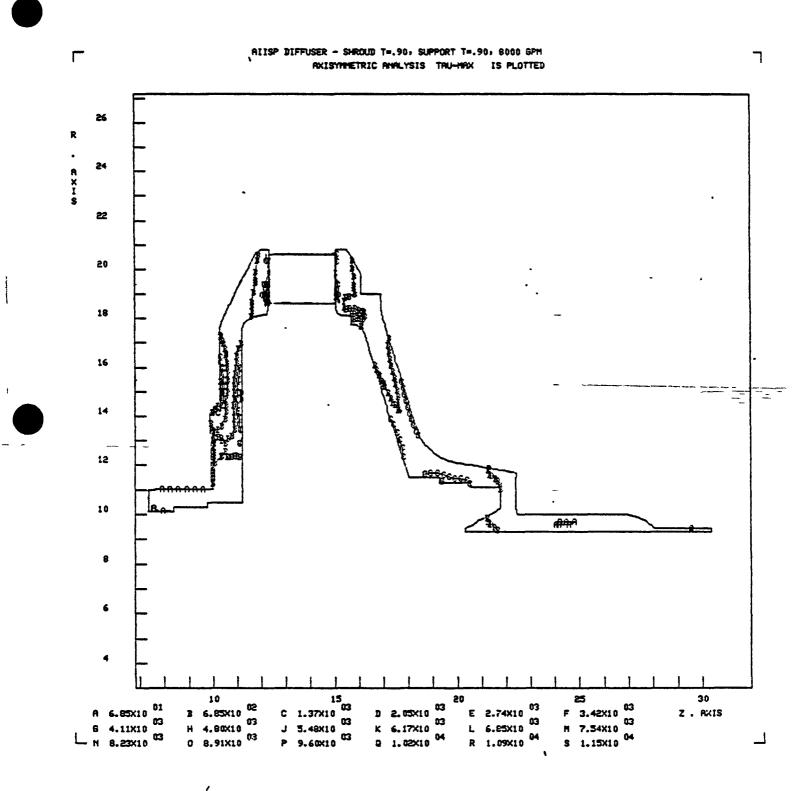
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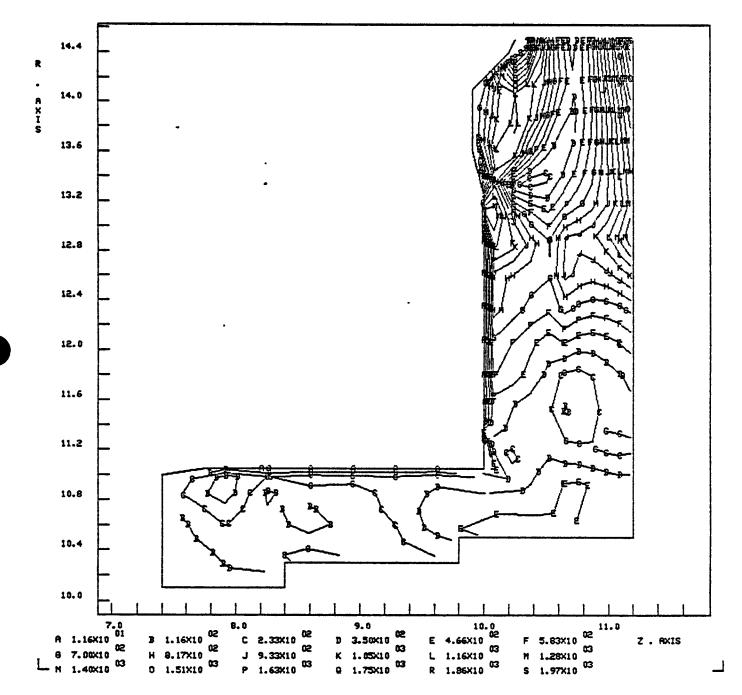
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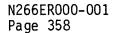
Page 109

## FIGURE 96

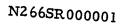
ALISP DIFFUSER - SHROLD T=.90, SUPPORT T=.90, 8000 GPM AKISYMMETRIC ANALYSIS TAU-MAK IS PLOTTED



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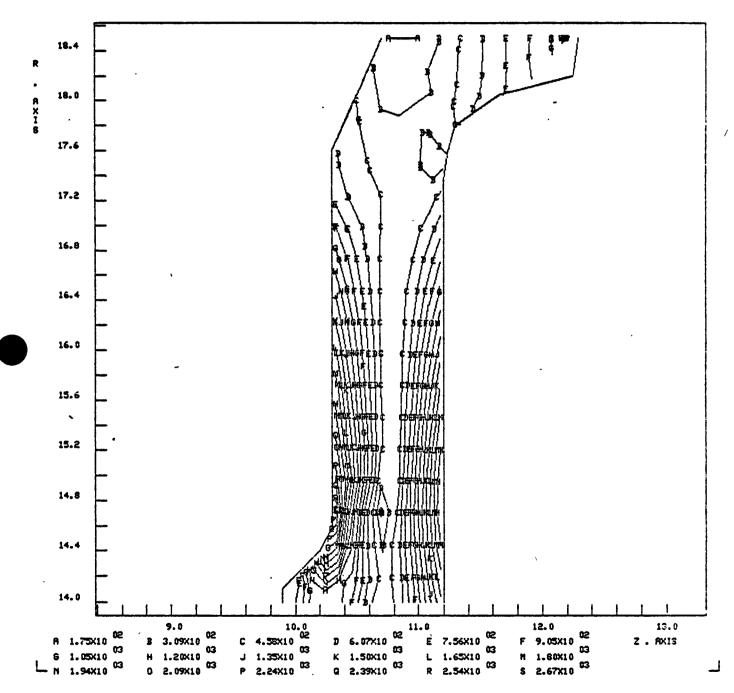
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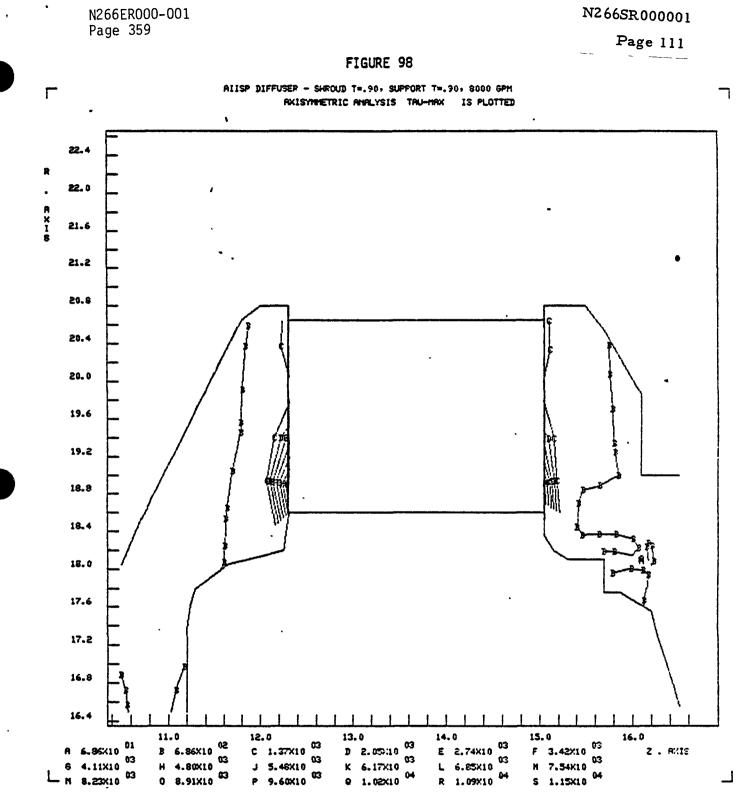
## - -ge 110

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#### FIGURE 97

#### ALISP DIFFUSER - SHROUD T=.90, SUPPORT T=.90, 3000 GPM AXISYMMETRIC ANALYSIS TAU-MAX IS PLOTTED



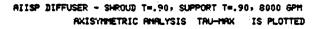


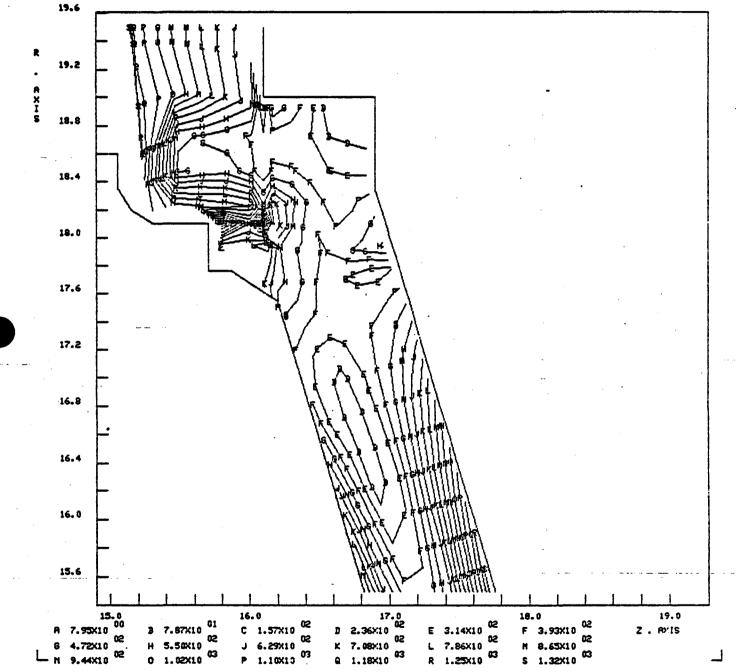
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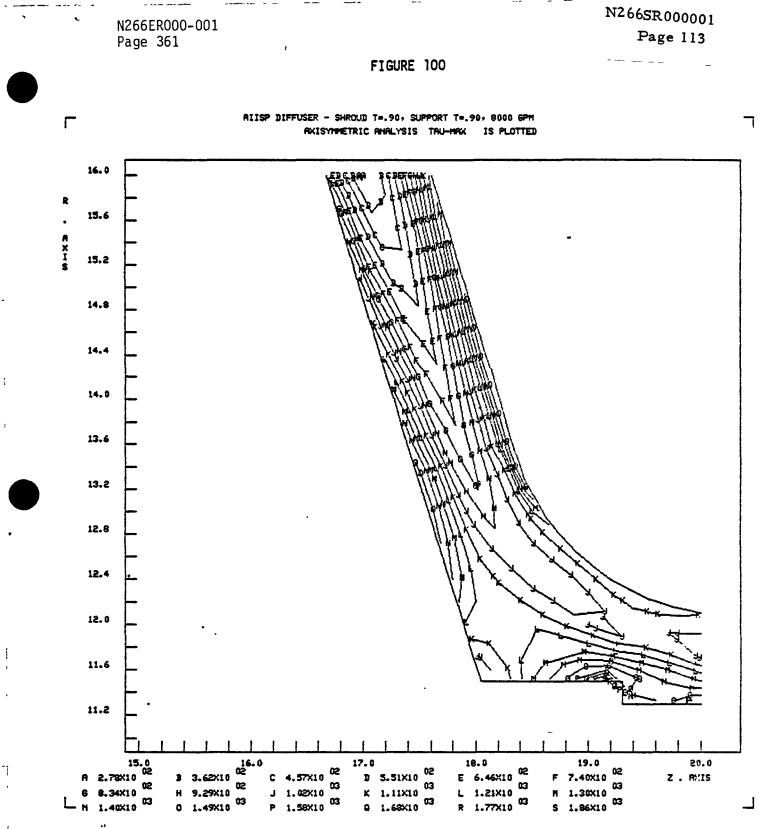
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## FIGURE 99







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## FIGURE 101

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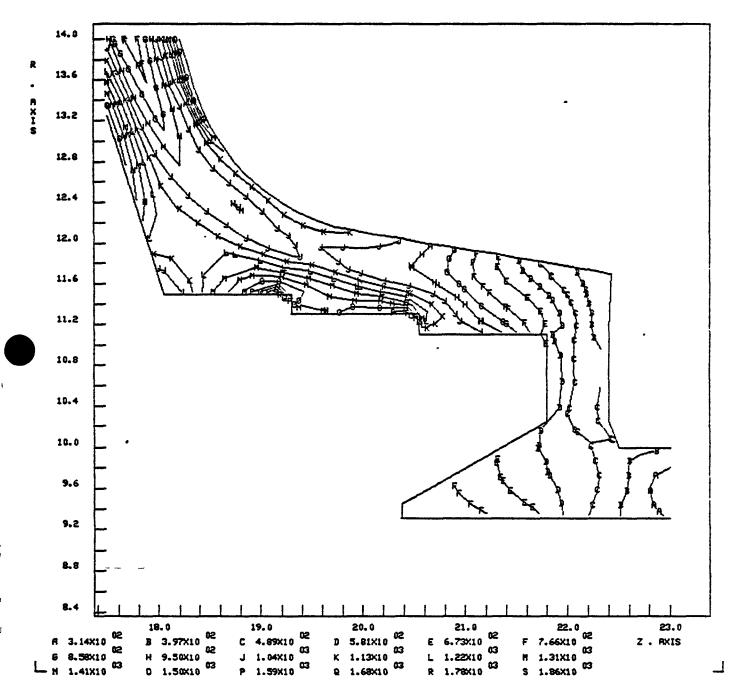
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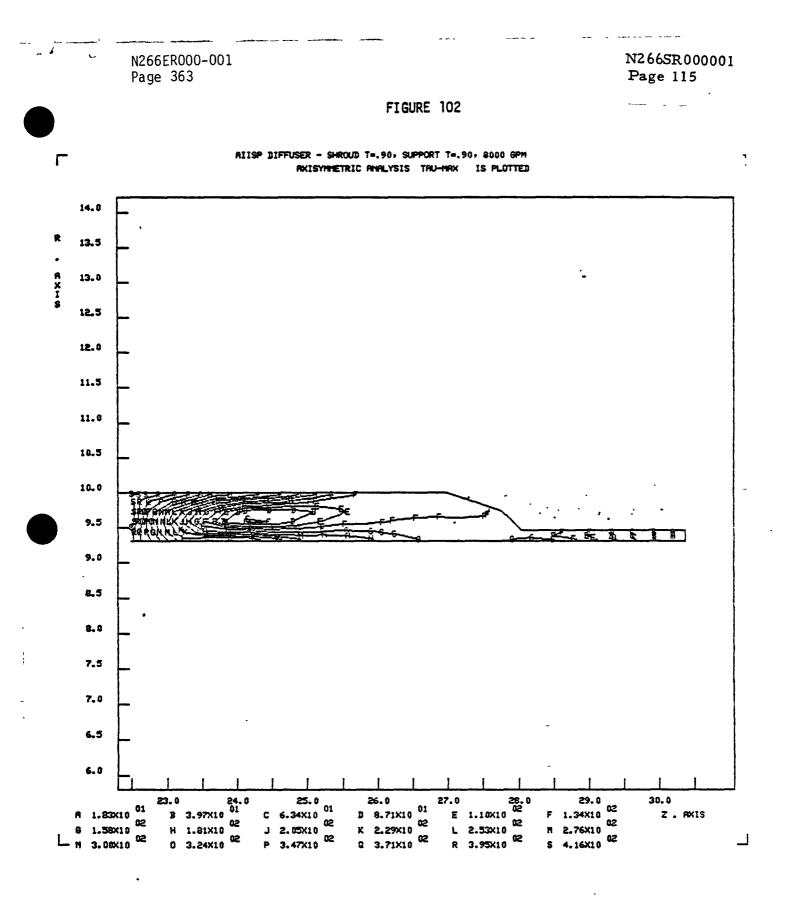


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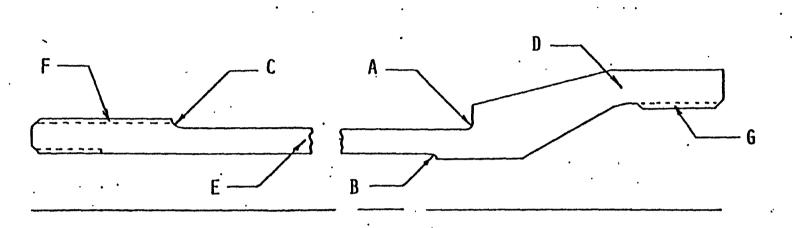
#### ALISP DIFFUSER - SHROUD T=.90, SUPPORT T=.90, 8000 GPM AKISYMMETRIC ANALYSIS TAU-MAK IS PLOTTED





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FIGURE 103 SHAFT EXTENSION STRESS INTENSITIES



• OPERATING CON	DITIONS	•	• 5
TEMPERATURE	1050°F		Ī
SPEED	1110 rpm		
AXIAL LOAD	22.6 KIPS		
• MATERIAL:	A286		
$1_{S_{M}} = 15.0$ KSI	(P <sub>M</sub> )		
$S_{M} = 20.0 \text{ KSI}$	$(P_L + P_B)$		

• <u>STRESS_INTI</u>	ENSITIES	5501
LOCATION	S KSI	DES I Marg
Α	15,6	,2
В	15,1	.3
С	7,9	1.5
D	6,5	2.0
E 1	4.5	2,3
F <sup>1</sup>	2.7	4.5
. G <sup>1</sup>	4.0	2.7

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# APPENDIX I

# INTERMEDIATE SIZE INDUCER PUMP -STRUCTURAL ANALYSIS AND TRANSIENT DEFORMATION STUDIES

ESG Document N266SR000-002

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			NUMBER		REV ' TR/CHG NO.
	Rockwell International Energy Systems Group SUPP	ORTING DOCUMENT	N266SR0	00-002	NC SEE SUMMARY OF CHG
DD	OGRAM TITLE		DOCUMENT	_	
1			Stress I		
	Intermediate Size Ind	KEY NOUNS	1916, 96	ructural and	
DC	CUMENT TITLE		ORIGINAL IS		t Deformation
	Intermediate Size Ind	ucer Pump - Structural	ORIGINAL IS	SUE DATE	
	Analysis and Transien		GO NO.	S/A NO.	
	5				PAGE 1 OF TOTAL PAGES 132
PR	EPARED BY/DATE	DEPT MAIL ADDR	09280	22000	BEL DATE
	EPARED BY/DATE T. K. Cheng ッベ J. N. Nishizaka g.7	Ching 731 LB35			5-7-79BK
	J. N. Nishizaka g.7	<b>n.7L.</b> 731 LB35		BOX ONLY)	ASSIFICATION
I.F	&D PROGRAM? YES NO		] ;	DOE DOD	RESTRICTED
AP	PROVALS	0.00 5/7/29ATE	UNCL CONF.		DATA DEFENSE
	R. V. Anderson K. N. T. J. Boardman	Differ Slill	SECRET		INFO.
		i ent	AUTHORIZE		LDATE
L			CLASSIFIER		
	DISTRIBUTION	ABSTRACT			
*	NAME MAIL ADDR	This report summarizes	s the stri	ictural a	nd thermal
*		transient deformation			
	R. V. Anderson (8) LBO2 R. J. Beeley TO19	Size Inducer Pump. Th	ne analyse	es were p	erformed in
*		accordance to the requ	irements	of_N2665	T310001,
	R. A. Castle LB35	the specification for	the ISIP.		•
*	Linke oneng LDDD	The results of stress	analvsis	indicate	that the
*		thermal transient str	-		•
	M. A. Grisham LB26	the stress strain lim	•		
	G. J. Hallinan LB39	which was used as a	guide. T	he summ	nary of
<b> </b> *	R. K. Hoshide JB05	results are shown on	Pages 17	, 21, and	d 25
Î.	J. L. Lockett LB39 A. A. Loffredo LB35	,		·	u.
	E. M. Mouradian LB35				
	G. W. Meyers LA10				
	D. K. Nelson LB35				
*	J. N. Nishizaka LB35 C. Q. Torrijos LB26				
	K. H. Yun LB35				
	···· ··· · ··· · ··· ·				
			<u>.</u>		
1		RESERVED FOR PROPRIETARY/LEGA	L NOTICES		
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		This report was prepared a			
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	721 D 260/54-1444	nor any of its contractors.	subcontracto	rs, or their	employees, makes any
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1	COMPLETE DOCUMENT	sibility for the accuracy, apparatus, product or proce	completences ess disclosed	or redrese	ents that its use would
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### 1.0 INTRODUCTION

The Intermediate Size Inducer Pump (ISIP) utilizes the pump frame from the FFTF Prototype Pump as a test vehicle for an inducer impeller assembly. Construction requirements for the FFTF prototype pump may be found in Westinghouse Specification EWS-1551, which was written for the complete pump. ESG Specification N266ST310001 covers construction requirements for those parts used in the ISIP design to replace prototype pump parts. A complete description of the prototype pump is given in the Westinghouse Operation and Maintenance Manual, OMM-051-00-005. The ISIP Operation and Maintenance Manual N266OMM000001 (Reference 10) describes those parts of the pump assembly which are different for the ISIP configuration.

Structural analyses of the ISIP components in the region of the inducer/impeller assembly was performed to determine the effects of steady-state operation and of thermal transients which are defined as part of the test requirements in the ISIP specification. Evaluation of the structural integrity of the ISIP parts was based on using analytical methods and acceptance criteria of the Section III ASME Boiler and Pressure Vessel Code and appropriate RDT standards as applied to designs for high-temperature service. Evaluation of the steady-state effects are reported in N266SR000001 (Reference 5). This report covers the effects of operation during thermal transients, superimposed on those steady-state conditions.

In addition to the structural analysis, a thermal deformation analysis was conducted to determine the effects of thermal transients on critical regions such as fits and running clearances to permit evaluation of the functionability of the design and of the restrictions, if any, which should be placed on transient testing.

RDT F9-4 (REF. 1)

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### 2.0 SUMMARY

The thermal deformation analysis was performed for the six test transients for which thermal analysis are reported in Reference 7. The critical clearance changes between rotating and static components are listed in Table 1.

The analysis shows a reduction of 3 mils during thermal transient E-207 at the bearing and journal, and a 7-mil clearance reduction at the rear labyrinth seal during transient E-203.

Table 2 summarizes the results of component strain evaluation. Based on the criteria of RDT Standard F9-4, Section 6, for strain limit, the total accumulated strain of 0.23% is within the 1%, and the total creep-fatigue damage fraction of 0.026 is less than 0.6 as allowed in the specification ( REF. 6)

### 3.0 DISCUSSION

The functional and structural integrity of the inducer/impeller assembly of the intermediate size inducer pump was evaluated based on Subsection NB, Section III Class 1 and Code Case 1592. In addition to the Code criteria used for evaluation of the final analysis, the following stress limits were used for evaluation of the initial steady-state analysis performed by Rocketdyne (Division 055) under IDWA N-1289 (Reference 5).

Steady-state stress limits for Type 304SS and CF8 stainless steel parts at  $1050^{\circ}F$  were:

Primary Membrane Stress  $(P_m) = 7,450 \text{ psi}$ Local Membrane Plus Bending  $(P_L + P_b) = 7,730 \text{ psi}$  Ref. 8

The design criteria for the A286 material used in the shaft extension tie-bolt at  $1050^{\circ}F$  are:

 $P_{m} = 15,000 \text{ psi}$  $P_{L} + P_{b} = 20,000 \text{ psi}$  Ref. 8

These steady-state stress limits were selected to have adequate margin below the Code criteria, to provide a high probability of success in meeting the Code criteria during subsequent transient analyses.

Before using the ESG thermal model for analysis of ISIP test transients, an "umbrella" set of transients was selected from those actual transients which had been run during sodium testing of the FFTF prototype pump and analyzed with the ESG thermal model. Reference 4 shows a comparison of the calculated temperatures output from the ESG model



(using actual test input data) to actual temperatures measured during the tests. This data was used to verify the validity of the model. The model was then used with the ISIP test input requirements (which do not differ from previous FFTF pump test requirements) to show that the predicted temperature variations around the critical sodium bearing support structure and other adjacent FFTF parts would not be more severe, or significantly different, than those which had been previously undergone during sodium tests. Structural integrity of the prototype pump parts and functionability of the sodium bearing during ISIP transient tests was based on these results. For the recently designed ISIP parts, results of the thermal analysis were used as input to the ESG stress model for structural evaluation. Calculated stresses for the thermal transient stresses are shown in Table 2.

### 3.1 TEST CRITERIA

The original transient test requirements of the ISIP specification (Reference 6) included nine thermal transients identical to those previously specified for the FFTF prototype pump. Three of the transient tests were subsequently deleted, leaving six transient tests to be performed on the ISIP, as presently described in Reference 9. The three transients which were deleted were judged not to be significant to the ISIP parts and would only retest the overall pump structure. Based on the test request, the total operating time is expected to be approximately 4000 hours. It is estimated that about 3000 hours will be logged as steady-state operation at  $950^{\circ}$ F, including a 2000-hour design point endurance run and a 300-hour off-design endurance run, and the remainder of the time will be at reduced temperatures ( $400^{\circ}$ F to  $850^{\circ}$ F). The total time during which the pump structure will be responding to thermal transients will be less than 6 hours.



NO

Table B-37 shows the six thermal transients from the present test request. The original maximum temperature, as listed in the design specification, was 1050<sup>0</sup>F. For testing, this temperature was later reduced to 950°F as being more representative of the maximum temperature for which present LMFBR's are being designed. The rate and range ( $\Delta t$ ) of the transients was not changed.

### 3.2 ANALYTICAL PROCEDURE

The analysis of deformation and stress of the inducer/impeller assembly was performed using the APSA (Axisymetrical, Planar Structural Analysis) finite element computer code. Finite element models were developed to structurally represent the area of concern. A separate finite element model consisting of time histories of temperature field for thermal transients was developed. The TAP (Thermal Analysis Program) computer code was used to calculate and provide the temperature field. The worst critical time slice in determining the maximum stress and maximum deformation at various sections of the pump was determined from TAP printout. APSA computer model utilized the TAP temperature field for thermal stress analysis and the deformation analysis.

The steady-state condition (operating condition) which considered the maximum combination of stresses was documented in Reference 5. The stress intensities of various sections were utilized in the calculation of strain fatigue evaluation.

### 3.3 TRANSIENT DATA

Temperature distributions in the pump inducer/impeller regions were determined as a function of time for the transients.

Transients, time-history thermal analysis was performed and documented in Reference 7. The calculated temperature results were stored on tapes that were used as input for the deformation and stress analysis. The points for which temperatures were calculated and stored are exhibited in Figure 3.

The capacitance-weighed average temperature of various locations in the inducer/impeller region were determined as a function of time and transient. The differences between these temperatures were plotted, as exhibited in Appendix B.

The capacitance-weighted average temperature plots were examined to determine the worst time slice for various interfaces. There were six transients considered (Reference 7), and two worst time slices for each transient were utilized in determining the deflection and stress. The clearance change at various interfaces utilized the transient time slice and were documented in Appendix B. Table 3 shows the worst stress intensities of the pump element for each transient.

### 3.4 STRUCTURAL CRITERIA

The structural criteria employed in evaluating the pump inducer/ impeller is described below.

All components were evaluated using elastic analysis methods as provided for in the pump specification (Reference 6, Paragraph 3.2.4). The analysis criteria are as presented in the RDT Standard F9-4(REF. 1)"Construction of Nuclear System Components at Elevated Temperature."

A summary of the method used in evaluating the strain fatigue limits is outlined below:



Structural Analysis Method Outline Accumulated Strain Analysis (Ref. 1) Bree Complete Relaxation Method. Deformation and strain limits for structural integrity are considered to have been satisfied and a detailed inelastic ratcheting analysis need not be performed if the following four conditions are satisfied: 1. The approximate inelastic strain averaged through the thickness,  $\varepsilon_{ave}$ , is less than the limit of T-1310 of RDT F 9-4, with:  $\varepsilon_{avg} = \varepsilon + \varepsilon_{r}$ , where:  $\epsilon_{c} = \text{cumulative creep strain based on the primary stress}$  $(P_{L} + P_{b}/K_{t})^{\circ}$  and the appropriate isochronous stressstrain curves,  $\varepsilon_r$  = cumulative ratchet strain based on Bree's complete relaxation analysis. The values of  $\varepsilon_{r}$  are given by:  $\varepsilon_r = \sum_{i N_i} (\Delta \varepsilon_r)_i$ , where: N<sub>i</sub> = number of type i cycles,  $(\Delta \epsilon_r)_i$  = ratchet strain per cycle for type i cycles from Bree's complete relaxation equations.

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$$(\Delta \varepsilon_{\mathbf{r}})_{\mathbf{i}} = \frac{\mathbf{S}_{\mathbf{m}}}{\mathbf{E}} \left\{ 1 - \mathbf{x}'' + \mathbf{y}'' \left[ 1 - 2 \left( \frac{1 - \mathbf{x}''}{\mathbf{y}''} \right)^{-1/2} \right] \right\}$$

in region S<sub>1</sub> of Fig. 4

$$(\Delta \varepsilon_{r})_{i} = \frac{S_{m}}{E} \left\{ 1 - x'' + 2y'' \left[ 1 - 2 \left( \frac{1 - x''}{y''} \right)^{1/2} \right] \right\},$$

in region R<sub>1</sub> of Fig. 4

$$(\Delta \varepsilon_r)_i = \frac{S_m}{E} [x''(y'' - 1)]$$

in regions S<sub>2</sub> and P of Fig. 4 and:

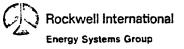
$$(\Delta \epsilon_{r})_{i} = \frac{S_{m}}{E} [x''(2y'' - 1) - 1]$$

in region R<sub>2</sub> of Fig. 4 In the above:

$$\mathbf{x''} = \left(\mathbf{P}_{\mathbf{L}} + \frac{\mathbf{P}_{\mathbf{b}}}{\mathbf{K}_{\mathbf{t}}}\right)_{\max} / \mathbf{S}_{\max}$$

and:

$$y'' = (Q_R)_{max}/S_m$$



--

Cree	ep-Fatigue Damage Analysis ( SIMPLIFIED METHOD )
	ume <sup>c</sup> eff <sup>= c</sup> eff range <sup>= c</sup> t ume <sup>c</sup> eff <sup>= c</sup> eff <u>E</u>
1)	Pick <sub>Geff</sub> and E for the relevant element in the APSA printout (namely, the element at the critical surface of the selected section), for <u>every</u> transient.
2)	Using the "Design $\epsilon_t$ vs No. of Allowable Cycles" plot, Figure T1430 (CODE CASE 1592), find N <sub>d</sub> for every transient.
3)	Determine the number of occurrences for each transient
4)	Total fatigue damage fraction = $\sum \frac{n}{N_d}$ .
5)	Creep Damage Analysis: Creep Damage Fraction - Simplified Analysis Method for the Cycle Selection
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Determine  $\left[ \left( P_{L} + P_{B} + Q_{max} \right) \right]$ If  $S_{y} \ge \left[ P_{L} + P_{B} + Q_{max} \right]$  then  $\underline{S_{K}} = \left[ P_{L} + P_{B} + Q_{max} \right]$ If  $S_{y} \le \left[ P_{L} + P_{B} + Q_{max} \right]$  then

 $S_{K} = 1esser of 1.25 \times S_{y}$ 

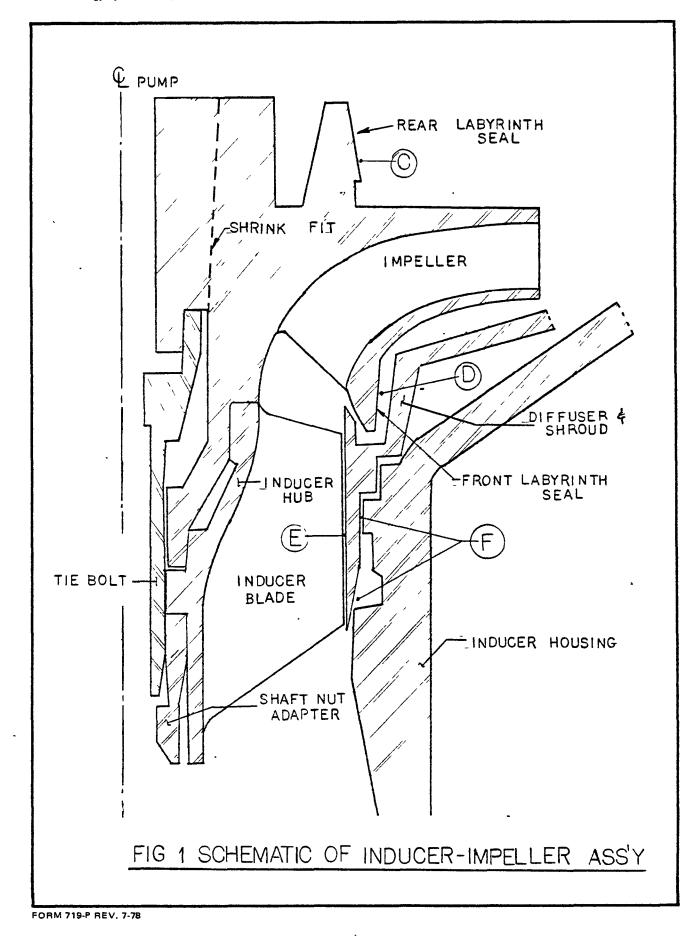
In stress rupture curve, find T<sub>d</sub> using  $\frac{S_k}{0.9}$ .

6) 
$$\sum \frac{n}{N_d} + \sum \frac{t}{T_d} \leq 0.6$$

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	TABLE 1	
CRITICAL	CLEARANCE (mils)	CHANGES

	Decim			Transi	ent		
Location*	Design Clearance	E-202 100 sec	E-203 100 sec	E-204 100 sec	E-207 275 sec	E-208 115 sec	E-210 50 sec
A	13	+2.4	-1.7	+3.1	+4.6	+3.7	+2.2
В	13	+1.9	-1.3	+2.6	+3.5	+2.8	+2.4
С	50	+6.7	-7.2	+9.2	+11.8	+10.6	+6.6
D	50	+0.9	+5.2	-0.7	-1.5	-0.9	+2.6
E	50	+2.0	+2.9	-3.3	-2.9	-3.7	-3.0
F	50	+8.7	-6.1	+11.6	+13.0	+13.1	+10.5

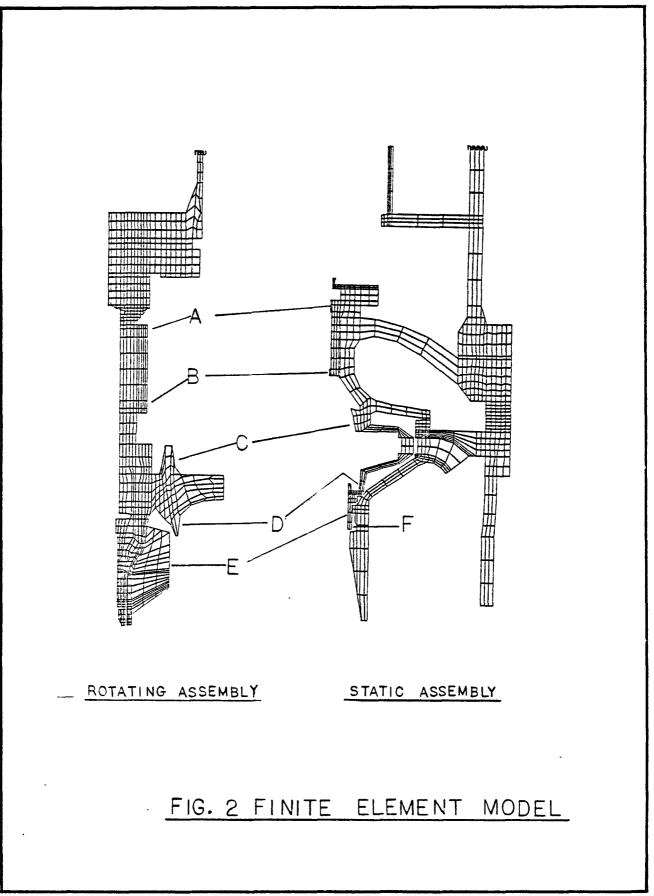
Note: The values listed under the transient column are <u>changes</u> in the original clearance at isothermal temperature conditions.

For example, at Location A, the original clearance (13 mils) is increased by 0.0024 in. during Event E-202 and decreased by 0.0017 in. during E-203.

\*See Figures 1 and 2.



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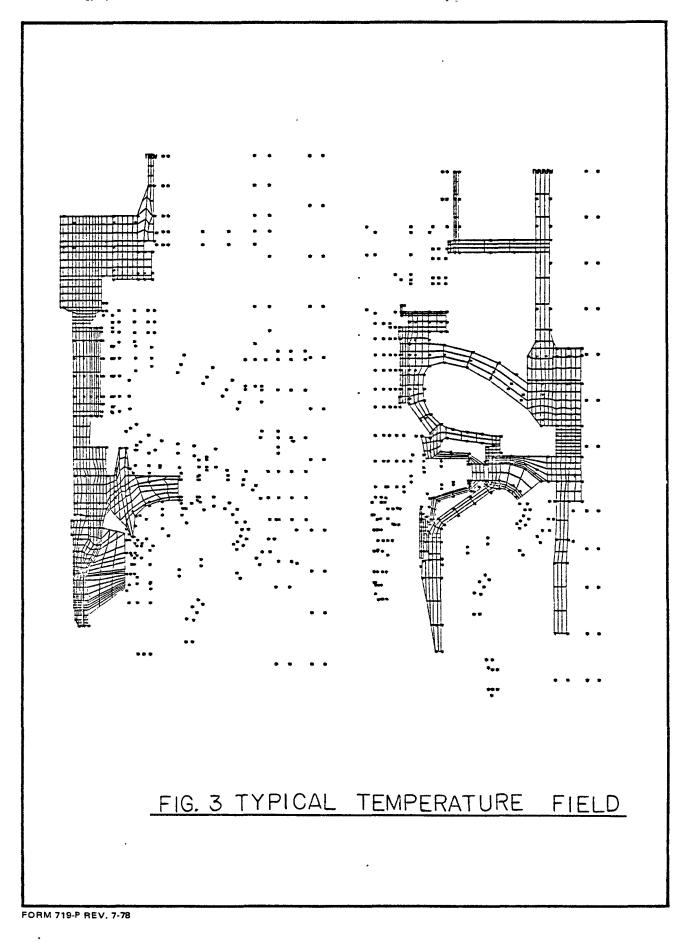


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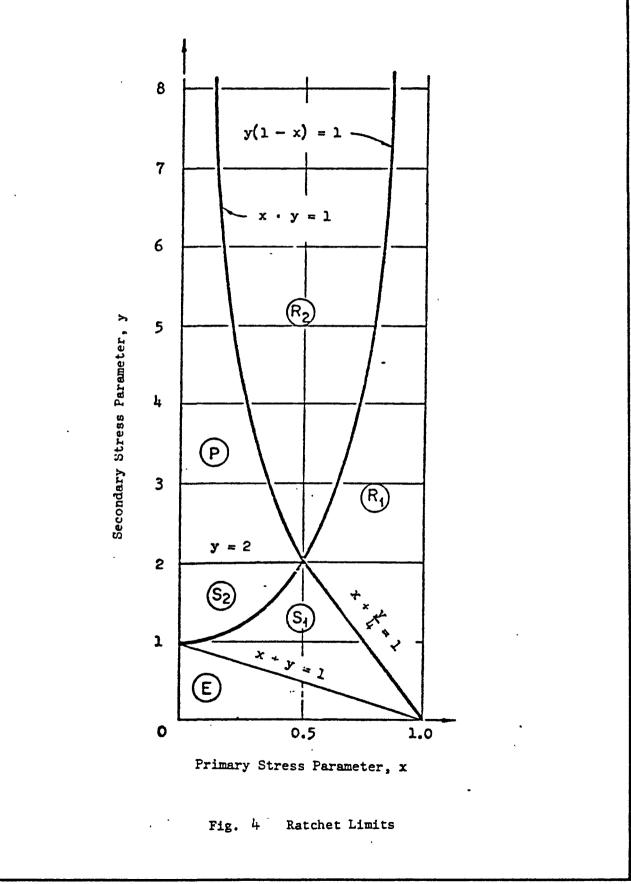




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									DATE:	CHECKED SY,	PREPARED BY.
COMPONENT		T E	EST -	TRANSIE	NT		<b> </b>	Deeven			
	E-202	E-203	E-204	E-207	E-208	E-210	STRAIN	Design		+	L
(ELEMENT)	0/0	0/0	0/0	0/0	0/0	0/0	SOURCE	Marqin			
	0.00073	0.00056	0,00380	0.00110	0,00450	0,00380	Q' Per Q' cy cl e	D.M= 1%-1			
INDUCER HUB	0.02	0.02	0.02	0.02	0,02	0.02	P <sub>m</sub>	.034			Ĩ
(531)		Accum	ULATED 971	RAIN	0,03	4 010	L	>10			Rock
INDUCER	0,00108	0.01042	0.01903	0.01100	0,02 00	0.01790	Q.			Energy Systems Group	Rockwell International
BLADE	0.04	0.04	0.04	0.04	0.04	0.04	Pm )			ns Gro	itema
(666)		Accum	ULATED 6	TRAIN	0,12	do		7.33		ŧ	itiona
IMPELLER	0.00977	0,00200	0.00990	0,00840	0.01230		Q				=
	0,04	0.04	0.04	0.04	0.04	0.64	Pm				
(648)		Accu	MULATED	STRAIN	0.00	12 %		9.86		<u> </u>	
SHAFT (412)	0.01020	0,00960	0,02100	0.04540	0,02800	0,01100	Q		NODEL	REPORT NO	N266
	0,1	0,1	0.1	0.1	0.1	0.1	Pm · ·		Ņ	<u>.</u>	N266SR000002
( 412 )		Accu	MULATED	STRAIN	0.11	5 0/0	•	3.44			1002
		TAB	LE 2	Compor	NENT ST	<u>RAIN</u> (4/1	lowable str	ain 1%)			

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COMPONENT		T {	EST	FRANSIE	NT					
(ELEMENT)	E-202	E-203	E-204	E-207	E-208	E-210				
	loobec	loo hec	loobac	275 bec	115 bec	50 bec		.		
INDUCER HUB (531)	15400	15800	20000	16000	20600	19000			Energy	<b>D</b> Bank
INDUCER BLADE (666)	13000	22200	27600	22200	28000	25600			Energy Systems Group	Rockwell International
IMPELLER (648)	2   200	14000	21000	19800	NN 000	10000				
SHAFT (412)	18800	18600	25000	33400	28160	18400	- I 	MODEL NO.	22	N266SR000002
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# APPENDIX A STRUCTURAL ANAYSIS

a. Strain Limit Evaluation

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b. Creep-Fatigue Damage Evaluation



### STRUCTURAL ANALYSIS

The Bree Complete Relaxation Method of RDT Standard (Reference 1) was used to determine the creep strain limit for pump components. The primary stress (Pb + P1) has utilized the stress intensity value from the stress report by Rocketdyne on the steady-state stress analysis (N266SR000001, Reference 5). The thermal transients stress (Q) were obtained from the time-history iteration of transients. Two worst-time slices were selected for each transient. The procedure was described in Section 3 of this report.

Table <u>A-1</u> and Table <u>A-2</u> summarized the stresses and strains, respectively, for different parts of inducer-impeller assembly for each transient.

The total creep-fatigue damage fraction was analyzed based on the method described in Section 3 of this report. The calculation showed that the creep-fatigue damage fraction of 0.026 which was smaller than 0.6.

		N266ER000-0 Page 393	001		
PREPARED BY, TK CHENG	Rockwell Internation	25	N266SR000002 25 REPORT NO.		
DATE	ISIP				
-	477265 Intensities	· · · · · · · · · · · · · · · · · · ·			
	Component	Stress	D.M.		
C .	inducer hub	$P_{m} = 2.93$ KG1	1.63		
e	Inducer Blade	рт=5.6 Кы	0.38		
e	Impeller	Pm = 5.9 K61	0.31		
e	shaft.	Pm = 7,48 K6i	0.03		
*	htrens intensity are from 1) See page 8 2) Stress Intensities 3.) Actual T= 950°F 4) So = 14,300 psi In this Analys	base on 1050°F (used 7,730 p	•		

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PREPARED BY:	Rockwell International Energy Systems Group	N266SR000002
DATE:	IGIP	MODEL NO.
	Inducer Blade	- T.   Boo-A. 4 Code Cune 1592)
	$P_{+}+P_{-}/0.9 = 5.6 \text{ KSI}$	
	$\epsilon = 0.04 $ %	
Q	Impeller	
	P6+P_ /0.9 = 5.9 K51	
	$E_{c} = 0.04 $ %	
Ğ	shaft	
	Pb+P1/0.9 = 7-5 KG1	
	$e_c = 0.1 \circ 0.1$	
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COMPONENT		Τ	EST 1	FRANSIE	NT		
	E-202	E-203	E-204	E-207	E-208	E-210	STRESS
(ELEMENT)	100 her	100 bec	100 hec	275 bec	115 bec	50bec	SOURCE (Kmi)
	2.93	2.93	2, 93 Kol	2.93	2.93	2.93	Pm
INDUCER HUB	15.4	15.8	20.0	16.0	20.6	19.0	Q
(531)	18.33	18.73	22.93	18.93	23.53	21.93	P <sub>m</sub> +Q
INDUCER	5,6	5.6	5,6	5.6	5.6	5.6	Pm
BLADE	13.0	22.2	27.6	22.2	18.0	25.6	Q
(666)	18.6	27.8	37.2	27.8	33.6	31.2	P <sub>m</sub> +Q
IMPELLER	5.9	5.9	5,9	5.9	5.9	5.9	Pm
	21.2	14.0	21.0	19.8	22.0	20.0	Q
(648)	27.1	19.9	26.9	25.7	27.9	25.9	P <sub>m</sub> +Q
SHAFT	7.5	7,5	7.5	7.5	1.5	7.5.	Pm
	18.8	18.6	25.0	33.4	28.2	18.4	Q <sup>.</sup>
(412)	26,3	26.	32.5	40.9	35.7	25.9	P <sub>m</sub> +Q

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MODEL NO.

TABLE A-1

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I.

COMPONENT		TE	EST 7	<b>FRANSIE</b>	NT		
	E-202	E-203	E-204	E-207	E-208	E-210	STRAIN
(ELEMENT)	•/0	0/0	0/0	0/0	0/0	0/0	SOURCE
	0.00073	0.00092	0.00380	0,00   0	0.00450	0.00380	Q (per)
INDUCER HUB	0.02000	0.02000	0,02000	0.02000	0.02000	0.02000	Pm
(531)	0.02073	0.02092	0.02380	0.02110	0.02450	0.02380	Total
INDUCER	0.00108	0.01042	0.0 9.03	0.01100	0.02/00	0.01790	Q (per Q (cycle)
BLADE	0.04000	0.04000	0.04000	0.04000	0.04000	0.04000	Pm
(666)	0.04   08	0,05042	0.05903	0.05100	0.06100	0.05790	Total
	0.00 977	0,00200	0.00990	0,00840	0.01230	0.00980	Q (per)
	0,04000	0,04000	0.04000	0,04000	0,04000	0.04000	Pon
(648)	0.04917	0.04200	0.04990	0.04840	0.05230	0.04980	Total
SHAFT	0.01020	0.00960	0.02100	0.04540	0.02800	0,0100	Q (per)
(412)	0.10000	0.10000	0.10000	0,0000	0.10060	0.10000	Pm
	0.11020	0.10960	0.12100	0.14540	0.12800	0.11100	Total

TABLE A-2

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MODEL NO.

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		N266ER000-001
CHECKED BY	Rockwell International Energy Systems Group	Page 397 N266SR000002
DATE	IGIP	MODEL NO.
Ele ( Te	Q = 15.4 Kb1 Pm = 2.9 Kb1 mperature for $E - 202$ 750° Gy = 17.3 Kbi @ 750° Gy = 18.2 Kbi @ 600° Sm = 15.1 Kbi @	$F \rightarrow 600^{\circ} F$ $F \rightarrow 600^{\circ} F$ $F \rightarrow 600^{\circ} F$ $F \rightarrow 5_{mean} = 17.8.65i$ $675^{\circ} F (mean famp, Code Case 1592)$ $Region 6i$ $F = \frac{12}{3}i$
ι.	Bree Relaxation Method X'' = 2.9 / 15.1 = 0.19 Y'' = 15.4 / 15.1 = 1.02 $\Delta \epsilon_r = \frac{Gm}{E} \{1 - x'' + Y'' [1 - 2(\frac{1 - x''}{Y'})]$	$\left[\frac{1}{n}\right]^{\frac{1}{2}}$

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CHECKED BY,	- Rockwell International Energy Systems Group	- N266SR000002 - 30
DATE:	ISIP	MODEL NO.
		·
	1 har 1 the marks	
	<u>Strain Limito Evalua</u>	1101
Te	at Transient E-202 @	100 bec.
		Inducer Blade (Fig. B-10)
	Q = 13.0  Kbl	
	$P_{m} = 5.6 \text{ Km}$	
T	emperature for E-202 7	$L_0^{\bullet} = \rightarrow (000^{\circ} = \cdot)$
1-		
	Sy = 17.3 KGi @7	$50^{\circ}F - 5_{imean} = 17.8 \text{ Km}$
	•	
		€ 675° F (mean tamp
		A code Cape 1592)
	E = 25.0 × 10 p	51
	1. Bree Relaxation Mathod	
	X'' = 5.6 / 15.1 = 0.37	)
	Y" = 13.0/15.1 = 0.86	Region 5,
	ratchet strain per cyc	le (Der)
	$(\Delta \ \text{er}) = \frac{\text{Sm}}{\text{E}} \left\{ 1 - x'' + y'' \right\}$	$\left[1-2\left(\frac{1-x''}{y''}\right)^{1/2}\right]$
	$=\frac{1500}{25\times10^{6}}\left\{1-0.37\right\}$	$+0.86\left[1-2\left(\frac{1-0.37}{0.86}\right)^{\frac{1}{2}}\right]$
	= 0.00/08 0/0	

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prepared by, checked by, LJ.E.E.	Rockwell International Energy Systems Group	N266SR000002 - 31 N266ER000-001 -Page 399
		·
	Strain Limits Evaluation	
	of Transient E-202 @ 100	
E	ement 648 @ 1mpe	ller (f14. B-10)
	Q = 2 .2  Kb	
	$P_{m} = 5.9 \text{ Kal}$	
T	emperature for E-202 750°F	-> 600°F.
	Sy = 17.3 K6i @750°F Sy = 18.2 K6i @600°F	]- 6. Imeon = 17.8 1/6 1/6 1
	$B_{m} = 15.1 \text{ Koi} = 6$ (Table I-14.3A c	1
	E = 25.0 × 106 psi	
ţ.	Bree Relaxation Method (RD	T F 9-5T)
r	X'' = 5.9/15.1 = 0.39 Y' = 21.2/15.1 = 1.4	Region 51
	ratchet strain per cycle $(\Delta Er)$	<b>1</b>
	$(\Delta \epsilon_r) = \frac{G_{m}}{E} \{ 1 - x'' + y'' [ 1 - 2 ( - 2 - 2) ]$	$\frac{1-x''}{Y''}$
	$= \frac{15100}{25\times106} \left\{ 1 - 0.39 + 1.4 \left[ 1 - 0.39 + 1.4 \right] \right\}$	$2\left(\frac{1-0.39}{1.4}\right)^{1/2}$
	= 0.00977 010	

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PREPARED BY,	Energy Systems Group	N266SR000002 32 N266ER000-001 Page 400
	<u>Strain Limits Evaluation</u>	-
_	<u>ot Transient</u> E-202 @ 100 ement 412 @ sha	
	Q = 18.8  KB1 $P_{m} = 7.5 \text{ KB1}$	
Te	mperature for E-202 750°F Sy = 17.3 KGi @750°F Sy = 18.2 KGi @600°F	
	by = 18.2 Kbi @ 600°F Bm = 15.1 Kbi @ (Table I-14.3A	675° F (mean temp.)
	E = 25.0 × 10 <sup>6</sup> psi 1. Bree Relaxation Method	
	X'' = 1.5 / 15.1 = 0.5 Y'' = 18.8 / 15.1 = 1.25	Region 51
	ratchet strain per cycle ( $\Delta$ ( $\Delta$ Gr) = $\frac{5m}{E} \{ 1 - x'' + y'' [ 1 - y'' + y'' ]$	$2\left(\frac{1-Y''}{Y''}\right)^{1/2}$
	$= \frac{1500}{25 \times 106} \left\{ 1 - 0.5 + 1 \right\}$ $= 0.0102 0/0$	$25\left\{1-2\left(\frac{1-0.5}{1.75}\right)^{1/2}\right\}$
	1	•

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PREPARED BY	Energy Systems Group	N266SR000002 33
	ISIP	N266ER000-001 Page 401
<u>Ele</u> 6 F	<u>Strain Limits Evaluation</u> <u>E Transient</u> E-203 @ 1 <u>ment</u> 531 @ Ind R = 15.8 K61 hn = 2.9 K61 compensature for E-203 5 $G_T = 19.4$ K61 @ 500°	lucer Hub 100°F → 650°F
	Gy = 19.4 K6i @ 500° Gy = 18.0 K6i @ 650 Gm = 15.1 K6i @ 575	5°F (Nilean Temp)
	$(Table I - 14.3 A Come = 25.4 \times 10^6 ps1$	ode Cobe 1592)
	1. Bree Relaxation Method X'' = 2.9/15.1 = 0.19 Y'' = 15.8/15.1 = 1.05	Ragion 61
	ratchet ötrain per cycle (s	6r)
	$(\Delta \epsilon_r) = \frac{5m}{\epsilon} \left\{ 1 - x'' + y'' \left[ 1 - 2 \right] \right\}$	, , ,
	$= \frac{15100}{25.4\times10^{6}} \left\{ 1 - 0.19 + 1.10 \right\}$	$.05\left[1-2\left(\frac{1-0.19}{1.05}\right)^{1/2}\right]$
	= 0.00092 %	

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PREPARED BY,	- · · · · · · · · · · · · · · · · · · ·	Page 402 Rockwell interna Energy Systems Gro		1	N266SR000002 34
CHECKED BY, WI.T.C.	IGIP				REPORT NO.
DATE:	1.016				MODEL NO.
	Strai	n Limits E	valuatio	<u>n</u>	
Te5-	t Transient	E-203	C	100	hec
tele	ment	666	@ _	Induce	r Blade
` ſ					
	a = 12.2				
f	m = 5.6	K61			
- 16	mperature	•			
	64 :	= 19.4 K6	i C t	500°F -	- m = 18.7  K
	64 :	= 18.0 KA	n ea	050°F ·	- Innean
					(Mlean Temp)
		Table I-1			1
	£ =	25.4 ×10	<b>p</b> 5	(	
(	Bree Re	axation Met	hod		
	•	•••••			
<i>,</i>	$\sim = \sim$	5,6/15.1 =	0.67	$\left\{ \right\}$	S1 Region
		22.2/15.1=	=  ,4]	1	
	ratchet a	strain per	cycle	(DE	r)
-		•			
	$(\Delta G_r) =$	$\frac{6m}{E}\left\{1-X\right\}$	"+Y"[I·	-2 (-	
	=	15100	- 0,37	+1.47[1	$-2\left(\frac{1-0.37}{1.47}\right)^{1/2}$
	=	0.01042	þ		
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	N266ER000-001	
PREPARED BY	Page 403 Rockwell International Energy Systems Group	N266SR000002 35
DATE:	I61P	MODEL NO.
Teg	<u>Strain Limits Evaluation</u> <u>t Transient</u> E-203 @ 10	0 her.
	ment 648 C Imip	
	R = 14.0  Km	
	R = 14.0  KB1 Pm = 5.9  KB1	
Ĩ	m = 5.9 Not	
Te	emperature for E-203 500	°F → 650°F
	6y = 19.4 K61 @ 500° F	
	67 = 19.4 KGI @ 500°F 67 = 18.0 KGI @ 650°F	$= \frac{1}{1} $
	6m = 15.1 KGi @ 575°	F (Mlean Temp)
	(Table I-14:3A Cod.	e Cobe 1592)
	E = 25.4 ×106 p61	,
ł	1. Bree Relaxation Method	
~	X'' = 5.9/15.1 = 0.39 Y'' = 14.0/15.1 = 0.93	S1 Region
	ratchet strikin per cycle (	26r)
	$(\Delta G_{r}) = \frac{G_{m}}{E} \{1 - x'' + Y'' [1 - 2]$	
	$= \frac{15100}{25.4\times10^6} \left\{ 1 - 0.39 + 0 \right\}$	$0.93 \left[ 1 - 2 \left( \frac{1 - 0.39}{0.93} \right)^{1/2} \right]$
	= 10,002 .	
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	N266ER000-001	
PREPARED BY	Page 404 Rockwell International Energy Systems Group	N266SR000002 <del>df</del>
DATE	IGIP	MODEL NO.
	Strain Limits Evaluation	
	<u>t Transient</u> E.203 @ 100	
tele	ment 412 C shaf	t
	R = 18.6  Km	
f	$P_{m} = 1.5 \text{ KeV}$	
Te	emperature for E-203 500	°F → 650°F
	67 = 19.4 KGI @ 500°F	
	67 = 19.4 KGI @ 500°F 67 = 18.0 KGI @ 650°F	- 100 = 10.1
	6m = 15.1 KSi @ 575°	F (Mean Temp)
	(Table I-14.3A Code	e Cabe 1592)
	E = 25.4 × 106 p51	
	1. Bree Relaxation Method	
-	X"= 1.5/15.1 = 0.5	31 Region
	√" = 1B.6/15.1 = 1.2B	
	ratchet strain per cycle (DE	r)
	$(\Delta tr) = \frac{bm}{E} \left\{ 1 - \chi' + \gamma'' \right[ 1 - 2$	~ ~
	$= \frac{15 00}{25.4\times106} \left\{ \left  -0.5 + 1.23 \right  \right\}$	$-2\left(\frac{1-0.5}{1.23}\right)^{1/2}$
	= 0.009690	

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		N266ER000-001	
PREPARED BY		Page 405 Rockwell International	N266SR000002 37 -
CHECKED BY: /	1	Energy Systems Group	REPORT NO.
DATE:		IGIP	MODEL NO.
	<u>Elem</u> Q = Pm	= $20.0 \text{ K41}$ = $2.9 \text{ K41}$ parature for $= 200$ Br	ucer Hub
		by = 16.5 K6i @ 85°F - 67 = 17.9 K61 @ 65°F - 6m = 15.0 K61 @ 75° (Table I-14.3A Code C E = 24.5 × 106 P61	F (mean temp.)
	(,	Bree Relaxation Method X'' = 2.9/15.0 = 0.19 Y'' = 20.0/15.0 = 1.375	52 Region
		ratchet . strain per cycle (2	ser)
		$(\Delta \epsilon_r) = \frac{\beta_m}{\epsilon} \left[ x''(r''-1) \right]$	
		$= \frac{15000}{24.5 \times 10^{6}} \left[ 0.19 (1.3) \right]$	3-1)
		= 0.0038 %	

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	N266ER000-001	
PREPARED BY	Page 406 Rockwell International Energy Systems Group	N266SR000002
	IGIP	REPORT NO.
	Strain Limits Evaluation	
Toot	Transient E-204 @ 10	o sec.
	ient 666 @ Induc	
() :	= 27.6 Kol	·· )
	= 5.6 Kol	
Too	nparature for E-204 B50	
( <i>124</i> )	$by = 16.5 \text{ Koi } @ 850^{\circ} \text{F} -$	, .
	6y = 17.9 Ko1 @ 65°F-	
	Sm = 15.0 K61 @75°F	
	(Table I-14.3A Coda Ca	
	$E = 24.5 \times 10^6 \text{ ps}$	
(.	Brze Relaxation Method	
	X'' = 5.6/15.0 = 0.37	he Region
	1 = 27.6/16.0 = 1.84	N
	ratchet bitrain per cycle	
	$(\Delta \epsilon_r) = \frac{G_{em}}{\epsilon} [\chi''(\gamma''-1)]$	
	$= \frac{15000}{24.5 \times 106} \left[ 0.37 (1.84-1) \right]$	
	= 0.01903 00	

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	N266ER000-001	
PREPARED BY	Page 407 Rockwell International Energy Systems Group	N266SR000002 - 39
CHECKED BY, H.F.F.	IGIP	REPORT NO.
Q Pm Ten	$\frac{5 \text{ train Limits Evaluation}}{\text{Transfert}} = 2.204 @ 100 \\ \text{ent} & 048 @ 1000 \\ \text{ent} & 048 & 048 \\ ent$	eller o F - 650 F - Sy = 17.2 K mean F (mean temp.)
	Bree Relaxation Method X'' = 5.9/15.0 = 0.39 Y'' = 21.0/15.0 = 1.40	51 Region
	ratchet 6train per cycle ( $\Delta$ ( $\Delta$ Gr) = $\frac{5m}{E} \{ 1 - x'' + \gamma'' [ 1 - 2 ]$ = $\frac{15000}{24.5 \times 10^6} \{ 1 - 0.39 + 1.4 [$	$\left(\frac{ -\mathbf{x}'' }{ \mathbf{y}'' }\right)^{1/2}$
	= 0.0099 %	

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·····	N266ER000-001	
PREPARED BY	Page 408 Rockwell International Energy Systems Group	N266SR000002
CHECKED BY, 1.1. D. E.	IGIP	MODEL NO.
	Strain Limits Evaluation	
	Transford to 1	
Elem	<u>Transient</u> E-204 @ 10 ent 412 @ sha	
	= 25,0 K61	
	= 7.5  KGI	
		• /. •
1 <i>2m</i>	parature for E-204 B50	0 F → 650 F
	6y = 16.5 K6i @ 85°F - 6y = 17.9 K61 @ 65°F -	- Gy = 17.2 KB
		njizon
	Sm = 15.0 K51 @750°1 (Table I-14.3A Coda C	
	$E = 24.5 \times 10^6 \text{ ps}$	
(.	Bree Relaxation Method	
	×"= 1.5/15.0 = 0.15	S, Region
	Y'' = 25.0/15.0 = 1.67	N
	ratchet strain per cycle (	
	$(\Delta \epsilon_r) = \frac{s_{m}}{\epsilon} \left\{ 1 - \chi'' + \gamma'' \right\} - 2$	$\left(\frac{1-\chi^{n}}{\chi^{n}}\right)^{n}$
	$= \frac{15000}{24.5x06} \left\{ 1-0.5+1.67 \right\}$	$\left[1-2\left(\frac{1-0.5}{1.67}\right)^{\frac{1}{2}}\right]$
	= 0.0210 ,00	

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CHECKED BY. L.L. F.		N266ER000-001		
	Page 409 Rockwell International Energy Systems Group	N266SR000002 41		
DATE:	IGIP	MODEL NO.		
<u>Ten</u> <u>Elem</u> Q Pm Ten	<u>Strain Limits Evaluation</u> <u>Transient</u> E-207 @ <u>ent</u> 531 @ 2 = 16.0 K61 = 2.9 K61 perature for E-207 950 Sy = 15.9 K6i @ 950 Sy = 15.0 K6i @ 600 Sm = 15.0 K6i @ 600	$\frac{\delta n}{275}  Sec.$ $Inducer Hub$ $\delta^{\circ}F \rightarrow 620^{\circ}F$ $\delta^{\circ}F = -\frac{5}{1}  S_{Imean} = 11.0 \text{ K/s}^{\circ}$		

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Prevents pr. Page 410 Product International Product International Product International Product International Product International IGENT IN IGENT		N266FR000-001	
$\frac{6 \text{trains Limits Evaluation}}{\text{Teast Transient}} = 2.07  (2.275 \text{ Gec.})$ $\frac{\text{Element}}{\text{Element}} = 6.66  (2.175 \text{ Gec.})$ $\frac{\text{Element}}{\text{Rm}} = 5.6 \text{ K61}$ $\text{Temperature for $E-207$} = 950^{\circ}\text{F} \rightarrow 6.20^{\circ}\text{F}}$ $\frac{6}{97} = 15.9 \text{ K6i}  (2.95^{\circ}\text{F}) \rightarrow 4.20^{\circ}\text{F}}$ $\frac{6}{97} = 15.9 \text{ K6i}  (2.95^{\circ}\text{F}) \rightarrow 4.20^{\circ}\text{F}}$ $\frac{6}{97} = 15.0 \text{ K6i}  (2.95^{\circ}\text{F}) \rightarrow 4.20^{\circ}\text{F}}$ $\frac{15.0 \text{ K6i}}{1600 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}{15.0 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}$ $\frac{15.0 \text{ K6i}}{1600 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}{15.0 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}$ $\frac{15.0 \text{ K6i}}{1600 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}{15.0 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}{15.0 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}$ $\frac{15.0 \text{ K6i}}{15.0 \text{ F}} \rightarrow 4.20^{\circ}\text{F}}{15.0 \text{ F}} \rightarrow 4.20^{\circ}\text{F}} \rightarrow 4.20^{\circ}$		Rockwell International	42
$\frac{\text{Test Transient}}{\text{Element}} = E - 207  (e) \ 275 \ \text{fec.}$ $\frac{\text{Element}}{\text{Q}} = 0.42 \ \text{Kel}$ $P_{m} = 5.0 \ \text{Kel}$ $Te.mperature \ \text{for} \ E - 207 \qquad 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.4 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.4 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.4 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.0 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.0 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.0 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.0 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F} \rightarrow 620^{\circ} \text{F} \rightarrow 620^{\circ} \text{F}$ $\frac{6}{7} = 15.0 \ \text{Kel}  (e) \ 950^{\circ} \text{F} \rightarrow 620^{\circ} \text{F} \rightarrow 620^{\circ$	DATE	ISIP	MODEL NO.
$\begin{array}{l} \beta_{\text{m}} = 15.0 \ \text{Koi}  @ \ 785^{\circ} F \ (\text{Mean tamp} \\ (\text{Table I-14.3A code Case 1592}) \\ E = \ 24.1 \times 10^{6} \ \text{psi} \\ \end{array}$ $\begin{array}{l} E = \ 24.1 \times 10^{6} \ \text{psi} \\ \hline E = \ 24.1 \times 10^{6} \ \text{psi} \\ \end{array}$ $\begin{array}{l} N \text{Brze Relaxation Method} \\ \times^{11} = \ 5.6 \ / 15.0 = \ 0.37 \\ \gamma^{''} = \ 27.2 \ / 15.0 = \ 1.48 \end{array} \right\}  G_{1} \ \text{Region} \\ \gamma^{''} = \ 27.2 \ / 15.0 = \ 1.48 \end{array} \right\}  G_{1} \ \text{Region} \\ \begin{array}{l} \text{ratchet strain per cycle} \ (\Delta E_{r}) \\ (\Delta E_{r}) = \ \frac{5m}{E} \left\{ 1-X'' + \gamma'' \left[ 1-2 \left( \frac{1-X''}{Y''} \right)^{k} \right] \right\} \\ = \ \frac{15000}{24,1\times10^{6}} \left\{ 1-0.37+1.48 \left[ 1-2 \left( \frac{1-0.57}{1.48} \right)^{k} \right] \end{array}$	Ele (	$\frac{+ \text{ Transient}}{\text{ment}} = 27.2 \text{ (Cm)} = 27.2 \text{ (Gm)}$ $\frac{1}{2} = 27.2 \text{ (Gm)} = 5.6 \text{ (Gm)}$ $\frac{1}{2} = 5.6 \text{ (Gm)} = 5.6 \text{ (Gm)}$ $\frac{1}{2} = 5.6 \text{ (Gm)} = 5.6 \text{ (Gm)} = 5.6 \text{ (Gm)}$	rer Blade $\rightarrow 620^{\circ} F$
1. Bree Relaxation Method $X^{11} = 5.6 / 15.0 = 0.37$ $Y'' = n7. n / 15.0 = 1.48$ $G_{1} \text{ Region}$ $ratchet strain per cycle (\Delta E_{r})$ $(\Delta E_{r}) = \frac{5m}{E} \left\{ 1 - X'' + Y'' \left[ 1 - 2 \left( \frac{1 - X''}{Y''} \right)^{k} \right] \right\}$ $= \frac{15000}{244.1 \times 10^{6}} \left\{ 1 - 0.37 + 1.48 \left[ 1 - 2 \left( \frac{1 - 0.37}{1.48} \right)^{k} \right]$		(Table I-14.3A	1
$X^{11} = 5.6 / 15.0 = 0.37$ $Y'' = 22.2 / 15.0 = 1.48$ $G_{1} \text{ Region}$ $Y'' = 22.2 / 15.0 = 1.48$ $G_{1} \text{ Region}$ $Y'' = 2.2 / 15.0 = 1.48$ $G_{2} \text{ Cycle} \left(\Delta G_{1}\right)$ $(\Delta G_{1}) = \frac{5m}{E} \left\{1 - X'' + Y'' \left[1 - 2\left(\frac{1 - X''}{Y''}\right)^{k}\right]\right\}$ $= \frac{15000}{24,  X 06} \left\{1 - 0.37 + 1.48\left[i - 2\left(\frac{1 - 0.37}{1.48}\right)^{k}\right]$	۱	•	
$(\Delta \epsilon_{r}) = \frac{5m}{E} \left\{ 1 - \chi'' + \gamma'' \left[ 1 - 2\left(\frac{1 - \chi''}{\gamma''}\right)^{k_{2}} \right] \right\}$ $= \frac{15000}{14.1 \times 10^{6}} \left\{ 1 - 0.37 + 1.48 \left[ 1 - 2\left(\frac{1 - 0.37}{1.48}\right)^{k_{2}} \right]$	, ,	$X^{11} = 5.6 / 15.0 = 0.37$	} G, Region
·			N
= 0.011 0 0			$1.43 \left[ 1 - 2 \left( \frac{1 - 0.37}{1.48} \right)^{1/2} \right]$

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N266ER000-001		
CHECKED BY	Page 411 Rockwell International Energy Systems Group	N266SR000002 43
DATE,	ISIP	MODEL NO.
DATE,		MODEL NO.
	Strain Limits Evaluation	
Ter	ot Transient E-207 @ 275	bec.
Ele	ment 648 @ Imp	eller
(	Q = 19.8  Kbl	
ł	m = 5.9 KG1	
Te	mperature for E-207 950°F	-> 620° F.
	Sy = 15.0 KGi @ 950 F	, ,
	Gy = 15.9 K6i @ 950°F Gy = 18.0 K6i @ 620°F	- 54 mean = 17.0KG
	6m = 15.0 Koi @ 7	
	(Table I-14.3A	,
	E = 24.1 × 106 ps1	
(.	Bree Relaxation Method	
	X"= 5.9/15.0 = 0.39 7	
	X'' = 5.9/15.0 = 0.39 Y'' = 19.8/15.0 = 1.32	5, Region
	. Ratchet "Strain per cycle (D	Er)
	$(\Delta \epsilon_{\rm Y}) = \frac{5m}{E} \left\{ 1 - x'' + T'' \right\}$	$(\frac{1-x''}{Y''})^{2}$
	$= \frac{15000}{24.1 \times 10^{6}} \left\{ 1 - 0.39 + 1.3 \right\}$	$2\left[1-2\left(\frac{1-0.3q}{1.32}\right)^{1/2}\right]$
	= 0.0084 010	

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PREPARED BY	Page 412 Rockwell International Energy Systems Group	N266SR000002
DATE:	ISIP	MODEL NO.
	Strain Limits Evaluation	
Ter	ot Transient E-207 @ 275	bec.
Ele	ement 412 @ Shaf	t
(	a = 33.4 Kb1	
ł	Pm = 7.5  KG	
Te	mperature for E-207 950°F	
	Gy = 15.9 K6i @ 95° F Gy = 18.0 K6i @ 620° F	1-6
	Sm = 15.0 Koi @ 7	1
	(Table I - 14.3A) E = 24.1 × 10 <sup>6</sup> P51	ore lare (5%2)
	1. Bree Relaxation Method	
,	x'' = 1.5 / 15.0 = 0.5	0
	Y"= 33.4/15.0 = 2.23	Rr Region
	ratchet strain per cycle (	Der)
_	$(\Delta \epsilon_r) = \frac{6m}{E} [X''(2Y''-1) - 1]$	]
•	= 15000 [0.5 (2x)	2.23-1)-1]
	= 0.0454 %	

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N266ER000-001		
PREPARED BY:	Page 413 Rockwell International Energy Systems Group	N266SR000002
CHECKED BY: 41, T. L.		REPORT NO.
DATE		MODEL NO.
<u>Teot</u> <u>Elern</u> Q = Pon Ten	$b_{Y} = 15.9 \text{ K6i} \oplus 950^{\circ} \text{F} -$ $b_{Y} = 17.5 \text{ K6i} \oplus 725^{\circ} \text{F} -$ $G_{m} = 14.9 \text{ K6i} \oplus 838^{\circ} \text{I}$ (Table I-14.5A Code C $E = 23.7 \times 10^{\circ} \text{ Poi}$ Bree Relaxation Method x'' = 2.9/14.9 = 0.19 Y'' = 20.6/14.9 = 1.38 Vatchet Strain per cycle (	5 Sec. Aucer Hub $p^{\circ}F \rightarrow 725^{\circ}F$ f = 24 = 16.7  Kel mean F = (mean + temp.)
		ser)
	$(\Delta \epsilon_r) = \frac{S_{om}}{\epsilon} \left[ x''(y''_{-1}) \right]$	]
	$= \frac{14900}{23.7\times10^{6}} \left[ 0.19 (1.3) \right]$	8-1)]
	= 0.0045 0/0	

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PREPARED BY:	N266ER000-001 Page 414 Rockwell International Energy Systems Group	N266SR000002 46 REFORT NO.
DATE:	ISIP	MODEL NO.
	Strain Limits Evaluation	
Te	at Transient E. 20B @	
Ela	ement 666 @ In	ducer Blade
(	Q = 28.0 KAI	
	Pm = 5.6  KGI	
-	Emparature for E-20B 9	50°F → 725°F
	6y= 15.9 K5ì @ 950°F	6
	67= 15.9 KGI @ 950°F 67= 17.5 KGI @ 725°F	$-\frac{1}{m^{2}an} = 16.71$
	Sm = 14.9 Kb1 @.838	F (mean temp.)
	(Table I-14.3A Coda	
•	E = 23.7 × 106 pol	
	1. Bree Relaxation Method	
	X'' = 5.6/14.9 = 0.38 Y'' = 28.0/14.9 = 1.88	52 Ragion
		_
	ratchet Strain per cycle	(& Gr)
	$(\Delta \epsilon_{r}) = \frac{\beta_{m}}{E} \left[ x''(\gamma''-\iota) \right]$	-
	$= \frac{14900}{23.7\times106} \left[ 0.38 \left( 1.69 \right) \right]$	6-1)]
	= 0.021 0/0	

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N266ER000-001		
PREPARED BY	Page 415 Rockwell International Energy Systems Group	N266SR000002
CHECKED BY, 1 T. L.	IGIP	MODEL NO.
<u>Elern</u> Q = Pom Ten	$\frac{5 \text{ train Limits Evaluation}}{\text{Transient}} = 2208 @ 111}$ $ent = 648 @ Imp$ $= 22.0 \text{ Kol}$ $= 5.9 \text{ Kol}$ $perature for E-208 .95$ $af = 15.9 \text{ Kol} @ 950°F - 67 = 17.5 \text{ Kol} @ 925°F - 67 = 17.5 \text{ Kol} @ 925°F - 67 = 17.5 \text{ Kol} @ 925°F - 67 = 14.9 \text{ Kol} @ 2835° (Table I-14.3A Code C)$ $E = 23.7 \times 10^{6} \text{ Pol}$ $Bree \text{ Relaxation Method}$ $x'' = 5.9/14.9 = 0.4 \text{ T''} = 22.0/14.9 = 1.48 \text{ T''}$ $ratchet6train per cycle$ $(\Delta Er) = \frac{3m}{E} \left\{ 1-x''+T''[1-2] = \frac{14900}{23.7 \times 10^{6}} \left\{ 1-0.4+1.48 = 0.0123 \cdot 6 \right\}$	$2E   Er $ $2E   Er $ $= 725^{\circ} F$ $= 725^{\circ} F$ $= 16.7 \text{ Km}$ $F (mean temp.)$ $= abe (1592)$ $Region 5_{1}$ $(\Delta \in r)$ $(\frac{1-x''}{Y''})^{1/2}]$

	N266ER000-001	
CHECKED BY, W.F.F.	Page 416 Rockwell International Energy Systems Group	N266SR000002 <u>df</u> 48 <b>report no</b> .
DATE:	IGIP	MODEL NO.
<u>Elern</u> Q : Pon Ten	$\frac{5 \text{ train Limits Evaluation}}{\text{Transfert}} = 2.08 @ 111ent 412 @ 3ha= 28.2 Ko1= 7.5 Ko1= 7.5 Ko1= 7.5 Ko1= 17.5 Ko1 @ 95°F -on = 14.9 Ko1 @ 95°F -om = 14.9 Ko1 @ 95°F -om = 14.9 Ko1 @ 838°F(Table I - 14.0 A Code CE = 28.7 × 10° po1Bree Relaxation Methodx'' = 7.5 / 14.9 = 0.5T'' = 7.5 / 14.9 = 0.5T'' = 7.5 / 14.9 = 1.89Vatchet Strain per cycle ((\Delta C_{T}) = \frac{5m}{E} \{ 1 - X'' + Y''[1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -$	ft $ft = 725^{\circ}F$ $y = 16.7 K$ $f = (mean + termp.)$ $abe (159.2)$ $Region G_{1}$ $\Delta \in r$ $2 \left(\frac{1-x''}{y''}\right)^{1/2}$

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	N266ER000-001	
PREPARED BY	Page 417 Rockwell International Energy Systems Group	N266SR000002 49
CHECKED BY	I-6IP	MODEL NO.
	<u>Strain Limits Evaluation</u> <u>Transient</u> E-210 @ <u>ment</u> 531 @ I	50 hec
G	= 19.0 Km	
	m = 2.9  KGI	
Te	mperature for E-210	Q50°F → 800°F
	Gy = 15.9 KGI @ 98 Gy = 16.8 KGI @ 8	$50^{\circ} F \rightarrow 0.7 = 16.3 \text{ Kb}$
	6m = 14.6 KSi @ E	595°F (Mizan Temp)
	(Table I-14.3A	Code Cabe 1592)
1	E = 23.3 × 106 Bree Relaxation Method	
4 j		
	X'' = 2.9/14.6 = 0.2 Y'' = 19.0/14.6 = 1.3	} Region Sz
	ratchet strain per cycle	
	$(\Delta G_{F}) = \frac{Sm}{E} \left[ X^{"} (Y^{"}-I) \right]$	-
	$= \frac{14600}{23.3\times10^{10}} \left[ 0.2 (1.3) \right]$	
	= 0.003B ofo	

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	PREPARED BY, CHECKED BY, UI, D. F.	Page 418 Rockwell International Energy Systems Group	N266SR000002	
	CHECKED BY: VI. H. F.	IGIP	MODEL NO.	
`.		Strain Limits Evaluation		
	Test	<u>t Transient</u> E-210 @ 1	50 bec	
	Elec	ment 666 C In	ducer Blade	
	۵ ۵	2 = 25.6  Km		
	ρ.	m = 5.6  K61		
	Te	imperature for E-210 Q	15°F → Boo"F	
		67 = 15.9 KGI @ 950° 67 = 16.8 KGI @ 800	F- b - 163"	
~	5m = 14.6 KSi @ B15°F (Mean Temp)			
		(Table I-14.3A C	ode Cabe 1592)	
		$E = 23.3 \times 10^6$		
	(.	Bree Relaxation Method		
	~	x'' = 5.6/10.6 = 0.38	Region Sr	
		Y'' = 25.6/14.6 = 1.75	J V	
		ratchetstrain per cycle (	∆€r)	
		$(\Delta \epsilon_{T}) = \frac{Sm}{\epsilon} \left[ x''(Y''-1) \right]$		
		$= \frac{14600}{33.3\times106} \left[ 0.38 (1) \right]$	-75-1)]	
-		= 0.0179 %	•	
	N 152-R-2 REV. 8-78			

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PREPARED BY.		Page 419 Rockwell Internation Energy Systems Grou		N266SR000002 <u>*</u> 51
OHECKED BY, W. J. J.	I6IP			MODEL NO.
	<u> </u>			
	Strain	Limits E	valuation	
Test	Transient	E-210	e t	50 hec
the	ment	648	C I	mpeller
	= 20.0 K			
P	m = 5.9 K	61		
Te	mperature f	or E-210	a	50°F → 800°F
	67 = 67 =	15.9 KG 16.8 KG	i @ 950° Di @ 800°	$F = b_{1} = 16.3 \text{ KH}$ $F = 16.3 \text{ KH}$
	$b_m =$	14.6 KS	i @ B16	F (Mizan Temp)
				de Cabe 1592)
		23.3×10		
l.	Bree Relaxo			
, ,	x' = 5.0 Y' = 10.0		l	Region SI
	ratchet str	ain per c	ucle (2	ser)
	$(\Delta \epsilon_r) = -2$	<u>Sm</u> {  - x"	+ 7" [ 1- 2	$\left(\frac{1-x''}{Y''}\right)^{1/2}$
	> <u> </u>	4600 13:3×106 {  -	0.4+1.37[	$1-2\left(\frac{1-0.4}{1.37}\right)^{1/2}$
	= 0	1.009B ofo		

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	N266ER000-001	
PREPARED BY,	Page 420 Rockwell International	N266SR000002 52
CHECKED BY, W. T. F.	Energy Systems Group	EFPORT NO.
DATE,	IGP	MODEL NO.
<u>telen</u> Q P	$\frac{\text{Strain Limits Evaluation}}{\text{Transient}} = E \cdot 210 @$ $\frac{\text{nent}}{412} @ 51$ $= 18.4 \text{ Koss}$ $m = 1.5 \text{ Koss}$ $mperature for E \cdot 210 @$ $G_T = 15.9 \text{ Koss} @ 950^{\circ}$ $G_T = 16.8 \text{ Koss} @ 800^{\circ}$	haft 150°F → B00°F
	5m = 14.6 KGi @ B1 (Table I-14.3A C E = 23.3 × 106	I
(.	Bree Relaxation Method X'' = 7.5 / 14.6 = 0.51 Y'' = 18.4 / 14.6 = 1.26	Region Si
	Ratchert Strain per cycle (2 $(\Delta E_{\rm f}) = \frac{3m}{E} \begin{cases} 1 - x'' + T'' [1 - 2] \\ - \frac{14600}{23.3 \times 10^6} \begin{cases} 1 - 0.5 + 1.26 \end{cases}$	$\left(\frac{1-\chi^{11}}{\gamma^{11}}\right)^{1/2}$
	= 0.01/0/0	

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		N266ER0		
PREPARED BY		Page 42 Rockwell Inter Energy Systems (	national	N266SR000002 53 ×
CHECKED BY:	1.1, Z, A.			REPORT NO.
		ISIP		MODEL NO.
<u>. '''</u>		<u>, , , , , , , , , , , , , , , , , , , </u>		
			-	
		Creep-Fatigue	Jamage	
	Test	<u>irangient</u> E. (	207	
	Eleme	nt		
	p.	1+Q = 40.9 Km	> 6	
	СЛ.		/ 034	= 15.9 KB1
	1	at culo aco	- -	
	١.	25 GY / 0.9 = 22.0	Q K01	
	1. C	eep Damage		
		•		
		The allowable duration	I To , from	1 Fig. I.14.6A
			Co	de Cupe 1592
		$Td = 6 \times 10^4 Hrs$		
		$1a = 6 \times 10 \text{ Hrs}$		
		the end duration	a fer and an and a safe	La Mar ( Maria
		the cycle duration	of transferry	100 Ars. Assum
		the creep damage	, per cycle	
		•		
		$\frac{t}{Td} = \frac{10}{1000}$	0,001	1

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CHECKED BY. W. P.F.	ISIP	MODEL NO.
	Creep-Fatigue Damage	
2,	Fatigue, Damage	
	$E e_{ment} + 412 \otimes ohaft \otimes ti$ $E_t = 40.9 \times 10^3 / 22.9 \times 10^6 =$	•
	$Nd = 2 \times 10^3$ cycles	
	The fatigue damage fractic	off per cycle will be
	$\frac{n}{Nd} = \frac{1}{2 \times 10^3}$	
· 'n.	The total creep-Fatigue Do $\sum \frac{t}{Td} + \sum \frac{n}{Nd} \leq 1$	mage
r	$\sum \frac{t}{Td} + \sum \frac{n}{Nd} = (6)$	$(2) \frac{100}{6\times10^4} + (6\times2) \frac{1}{2\times10^5}$
	= 0,0	2+0,006
	= 0.0	026 <1
		-

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Table I-14.3A  $S_{\rm mf}$  — Allowable Stress Intensity Values, 1000 psi Type 304 SS — 30-YS, 76-UTS (30-YS, 70-UTS)

Temp. * F	1 hr	10 hr	30 hr	10 <sup>2</sup> hr	3 X 10 <sup>3</sup> hr	10 <sup>3</sup> hr	3 X 10' hr	10 <sup>4</sup> hr	3 X 10 <sup>4</sup> lw	10 <sup>9</sup> hr	3 X 10' hr
800	15.1	15.1	15.1	15.1	15.1	15.1	15.1	15.1	15.1	15.1	15.1
850	14.8	14.8	14.8	14.8	14.8	14.8	14.8	14.8	14.8	14.0	14.8
900	14.6	14.6	14.6	14.6	14.6	14.6	14.6	14.6	14.6	14.6	14.6
950	14.3	14.3	14.3	14.3	14.3	14.3	14.3	14.3	14.3	14.2	12.2
1000	14.0	14.0	14.0	14.0	14.0	14.0	14.0	14.0	13.1	11.1	9.3
1050	13.6	13.6	13.6	13.6	13.6	13.6	13.6	12.2	10.3	8.7	7.3
1100	13.2	13.2	13.2	13.2	13.2	13.2	11.5	9.7	8.2	6.8	5.7
1150	12.9	12.9	12.9	12.9	12.9	11.0	9.3	7.7	6.4	5.3	. 4.4
1200	12.7	12.7	12.7	12.2	10.6	8.9	7.4	6.1	5.1	4.1	3.4
1250	12.3	12.3	11.9	10.3	8.7	7.2	5.9	4.9	4.0	3.2	2.7
1300	11.9 (11.8)	11.4	10.0	8.5	7.0	5.9	4.8	3.9	3.2	2.5	2.1
1350	10.9 (10.5)	9.7	8.4	7.1	5.9	4.8	3.9	3.1	2.5	2.0	1.6
1400	9.5 ( 9.0)	0.1	6.9	5.9	4.8	3.9	3.1	2.5	2.0	1.6	1.2
1450	8.2 ( 7.5)	6.8	5.8	4.6	3.0	3.0	2.4	1.9	1.5	1.2	0.9
1500	7.0 ( 6.4)	5.3	4.4	3.5	2.8	2.2	1.7	1.3	1.0	0.8	0.6

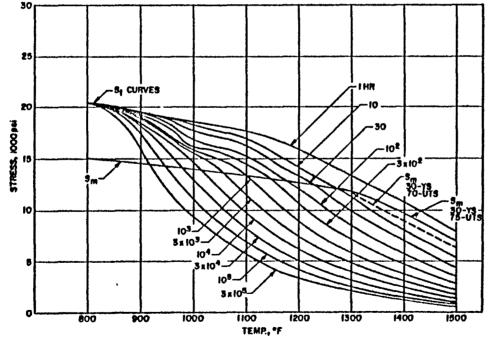


Fig. 1-14.3A Smt - Type 304 SS

CASE

N-47

1592-10)

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## CASE

N-47-12 (1592-12)

## CASES OF ASME BOILER AND PRESSURE VESSEL CODE

Table 1-14.5

N266SR000002 56

Ťemp., F	304 SS	316 SS	Ni-Fe-Cr Alloy 800H	2% Cr-1 Mo	Ni-Cr-Fe-Ct Alloy 718	
		(Stress	es in ksi Units)			
RT	30.0 ·	30.0	25.0	30.0	150.0	
100	28.8	29.2	24.3	29.4	148.4	
200	25.0	25.8	22.5	27.8	143.9	
300	22.5	23.3	21.1	26.8	140.7	
400	20.7	21.4	20.0	26.6	138.3	
500	19.4	19.9	19.0	26.5	136.7	
600	18.2	18.8 -	18.3	26.5	135.4	
700	17.7 -	18.1	17.5	26.5	134.3	
750	17.3	17.8	17.2	26.5	133.7	
800	16.8 ·	17.6	16.8	26.5	133.1	
850	16.5-	17.4	16.5	26.3	132.4	
900	16.2	17.3	16.3	25.6	131.5	
950	15.9 -	17.1	16.1	24.7	130.5	
1000	15.6	17.0.	15.8	23.6	129.4	
1050	15.2 -	16.7	15.6	22.1	128.0	
1100	14.7	16.5	15.3	20.4		
1150	14.4	16.4	15.0	18.4		
1200	14.1	16.2	14.8	16.1		
1250	13.7	15.8	14.5			
1300	13.2	15.3	14.3			
1350	12.5	14.9	14.0			
1400	11.6	14.4	13.7			
1450	10.6	13.8	13.4	<u>.</u>		
1500	9.5	13.1	13.0			
1550			12.3			
1600			11.0			

<sup>&</sup>lt;sup>1</sup>The tabulated values of yield strength are those which the Committee believes are suitable for use in design calculations required by this Case. At temperatures above room temperature the yield strength values correspond to the yield strength trend curve adjusted to the minimum specified room temperature yield strength. The yield strength values do not correspond exactly to either "average" or "minimum" as these terms are applied to a statistical treatment of a homogeneous set of data.



homogeneous set of data. Neither the ASME Materials Specifications nor the rules of this Case require elevated temperature testing for yield strengths of production material for use in Code components. It is not intended that results of such tests, if performed, be compared with these tabulated yield strength values for ASME Code acceptance/ rejection purposes for materials. If some elevated temperature test results on production material appear lower than the tabulated values by a large amount (more than the typical variability of material and suggesting the possibility of some error) further investigation by retests or other means should be considered.



## Table I-14.6A

Expected Minimum Stress-to-Rupture Values, 1000 psi Type 304 SS

Temp., *F	1 hr	10 hr	30 hr	10² hr	3 X 10 <sup>3</sup> hr	10 <sup>3</sup> hr	3 X 10 <sup>3</sup> hr	10 <sup>4</sup> hr	3 X 10° hr	10 <sup>5</sup> hr	3 X 10' hr
800 -	57	57	57	57	57	57	57	57	51	44.3	39
850	56.5	56.5	56.5	56.5	56.5	56.5	50.2	45.4	40	34.7	30.5
900	55.5	55.5	55.5	55.5	51.5	46.9	41.2	36.1	31.5	27.2	24
950	54.2	54.2	51	48.1	43	38.0	33.5	28.8 .	24.9	21.2	18.3
1000	52.5	50	44.5	39.8	35	30.9	26.5	22.9	19.7	16.6	14.0
1050	50	41.9	37	32.9	28.9	25.0	21.6	18.2	15.5	13.0	11.0
1100	45	35.2	31	27.2	23.9	20.3	17.3	14.5	12.3	10.2	8.6
1150	38	29.5	26	22.5	19.3	16.5	13.9	11.6	9.6	8.0	6.6
1200	32	24.7	21.5	18.6	15.9	13.4	11.1	9.2	7.6	6.2	5.0
1250	27	20.7	17.9	15.4	13	10.8	8.9	7.3	6.0	4.9	4.0
1300	23	17.4	15	12.7	10.5	8.8	7.2	5.8	4.8	3.8	3.1
1350	19.5	14.6	12.6	10.6	8.8	7.2	5.8	4.6	3.8	3.0	2.4
1400	16.5	12.1	10.3	8.8	7.2	5.0	4.7	3.7	3.0	2.3	1.9
1450	14.0	10.2	8.8	7.3	5.8	4.6	3.8	2.9	2.3	1.0	1.4
1500	12.0	8.6	7.2	6.0	4.9	3.0	3.0	2.4	1.8	1.4	1.1

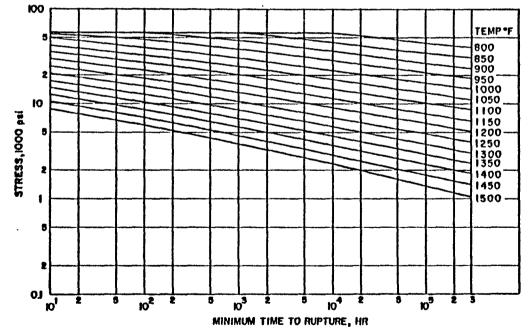


Fig. 1-14.6A Stress-to-rupture (minimum)



CASES OF ASME BOILER AND PRESSURE VESSEL CODE

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## N266ER000-001 Page 426 N266SR000002 58 N-47 (1592-10)

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## CASES OF ASME BOILER AND PRESSURE VESSEL CODE

Temp., ° F	(Static) Modulus of Elasticity, psi × 10 <sup>-6</sup>							
	304 SS and 316 SS	Ni-Fe-Cr Alloy 800H	2% Cr - 1 Mo	Ni-Cr-Fe-Ct Alloy 718				
70	28.3	28.5	29.9	-				
100	_	-		29.0				
200	27.7	27.8	29.5	28.38				
300	27.1	27.3	29.0	27.93				
400	26.6	26.8	28.6	27.51				
500	26.1	26.3	28.0	27.10				
600	25.4	25.7	27.4	26.69				
700	24.8	25.2	26.6	26.26				
750	- 1	• –		-				
800	24.1	24.6	25.7	25.82				
850	23.7	24.4	-	-				
900	23.3 •	24.1	24.5	25.35				
950	22.9	23.8	-	-				
1000	22.5	23.5	23.0	24.84				
1050	22.1	23.3	-	24.56				
1100	21.7	22.9	20.4					
1150	21.3	22.7						
1200	20.9	22.4	15.6					
1250	20.5	22.1						
1300	20.1	21.7						
1350	19.7	21.4						
1400	19.2	21.1						
1450	18.7	20.7						
1500	18.3	20.3						
1550	1	19.8						
1600	I	19.2						

Table I-14.7. Modulus of Elasticity vs. Temperature





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CASE

### CASES OF ASME BOILER AND PRESSURE VESSEL CODE

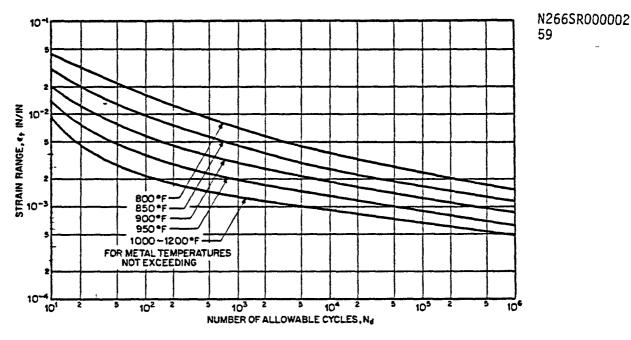


Fig. T--1430-1A,1B Design fatigue strain range,  $\epsilon_{\rm f}$ , 304 SS and 316 SS -- elastic analysis

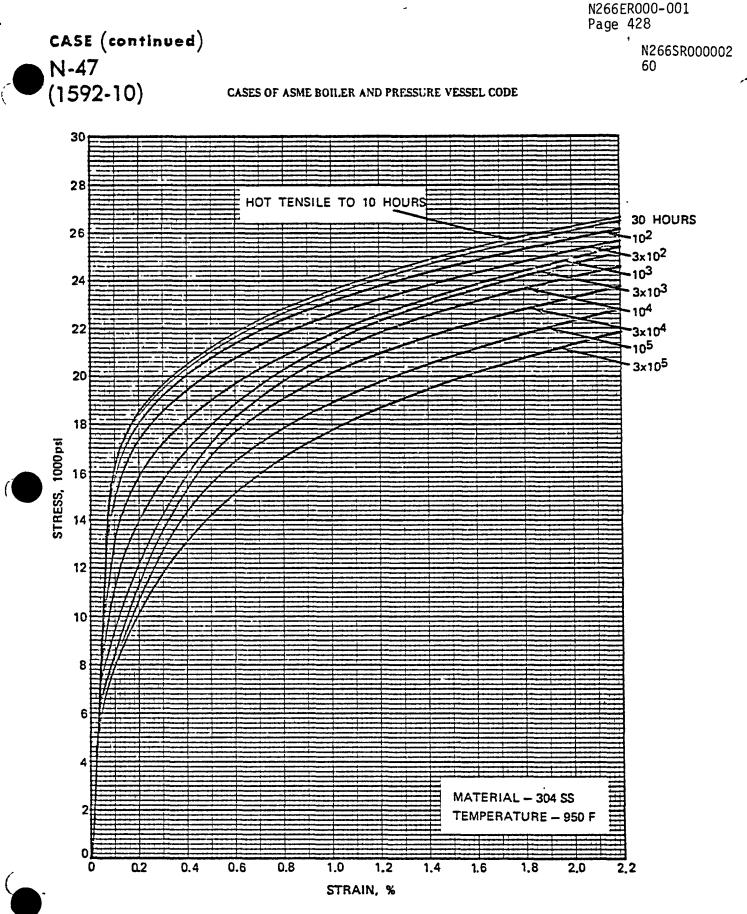
#### Table T--1430-1A, 1B

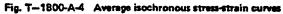
# Design Fatigue Strain Range, $e_{f}$ , for 304 SS and 316 SS (Elastic Analysis)

<i>N<sub>d</sub></i> Number of		e <sub>f</sub> , Strain F	Range (in./in.) (	it Temperatu	FØ
Cycles	800 F	850 F	900 F	950 F	1000-1200 F
10 <sup>1</sup>	.0448	.0303	.0201	.0137	.00915
2×10'	.0318	.020	.0124	.0078	.00472
4×10 <sup>1</sup>	.0231	.0145	.00867	.0051	.00322
10 <sup>2</sup>	.0168	.00982	.00587	:00355	.00212
2×10 <sup>3</sup>	.0125	.00772	.00469	.0028	.00174
4×10 <sup>2</sup>	.00956	.00612	.00387	.0024 -	.00152
10'	.00711	.00462	.00304	.00198	.00129
2×10'	.00576	.00382	.00257	.00173	.00114
4×10'	.00476	.00322	.00222	.00153	.00104
104	.00376	.00261	.00186	.0013	.000922
2×104	.00316	.00222	.00164	.00116	.000842
4×104	.00269	.00202	.00144	.00106	.000762
105	.00224	.00162	.00122	.000899	.000662
2×10'	.00196	.00147	.00108	.000799	.000602
4×10 <sup>4</sup>	.00176	.00131	<b>.0</b> 00966	.000719	.000544
104	.00151	.00112	.000826	.000619	.000482

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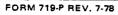
NO . N26 PAGE . 61

## APPENDIX B

## THERMAL DEFORMATION ANALYSIS

## Figure

B-1	APSA Model for Static Assembly
B-2	APSA Model for Rotating Assembly
B-3	Finite Element Model @ Bearing Area - Node No.
B-4	Finite Element Model @ Bearing Area - Element No
B-5	Finite Element Model @ Bearing Area - Node No.
B-6	Finite Element Model @ Bearing Area - Element No



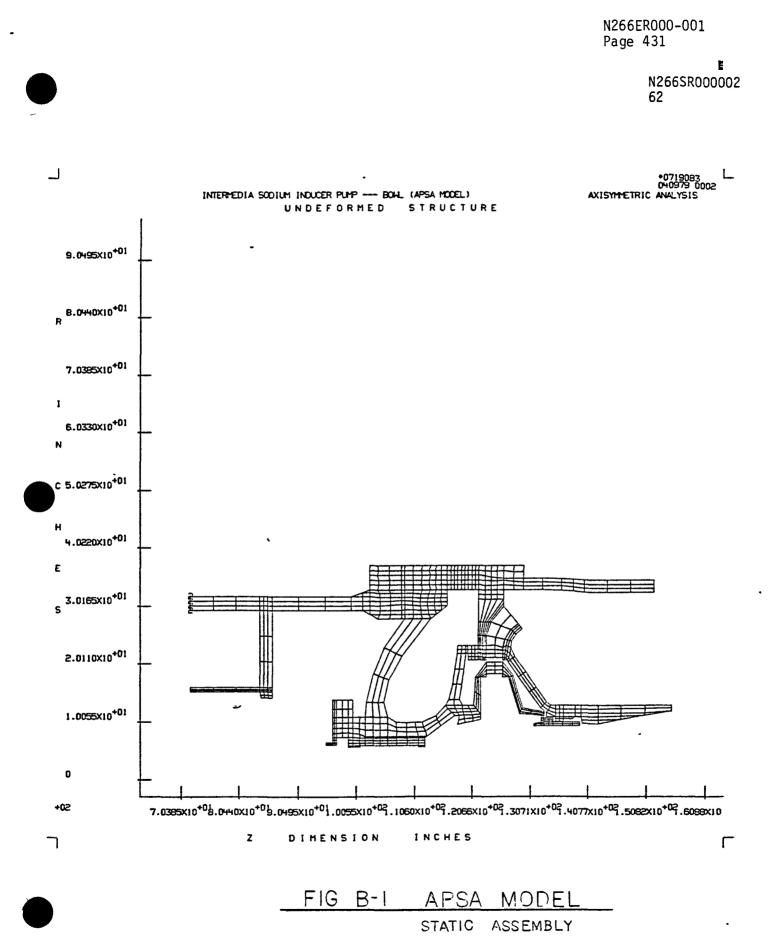
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#### THERMAL DEFORMATION ANALYSIS

The finite element computer program (APSA) has been used to determine the deflection of pump component during thermal transient events. As described in Section 3 of this report, the worst-time slices with maximum temperature difference ( $\Delta T$ ) were obtained through the iteration of the temperature time-history process. The worst-time slices for each transient were used in the stress-deformation model to determine the clearance change between all critical components. Figure B-1 through Figure B-12 showed the APSA stress model of nodes and element for various parts of the inducer-impeller assembly. Table B-1 through Table B-36 indicated the calculation of clearance from computer output for pump elements.



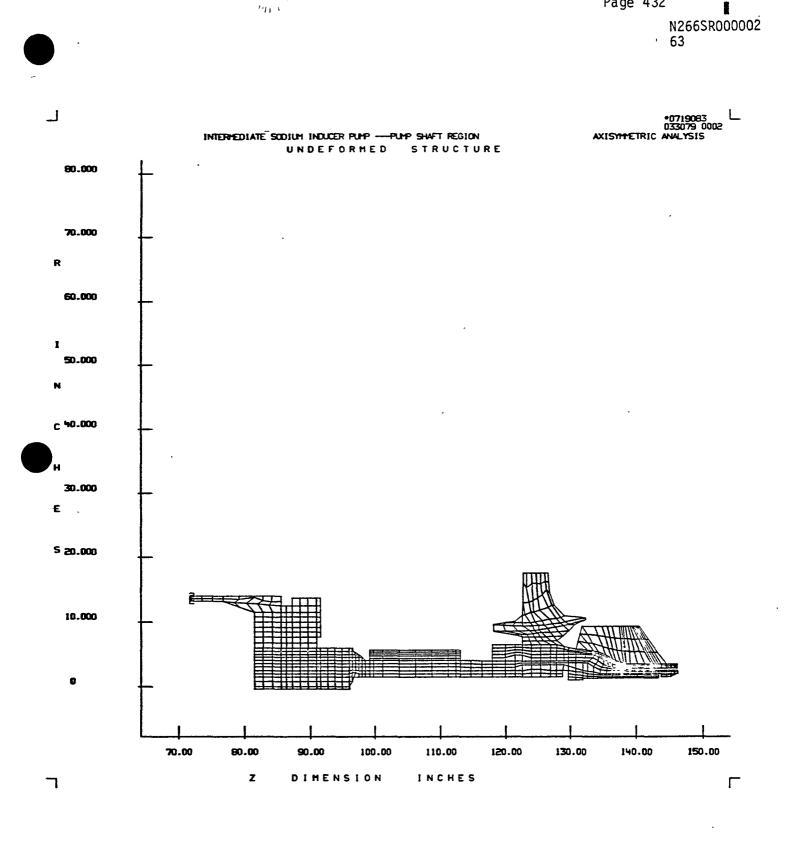


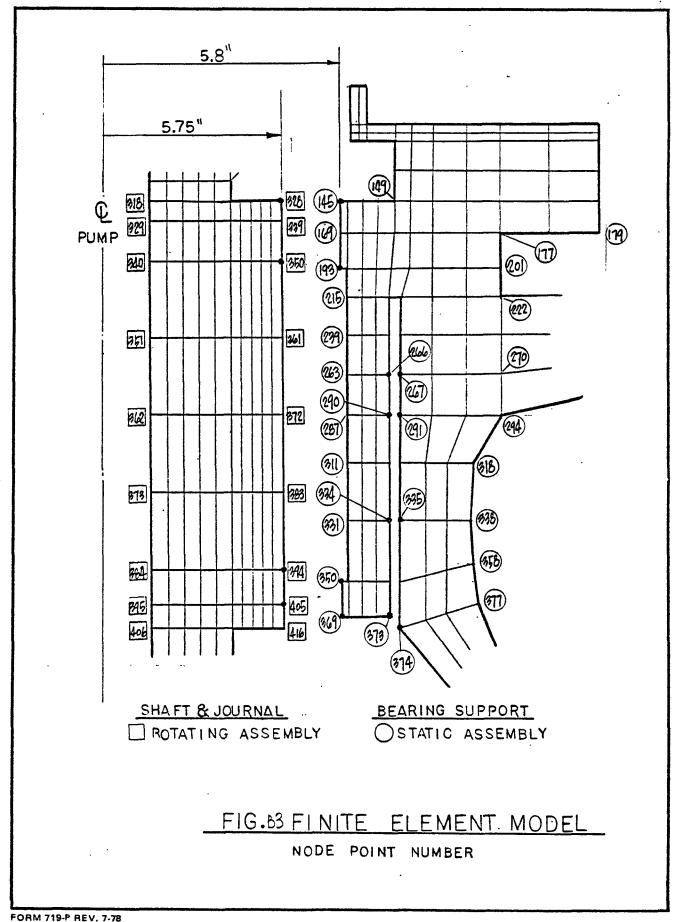
FIG. B-2 APSA MODEL

ROTATING ASSEMBLY

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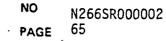


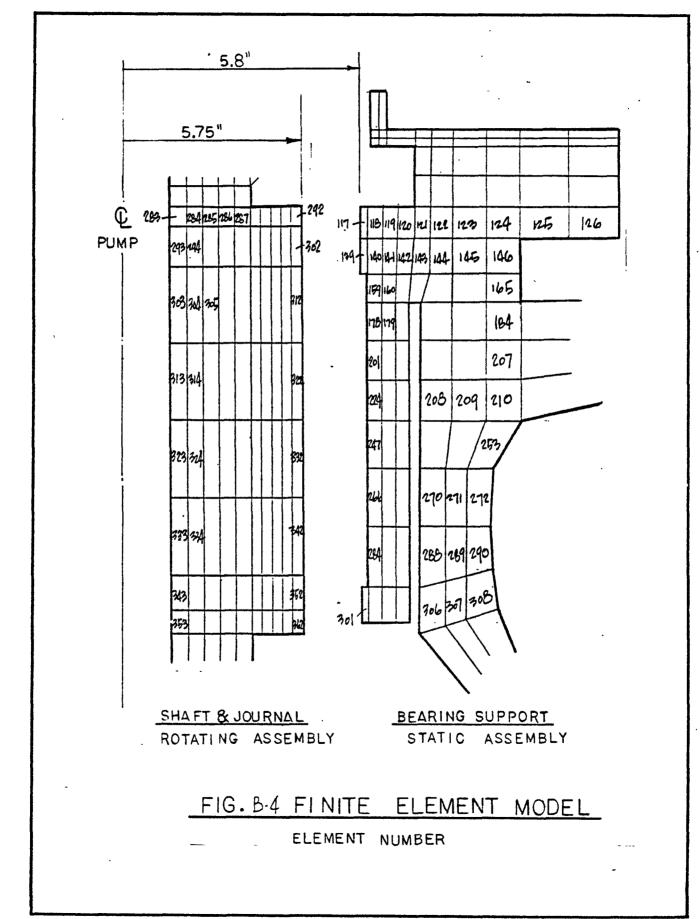
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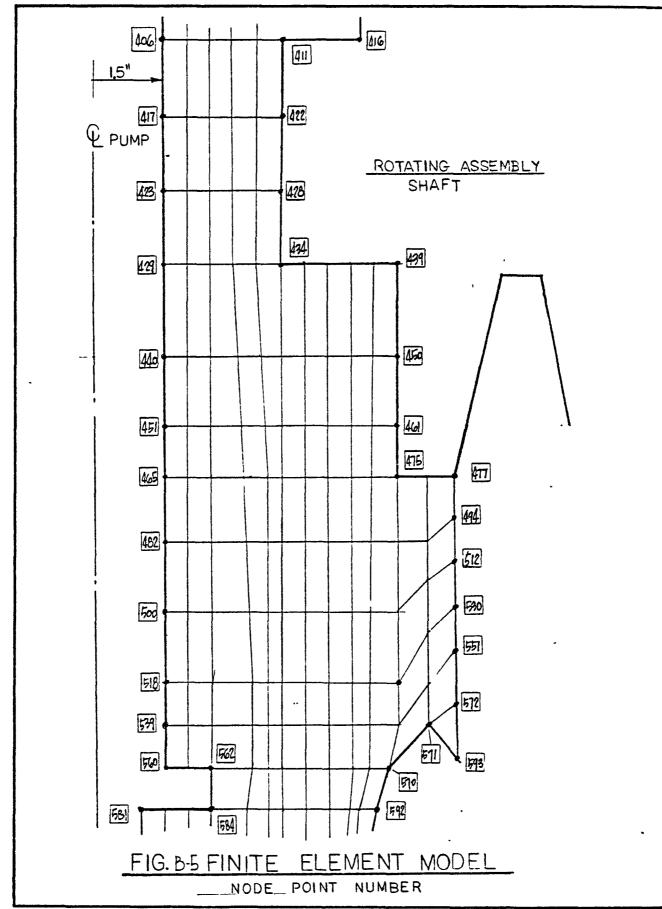


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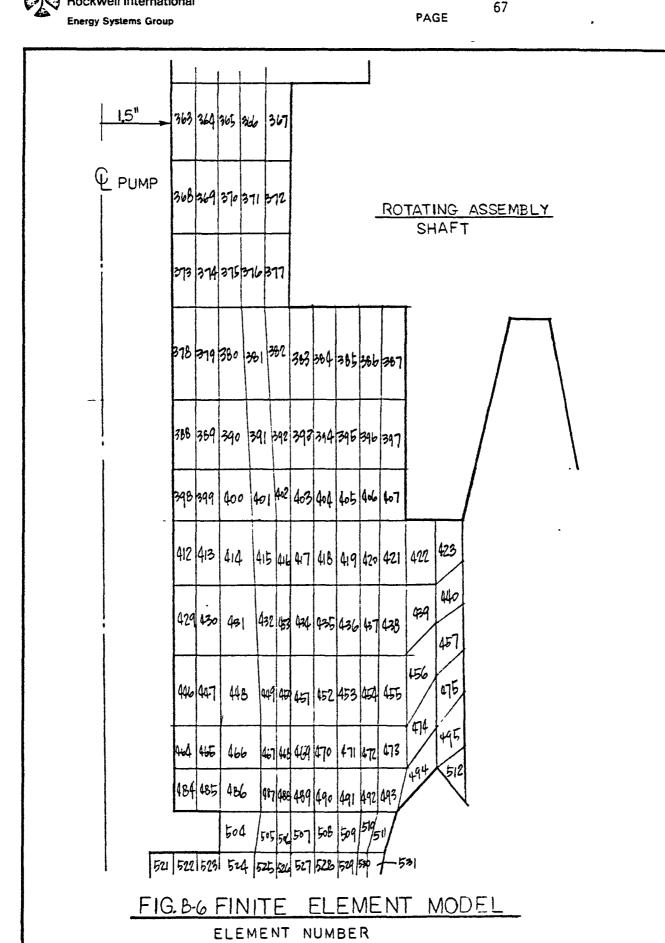
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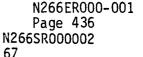


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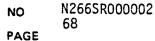
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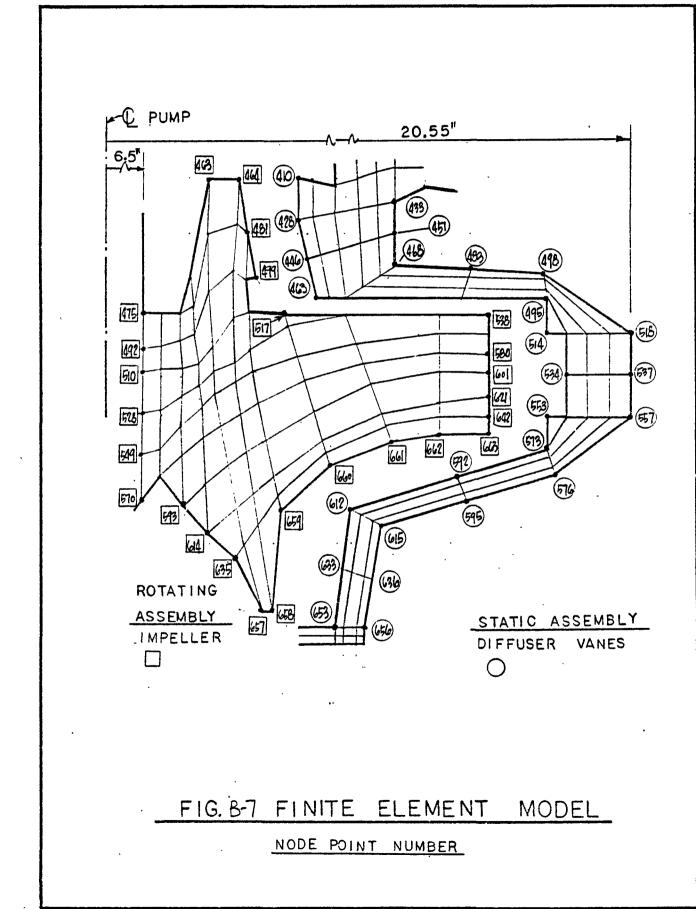
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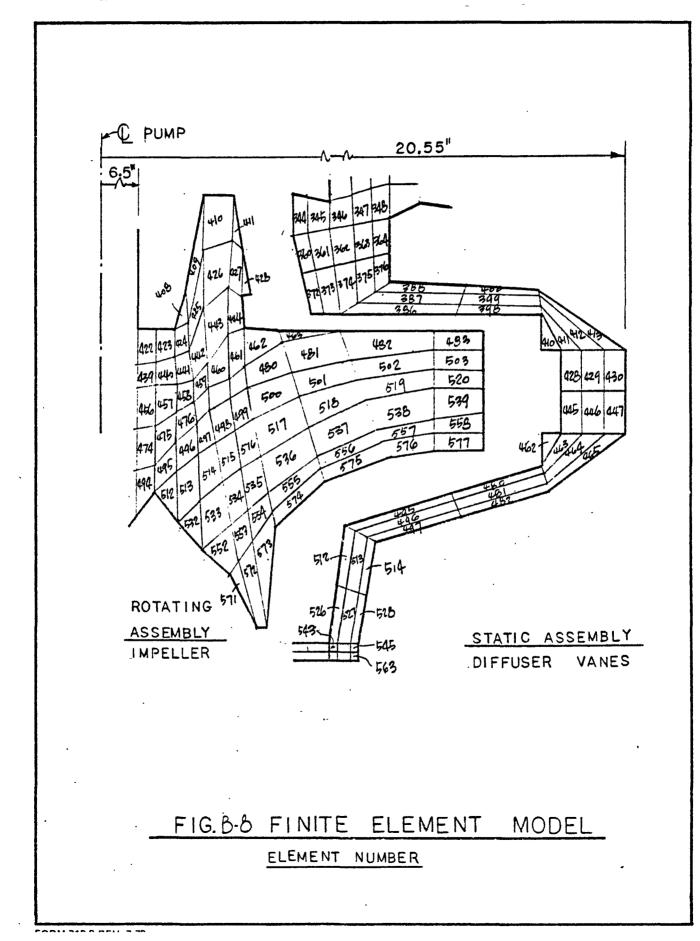


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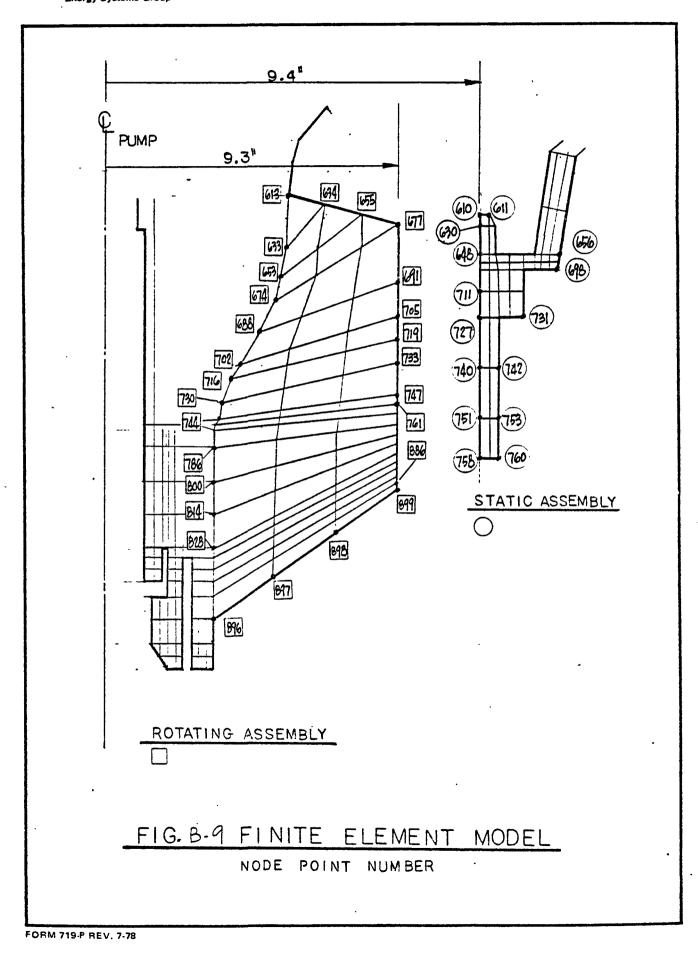


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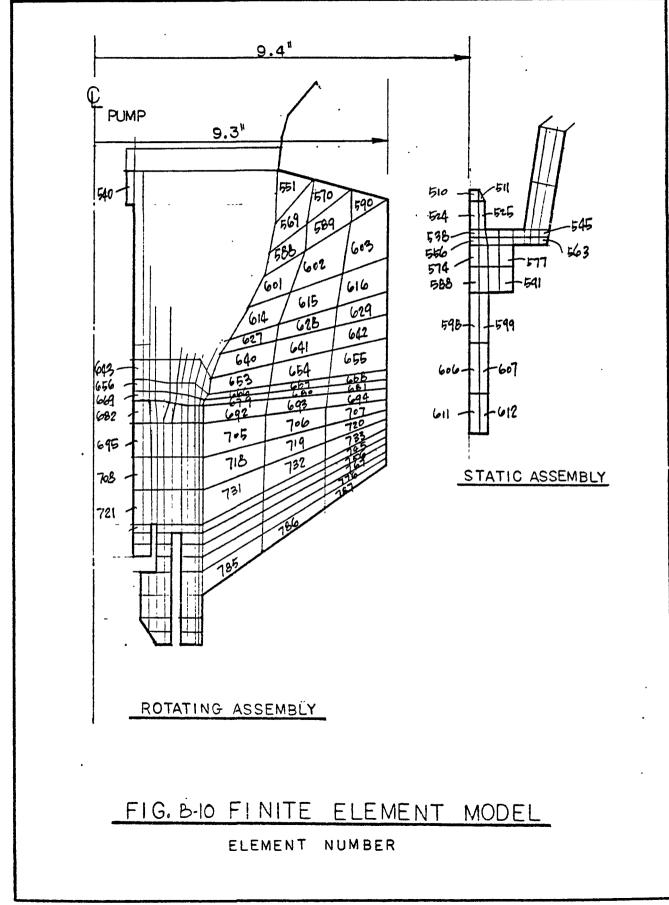
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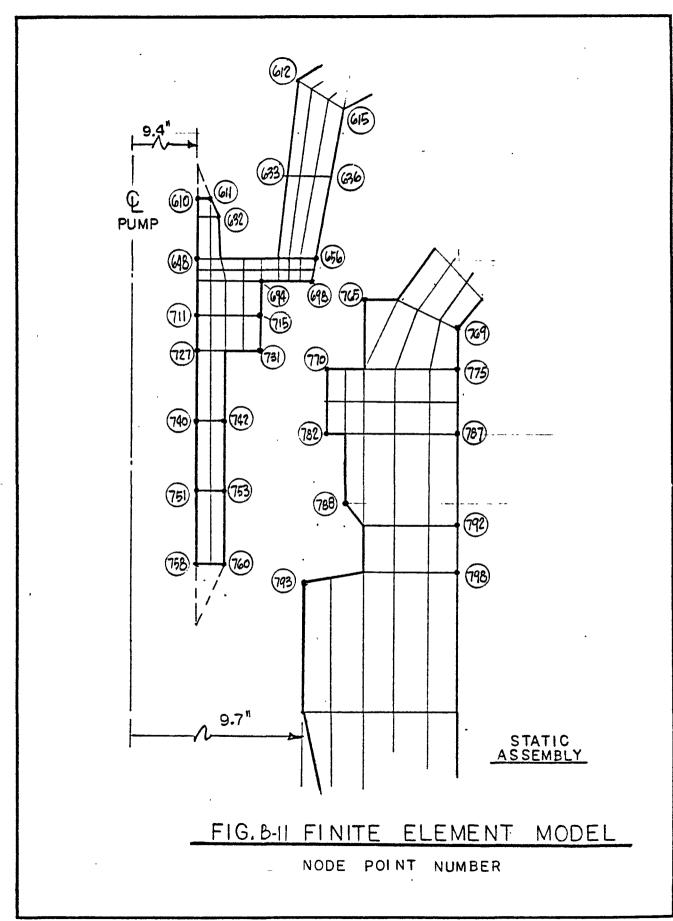


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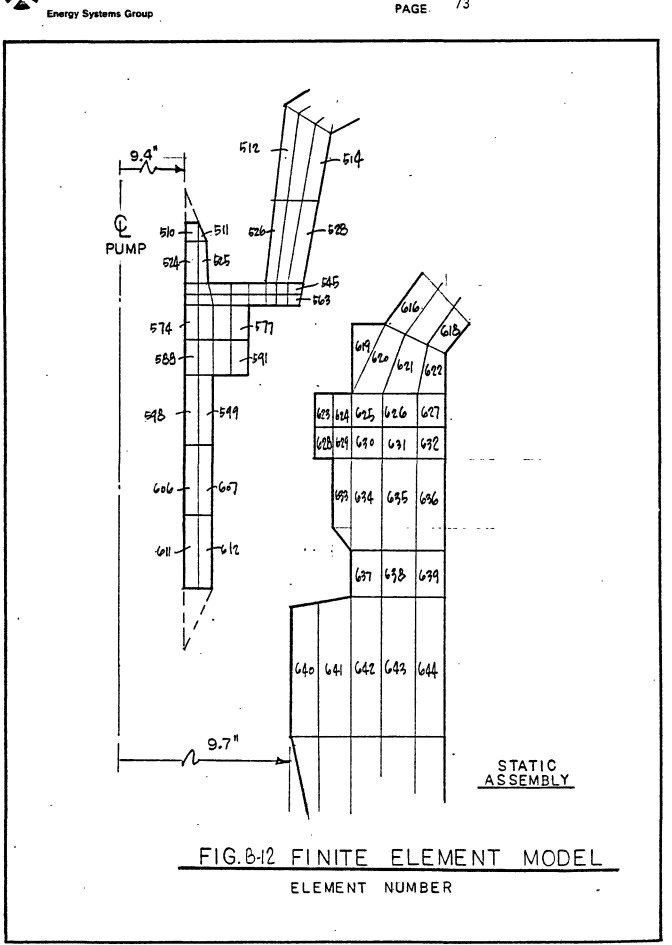
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TABLE B.1

RADIAL CLEARANCE CHANGE ( ) E202 TEST TRANSIENT (MILS)

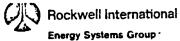
* NODES	TIME	= 100	SEC.	TIME =	280	SEC.
STA,-	STAT IC-R	OTAT IN G	'=(△)	STATIC -	ROTATIN	G =(△)
145-328	38.7	36.3	+2.4	34.5	32.8	+1.7
193 - 350	38.B	37.4	+1.4	35.6	33. <u>8</u>	+1.8
239_361	39.7	37.9	+1.8	35.8	34.6	+1.2
287-372	39.0	38.0	+1.0	32.9	34.9	+2.0
331-383	38.5	37.5	+1.0	33.5	34.3	+0,8
350-394	36.9	36.9	+1.0	32.3	33.0	+0.5
369_405	36.4	34.5	+1.9	32,2	32.0	40.2
-	.:		·			1 . 6

\* LOCATIONS EXHIBITED IN FIG, B-3

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TABLE B.2

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E203 (MILS)

* NODES	ТІМЕ	= 100	SEC.	TIME =	280	SEC.
STA,-	STAT IC-R	OTATIN G	;=(∆)	STATIC -	ROTATIN	IG =(△)
145-328	24.9	26.6	-1.7	29.0	30.1	-1.1
193 - 350	24.8	25.5	-0.7	27.9	29.0	-1.1
239_361	26.0	25.1	+0,9	29.8	283	-1.5
287-372	26.7	25.0	+1.7	31.6	28.0	+3.6
331-383	27.2	25.4	+1.8	32.2	28.5	+3.7
350-394	n6.6	27.0	-0,4	31.1	nq.q	+1.2
369_405	27.1	28.4	-1.3	31.2	30.9	-
-				- ,		+0.3

\* LOCATIONS EXHIBITED IN FIG. B-3

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TABLE B-3

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E204 (MILS)

* NODES	TIME	= 100	SEC.	TIME =	210	SEC.
	STAT IC-R	OTATIN	⊊=(∆)	STATIC -	-ROTATIN	IG =(△)
145-328	44.7	41.6	+3.	40,8	38.0	+ 2.8
193 - 350	44.9	43.	+ 1.8	42.1	39.7	+ 2.4
239-361	45.9	43.8	+ 2.1	42.2	40,8	+ 1.4
287-372	44.9	43.9	+ 1.0	39.7	41.1	- 1.4
331-383	44.3	43.2	+ 1.0	38.9	40.3	- 1.4
350-394	42.3	41.1	+ (.2	37.4	38.2	- 0.8
369_405	41.7	39.1	+ 2.6	37.2	36.5	+ 0.7
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\* LOCATIONS EXHIBITED IN FIG. 53

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TABLE B-4

RADIAL CLEARANCE CHANGE (Å) TEST TRANSIENT E207 (MILS)

* Nodes	TIME	= 175	SEC.	TIME	= 385	SEC.
STA-	STAT IC-R	OTATIN	G=(∆)	STATIC	-ROTAT IN	۹G =(△)
145-328	45.7	41.1	+4.6	41.1	37.4	+ 3.7
193 - 350	47.2	43.7	+ 3.5	43.4	39.6	+ 3.8
239_361	47.0	45.3	+ 1.7	42.8	41.3	+ 1.5
287-372	43.8	45.7	- 1.9	38.9	41.8	- 2.9
331-383	42.6	44.5	- 1.9	37.7	40.7	- 3.0
350-394	40.B	41.0	- 0.2	36.3	37.7	- 1.4
369_405	40.2	38,3	+ 3.5	36.0	35.6	+ 0,4
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\* LOCATIONS EXHIBITED IN FIG, B-3

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	•	N266ER000-001 Page 447
	TABLE 0-5	
	RADIAL CLEARANCE CHANGE TEST TRANSIENT E200 (MILS)	

* NODES	ТІМЕ	= 115	SEC.	TIME =	240	SEC.
STA,-	STAT IC-R	OTATIN	;=(△)	STATIC -	ROTATIN	IG =(∆)
145-328	50.7	47.0	+3.7	45.9	42.8	+3.1
193 - 350	51.0	48.8	+ 2.2	47.5	44.6	+ 2.9
239_361	5.2.0	49.6	+ 2.4	47.5	45.9	+ 1.6
287-372	50.6	49.8	- 0,8	44.6	46.2	- 1.6
331-383	49.9	49.0	-0.9	43.7	45.4	- 1.7
350-394	47.7	46.5	-1.2	42.1	40.0	- 0.9
369_405	47.0	44.2	+2,8	41.9	41.3	+ 0.6
-	::					

\* LOCATIONS EXHIBITED IN FIG. 53

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TABLE B-G

RADIAL CLEARANCE CHANGE TEST TRANSIENT E 20 (MILS)

* NODES	TIME	= 50	SEC.	TIME	= 150	SEC.
STAROT.	STAT IC-R	OTATIN G	;=(∆)	STATIC	-ROTATIN	IG =(△)
145-328	52.1	49.9	+ 2.2	49.3	46.7	+ 2.6
193 - 350	52.0	50.B	+ 1.2	50.1	48.1	+2.0
239_361	53.7	51.1	+ 2.6	50.8	48.9	+1.9
287-372	53.5	51.1	+ 2.4	48.9	49.1	- 0.2
331-383	53.1	50.7	+ 2.4	48.3	48.5	- 0.2
350-394	50.9	49.3	+ 1.6	4666	46.7	- 0.]
369_405	50,3	47.9	+ 2.4	46.3	45.3	+ 1.0
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\* LOCATIONS EXHIBITED IN FIG. B-3

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### TABLE B.7

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E202 (MILS)

* NODES	ТІМЕ	=  00	SEC.	TIME	= 280	SEC.
STASTA.	OUTER	- INNER	$\zeta = (\Delta)$	OUTER	- INNE	$R = (\Delta)$
765 - 694	67.9	59.2	+ 8.7	60.7	56.5	+ 4.2
772 - 731	67.7	60.8	+ 6.9	60.5	56.7	+ 3.8
770 - 729	62.9	56.3	+ 6.6	56.3	52B	+ 3.5
782 - 742		56.7			52.8	
-						
-						
-						
-		••				

\* LOCATIONS EXHIBITED IN FIG. B-1

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TABLE B-8

RADIAL CLEARANCE CHANGE (ム) TEST TRANSIENT E203 (MILS)

* NODES	TIME	=  00	) SEC.	TIME :	= 280	SEC.
STA STA.	OUTER -	- INNER	= (\Delta)	Durrer	- INNER	( = (△)
765-694	52.3	58.4	-6.1	59.4	61.1	- 1.7
772 - 731	52.3	56.8	- 4.5	59.5	60.8 -	- 1.3
770 - 729	48.3	53.0	- 4.7	55.0	56.6	- 1.6
782 - 742	48.1	52.7	- 4.6	54.7		-1.8
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-						
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-	•• ••					

\* LOCATIONS EXHIBITED IN FIG. B-I

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TABLE B-9

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E204 (MILS)

* NODES	TIME	=  0	0	SEC.	TIME	= 210	SEC.
STA - STA	OUTER	- INNER	2 =	(∆)	OUTER	- INNE	$e_R = (\Delta)$
765 - 694	77.6	660	+	11-6	69.8	62.6	+ 7.2
772 - 731	77.6	68.1	+	9.5	69.8	63.	- + 6.7
770 - 729	7.2.2	63.	+	9.1	65.0	58.7	+ 6.3
782 <b>–</b> 742							+ 6.7
-							
-							-
-		•					
-	•						

\* LOCATIONS EXHIBITED IN FIG, B-1

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TABLE B.10

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E207 (MILS)

* NODES	TIME	= 27	5 SEC.	TIME	:= 38	5 SEC.
STA STA	OUTER .	- INNER	. = (∆)	Outer	r - Inn	$ler = (\Delta)$
765 - 694	74.6	61-8	+13.0	67.3	59.4	+ 7.9
772 - 731	74.5	63.6	+ 10.9	67.1	60.0	+ 7.1
770 - 729	69.5	58.9	+ 10.6	62.6	55.7	+ 6.9
782 - 742	70.2	59.4	+ 10,8	63.1	55.9	+ 7.2
-						
-						
-						
-	••	•				

\* LOCATIONS EXHIBITED IN FIG. B-1

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TABLE B-11

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E208 (MILS)

* NODES	ТІМІ	E =	5 s	EC.	TIME :	= 240	SEC.
STA STA	OUTER	- INNE	R = (	∆)	Outer	- INNE	$R = (\Delta)$
765 - 694	87.5	74.4	+ 1	3.1	78.6	71.2	+ 7.4
772 - 731	87.5	76.7	+ 1	0,8	78.6	71.7.	· + 6.9
770 - 729		71.1			1		+ 6.5
782 - 742	81.8	71.6	+	0.2			+ 6.9
-							
-							
-		• .					
-							

\* LOCATIONS EXHIBITED IN FIG. B-1

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# TABLE B-12

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E20 (MILS)

* NODES	ТІМ	E = 5	O SEC	TIME	= 150	SEC.
STA STA.	OUTER	- INNE	$R = (\Delta)$	Duter	- INNE	$e_{R} = (\Delta)$
765-694	94.6	84.1	+10.5	87.0	79.9	+ 7.1
772 - 731	94.7	863	+ 8.4	87.0	80.5	•+ 6.5
770 - 729	87.9	80.0	+ 7.9	80.9	74.8	+ 6.1
782 - 742	88.0	80.5	+ 7.5	B1.3	75,0	+ 6.3
-						
-						
-		•				
-		•• ••				

#### \* LOCATIONS EXHIBITED IN FIG. B-11

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## TABLE B-13

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E202 (MILS)

* NODES	ТІМЕ	= (c	O SEC.	TIME	= 280	SEC.
STA ROT.	STATIC-	ROTATIN	G=(∆)	STATIC-	ROTATING	= (\(\Delta\)
633 - 659	62.0	62.1	- 0.1	59.5	58.2	+1.3
653 - 658	61.1	60.2	+ 0.9	58.5	56.7	+ 1-8
-						
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-		•				

#### \* LOCATIONS EXHIBITED IN FIG. 8.7

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TABLE B-14

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E203 (MILS)

* NODES	ТІМЕ	= 10	00	SEC.	TIME	= 280	SEC.
STA ROT.	STATIC-F	ROTATIN	IG = 1	(∆)	STATIC-1	ROTATING :	= (4)
633 - 659	62.2	57.0	+	5.2	64.6	60.9	+ 3.7
653 -658	60.8	56.2	+	4-6	63.4 .	59-8.	+ 3.6
-	•					·	
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			•				
-							
-							
_	-						

\* LOCATIONS EXHIBITED IN FIG. B-7

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### TABLE B-15

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E204 (MILS)

* NODES	ТІМЕ	=  00	SEC.	TIME	= 210	SEC.
STA - ROT.	STATIC-	ROTATING	$i=(\Delta)$	STATIC-	ROTATING :	= (\Delta)
633 - 659	69.0	69.7	-0.7	65.8	65.6	+0.2
653 -658	68-1	67.5	+ 0.6	64.8 -	63.7	+1.1
-	•					
-						
-				•		
-			-			
_						
-	-	-				

#### \* LOCATIONS EXHIBITED IN FIG. B-7

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## TABLE B-16

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E207 (MILS)

* NODES	TIME	= 275	SEC.	TIME	= 385	SEC.
STA ROT.	STATIC-R	OTATING	=(△)	STATIC-1	ROTATING =	= (\(\D))
633 - 659	64.6	66.1	1.5	62.4	62.3	+0.
653 - 658	63.8	63.9	-0.1	61.5 -	60.4	+ 1-1
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#### \* LOCATIONS EXHIBITED IN FIG. B-7

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			TRANS	SIENT	E208		
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* N (	DDES	ТІМЕ	E =	5 SEC.	TIME	= 240	) SEC.
		STATIC-	ROTATIN	$G=(\Delta)$	STATIC -	ROTATING	= (\Delta)
633	-659	77.8	78.7	- 0,9	74.9	74.2	+ 0.7
653	-458	76.8	76.2	+0.6	73.8	72.1	+1.7
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# TABLE B-18

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E 20 (MILS)

* Nodes	TIME	= 50	SEC.	TIME =	: 150	SEC.
STA ROT.	STATIC-	ROTATING	9=(∆)	STATIC-R	otating	= (\(\Delta\)
633 - 659	88.2	86.9	+ 1.3	84.1	82.9	+1-2
663 - 668	86.9	84.3	+2.6	B2.7*	80.7	+2.0
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#### \* LOCATIONS EXHIBITED IN FIG. B-7

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		TAB	LE	B-19			
	RA	DIAL CL TEST (MII	TRANS		-	۵)	
	<b>F</b>						
	* NODES	TIME	= 100	> SEC.	TIME	= 280	SEC.
	*NODES STA ROT.				1		
	NODES STA ROT. 410 - 464	STATIC . 61.6	- Rotati 54.9	$NG = (\Delta) + 6.7$	STATIC 54.7	-Rotatin 51.5	
	NODES STA ROT.	STATIC . 61.6	- Rotati 54.9	$NG = (\Delta) + 6.7$	STATIC 54.7	-Rotatin 51.5	G = (∆)
	NODES STA ROT. 410 - 464	STATIC - 61.6 60.6	- Rotati 54.9 56.9	NG=(∆) +6.7 +3.7	Static 54.7 55.7	-Rotatin 51.5	$G = (\Delta)$ + 3.2 + 2.5
	NODES STA ROT. 410 - 464 446- 481	STATIC - 61.6 60.6	- Rotati 54.9 56.9	NG=(∆) +6.7 +3.7	Static 54.7 55.7	-Rotatin 51.5 53.2	$G = (\Delta)$ + 3.2 + 2.5
	NODES STA ROT. 410 - 464 446- 481	STATIC - 61.6 60.6	- Rotati 54.9 56.9	NG=(∆) +6.7 +3.7	Static 54.7 55.7	-Rotatin 51.5 53.2	$G = (\Delta)$ + 3.2 + 2.5
	NODES STA ROT. 410 - 464 446- 481	STATIC - 61.6 60.6	- Rotati 54.9 56.9	NG=(∆) +6.7 +3.7	Static 54.7 55.7	-Rotatin 51.5 53.2	$G = (\Delta)$ + 3.2 + 2.5

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## TABLE B-20

RADIAL CLEARANCE CHANGE ( $\Delta$ ) TEST TRANSIENT E203 (MILS)

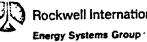
* NODES	ТІМЕ	=  00	SEC.	тіме	= 280	SEC.
STA ROT.	STATIC	- ROTATI	$NG = (\Delta)$	STATIC	-ROTATIN	$\Xi = (\Delta)$
410 - 464	42.9	50.	-7.2	49.7	53.5	-3.8
446- 481	50.9	51.3	-0,4	55.9	55.0.	+0.9
463 - 499	55.1	52.5	+2,6	58.9	56.4	+2.5
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# \* LOCATIONS EXHIBITED IN FIG. 3-7

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# TABLE B-21

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E204 (MILS)

* NODES	ТІМЕ	= 100	SEC.	TIME	= 210	SEC.
STA ROT.	STATIC	- ROTATIN	<b>q=(</b> ∆)	STATIC	-ROTATIN	$\mathfrak{G} = (\Delta)$
410 - 464	70.8	61.6	+9.2	64.3	57.9	+6.4
446- 481	68.6	64.1	+4.5	63.5	60.0	+ 3.5
463 - 499	66.9	65.8	+1.1	62.7	61.5	+1.2
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# \* LOCATIONS EXHIBITED IN FIG. 6-7

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TABLE B-22

RADIAL CLEARANCE CHANGE ( $\Delta$ ) TEST TRANSIENT E207 (MILS)

* NODES	TIME	E = 27	5 SEC.	TIME	= 385	SEC.
STA ROT.	STATIC	- ROTAT	$iNG = (\Delta)$	STATIC	-ROTATIN	$fa = (\Delta)$
410 - 464	70.4	58.6	+11.8	62.9	55.4	+7.5
446- 481	66.0	6.1.0	+5,0	61.1	57.3.	+3.8
463 - 499	63.2	62.6	+0.6	59.8	58.B	+1.0
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\* LOCATIONS EXHIBITED IN FIG. 8-7

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## TABLE B-23

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E20  $\beta$ (MILS)

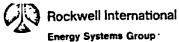
* NODES	TIME	: = 115	SEC.	TIME	= 240	SEC.
STA ROT.	STATIC	- ROTAT	$iNq = (\Delta)$	STATIC	-ROTATIN	$G = (\Delta)$
410 - 464	80-1	69.5	+10.6	72.1	65.6	+ 6.5
446- 481	77.5	72.2	+ 5.3	71.7	67.9.	+3.8
463 - 499	75.4	74.1	+ 1.3	71.0	69.6	+1.4
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#### \* LOCATIONS EXHIBITED IN FIG. 5-7

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TABLE B-24

RADIAL CLEARANCE CHANGE (△) TEST TRANSIENT E 20 (MILS)

* NODES	ТІМЕ	:= 5	O SEC.	TIME	= 150	SEC.
STA ROT.	STATIC	- ROTA	$TING = (\Delta)$	STATIC	-Rotatii	伝=(△)
410 - 464	83.8	77.2	+6.6	78.9	73.1	+ 5.8
446- 481	84.2	80.0	+4.2	79.6	75.6.	+ 4.0
463 - 499	83 <b>.</b> 8	82.0	+ 1-8	79.5	77.6	+1.9
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\* LOCATIONS EXHIBITED IN FIG. B.7

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### TABLE B-25

RADIAL CLEARANCE CHANGE ( $\Delta$ ) TEST TRANSIENT E202 (MILS)

* NODES	TIME	= (00	SEC.	TIME	= 280	SEC.
STAROT.	STATIC	- ROTATIN	G=(∆)	STATIC	-ROTATIN	$G = (\Delta)$
630-677	50.3	51.3	-1.0	49.2	49.2	0,0
64.8-691	51.3	51.6	-0.3	49.3	49.2	+0.1
727-705	53.0	51.7	+1.0	49.6	49.2	+0,4
751-761	52.4	50.9	+2.0	49.4	49.1	+0.3
758-886	50.3	50,3	0	49.1	48.9	+0.2
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\* LOCATIONS EXHIBITED IN FIG. B-9

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# TABLE B-26

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E203 (MILS)

<b>_</b>						
* NODES	TIME	= 100	SEC.	TIME	= 280	SEC.
STAROT.	Static -	ROTATINE	$\dot{a} = (\Delta)$	STATIC	-ROTATIN	$\mathbf{G} = (\Delta)$
630-677	52.5	49.6	+2.9	53.6	52.9	+ 0.7
64.8-691	51.5	49.9	+1.6	53.4	52.9	+ 0.5
727-705	49.8	50.0	-0,2	53.2	52.9	+0.3
751-761	50.4	50.4	0,0	53.2	52.9	+0.3
758-886	52.5	51.5	+1.0	53.5	53.1	+0.4
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\* LOCATIONS EXHIBITED IN FIG. 8-9

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NEEDE HELDERGUING Energy Systems Group N266SR000002 CHECKED BY 100 DATE. MODEL NO. N266ER000-001 Page 469 TABLE B:27 RADIAL CLEARANCE CHANGE ( $\Delta$ ) TEST TRANSIENT E204 (MILS) \* NODES TIME = |00 sec.|TIME = 210SEC. STA.-ROT. STATIC - ROTATING =  $(\Delta)$  STATIC - ROTATING =  $(\Delta)$ 55.7 59.0 -3.3 54.3 630-677 55.2 -0.9 64.8-691 57.1 58.6 -1.5 54.6 55.1 -0.5 727-705 59.4 58.5 +0.9 55.2 55. +0,1 58.6 57.8 751-761 +0.8 55.1 55.0 +0.1 54.4 54.4 55.7 56.2 758-886 -05 0.0 \* LOCATIONS EXHIBITED IN FIG. B-9 N 152-R-2 REV. 8-78

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TABLE B-28

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E207 (MILS)

\* NODES TIME = 275 SEC. TIME = 385 SEC. STA.-ROT. STATIC - ROTATING = ( $\Delta$ ) STATIC - ROTATING = ( $\Delta$ ) 52.4 55.3 -2.9 51.4 52.2 630-677 -0.8 64.8-691 53.5 55.0 -1.5 51.8 52.2 -0.4 727-705 55.4 55.0 +0.4 52.4 52.3 +0,1 54.8 54.5 +0.3 52.3 52.2 751-761 +0. 52.5 53.0 -0.5 51.6 51.6 758-886 0.0

\* LOCATIONS EXHIBITED IN FIG, B-9

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TABLE B-29

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E208 (MILS)

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* NODES	ТІМ	E. = 11	5 SEC.	TIME	:= 240	SEC.
STAROT.	Static	- ROTATI	$NG = (\Delta)$	STATIC	-ROTATI	$NG = (\Delta)$
630-677	62.9	66.6	-3.7	61.8	62.6	-0.8
64'8-691	64.5	66.1	-1.6	62.1	62.5	-0.4
727-705	66.9	660	+0.9	62.7	62,5	+0.2
751-761	66.0	65.3	+0.7	62.6	62.4	+0.2
758-886	63,0	63.6	-0.6	62.0	61.9	+0.1
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\* LOCATIONS EXHIBITED IN FIG. B-9

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	RA	TEST	LEARAN T TRAN ILS)	NCE CHA SIENT	NGE (4 E 210	∆)	
	* NODES	ТІМ	E = 5	Ø SEC.	TIME	= 150	SEC.
	STAROT.	STATIC	- ROTAT	$ING = (\Delta)$	STATIC	-ROTATIN	$G = (\Delta)$
	630-677	71.3	74.3	-3.0	69.4	70.3	-0.9
	64.8-691	72.9	73.8	-0.9	69.7	70.2	-0.5
	727-705	15.3	73.7	-1.6	70.3	70.2	+0.1
	751-761	74.3	73.0	-1-3			+0.1
r	758-886	71.1			69.5	69.4	+0.1
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# TABLE B-31

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E202 (MILS)

* NODES	ТІМІ	E =	SEC.	TIME	***	SEC.
STA STA.	OUTER	- INNER	=(∆)	OUTER	- INNER	$x = (\Delta)$
267 - 266	51.0	47.7	+3.3	47,4	42.0	+5,4
291 - 290	50.9	47.4	+3.5	47.5	41.4	+6.1
335 - 334	50.1	47.0	+3.1	46.1	40,8	+5,3
374 - 373	•	45.6	-		40,5	
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### \* LOCATIONS EXHIBITED IN FIG. B-3

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TABLE B-32

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E203 (MILS)

* NODES	ТІМІ	E =  0	O SEC.	TIME	= 280	SEC.
STA - STA.	OUTER	-INNER	=(∆)	OUTER	- INNER	$(\Delta) = (\Delta)$
267 - 266	32.3	32.3	0.0	35.7	37.9	-2.2
291 - 290	32.4	32.6	-0.2	35.6	38.5.	-2.9
335 - 334	33.	33.0	+0.]	37.0	39.1	-2.1
374 - 373	BB,0	34:3	-1.3	38.3	39.4	-1.1
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\* LOCATIONS EXHIBITED IN FIG. B.3

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TABLE B-33

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E204 (MILS)

* NODES	ТІМІ	E =  00	) SEC.	TIME	= 210	SEC.
STA,-STA.	OUTER	-INNER	= (\Delta)	OUTER	- JANER	= (△)
267 - 266	59.1	54.9	+4.2	56.0	49.0	+6.9
291 - 290	58.9	54.6	+4.3	56.1	48.1	+8.0
335 - 334	57.9	54.0	+3.9	544	47.4	+7.0
374 - 373	57.9	52.2	+5.7	53.	46.6	+6.5
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\* LOCATIONS EXHIBITED IN FIG. B.3

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	* NODES	тім	E = 21	5 SEC.	TIME	= 385	SEC.
	STA-STA.	OUTER	- INNER	$\mathcal{R} = (\Delta)$	OUTER	- INNER	= (△)
	267 - 266	63.0	54.4	+ 8.4	58.5	48.6	+ 9.9
			53.2		58.7		+11.6
	335 - 334 374 - 373	60.4	52.1	+8.3	55.5	46.0	+ 9.5
	374 - 373	58.9	50,3	+8.6	52.8	45.2	+ 7.2
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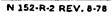
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# TABLE B-35

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E208 (MILS)

* NODES	ТІМІ	E = 115	SEC.	TIME	= 240	SEC.
STA STA.	OUTER	-INNER	=(△)	OUTER	- INNER	$x = (\Delta)$
267 - 266	67-1	62.0	+ 5.1	63.2	55.2	+ 8.0
291 - 290	67.0	61.5	+5,5	63.3	54.1	+9.2
335 - 334	65.7	60.8	+4.9	61.3	53,3	+8.0
374 - 373	65.6	58.8	+6.8	59.6	52.6	+7.0
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### \* LOCATIONS EXHIBITED IN FIG. B.3



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## TABLE B-36

RADIAL CLEARANCE CHANGE  $(\Delta)$ TEST TRANSIENT E 20 (MILS)

* NODES	тімі	E = 50	SEC.	TIME	= 150	SEC.
STA - STA.	OUTER	-INNER	=(△)	OUTER	- INNER	= (△)
267 - 266	68.2	65.1	+3.1	66.2	60,2	+ 6.0
291 - 290	68.1	65.0	+ 3.1	66.2	59.8.	+ 6.4
335 - 334	67.4	64.7	+2.7	65.0	58.9	+6.
374 - 373	67.8	63.1	+4.7	64.2	58.1	+6,
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\* LOCATIONS EXHIBITED IN FIG. B-3

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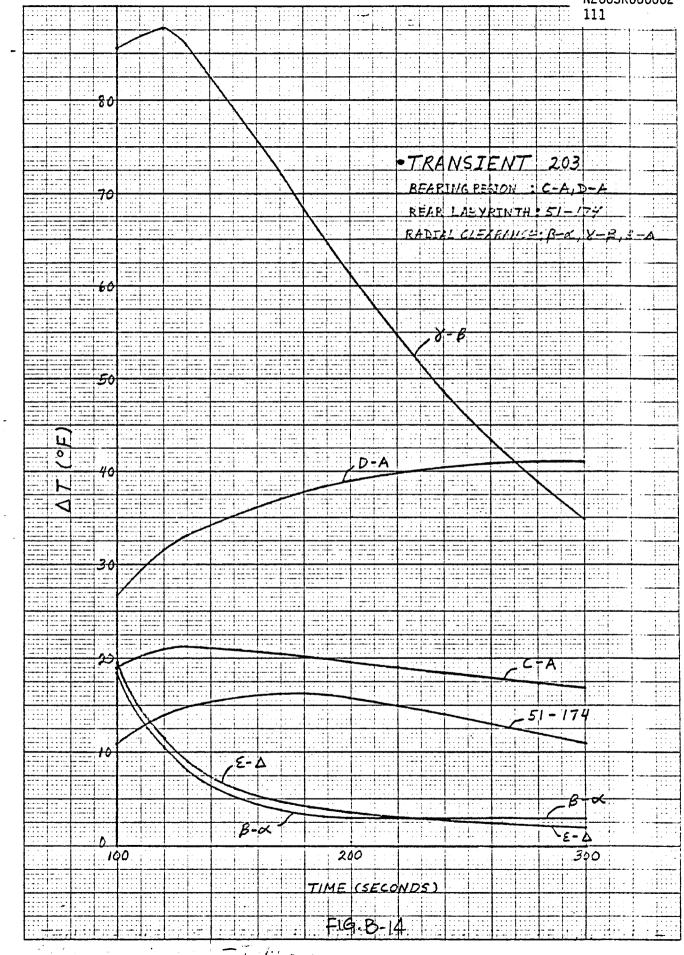
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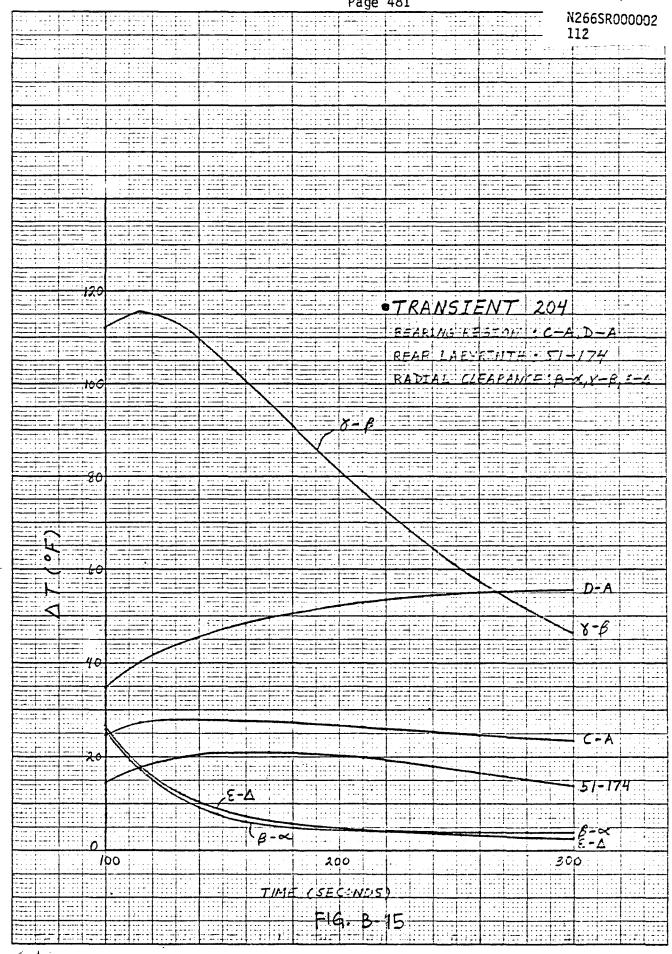


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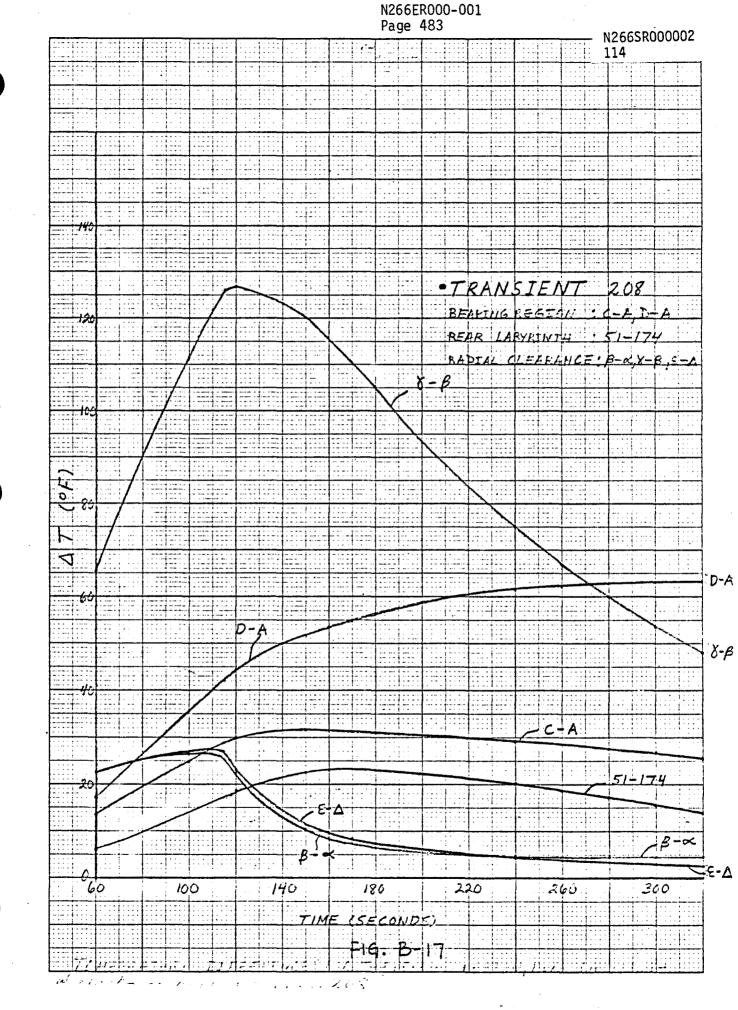
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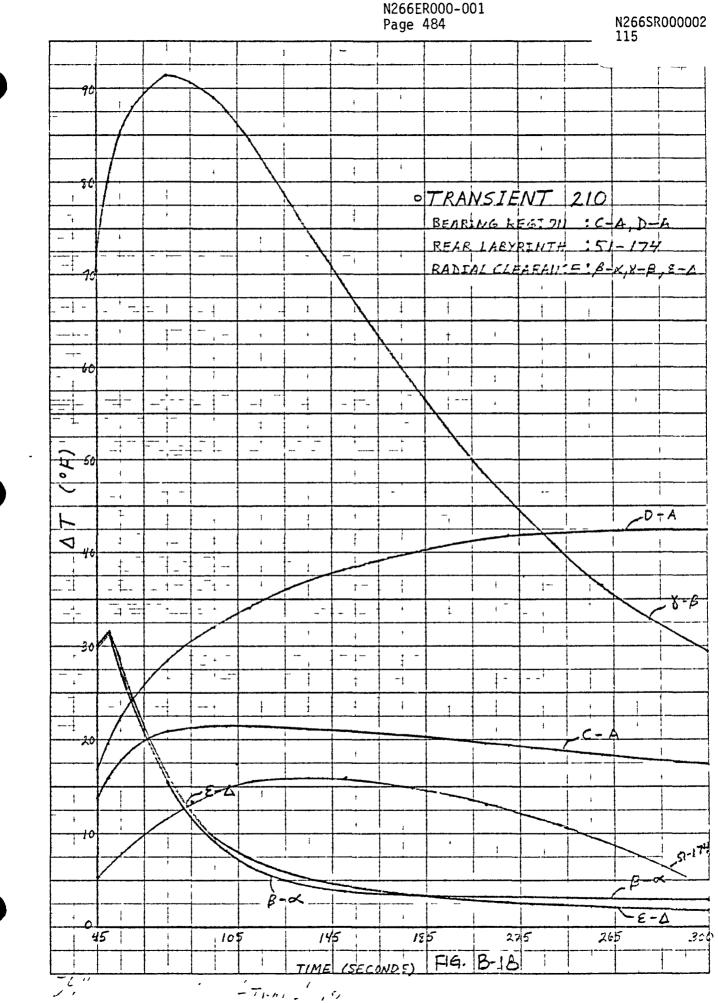
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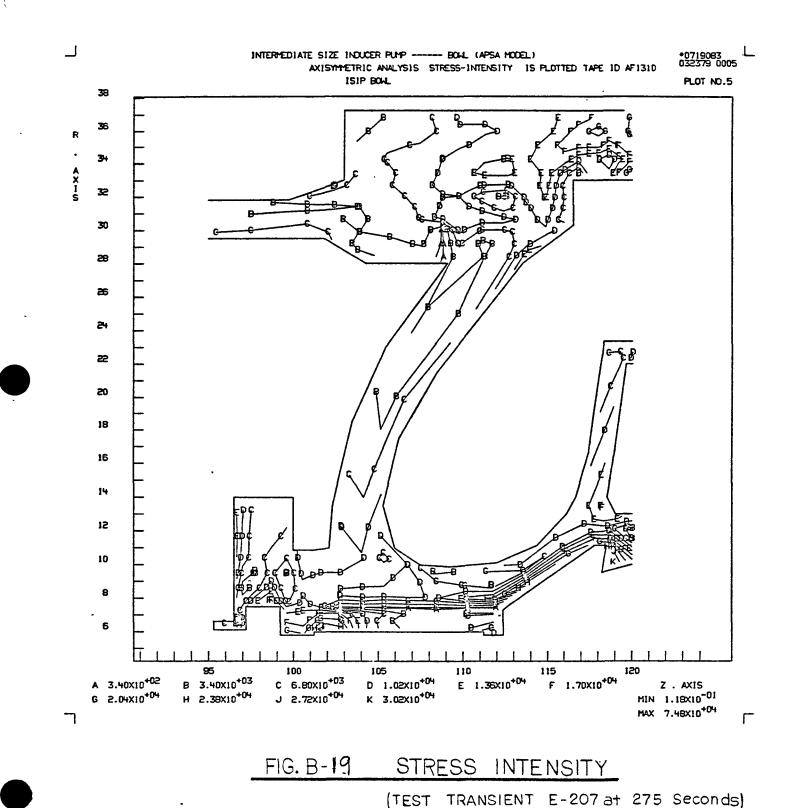
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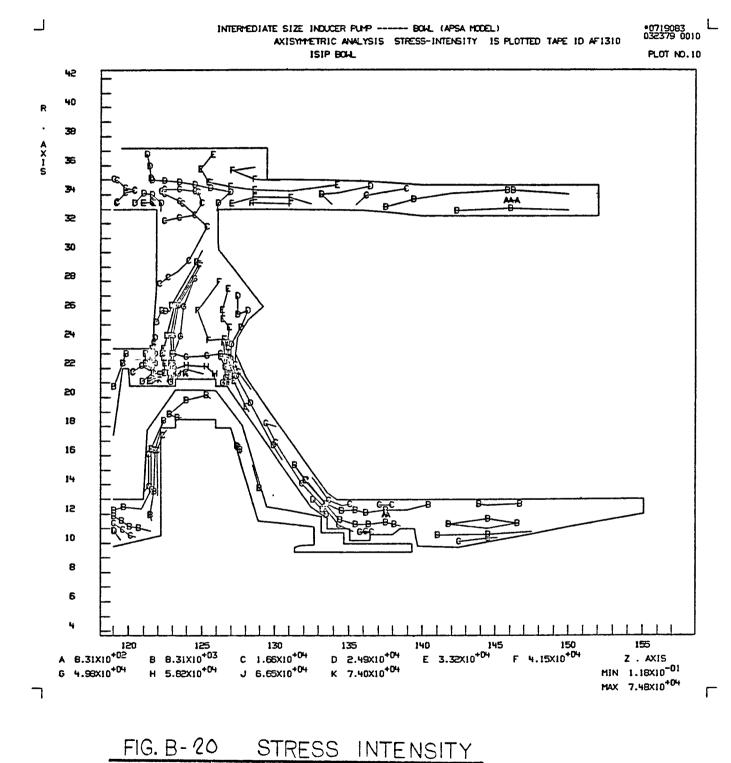
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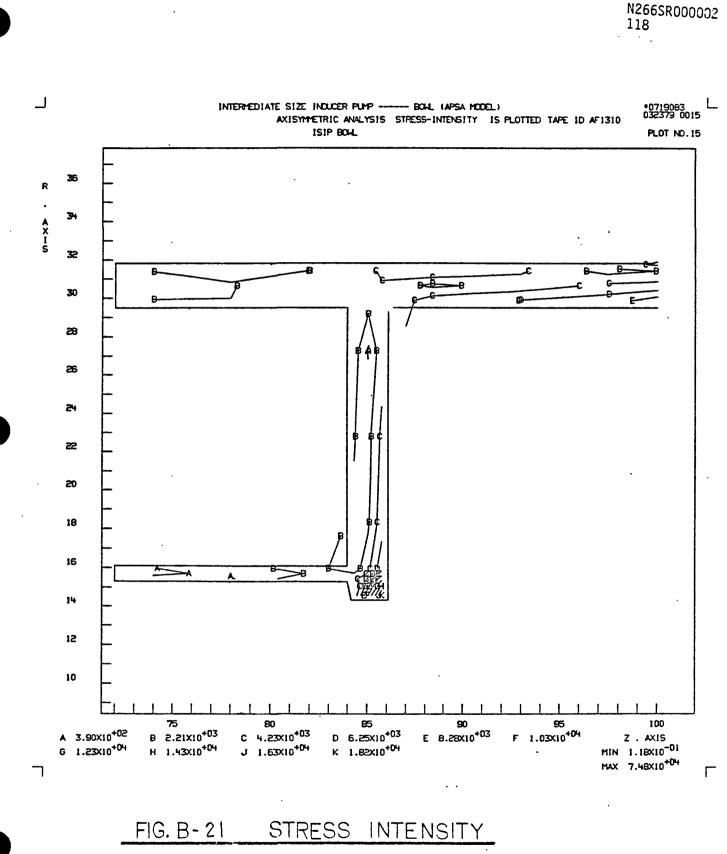
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(TEST TRANSIENT E-207 at 275 Seconds)

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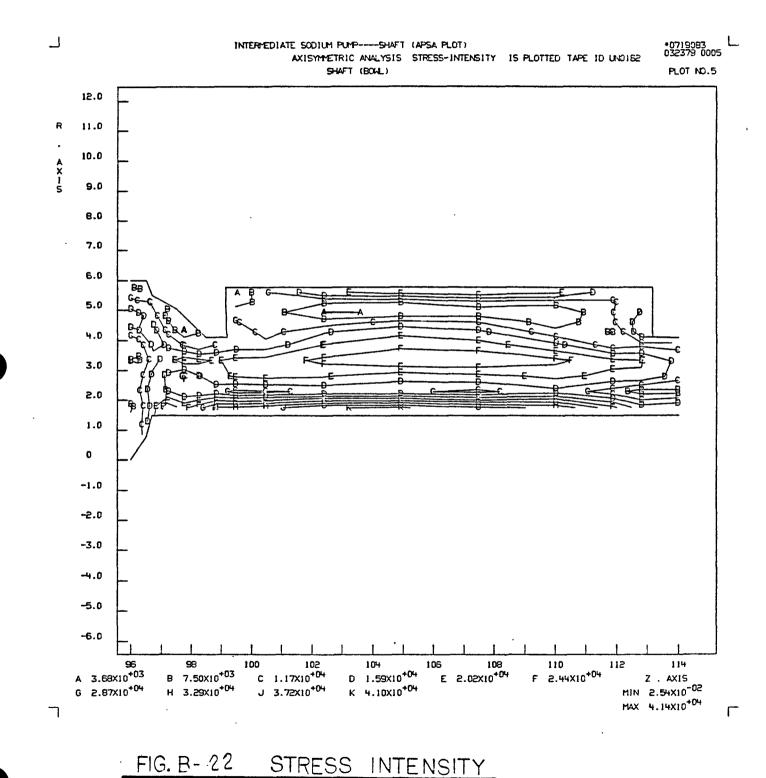


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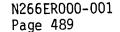
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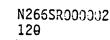
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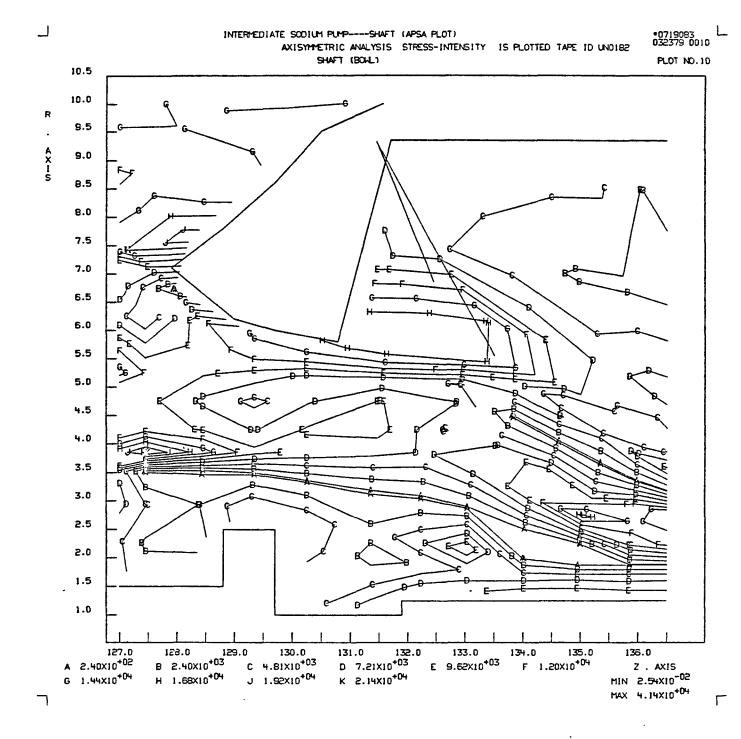


FIG. B-23 STRESS INTENSITY (TEST TRANSIENT E-207 at 275 Seconds)

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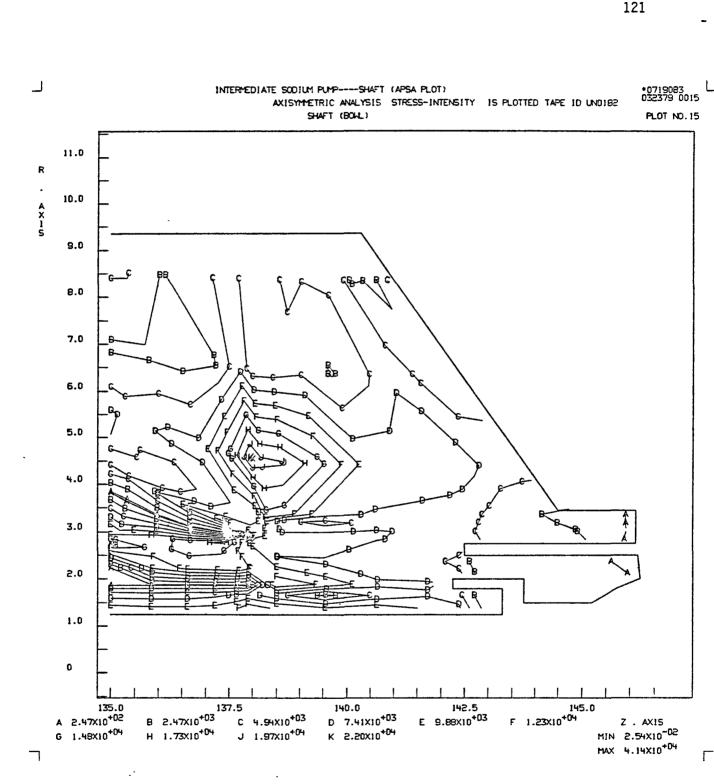


FIG. B-24 STRESS INTENSITY (TEST TRANSIENT E-207 at 275 Seconds)

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TABLE B-37

#### THERMAL TRANSIENTS

Transient Number*	Sodium Flow Rate (gpm)	Initial Temp. F	Final Temp. F	ΣΔΤ F	odT/dt <sup>o</sup> F/sec
201					
- 202	14500	750	600	-150	-1.5
203	14500	500	650	+150	+1.5
204	14500	850	650	-200	-2.0
205					
206			•		
207	14500	950 <del>**</del>	620 <sup>*</sup> *	-330	-1.2
208	14500	950**	725** <sub>.</sub>	-225	-2.0
210	14500	950**	800**	-150	-3.0

\*From Specification N266ST310001, Table 4-II (Ref. 6 )

\*\* Note see Reference 9



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#### APPENDIX C

#### COMPUTER PROCEDURES FOR STRUCTURAL AND THERMAL DEFORMATION ANALYSIS

#### References

- J. F. Newell and S. F. Persselin, "Finite Element Axisymmetric and Planar Structural Analysis," SSME 74-1282, Rocketdyne Division, Rockwell International, Canoga Park, California 91304, April 18, 1974
- H. C. Hsiung, "Computer Procedures to Make Thermal Stress Runs Using the APSA Computer Code," IL 600-77-216, Atomics International Division, Rockwell International, Canoga Park, California 91306, June 13, 1977

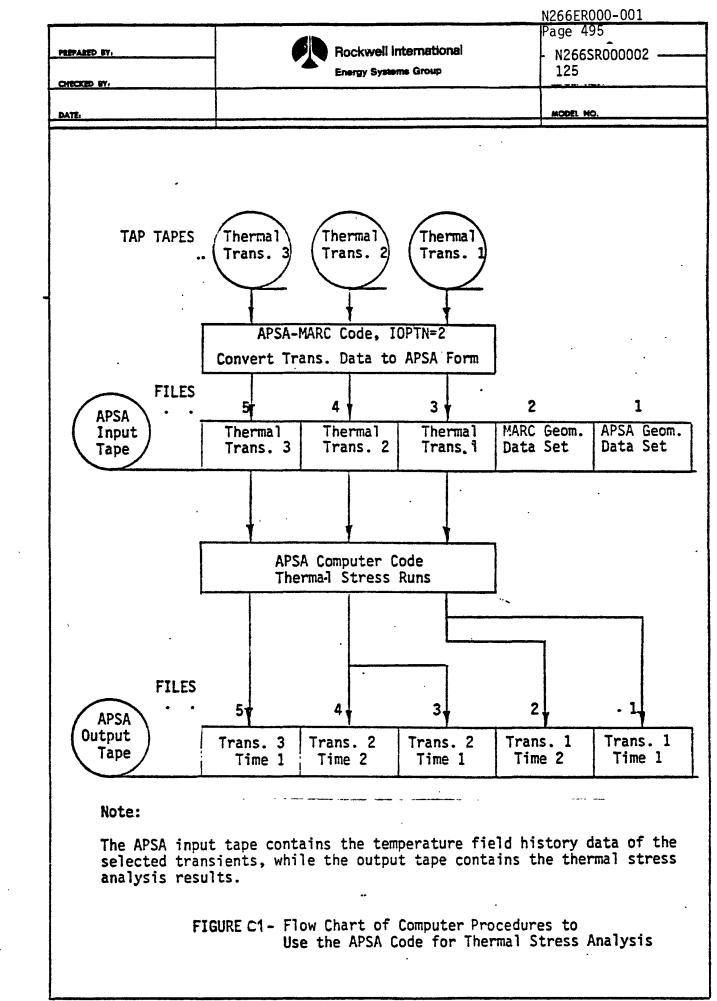


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In the evaluation of structural and thermal deformation analyses for ISIP. APSA-Mark Interface Computer Code has been utilized to input thermal transient data into APSA finite element program. TAP (Thermal Analysis Program) was used to determine critical temperature difference  $(\Delta T)$  through the time-history iteration of each transient for various cross section of pump components. The critical temperature field and time slices of each transient were then used as input for calculating thermal stress and deflection in APSA program. Figure C1 shows the flow chart of computer procedure used. The basic purpose using APSA-Mark Interface Computer Code was that the two programs have different purposes of usage. The computer input cards setup is shown in Figures C2, C3, and C4. Figure C2 shows the coordinates input of temperature field nodes from TAP tape into APSA tape File 1. Figure C3 is the setup for storing TAP temperature field and time slices in APSA tape File 2. APSA finite element model uses the temperature time slice from File 2 for determining the stress and deflection as shown in Figure C4.

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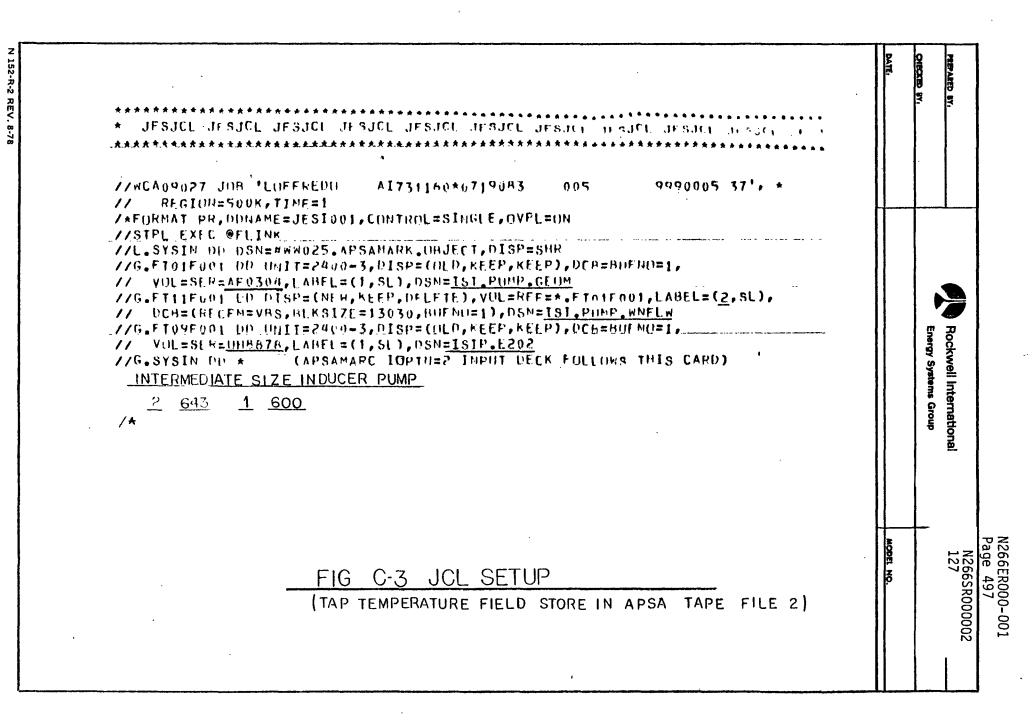
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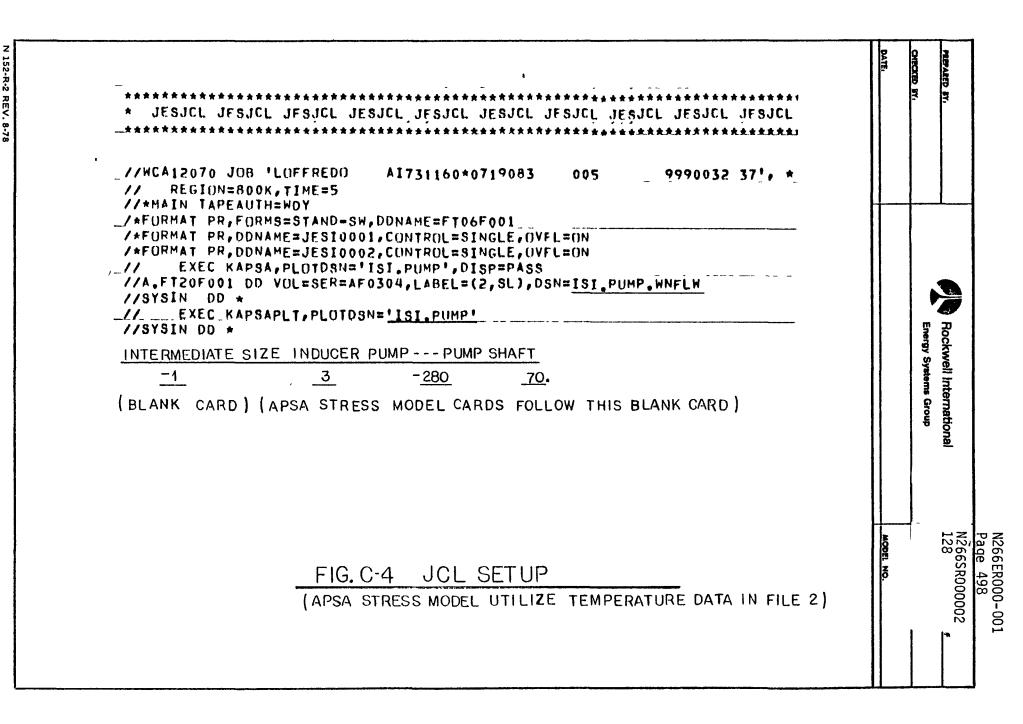


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// LXEC PG4=TEBGENER			
//SYSIN DD DUMMY //SYSPRINT DD SYSOUT=A			
//SYSUT2 DD UHIT=3400-3.DISP=(NEW,KEFP.DELFTF).DSN=ISI.PUHP.GEDM, // DCB=(RECFM=FB.LRECL=80.BLKSTZE=6400)		5	Ro
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#### APPENDIX J

#### TRANSIENT THERMAL ANALYSIS OF ISIP

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#### I. INTRODUCTION AND SUMMARY

The purpose of this study is to evaluate the transient thermal behavior of the intermediate size inducer pump (ISIP) during the six thermal transients.

An overall thermal model (Figure 2) has been set up for the pump based on the drawing of Figure 1 (Reference 1).

Approximately 10 thermal transients are indicated in the specification (Reference 2). Of these, six were analyzed, some with minor temperature modification, as discussed in Reference 3. Table I shows the updated pump design point, and Table II shows the list of six transients that were analyzed.

The basic pump frame for the ISIP is from the FFTF prototype pump. Some of the pump internals have been changed according to the Rockwell International design. The changes included new inducer, impeller, diffuser, and other necessary adapter hardware. The original impeller has been replaced.

The results of the thermal analysis are stored on magnetic computer tape (corresponding to the nodal model of Figure 2). Some of the results are summarized in the figures of this report.

The purpose of the analytical effort (both thermal and structural) is to establish the pump's capability to withstand thermal transients without damage or alternatively, to indicate that particular transients must not be run in the test program.

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# TABLE I HYDRODYNAMIC DESIGN POINT

Flow Rate	14,500 gpm
Total Head Across Pump	500 ft
Shaft Speed	1,100 rpm
Type of Fluid	Sodium
Maximum Inlet Transient Temperature	950 <sup>0</sup> F
Minimum Inlet Transient Temperature	600 <sup>0</sup> F

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TEST THERMAL TRANSIENTS

TRANSIENT NUI IBER	SODIUM FLOW RATE (gpm)	INITIAL TEMP. °F	FINAL TEMP. °F	Σ.ΔT ° F	dT/dt. °F/sec	CRITICAL TIMES (SEC)
202	14500	750	600	-150	-1.5	100 280
203	14500	500	650	+150	+1.5	100 280
204	,14500	850	650	-200	-2.0	100 210
207	14500	950	620	-330	-1.2	275 385
208	14500	950	725	-225	-2.0	115 240
210	14500	950	800	;-150 1	-3.0	50 150

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Thermal analysis was conducted using the TAP computer program package. A conservative two-dimensional model (Figures 2 and 3) was constructed to simulate the geometry of the ISIP. Symmetry was assumed in setting up the model. In Reference 9, calculations were made with this model and the results compared with FFTF tests. These results verified the validity of this model.

The design specification for the thermal model required the ISIP to withstand the specified thermal transients. The effects of thermally induced stresses and deflections must be evaluated.

Figure 3 shows the nodal network and flow pattern for the sodium nodes. Flow paths were obtained from Reference 4. Flow conditions are discussed in Appendix A. The sodium flow pattern is built into the model.

The overall thermal model of the ISIP was set up based on Figure 1. The thermal model in Figure 4 was processed using the STAMP program (Reference 5) generating the nodal network with the areas, form factors, and nodal volumes for use in the TAP program (References 6 and 7). Additional supporting calculations are shown in Appendix A. These include form factor calculations for the inducer, impeller, diffuser, sodium flow node volumes, and heat transfer coefficients.

The thermal properties of sodium were taken as constant as shown in Appendix A. The properties of the stainless steel and sodium were taken from Reference 8. The thermal conductivity and thermal capacity for the stainless steel were input into the TAP program as functions of temperature.



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Heat transferred by mass transport between volumes was accounted for by fluid channel elements. For these, specific mass flow rate and direction were specified by Reference 4. Pump bowl and pump casing wall outer surfaces were assumed adiabatic. The inlet nozzle was added to the network generated by hand as shown in Figure 2.



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#### 111. DISCUSSION OF RESULTS

The results of the transients computer runs are stored on magnetic tapes, as indicated in Table III. The data now shown on the computer output sheets or CRT's can be retrieved a a later time. Also, the data can be called from the tapes for use with the APSA program for stress and deflection analysis.

The critical times for thermal deflection (i.e., when the deflection is a maximum) during transients has been determined. This determination has been made for three different locations: (1) AI modification, (2) rear labyrinth, and (3) bearing region.

#### AI MODIFICATIONS Α.

Figure 5 shows the relative position of the ISIP new hardware. This includes the impeller, inducer, shaft nut, and tie bolt. The weighted temperature for each of the four components were plotted versus time. It can be seen that for each of the six transients in Figure 6 through Figure 11, the greatest temperature difference occurs between the impeller and the shaft nut. Thus, the critical time is taken to be when the greatest temperature difference occurs. Figure 12 shows some thermal nodes at particular places, tie bolt, inducer, and inducer tunnel. The temperature differences across the tie bolt, inducer, and inducer tunnel can be seen on Figures 13 through 15. Figure 16 shows subdivisions of the ISIP for the rotating and nonrotating parts with their nominal radial clearances.

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# TABLE III TRANSIENT TEMPERATURE DATA

Transient Number	Tape Name	Tape Volume Serial Number
202	ISIP.E202	UH 8878
203	ISIP.E203	UG 5728
204	ISIP.E204	UP 8892
2^7	ISIP.E207	AE 9996
208	ISIP.E208	UP 7819
210	ISIP.E210	UL 1717

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#### B. REAR LABYRINTH

Figure 17 shows the position of the rear labyrinth with its respective radial clearance. For temperative deflections, Nodes 174 and 51 were chosen for the nonrotating part and rotating part, respectively.

#### C. BEARING REGION

For radial thermal deflection, Figure 18 shows the subdivisions of the bearing region. Temperature differences between the shaft and the bearing, shaft and the bearing support and bearing were plotted as functions of time.

The results of the thermal analysis were made available to the stress unit. On the basis of temperature differences for the three regions discussed above, the critical times for thermal deflections were determined. The temperature distributions for these time slices are employed by the stress analyst to determine stress distributions and gap defelctions. Two critical times were determined for each of the six transients. Appendix B shows the thermal deflections for each of the six transients (Reference 10).

The individual transients are discussed below.

#### 1. Transient 202

It is a down transient. The first cirtical time, 100 sec after the start of the transient, was selected for the region of the inducer and impeller (Figures 6 and 13) and for the radial clearance of the blade and the static assembly (Figure 19). The second critical time (280 sec) Rockwell International Energy Systems Group

was determined for the bearing region. For the rear labyrinth region, the time was determined to be 180 sec. However, the highest temperature difference at this particular time is only  $16^{\circ}$ F, and the gap has a radial clearance of 50 mils.

### 2. Transient 203

This is the only up transient. The slope of the transient  $(1.5^{\circ}F/sec)$  is the same value as in Transient 202. Due to the same identical conditions (but different startup temperatures), the critical times were found to be the same as in Transient 202, that is at 100 and 280 sec. It can be seen from Figures 7, 13, and 20, that the temperature differences for the three separate regions are essentailly the same as Transient 202 except for a change in sign.

#### 3. Transient 204

It is a down transient. The first critical time (100 sec) was selected for the inducer and impeller (Figures 8 and 14) and for the radial clearance of the blade and the nonrotating part of the ISIP (Figure 21). The second critical time was dtermined to be 210 sec. At this time, the bearing region and rear labyrinth portion have temperature differentials of 94% and 95%, respectively, of their peak values.

### 4. Transient 207

This is a down transient with the greatest overall temperature change (nominally  $330^{\circ}$ F). According to Figures 9, 14, and 22, the first critical time was determined to be 275 sec for the new hardware of the ISIP. At this time, the rear labyrinth region at 96% of its peak value (Figure 22). For the bearing area, the time chosen was 385 sec. Both temperature differentials are over 95% of their peak values at t = 385 sec.



#### 5. Transient 208

The weighted temperature and temperature differences for the down Transient 208 can be seen in Figures 10, 15, and 23. The first critical time was determined to be 115 sec for the inducer and the impeller region. The second critical time was determined to be 240 sec for the bearing portion and the rear labyrinth area (Figure 23).

#### 6. Transient 210

This is the down transient with the steepest slope, dT/dt (nominally  $-3.0^{\circ}$ F/sec). Figures 11, 15, and 24 show the first ciritcal time to be 50 sec for the new hardware area. The second critical time was determined to be 150 sec for the rear labyrinth portion and the bearing region.

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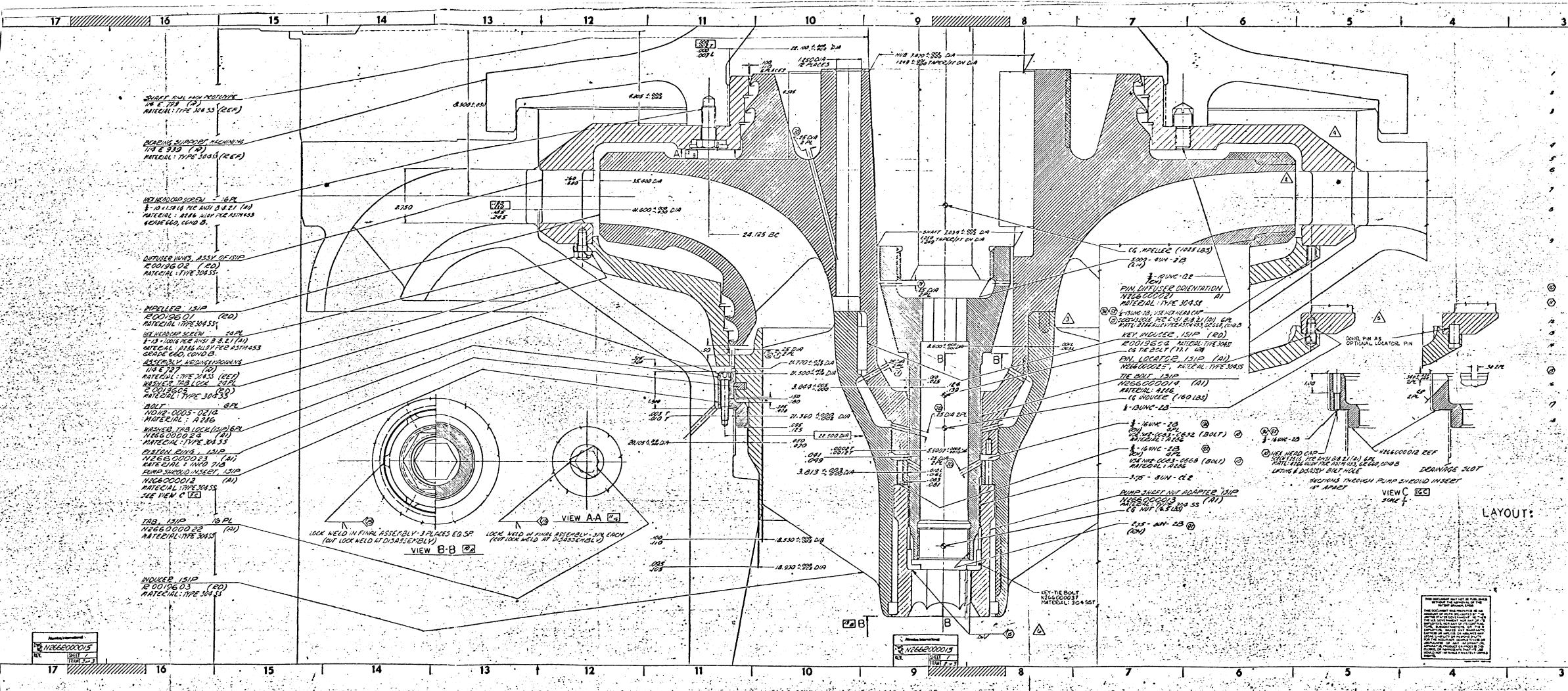


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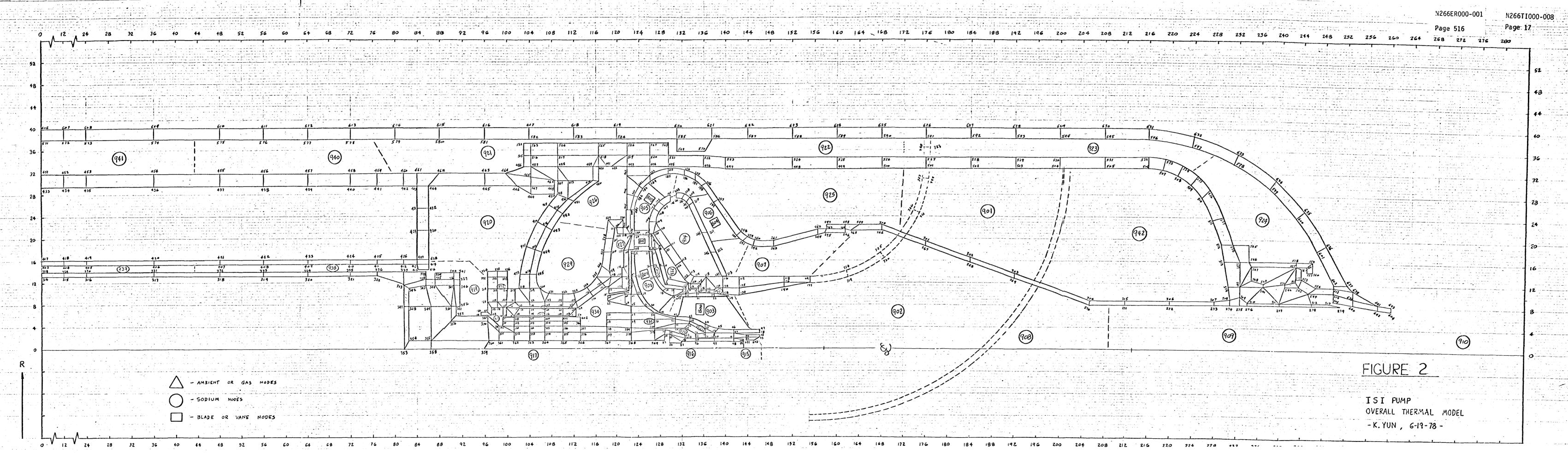
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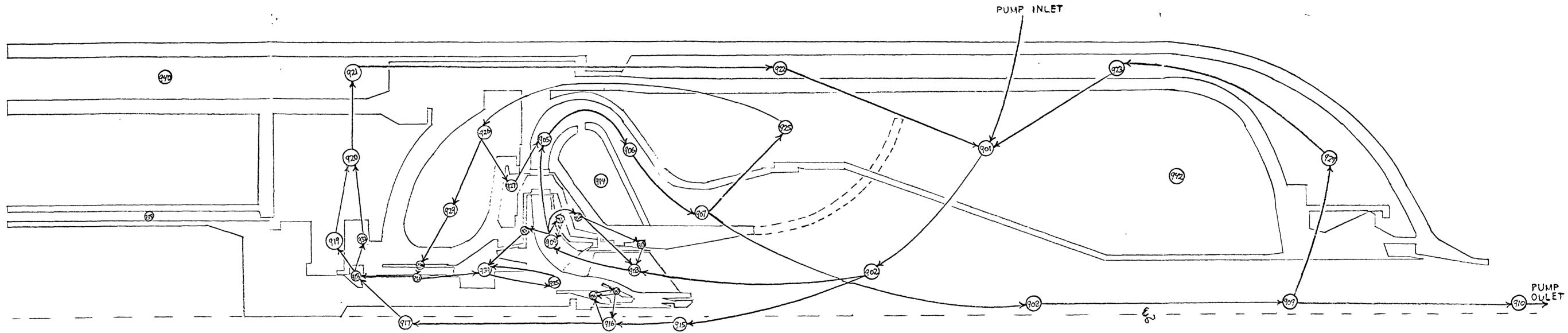
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N266TI090-C08 N266ER000-001 SIONS CO. 503090 BESCHITTON A SEE CENSION RECCED Page 515 NOTES UNLESS OTHERWISE SPECIFIED THIS LATOUT IS BASED ON WESTINGHOUSE COMPONENTS MODIFIED BY READER PER DEAMING N266 SK 000017 (AI) INTERFILE CONTROL DIMENSIONS PER N266E000002 (AI. TURRAINCE STUDY PER N266 SK000011 (AI) CRIGIN SYMBOLS OF REFERENCED DRAWINGS : (AI) ATOMOS INTERNATIONAL (R) RESTINGHOUSE ELECTRIC CORPORATION ASSEMBLY LAD DISASSEMBLY PER CMM-051-00-005, REVISION 2 ADDENDUMI DYNAMIC EALANCE OF ECTATING PARTS PER SPEC N2665T 2700001/A TITE LOCATION OF MATERIAL AVAILABLE FOR MACHINING TO EALANCE A COMPONENT PASSAGE FOR D VENTING 62 DEAINING DIMENSION INT 15 TO BEREAD : MAN TIGHT (INTERFERENCE XXXL YYY LOOSE (MEARANCE FIT); FITS ARE GIVEN PER DIAMETER. PEONISIONS FOR ASSEMBLY DISASSEPBLY HANDLING (HOISTING) TOCLING REPOVE IN FURTL ASSEMBLY CORRELATION OF DIFFUSER VANES TO BE ESTABLISHED PER DRAWING NIEGS SKOODOIT GIN 5,6 47. CALCULATED VOLUME OF RESIDUAL SODIUM IN UNDEAINED POCKETS 48.2 INS. SYMBOL & INDICATES CENTER OF GRAVITY E PITS DE BASED ON ARITHMETIC AVERAGE OF SIZES BY MEASUREMENT OF AS BUILT . COMPONENTS; OTHER FITS ARE BASED SH CRAWING SIZES AND THEIR TOLERANCES. FER EPECIFICATION MODIADIOTOON VISUALLY INSPECT 5× MAG AL CLAPSWENTS OF THE ASSEMBLY TO BE CLEANED PER NOOTAOHOOD LEVEL 3. CONSTRUCT TO THE ECOULESCENTS OF THE SPECIFICATION NO NEEDS TO SIGOD! LAYOUT PER SPECIFICATION N266 ST310001 FIGURE INTERMEDIATE SODIUM PUMP NDUCER. MICROFILMED REDUCED DRAWING RELEASED . ميلينون DEDETROS DEPT. - F. ENCER S HOT ASY THE TOTAL AND A SECONDARY AND A SECOND Rockwell International Corporation Atomics International Division





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N266TI000-008 Page 18

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FIGURE 3

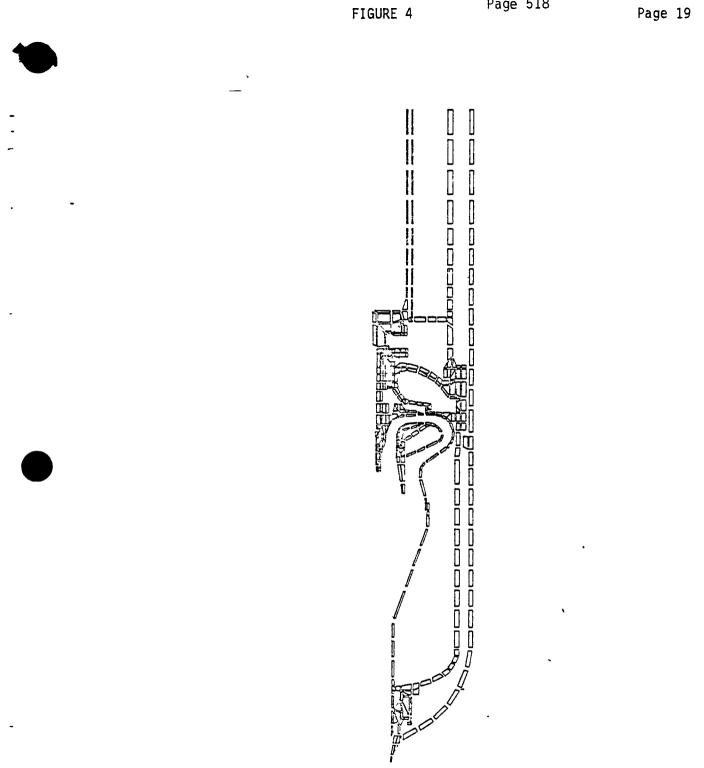
FLOW PATTERN FOR

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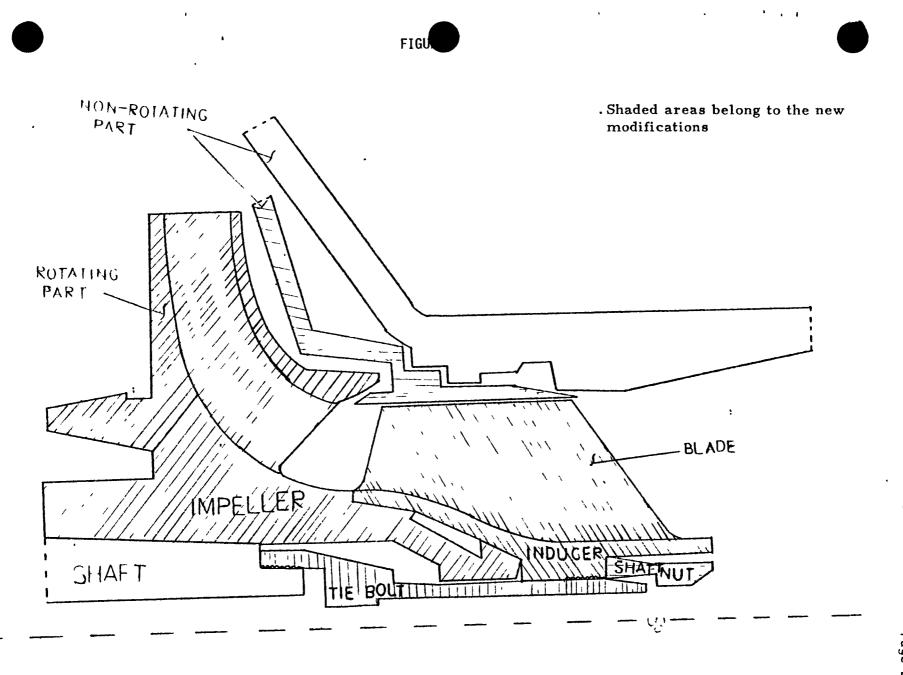


STAMP OUTPUT CRT (ISIP)

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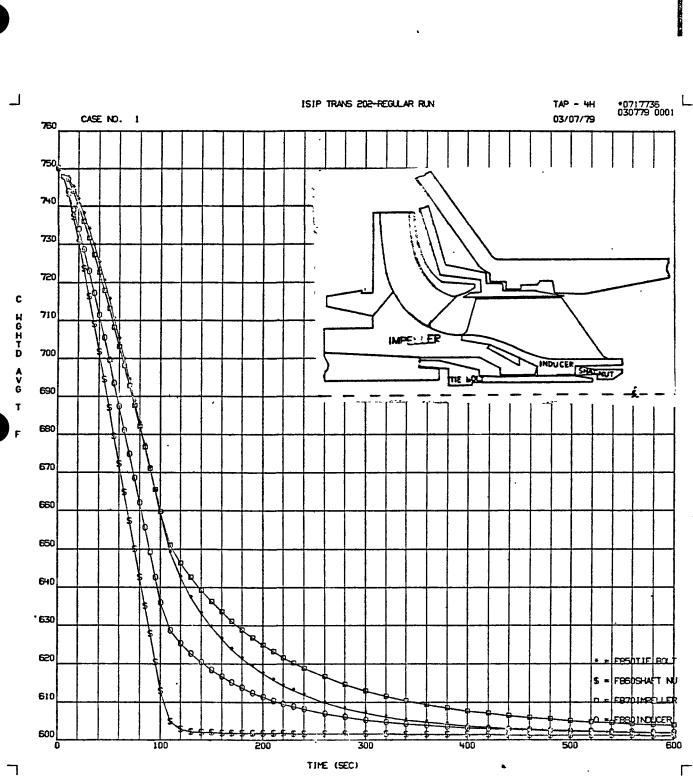


ISIP NEW HARDWARE

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WEIGHTED AVERAGE TEMPERATURE - TRANS 202

FIGURE 6

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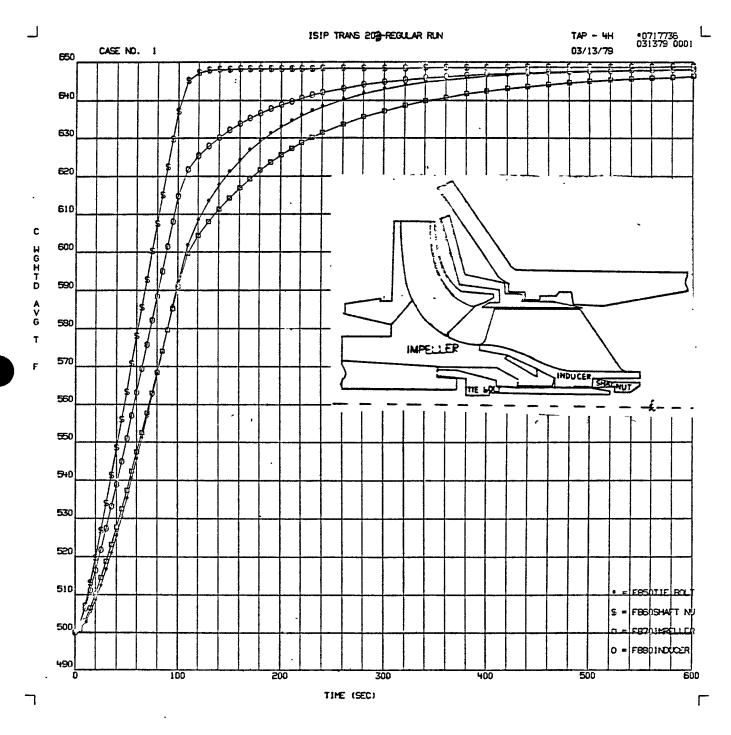
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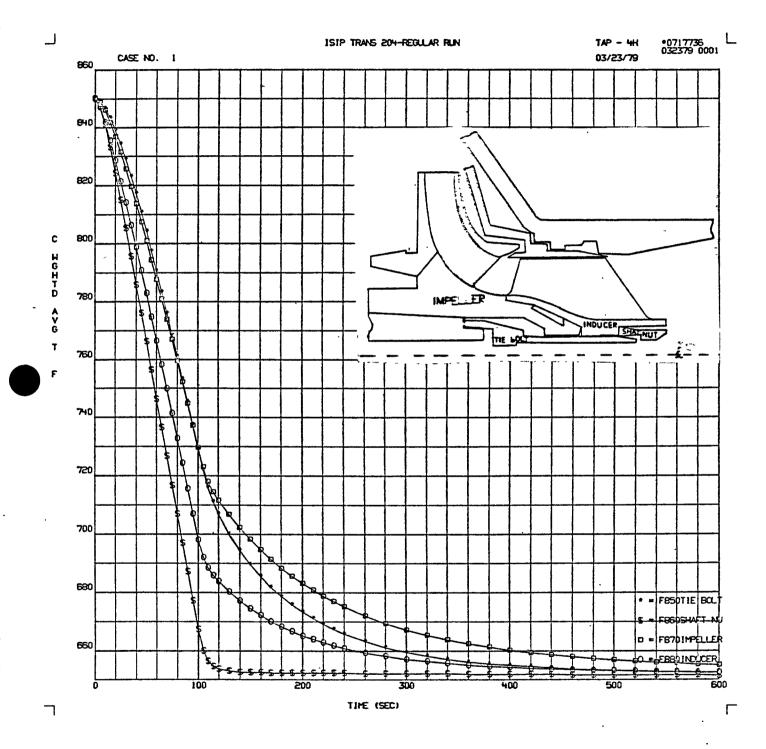
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N266ER000-001 N266TI000-008 Page 522 Page 23

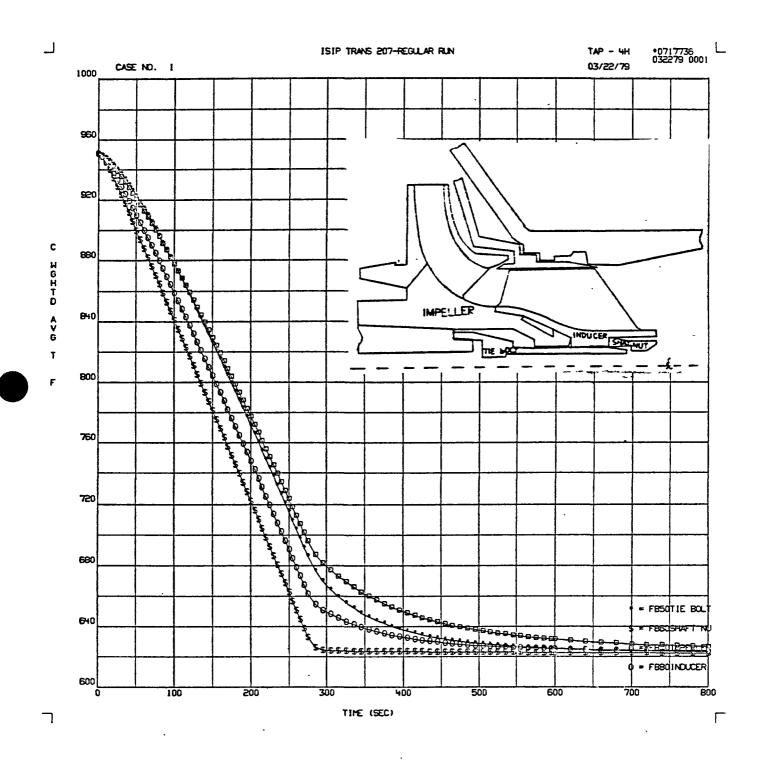


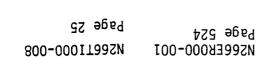


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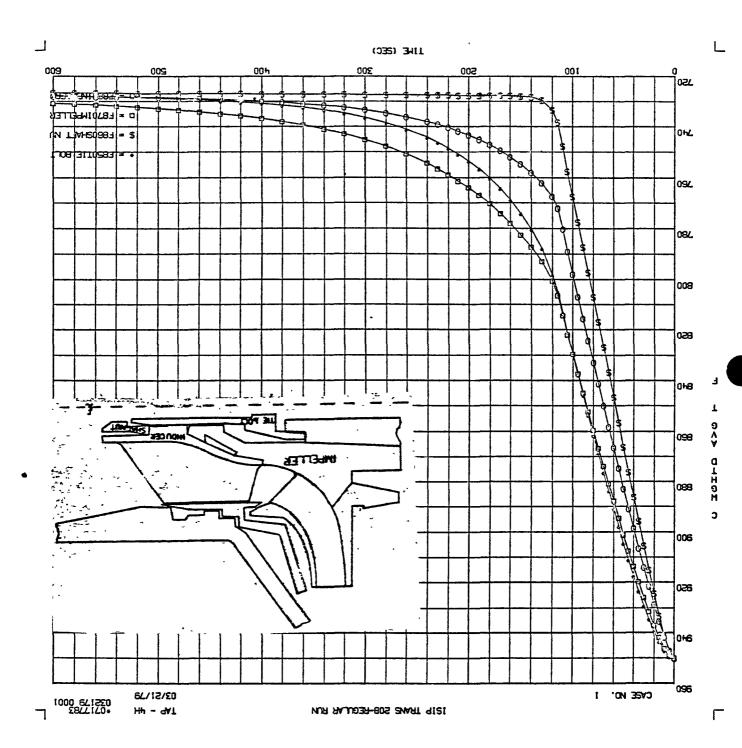
N266TI000-008 Page 24









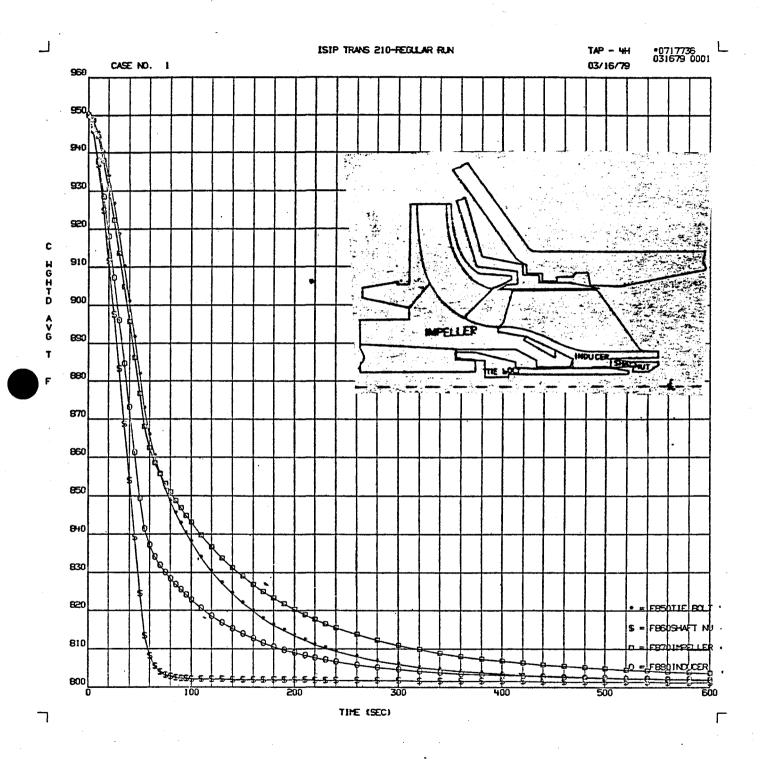


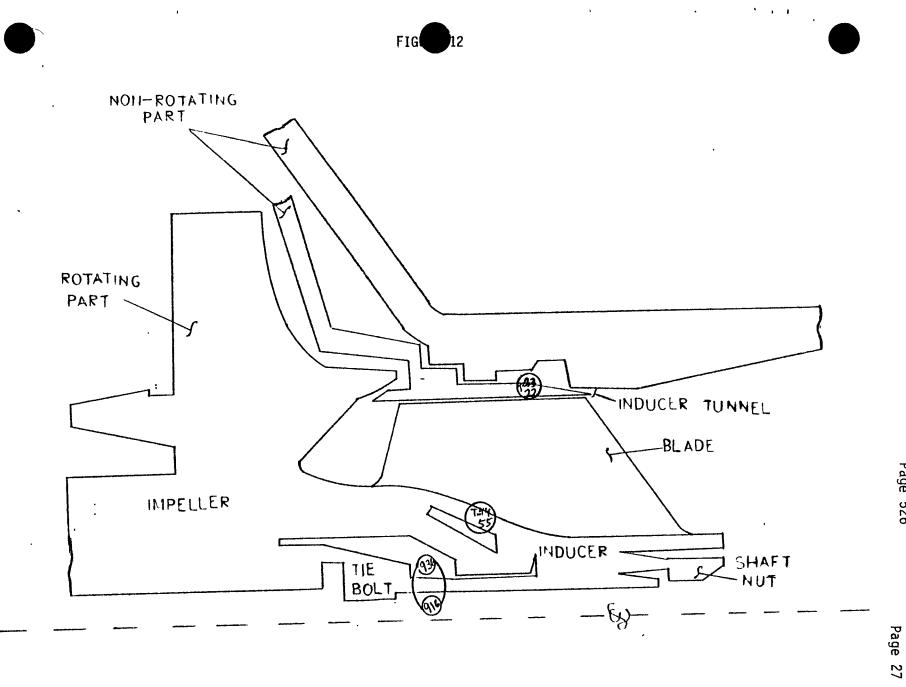
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Page 26

# FIGURE 11

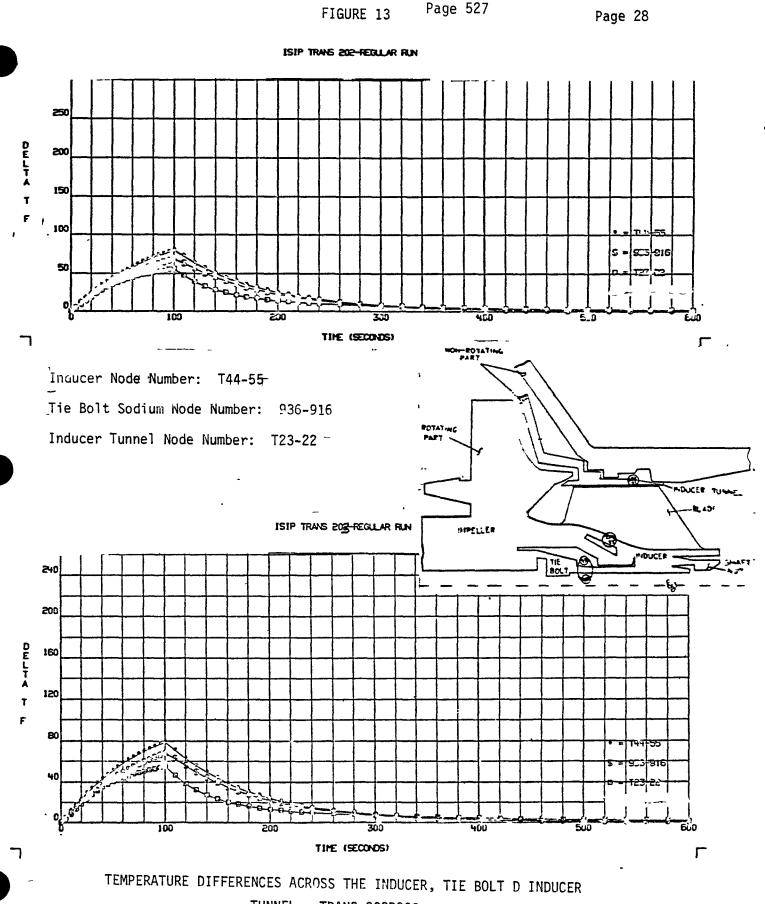




NODE NUMBER ACROSS INDUCER, TIE BOLT, AND INDUCER TUNNEL

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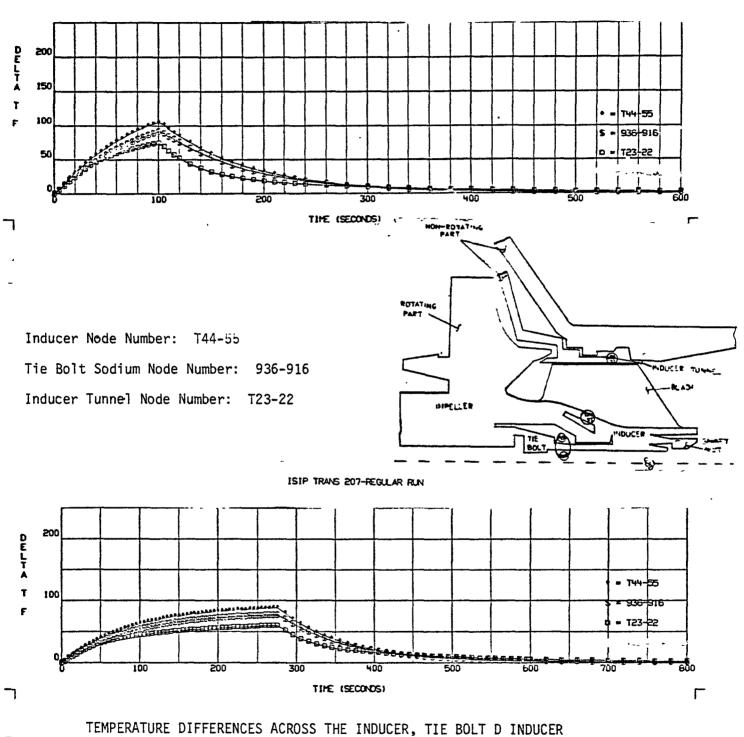
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FIGURE 14

ISIP TRANS 204-REGULAR RLN



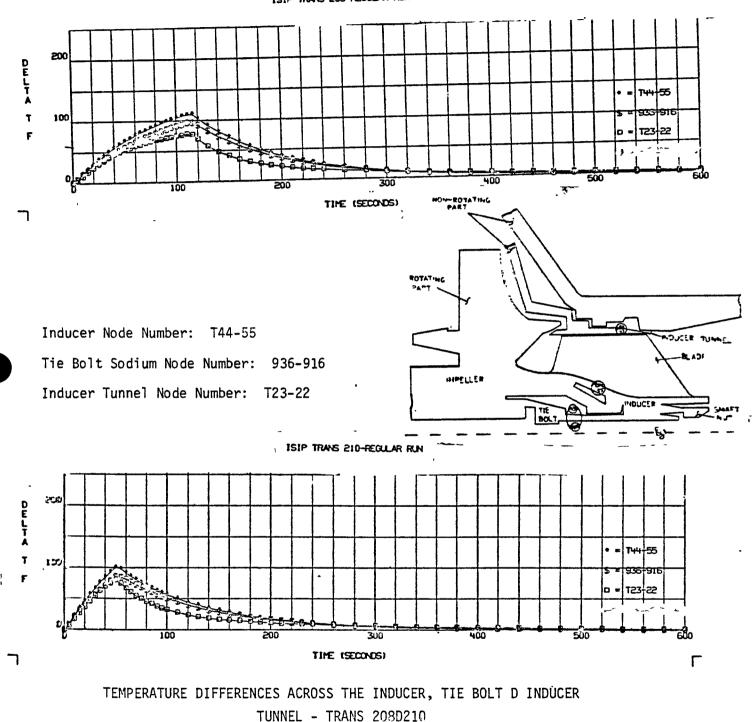
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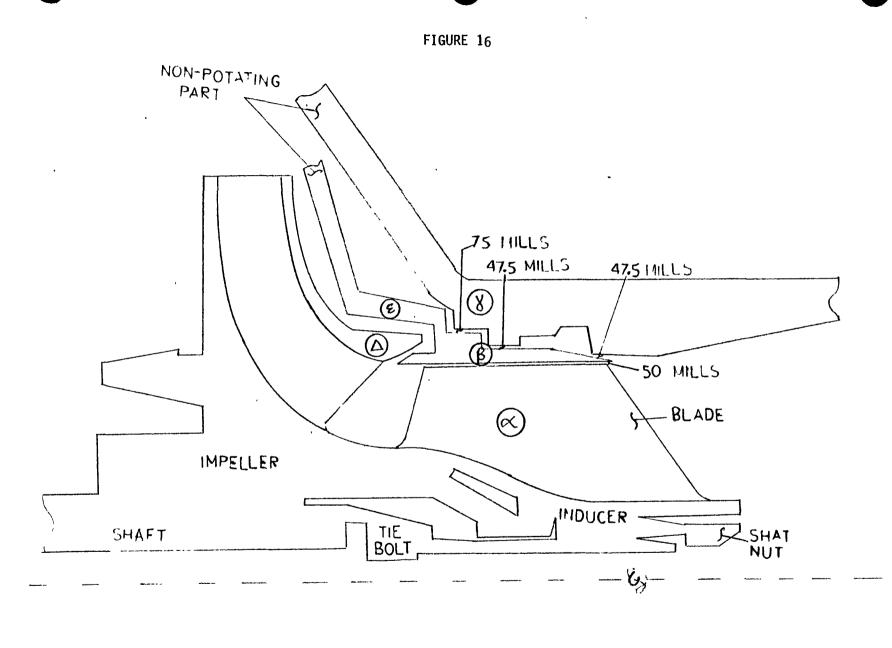
N266ER000-001 Page 529 N266TI000-008 Page 30

FIGURE 15

ISIP TRANS 200-REGULAR RUN



ISIP-THERMAL EFFECT ON RADIAL CLEARANCE



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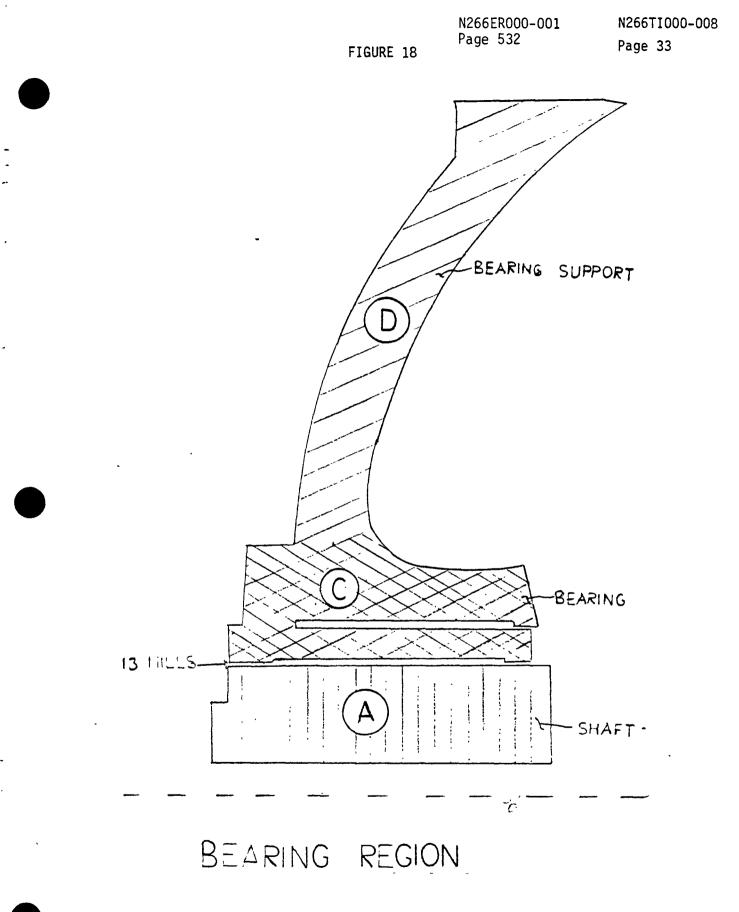
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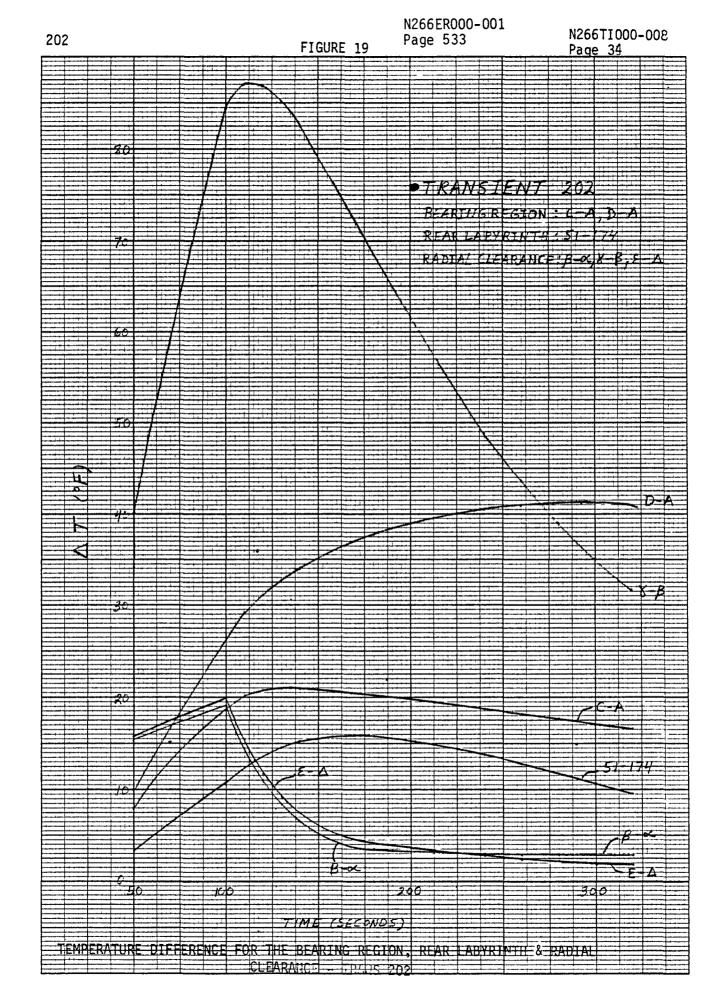
NON-ROTATING (174) 50 Mil 4 (51) ROTATING PART . 5. j.

FIGURE 17

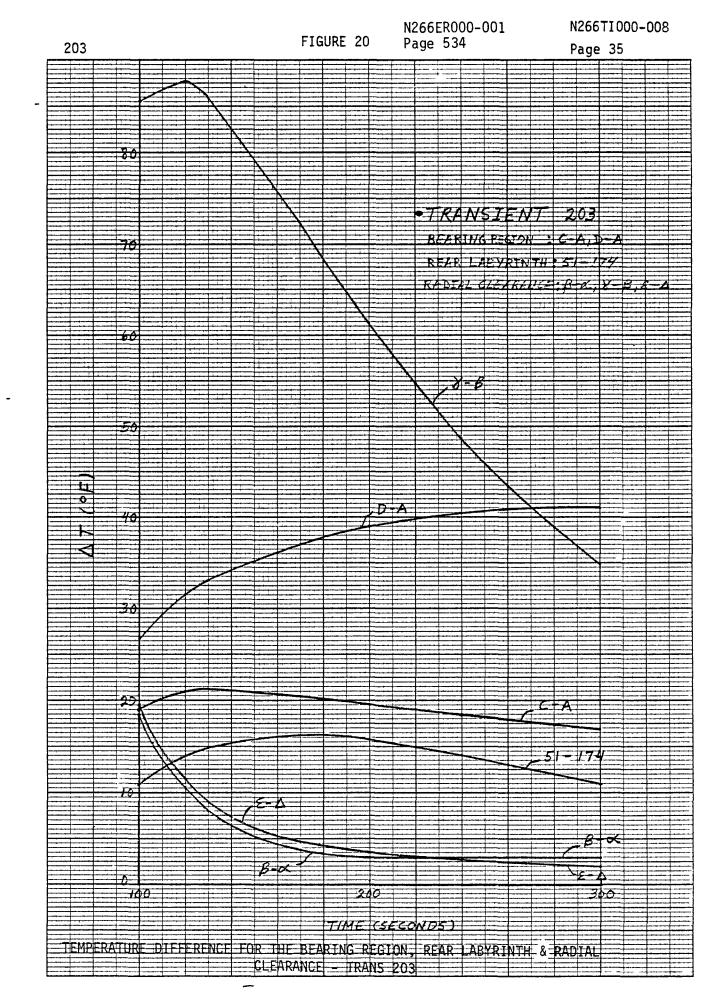
REAR LABYRINTH

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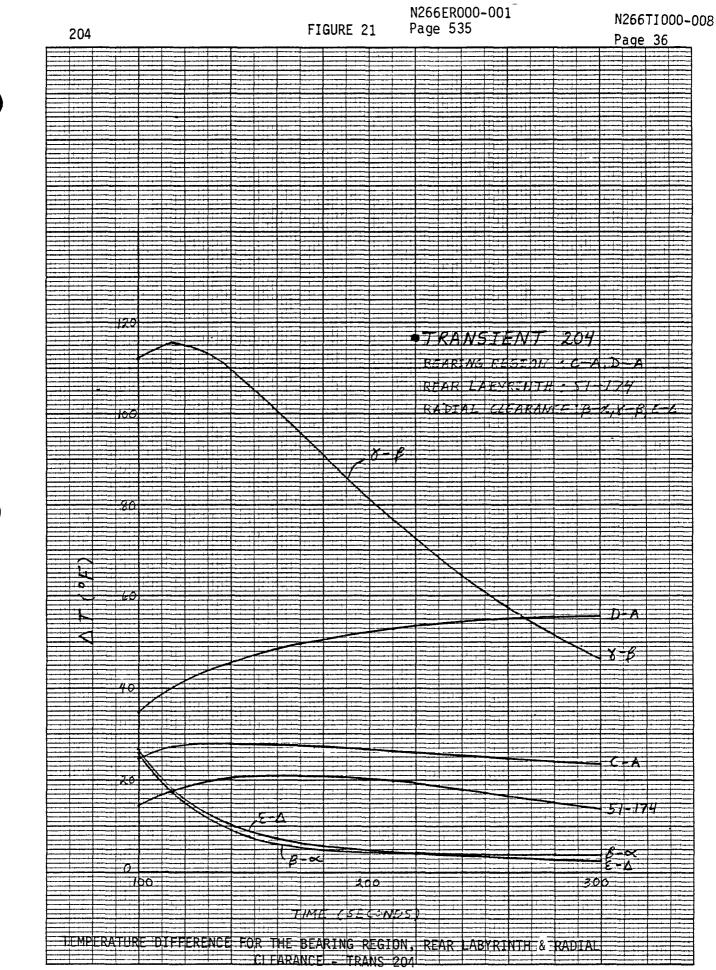




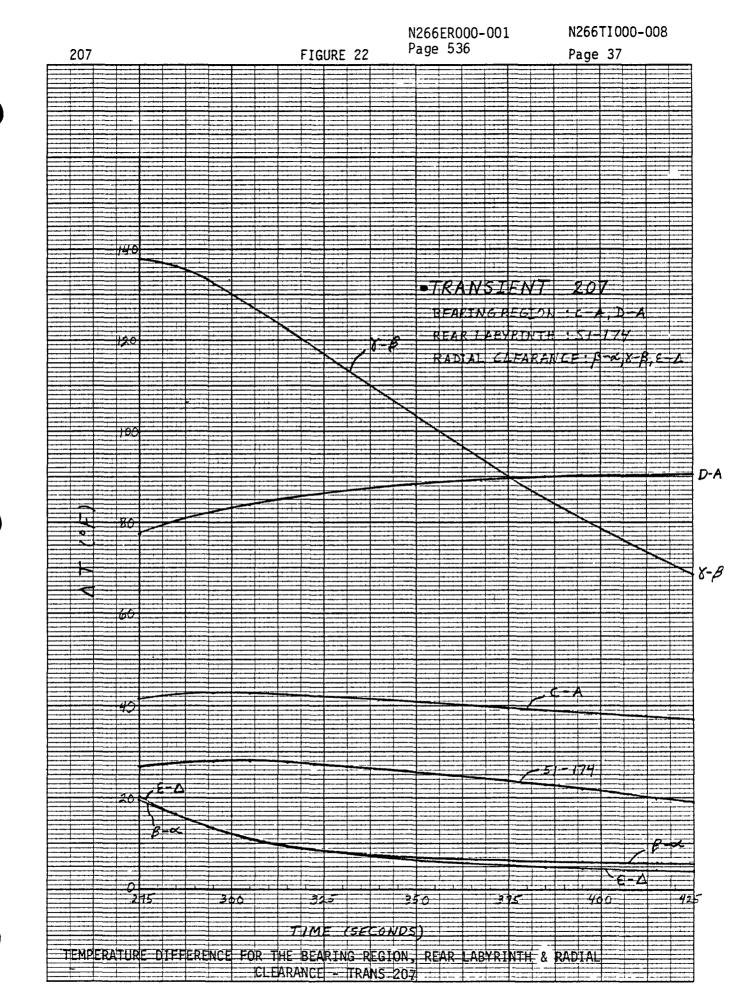
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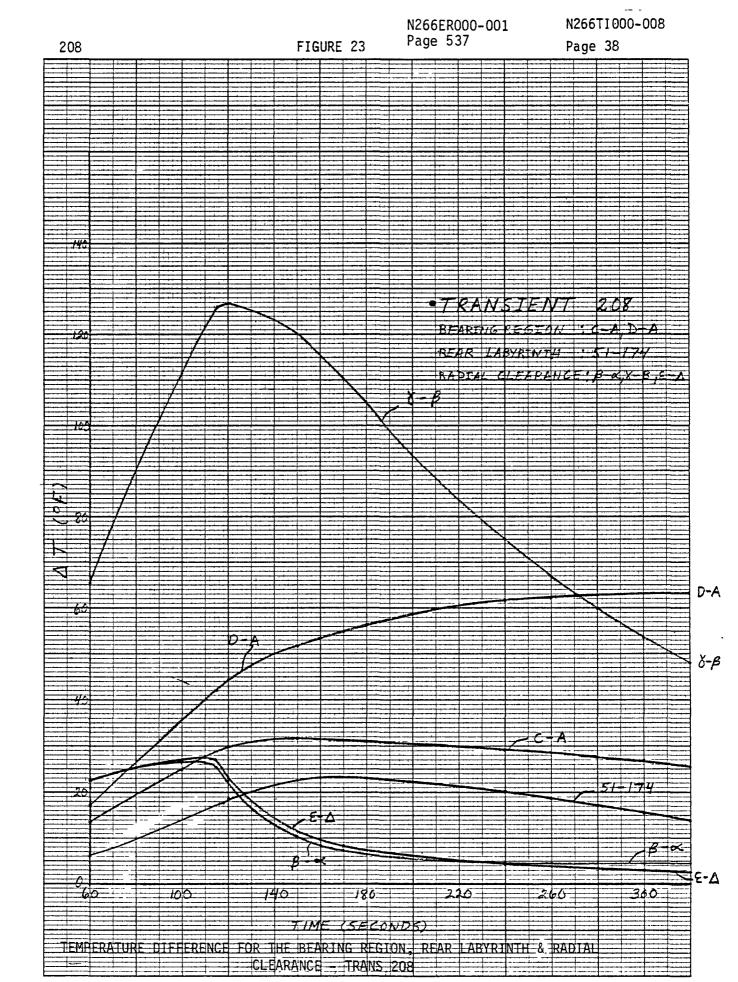
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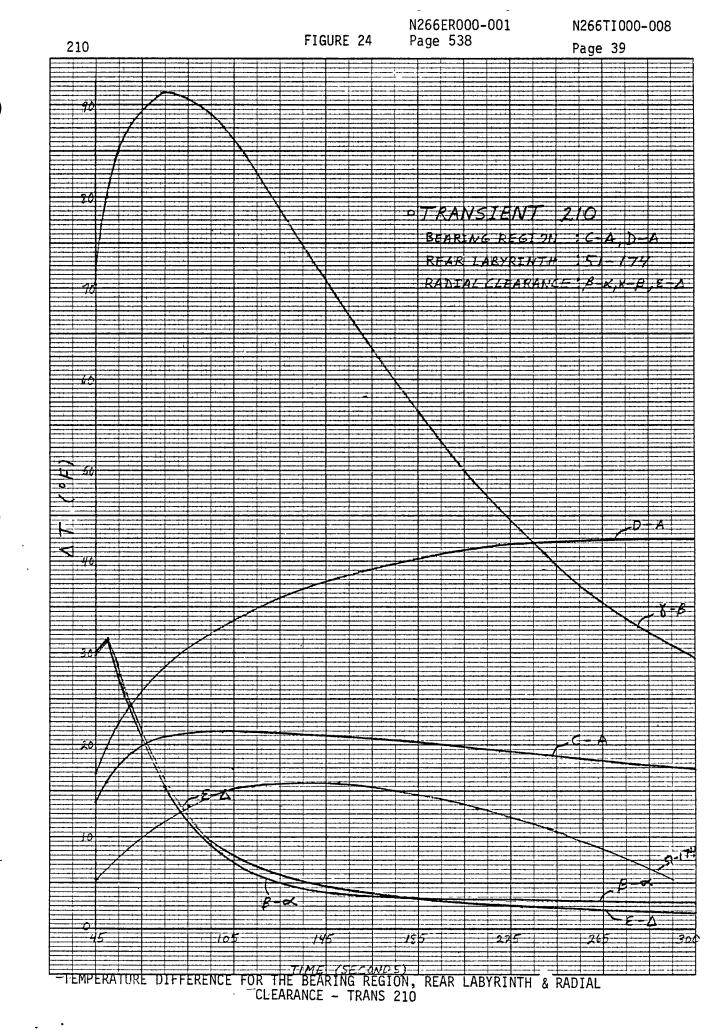


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## APPENDIX A

## SUPPORTING CALCULATIONS

This appendix contains hand calculations made in support of setting up the TAP computer model of the ISIP. Included are calculations on conductances and capacintances of the blade and diffuser regions, sodium node volumes and capacitances, sodium zone flow areas, and hydraulic diameters, and sodium side heat transfer coefficients.

N256ER000-001 Page 540 Rockwell International PREPARED BY. K. YUN OF Atomics international Division DMH EPORT NO. N266TI000-008 ISIP - Inducer Blade DATE: 6/2/78 MODEL NO INDUCER BLADE - FORM FACTOR CALCULATIONS From AI Drawing No. Roo19603 Section A-A : Average Radius (R) of Inducer Base :  $R = \pm (3,313 + 5,679) = 4.5"$ R= 9.265" 5.679 · From Drawing No. Roo19603 Section B-B:  $\frac{Blade}{Girsup fermsc} = \frac{15.5 + 6.7}{14.55} = 1.526$ · Total Effective Blade Circum Eerence = 1.526 × Inducer Circumference · Projected Surface Area of 1 full Circumterence of Blades (one face only)  $=\pi (R_0^2 - \bar{R}^2) = \pi (9.265^2 - 4.5^2) = 206.06$  in · However, we have 1.526 Blades, 2 taus per plade  $\begin{array}{l} A \\ (Surface for) \\ (Convection) \end{array} = 206.06 \frac{in^2}{face} \times 2 \frac{face}{black} \times 1.526 \frac{black}{black} = 62 E.9 \frac{in^2}{m^2} \end{array}$ · Blade Cross section Base of Triangle = 1.4"  $h \rightarrow t$   $\int \delta x R = 1.865$   $h \rightarrow t = .7"$ 14"  $\delta_{X} = \frac{t}{1} = \frac{.7}{.175}$ I for conduction in the divection normal To surface N 152.8-2 REV. 2-76

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THE AND BY. K. YUN THE ADDRESS TO THE ADDRESS TO THE PAGE 542 THE TOTAL TOT			N2	66ER000-001
CONDUCTION Between [NDUCER BLADE TO HUD (From NODE TBOD TO HUB) $Y_{T} = Ar \cdot K_{15} / n$ Assume $h = 5.125''/3 = 1.705''$ $A_{T} = 2\pi (4.5+1,708) \times 1.4 \times (3/3) \times 1.526$ $= 55.55 \times K_{55} / 1.708 = 32.526 \cdot K_{1}$ $Y = Y_{T} \times G$ where, G is the ratio (Measured length of element / 13.4'' $Y = \frac{V}{13.4} + \frac{V}{$	CHECKED SY: DMH	Atomics International Division	Pa PAG	ge 542 емо. <sup>43</sup> оғ
$(From NODE TB00 TO HUB)$ $Y_{T} = At K_{55} / n$ Assume $h = 5.125''/3 = 1.705''$ $A_{T} = 2T(4.5+1.708) \times 1.4 \times (2/5) \times 1.526$ $= 55.55 \times K_{55} / 1.708 = 32.526 \cdot K_{55}$ $Y_{T} = 55.55 \times K_{55} / 1.708 = 32.526 \cdot K_{55}$ $Y = Y_{T} \times C_{1}$ Where, $C_{1}$ is the ratio $(Measured lengTh of element / 13.4'')$ $\frac{Y}{1831} = \frac{C}{1.2/13.4} + \frac{2.913}{2.913} \frac{K_{55}}{1.55}$ $\frac{Y_{T}}{1838} = 2.6/13.4 + \frac{2.913}{15} \frac{K_{55}}{15}$	DATE: 10/16/78	ISIP BLADE TO INDUCER	HUB MO	DEL NO.
1837 1.2/13.4 2.913 Kss 1838 2.6/13.4 6:31F Kss	T	$Y_T = AT K_{ss}$ $F_T = 22.2^{\circ}$ $Assume h$ $A_T = 2\pi (4.$ $= 55.$ $Y_T = 55.55^{\circ}$ $K_* = 9.265^{\circ}$ $Y = Y_T \times G$ $Where, G is the$	= 5.125"/ 5+1.708)×1 55 × Kss /1.70	.4 * ( <sup>2</sup> /3) x 1.5 26 8 = 32.5 26 · K <sub>55</sub>
1837 1.2/13.4 2.913 Kss 1838 2.6/13.4 6.31F Kss			Y	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		1837 1.2/13.4 2. 1838 2.6/13.4 6 1839 2.6/13.4 6 1840 2.6/13.4	.913 Kss 131F Kss 1	

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TE, 10/1-	7/78	151P - Impeller B	lade	MODEL NO.	
		From Impeller	Blade To	b Hvb	
	= 91.72				
For	Y 1842 -	$\gamma \gamma 1846$ , $\gamma = G$	x YT		
For	Y1847 .	-Y1851 , $Y=G$	2 * YT		
	Y	Ci or Cz	Y		
	1842	2.4/12.5	17.61 Ks	\$	
	1843	4.1/12.5	30.08 K	55-	
	1844	3.1 / 12.5	22.75 K	55 '	
	1845	2.3/12.5 .	16.88 K	·s -	
	1846	1.6/12.5	11.74 K	. < /	
	1847	1.35/10.	12.38 Ks	5 1	
	1848	2.45/10.	22.47 K	55 (	
	1849	2.6/10.	23.85 K	55 /	
	1850	2.6/10.	23.85 K	esi	
	1851	1.0/10.	9.172 K	<b>65</b> .	

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$$\frac{1}{10000 \text{ M} \text{ K} \cdot Y_{U} + \text{ M} \text{ Rockwell International Animal International Inter$$

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N266ER000-001 548 PREPARED BY, K. YUH Rockwell International 49 PAGE NO. Atomics International Division DMH REPORT NO. N266TI000-008 CHECKED BY. 151P - Westing house Distance Vane 6/5/78 DATE Westinghouse Differen Vome Based on Drawing No. NZ66 Roooo15 (L2)10.27" (H1) £ = .225" avg. 1 2.75" (Hi) 10" (Li)H2: From Westinghouse Drw. 933 D757  $H_2 = (4.3^2 + 2.75^2)^2 = 5.104^4$ 4.3 2.75  $L_{2} = \int (H_{2} - H_{1})^{2} + L_{1}^{2} \int \frac{t_{2}}{t_{2}} = 10.27''$  $A_{(2705)} = (11) [(10" + 10.27")/2] (.225") = 25.03 \text{ in}^{2}$ For Conduction Y  $A\left(\begin{array}{c} Convective}{Surface}\right) = (11)\left(2\frac{Sides}{hlade}\right)\left[\frac{(2.75+5.104)}{2}\right] \times (10^{2})$ 11 black = 863.9 in<sup>2</sup>  $\overline{t} = .225'' \rightarrow \delta_t = \frac{t}{4} = \frac{.225}{4} = .05625''$  $H = (2.75+5.104)/2 = 3.927 \rightarrow S_H = \frac{H}{4} = .98175$  $\bar{L} = (10 + 10.77)/2 = 10.135''$ 

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N266ER000-001 Page 550 PREPARED BY, K. YUN **Rockwell International** PAGE NO. 51 OF Atomics International Division REPORT NO. N266TI000-008 DMH CHECKED BY 151P - W. Ditfucer Vame To Hub 10/17/78 DATE MODEL NO. WESTINGHOUSE DIFFUSER VANE CONDUCTION From HUB . Τo YT = 2.5.55 Kss (Btu/sec oF)  $Y = C \times Y_{\tau}$ Y Ci or Cz Y .6/10. 1856 1.533 K46 1.8/10 4.599 Kis 1857 2.2/10 5,621 Kis 1858 8.176 K ... 3.2/10 1859 C 1860 2.2/10 5,621 Kas 7.452 K45 2.1/7.2 1861 2.1/7.2 7.452 Kss 1862 2,2/7.2 7.807 145 1863 .8/7.2 2.839 Kss 1864

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N266ER000-001 Page 551 K. YUN 52 PREPARED BY PAGE NO. **Rockwell International** Atomics International Division OMH EFORT NO. N266TI000-008 CHECKED BY. 151P - Turning Vane 6/5/78 DATE NODEL NO Vane Form Factor Turning  $\frac{q_{11}}{co215} = 10.0$ 10.0 Design & Dimension Based m W.E.C. Drawing No. 9330763 - d -12.4  $\mathcal{D} = \int \left(\frac{3.53}{(L_{02}+0)}\right)^2 + 2.44^2 = 4.33''$ 10" - 5.28 В 12.8" 2.44  $A_{A} = .5(5.28 \times .931) = 2.458$  10<sup>2</sup>  $A_{B} = .5 (3.53 + 5.28) (10 - .931) = 39.949 in^{2}$ S = .5(3.53 + 2.44 + 4.33) = 5.15 $A_{c} = \int S(s-3.53)(s-2.44)(s-4.33) = 4.306 \text{ in}^{2}$  $A_5 = A_A + A_B + A_c = 46.71$  in<sup>2</sup> = (16 vanes) (2 Face ) (46.71) = 1494.8 in 2 Ast N 152-8-2 REV. 2-76

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ATE: 7/20/78	ISIP	MODEL NO.
Cred (Assume) $Cred (Sample Condition (Sample Conditition (Sample Condition (Sample Condition (Samp$	$\frac{1}{P = V(PCP)}$ $\frac{1}{PCP} = 0.0094495 V$	750°F :
u.	$\frac{BTU}{in^{3}} e^{F}$ $\frac{BTU}{in^{3}} e^{F}$ $\frac{D^{2}V}{4} = \frac{\pi}{4} (24)^{2} (16) = 7238.23 in^{3}$ $V_{901} = 723$	8,2 in <sup>3</sup>
	$C_{901} = 68,$	40 BTU /OF
902 V	$= \frac{\pi}{4} D^{2} L = \frac{\pi}{4} (24)^{2} (11) = 4976.28 \text{ in}^{3}$ $V_{902} = 4976$ $C_{902} = 47.6$	0.3 in <sup>3</sup> 02 b7U/0F ~
- "		2703.44 in3 2703.4 in3 25.55 BTU/F

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Page 555 PREPARED BY. EMMI PAGE NO. 56 **Rockwell International ~** Atomics International Division REPORT NO N256TI000-008 7/20/78 TSTP DATE MODEL NO  $V_{a} = \pi \dot{R} \rho L = \pi (11^{2})(11.5) = 4371.53$ 908  $\frac{b}{c} = \pi \left( R_{u}^{2} + R_{L}^{2} + R_{v}R_{v} \right) \left( \Delta - \right) \left( \frac{1}{3} \right) = \pi \left( 13^{2} + 21.5^{2} + 13 \times 21.5^{2} \right) \left( \frac{1}{3} \right) (9) = 8583.62$   $\frac{b}{c} = \pi R^{2} \Delta L = \pi (21.5)^{2} (4) = 5808.80$  $V_{1} = \pi \left( R_{2}^{2} + R_{2}^{2} + R_{3} R_{2} \right) \left( \Delta L \right) \left( \frac{1}{3} \right) = \pi \left( 21.5^{2} + 8^{2} + 8 \times 21.5 \right) \left( 37.5 \right) \left( \frac{1}{3} \right) = 27420.21$ Ve = TR<sup>2</sup> oL = TT (8)<sup>2</sup>(3.5)= 703.72 V908 = 46,887,89 Subtrad Volume of Node 902:  $V_{902} = V_{902}^{\prime} - V_{902} = 46,887.9 - 4976.3 = 41911.6$  in<sup>3</sup>  $V_{908} = 41,911.6$  in<sup>3</sup> C 908 = 396.05 BTU  $V = \pi R^2 \Delta L = \pi (8)^2 (51) = 10,254.16$ 909 Vana = 10, 254.2 in3 C 909 = 96.90 BT %F 910 DISCHARGE NODE Vi = 2TT R A 911 a: Ra= 11.5 b:  $\bar{R}_{h} = 14.5$  "  $A_a = (4 \times .6) = 2.4$ AL= (6.5)(55)= 5.525  $V_a = 2\pi (11.5)(2.4)$  $V_{h} = 2\pi (A, 5) (5.525)$  $V_{a} = 173.42$  in<sup>3</sup>  $V_{h} = 503,36$ Van = 676.79 Van = 676.8 in 3 Cq11 = 6.40 BTUV  $V = 2\pi R A_{crain}$ 912 R= 14.5 inch Across = = = (5)(7.5) = 10 V= 271 RA = 2+ (14.5)(10)= 911.06  $V_{912} = 9/1.1 \text{ in}^3$ Cq12 = 8.61 BTU

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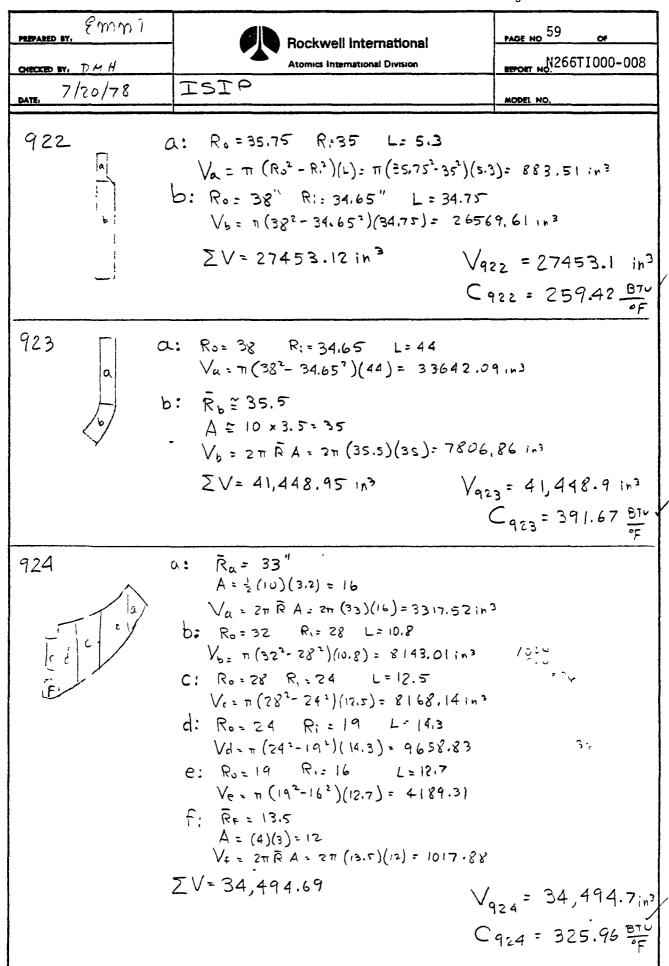
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DATE: 7/2	0/72	ISIP	MODEL NO.
		A = (0.6)(3) = 1.8	
937		•	2
	V	$= 2\pi RA = 2\pi (4)(1.8) = 45.24 \text{ in}^{3}$	
			$V_{937} = 45.24 \text{ in}^3$
			C937 = 0.43 BTL
938	Ro	= 15.3 R1= 14.0" L= 40.5	
120	V=	$\Pi \left( \mathbb{R}_{0}^{2} - \mathbb{R}_{1}^{2} \right) (L) = \pi \left( 15.3^{2} - 14.0^{2} \right) (46)$	0.5) = 4846.36
		•	$\sqrt{932} = 4846.4 \text{ in}^3$
			$C_{938} = 45.80 \frac{57}{10}$
			C 938 = 73.00 -F
939	Ro=	15.3 R= 14.0 L= 43.5	
	V-	$\pi(15.3^2 - 14.0^2)(43.5) = 52.05.35$	
			$V_{939} = 5205.4$ in <sup>3</sup>
			Caza = 49.19 Er -
			~154 °F.
940	$R_0 = 3$	58 Ri = 31.8 L = (77.5-43.5) = 34	
	V <del>-</del> 17	$(38^2 - 31.8^2)(34) = 46224.89$ in 3	Vq40= 46224.9 ;
			$C_{940} = 436.80 \frac{BT}{2}$
			- 940 - 436.80
941	Ro=	38 R; = 31.8 L= 43.5	
	V= T	- (38 <sup>2</sup> -31,8 <sup>2</sup> )(43.5)= 59140.67	$V_{941} = 59 140.7 \text{ in}^3$
			Cq41 = 558.85 8
<u> </u>	······································		,
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N 152-8-2 REV. 2-76

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8 Tritin PAGE NO. 64 PREPARED BY **Rockwell International** Atomics International Division REPORT NO.N266TI000-008 CHECKED BY. DMH 7/20/73 DATE  $V_{PPev}$ : Ro= 32.6 Ri= 21.3  $A_{v} = \pi (R_{v}^{2} - R_{v}^{2}) = (32, 6^{2} - 21.3^{2})\pi$ 942 a: Au= 1913.45 Lower Ro = 37.6 R. = 9 AL =  $\pi (R_0^2 - R^2) = \pi (37.6^2 - R^2)$ ٥ L= 33.5 AL= 3084.29 - $V_{\alpha} = \frac{1}{3} \left( A_{u} + A_{L} + \sqrt{A_{u}A_{L}} \right) = \frac{33.5}{3} \left( 1913.45 + 3084.29 + \sqrt{(1913.95)(3084.27)} \right)$ Ь Va = 82,935.59 in 3 ~ Ro= 37.6 R= 9 L= 10.5 h:  $V_{b} = \pi (R_{0}^{2} - R_{1}^{2})(L) = \pi (32.6^{2} - 9^{2})(10.5) = 32385.05$ c: Fllipsoid (half) V= = = abc = 4 (32.6) (37.6) (15) = 33, 387.59 -ZV'= 82 935,59 + 32,385.05 +33387.59 = 148708.23 in3 Subtract Volumie 901 V901= 7238,2 V942 = 148,708.23 - 7238.2 = 141470.0  $V_{942} = 141, 470.0 \text{ in}^3$ G942= 1336.83 BTU

N 152-R-2 REV. 2-76

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PREPARED BY, K. YUP			I International		PAGE	NO. 66	Of
CHECKED BY, DMH		Atomics Inte	mational Division		REPOR	t no. N266T	1000-008
DATE: 10/16/78	ISIP				MODE	L NO	
	,,,,	<u> </u>	<u></u>				
CALCULA	T10N	e For	m Fact	6 F 6			
		· · · · · · · · · · · · · · · · · · ·					
DUMMY	Ŷ	CONV Cond	E = Surtace E = Ac/L	Are	4		
EBOI	1801 (	ONV.	TEX 1.25 X12 X	2.3	=	108.4	in <sup>2</sup>
EBOZ	1802	"	"	4.5	H	212.1	<i>h</i>
EB03	1803	11		4.1	=	193.2	<i>a</i> ,
E 804	1804	h	<i>ð</i> 1	2.1	×	98.96	ų
E805	1805	1.	•,	.3	=	14.14	11
E806		11	24×2(Z+1) ×	Z.1	11	30 Z. 4	//
E807		"	11	2.1	2	302.4	h
ESOB		"	π×7.5 × 4 ×	0.5	F	15.708	Inz
E809		11	"	1.7	×	53.407	1,
EBID		11	11	2.2	=	69.11	"
EBII		"	4	1.5	<b>3</b>	47.12	<i>(</i> )
EBIZ		11	11	0.5		15.708	,
E813	bee calcula	tim of Y	1823 - Y1827)		= ]:	295 in 1	2
E814					= );	008 "	
EB15					= 1	008 n	
E816					=	768 11	
E 817					=	384 "	
EBIS					=	295 11	
E 8 19					= 1	00B 11	
EEZO					= 10	108 11	
EBZI	V				= 7	68 11	

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PREPARED BY, K. YUN	Rockwell International	PAGE NO. 67 OF
CHECKED BY, DMH	Atomics International Division	REPORT NO. N266T1000-00
DATE, 10/16/78	ISIP	MODEL NO.
EB22		= 384 in <sup>2</sup>
E823		= 1295 in
EB24		= 1008 1,
E825		= 1008 11
EB26		= 768 "
EBZT	<b>,</b> 7	= 384 //
EBZB	$\pi (38^2 - 31.8^2)$	$= 1360 \text{ in}^2$
EBZQ		$= 1360 \text{ in}^2$
E830	$\pi(15.3^2 - 14^2)$	$= 119.7 \text{ in}^2$
E831		$= (19.7 \text{ in}^2)$
		•
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	•				N266ER000-00 Page 567	)1
PREPARED BY,		Bockw	ell Interna	tional	PAGE NO. 68	OF
CHECKED SY:			nternational Dr		REPORT NON266T	1000-008
DATE:	ISIP				MODEL NO.	
				<u></u>		
TRANSIE	INTS:					
#	° <del>r</del>	Ŧ				
201 750.	+ 600	675	3- 2	teleted b	4 T.J.B 3-	5-79
202 750.	→ 600	675			N N	
203 500-	→650	575				
204 850	÷ 650	750	-	₹ ¥ 793		
205 700	→ 850	775	2 del	to the las	T.I.B 3-5-	-74
206 1050.	+ 720	885		2	1, = , = , = = =	,,
	→ 720	885	2.	1 1.0. 1		,
÷ -	→ 825	938	Y M	ochified,	Temper Luce . T. 1. B - 3 - 5 - 7	-céleric
210 1050	⇒ 900	975	منظر ک آ	g 100°F.	7.1.12 - 3 - 5 - 7	9
	Assume	Ţ	~ 800°	F		
	•	Na		_	,	
SODIUM Pr	ROPERTIES @	800	°F	(Goldøn	e Tokar)	<b>`</b>
k = 4	0.62 BTU/hr A	40				
$\mu = 0,$	6437 1bm/nrf	+	マーク・	<u>,6437</u>	0.01213 fr2	
Q = 5	3.053 lb~/ft3		-			-h -
			ン= 5	3.053 × 1 3.053	= 3.37032 X	$10 \frac{ft^2}{sec}$
	·		_			

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		N266ER000-001 Page 568
PREPARED BY:	Rockwell International Atomics International Division	PAGE NO. 69 OF REPORT NON266T1000-008
$Q = \frac{f_{+3}}{s_{ec}} =$	$GPM \frac{gal}{min} \times \frac{min}{60 \text{ sec}} \times \frac{231}{172B} \frac{ft^3}{gal} =$	. 002 2 2 8
	$\frac{f_{+3}}{f_{+2}} = 0.002228 \times GPM = \frac{GPM}{448.8}$ $\frac{f_{+3}}{f_{+2}} = \frac{Q}{A} \frac{f_{+3}}{f_{+2}} = \frac{Q}{A} \frac{FPS}{f_{+2}}$	3
L	$\frac{2}{2} = \frac{V_{FPS} D_{HFT}}{3.37 \times 10^{-6}} = 2.9671 \times 10^{5}$	V D
F	$Re \cong 3.0 \times 10^5 \bigvee_{FPS} D_{H}$	
-	$NU = 7.0 + \frac{1}{40} (Re Pr)^{0.8}$ $Pe^{1.00482}$	
	$h = N_{\nu} \frac{k}{D_{\mu}}$	
h	$\frac{B_{TU}}{hr ft^{\circ}r} = \frac{40.62}{D_{H}} \times NU$	
		•

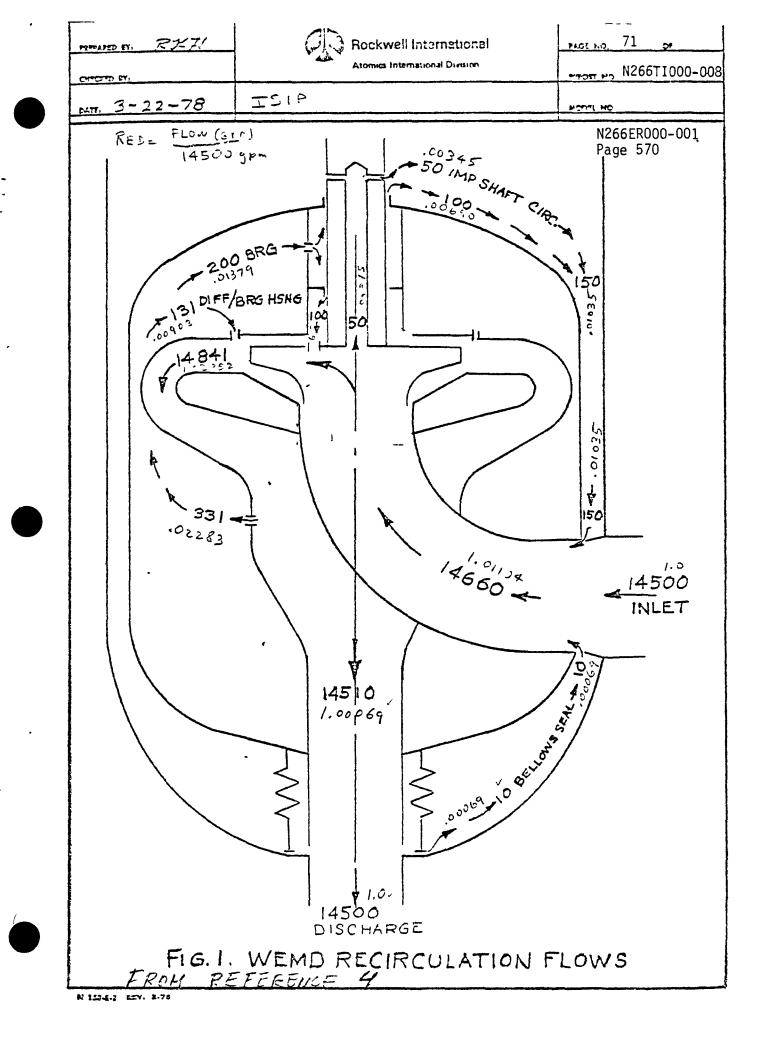
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## N266TI000-008

P	a	ae	9	7	0

FLOW	FULL (100%)
1/05E	FLOW RATE
<u> </u>	(GPM)
900	14,500
901	14,660
902	14,600
903	14,644
904	16,001
905	14,841
-	
506	14,841
907	14,841
903	14,510
9:0	14,510
5.10	14,500
911	648
912	74
913	34
914	-
915	50
916	54
9.7	50
4.0	150
-19	60
920	150
921	150
922	150
.623	10
5-14	10
975	331
926	331-
927	131 .
928	-
929	200
930	209
931	100
9:2	40
ł	
933	
234	678
525	678
936	21
937	÷4

Page 70	
FLOW NOLE	FULL (100%). FLOW LATE (GPM)
938	D
939	0
940	0
941	Ð



$$\frac{1}{12} = \frac{1}{12} \frac{1}{12}$$

N 152-8-2 REV. 2-76

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$$\frac{P2665700-001}{P26957}$$

$$\frac{P26570}{P26572}$$

$$\frac{P26570}{P2677}$$

$$\frac{P26570}{P2677}$$

$$\frac{P26707}{P2677}$$

$$\frac{P26$$

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	N266ER000-001 Page 574
PREPARED BY. EII'IM Bockwell International	page no, 75 of
CHECKED BY, DMA Atomics International Division	REPORT NO N266TI000-008
(	MODEL NO.
NODE 907 TO 10 27 FULL FL	.ow= 14841 gpm
FLOW CONDITION: AXIAL R;= 1	9 inch 3 inch
$ = \pi (R_{3}^{2} - R_{1}^{2}) = \pi (19^{2} - 13^{2}) (\frac{1}{144}) = 4.189 \text{ ft}^{2} $	
(5) $D_{4} = 2 \times (R_{0} - R_{1}) = 2(19 - 13)_{12} = 1.0 \text{ ft}^{-1}$	
-31 728 60 FULL FLOW = 14841 9FM	
$ \square \qquad \square $	$7\frac{f+3}{sec}$
$-\frac{4}{6}  (3)  \bigvee \frac{f_{1}}{s_{ec}} = \frac{Q_{cFs}}{A_{cT}^{2}} = \frac{33.0657}{4.189} = 7.894 \frac{f_{1}}{s_{ec}} -$	
	in ab
(2) Re $\cong 3 \times 10^{5} (\frac{1}{2}) (D_{\mu}) = 3 \times 10^{5} (7.894) (1.0) = 2$	.368 X10-
() $P_e = R_e F_r = (2.368 \times 10^6)(.00482) = 11414.5$	, -
$O   NU = 7 + \frac{1}{40} (Fe)^{3.5} = 7 - \frac{1}{20} (11414.5)^{6.8} = 51.05$	-
$ O   NU = 7 + \frac{1}{40} (Pe)^{2.5} = 7 + \frac{1}{20} (11414.5)^{6.8} = 51.05 - \frac{1}{20} (11414.5)^{6.8} = 51.05 - \frac{1}{20} = \frac{1}{10} (11414.5)^{6.8} = 51.05 - \frac{1}{10} = \frac{1}{10} (11414.5)^{6.8} = \frac{1}{10} (1$	$hos = 2073.5 \frac{BTU}{hr ft^2 e_F}$
%FLOW FLOW V RE PE N gpm Ft/sec	Nr Fl <sup>2</sup> F
	1.05 2073
(2,000) 82.759% 12282 6.53 1.96 × 106 9 147 4	4.86 1822
	7 284.3

N 152-8-2 REV. 2-76

$$\frac{1}{112} \frac{1}{112} \frac{1}$$

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$$\frac{1}{Poge 576} = \frac{1}{Poge 576} = \frac{1}$$

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$$\frac{26662000-001}{Page 577}$$

$$\frac{279}{Page 577}$$

$$\frac{1}{Page 57}$$

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$$\frac{1}{11} \frac{1}{200} \frac{1}{11} \frac{1}{200} \frac{1}{11} \frac{1}{11}$$

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$$\frac{11}{11544} = \frac{21774}{178} = \frac{11}{123} = \frac{11}{133} = \frac{11}{133}$$

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$$\frac{\frac{1}{2}}{\frac{1}{2}} = \frac{1}{2} \frac{1}{2$$

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$$\frac{826657000-001}{996552}$$

$$\frac{826}{10000}$$

$$\frac{83}{1000} m. D/H$$

$$\frac{1}{1000} m. D/H$$

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$$\frac{1}{12} \frac{1}{12} \frac$$

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$$\frac{11}{12} \frac{11}{12} \frac{11$$

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$$\frac{8265 \text{ Process}}{1000-001} = \frac{8265 \text{ Process}}{1000-002}$$

$$\frac{8265 \text{ Process}}{1000-003} = \frac{8265 \text{ Process}}{1000-003} = \frac{8273}{1000-003} = \frac{8273}{100-000-$$

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$$\frac{8266EB00-001}{100000} = \frac{800}{90} = \frac{90}{2} = \frac{800}{1000000} = \frac{90}{2} = \frac{100}{2} = \frac{90}{2} = \frac{100}{2} = \frac{$$

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N 152-R-2 REV. 2-76

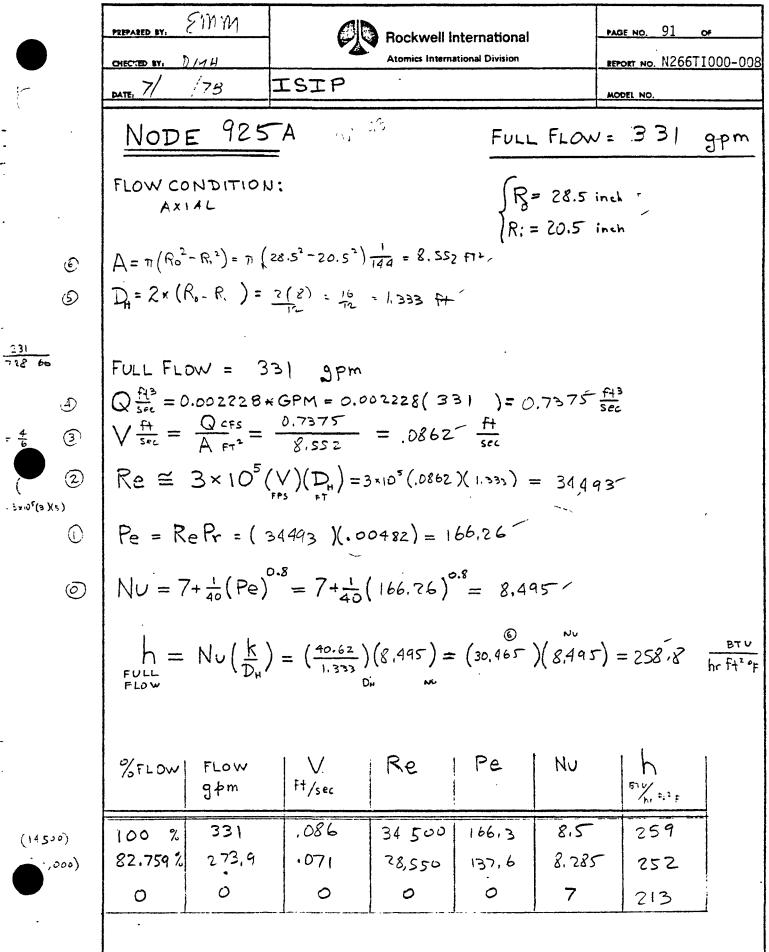
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		N266ER000-001 Page 591
PREPARED BY, K, YUN	Rockwell International	PAGE NO. 92 OF
CHECKED BY, DMH	Atomics International Division	REPORT NO. N266TI000-00
DATE: 10/13/78	151P	MODEL NO.
$A = 24 \times 2 \times 1$ $D_{H} = 4 \times A_{c} / P$ $Q = 0.002228$ $V = Q_{cFS} / A_{FH}^{2}$ $R_{e} \simeq 3 \times 10^{5} (V)$ $Pe = Re Pr = 0$		0.7375 $\frac{ft^2}{sec}$ F <sup>+</sup> /sec = 7.3674×10 <sup>4</sup>
	$) = 9,743 \frac{40.62}{.111} = 3562$	•
% Flow		h Btu/nr ft20F
100 %		3562.
82.759		3421.
0.0		z 559

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						N266ER000-00 Page 594	)1
	PREPARED BY. EININ	<b>B</b> IE	Bockwell	nternational		AGE NO. 95	OF
	CHECKED BY: DMH		Atomics Intern			EPORT NO.N266TI	000-008
{	DATE, 7/ 178	ISIP				NODEL NO.	
-	NODE 92	9 - 1 4	6	FULL	FLOW =	200	gpm
••	FLOW CONDITIO			(R   + =	= 16.5 in : 11 in	ch <sup>-</sup>	
	A= 211 RH - 21						
5	$D_{H} = 2 \times (H) =$		F+				ł
$= \frac{4}{6} \qquad (3)$	FULL FLOW = $Q \frac{ft^3}{s_{ec}} = 0.002228$ $V \frac{ft}{s_{ec}} = \frac{QcFs}{AFt^2} =$ $Re \cong 3 \times 10^5$ Pe = RePr = ( $NU = 7 + \frac{1}{40}(Pe)$ $h = Nu(\frac{k}{D_H})$	$*GPM = 0.0 0.4456 7.919 (\bigvee)(D_{H}) = 330947 (.0)= 7 + \frac{1}{40}(1)$	$= 0.056^{\circ}$ $8 \times 10^{5} (.0563)$ 0482) = 1 $(149.16)^{6}$	$3 - \frac{f+}{sec}$ )(1.893) = 49,16 	= 30947  7 1	<b>,</b> -	, , 
	$h = Nu(\frac{k}{D_{H}})$	$\Big) = \Big(\frac{40.62}{1.833}\Big)$	(8.37) =	(22,156	)( 8,37)	= 185.5	hr ft2 %
						. 1	,
	%FLOW FLOW	Ft/séc	Re	Pe	Nu	h Bruy Fi <sup>2</sup> F	
(14520)	100 % 200	.056	30950	199.2	8.4	185	
(2,000)	82.759% 165.5	.0466	25610	123.4	8,18	181	
	0 0	0	0	0	7	155	
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				Page 595
	PREPARED BY, EINM	Rockwell Interr Atomics International		PAGE NO. 96 OF REPORT NO.N266TI000-008
с. Г.	DATE: 7/ 78	ISIP		MODEL NO.
-	<u>Node 930</u>		FULL FLOW	1=200 gpm
-	FLOW CONDITION arune unifor (actually, flu	men distributed axially.		
E	A= 27 RH = 2.	$\pi(7.5)(10) \frac{1}{144} = 3.27ft$	OR	20,5
6	$D_{H} = 2 \times (\Delta \hat{R}) = a \text{ study y, this was } $	2(.5) = .0833		
<u>-31</u> 728 60	FULL FLOW = $2$ $O \frac{R^3}{2} = 0.002223$	00 gpm GPM = 0.002228( 200	)= 0.4456	<u>ft</u> 3
) + 4 3	$\bigvee \frac{ft}{Se_L} = \frac{QcFs}{AcT^2} =$	$\frac{0.4456}{3.27} = 0.1362 - \frac{1}{1362}$	Ft Sec	SEC .
	_	$(\bigvee)(D_{H}) = 3 \times 10^{5} (.1362)(.0)$		4-
	Pe = Refr = (	3404 )(.00482) = 16.0	108-	,
Ø		$= 7 - \frac{1}{20} (16,408)^{0.8} =$		
	$h_{\text{FULL}} = N_{\text{U}} \left( \frac{k}{D_{\text{H}}} \right)$	$= \left(\frac{20.62}{.0833}\right) \left(7.734\right) = \left(4$	5 NU 87,44)(7.234	$) = 3526 - \frac{BTU}{hr ft^2 r}$
-	%FLOW FLOW gpm	Ft/sec,	e Nu	BTU hr F42 F
(+4 5 ° 0) (+2 ,000)	100 % 200 82.759% 165.5 0 0	)   16   13,   0   0	,,,,,,	
	, , , , , , , , , , , , , , , , , , ,			= U NINY

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PREPARED BY. V. VUN	Rockwell International	PAGE NO. 98 OF
CHECKED BY, DIMA	Atomics International Division	REPORT NO. N266T1000-
DATE: 10 3 7 4	151P	MODEL NO.
NODE 9	<u>35</u> Fu	11 Flow = 678 G
Flow Condit Axial Ela Elow Po	w through 12 - 1.25" DIA	- 12.5" LONG
2	] × 12 = 14.726 in <sup>2</sup> - = 0.1022 " = 0.10417 {t	6 ±t <sup>2</sup>
Full Flow	= 678 GPM	
$Q \frac{4t^3}{5e_c} = 0.00$	2228 (678) = 1.5106 ft <sup>3</sup> /sec	:
$V \frac{ft}{sec} = \frac{Q_{CFS}}{A_{tt}}$	= <u>1.5106</u> = 14.772 ft/sec	
$R_e \cong 3 \times 10^5$ (	$V)(D_{H}) = 3 \times 10^{5} (14.772) (0.10417) =$	4.616× 105
	$4.616\times10^{5})(.00482) = 2225.^{-1}$	
$N_{\mu} = 7 + \frac{1}{40}$	$(P_e)^{\cdot 8} = 18.907$	
$h_{\frac{1}{2}011} = Nu(-$	$\frac{\kappa}{D_{\rm H}} = (18.907) \left(\frac{40.62}{.10417}\right) = 7373.$	hr ft <sup>2</sup> °F
		-
		h
100%		7373.
82.159 %		6720.
1		

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• •	PREPARED BY. EMM CHECKED BY. DMH DATE: 7/ /78		ockwell International	REP	ORT NON266TI	œ 000-008
-	NODE 936		FULI	_ FLOW =	<u>4</u>	gpm
	FLOW CONDITION	J;	J.R	= 215 incl = 1 incl		
-	$A = 2\pi \bar{R} \Delta R \Delta R = 2\pi \bar{R} \Delta R = 2\pi R$		D.1091 Az	= ( Inci	^	
	FULL FLOW = $Q \frac{ft^3}{sec} = 0.002728$ $V \frac{ft}{sec} = \frac{QcFs}{AFt^2} =$	* GPM = 0.002		008912 <del>54</del>	3	
(2) 3 x 10 <sup>r</sup> (3 )(5 )_ (	Re ≅ 3×10 <sup>5</sup> Pe = RePr = (	FPS PT		= 4085		,
Ö	$N\upsilon = 7 + \frac{1}{40}(Pe)$	$=7+\frac{1}{40}(10)$	$(7.69)^{0.8} = 7.2^{-1}$			
	$h_{\text{FULL}} = N_{\text{U}} \Big( \frac{k}{D_{\text{H}}} \Big)$	$ = \left(\frac{40.62}{.1667}\right) \left(\frac{7}{D_{H}}\right) $	© 1,27) = (243.72 M	)(7,27) =	= 1772´	BTU hr ft² °F
-	%FLOW FLOW	V. Ft/sec	Re Pe	NU	BT W hr ft <sup>2</sup> F	
(14520) (14520)	100 % 4.0 82.759 % 3.31 . 0 0		1085   19.7 3381   16.295 0   0	7,27 7,233 7	1772 1763 1706	-
-				·	<u> </u>	-

	PREPARED BY. EIMM CHECKED BY: D.M.H DATE: 7/ /78	Rockwell Intern Atomics Internationa	1	PAGE NO. 100 OF REPORT NO. N266TI000-008 MODEL NO.
-		-939 12	FULL FLOW	
	FLOW CONDITION	J:	$\int R_{e}^{2}  5,25 $ $R_{i}^{2} =  4 ^{2}$	nel (
		$= \frac{1}{12} (15.25^2 - 14^2)_{144} = 0.80F$ $= \frac{2(1.75)}{12} = 0.20833 \text{ ff}$	$ R_{i} =  4 $ i of $DR = 1.25$	nch (
		) $gpm$ *GPM = 0.002228( ) 		<del>f1</del> 3 Sec
( ( 5 x 10 <sup>5</sup> (3 X 5 )	Re ≅ 3×10 <sup>5</sup>	$\left(\bigvee_{\text{FPS}}\right)\left(D_{H}\right) = 3 \times 10^{5} ()$	) = 0	
		)(.00482) =	D	
0		$^{0.8} = 7 + \frac{1}{40} (0)^{0.8} =$		
	$h_{\text{FULL}} = N_{\text{U}} \Big( \frac{k}{D_{\text{H}}} \Big)$	$ = \left(\frac{40.62}{.20\varepsilon^{33}}\right) \left(7\right) = \left(1000000000000000000000000000000000000$	© NU 196,98)(7	$) = /365 \int \frac{BTU}{hr ft^{2} r}$
-	%FLOW FLOW	V. Re Ft/sec	Pe Nu	BT W FIT F
(145°°) ,000)	100 % () 82.759 % () 0 ()	. 0 0	0 7	(1365
-			·	

	PREPARED BY. EINM CHECKED BY. DMH			PAGE NO. 101 OF N266TI000-008
1-		ISIP		MODEL NO.
•	<u>NODE 940</u>	941 - 13	FULL FLOW	1=.0 g.pm
	FLOW CONDITION	۱:	$\int R_{\rm s} = 38$ $R_{\rm i} = 32$	inch -
6	A=		$(R_i = 3Z)$ $\delta R = 6''$	inch
Ś	$D_{H} = 2 \times ( \Delta R ) =$	2(6) = 1.0		
<u>-31</u> 728 60	FULL FLOW =	0 apm		
. <b>4</b> )	$Q \frac{f_{13}}{s_{ee}} = 0.002225$	GPM = 0.002228( 0		ft <sup>3</sup> Sec
		= D ·		
2 5×10 <sup>5</sup> (3)(5)	Re ≅ 3×10 <sup>5</sup>	$\left(\bigvee_{T \in \Sigma}\right) \left( \bigcup_{H \in T} \right) = 3 \times 10^{5} () ()$	$\rangle = 0$	
	Pe = RePr = (	)(.00482) = 0		,
Ø	$NU = 7 + \frac{1}{40}(Pe)$	$=7^{-1}\frac{1}{40}(0)^{0.8}=$	7	
	$h_{\text{FULL}} = N_{\text{U}} \left( \frac{k}{D_{\text{H}}} \right)$	$= \left(\frac{20.62}{I}\right) \left(\begin{array}{c}7\\\end{array}\right) = \left(2$	10.62)(7	$) = 28 \ 4 \ \frac{BTV}{hr \ ft^2 \ r}$
-	%FLOW FLOW gpm	V. Re T	Pe Nu	BT W Nr Fl <sup>2</sup> F
(14 500)	100 % 82.759 % 0 0	0 0	0 7	]284
	· ·	/ / /	<u> </u>	l

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PREPARED BY, K, YUN 102 **Rockwell International** Atomics International Division N266TI000-00 DITH REPORT NO. CHECKED BY: 774 ISIP 10/10/76 DATE NODEL NO NODE 942 Flow Condition : Stagnant Operating Temp. Range: 600°F~1050°F (T942)  $R_{a_{H}} = Gr_{H} \cdot Pr = A \cdot H^{3} \cdot \Delta T \cdot Pr$ where  $A = \int^2 g \beta / \mu^2$  $1.35 \times 10^8 \times \Delta T < R_{q_1} = G_{r_1} \cdot P_r < 2.25 \times 10^8 \times \Delta T$ " For PTI ( Wall - NA) between .37"F- 89 "F, 5 × 107 { Ray \$ 2 × 10 " Therefore, Eg. 5.107 of O.E. Dwyer can be applied.  $\overline{N}_{H_{H}} = \frac{\overline{h} \cdot H}{k} = 0.16 \left[ \left( Ra_{H} \right) \left( \frac{r}{H} \right) \right]$  $= 0.16 \left[ (A \cdot P_r \cdot H^3 \Delta T) (r/H) \right]^{0.3}$ = 0.16 ( A.Pr. AT. H2.r] 0.3 At a given surface (H,r) Th becomes  $\bar{h} = .16 \frac{k}{H} (A \cdot Pr \cdot H^2 \cdot r)^{3} (\Delta T)^{0.3}$ where ,  $C = .16 \left(\frac{k}{H}\right) \left(A \cdot Pr \cdot H^2 \cdot r\right)$  $= C (\Delta T)^{\prime,3}$ 

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REPARED BY, K.YU		ell International Iternational Division	PAGE NO. 103 OF	
HECKED BY: $Dm H$ ATE: $1C/10/75$	8 ISIP		REPORT NON266TI000	-008
	Na (Yff**f)			*
T (°F)				t rz
500	1.42 × 106	45.43	260.06	
600	1.66× 11	43.79	262.7	
700	1.89 × "	42.18	z63.1	
800	2.14 × 11	40.62	263.	
900	2.38 × "	39.09	261.3	
1000	2.64× "	37.61	259.3	
100	Z.90 × 11	36.17	256.5	
1200	3,18× 11	34.78	253.57	
G at G at	from Golden & (ri/r.) <sup>3</sup> V2 is 1.477 time T1 can be a operating to	es greater .	260. at	
Υ μ\$·	$C_{a} + r_{1} = 26$ $C_{a} + r_{2} = 36$			
	$h = r_1 = 260$ h = 384	$(\Delta T)$ Btu/hr $t^{2}$	of = .0005015 (27) = .0007407 (27) <sup>3</sup> B	Btu/seci

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#### APPENDIX B

CLEARANCE CHANGES

This appendix contains the results of the thermal radial clearance effect using the APSA program given in Reference 10.

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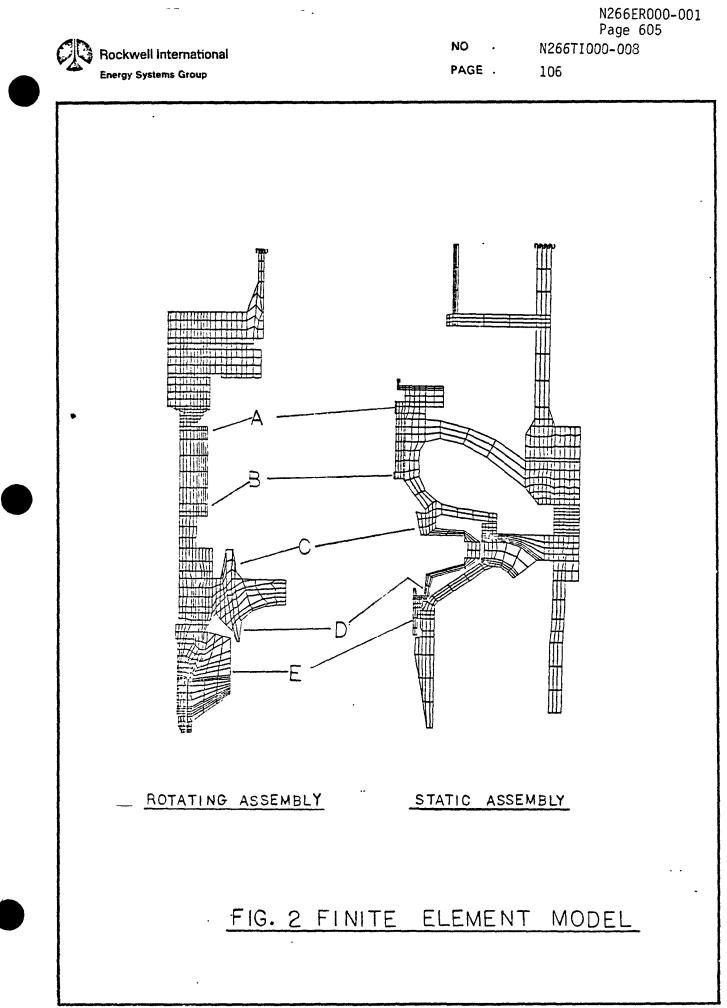
CRITICAL CLEARANCE CHANGES (MILS)

*	Panigo .			Transpert	1.		
Location	Jeangin	E.202 100.60C	E-283 100 per	E·204 100 pec	E-207 275,000	E 208 115 bec	5-210 504ec
A	13	+ 2.4	-1.7	+3.1	+4.6	+3.7	+2,2
B	13	+ 1.9	-1.3	+2.6	+3.5	+2.8	+2.4
C	50	+6.7	-7.2	+9.2	+11.8	+10,6	+6.6
P	50	+0.9	+ 5.2	-0.7	-1.5	-0.9	+2.6
E.	50	+2.0	+2.9	-3.3	- 2.9	-3,7	-3,0

Note =

The value listed under the transient column are <u>changes</u> in the original clearance at isothermal temperature conditions.
For example, at location A, the original clearance (13 mils) is increased by 0.0024 inch during Event E 202 and decreased by 0.0017 inch during E 203.

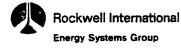
bee Figures 2



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APPENDIX C

# TRANSIENT ANALYSIS - COMPUTER LISTING (TAP PROGRAM)

(Computer printout removed for brevity.)



## APPENDIX K

VERIFICATION OF THERMAL MODEL FOR ISIP (INTERMEDIATE-SIZE INDUCER PUMP)

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### TABLES

# <u>Table</u>

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I. INTRODUCTION

The ISIP (Intermediate-Size Inducer Pump) is to be installed within the FFTF pump casing. A thermal model has been set up by AI to represent the ISIP, using techniques of the STAMP and TAP computer programs. The purpose of this thermal model is for use in calculating the thermal behavior of the ISIP during transients. The results are to be employed in stress and deflection analysis.





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### II. PURPOSE

The purpose of this report is to show the results of checkout runs with the computer thermal model of the ISIP (Intermediate-Size Inducer Pump). The calculated results are compared to the experimental measurements taken during the thermal testing of the FFTF pump. The agreement between the experimental and computer temperature values is reasonably good, such that the thermal model of the ISIP can be considered to be an adequate thermal representation of the pump.

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III. DISCUSSION

The FFTF pump underwent extensive thermal transient testing, as reported in Reference 1 (Westinghouse Report 5080). A series of nine transients were planned to be run. Herein, these are referred to as "SPECIFICATION TRANSIENTS," and are shown in Table I (also see Reference 2). The sodium flow rate and pump inlet sodium temperature versus time is indicated.

The manipulation of the experimental facility does not allow exact duplication of the transient that is planned (due to imperfect control on flow rates, temperatures, etc.). Thus, the transients to which the FFTF pump was actually subjected were somewhat different, and are herein referred to as "test transients." These are shown in Figure 1 and Table II, as taken from Reference 1.

The casing of the FFTF pump has been modified somewhat for the installation of different components, such as to form the ISIP (ISI pump). Much of the overall structure remains unchanged. A thermal model has been set up to represent the ISIP using the STAMP and TAP computer programs (References 3 and 4). As a checkout of this model, three test transients were run: 205-TEST, 207-TEST, and 210-TEST (see Figure 1). These three were chosen because:

- Transient 205 is one of only two "up" transients (the 1) other being almost identical in nature)
- Transient 207 is the "down" transient with the greatest 2) overall temperature drop (nominally 330<sup>o</sup>F)
- Transient 210 is the "down" transient with the steepest 3) slope, dT/dt (nominally 3.0°F/sec).

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In Reference 1, temperature versus time plots are shown for 14 different locations (where thermocouples were installed) for both test measurements and Westinghouse's prediction of temperature response. Plots of AI's calculational results for those some 14 locations have been superimposed on the measured and Westinghouse prediction curves taken from Reference 1. These are shown in Appendix A.

The AI data is the calculated response of the nodal points in the AI TAP thermal computer model lying closest to the thermocouple locations. The nodal map for the AI thermal model is shown in Figure 2.

The thermocouple locations are shown in Figures 3a and 3b. Also indicated are the location designations (1 through 14) used in the plots of Appendix A and the AI thermal model node numbers. Reasonably good agreement was obtained between AI's calculations and the measured data, as can be seen by inspection of the figures of Appendix A.

For Location 1, quite good agreement was obtained between AI calculations and measured data.

For Location 2, there was no measured data for 205, with a wide discrepancy between AI and Westinghouse predictions. For 207, there is good agreement with measured data. For 210, there is moderately good agreement, although AI is showing somewhat faster response. The zone of Location 2 is a large sodium cavity in which the mode of mixing is quite uncertain. However, it is a region that does not affect bearing behavior.

For Location 3, Transient 205, agreement between measurements and AI data is not very close, although AI's preduction is closer than the Westinghouse values. For 207 and 210, AI's data shows more sluggish

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response than the measured data. Location 3 is a large sodium zone wherein mixing mode is uncertain. Also, it is a zone that does not influence the bearing region. It would appear that the natural convection parameters in the Westinghouse made gives good response for down transients, but does not for up transients. AI's results are intermediate.

For Locations 4, 5, 6, 7, and 8, agreement is generally quite good, although occasionally there appears to be a stray measurement curve (which does not agree with its fellow TC data).

For Location 9, AI's data shows considerably slower response than both the measurements and the Westinghouse prediction. This is because in this region the ISIP's design is different. The zone represented by Location 9 has an extra steel barrier between itself and the flow sodium, so as to delay the transient being felt there.

For Locations 10, 11, 12, 13, and 14, agreement between AI values and the measured data is quite good.

When inspecting the temperature versus time curves of Appendix A, it should be borne in mind that there is some displacement of the measured temperature, due to an offset in the reading of the thermo-couples. This is sometimes as much as  $20^{\circ}$ F. Mental adjustment for this displacement should be made when comparing the curves of measured and calculated data.

In addition to the temperature versus time plots shown in Appendix A, several sets of temperature differentials versus time are shown in Appendix B. Temperature differentials between Location Pairs 4-8, 4-9, 4-10, and 4-11 are given. All are expected to show agreement, except Location Pair 4-9. Because of the design change and the resultant more sluggish response at Location 9, the temperature differential,  $\Delta T = T4 - T9$ , should be considerably less than in the FFTF test. The figure of Appendix B shows that that is the case.

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#### IV. CONCLUSION

The purpose of this set of three transient calculations was to check out the thermal computer model set up for the Intermediate-Size Inducer Pump (ISIP). Comparison of the test with the FFTF pump indicates that the model is satisfactory. On this basis, it is judged that the model can be used for further calculations involved in the thermal analysis of the ISIP.

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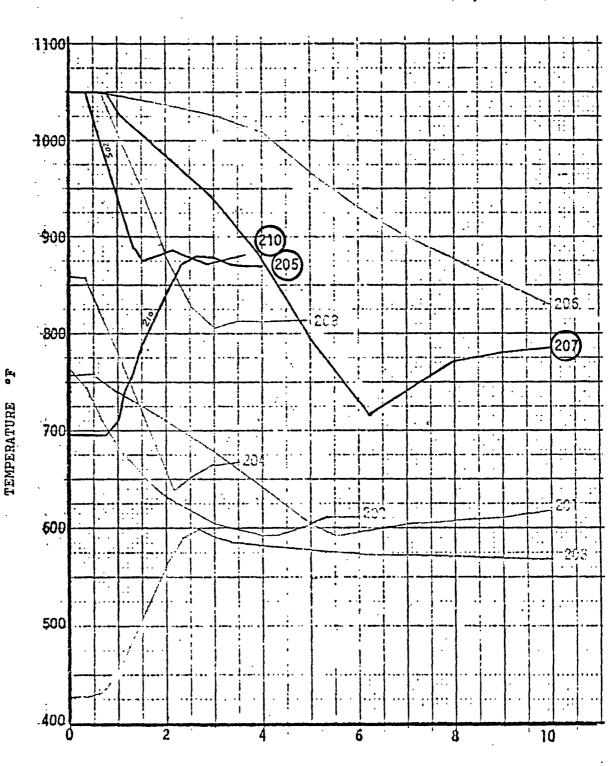
## FIGURE 1

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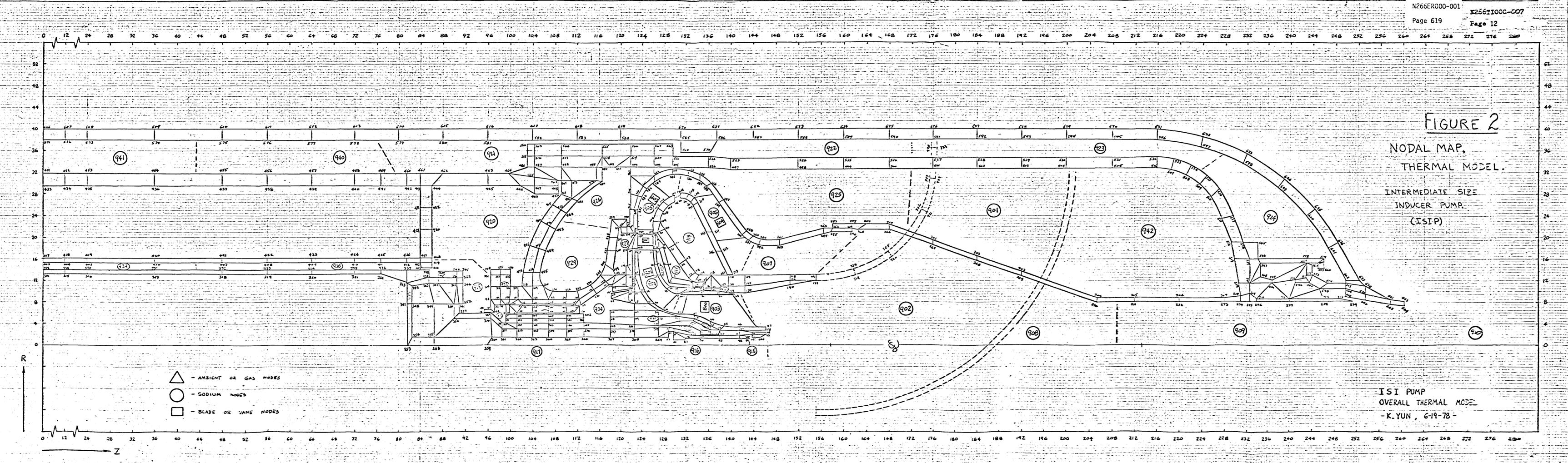
"TEST-TRANSIENTS" For FFTF Testing

Taken from Pg. 34, Figure 9 of Westinghouse E.M. #5080, Reference 1.

See: 205-TEST 207-TEST 210-TEST



TIME, Minutes



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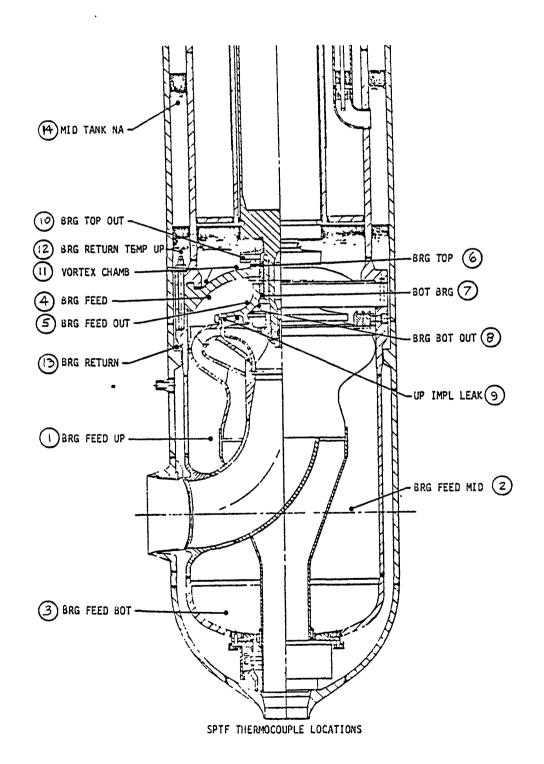
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FIGURE 3-a

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FFTF TEST THERMOCOUPLE LOCATIONS

Taken from Pg. 30, Figure 5 of Westinghouse E.M. #5080, Reference 1. () Circled locations correspond to Appendix A locations.



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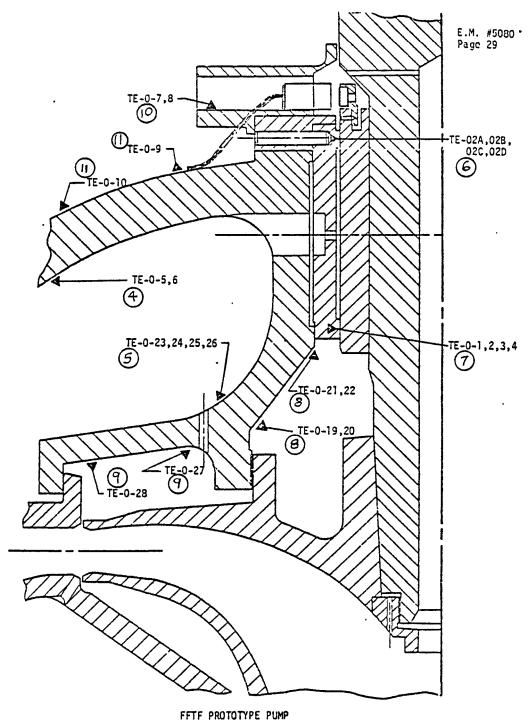
Page 14

FIGURE 3-b

FFTF TEST THERMOCOUPLE LOCATIONS

(Bearing Area)

Taken from Pg. 29, Figure 4 of Westinghouse E.M. #5080, Reference 1. (2) Circled locations correspond to Appendix A locations.



BEARING AREA THERMOCOUPLES

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# TABLE I

# SPECIFICATION TRANSIENTS

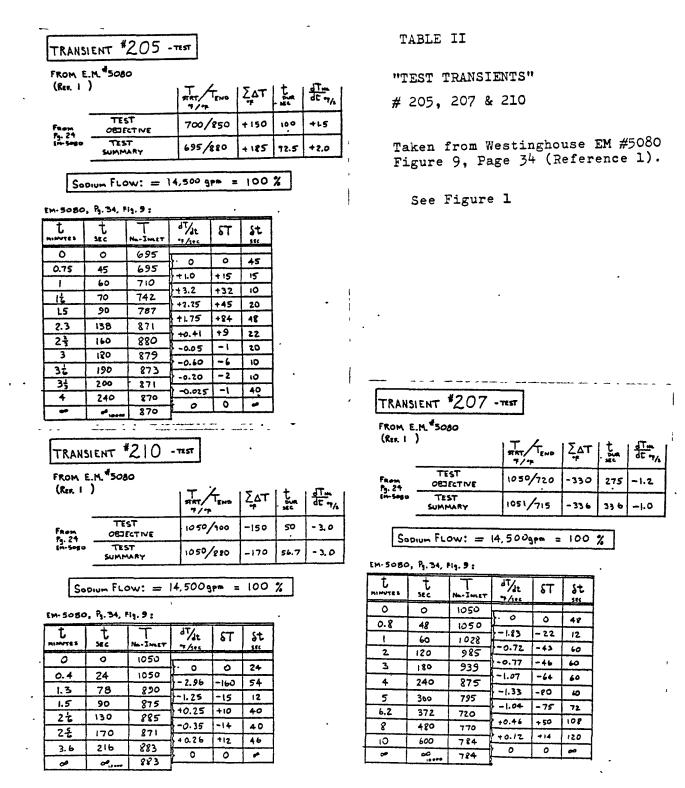
(Taken from Table 4-II, Reference 2)

Transient Number	Flow (gpm)	Initial Temp. (F)	Final Temp. (F)	Temp. Change (F)	Trans Rate (F/sec)
201	14,500	750	600	-150	-0.4
202	14,500	750	600	-150	-1.5
203	14,500	500	650	+150	+1.5
204	14,500	850	650	-200	-2.0
205	14,500	700	850	+150	+1.5
206	12,000	1050	720	-330	-0.4
207	14,500	1050	720	-330	-1.2
208	14,500	1050	825	-225	-2.0
210	14,500	1050	900	-150	-3.0

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#### Page 16





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#### V. REFERENCES

- 1. A. E. Reed, "SPTF Thermal Transient Testing: A Comparison of Analysis and Test Results," Engineering Memorandum E.M. 5080, August 1977, Westinghouse Electric Corp., Electro-Mechanical Division, Cheswick, Pennsylvania
- D. R. Paradise, "Specification: Pump, Sodium, Inducer, Intermediate-Size (ISIP," N266ST310001, April 1978, and Rev. A, June 1978, Atomics International
- 3. R. E. Craig, "Stress to Thermal Adaptation Model Program (STAMP) Description and User's Manual," TI-036-610-007, July 1974, Atomics International.
- E. Moody, "Thermal Analyzer Program Revision (TAP-4SG)," TJ-099-411-015, August 1974, Atomics International



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### APPENDIX A

### COMPARISON OF AI CALCULATIONS WITH FFTF TEST MEASUREMENTS AND WESTINGHOUSE PREDICTIONS

Reference 1 (Westinghouse E.M. 5080) shows plots of temperature versus time for 14 locations within the FFTF pump. These are results of test measurements and Westinghouse prediction calculations. The plots for Test Transients 205-TEST, 207-TEST, and 210-TEST are shown in this appendix. The results of AI calculations for the same transients and the same locations have been superimposed upon these curves for comparison. The AI curves are the heavy-dashed lines.

Appendices A-1, A-2, and A-3 are for Test Transients 205, 207, and 210, respectively. The 14 locations are as shown in Figure 3 and in Table A. The location is also shown on each individual plot.

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# TABLE A TEMPERATURE MEASUREMENT LOCATIONS (See Figure 3)

Figure and Location	Location	AI Thermal Model	
Number	Description	Node Number	TE Numbers
1	Brg. Feed Up	925	33, 34
2	Brg. Feed Mid	925	35
3	Brg. Feed Bot	942	36
4	Brg. Feed	929	5,6
5	Brg. Feed Out	929	23, 24, 25, 26
6	Brg. Top	144	2A, 2B, 2C, 2D
7	Brg. Bot	168	1, 2, 3, 4
8	Brg. Bot, Out	934	19, 20, 21, 22
9	Up Impl. Leak	927	27, 28
10	Brg. Out Top	932	7,8
11	Vortex Chamber	<b>`</b> 920	9, 10
12	Brg. Return Temp Up	921	11, 12, 13, 14
13	Brg. Return	922	29, 30, 31, 32
14	Mid Tank Na	940	15, 16, 17, 18



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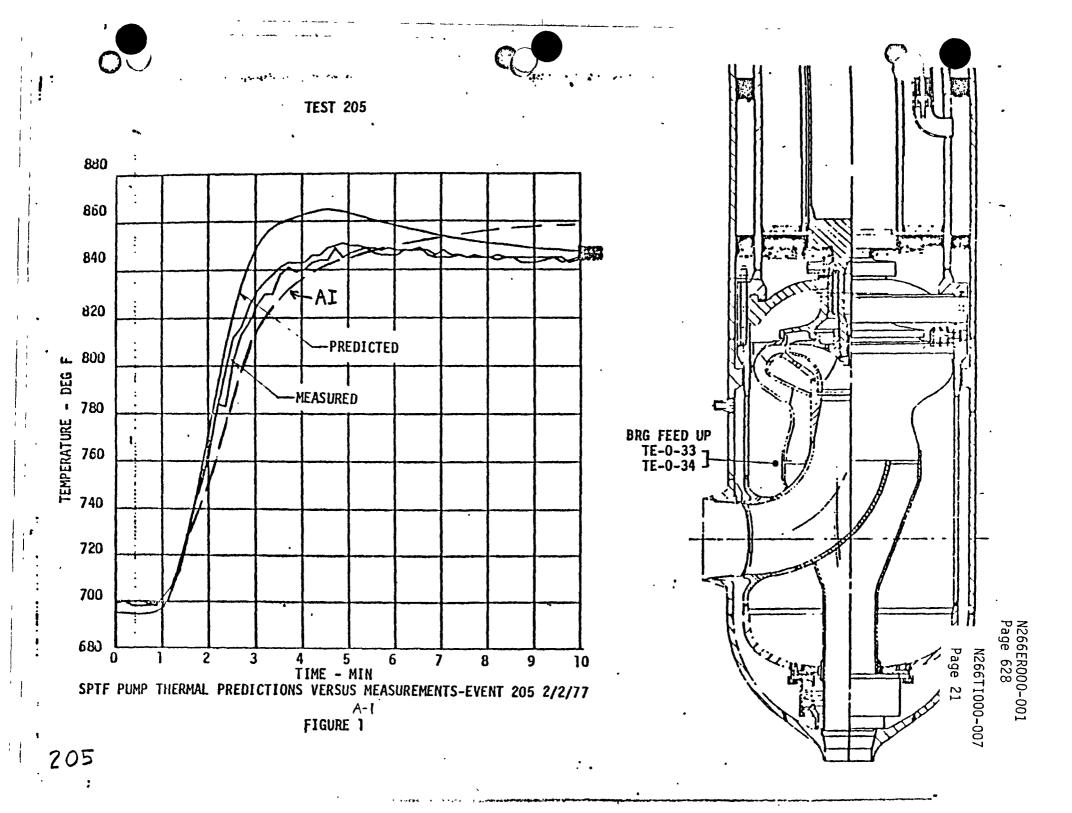
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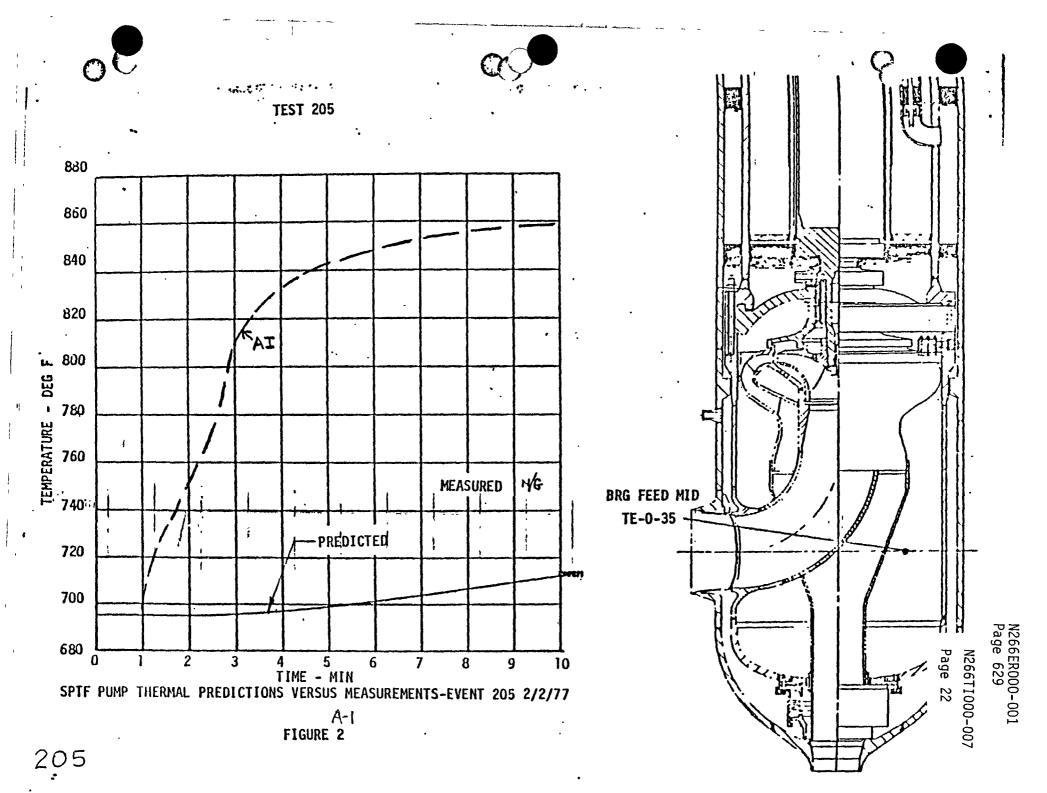
APPENDIX A-1

TRANSIENT 205-TEST



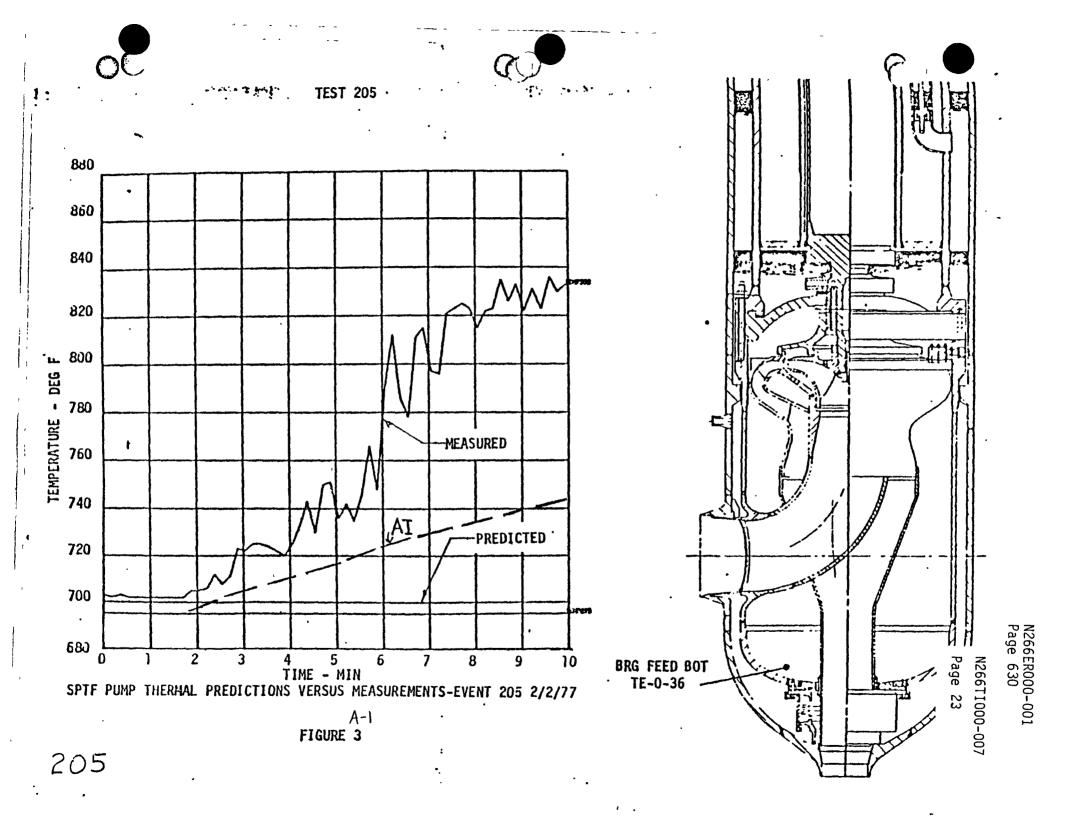
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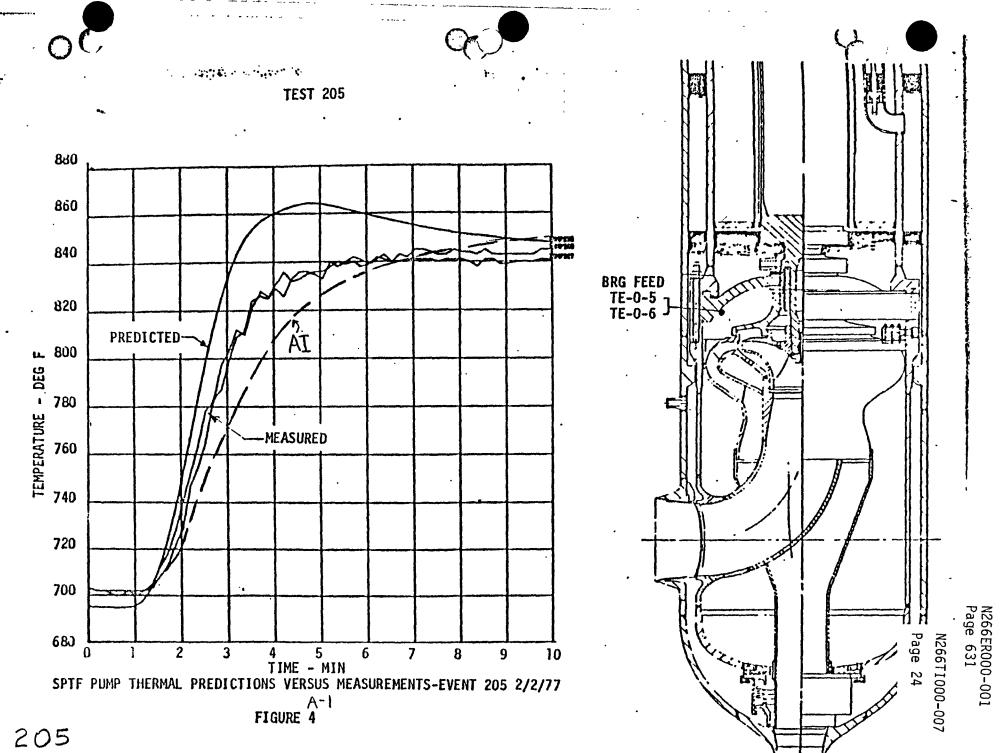




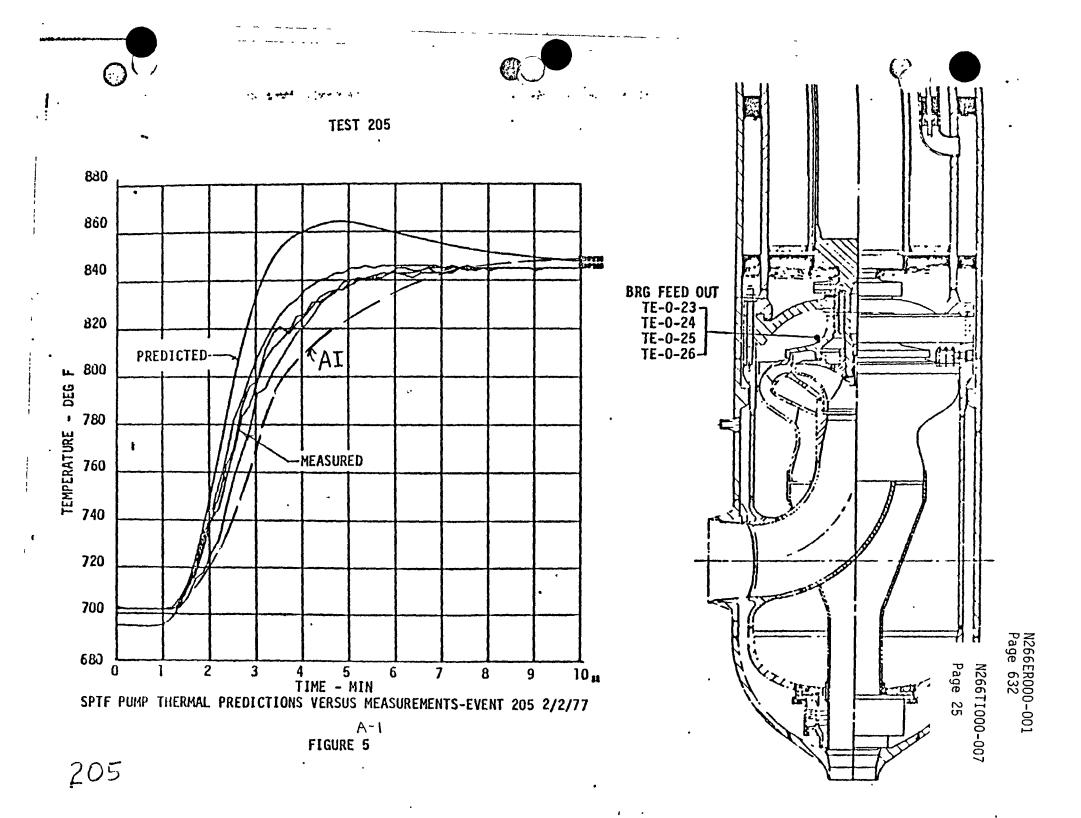
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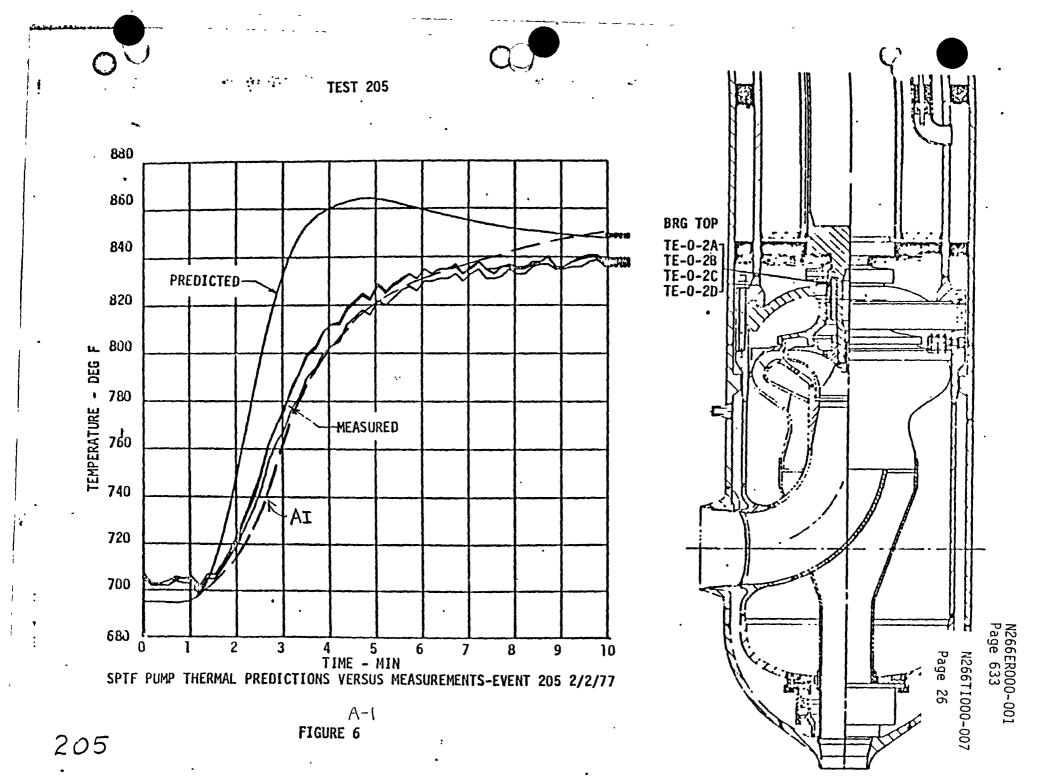
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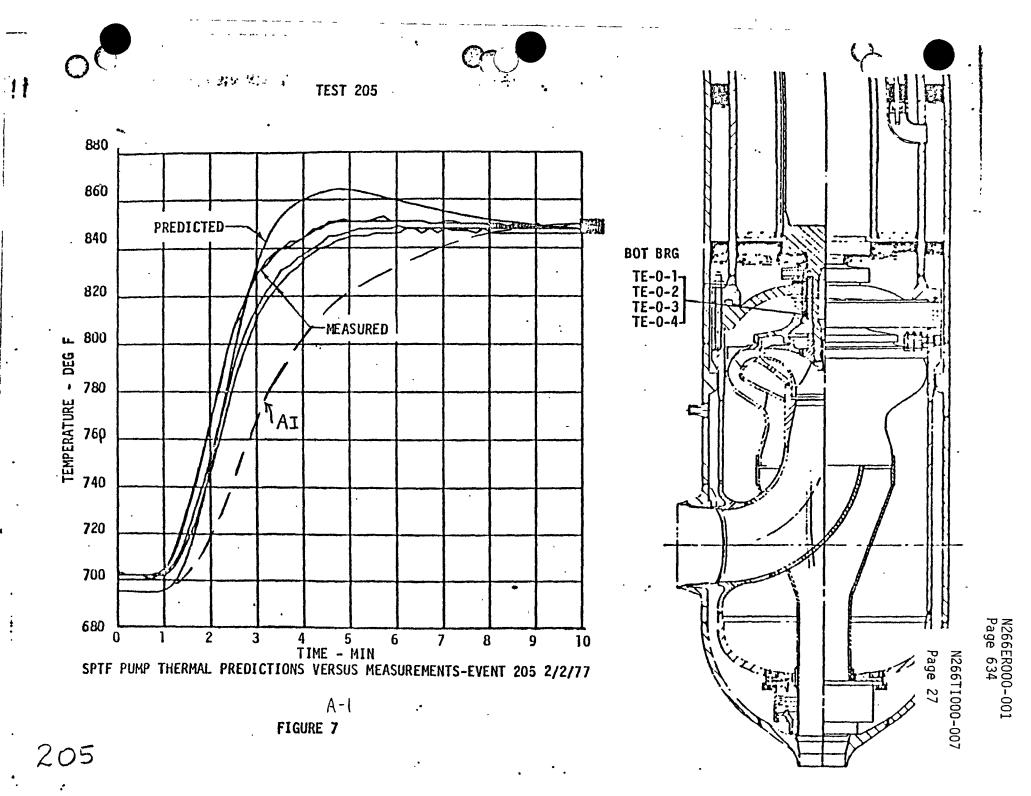


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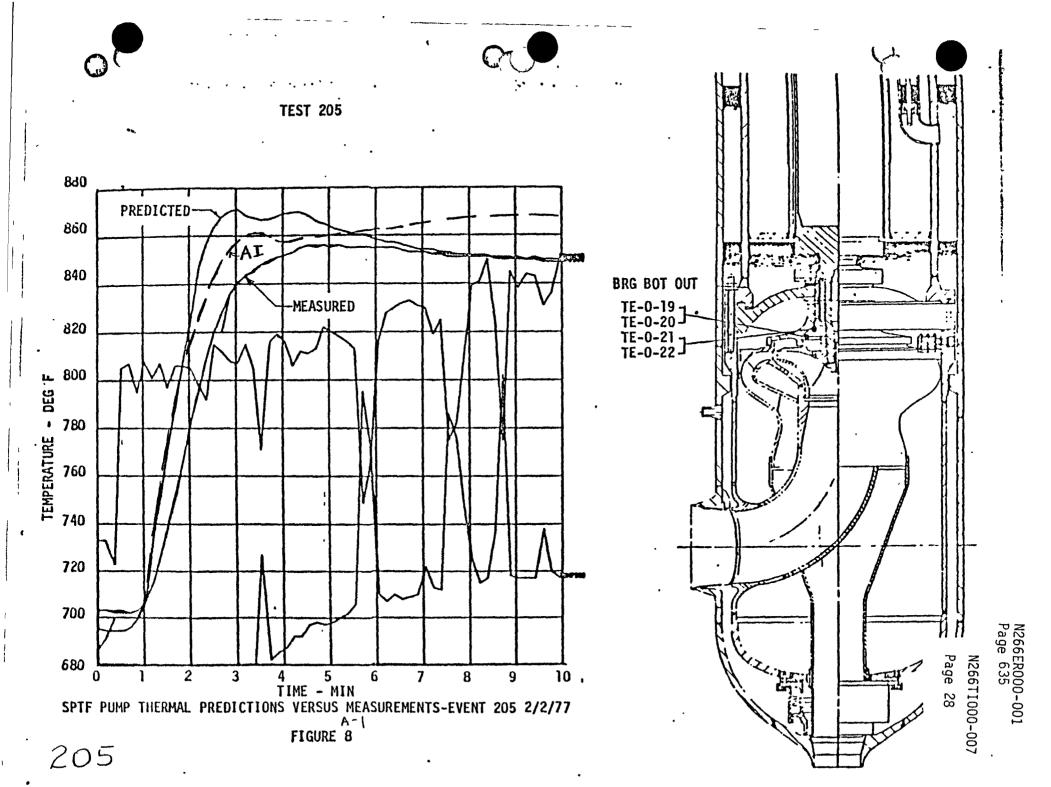


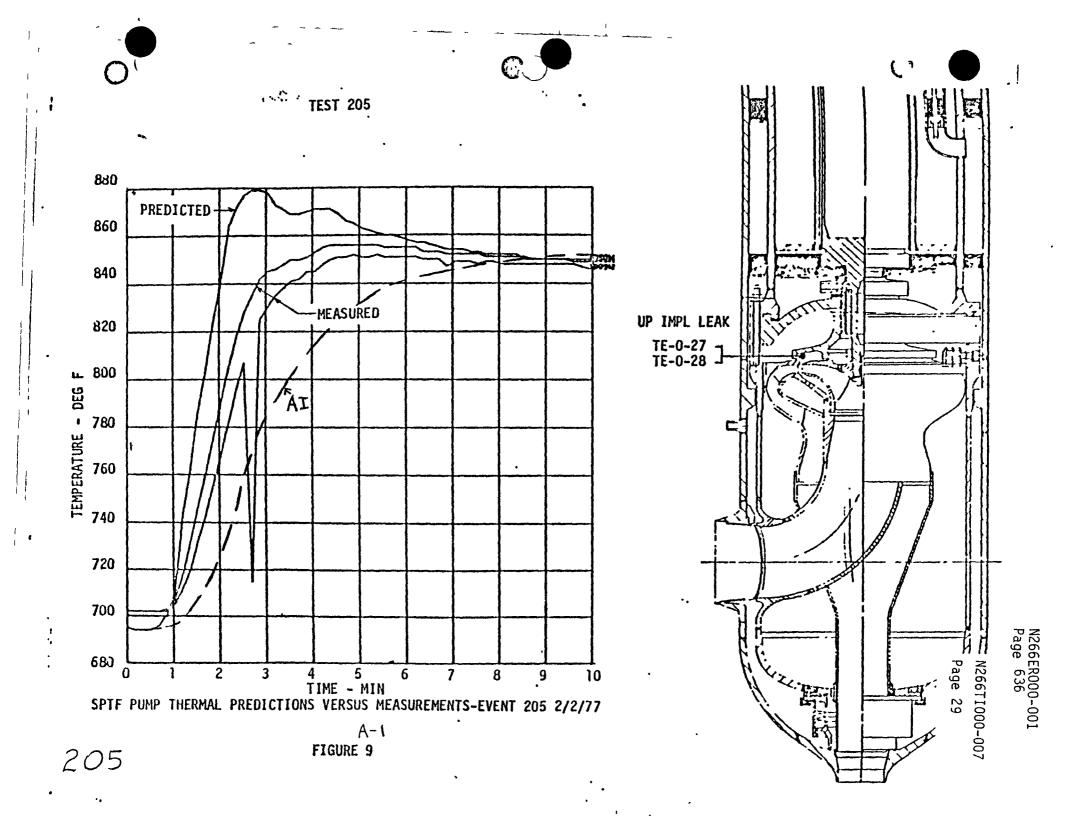


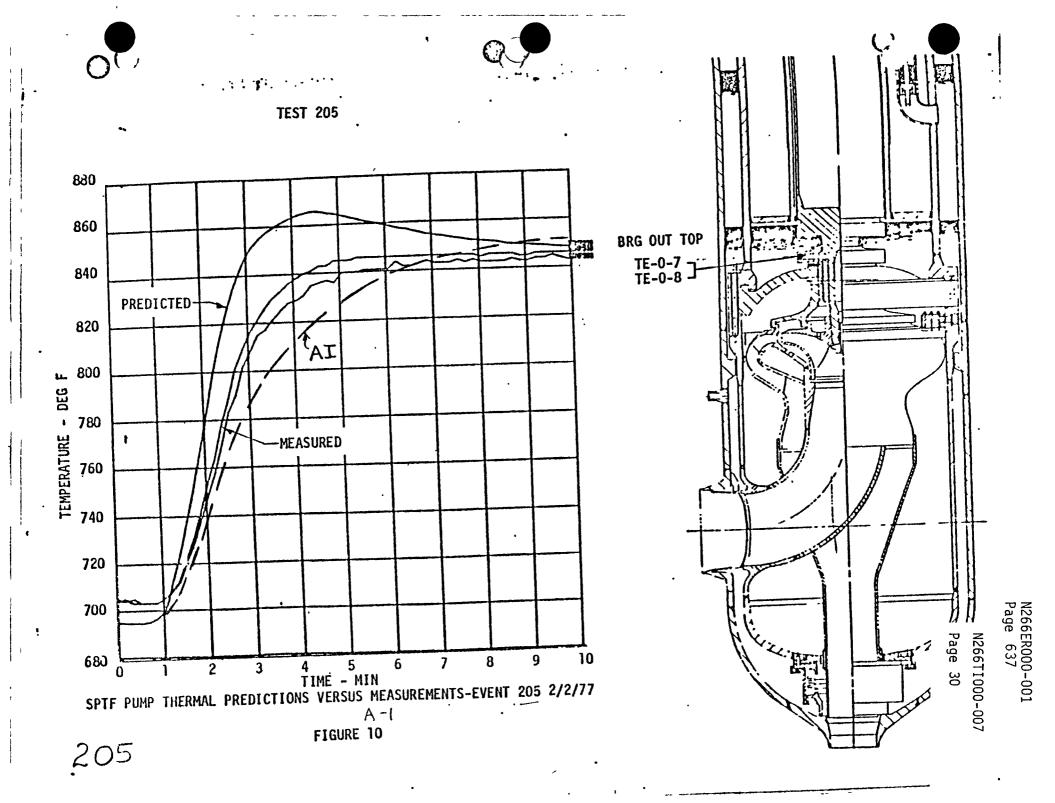
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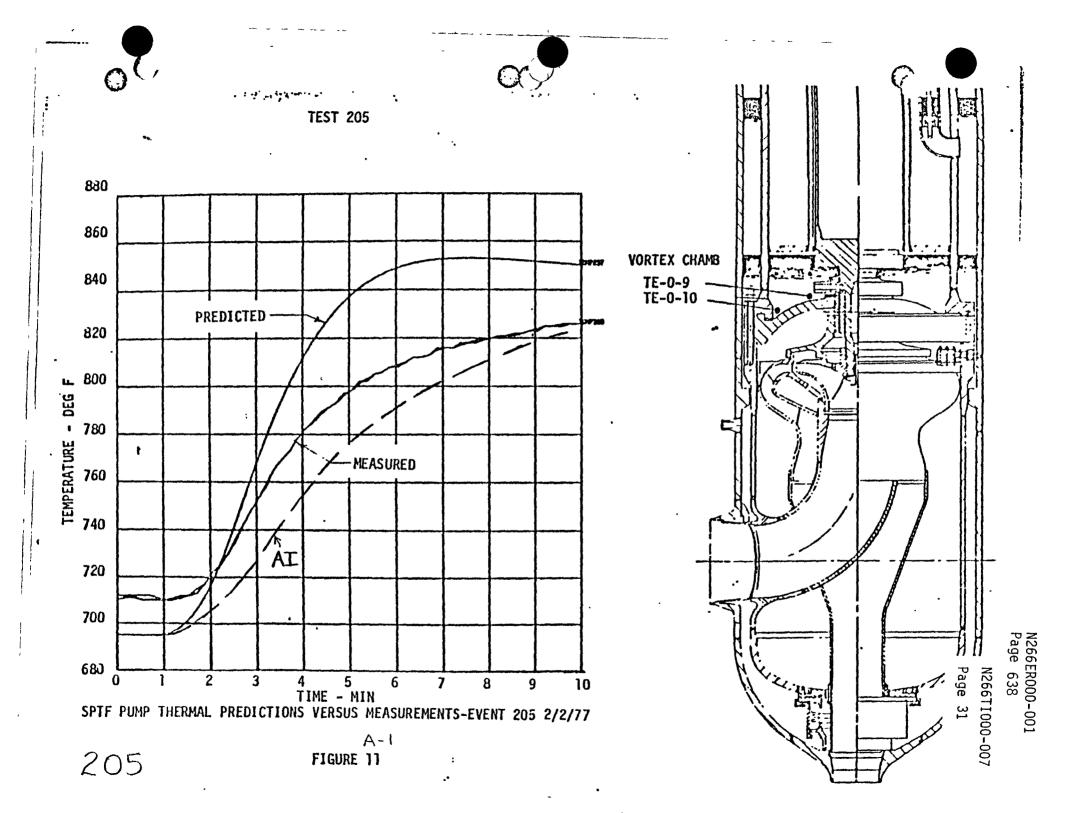


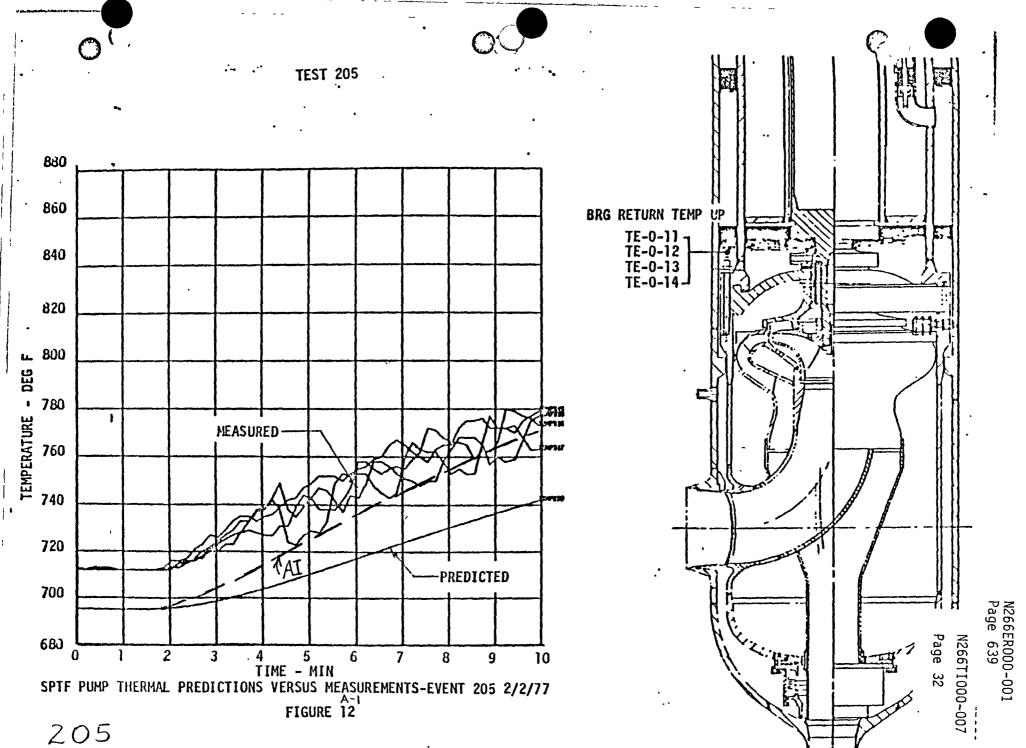
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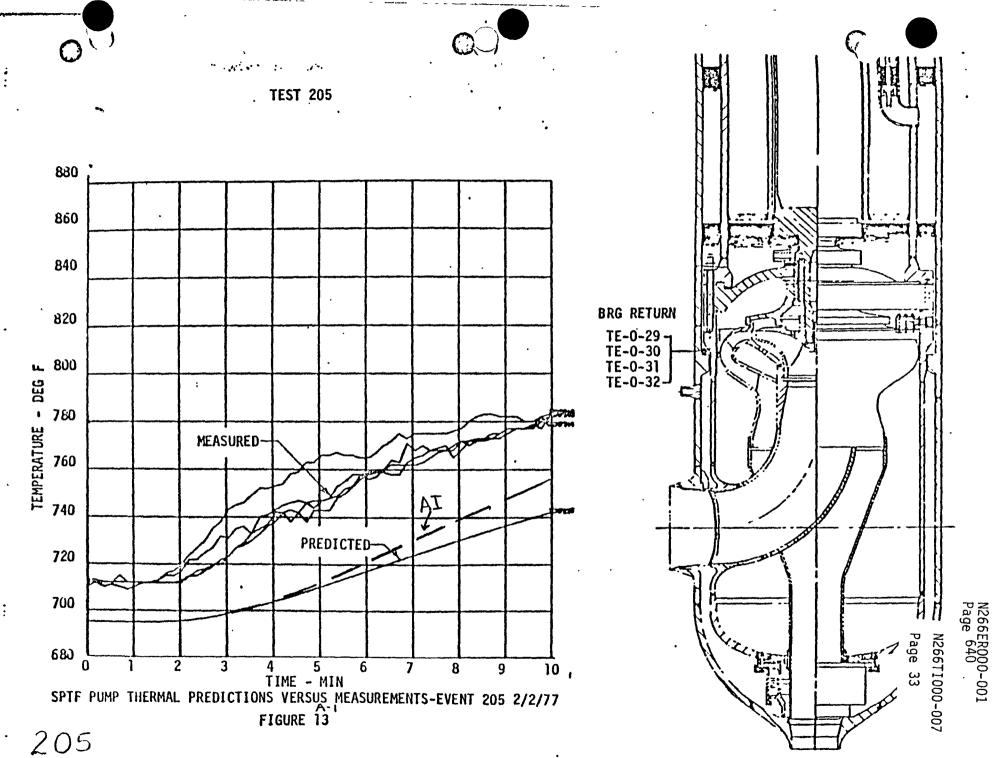


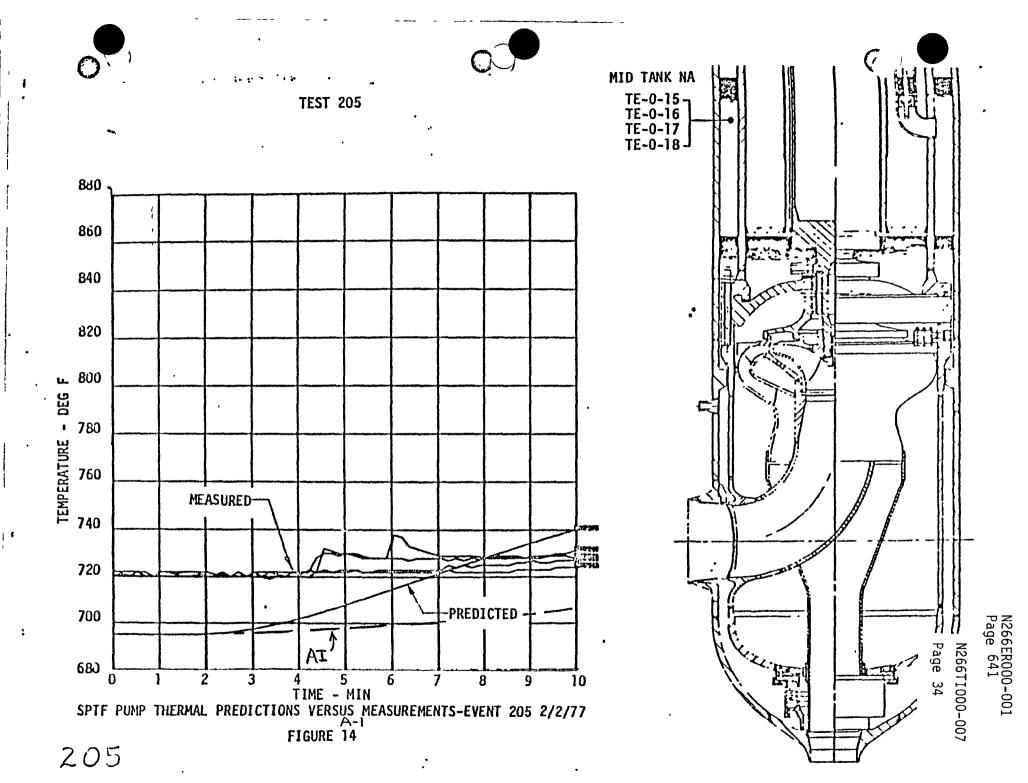














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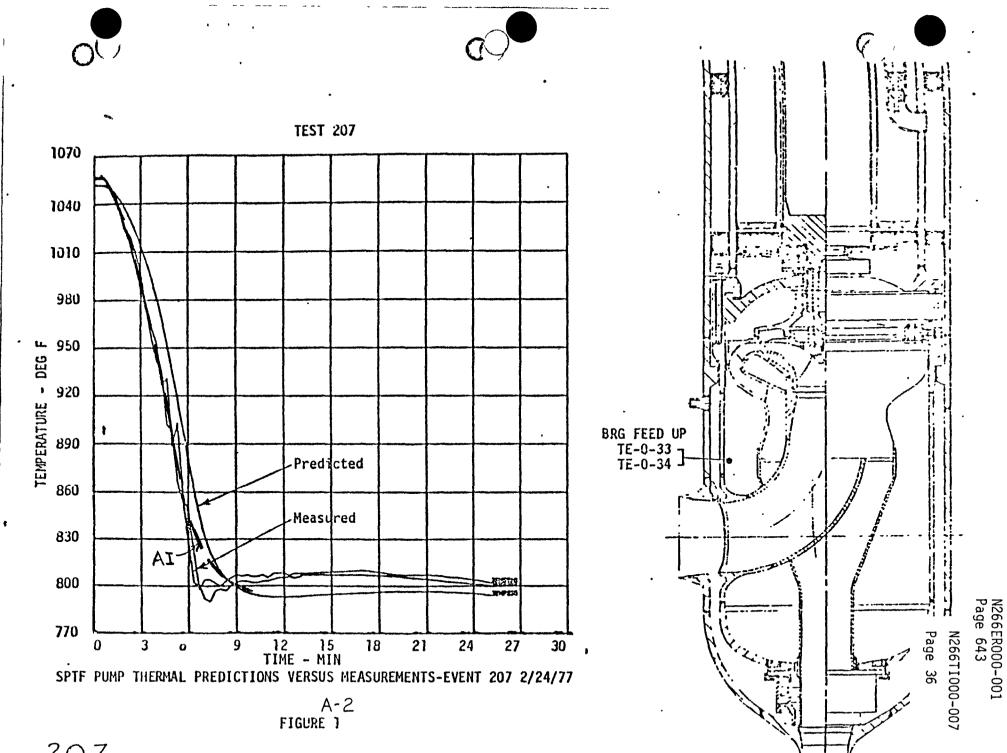
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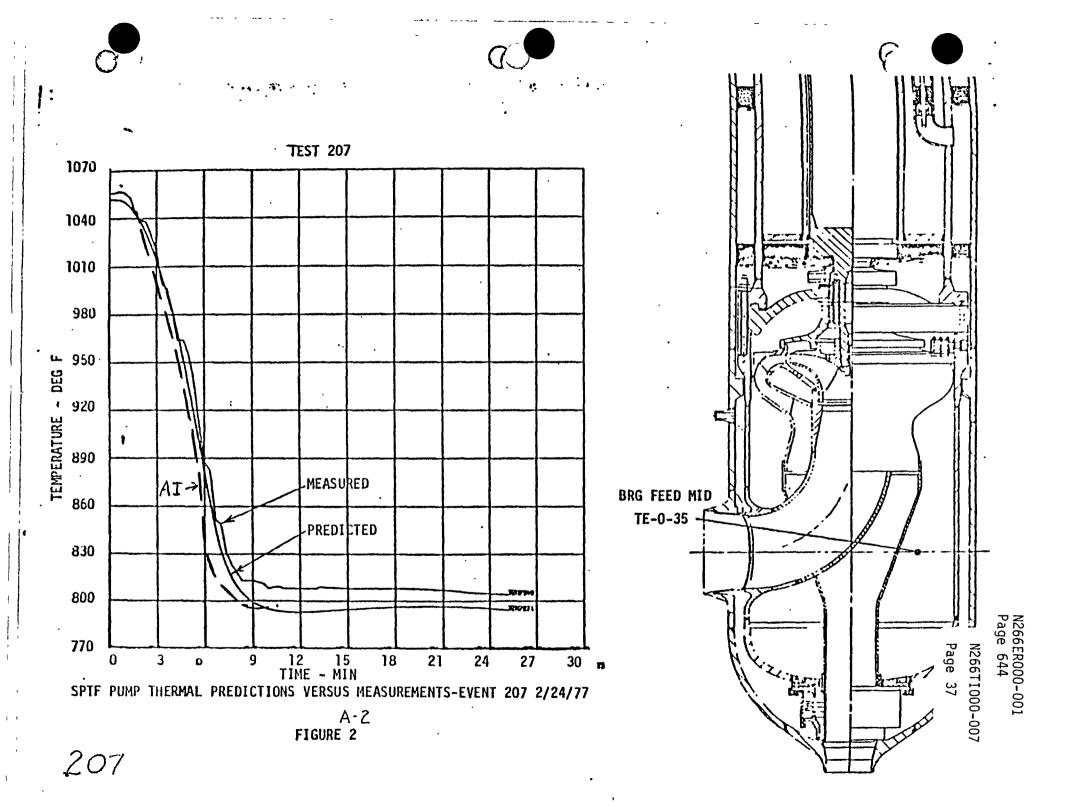
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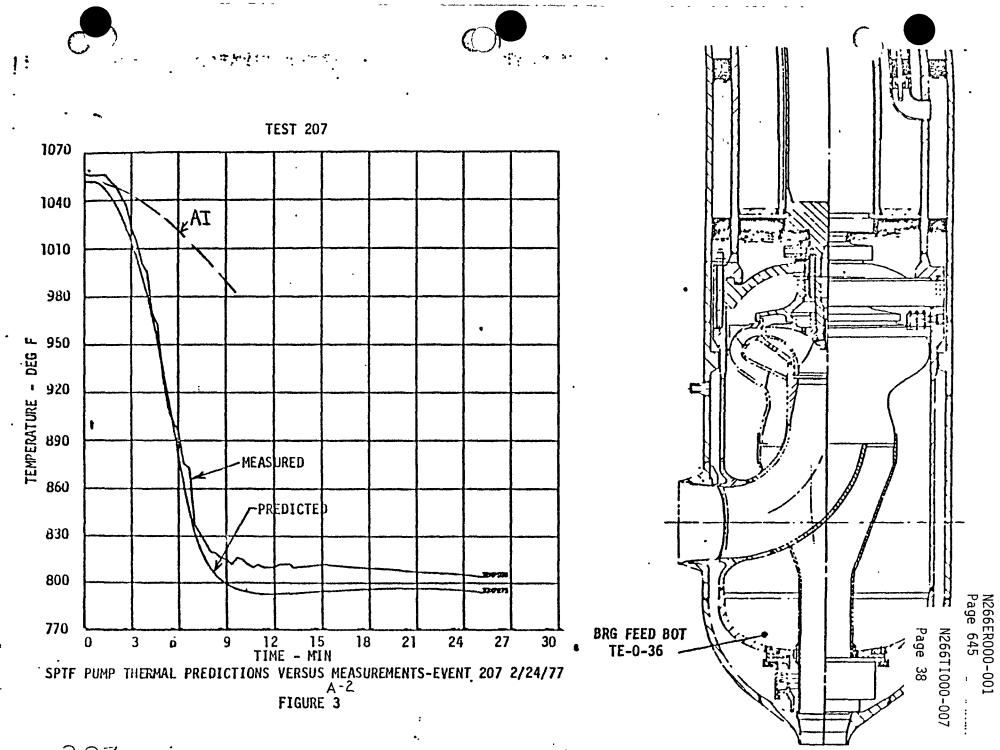
APPENDIX A-2

TRANSIENT 207-TEST

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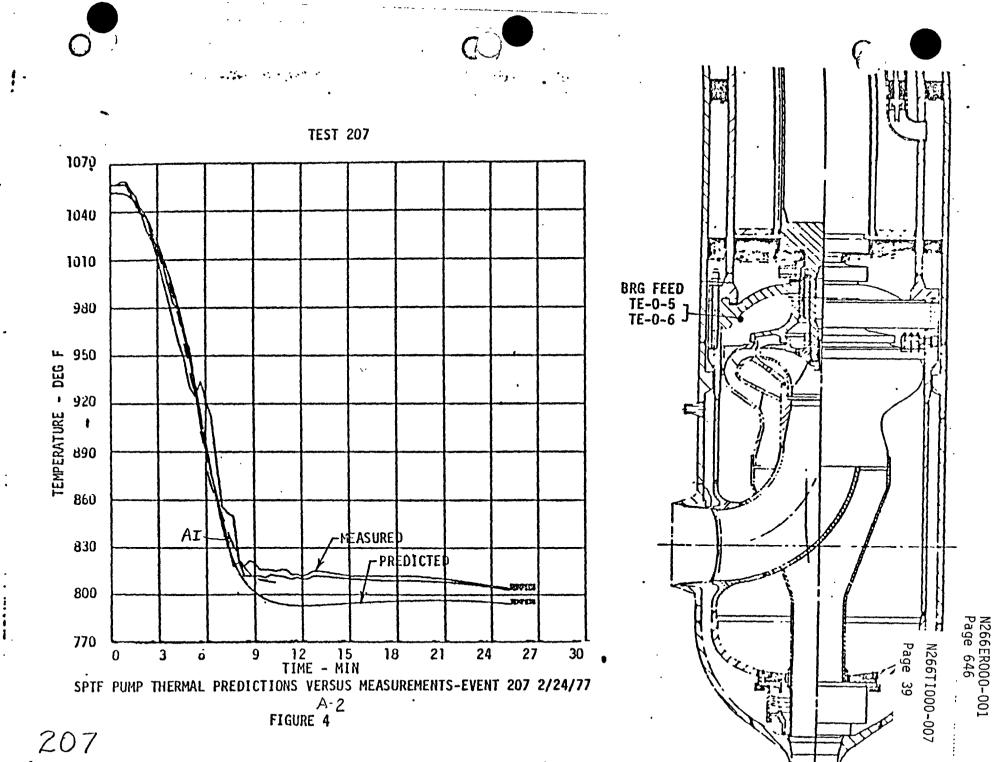


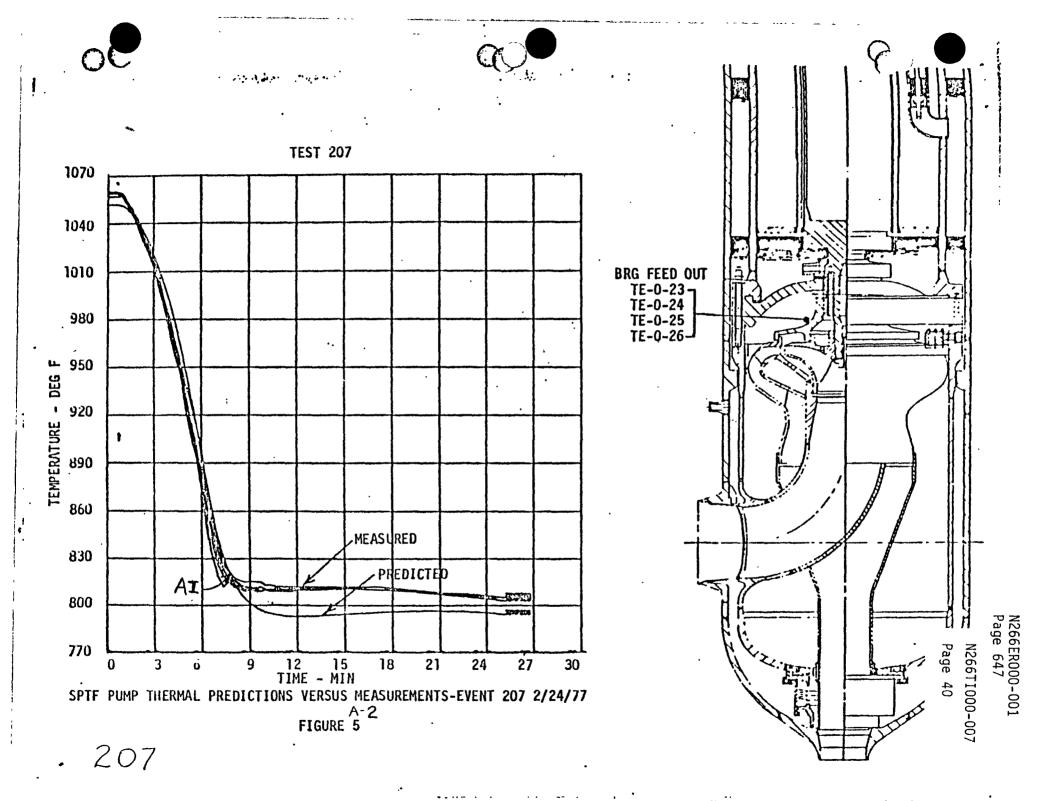


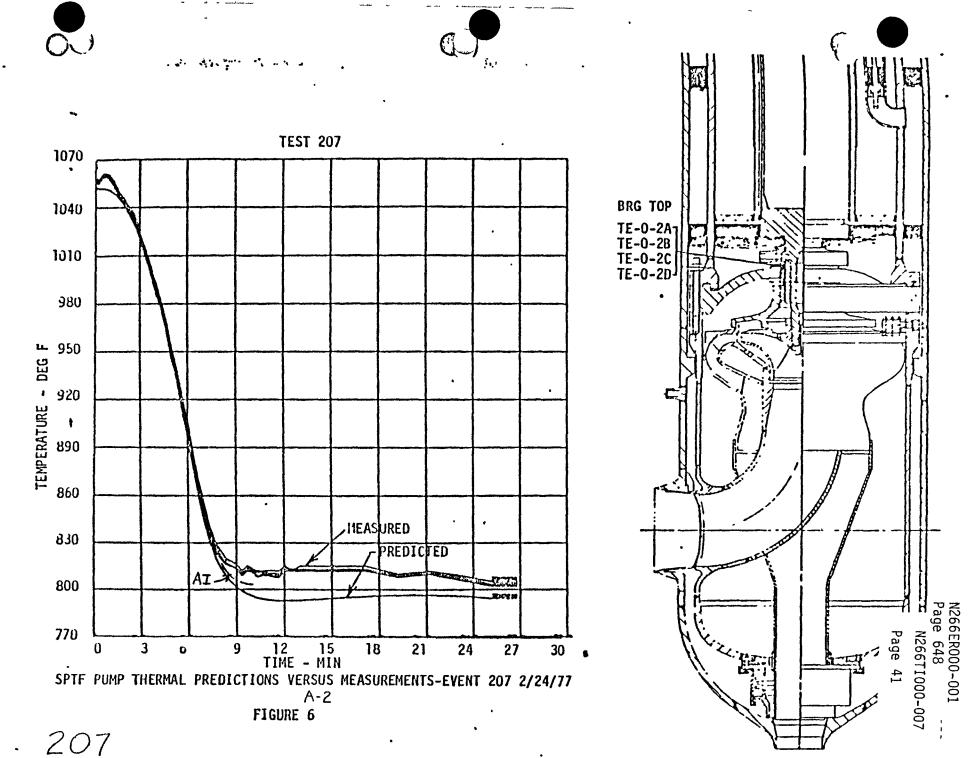


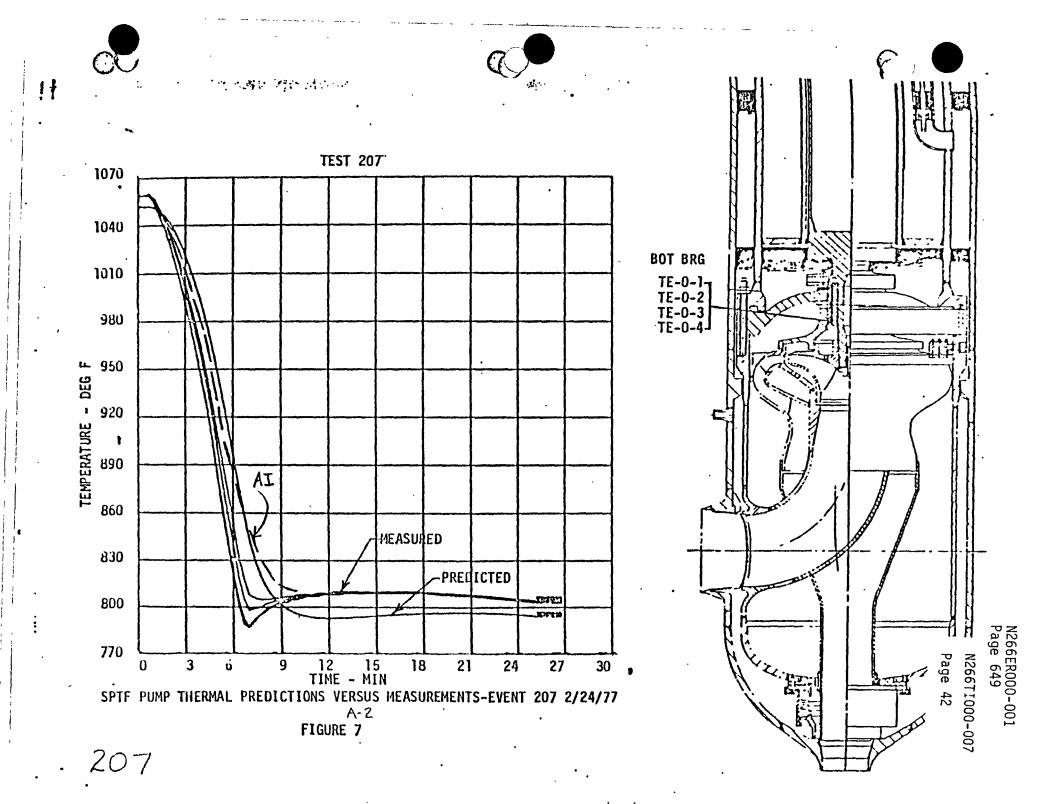
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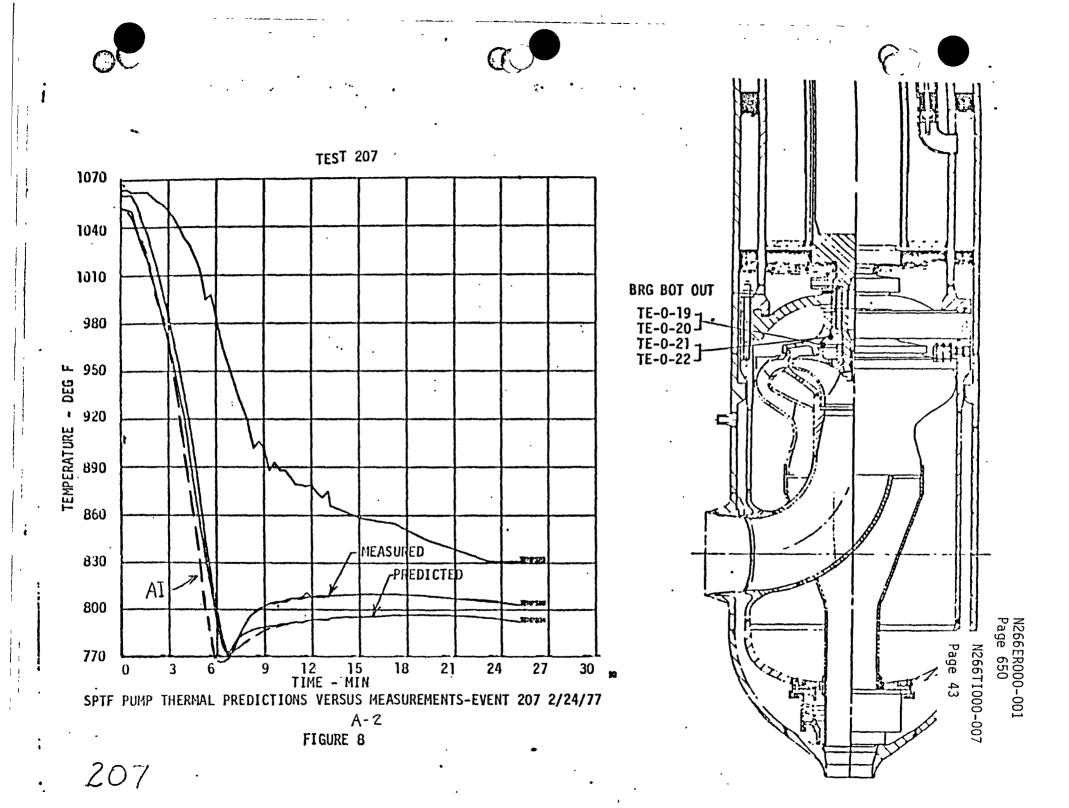
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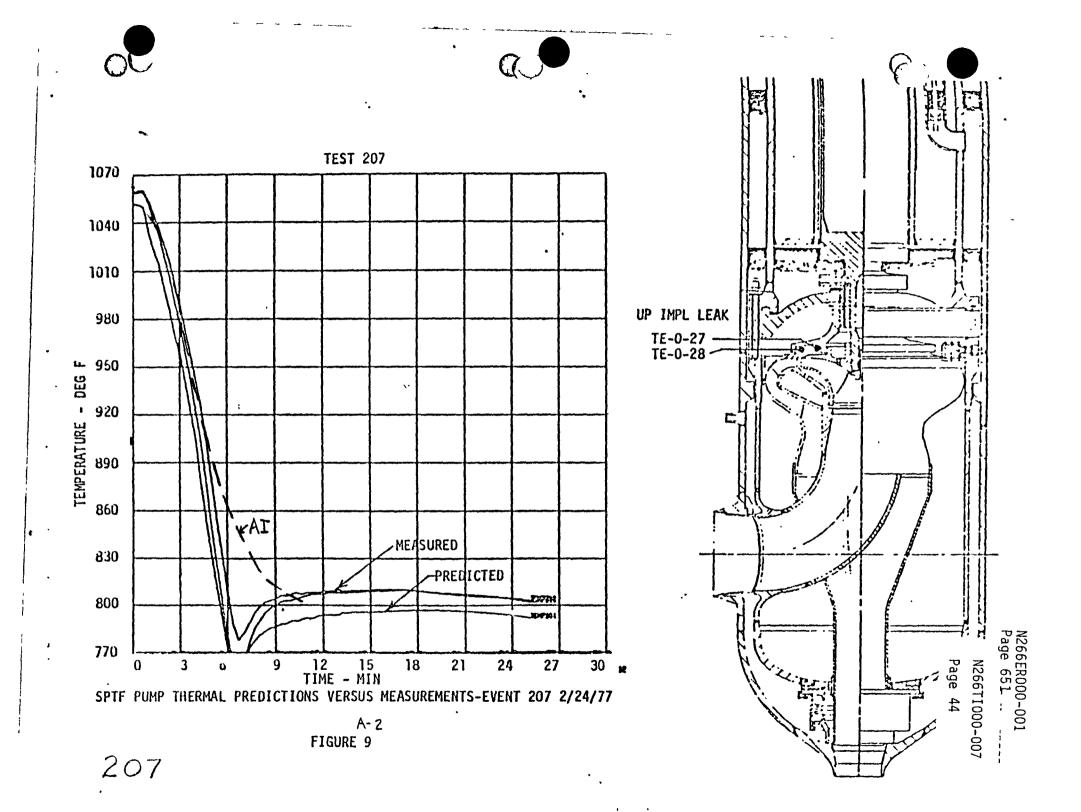


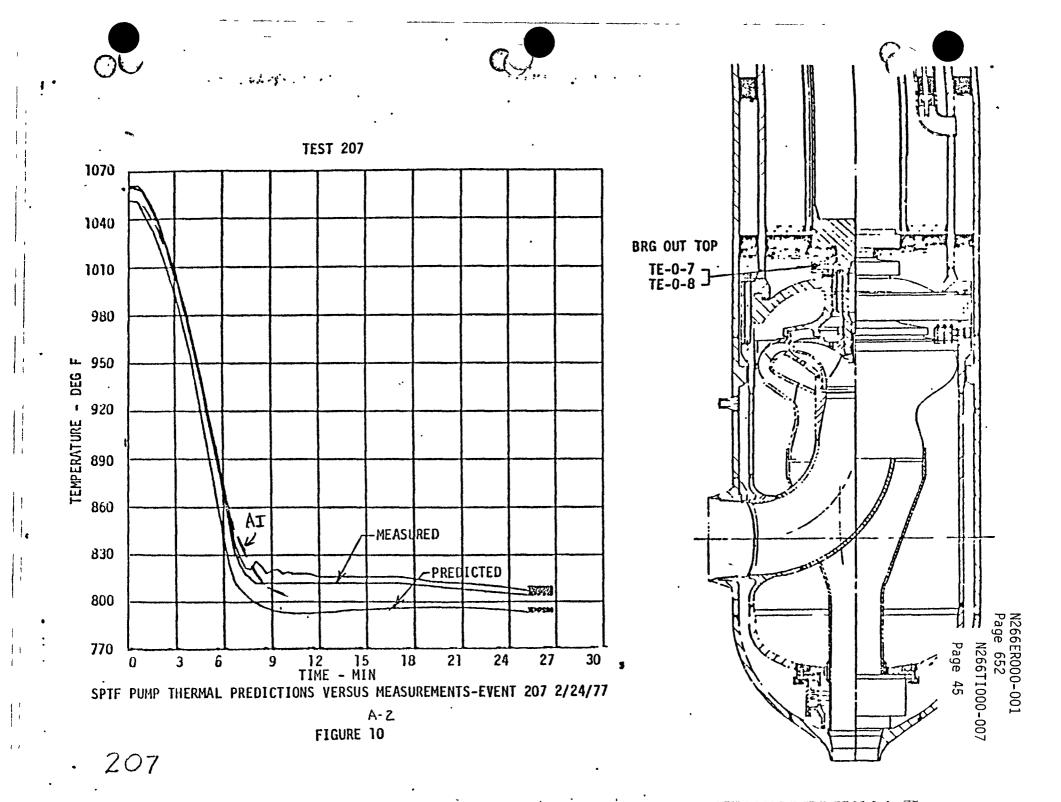


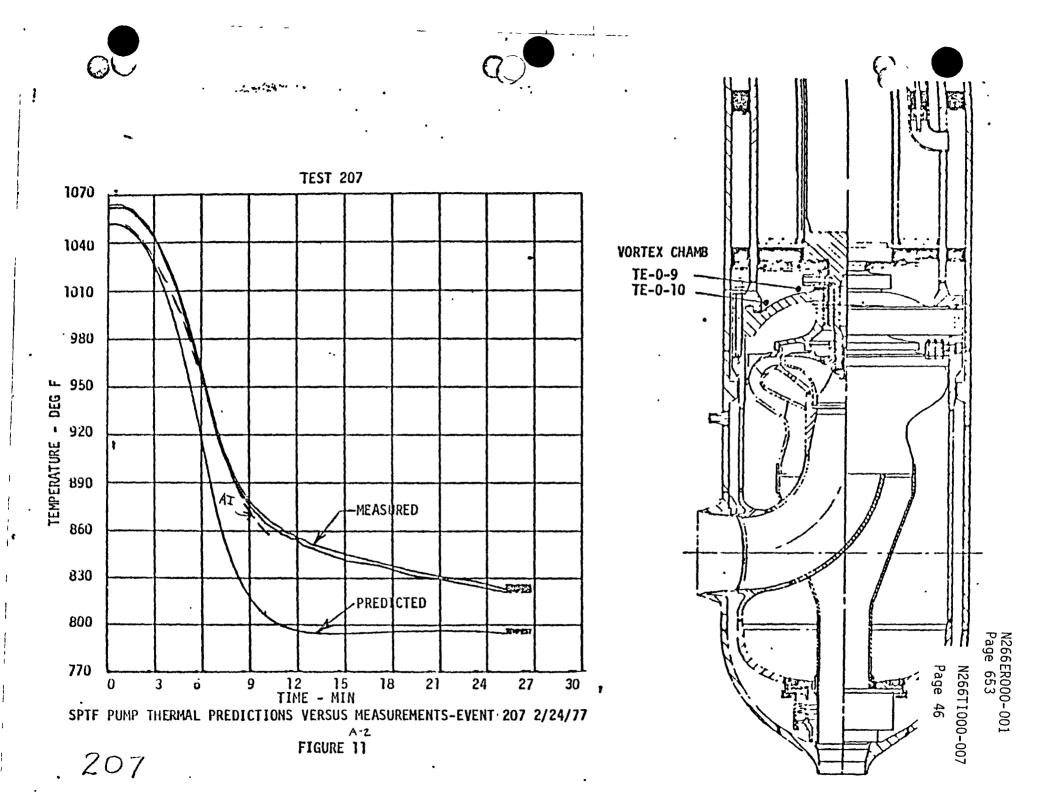




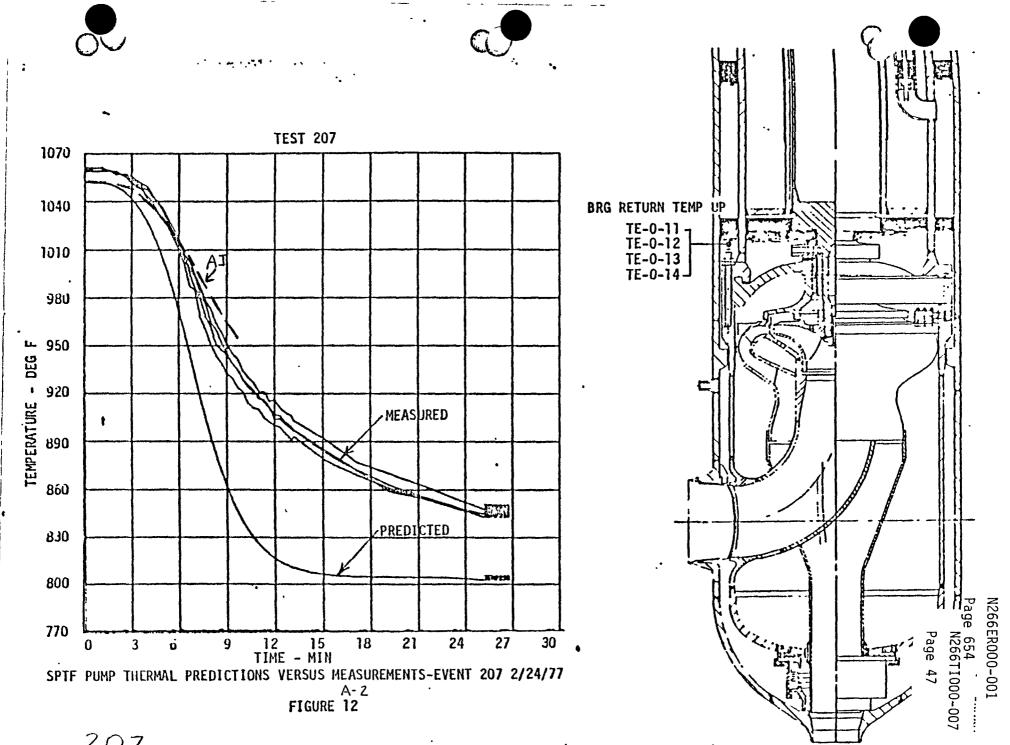


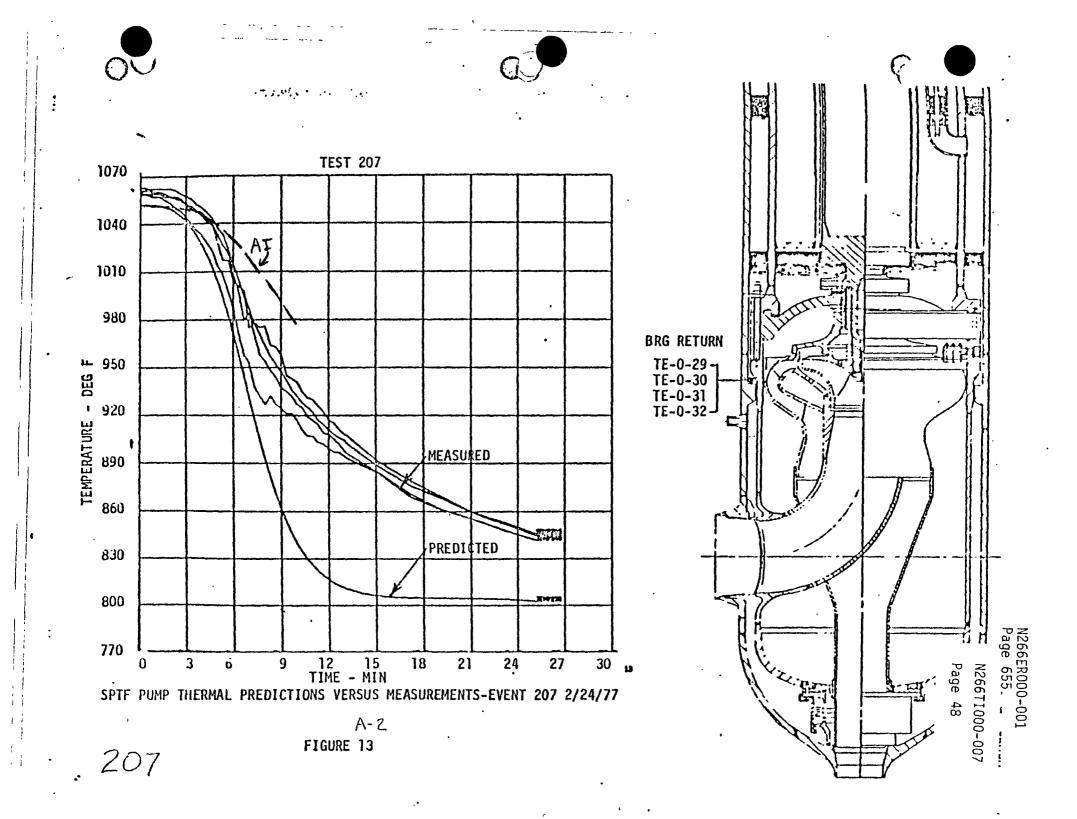


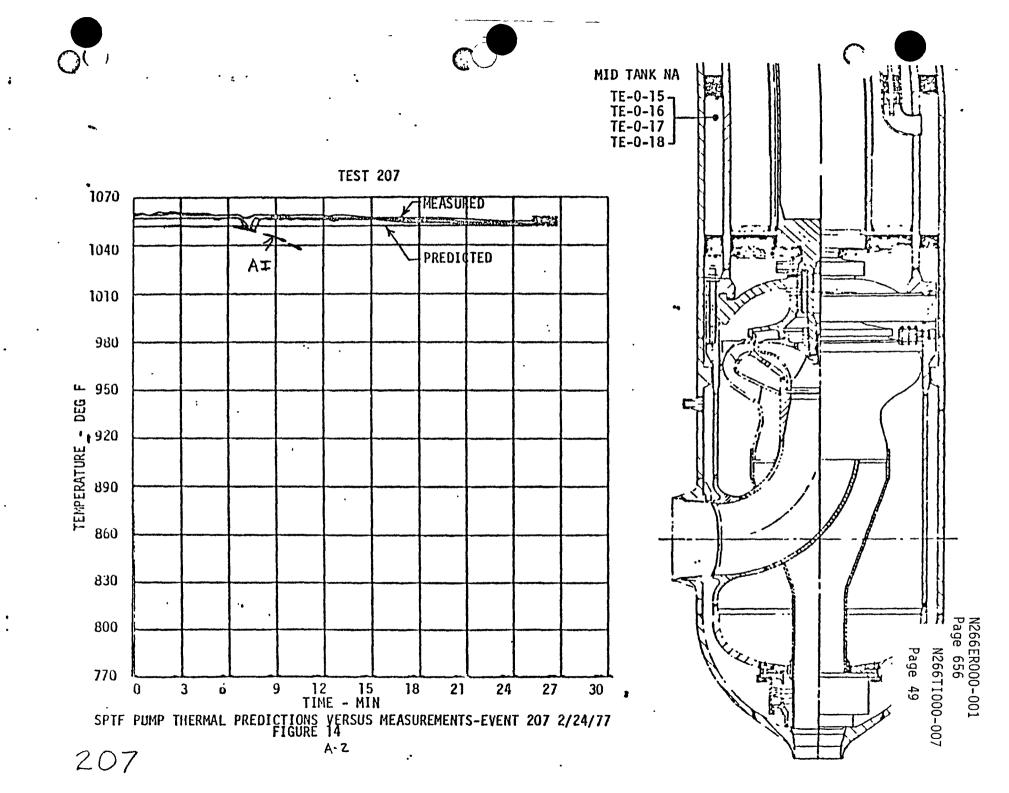




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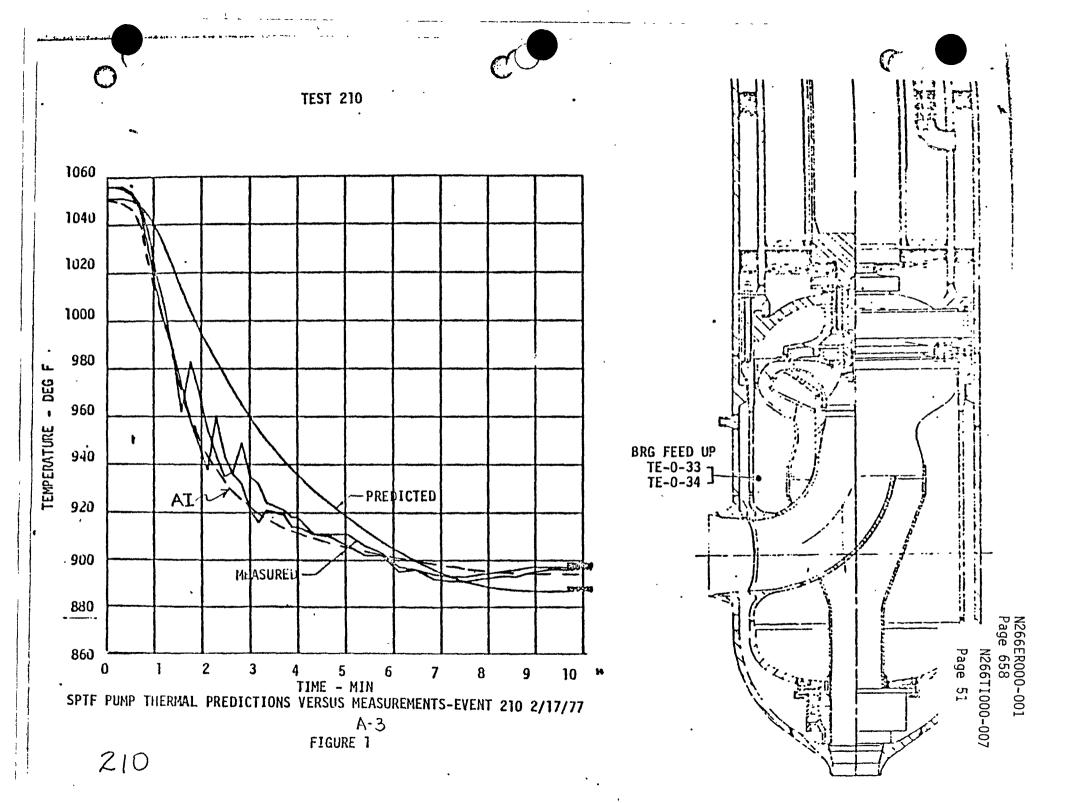


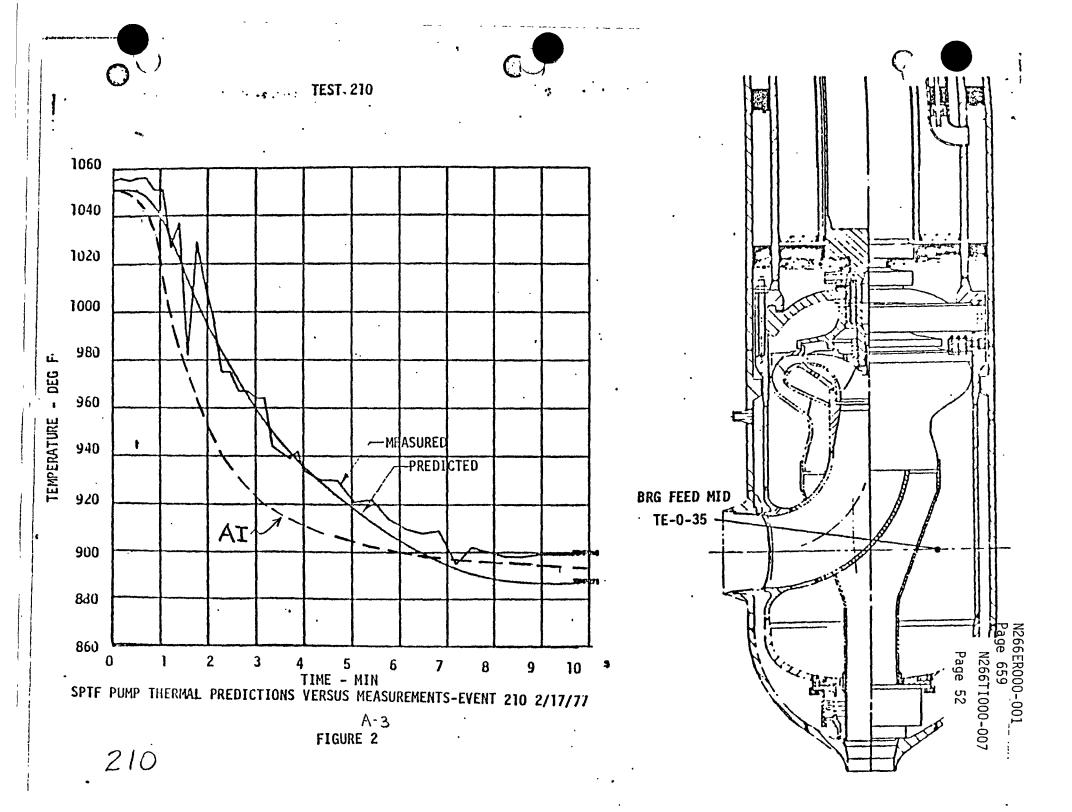
Rockwell International Energy Systems Group

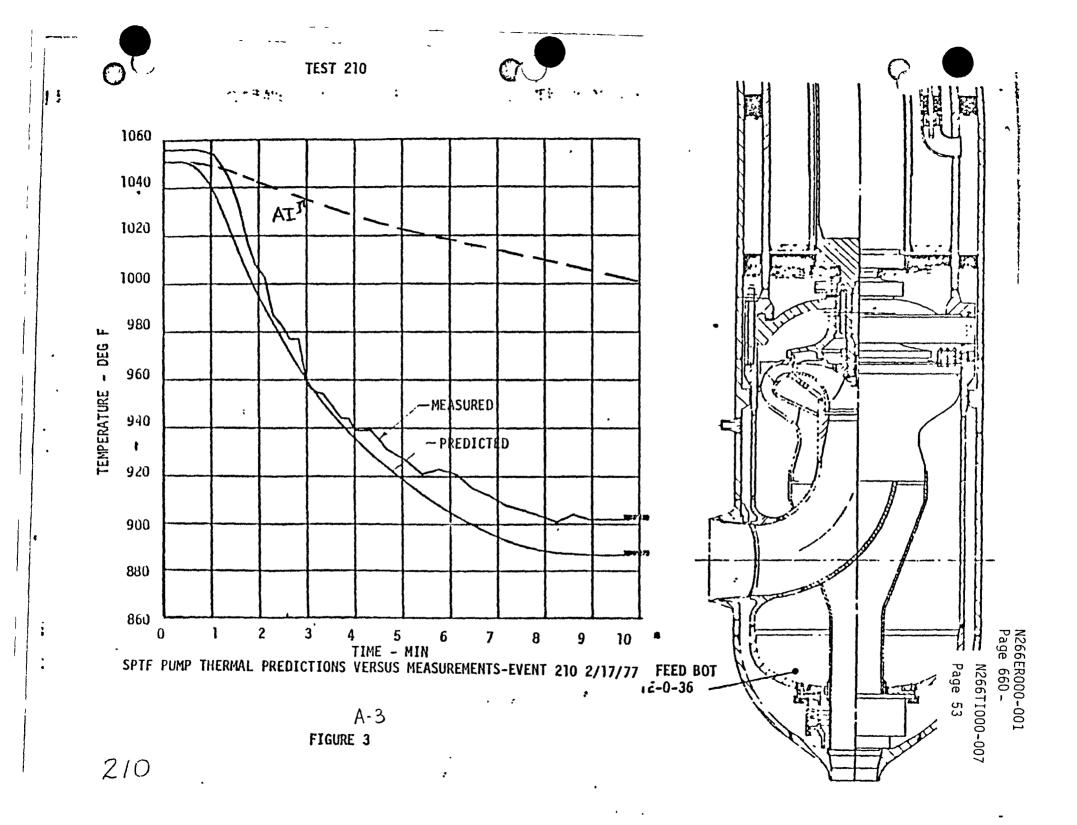
N266ER000-001 Page 657 N266TI000-007 NO . 50 PAGE .

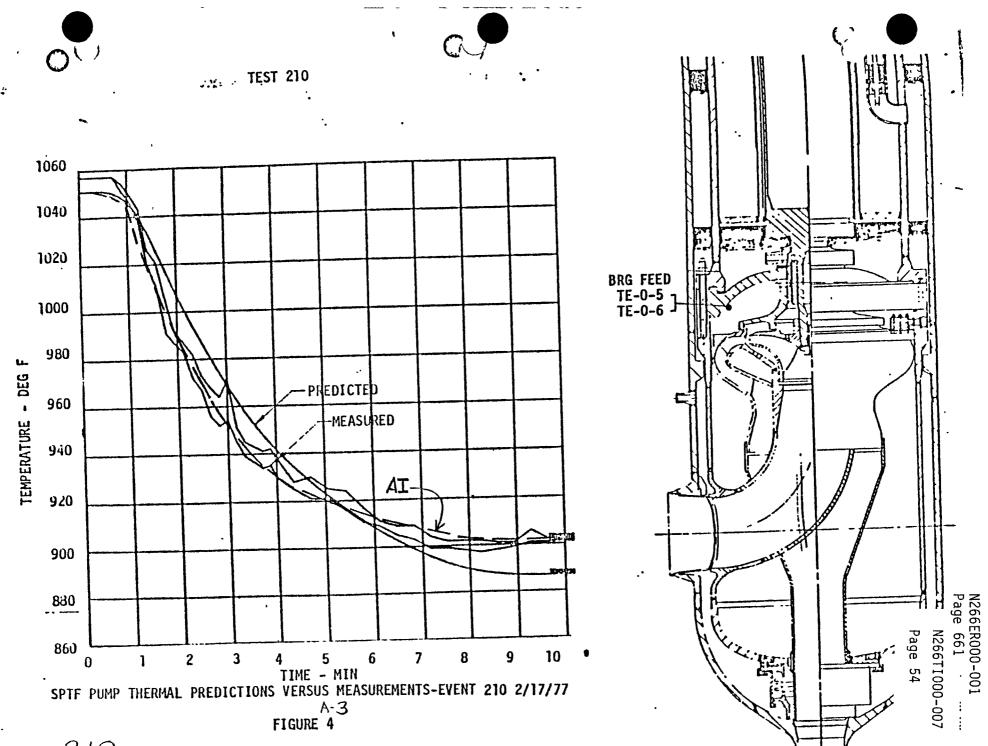
APPENDIX A-3

TRANSIENT 210-TEST



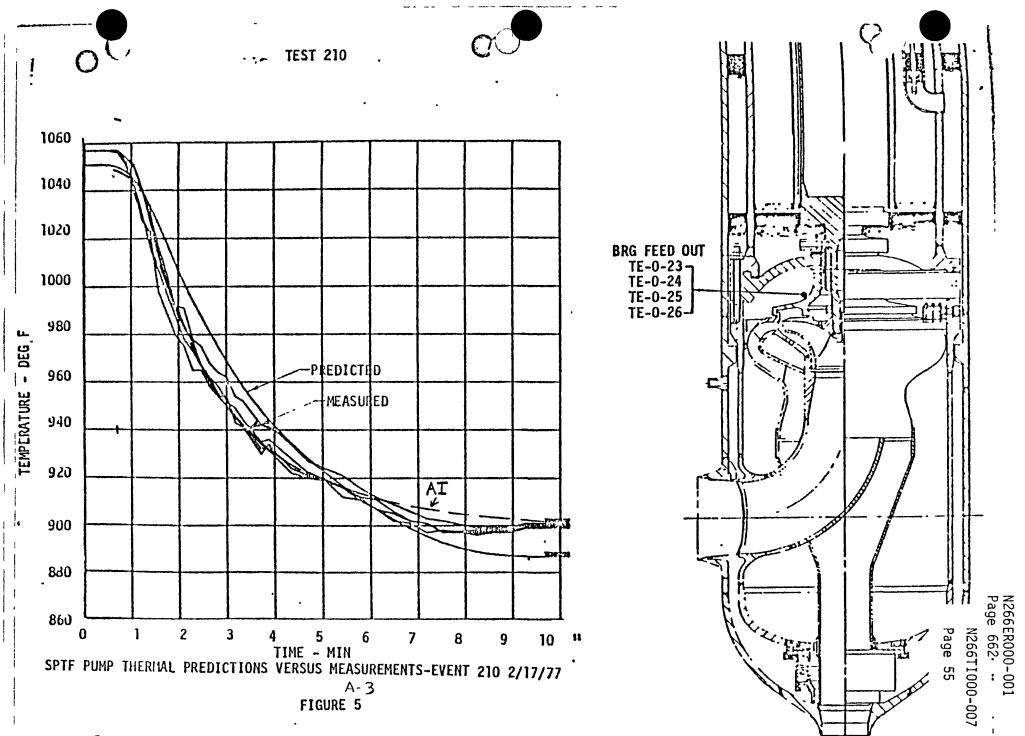




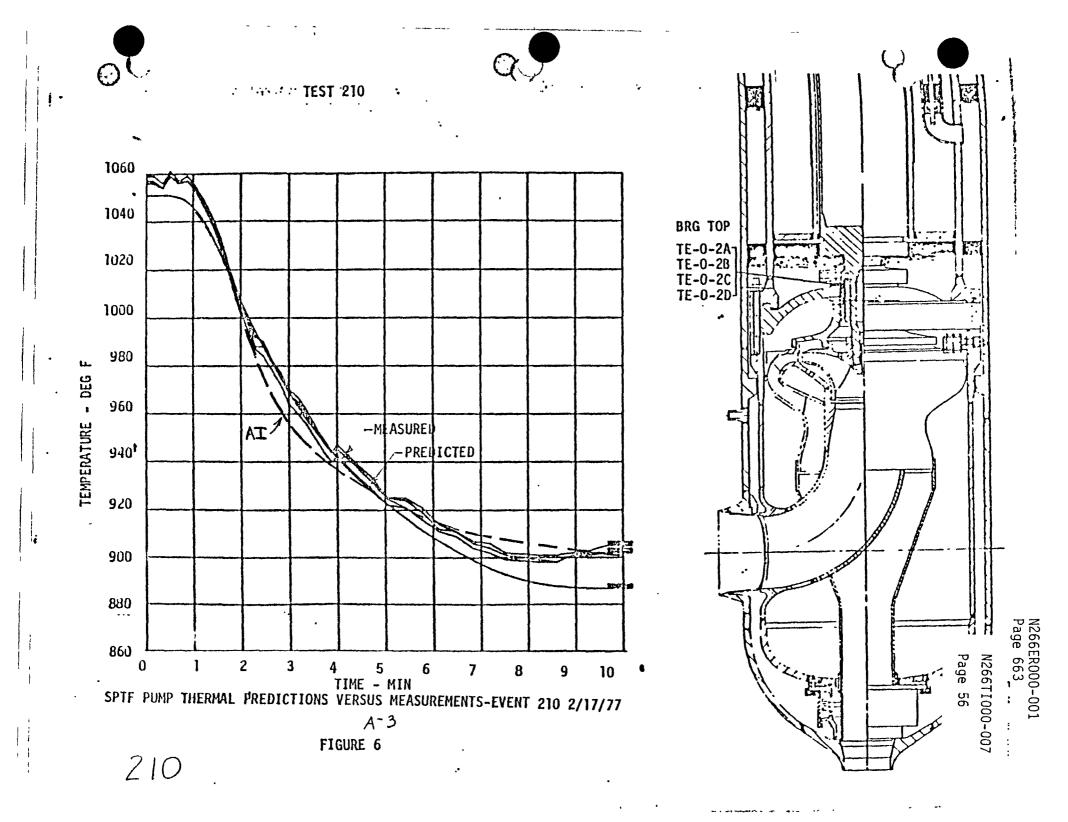


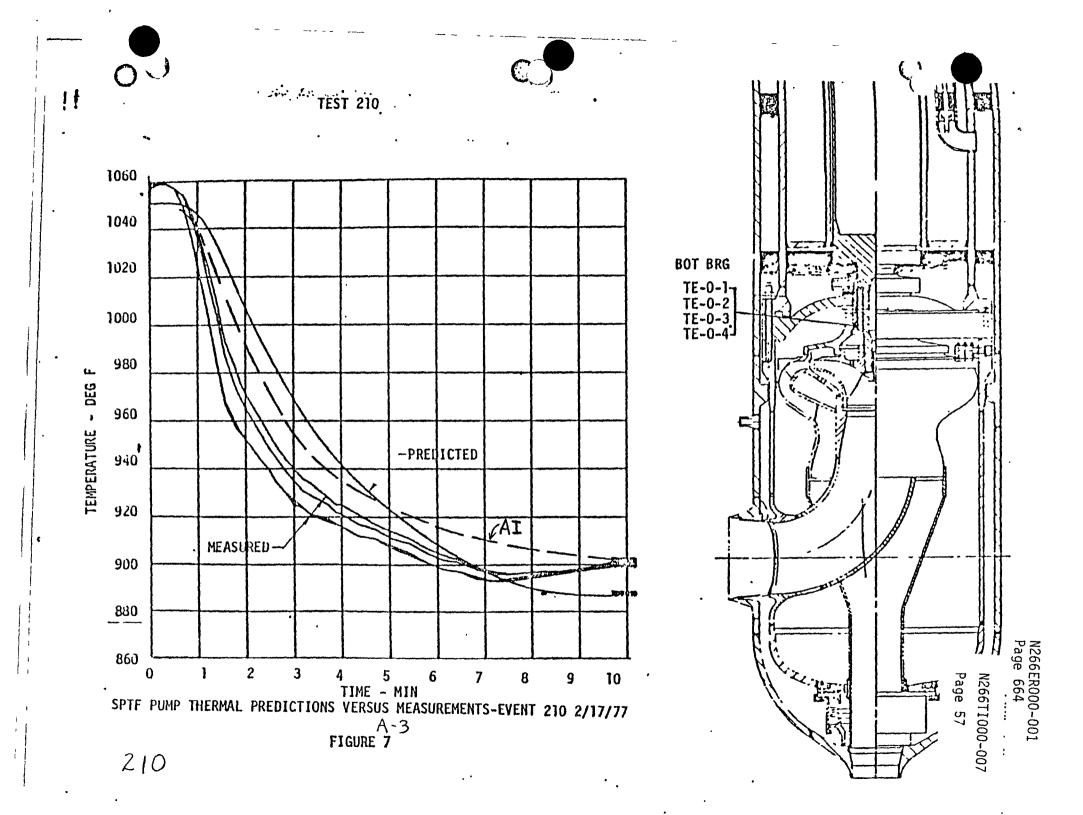
210

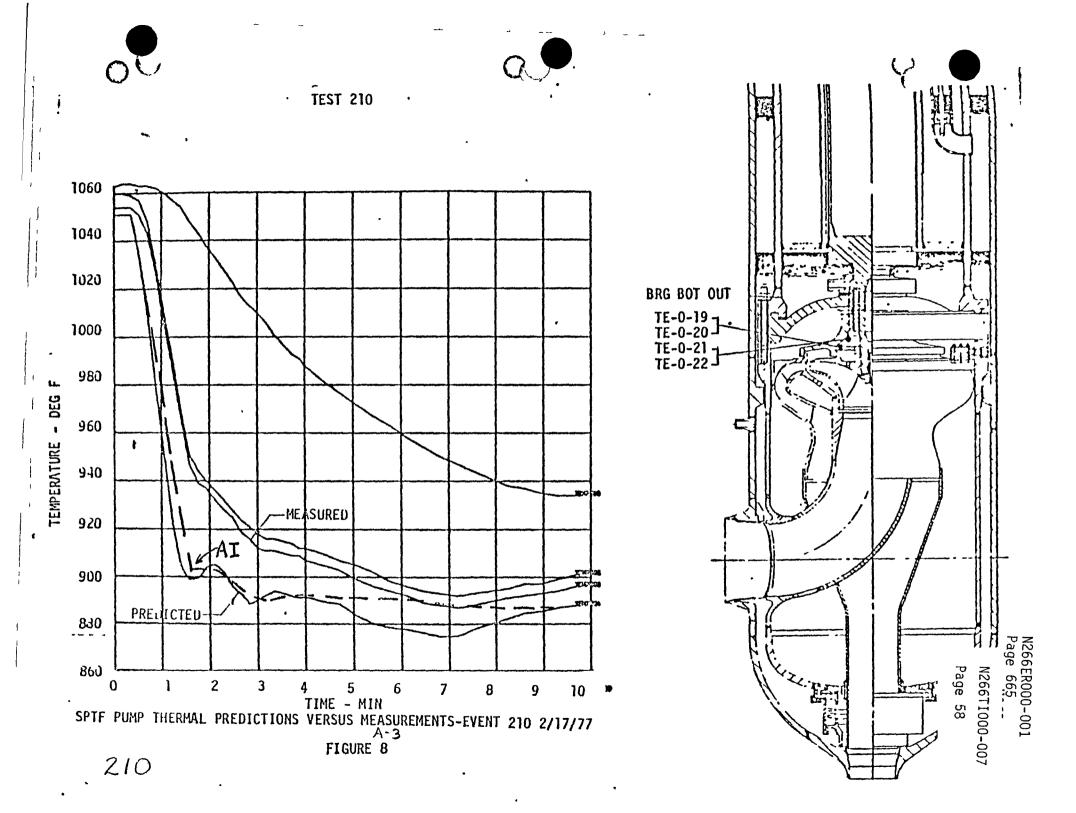
.

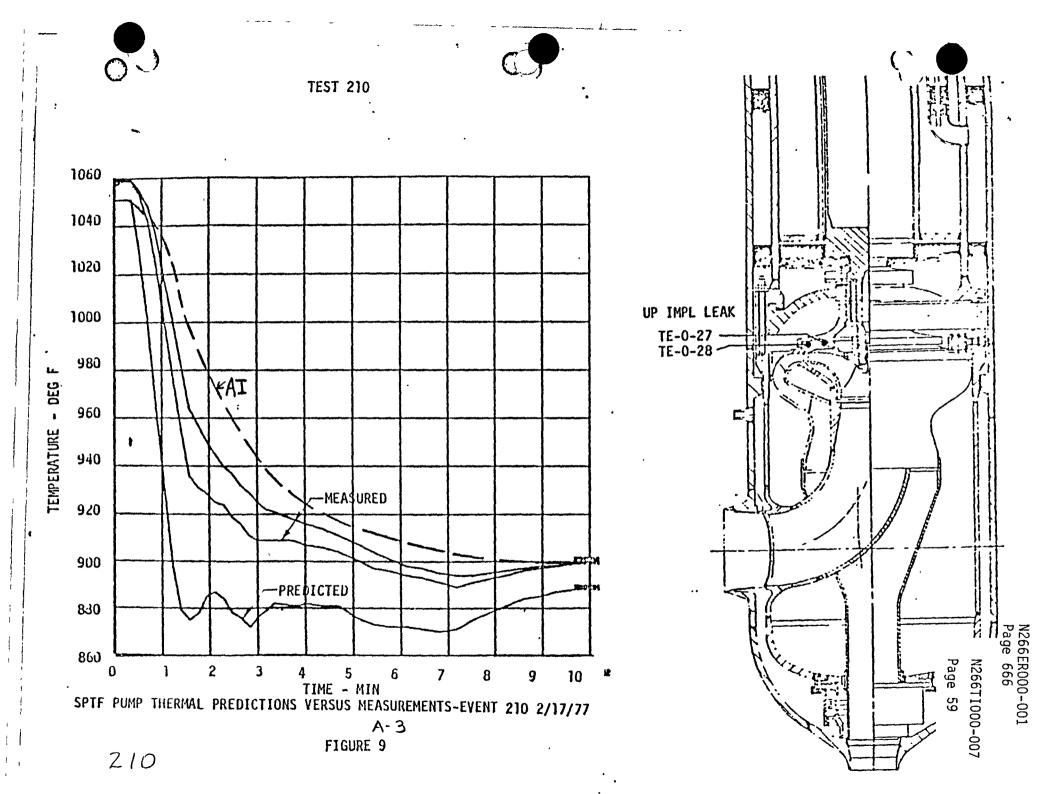


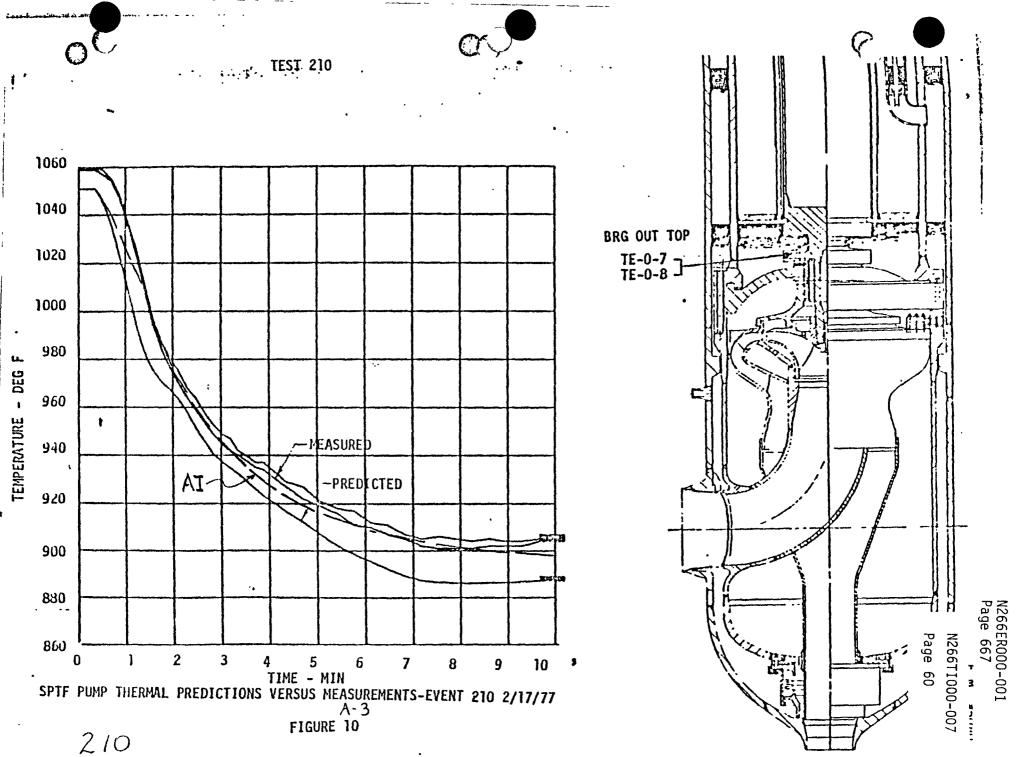
· 210

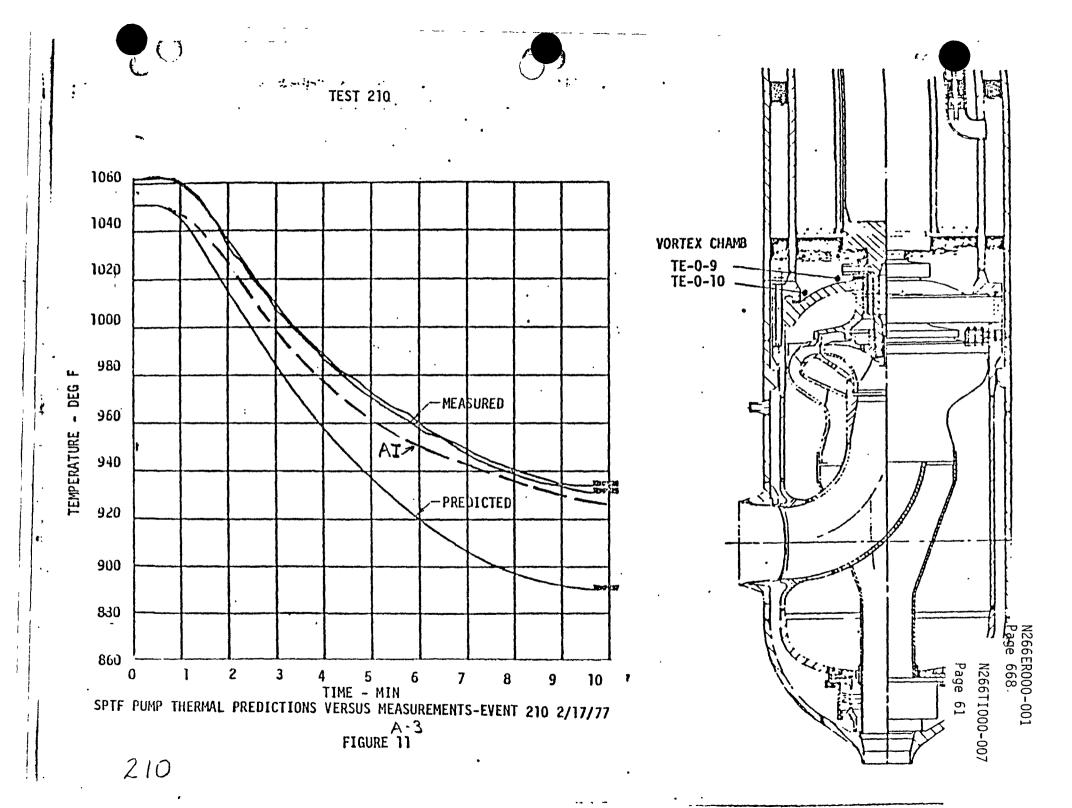


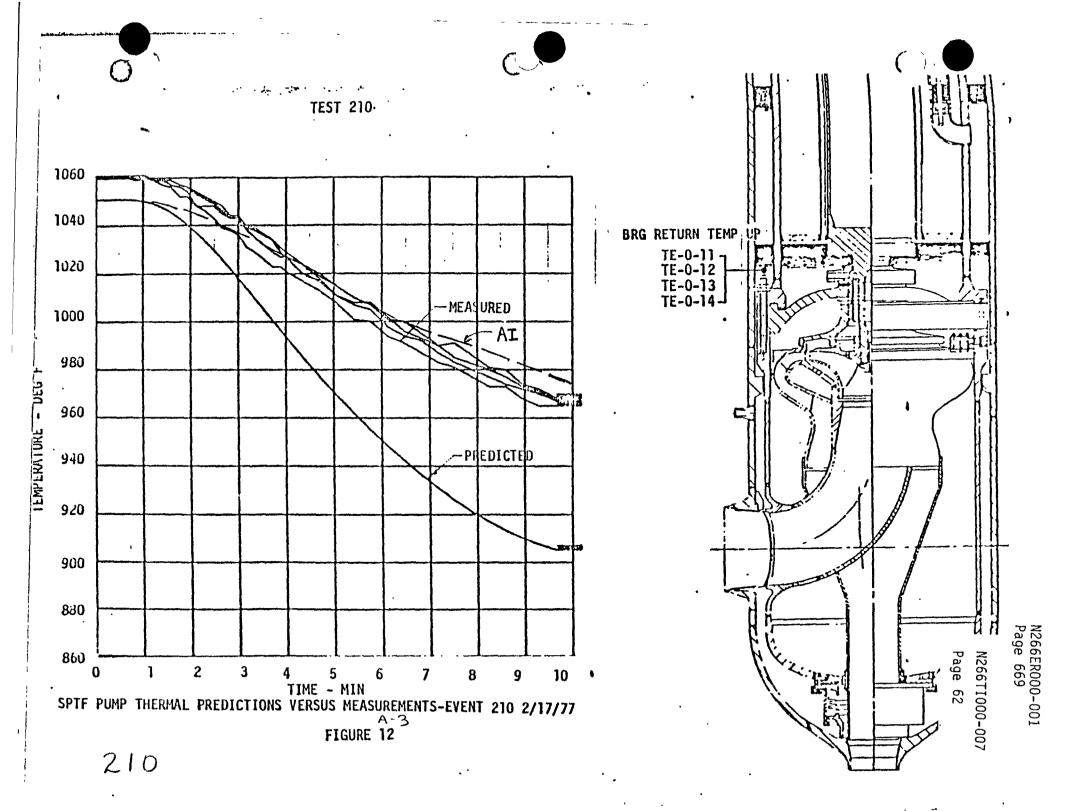


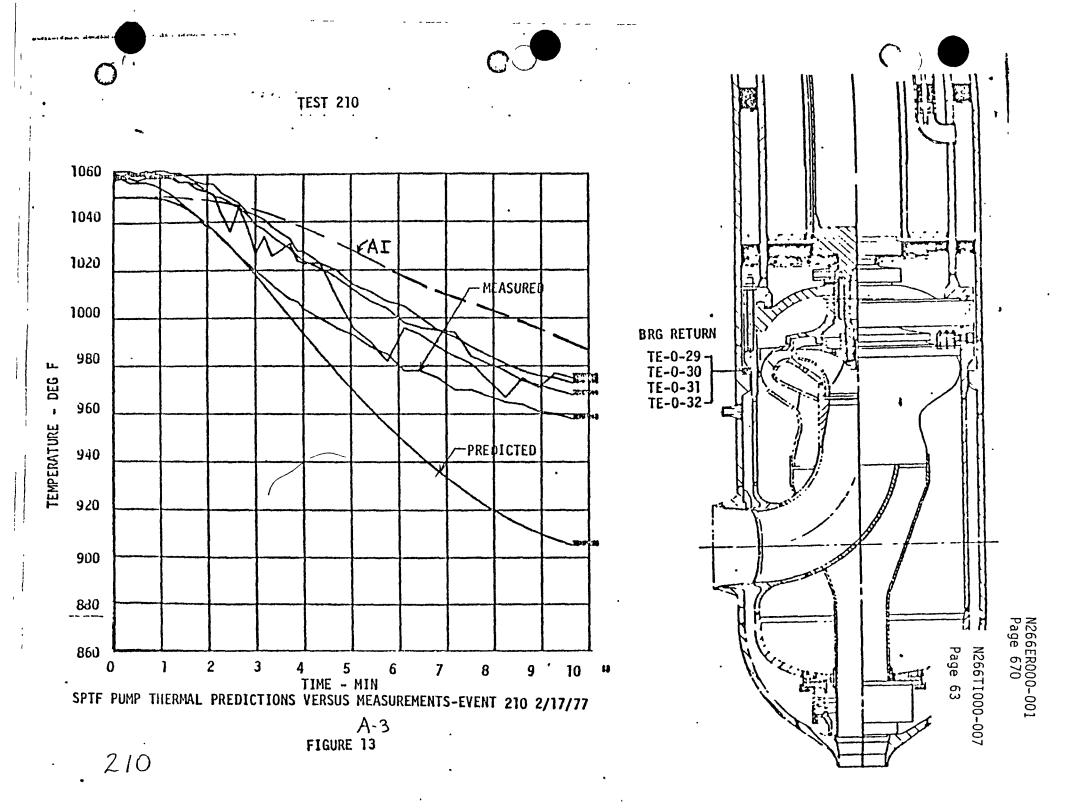


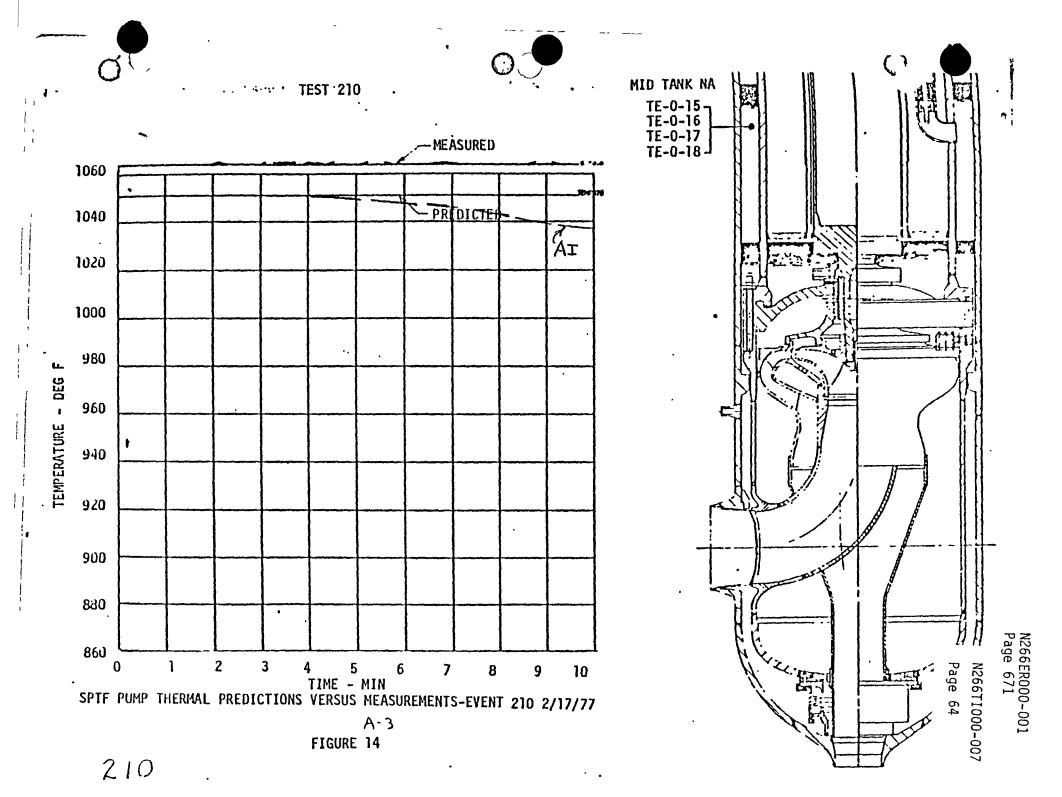














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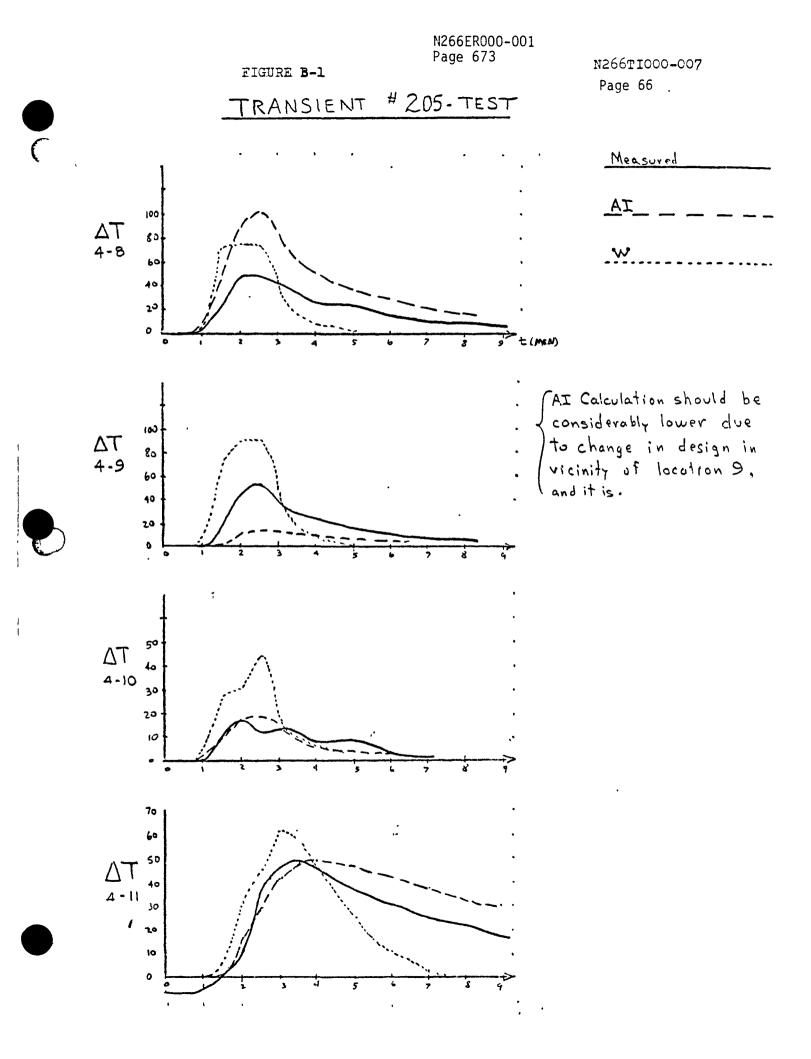
## APPENDIX B TRANSIENT TEMPERATURE DIFFERENTIALS (Location Pairs: 4-8, 4-9, 4-10, 4-11)

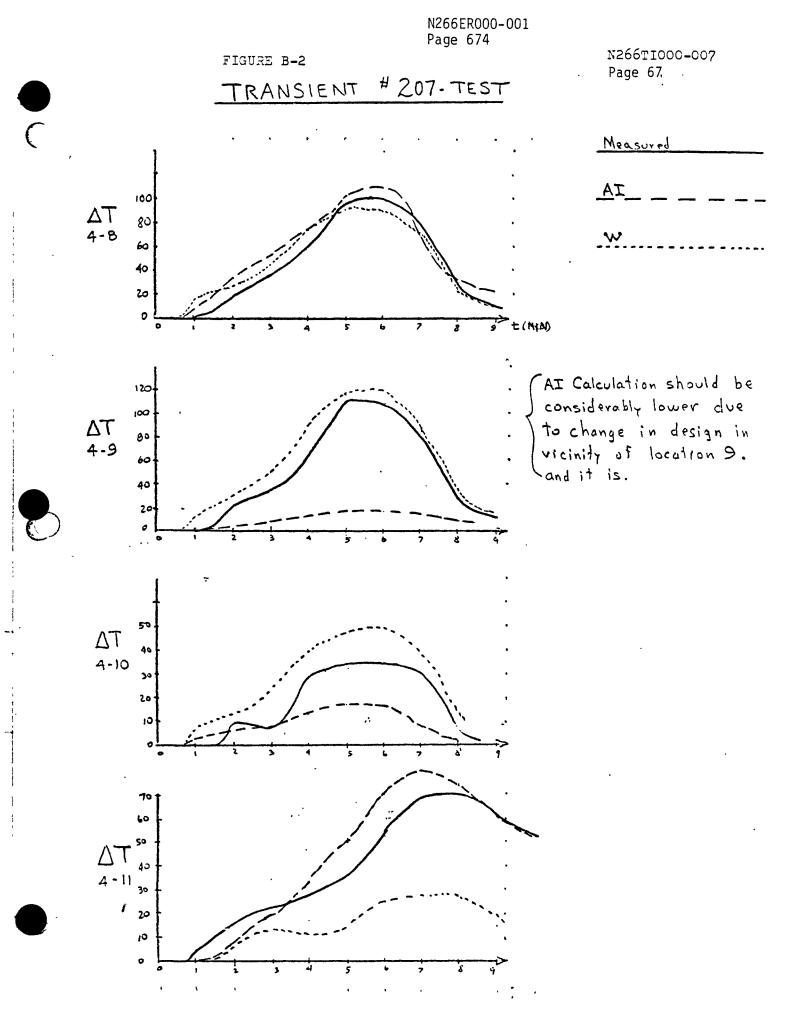
In Appendix A, temperature versus time plots are shown for the 14 thermocouple locations. Based on this information, temperature differentials between four pairs of locations were determined and plotted. These plots are shown in Figures B-1, B-2, and B-3 for Test Transients 205, 207, and 210, respectively. The data is shown: measured, solid line; AI results, dashed line; and Westinghouse prediction, dotted line.

The results show generally good agreement. An important exception is the  $\Delta T$  data for the Location Pair 4-9. In the ISIP, there are design changes in the vicinity of Location 9 which cause that region to respond more slowly to the transient. Thus,  $\Delta T$  (4-9) is expected to be less than for the FFTF test, and this indeed is the case.

Locations for Points 4, 8, 9, 10, and 11 are shown in Figure 3 (also see Table A of Appendix A).

Tables B-1-a through B-3-c are the local temperatures and temperature differentials versus time for the locations indicated. The data for the T.C. measurements and Westinghouse data are taken from the plots of Reference 1, which are also shown in Appendix A. The AI data has been taken from the computer run output.

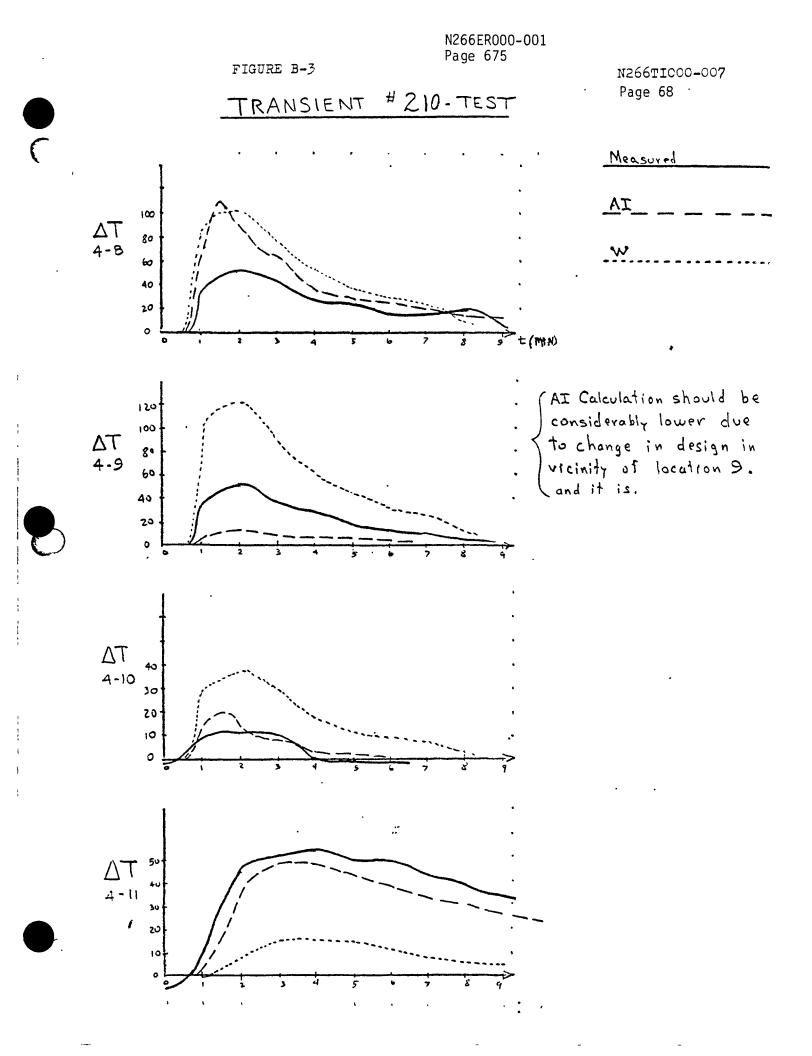




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TABLE B-1-a

TRANSIENT #205-TEST

FROM T.C. MEASUREMENTS

ТІМ	E	4	8	9	(0)		ΔΤ	ΔΤ	ΔΤ	ΔΤ
SEC.	MIN	T 929.AI)	TE 19,	T927	T932	7920	(4-8)	(4-9)	(4-10)	(4-11)
-		TE 5,6	20,21,22	TE 27,28	TE 7.8	TE 9,10	1			
0	0	703	703	703	704	710	0	Э	-1	- 7
60	1	703	705	705	704	710	-2	-2	-1	-7
		713	740	739	720	712	-27	-26	-7	+1
120	2	732	780	776	748	721	(-48)	- 44	(-16)	+ 11
		774	820	826	785	735	-46	(-5Z)	-11	+ 39
180	3	799	840	836	811	752	-41	-37	-12	+47
ļ		819				769				750
240	4	828	851	850	.835	781	-23	- 22	-7	47
ļ										
300	5	834	856	852	842	798	- 22	-18	-8	36
360	6	840	855	852	843	809	-15	-12	- 3	31
420	7	842	853	850	844	816	-11	-8	-2	26
480	8	84 2	851	849	844	820	-9	-7	-2	22
540	٩	842	850	848	844	82.4	-8	-6	- 2	18
600	10	842	850	847	844	826	-8	-5	-2	16
				~						<u> </u>



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TABLE B-1-6 TRANSIENT #205-TEST AI CALCULATION 1/10/79

TIM	ε	4	8	9	(0)		ΔΤ	ΔΤ	ΔΤ	ΔΤ
		T 929(AI)		T927	T932	T920	(4-8)	(4-9)	(4-10)	(4-11)
SEC.	MIN	TE 5,6	TE 19, 20,21,22	TE 27.28	TE 7.8	TE 9,10				
1										
0	0	695	695	695	695	695	0	0	0	0
60	1	695	703	695	697	695	-8	0	2	0
110	1 - 5/6	712	792	721 ,	728	702	-80	- 9	-16	10
120	2	720	808	729	736	704	- 88	-9	-16	16
130 140		728 737 746 756	823 839 847853-	729 759 768	746 764	703 716 -	-95 -102		C.	20 30
180	3	773	857	785	787	731	- 84	-12	-14	42
210		794	855	803	802	745	-61	-9	-8	49
240	4	807	857	816	·813	757	-50	- 9	-6	50
260	4 - 13	814 820	858 859	822 827	824	764 771	-44 -39	-8 -7	-5 -4	50 49
300	5	824	860	831	828	777	-36	-7	-4	47
360	6	834	862	840	837	791	-28	-6	-3	43
				.:						[
420	7	841	863	846	843	802	- 22	- 5	- 2	39
480	8	845	864	849	848	811	-19	-4	- 3	34
			•	*						
540	9	848	865	852	851	817	-17	4	-3	31
600	10	851	865	854	853	823	-14	-3	- 2	28
1										

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TABLE B-1-C TRANSIENT #205-TEST W PREDICTION

.

		(4)	8	9	(10)		ΔΤ	ΔT	ΔΤ	ΔΤ
TIM	E	T 929(AI)		T927	T932	T920	1			
SEC.	MIN		TE 19,				(4-8)	(4-9)	(4-10)	(4-11)
		TE 5,6	20,21,22	TE 27, 28	TE 7.8	TE 9,10				
0	0	695	695	695	695	695	0	0	0	0
		695	695	695	.695	695	0	0	°	0
60	1	696	702	707	700	695	-6	- (1	- 4	0
		708	778 '	780	735 .	703	-70	- 72	-27	5
120	2	748	820	839	778	717	-72	(-91)	- 30	31
•		788	861	876	822	742	(-73)	-88	(-44)	46
180	3	832	870	878	848	768	- 38	-46	-16	64
		851	867	868	858	792	-16	-17	-7	59
240	4	860	868	870	864	812	-8	-10	-4	48
· ·		863	868	869	865	826	-5	-6	-2	37
300	5	864	864	864	864	837	0	0	D	27
		862	861	860	862	844	+ (	+2	0	18
360	6	860	858	. 858	859	848	+2	+2	+1	12
		857				851				6
420	7 ·	855	855	854	855	852	0	+1	0	3
480	8	. 851	852	853	852	852	-1	-2	-1	-1
			-	·						
540	٩	849	851	852	849	851	- 2	-3	J	- 2
			·							
600	10	848	850	851	848	851	- 2	- 3	D	- 4
								<u> </u>	<u> </u>	

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TABLE B-2-a TRANSIENT #207-TEST

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FROM T.C. MEASUREMENTS

TIM	ε	4	8	9	(0)		ΔΤ	ΔT	ΔΤ	ΔΤ
SEC.		T 929(AI)	T934 TE 19,	T927	T932	T920	(4.8)	(4-9)	(4-10)	(4-11)
560.		TE 5,6	20, 21, 22	TE 27.28	TE 7.8	TE 9,10				
0	0	1058	10/3	1060	1060	1040	-5	-2	- 2	0
		10 3 6	1063	1080		1060	<u> </u>	- 6		
60	1	1056	1054	1055	1058	1060	2	1	-2	-4-
120	2	1040	1020	1020	1030	1055	20	20	10	-15
180	3	1016	981	982	1008	1042	35	34	8	-26
240	4	1005	944	935	975	1022	61	61	30	-17
300	5	955	855	- 845	920	992	100	(110)	(35)	- 37
360	6	905	800	797	870	958	(105)	108	35	- 53
420	7.	855	772	774	825	925	83	81	30	- 70
480	8	821	792	794	816	893	29	27	5	(-72)
540	٩	815	803	803	815	877	12	-12	0	-62
600	10	815	805	805	815	868	10	10	0	-53
					<u>.</u>					

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TIM	ε	4	8	9	$\bigcirc$		ΔΤ	ΔT	ΔΤ	ΔΤ
1		T 929(AI)	T934	7927	T932	7920	(4-8)	(4-9)	(4-10)	(4-11)
SEC.	MIN	TE 5,6	TE 19, 20,21,22	TE 27, 28	TE 7.8	TE 9,10				
0	0	1050	1050	1050	1050	1050	0	G	0	0
60	1	1050	1040	1050	1048	1050	10	0	2	0
						•				
120	2	1037	999	10.33	1030	1045	38	4	7	-8
·										
180	3	1012	. 958	1006	1003	1033	54	6	9	-21
			•			·				
240	4	979	901	969	966	1014	78	10	13	- 35
280	42/3	950	854	938	935	996	95	12	15	-46
300	5	934	830	920	917	986	104	14	(7)	-52
320 340	5 % 5 %	916 898	801 788	902 883	900 882	975 964	107 110	15	16 16	-59 -66
360	6	880	768	865	864	952	112	15	16	- 72
380 400	6 13 6 2/3	862	752 755	846 831	846 834	939 927	91	16) 15	76 12	- 77 -81
420	7	833	760	820	824	915	73	13	9	(382)
440	73	824	766	812	818	905	58	12	6	-81
480	8	814	779	806 .	812	888	35	8	2	- 74
							-	<u> </u>		
540	9	811	785	804	808	872	26	· 7	3	- 61
600	10	810	790	805	808	862	20	5	2	-52
				<u> </u>		<u> </u>				

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TIM	E	4	8 T 224	9	(0) T932	(1) T920	ΔΤ	ΔΤ	ΔΤ	ΔΤ
SEC.	MIN	T 929(AI) TE 5,6	T934 TE 19, 20,21,22	T927 TE 27, 28	TE 7.8	TE 9,10	(4-8)	(4-9)	(4-10)	(4-11)
!										
0	0	1050	1050	1050	1050	1050	0	ο	0	0
1										
60	1	1049	1034	1037	1041	1049	15	12	8	0
120	2	1034		1004	1020	1041	24	30	14	-7
	~	10.34		1004	1020				'·	·
180	3	1010	966	960	994	1025	44	50	16	-15
						•				
240	4	997	920	906	952	1002	77	91	45	-5
	<b> </b>								ļ	
300	5	950	857	831	920	961	(93)	119	30	-11
360	6	890	798	770	839	920	92	(120)	(51)	<u>~30</u> `
420	7	847	774	766	809	868	73	81	38	- 21
480	8	810	785	779 -	797	838	25	31	13	- 28
540	9	802	789	785	795	817	13	17	7	-15
600	10	795	791	785	794	808	4	8	1	_13
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TABLE B-3-2 TRANSIENT #210 -TEST FROM T.C. MEASUREMENTS

SEC.       MIN       TE 19, 122       TE 27,25       TE 7,8       TE 9,10 $(4-8)$ $(4-9)$ $(4-10)$ $(4-11)$ 0       0       1057       1058       1059       1062 $-1$ $-2$ $-2$ $-5$ 60       1       1050       1012       1015       1040       1060       38       35       10 $-10$ 120       2       988       936       938       977       1035       (52)       50       (11) $-47$ 180       3       956       915       918       946       1008       41       38       10 $-52$ 240       4       934       909       910       934       988       255       24       0 $(-54)$ 300       5       922       902       905       920       972       20       17       2 $-50$ 360       6       910       895       896       912       960       15       14 $-2$ $-50$ 420       7       904       890       894       906       948       14       10 $-2$ $-44$	TIM	E	4	8 7934	چ <sub>7</sub> و۲	(0) T932	(1) T920	ΔΤ	ΔT	ΔΤ	ΔΤ
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	SEC.	MIN	T 929(AI) TE 5,6	TE 19,				(4-8)	(4-9)	(4-10)	(4-11)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	i										
120 $2$ $988$ $936$ $938$ $977$ $1035$ $(52)$ $(50)$ $(11)$ $-47$ $180$ $3$ $956$ $915$ $918$ $946$ $1008$ $41$ $38$ $10$ $-52$ $240$ $4$ $934$ $909$ $910$ $934$ $988$ $25$ $24$ $0$ $-54$ $300$ $5$ $922$ $902$ $905$ $920$ $972$ $20$ $17$ $2$ $-50$ $300$ $5$ $922$ $905$ $920$ $972$ $20$ $17$ $2$ $-50$ $360$ $6$ $910$ $895$ $896$ $912$ $960$ $15$ $14$ $-2$ $-50$ $420$ $7$ $904$ $890$ $894$ $906$ $948$ $14$ $100$ $-2$ $-44$ $480$ $8$ $900$ $895$ $903$ $940$ $18$ $5$ $-3$ $-35$ $540$ $9$ $900$ $895$ $897$ <td>0</td> <td>0</td> <td>1057</td> <td>1058</td> <td>1059</td> <td>1059</td> <td>1062</td> <td>-1</td> <td>-2</td> <td>-2</td> <td>-5</td>	0	0	1057	1058	1059	1059	1062	-1	-2	-2	-5
120       2       988       936       938       977 $1035$ $(52)$ $(50)$ $(11)$ $-47$ 180       3       956       915       918       946 $1008$ 41       38 $10$ $-52$ 240       4       934       909       910       934       988       25       24 $0$ $-54$ 300       5       922       902       905       920       972       20       17       2 $-50$ 360       6       910       895       896       912       960       15       14 $-2$ $-50$ 420       7       904       890       894       906       948       14 $10$ $-2$ $-44$ 480       8       900       892       895       903       940 $18$ $5$ $-3$ $-36$ 540       9       900       895       897       903       935 $5$ $3$ $-3$ $-35$	•			•							
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	60	1	1050	1012	1015	1040	1060	38	35	10	-10
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$						, ·					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	120	2	988	936	938	977	1035	(52)	(50)	(1)	-47
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$											
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	180	3	956	915	918	946	1008	41	38	10	-52
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$							•		<u></u>		ļ
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	240	4	934	909	910	934	988	25	24	0	-54
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$									· .		
420       7       904       890       894       906       948       14       10 $-2$ $-4a$ $480$ 8       900       882       895       903       940       18       5 $-3$ $-4a$ $540$ 9       900       895       897       903       935       5 $3$ $-3$ $-35$	300	5	922	902	905	920	972	20	17	2	-50
420       7       904       890       894       906       948       14       10 $-2$ $-4a$ $480$ 8       900       882       895       903       940       18       5 $-3$ $-4a$ $540$ 9       900       895       897       903       935       5 $3$ $-3$ $-35$										<b></b>	
480       8       900       882       895       903       940       18       5       -3       -4         540       9       900       895       897       903       935       5       3       -3       -35	360	6	910	895	896	912	960	15	14	-2	-50
480       8       900       882       895       903       940       18       5       -3       -4         540       9       900       895       897       903       935       5       3       -3       -35	ļ										
540 9 900 895 897 903 935 5 3 -3 -35	420	7.	904	840	894	906	948	14	10	-2	-44
540 9 900 895 897 903 935 5 3 -3 -35											- 1
	480	8	900	882	895	903	740	18	5		-40
	510	9	800	205	007	802	075	<u> </u>			- 3 ~
600 10 902 900 900 904 935 2 2 -2 -33	540		700	875	871	705	232	1 5	2	<u> </u>	1-32
	600	10	902	900	900	904	935	2	2	- 2	- 3 3
	<b> </b>		106						<u>↓</u>		·
		┝───╁	<u> </u>					<u>}</u>		<del> </del>	†

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TIM	e	4	8	9	(0)		ΔΤ	ΔΤ	ΔΤ	ΔΤ
		T 929(AI)	T934	〒927	T932	T920	(4-8)	(4-9)	(4-10)	(4-11)
SEC.	MIN	TE 5,6	TE 19, 20,21,22	TE 27, 28	TE 7.8	TE 9,10		( /		
1										
0	0	1050	1050	1050	1050	1050	0	े	0	0
60		1044	977	1039	1031	1048	67	5	13	- 4
90	12	1021	911	1009	1001	1039	110	(12)	20	-18
120	2	991	904	979	977	1026	87	12	14	-35
150 ·	22	969	899	959	959	1012	70	10	10	-43
180	3	952	889	943	944	1000	63	9	8	-48
210	31	939	893	931	934	-988	46	8	5	-49
240	4	930	894	924	927	978	36	6	3	-48
300	5	920	891	914	917	963	29	6	3	- 43
										•
360	6	913	890	908	911	952	23	5	2	-39
420	7	909	889	904	906	943	20	5	3	-34
480	8	905	. 888	902	903	936	17	3	2	- 31
540	9	903	883	900	900	931	15	· 3	3	-28
		1								
600	10	901	882	898	898	926	14	3	3	- 25
		<u> </u>	[				1			



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TABLE B-3-C TRANSIENT #210 -TEST W PREDICTION

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TIM	ε	<b>(4)</b>	8 7934	9 T927	(0) T932	(1) T920	ΔT	ΔT	ΔΤ	ΔΤ
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### APPENDIX L

## MODEL INDUCER WATER TUNNEL TEST REPORT

# Rocketdyne Document R/H 9113-3741 (Assigned ESG Document number is N266TR000-002)

Figures 12 thru 26 have been removed from this document because they contain proprietary information, as defined by DOE contract.

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# **Rockwell International**

Rocketdyne Division 6633 Canoga Avenue Canoga Park, California 91304

RI/RD79-142

INTERMEDIATE SODIUM INDUCER PUMP MODEL INDUCER WATER TUNNEL TEST REPORT R/H 9113-3741 9 FEBRUARY 1979

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### PREPARED BY

Rockwell International Corporation Rocketdyne Division 6633 Canoga Avenue Canoga Park, California 91304

E. D. Jackson Manager Hydrodynamics Unit

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APPROVED BY (X. E. Wolf)

Project Engineer Sodium Pump Program

D. E. Davis Program Manager

Dynamic Power Programs

PREPARED FOR

Energy Systems Group Atomics International Division Under IDWA No. N-1327 Authorized Under ESG Prime Contract EY-76-C-03-0824

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### INTRODUCTION

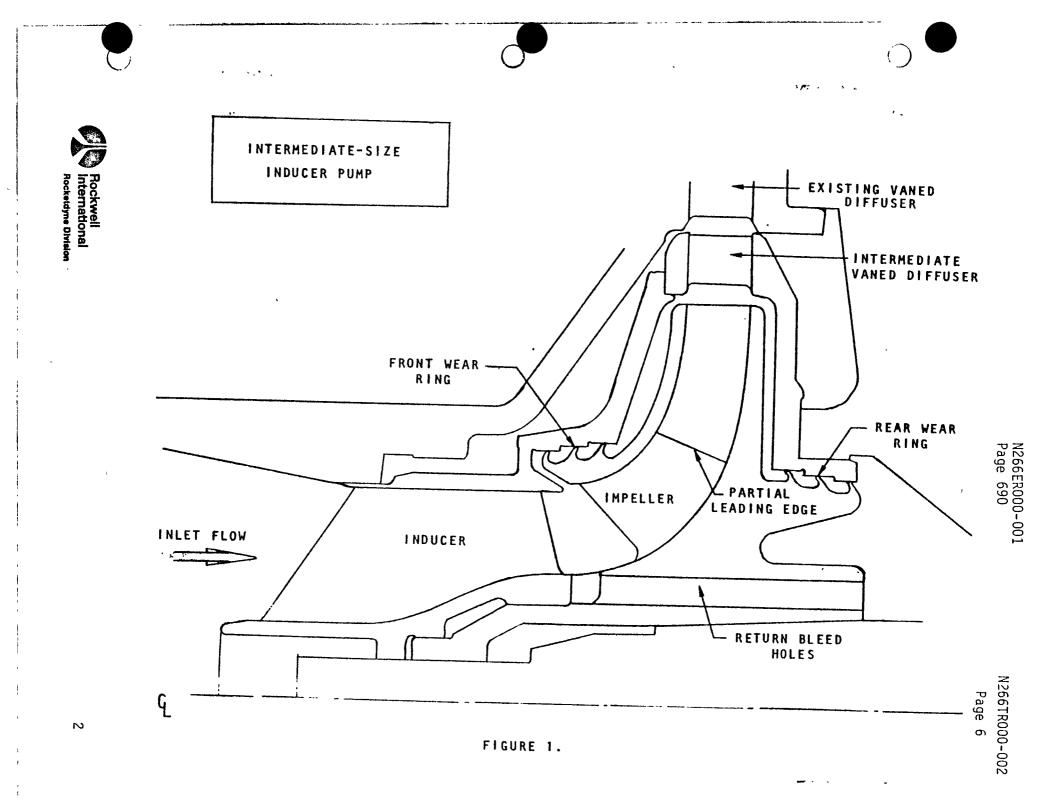
The Intermediate-Size Inducer Pump (I.S.I.P.) was designed to operate in the existing FFTP pump housing and to achieve the required pump head rise at the same speed and flow as the existing pump. The existing pump consists of four basic hydrodynamic elements:

- 1. Inlet Elbow
- 2. Centrifugal Impeller
- 3. Vaned Diffuser
- 4. Discharge Housing

All of these elements except the centrifugal impeller were to be retained in an unmodified form for the I.S.I.P. design. The centrifugal impeller was to be replaced with a new design consisting of both an inducer and centrifugal impeller. The objective is to demonstrate the capability of designing an inducer pump for long life in sodium operation so that the advantages of the inducer pump can be realized in future sodium pump applications. These advantages consist primarily in the smaller envelope size and lower weight realized as a result of the better suction performance capability of the inducer. These advantages result in significant cost savings and ease of fabrication and handling for the very large pumps required in many of the reactor coolant loop systems.

Figure 1 shows a cross-section of the primary pump components. The most significant hydrodynamic challenge in the design is to achieve the long





life in the inducer. To provide early confidence in the design before finalizing the fabrication and initiating testing of the full-size pump in sodium, a model of the inducer was fabricated for testing in the Rocketdyne water tunnel. The testing included both life and performance tests using a one-third scale model. The testing was successful and demonstrated both excellent performance and life characteristics for the Rocketdyne design. This report describes both the test program and test results.



### TEST ARTICLE

The inducer was designed based on the same design practices established and demonstrated by the successful waterjet inducer designs by Rocketdyne. The primary dimensions of both the full-size and water model of the inducer are given in Table 1. As can be seen, the model is almost exactly a onethird scale version of the full-size. The model inducer is defined by drawing number EWR 344240.

This test article was installed in the test adapter as shown in drawing number EWR 344200. The test adapter consisted of an inducer shaft supported on the test rolling element bearings and splined to an impeller assembly. The impeller assembly, which was driven by the facility gearbox, provided the head requirements to circulate the fluid through the system.



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### TABLE 1. I.S.I.P. INDUCER FEATURES

PARAMETER	FULL-SIZE HARDWARE	WATER-MODEL HARDWARE
No. of Blades	4	4
Tip Diameter, In.	18.53	5.986
Inlet Hub Diameter, In.	6.626	2.140
Disch Hub Diameter, In.	11.358	3.669
Tip Radial Clearance, In.	0.050	0.016
Speed, RPM	1110	6322
Tip Speed, FPS	89.7	165.1
Design Flow, GPM	14,600	2803
Inlet Flow Coefficient	0.222	0.222
Disch Flow Coefficient	0.310	0.310



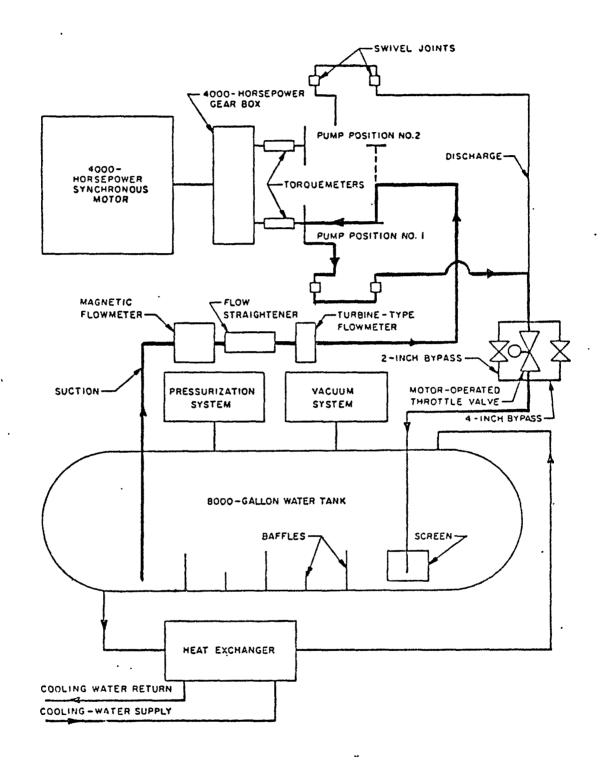
### TEST FACILITY

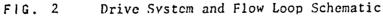
The testing was conducted at Rocketdyne's Pump Calibration Facility in Dept. 592. The pump was driven by a 1200 RPM, reversible, synchronous electric motor, which is rated at 4000 horsepower. The motor drives through a 4000 horsepower gearbox, which has two output shafts. One shaft is capable of producing speeds of 6322 and 8013 RPM. The other shaft is capable of producing speeds of 6322 and 10,029 RPM. The pump was run on the North powerhead (pump position No. 1) at 6322 RPM for this inducer test.

Figure 2 shows a schematic of the drive system and flow loop. An 8000 gallon water tank supplies water for the flow loop. This tank is rated at 150 psi with a vacuum capability of 28.5 inches of vacuum. The flow is measured by a turbine flow meter in the inlet line and regulated by a motor-operated throttle value in the discharge line, whereas, the inlet pressure is regulated by controlling the tank pressure.

The inlet ducting consists of 8-inch schedule 40 steel piping, and the discharge loop is 4-inch diameter steel piping. All metallic coupling joints were heavily greased to assure an air tight system. An orifice was installed in the inlet line to keep the tank pressure up during cavitation tests to further avoid air leaks.

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The inducer is mounted on its shaft which is supported by its own bearing system as shown in drawing number EWR 344200. The inducer shaft is connected to an impeller shaft by a quill shaft. The impeller is an 11-inch tip diameter centrifugal impeller previously designed and fabricated at Rocketdyne and used in the current program as a slave impeller to generate the required head to provide the design flow of the inducer. The impeller is far enough downstream of the inducer to permit instrumentation to be inserted between the two for measuring inducer performance without impeller interference. The test arrangement is designed to establish the inducer performance characteristics as an independent component. The only drawback of this facility arrangement is that the only facility torquemeter available is located between the impeller and the drive gearbox. Thus, there is no way to separate the drive torque of the inducer from the slave impeller, hence no way to determine the efficiency of the inducer. This is not a significant problem because the overall sodium pump efficiency is determined during sodium pump tests and is primarily driven by the centrifugal impeller and discharge system rather than the inducer.

The impeller housing and shaft system was mounted rigidly to a steel frame to assure perfect alignment with the driving motor and, thus, avoid possible oscillation of the system. Testing verified that both the alignment and quill shaft arrangement were satisfactory to prevent any significant rotor dynamic vibrations in either the inducer or impeller.

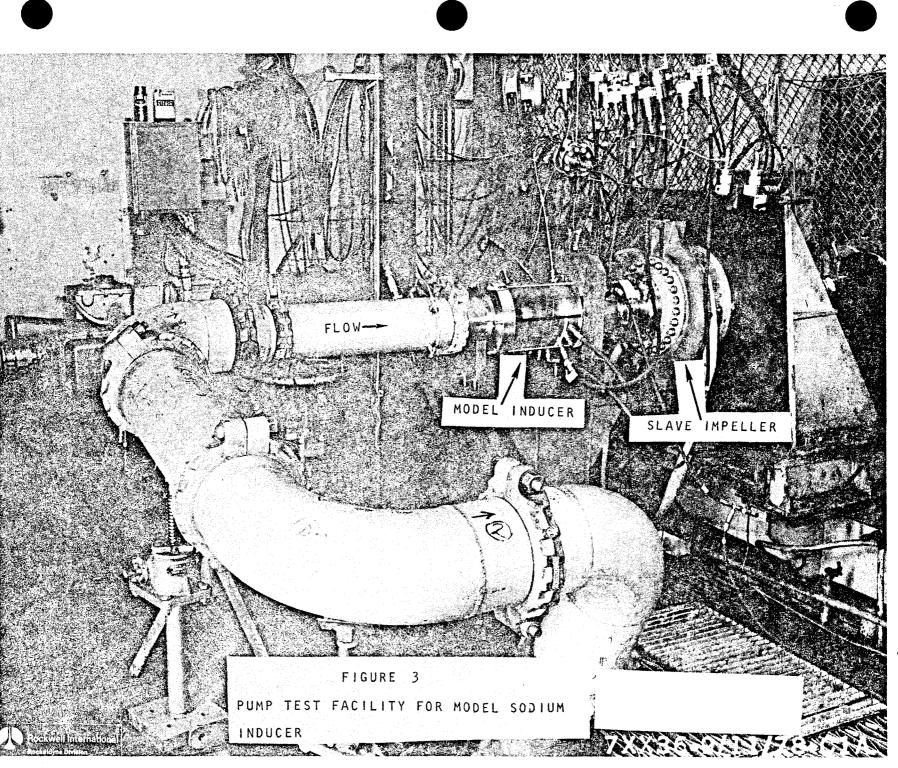
The inducer was enclosed in a plastic viewing tunnel, which allowed both



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photographic and visual observation of the cavitation characteristics of the flow through the inducer. The test setup is shown in Fig. 3. The inducer-to-tunnel clearance was measured to be  $0.016 \pm 0.001$  inch radially for the initial test series representing a concentric build. Later testing was done with an eccentric tunnel and a reduced clearance concentric tunnel, but only the results of the initial testing are reported here.





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#### TEST INSTRUMENTATION

Table 2 presents a list of the instrumentation used during the testing. The inlet pressure consisted of a 4-hole piezometer ring located sufficiently upstream of the inducer to avoid interference effects due to the inducer tip backflow. Downstream of the inducer, two total pressure (Kiel) probes were used to measure the discharge pressure at the mid-blade height position. These probes are subject to clogging due to solid material in the water, and the use of two probes provides more assurance of getting good data during the tests. Yaw probe surveys were planned to provide head distribution as a function of radius but were not carried out due to scheduling conflicts in the facility. There were also numerous static pressures recorded along the tip over the inducer and at the inducer discharge. These were all single point static pressures and provide an indication of the head distribution through the inducer. Drawing number EWR 344205 shows the location of these taps with the same identification keys as used in Table 2.

Other instrumentation included the turbine flowmeter, speed, and torquemeter. These are all standard facility instruments. The speed is fixed during these tests by the electric motor and is recorded only for measuring transients if desired. As previously discussed, the torquemeter measures the input torque to both the inducer and slave impeller so it cannot be used to determine inducer efficiency. Water temperature is measured in the inlet line to permit calculation of the water density and vapor pressure. The other measured pressures are used



### TABLE 2. INSTRUMENTATION

	RANGE
Inlet Static Pressure, Piezometer, PSIA	0 ÷ 100
Discharge Total Pressure, '#1 Tunnel 🔿 PSIG	0 ÷ 500
Flowrate, GPM	0 ÷ 4000
Speed, RPM	6322
Torquemeter, IN LB	0 ÷ 10,000
Water Temperature, <sup>O</sup> F	40 ÷ 140
Discharge Total Pressure #2 Tunnel   PSIG	0 ÷ 500
Pump Discharge Static Pressure, Pipe, PSIG	0 ÷ 500
Pump Delta Pressure, PSI	0 ÷ 500
Static Pressure, Tunnel $ig A$ , PSIG	0 ÷ 100
Static Pressure, Tunnel 🔘 PSIG	0 ÷ 200
Static Pressure, Tunnel (D) PSIG	0 ÷ 200
Static Pressure, Tunnel 🕑 PSIG	0 ÷ 200
Static Pressure, Tunnel 🕞 PSIG	0 <del>:</del> 200
Static Pressure, Tunnel 🜀 PSIG	0 <b>÷</b> 200
Static Pressure, Tunnel (H) PSIG	0 ÷ 200
Static Pressure, Tunnel 🕕 PSIG	0 ÷ 200

+ Circled letters refer to section locations on Drawing No. EWR 344205



for facility diagnostics and conducting of the tests.

All of the data are recorded by a digital acquisition system (Autodata 9 by Accurex) on a "floppy disk" which is transmitted post-test to a digital computer. The data are reduced to provide all pertinent data and calculated parameters by a data reduction program written specifically for the Pump Test Facility. The data are then printed in tabular form, and if desired, selected CRT (cathode ray tube) printouts are obtained.

In addition to the recorded data, photographic techniques were used with strobe-light stop-action cameras to record the cavitation patterns during certain tests. These photographic records were then spliced together to form an annotated presentation of the results. Still photographs were also used post-test to record the dye patterns after running life tests (to be described).



### TEST PROGRAM

The purpose of the test program was to conduct head-flow tests, cavitation tests, and dye tests for demonstrating the long life potential of the inducer by the absence of cavitation damage.

### Head-Flow Test

Head-flow tests were conducted using an inducer shaft speed of 6322 RPM, and an inlet pressure of 65.0 psia, well above the region of cavitation. Flowrates from 1950 to 3650 GPM were achieved in the test representing a variation of -30 to +30 percent about design flow. Data were sampled recorded on the Autodata 9 system at each specific flow after the flow had been stabilized. The basic purpose of the test was to define the head-flow characteristic of the inducer.

### Cavitation Test

An inducer shaft speed of 6322 RPM was used for the cavitation tests. Inlet pressure was set initially at approximately 50 psia and was allowed to continuously decay until the pump head fell off. This test sequence was performed at flowrates from 2100 to 3650 gpm, representing a flow variation of -25 to +30 percent about design flow. Data were continuously recorded on the AD9 system during the pressure decay. The purpose of the tests was to establish the suction performance characteristics of the inducer.



With the head generated by the inducer, the sodium impeller operates at a low enough suction specific speed that it does not experience any head fall-off due to cavitation until the inducer head falls off significantly (approximately 15 percent inducer head fall-off generally results in approximately 2-3 percent overall pump head fall-off). Thus, the suction performance established for the inducer from these tests also establishes the overall pump suction performance.

#### Design Point Life Tests

After coating the inducer blades with an insoluble dye, a twenty minute test was performed at 200 percent NPSH margin at the design flow of 2803 GPM. The inducer shaft speed was 6322 RPM and the inlet pressure determined based on the suction performance results of preceding tests. Five samples of data were recorded every five minutes on the Autodata 9. The dye used in the tests was the brand name "Magic Marker" marking ink applied to the blade pressure and suction surfaces by cotton swabs. This particular dye has been used extensively by Rocketdyne in developing other long-life inducer designs. The dye has been shown to be an effective indication of cavitation damage potential in that the dye is clearly removed during the 20 minute test if there is cavitation collapse on the blade, but no dye is removed if the cavitation collapse occurs in the fluid stream. Rocketdyne has tested parts in the field to demonstrate long life without cavitation damage after verifying the long-life design by the same type of dye tests described here. Rocketdyne has also tested models of inducers experiencing damage in the field and duplicated the



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damage potential by the dye removal in the model facility. Thus, it is believed such tests are an excellent screening test for providing confidence in the design at an early state in the design process with minimal costs. The use of the "Magic Marker" dye has a degree of correlation with field results and is easily and quickly applied. Thus, Rocketdyne believes that it is a valuable test procedure.

### Off-Design Life Test

These tests were conducted in the same manner as the Design Point Life Tests described above. Several flows were used in the test including 130 percent of design flow. The flow and NPSH margin were varied to establish life characteristics over a range of operating conditions to establish the best operating point and provide more confidence in the design. The NPSH margin at each flow was compared to the value resulting from operation at the proper speed and flow for the sodium in its facility. Five samples of data were recorded every five minutes on the Autodata 9 system.



#### TEST RESULTS

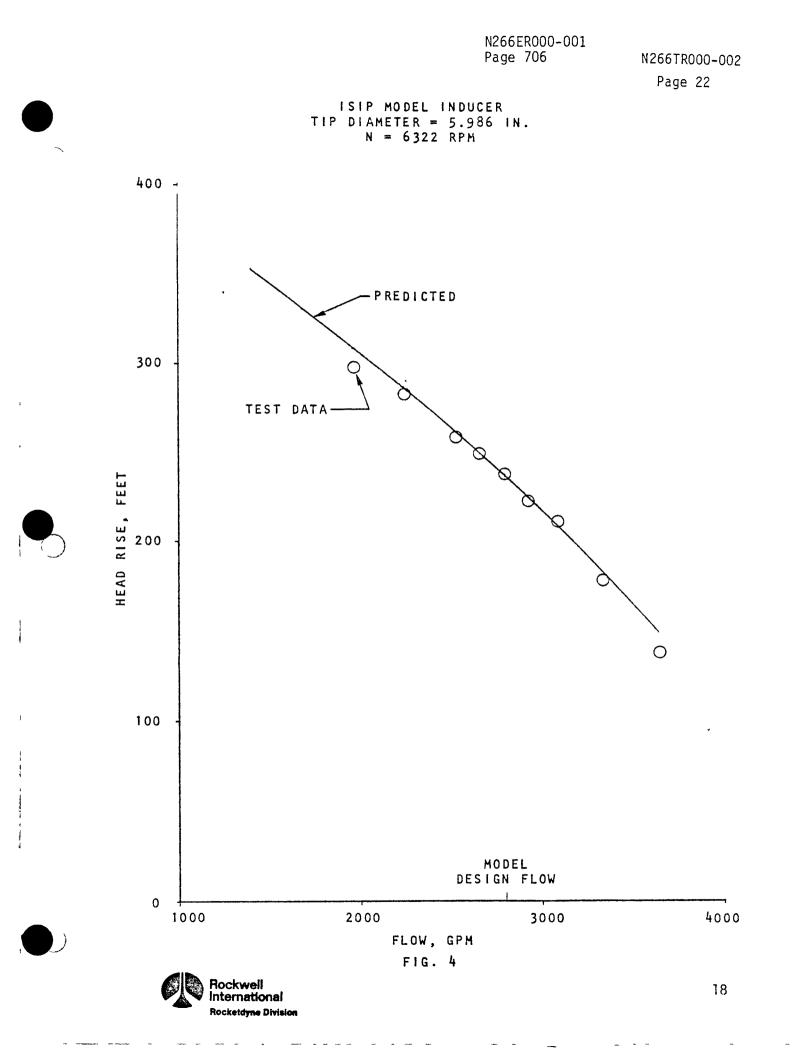
#### Inducer Head-Flow Performance

Figure 4 shows the head rise for the model inducer. Two computer programs were used to predict the head rise trend, and both showed excellent agreement, both with each other and with the test data. The analytical programs correctly predicted both the design point head and the slope of the head-flow curve (the off-design performance) over a large flow range.

Figure 5 presents the head-flow curve for the full-sized inducer. The slope of the head-flow curve is sufficiently flat to enable the inducer to continue to produce significant head rise at flows over 130 percent of the design flow. This head is sufficient to keep the impeller blades from experiencing cavitation in the sodium operation eliminating cavitation damage to the impeller. This is one of the advantages of the inducer pump over those without an inducer. Conventional centrifugal impellers cannot operate over a large flow range without significant cavitation unless the NPSH supplied is very large.

The slope of the inducer head-flow curve is negative down to at least 70 percent of design flow. This covers the expected range of steady-state operation of the sodium pumps at all but the lowest speed points. The pump would be expected to maintain a negative slope over an even larger

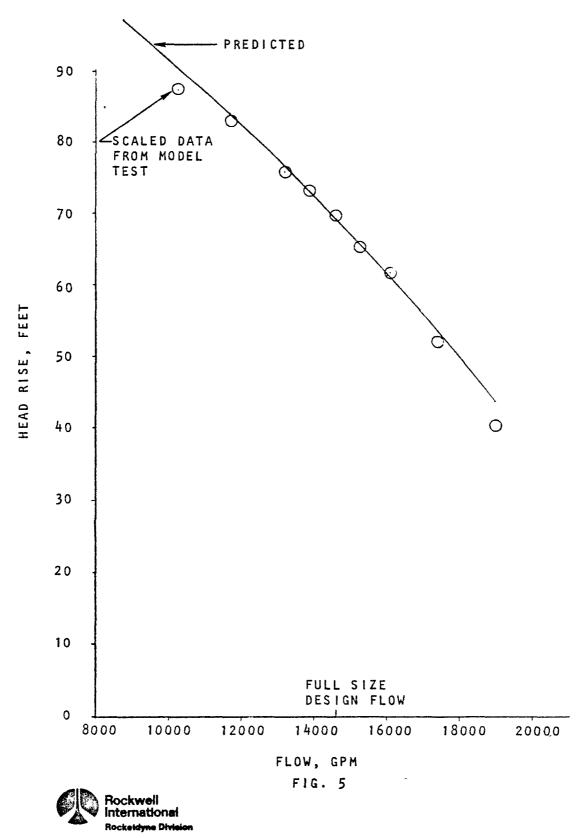




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flow range because the centrifugal impeller following the inducer has sufficient NPSH from the inducer to keep it out of cavitation at these low flows, and it would continue to develop more head after the inducer head began to decrease.

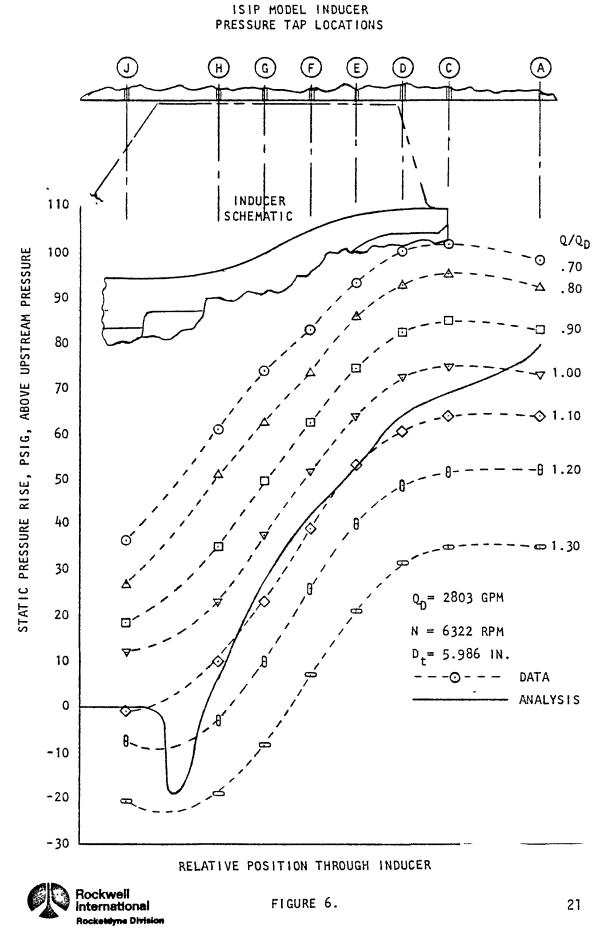
The data from the wall static pressures along the tip of the inducer give an indication of the head rise distribution through the inducer. Figure 6 presents the static pressure rise above inlet static pressure for various flow ratios. The figure also presents a sketch of the inducer with the indicated locations of the pressure taps. The data show an excellent trend of increasing pressure through the inducer. The agreement with theory is also seen to be very good. The data actually are higher than the prediction which probably indicates that there is less blockage through the blade rows than assumed in the quasi-three-dimensional flow analysis model. These results are sufficiently close to the desired distribution to give confidence in the design and its long-life potential.

### Inducer Suction Performance

The suction performance tests are run in the test facility with the throttle valve adjusted to maintain constant flow while dropping inlet pressure. The inlet pressure is decreased until a significant loss in head across the inducer is achieved. The data are reduced using computer generated CRT plots as shown in Fig. 7 and 8, the former showing the



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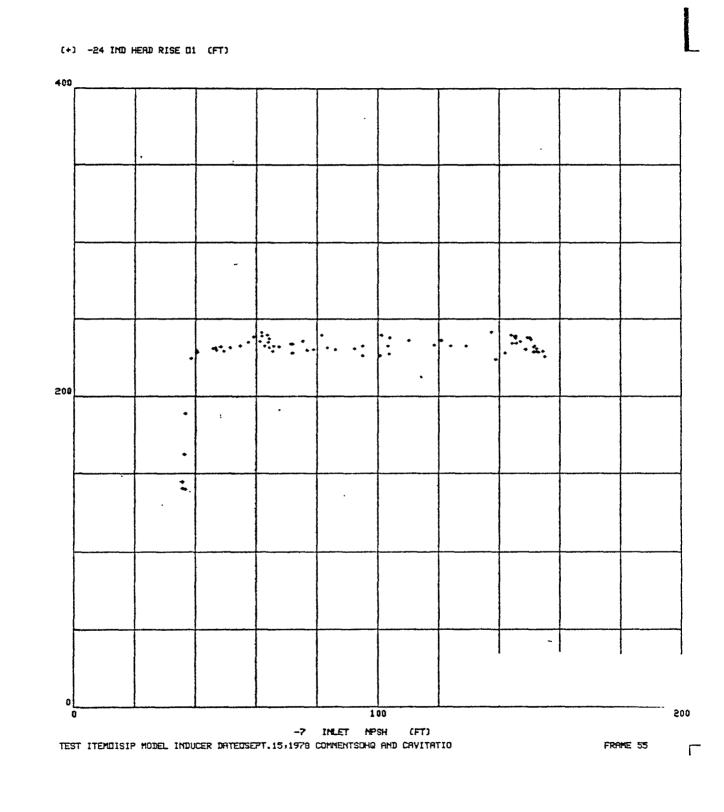


FIG. 7. CRT OF INDUCER HEAD RISE VS NPSH

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(+) -24 IND HEAD RISE D1 (FT)

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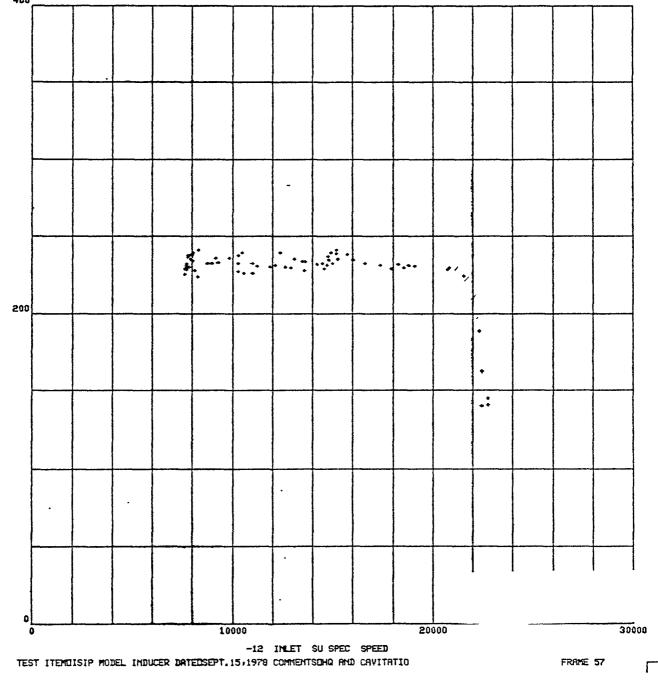


FIG 8. CRT OF INDUCER HEAD RISE VS SUCTION SPECIFIC SPEED



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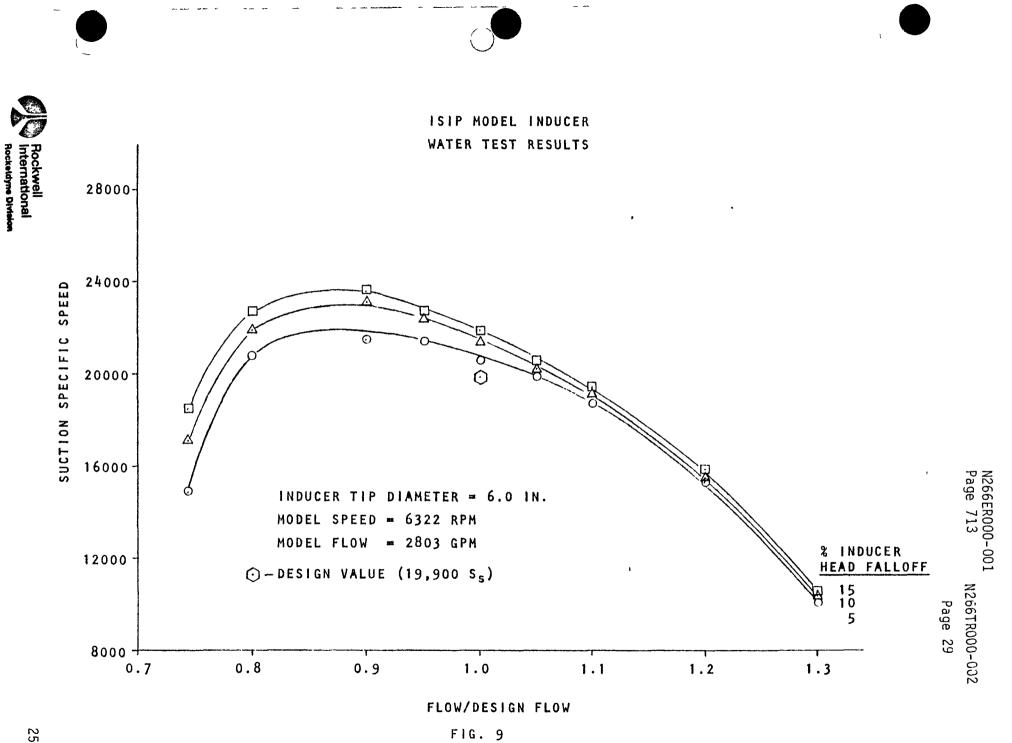
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inducer head rise as a function of inlet NPSH and the latter showing the same inducer head rise but as a function of suction specific speed. From these data, the NPSH and/or the suction specific speed can be determined for various percent fall-off of inducer head from its non-cavitating value. Generally, it is more accurate to work with the suction specific speed curve to get better resolution of the data.

A pump typical of the I.S.I.P. sodium pump will generate most of its head in the impeller. The inducer will only generate from 10 to 20 percent of the total head rise, and this inducer falls in the middle of this range. Thus, if the inducer head drops off by a certain percent, the total pump head will drop by a much smaller percent (from one-tenth to one-fifth as much) as long as the inducer is still generating sufficient head to keep the impeller out of cavitation head fall-off. This effect is even further accentuated by the fact that the impeller will actually make up for some of the loss experienced in the inducer because of the effect of the relative fluid angles. Thus, typically for this type of inducer-impeller combination, the critical NPSH quoted for the inducer based on tests without the impeller is defined as occurring at 15 to 20 percent inducer head fall-off. For the I.S.I.P. sodium inducer, the critical NPSH and suction specific speed were conservatively assumed to be at the 15 percent fall-off point. Thus, the total pump head should degrade by less than three percent for the quoted suction specific speeds.

The suction specific speed of the model inducer based on this criterion is shown in Fig. 9. The figure also shows the suction specific speed





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based on 5 and 10 percent of inducer head fall-off. All three curves are seen to be above the predicted value at the design flow. They also show good suction performance over a very large flow range. This will provide a much better NPSH margin to the impeller at the off-design points.

It should be understood that the data presented in Fig. 9 are direct results from water tests with no sodium-to-water correction factor. Rocketdyne's experience in testing cryogenic fluids has led to approaches to correct for the transition from water to cryogenic based on the difference in vapor pressure between the two fluids. This approach has also been used by other industrial and academic communities and is analytically sound. The vapor pressures in water and sodium are both so low that no correction factor should be needed. Such correction factors have been reported in some instances but are probably a result of the test facility rather than fluid thermodynamic behavior.

Using the suction specific speed data of Fig. 9, the required NPSH can be calculated for either the full-size or model pump. The calculation is based on the familiar equation

NPSH = 
$$\left[N \sqrt{Q}/N_{SS}\right]^{4/3}$$

where NPSH is in feet, speed (N) is in rpm, flow (Q) is in gpm, and  $N_{ss}$ 

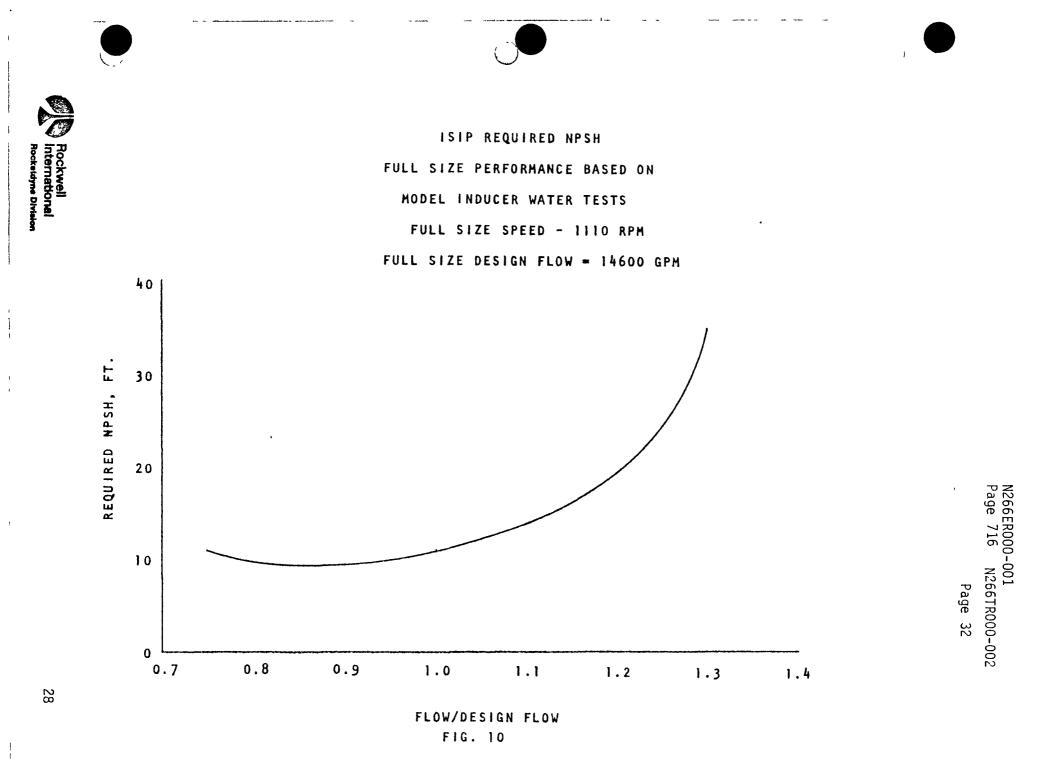


is the suction specific speed. This calculation was made using the flow and speed of the full-size pump to achieve the results shown in Fig. 10. It should be noted that the required NPSH shown in this figure is for a constant speed of 1110 rpm. If speed is varied, the required NPSH would vary directly with speed squared. At the design flow, the required NPSH is slightly over 11 feet. The required NPSH at the lower flows remains low as is typical of a good inducer design. At the higher flows, the required NPSH does increase with flow, but the increase is gradual enough that pump operation will be achieved over the full expected region of operation of flow.

During the cavitation testing, photographic movies were taken to permit observation of the development of the cavities as inlet pressure was dropped. A pressure gage was mounted adjacent to the plastic view tunnel to provide a direct correlation of inlet pressure and cavity development. Selected still photographs were made from the movies to illustrate the cavity patterns in the tip vortex. Figure 11 presents the ratio of the head divided by non-cavitating head as a function of inlet pressure and NPSH with flags to indicate where the still photographs were taken. The photographs included here are all at the design flow and represent NPSH margins from 243 percent down to zero percent.

The photographs are presented in Fig. 12 through 15, beginning at high NPSH and decreasing with successive figures. The inducer is to the left of the pressure gage. Flow direction is from the bottom of the figure up.





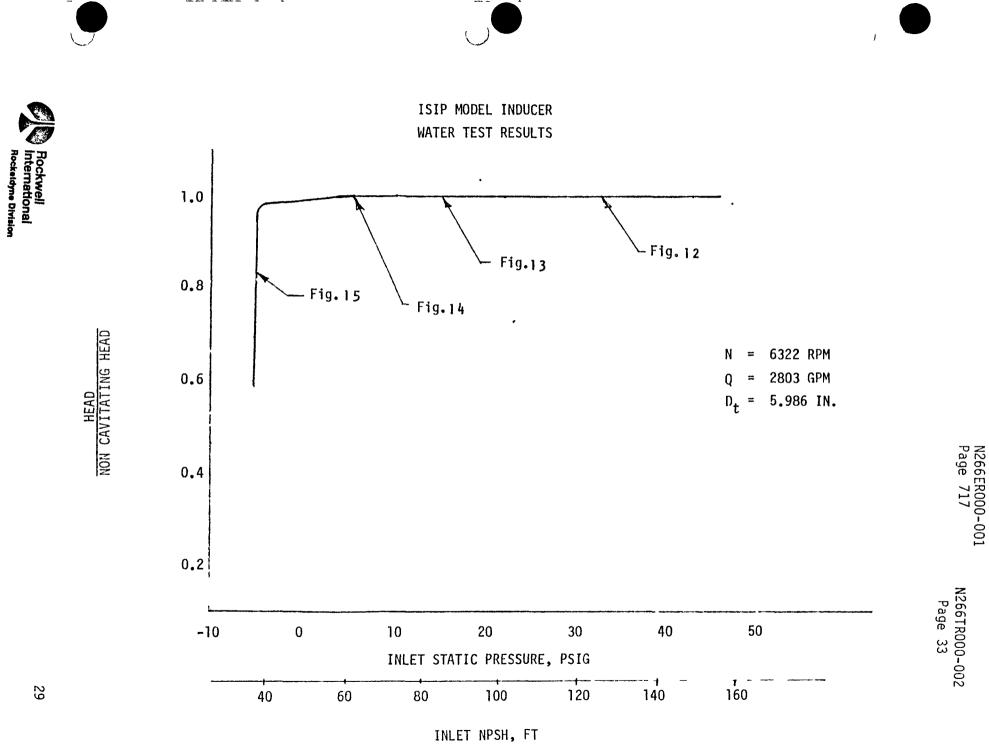


FIG. 11

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The inducer is rotating from left to right. The blades can be seen in part, and the tip vortex cavitation is fairly clear. In Fig. 12, this cavity is very small, and the collapse of the vortex can be seen between adjacent blades. In Fig. 13, the cavity has grown but still clearly collapses between blades. In Fig.14, the cavity can be seen on two adjacent blades, but is still very well contained in the fluid passage and does not extend into the region of the channel flow of the inducer. The last figure (Fig. 15) shows the cavity extended over the full length of the blade, but note that the NPSH margin is down to zero. These photographs indicate in general that the cavity is collapsing in the flow system rather than on the blade, but the dye tests (to be discussed) provide a more positive confirmation of this feature.

### Life Test Results

Testing for life in water is not as stringent as testing in sodium for laboratory tests have shown that if cavitation is collapsing in an area to cause damage, the damage rate in sodium is higher than it is in water. The magnitude of the variation has been quoted at different levels ranging from two orders of magnitude (Ref. 1) to a factor of approximately 3.0 (Ref. 2). Part of this difference was compensated for in the water tests of the model by testing at a higher inducer tip speed. Laboratory measurements of the effect of tip speed have not been totally consistent, but the majority of the data appear to support the dependency of damage



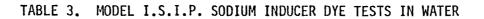
on the sixth power of the velocity. The model inducer was tested with a tip speed of 165.1 feet per second (fps) compared to 89.7 fps for the fullsize pump in sodium. Using the sixth-power relationship, this is equivalent to a damage rate 39 times faster due to the higher tip speed of the model.

However, the advantage of performing life tests with dye coatings is that the test is not attempting to identify and/or match damage rates. No attempt is made to measure the extent of damage and scale the rate to predict rate of failure of the full-size hardware. The dye test is designed to identify any potential region of cavitation damage regardless of rate. It takes very little time for a cavity bubble collapsing on the blade to remove the dye. Therefore, for a long-life design, no dye removal would be expected, and the dye test would have to verify that condition. Rocketdyne's design approach is to design to eliminate any cavitation collapse near the inducer blades. Thus, no dye removal during dye testing would be the expected result.

Table 3 presents the various operating conditions tested with dye, indicating both the target and actual test conditions. The flow was varied from approximately 95 to 130 percent of design flow, and the NPSH margin was varied for some of the flows. There was no removal of dye for any of the tests performed substantiating the long-life design features of this inducer. In fact, the I.S.I.P. model inducer showed a greater flow



		TARGET	VALUES		TEST RESULT VALUES				
BUILD	FLOW (GPM)	Q/Q <sub>DESIGN</sub>	INLET PRESSURE (PSIA)	NPSH MARGIN	FLOW (GPM)	Q/Q <sub>DESIGN</sub>	INLET PRESSURE (PSIA)	NPSH MARGIN	
CONCENTRIC	2663	0.95	50.4	270	2662	0.95	48.5	258	
	2803	1.00	50.4	240	2804	1.00	48.6	230	
			43.3	200	2811	1.00	43.0	197	
			31.7	130	2812	1.00	29.6	115	
			27.0	100	2806	1.00	26.0	97	
	2943	1.05	50.4	210	2943	1.05	48.4	197	
	3083	1.10	54.5	200	3087	1.10	54.4	199	
			34.0	100	3086	1.10	33.8	98	
	3364	1.20	48.7	100	3372	1.20	48.2	99	
	3476	1.24	49.4	70	3473	1.24	49.4	68	
	3644	1.30	67.0	50	3657	1.30	66.1	47	





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range for no dye removal due to cavitation than any previous inducer tested to date. The dye tests would indicate that long life could be expected in the sodium testing for flows varying from 95 to 130 percent of design flow and over a significant NPSH range. This provides the very highest confidence in the sodium testing, particularly considering the large difference in tip speeds between model and full-size.

The only way to document the results of the dye tests is through photographs of the blades post-test. Such photographs were made of each inducer blade for each test of Table 3. The photographs are not ideal in that light reflections and dye streaking that occurred when the blade was originally coated can appear as dye removal when no such removal was experienced. Nevertheless, it is instructive to include representative photographs to verify the results. Photographs were taken of each of the four blades of the inducer after each of the tests of Table 3. Reproductions of all of the photographs would be an unnecessary expense, but a representative photograph from each test is shown in Figs. 16 through 26. A mirror was used behind the inducer to show the backside of the blades.

The effects of lighting and dye streaking on the photographic coverage are evident on some of the photographs. Figure 16 shows some evidence of streaking. Several photographs indicate streaking near the trailing edge of the blade, but this is due to the light reflection. The light reflection also presents a light spot near the junction of the blade and the hub at the blade leading edge. The tips of the blades were not coated to prevent smearing any dye on the plastic tunnel.



## CONCLUSIONS

The testing of the model I.S.I.P. inducer with a concentric scaled tip clearance has been completed with the highest degree of success. The inducer met its design head and exceeded its design suction performance. The slope of the head-flow curve was consistent and negative over the full test range of ± 30 percent about design flow. The excellent suction performance was maintained over a wide flow range providing good NPSH margin to the impeller over this range. The life tests demonstrated the long-life characteristics of the design, indicating no evidence of dye removal due to cavitation from 95 to 130 percent of design flow and over a significant NPSH range. There was no dye removal under any of the test conditions tested on this inducer. Thus, the full-size pump can be tested in sodium with the highest confidence in its life characteristics.

Further testing of the model inducer with both an eccentric tunnel and with a reduced clearance concentric tunnel have been initiated but will be reported in a separate report.





## APPENDIX M

MODEL INDUCER WATER TUNNEL TEST REPORT - ECCENTRIC OPERATION

Rocketdyne Document R/H 9113-3756 (Assigned ESG Document number is N266TR000-004)

Figures 13 thru 36 have been removed from this document because they contain proprietary information, as defined by DOE contract.

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Rocketdyne Division 6633 Canoga Avenue Canoga Park, California 91304

RI/RD 79-192

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INTERMEDIATE SODIUM INDUCER PUMP MODEL INDUCER WATER TUNNEL TEST REPORT INFLUENCE OF ECCENTRIC AND REDUCED TIP CLEARANCE UPON PERFORMANCE

R/H 9113-3756

28 March 1979

## PREPARED BY

W. Rosenmann Rockwell International Corporation Rocketdyne Division 6633 Canoga Avenue Canoga Park, California 91304

E. D() Jackson Manager Hydrodynamics Unit

APPROVED BX Wo1

Project Engineer Sodium Pump Program

D. E. Davis Program Manager Dynamic Power Programs

PREPARED FOR

Energy Systems Group Atomic International Division Under IDWA No. N-1327 Authorized Under ESG Prime Contract EY-76-C-03-0824

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#### INTRODUCTION

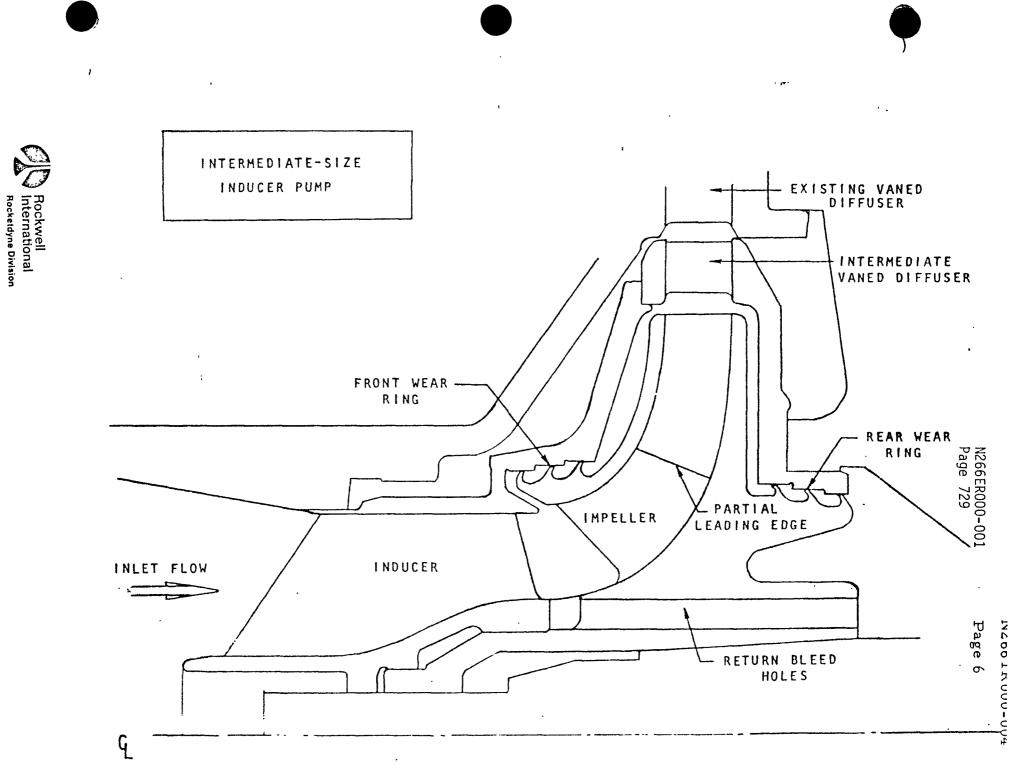
The Intermediate-Size Inducer Pump (I.S.I.P.) was designed to operate in the existing FFTP pump housing and to achieve the required pump head rise at the same speed and flow as the existing pump. The existing pump consists of four basic hydrodynamic elements:

- 1. Inlet Elbow
- 2. Centrifugal Impeller
- 3. Vaned Diffuser
- 4. Discharge Housing \*

All of these elements except the centrifugal impeller were to be retained in an unmodified form for the I.S.I.P. design. The centrifugal impeller was to be replaced with a new design consisting of both an inducer and centrifugal impeller. The objective is to demonstrate the capability of designing an inducer pump for long life in sodium operation so that the advantages of the inducer pump can be realized in future sodium pump applications. These advantages consist primarily in the smaller envelope size and lower weight realized as a result of the better suction performance capability of the inducer. These advantages result in significant cost savings and ease of fabrication and handling for the very large pumps required in many of the reactor coolant loop systems.

Figure 1 shows a cross-section of the primary pump components. The most significant hydrodynamic challenge in the design is to achieve the long





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life in the inducer. To provide early confidence in the design before finalizing the fabrication and initiating testing of the full-size pump in sodium, a model of the inducer was fabricated for testing in the Rocketdyne water tunnel. The testing included both life and performance tests using a one-third scale model. The testing was successful and demonstrated both excellent performance and life characteristics for the Rocketdyne design. This report describes both the test program and test results.



#### TEST ARTICLE

The inducer design was based on the same practices established and demonstrated by the successful waterjet inducer design concepts developed by Rocketdyne. The primary dimensions of both the full-size and water model of the inducer are given in Table 1. As can be seen, the model is approximately a one-third scale version of the full-size. The model inducer is defined by drawing number EWR 344240.

This test article was installed in the test adapter as shown in drawing number EWR 344200. The test adapter consisted of an inducer shaft supported on the test rolling element bearings and splined to an impeller assembly. The impeller assembly, which was driven by the facility gearbox, provided the head requirements to circulate the fluid through the system.

Two new tunnels for the inducer were fabricated. The first was eccentric with 0.007 inch offset of the tunnel inside diameter centerline from the inducer shaft centerline. Radial tip clearance ranged from a minimum of 0.007 inch to a maximum of 0.021 inch. This range represents the scaled worst case of the full size manufacturing tolerance eccentricity. The second tunnel was concentric with the inducer with a reduced radial tip clearance of 0.008 inch compared with the nominal model radial tip clearance of 0.016 inch in Table I. The eccentric tunnel, EWR 360711, was fabricated from clear acrylic plastic, and the concentric tunnel, EWR 360739 was fabricated from aluminum alloy.

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# TABLE 1. I.S.I.P. INDUCER FEATURES

PARAMETER	FULL-SIZE HARDWARE	WATER-MODEL HARDWARE
No. of Blades	4	4
Tip Diameter, In.	18.53	5.986
Inlet Hub Diameter, In.	6.626	2.140
Disch.Hub Diameter, In.	11.358	3.669
Tip Radial Clearance, In.	0.050	0.016
Speed, RPM	1110	6322
Tip Speed, FPS	89.7	165.1
Design Flow, GPM	14,600	2803
Inlet Flow Coefficient	0.222	0.222
Disch.Flow Coefficient	0.310	0.310



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#### TEST FACILITY

The testing was conducted at Rocketdyne's Pump Calibration Facility in Dept. 592. The pump was driven by a 1200 RPM, reversible, synchronous electric motor, which is rated at 4000 horsepower. The motor drives through a 4000 horsepower gearbox, which has two output shafts. One shaft is capable of producing speeds of 6322 and 8013 RPM. The other shaft is capable of producing speeds of 6322 and 10,029 RPM. The pump was run on the North powerhead (pump position No. 1) at 6322 RPM for this inducer test.

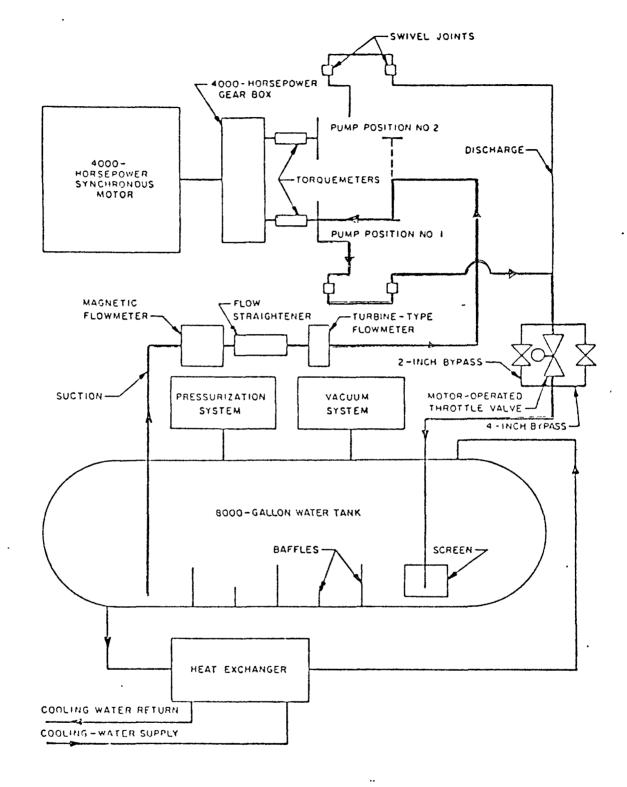
Figure 2 shows a schematic of the drive system and flow loop. An 8000 gallon water tank supplies water for the flow loop. This tank is rated at 150 psi with a vacuum capability of 28.5 inches of vacuum. The flow is measured by a turbine flow meter in the inlet line and regulated by a motor-operated throttle value in the discharge line, whereas, the inlet pressure is regulated by controlling the tank pressure.

The inlet ducting consists of 8-inch schedule 40 steel piping, and the discharge loop is 4-inch diameter steel piping. All metallic coupling joints were heavily greased to assure an air tight system. An orifice was installed in the inlet line to keep the tank pressure up during cavitation tests to further avoid air leaks.



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The inducer is mounted on its shaft which is supported by its own bearing system as shown in drawing number EWR 344200. The inducer shaft is connected to an impeller shaft by a quill shaft. The impeller is an 11-inch tip diameter centrifugal impeller previously designed and fabricated at Rocketdyne and used in the current program as a slave impeller to generate the required head to provide the design flow of the inducer. The impeller is far enough downstream of the inducer to permit instrumentation to be inserted between the two for measuring inducer performance without impeller interference. The test arrangement is designed to establish the inducer performance characteristics as an independent component. The only drawback of this facility arrangement is that the only facility torquemeter available is located between the impeller and the drive gearbox. Thus, there is no way to separate the drive torque of the inducer from the slave impeller, hence no way to determine the efficiency of the inducer. This is not a significant problem because the overall sodium pump efficiency is determined during sodium pump tests and is primarily driven by the centrifugal impeller and discharge system rather than the inducer.

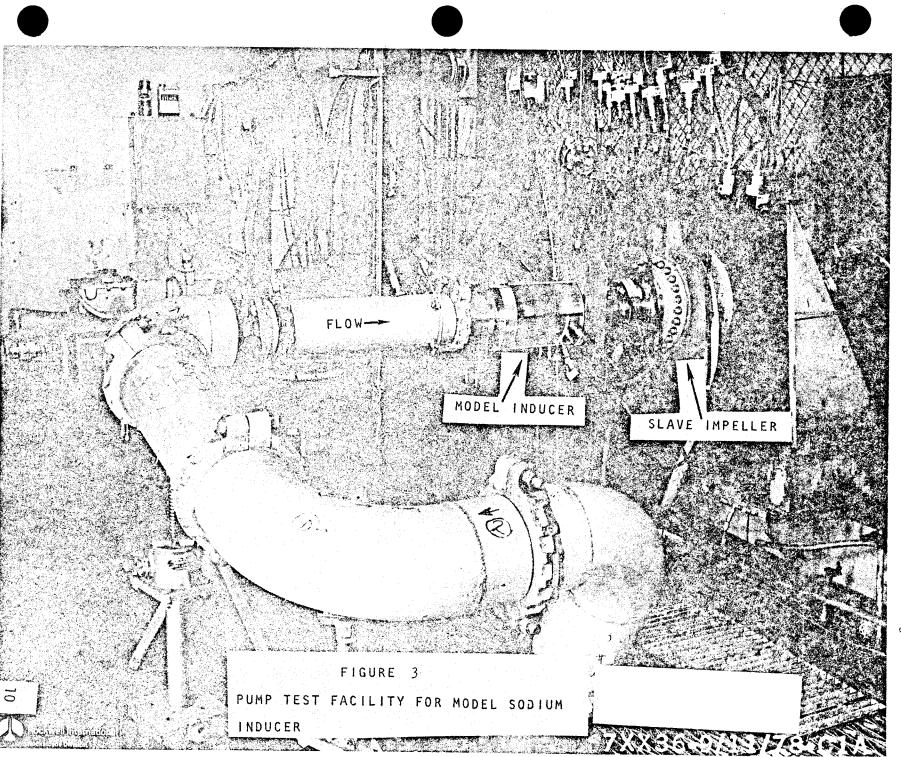
The impeller housing and shaft system was mounted rigidly to a steel frame to assure perfect alignment with the driving motor and, thus, avoid possible oscillation of the system. Testing verified that both the alignment and quill shaft arrangement were satisfactory to prevent any significant rotor dynamic vibrations in either the inducer or impeller.

The inducer was enclosed in a plastic viewing tunnel, which allowed both



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photographic and visual observation of the cavitation characteristics of the flow through the inducer. The test setup is shown in Fig. 3.

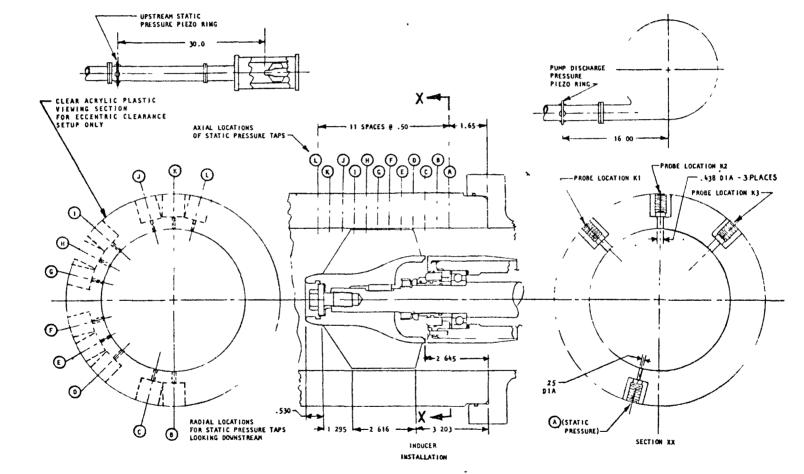


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## TEST INSTRUMENTATION

Table 2 presents a list of the instrumentation used during the testing. Figure 4 shows the pressure tap locations in the tester and facility. The inlet pressure consisted of a 4-hole piezometer ring located 30 inches upstream of the inducer to avoid interference effects due to the inducer tip backflow. Downstream of the inducer, two total pressure (Kiel) probes were used to measure the discharge pressure at the mid-blade height position. These probes are subject to clogging due to solid material in the water, and the use of two probes provides more assurance of getting good data during the tests. Yaw probe surveys were carried out to provide flow and pressure data as a function of radius and will be reported separately. There were also numerous static pressures recorded along the tip over the inducer and at the inducer discharge. These were all single point static pressures and provide an indication of the head distribution through the inducer. Drawing number EWR 344205 shows the location of these taps with the same identification keys as used in Table 2. They are also shown in Fig. 4.

Other instrumentation included the turbine flowmeter and an accelerometer fastened to the viewing section to detect excessive vibrations. The electric motor speed is fixed during these tests. The torquemeter is omitted for this test series. Water temperature is measured in the inlet line to permit calculation of the water density and vapor pressure. The



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## FIGURE 4. GENERAL ARRANGEMENT OF PRESSURE PICKUP LOCATIONS

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## TABLE 2. INSTRUMENTATION

	RANGE
Inlet Static Pressure, Piezometer, PSIA	0 ÷ 100
Discharge Total Pressure, #1 Tunne1 (A) PSIG	0 ÷ 500
Flowrate, GPM	0 ÷ 4000
Speed, RPM	6322
Torquemeter, IN LB	0 ÷ 10,000
Water Temperature, <sup>O</sup> F	40 ÷ 140
Discharge Total Pressure #2 Tunnel   PSIG	0 ÷ 500
Pump Discharge Static Pressure, Pipe, PSIG	0 ÷ 500
Pump Delta Pressure, PSI	0 ÷ 500
Static Pressure, Tunnel \land , PSIG	0 ÷ 100
Static Pressure, Tunnel 🔘 PSIG	0 ÷ 200
Static Pressure, Tunnel (D) PSIG	0 ÷ 200
Static Pressure, Tunnel (E) PSIG	0 ÷ 200
Static Pressure, Tunnel 🕞 PSIG	0 ÷ 200
Static Pressure, Tunnel 🌀 PSIG	0 ÷ 200
Static Pressure, Tunnel (H) PSIG	0 ÷ 200
Static Pressure, Tunnel 🛈 PSIG	0 ÷ 200

+ Circled letters refer to section locations on Drawing No. EWR 344205

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other measured pressures are used for facility diagnostics and conducting of the tests.

All of the data are recorded by a digital acquisition system (Autodata 9 by Accurex) on a "floppy disk" which is transmitted post-test to a digital computer. The data are reduced to provide all pertinent data and calculated parameters by a data reduction program written specifically for the Pump Test Facility. The data are then printed in tabular form, and if desired, selected CRT (cathode ray tube) graphic printouts are obtained.

In addition to the recorded data, photographic techniques were used with strobe-light stop-action cameras to record the cavitation patterns during certain tests. These photographic records were then spliced together to form an annotated presentation of the results. Still photographs were also used post-test to record the dye patterns after running life tests (to be described).

## TEST PROGRAM

The purpose of this test program was to conduct head-flow tests, cavitation tests, and dye tests for demonstrating the relative cavitation damage potential of the inducer at various radial tip clearance conditions.

## Head-Flow Test

Head-flow tests were conducted with a constant inlet pressure of 65.0 psig
which is sufficiently above the critical NPSH even at high flows to
demonstrate non-cavitating inducer performance. Nine flowrates from
1962 GPM to 3644 GPM were run representing a variation from -30 to +30
percent about the design flow of 2803 GPM. Flow was varied by changing
the control settings on the automatic flow control valve. Data samples
were recorded on the Autodata 9 system at each specific flow when stabilization
had been achieved.

#### Inducer Suction Performance

Inlet pressure was set initially at 80 to 85 psia and was allowed to decay continuously, while the flow was held constant, until the pump pressure rise decayed by 10 to 20 percent. The test sequence was performed at nine different flowrates ranging from 1962 to 3644 gpm. These latter extreme flow points represent ±30 percent deviation from the design flow of 2803 gpm. Data were continuously recorded on the Autodata system during the pressure

decay. The purpose of these tests was to establish inducer suction performance with the modified tip clearance conditions.

## Design Point Life Tests

After coating the inducer blades with a water-insoluble dye, twenty minute tests were performed at the design flow of 2803 GPM. With the eccentric tip clearance tunnel, three NPSH margins of 200, 100, and 50 percent above critical NPSH were used. With the concentric close tip clearance tunnel, the 200 and 100 percent NPSH' margins were used. Twenty operating data samples were acquired during these steady parameter runs every five minutes to maintain a record of compliance with specified operating conditions.

The dye erosion tests using "Magic Marker" dye has been proven, through extensive use at Rocketdyne, to be an excellent means of locating areas of potential cavitation damage during relatively short duration tests and thus reduce the need to conduct many costly, long duration runs which involve actual metal damage.

Cavitation sensitive coatings for water tests had been used previously by other researchers (Ref. 1) in connection with tests for liquid metal pumps. They used various types of acrylic coatings and even cadmium plating.

## Off-Design Life Test

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These tests were conducted in the same manner as the Design Point Life Tests

described above. Nine more tests were conducted with the eccentric tip clearance setup, and six more tests were conducted with the reduced tip clearance setup. NPSH margins ranged from 20 to 200 percent. Data acquisition during these runs was identical to that used during Design Life Tests.

#### TEST RESULTS

All of the data presented in this report are based on water tests. Long term experience at Rocketdyne has demonstrated that water tests give excellent predictability of pump performance with other liquids if proper conversion factors such as specific weight and vapor pressure are used to calculate the behavior with the other fluids.

## Inducer Head-Flow Performance,

Figure 5 shows the head rise for the model inducer with two different tip clearances. The test data for the eccentric tip clearance setup were almost identical to the data presented in Fig. 4 of Ref. 2 in which the same inducer was tested with a concentric tip clearance of .016 inch. In the reduced tip clearance setup, the head rise was slightly higher at design flow and above design flow. Below design flow, the head rise was slightly lower with the reduced tip clearance. The reduced clearance will result in less tip clearance flow and would be expected to lower the tip clearance losses. This would result in slightly higher head and efficiency. No explanation can be given for this curve crossover. Some scattering of data for the head rise values was encountered during the test series. The values shown in this graph were extracted from H-Q runs, high NPSH portions of cavitation runs, and life tests. Figure 6 presents the head-flow for the full-sized inducer using eccentric tip clearance. The impeller has the capability

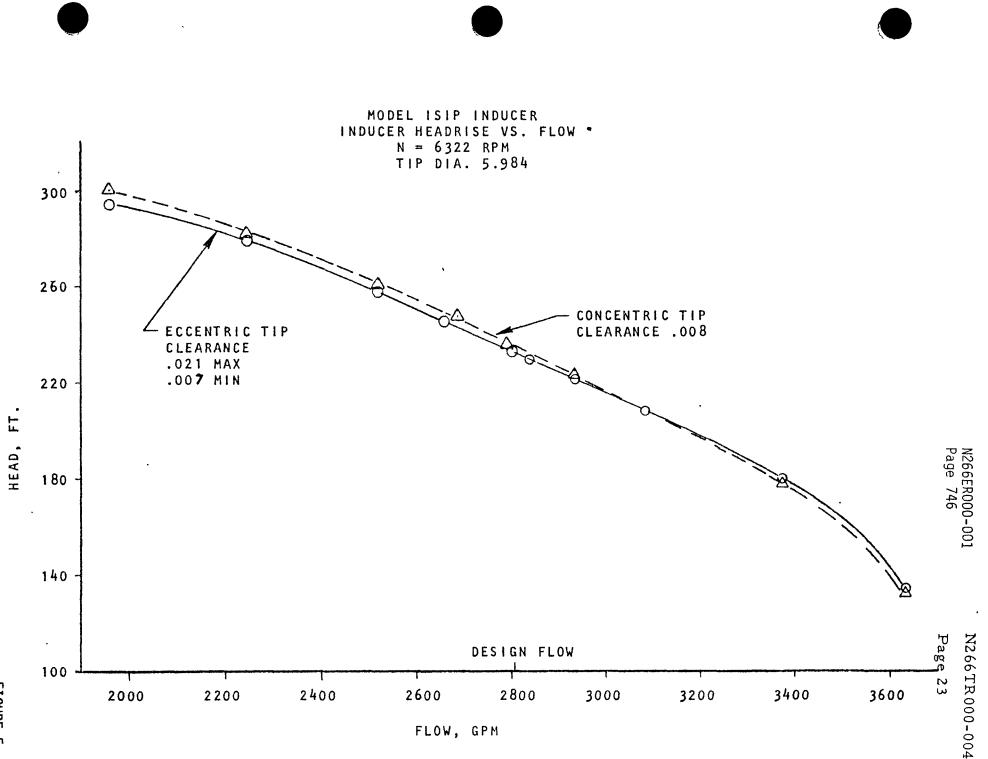
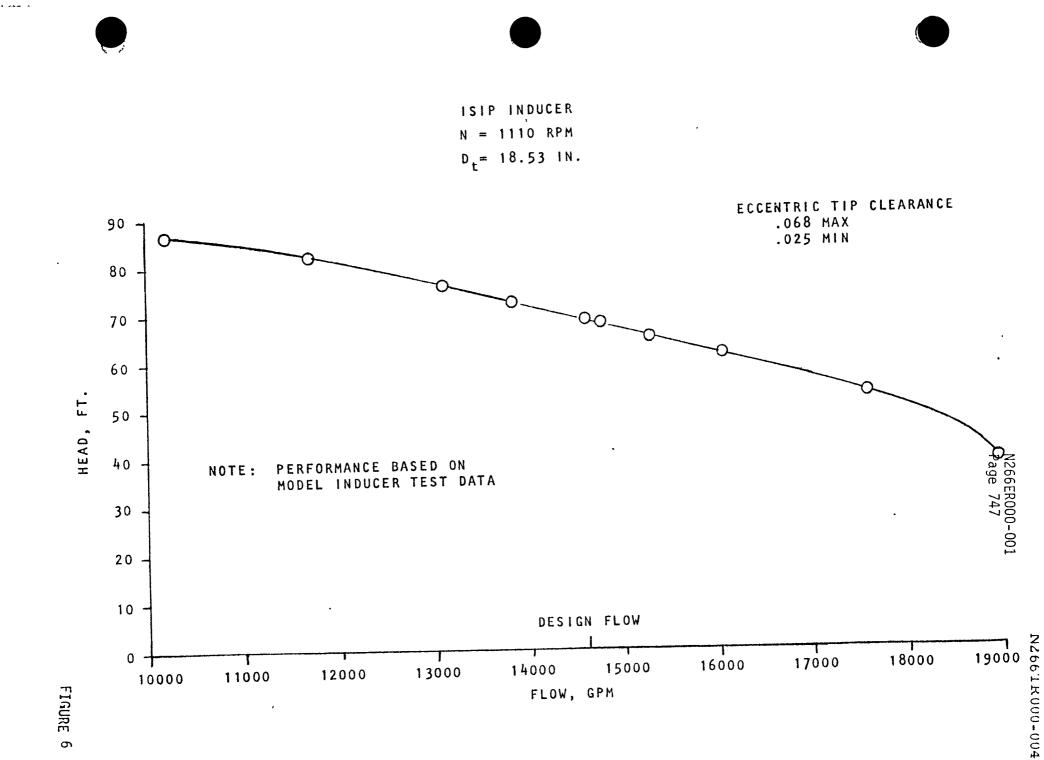


FIGURE 5



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of functioning normally without serious cavitation problems with this inducer performance. Based on these tests, it is clear that neither the eccentricity nor the reduced clearance had any significant effect on the non-cavitating head rise of the inducer.

#### Inducer Suction Performance

The suction performance of the inducer using the eccentric tip clearance tunnel is shown in Fig. 7. The curve shows suction specific speed versus  $Q/Q_{Design}$ . The latter represents the ratio of actual flow divided by design flow. Two values of head fall-off were used to determine the critical NPSH from which the suction specific speed was calculated. The numerical difference between the two suction specific speed curves amounted to only about three percent. This indicates a sharp head loss near the critical NPSH which is characteristic of well designed inducers. This characteristic can also be seen on the CRT graphic pTot in Fig. 8. The data shows a stable head rise down to just above the critical NPSH and then a sharp head loss below that point.

For the ISIP inducer, the critical NPSH values were conservatively assumed to be at 15 percent head fall-off. At this operating point, the impeller usually compensates for most of the inducer head loss by increased head rise within the impeller. Figure 9 shows the suction specific speed versus flow ratio for concentric normal tip clearance (from Ref. 2), eccentric normal tip clearance, and concentric reduced tip clearance.

At design flow and above, the three curves have only slight differences. At 70 percent to 90 percent of design flow deviations occurred between the

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MODEL INTERMEDIATE SODIUM INDUCER PUMP (ISIP)

6322 RPM

TIP DIA. = 5.986 INCH  $Q_{DESIGN} = 2803$  GPM ECCENTRIC TIP CLEARANCE: .021 MAX



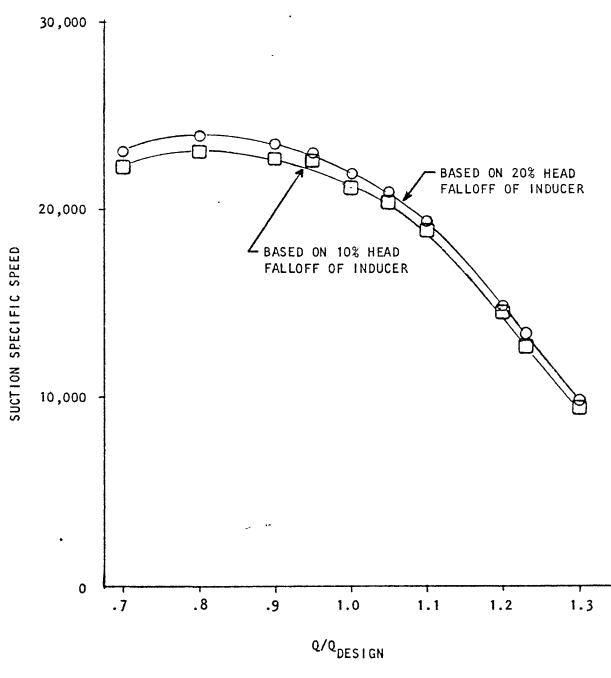
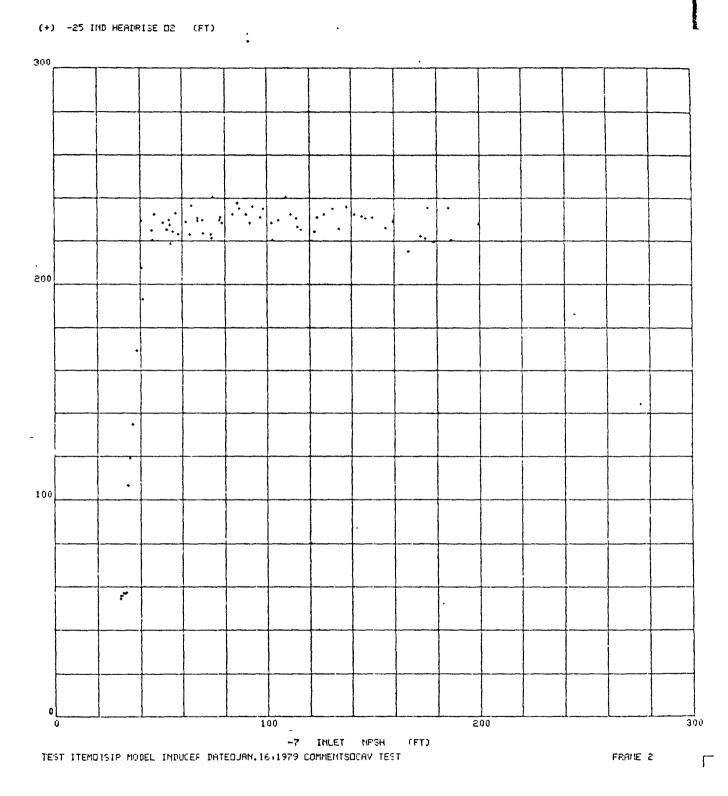


FIGURE 7 -

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FIGURE 8. CRT GRAPHIC DISPLAY SHOWING HEAD RISE VS. NPSH TIP CLEARANCE ECCENTRIC MIN. .007 IN. - MAX .021 IN. FLOW: 100 PERCENT OF DESIGN FLOW

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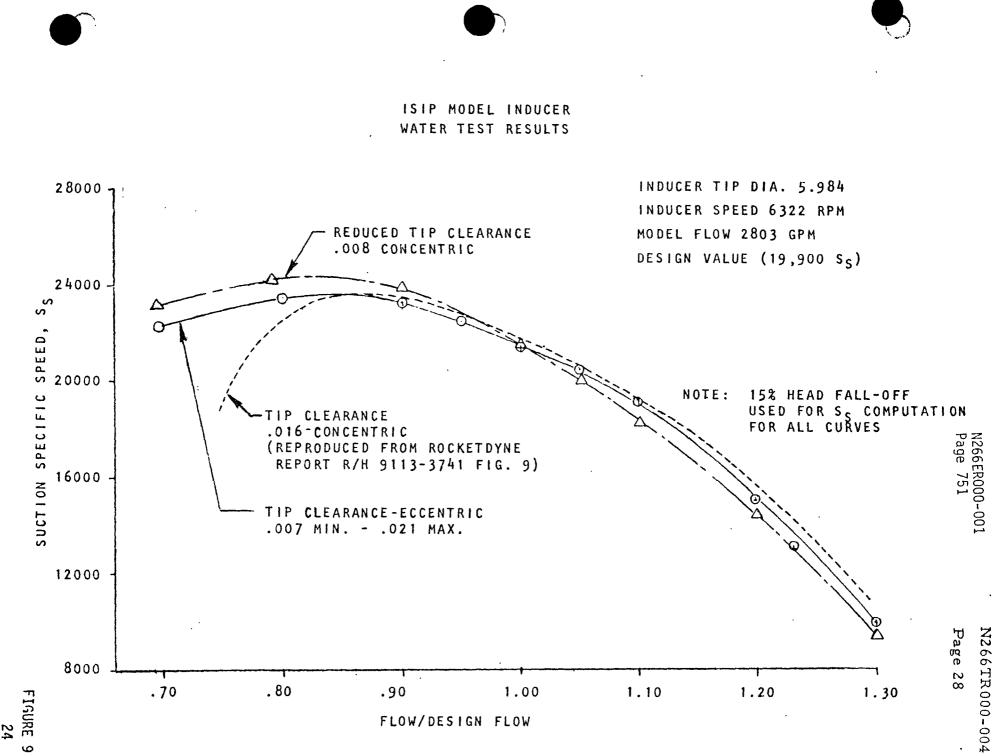
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three curves. The eccentric clearance setup exhibited somewhat better suction performance at the lower flows.

The reduced tip clearance setup also improved suction performance at flows below design flow. This result conforms with tests on other inducers.

At flows below approximately 85 percent of design flow there is an increase in tip leakage which flows opposite to the main flow direction and has an angular whirl velocity which is approximately one-half the inducer angular velocity. It mixes with the oncoming flow and imparts some angular velocity to it. This pre-whirl plus other flow disturbances usually cause a degradation in suction performance. Any tip clearance reduction which reduces this back flow improves the suction performance.

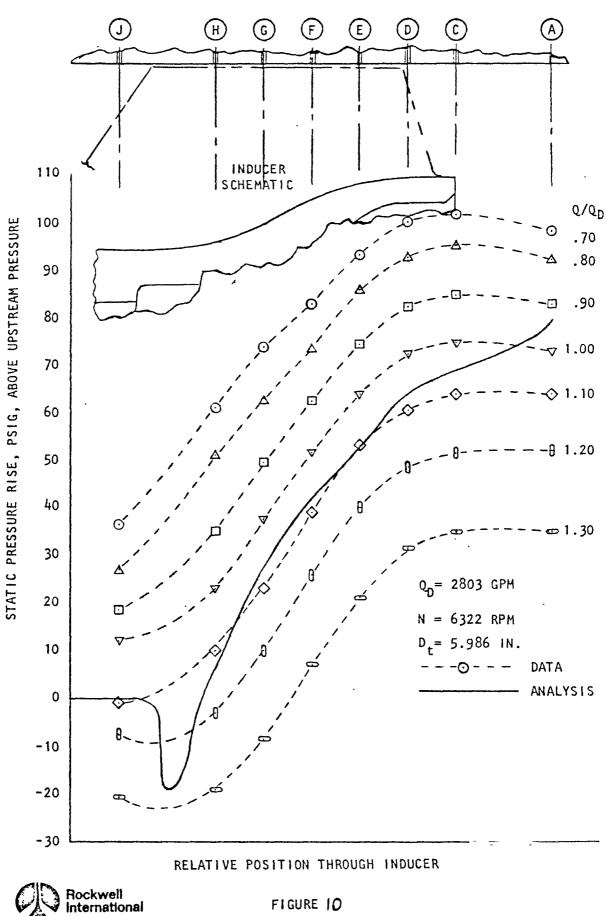
## Inducer Internal Performance

In addition to the upstream piezo ring, static pressure tap, and the downstream kiel total pressure probe, the test instrumentation consisted of wall static pressure taps which were located at various axial and circumferential locations between the leading and trailing edges of the inducer as shown in Fig. 4. The data obtained from these pressures are presented in Fig. 10 and 11.

Figure 10 shows data obtained during an H-Q run. The inlet pressure was high enough to prevent cavitation head loss at all flows which were tested. At design flow, the measured head rise increased almost linearly from the

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**Rocketdyne Division** 

leading edge to within 0.50 inch of the trailing edge measured axially along the tip. Aft of this point the rate of pressure rise gradually diminished to zero.

The performance was in full agreement with theoretical predictions based on a quasi-three-dimensional mathematical model. The negative pressure which occurs at station J is due to hub blockage which causes a static pressure drop as compared to conditions which revail in front of the inducer.

It may also be noticed that the front part of the inducer (between the leading edge and station H) performs like a turbine at flows above  $Q/Q_{Design}$  equals 1.10. A survey of the theoretical blade incidence angles leads to an expectation of zero or negative pressure rise at high flows in this area.

Figure 10 also shows predicted pressure rise at design flow based on quasithree-dimensional analysis.

The predicted data show a sharp pressure drop just aft of the leading edge. This curve dip is primarily due to the limitations of the math modeling analysis but is partially explained by a rapid rate of increase in blockage just aft of the leading edge without a corresponding change in blade angle. This dip could not be defined precisely by experimental data due to lack of a pressure tap at the affected axial location.

Figure 11 shows the data obtained during a cavitation run at design flow.

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## STATIC PRESSURE RISE VS INLET NPSH AS MEASURED ALONG VARIOUS AXIAL LOCATIONS MODEL ISIP INDUCER - EXPERIMENTAL DATA

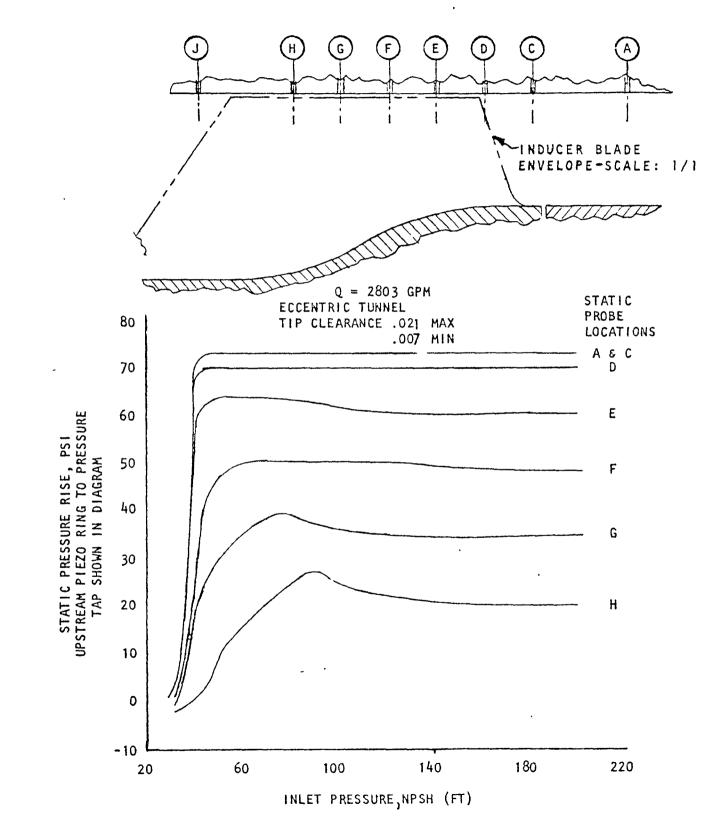


FIGURE 11

It confirms performance predictions that at certain operating conditions just above the critical NPSH the decreased head rise due to partial cavitation in the front part of the inducer is fully compensated by increased head rise in the aft part of the inducer. This phenomenon occurs in this test approximately between inlet NPSH values of between 45 and 60 feet. The reason for the rise in pressure above the non-cavitating pressure at stations G and H cannot be ascertained at this time. One possible reason is that localized increased pressure rise may occur just aft of the trailing boundary of the blade suction side cavity.

The most useful data shown in Figure 11 reveals that cavitation of sufficient magnitude to effect a shift in wall static pressures occurs at 120 feet of NPSH which is 200 percent above the critical NPSH of 40 feet at design flow.

An examination of the data at 80 percent of design flow shows that this pressure shift near the front part of the inducer also first occurs at approximately 200 percent above the critical NPSH.

Further examination of the data at 120 percent of design flow shows that this pressure shift between critical NPSH and 200 percent above critical NPSH virtually disappears since the forward part of the inducer has only a small head rise even in the non-cavitation operating regime.

## Motion Picture Test Data

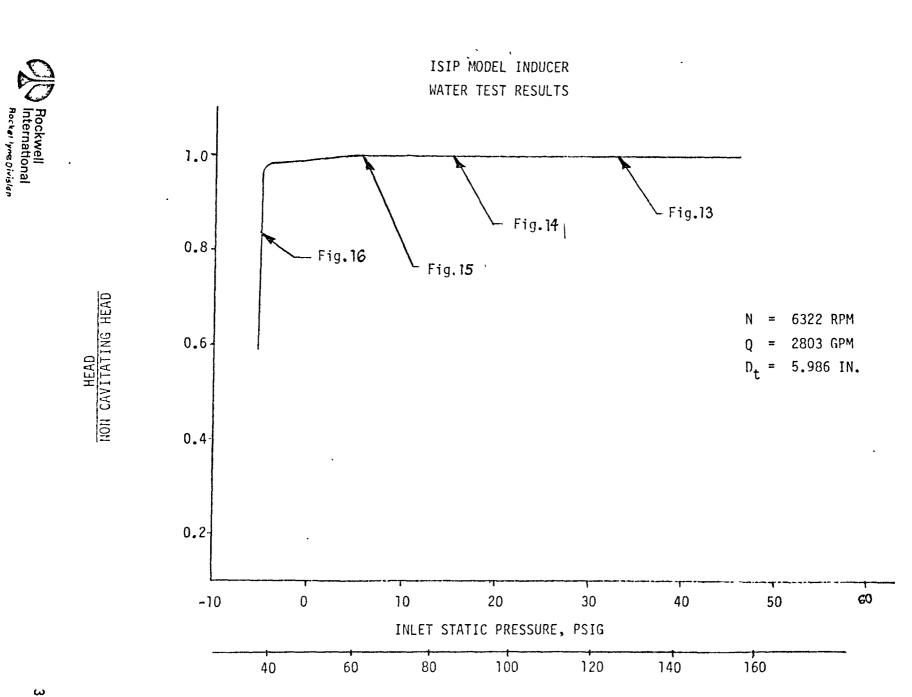
During the cavitation testing, photographic movies were taken to permit

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Page 34 observation of tip vortices and blade cavities as inlet pressure was being reduced. Tip vortices could easily be seen but blade suction side cavities were very difficult to observe due to turbulence. The pulse camera took approximately one picture for each five inducer revolutions. A pressure gage was mounted within the picture to provide direct correlation between inlet pressure and vortex generation. Figure 12 presents the ratio of the head divided by the non-cavitating head as a function of inlet pressure and NPSH with flags to indicate where the still photographs were taken. The photographs in this report include only those which were taken during the design flow run and are shown in Figures 13 through 16.

#### Life Test Results

Tests by other researches have shown that cavitation damage caused by collapsing vapor bubbles on the pump rotor surface is less in water than in sodium. The magnitude of the variation has been quoted at different levels ranging from two orders of magnitude (Ref. 3) to a factor of approximately 3.0 (Ref. 4). Part of this difference was compensated for in the water tests of the model by testing at a higher inducer tip speed. Laboratory measurements of the effect of tip speed have not been totally consistent, but the majority of the data appear to support the dependency of damage on the sixth power of the velocity. The model inducer was tested with a tip speed of 165.1 feet per second (fps) compared to 89.7 fps for the fullsize pump in sodium. Using the sixth-power relationship, this is equivalent to a damage rate 39 times faster due to the higher tip speed of the model.



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However, the advantage of performing life tests with dye coatings is that the test is not attempting to identify and/or match damage rates. No attempt is made to measure the extent of damage and scale the rate to predict rate of failure of the full-size hardware. The dye test is designed to identify any potential region of cavitation damage regardless of rate. It takes very little time for a cavity bubble collapsing on the blade to remove the dye. Therefore, for a long-life design, no dye removal would be expected, and the dye test would have to verify that condition. Rocketdyne's design approach is to design to eliminate any cavitation collapse on the inducer blades over the operating range.

Tables 3 and 4 present the various operating conditions tested with dye, indicating both the target and actual test conditions. The flow was varied from approximately 70 to 130 percent of design flow, and the NPSH margin was varied for some flows. There was no dye removal above 80 percent of design flow, substantiating the long-life design features of this inducer. In fact, the I.S.I.P model inducer showed a greater flow range for no dye removal due to cavitation than any previous inducer tested to date. The dye tests would indicate that long life could be expected in the sodium testing for flows varying from 90 to 130 percent of design flow and over a significant NPSH range. This provides the very highest confidence in the sodium testing, paricularly considering the large difference in tip speeds between model and full-size.

The only way to document the results of the dye tests is through photographs of the blades post-test. Such photographs were made of each inducer

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	TARGET VALUES				TEST RESULT VALUES				
BUILD	FLOW (gpm)	Q/Q <sub>DESIGN</sub>	INLET PRESSURE (PSIA)	PERCENT NPSH MARGIN	FLOW (gpm)	Q/Q <sub>DESIGN</sub>	INLET PRESSURE (PSIA)	PERCENT NPSH MARGIN	FIGURES
ECCENTRIC	2803	1.00	43.3	200	2789	1.00	43.0	198	17
	11	11	27.0	100	2798	11	28.4	109	18
	21	11	18.8	50	2 799	11	19.9	57	19
	2663	0.95	39.4	200	2684	0.96	40.2	205	20
	2523	0.90	37.0	200	2525	0.90	38.8	213	21
	2242	* 0.80	37.0	200	2246	0.80	38.3	210	22
	3083	1.10	54.5	200	3082	1.10	54.3	199	23
	3083	11	34.0	100	3081	11	34.3	101	24
	3364	1.20	48.3	100	3369	1.20	48.3	100	25
	3364	11	. 34.1	50	3366	11	34.4	51	26
	3644	1.30	67.0	50	3666	1.31	67.2	50	27
	3644	11	51.6	20	3660	11	52.9	2 2	28

# TABLE 3. MODEL I.S.I.P. SODIUM INDUCER DYE TESTS IN WATER

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# TABLE 4. MODEL I.S.I.P. SODIUM INDUCER DYE TESTS IN WATER

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	TARGET VALUES				TEST RESULT VALUES				
BUILD	FLOW (gpm)	Q/Q <sub>DESIGN</sub>	INLET PRESSURE (PSIA)	N P S H MA R G I N	FLOW (gpm)	Q/Q <sub>DESIGN</sub>	INLET PRESSURE (PSIA)	N P S H M A R G I N	FIGURES
CONCENTRIC	2803	1.00	43.3	200	2799	1.00	43.9	204	29
REDUCED TIP CLEAR.	2803	1.00	27.0	100	2804	1.00	28.2	108	30
OF .008 IN.	2663	0.95	39.4	200	2664	0.95	41.9	217	31
	2523	0.90	37.0	200	2514	0.90	37.9	206	32
	2242	0.80	37.0	200	2234	0.80	38.1	208	33
	3083	<sup>1</sup> 1.10	54.5	200	3081	1.10	55.0	<b>2</b> 02	34
	3364	1.20	48.3	100	3371	1.20	48.6	101	35
	3644	1.30	67.0	50	3660	1.31	66.7	50	36

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blade for each test (Table 3). The photographs are not ideal in that light reflections and dye streaking that occurred when the blade was originally coated can appear as dye removal when no such removal was experienced. Nevertheless, it is instructive to include representative photographs to verify the results. Photographs were taken of each of the four blades of the inducer after each of the tests of Table 3. Reproductions of all of the photographs would be an unnecessary expense, but a representative photograph from each test is shown in Figures 17 through 37. A mirror was used behind the inducer to show the backside of the blades.

Many pictures have large white areas on the inducer. These white areas are due to light reflection of the photographers flash from the glossy inducer surface. The tips of the blades were not coated to prevent smearing of dye on the plastic tunnel. In many cases the inducer blades suffered accidental scratch marks due to foreign matter, such as scale, circulating within the water tunnel loop. These scratch marks are not to be confused with erosion due to cavitaion action. A typical effect of this scratch erosion may be seen in Figure 36.

In contrast a typical example of dye erosion due to cavitaion action may be seen in Figure 22. Cavitation erosion was expected to occur during this test since the flowrate was maintained at 70 percent of design flow.

## CONCLUSION

The test program discussed in the Rocketdyne report Ref. 2 revealed that the I.S.I.P. inducer has exceeded all design objectives if installed concentrically with the housing and using a scaled down concentric tip clearance. The test program in this report has revealed that if the model size inducer is mounted eccentrically by approximately 0.007 inch due to manufacturing tolerance buildup, the performance of the inducer will not degrade or be subject to increased cavitation action as demonstrated by the test data shown in this report.

This test program also consisted of an experimental setup in which the I.S.I.P. inducer tip clearance was reduced by approximately 50 percent to .008 inch and concentric. The resulting slight improvement in head rise performance could be considered negligible in the overall pump performance.

There was an improvement in suction performance at 70 percent to 80 percent of design flow. However in this operating regime blade dye removal occurred and the inducer should not be operated for extended periods in this flow range. Severe rubbing marks were discovered in the aluminum sleeve after disassembly of this close tip clearance setup. This does not necessarily signify that rubbing would also occur in the complete pump since the latter may have greater shaft rigidity. However, in the overall picture, it appears that the slight gain in inducer performance does not warrant the increased risk of inducer rubbing against the housing bore. The life tests for the reduced tip clearance installation showed virtually no difference

in cavitation action on the inducer as compared to the normal tip clearance installation as evidenced by dye removal tests.

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